

# Pentium<sup>®</sup> Processor Family Developer's Manual



## Volume 3: Architecture and Programming Manual

### One good thing



1979 – 8086 and 8088 CPU

### leads to another...



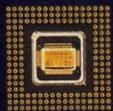
1982 – 80286 CPU

### and another...



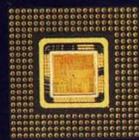
1985 – Intel386™ CPU

### and another...



1989 – Intel486™ CPU

### and another...



1993 – Pentium<sup>®</sup> Processor

1995 – Pentium<sup>®</sup> Processor  
(120 & 133 MHz)



# and another... and another..



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# **Pentium® Processor Family Developer's Manual**

## **Volume 3: Architecture and Programming Manual**

**NOTE:** The *Pentium® Processor Family Developer's Manual* consists of three books: *Pentium® Processor* Order Number 241428; the *82496/82497/82498 Cache Controller and 82491/82492/82493 Cache SRAM*, Order Number 241429; and the *Architecture and Programming Manual*, Order Number 241430.

Please refer to all three volumes when evaluating your design needs.

1995



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**1**

# **Getting Started**

**1**



# CHAPTER 1 GETTING STARTED

## 1.1. HOW TO USE THIS MANUAL

Chapter 1 provides an overview of this manual and the related Pentium® processor documentation. Also included are some notational conventions regarding reserved bits, instruction operands, number formats, addressing and exceptions found throughout the manual.

Chapter 2 provides an introduction to Intel's Pentium processor family. The remainder of this book presents the architecture of the Pentium processor in five parts:

- Part I—Application and Numeric Programming
- Part II—System Programming
- Part III—Compatibility
- Part IV—Optimization
- Part V—Instruction Set
- Appendices

The first three parts are explanatory, showing the purpose of architectural features, developing terminology and concepts, and describing instructions as they relate to specific purposes or to specific architectural features. The remaining parts are reference material for programmers developing software for the Pentium processor.

The first two parts cover the operating modes and protection mechanism of the Pentium processor. The distinction between application programming and system programming is related to the protection mechanism of the Pentium processor. One purpose of protection is to prevent applications from interfering with the operating system. For this reason, certain registers and instructions are inaccessible to application programs. The features discussed in Part I are those which are accessible to applications; the features in Part II are available only to programs running with special privileges or programs running on systems where the protection mechanism is not used.

The features available to application programs in protected mode and to programs in real-address and virtual-8086 mode are the same. These features are described in Part I of this book. The additional features available to system programs in protected mode are described in Part II. Part III describes virtual-8086 mode, how to mix 16-bit and 32-bit code, and compatibility considerations.

Part IV provides general optimization techniques for programming on Intel architectures. For additional information refer to AP-500, *Optimizations for Intel's 32-Bit Processors*, order number 241799.

### 1.1.1. Part I—Application and Numeric Programming

This section presents the features used by most application programmers. It includes features used in numeric applications which are object-code compatible with features provided by the Intel486™ DX processor, and the Intel487™ SX, the Intel387™ DX, and the Intel387 SX math coprocessors used with the Intel486 SX, Intel386™ DX and Intel386 SX processors, respectively.

**Chapter 3—Basic Programming Model:** This chapter introduces the models of memory organization, defines the data types, presents the register set used by applications, introduces the stack, explains string operations, defines the parts of an instruction, explains address calculations, and introduces interrupts and exceptions as they apply to application programming.

**Chapter 4—Application Programming:** Chapter 4 surveys the integer instructions commonly used for application programming. Instructions are considered in functionally related groups; for example, string instructions are considered in one section, while control-transfer instructions are considered in another. The concepts behind the instructions are explained. Details of individual instructions are deferred until Part V, the instruction-set reference.

**Chapter 5—Feature Determination:** This chapter discusses how to determine the CPU type and the presence of a math coprocessor in order to determine what features are available to an application. A program example is provided.

**Chapter 6—Numeric Applications:** This chapter gives an overview of the floating-point unit and reviews the concepts of numerical computation. The "Architecture of the Floating-Point Unit" section presents the floating-point registers and data types available to both applications and systems programmers. The "Floating-Point Instructions" section of this chapter surveys the instructions commonly used for numeric processing. Details of individual instructions are deferred until Part V, the instruction-set reference. The "Numerics Applications" section describes the Pentium processor's floating-point arithmetic facilities and gives short programming examples in both assembly language and high-level languages.

**Chapter 7—Special Computational Situations:** This chapter discusses the special values that can be represented in the real formats of the Pentium processor—denormal numbers, zeros, infinities, NaNs (Not a Number)—as well as the numerical exceptions.

**Chapter 8—Numeric Programming Examples:** Chapter 8 provides detailed examples of assembly-language numeric programming with the Pentium processor, including conditional branching, conversion between floating-point values and their ASCII representations, and use of trigonometric functions.

### 1.1.2. Part II—System Programming

This section presents the features used by operating systems, device drivers, debuggers, and other software which support application programs.



**Chapter 9—Real-Address Mode System Architecture:** This chapter explains the real-address mode of the Pentium processor as it relates to the system programmer. In this mode, the Pentium processor appears as a fast real-mode Intel 286 or Intel386 processor or a fast 8086 processor enhanced with additional instructions.

**Chapter 10—Protected-Mode System Architecture Overview:** Chapter 10 describes the features of the Pentium processor used by system programmers. System-oriented registers and data structures of the Pentium processor which are mentioned briefly in Part I are discussed in detail. The system-oriented instructions are introduced in the context of the registers and data structures they support. References to the chapters in which each register, data structure, and instruction is discussed in more detail.

**Chapter 11—Protected-Mode Memory Management:** This chapter presents details of the data structures, registers, and instructions which support segmentation and paging and explains how system designers can choose between an unsegmented ("flat") model of memory organization and a model with segmentation.

**Chapter 12—Protection:** This chapter discusses protection as it applies to segments and pages. It explains the implementation of privilege rules, stack switching, pointer validation, user and supervisor modes. The protection aspects of multitasking are deferred until the following chapter.

**Chapter 13—Protected-Mode Multitasking:** Chapter 13 explains how the hardware of the Pentium processor supports multitasking with context-switching operations and intertask protection.

**Chapter 14—Protected-Mode Exceptions and Interrupts:** This chapter explains the basic interrupt mechanisms of the Pentium processor, shows how interrupts and exceptions relate to protection, discusses all possible exceptions including floating-point exceptions, listing causes and including information needed to handle and recover from each exception.

**Chapter 15—Input/Output:** Chapter 15 describes the I/O features of the Pentium processor, including I/O instructions, protection as it relates to I/O, and the I/O permission bit map.

**Chapter 16—Initialization and Mode Switching:** Chapter 16 defines the condition of the processor and floating-point unit after reset initialization. It explains how to set up registers, flags, and data structures. The steps necessary for switching between real-address and protected modes are also identified.

**Chapter 17—Debugging:** Chapter 17 discusses how to use the debugging registers and other debug features of the Pentium processor.

**Chapter 18—Caching, Pipelining and Buffering:** Chapter 18 explains the general concept of caching and the specific mechanisms used by the internal cache on the Pentium processor. It explains how the superscalar pipeline architecture of the Pentium processor and the Translation Lookaside Buffer (TLB) relate to the system programmer.

**Chapter 19—Multiprocessing:** Chapter 19 explains the instructions and flags which support multiple processors with shared memory.

**Chapter 20—System Management Mode:** This chapter explains the operation of SMM used to implement power management functions. Some possible customer differentiation features are mentioned.

### 1.1.3. Part III—Compatibility

This section explains the features of the architecture which support programs written for earlier Intel processors. Three execution modes have support for 16-bit programming: 16-bit operations can be performed in protected mode with or without using the operand-size prefix, programs written for the 8086 processor or the real mode of the Intel 286 processor can run in real mode on one of the 32-bit microprocessors, and a virtual machine monitor can be used to emulate real mode using virtual-8086 mode, even while multitasking with 32-bit programs.

**Chapter 21—Mixing 16-Bit and 32-Bit Code:** This chapter explains how to mix 16-bit and 32-bit modules within the same program or task. Any particular module can use both 16-bit and 32-bit operands and addresses.

**Chapter 22—Virtual-8086 Mode:** Chapter 22 describes how to execute one or more 8086, 8088, 80186 or 80188 programs in a Pentium processor protected-mode environment.

**Chapter 23—Compatibility:** This chapter explains the programming differences between the Intel 286, Intel386, and Intel486 processors. This chapter compares the floating-point unit of the Intel486 and Pentium processors with the arithmetic of the numerics coprocessors used with earlier Intel processors.

### 1.1.4. Part IV—Optimization

Chapter 24 discusses general optimization techniques for programming in the Intel architecture environment. For additional information refer to AP-500, *Optimizations for Intel's 32-Bit Processors*, order number 241799.

### 1.1.5. Part V—Instruction Set

Parts I, II and III present the general features of the instruction set as they relate to specific aspects of the architecture. Part V, Chapter 25, presents the instructions in alphabetical order, with detail needed by assembly language programmers and programmers of debuggers, compilers, operating systems, etc. Instruction descriptions include an algorithmic description of operations, effect on flag settings, effect of operand- and address-size attributes, and exceptions which may be generated.



### 1.1.6. Appendices

The appendices present tables of encodings and other details in a format designed for quick reference by programmers.

## 1.2. RELATED LITERATURE

The following books contain additional material related to Intel processors:

- *Pentium® Processor Data Book*, Order Number 241428
- *82496 Cache Controller and 82491 Cache SRAM Data Book For Use With the Pentium® Processor*, Order Number 241429
- *Intel486™ Microprocessor Data Book*, Order Number 240440
- *Intel486™ Processor Hardware Reference Manual*, Order Number 240552
- *Intel486™ DX Processor Programmer's Reference Manual*, Order Number 240486
- *Intel486™ SX CPU/Intel487™ SX Math CoProcessor Data Book*, Order Number 240950
- *Intel486™ DX2 Microprocessor Data Book*, Order Number 241245
- *Intel486™ Microprocessor Product Brief Book*, Order Number 240459
- *Intel386™ Processor Hardware Reference Manual*, Order Number 231732
- *Intel386™ DX Processor Programmer's Reference Manual*, Order Number 230985
- *Intel386™ SX Processor Programmer's Reference Manual*, Order Number 240331
- *Intel386™ Processor System Software Writer's Guide*, Order Number 231499
- *Intel386™ High-Performance 32-Bit CHMOS Microprocessor with Integrated Memory Management*, Order Number 231630
- *376™ Embedded Processor Programmer's Reference Manual*, Order Number 240314
- *80387 DX User's Manual Programmer's Reference*, Order Number 231917
- *376™ High-Performance 32-Bit Embedded Processor*, Order Number 240182
- *Intel386™ SX Microprocessor*, Order Number 240187
- *Microprocessor and Peripheral Handbook* (vol. 1), Order Number 230843

## 1.3. NOTATIONAL CONVENTIONS

This manual uses special notation for data-structure formats, for symbolic representation of instructions, and for hexadecimal numbers. A review of this notation makes the manual easier to read.

### 1.3.1. Bit and Byte Order

In illustrations of data structures in memory, smaller addresses appear toward the bottom of the figure; addresses increase toward the top. Bit positions are numbered from right to left. The numerical value of a set bit is equal to two raised to the power of the bit position. The Pentium processor is a "little endian" machine; this means the bytes of a word are numbered starting from the least significant byte. Figure 1-1 illustrates these conventions.

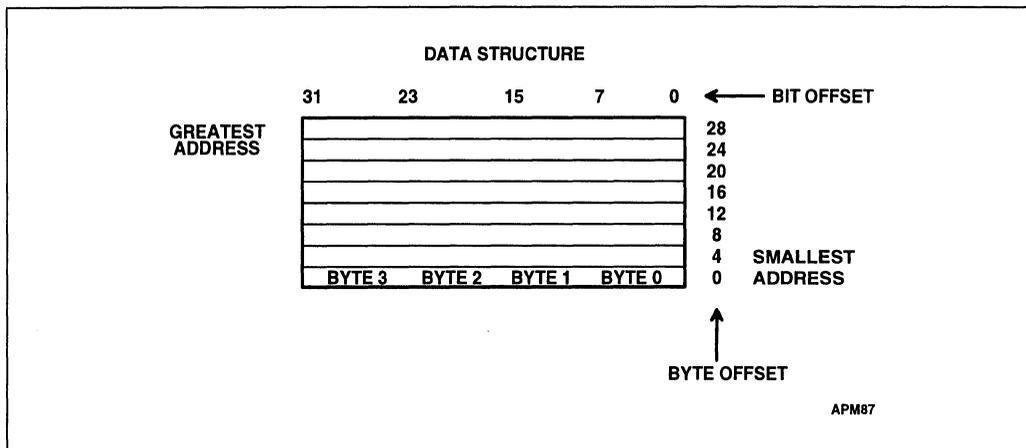


Figure 1-1. Bit and Byte Order

### 1.3.2. Undefined Bits and Software Compatibility

In many register and memory layout descriptions, certain bits are marked as *reserved*. When bits are marked as undefined or reserved, it is essential for compatibility with future processors that software treat these bits as having a future, though unknown, effect. The behavior of reserved bits should be regarded as not only undefined, but unpredictable. Software should follow these guidelines in dealing with reserved bits:

- Do not depend on the states of any reserved bits when testing the values of registers which contain such bits. Mask out the reserved bits before testing.
- Do not depend on the states of any reserved bits when storing to memory or to a register.
- Do not depend on the ability to retain information written into any reserved bits.
- When loading a register, always load the reserved bits with the values indicated in the documentation, if any, or reload them with values previously read from the same register.

**NOTE**

Depending upon the values of reserved register bits will make software dependent upon the unspecified manner in which the processor handles these bits. Depending upon reserved values risks incompatibility with future processors. **AVOID ANY SOFTWARE DEPENDENCE UPON THE STATE OF RESERVED PENTIUM PROCESSOR REGISTER BITS.**

**1.3.3. Instruction Operands**

When instructions are represented symbolically, a subset of the assembly language for the Pentium processor is used. In this subset, an instruction has the following format:

*label: mnemonic argument1, argument2, argument3*

where:

- A *label* is an identifier which is followed by a colon.
- A *mnemonic* is a reserved name for a class of instruction opcodes which have the same function.
- The operands *argument1*, *argument2*, and *argument3* are optional. There may be from zero to three operands, depending on the opcode. When present, they take the form of either literals or identifiers for data items. Operand identifiers are either reserved names of registers or are assumed to be assigned to data items declared in another part of the program (which may not be shown in the example).

When two operands are present in an arithmetic or logical instruction, the right operand is the source and the left operand is the destination.

For example:

```
LOADREG: MOV EAX, SUBTOTAL
```

In this example LOADREG is a label, MOV is the mnemonic identifier of an opcode, EAX is the destination operand, and SUBTOTAL is the source operand. Some assembly languages put the source and destination in reverse order.

**1.3.4. Hexadecimal Numbers**

Base 16 numbers are represented by a string of hexadecimal digits followed by the character H. A hexadecimal digit is a character from the set (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, A, B, C, D, E, F). A leading zero is added if the number would otherwise begin with one of the digits A-F. For example, 0FH is equivalent to the decimal number 15.

Numbers are usually expressed in decimal notation (base 10). When hexadecimal (base 16) numbers are used, they are indicated by an 'H' suffix. For example 16 = 10H.

### 1.3.5. Segmented Addressing

The processor uses byte addressing. This means memory is organized and accessed as a sequence of bytes. Whether one or more bytes are being accessed, a byte number is used to address memory. The memory which can be addressed with this number is called an *address space*.

The processor also supports segmented addressing. This is a form of addressing where a program may have many independent address spaces, called *segments*. For example, a program can keep its code (instructions) and stack in separate segments. Code addresses would always refer to the code space, and stack addresses would always refer to the stack space. An example of the notation used to show segmented addresses is shown below.

CS:EIP

This example refers to a byte within the code segment. The byte number is held in the EIP register. CS identifies the code segment.

### 1.3.6. Exceptions

An exception is an event which typically occurs when an instruction causes an error. For example, an attempt to divide by zero generates an exception. However, some exceptions, such as breakpoints, occur under other conditions. Some types of exceptions may provide error codes. An error code reports additional information about the error. Error codes are produced only for some exceptions. An example of the notation used to show an exception and error code is shown below.

#PF(fault code)

This example refers to a page-fault exception under conditions where an error code naming a type of fault is reported. Under some conditions, exceptions which produce error codes may not be able to report an accurate code. In this case, the error code is zero, as shown below.

#GP(0)

See Chapter 14, Protected-Mode Exceptions and Interrupts, for a list of exception mnemonics and their description.





2

**Introduction to the  
Intel Pentium®  
Processor Family**





## CHAPTER 2

# INTRODUCTION TO THE INTEL PENTIUM® PROCESSOR FAMILY

In 1985, Intel introduced the first in a line of 32-bit microprocessors compatible with the already broad base of existing Intel architecture software. That was the Intel386 microprocessor. The Intel 32-bit architecture has since grown to become the standard for cost-effective, high performance computing with an installed base of over 40 million units. Intel has continued to evolve and improve the basic implementation by incorporating the most advanced computer design and silicon technology. The Intel Pentium family is the most recent product of that effort.

The Intel Pentium processor, like its predecessor the Intel486 microprocessor, is fully software compatible with the installed base of over 100 million compatible Intel architecture systems. In addition, the Intel Pentium processor provides new levels of performance to new and existing software through a reimplementing of the Intel 32-bit instruction set architecture using the latest, most advanced, design techniques. Optimized, dual execution units provide one-clock execution for "core" instructions, while advanced technology, such as superscalar architecture, branch prediction, and execution pipelining, enables multiple instructions to execute in parallel with high efficiency. Separate code and data caches combined with wide 128-bit and 256-bit internal data paths and a 64-bit, burstable, external bus allow these performance levels to be sustained in cost-effective systems. The application of this advanced technology in the Intel Pentium processor brings "state of the art" performance and capability to existing Intel architecture software as well as new and advanced applications.

The Pentium processor has two primary operating modes and a "system management mode." The operating mode determines which instructions and architectural features are accessible. These modes are:

- **Protected Mode**

This is the native state of the microprocessor. In this mode all instructions and architectural features are available, providing the highest performance and capability. This is the recommended mode that all new applications and operating systems should target.

Among the capabilities of protected mode is the ability to directly execute "real-address mode" 8086 software in a protected, multi-tasking environment. This feature is known as Virtual-8086 "mode" (or "V86 mode"). Virtual-8086 "mode" however, is not actually a processor "mode," it is in fact an attribute which can be enabled for any task (with appropriate software) while in protected mode.

- **Real-Address Mode (also called "real mode")**

This mode provides the programming environment of the Intel 8086 processor, with a few extensions (such as the ability to break out of this mode). Reset initialization places

the processor in real mode where, with a single instruction, it can switch to protected mode.

- **System Management Mode**

The Pentium microprocessor also provides support for System Management Mode (SMM). SMM is a standard architectural feature unique to all new Intel microprocessors, beginning with the Intel386 SL processor, which provides an operating-system and application independent and transparent mechanism to implement system power management and OEM differentiation features. SMM is entered through activation of an external interrupt pin (SMI#), which switches the CPU to a separate address space while saving the entire context of the CPU. SMM-specific code may then be executed transparently. The operation is reversed upon returning.



# **Part I**

## **Application and Numeric Processing**



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3

# Basic Programming Model





## CHAPTER 3

# BASIC PROGRAMMING MODEL

This chapter describes the application programming environment (except for the floating-point features) as seen by assembly-language programmers. The chapter introduces the architectural features which directly affect the design and implementation of application programs. Floating-point applications are described separately in Chapter 6.

The basic programming model consists of these parts:

- Memory organization
- Data types
- Registers
- Instruction format
- Operand selection
- Interrupts and exceptions

Note that input/output is not included as part of the basic programming model. System designers can choose to make I/O instructions available to applications or can choose to reserve these functions for the operating system. For this reason, the I/O features are discussed in Chapter 9 and Chapter 15.

This chapter contains a section for each feature of the architecture normally visible to applications.

### 3.1. MEMORY ORGANIZATION

The memory on the bus of a Pentium processor is called *physical memory*. It is organized as a sequence of 8-bit bytes. Each byte is assigned a unique address, called a *physical address*, which ranges from zero to a maximum of  $2^{32}-1$  (4 gigabytes).

Memory management is a hardware mechanism for making reliable and efficient use of memory. When memory management is used, programs do not directly address physical memory. Programs address a memory model, called *virtual memory*.

Memory management consists of segmentation and paging. Segmentation is a mechanism for providing multiple, independent address spaces. Paging is a mechanism to support a model of a large address space in RAM using a small amount of RAM and some disk storage. Either or both of these mechanisms can be used. An address issued by a program is a *logical address*. Segmentation hardware translates a logical address into an address for a continuous, unsegmented address space, called a *linear address*. Paging hardware translates a linear address into a physical address.

Memory can appear as a single, "flat" address space like physical memory. Or, it can appear as one or more independent memory spaces, called *segments*. Segments can be assigned specifically for holding a program's code (instructions), data, or stack. In fact, a single program can have up to 16,383 segments of different sizes and kinds. Segments can be used to increase the reliability of programs and systems. For example, a program's stack can be put into a different segment than its code to prevent the stack from growing into the code space and overwriting instructions with data. Each segment defines a module.

Both the flat and segmented models can provide memory protection. Models intermediate between these extremes also can be chosen. The reasons for choosing a particular memory model and the manner in which system programmers implement a model are discussed in Chapter 11.

Whether or not multiple segments are used, logical addresses are translated into linear addresses by treating the address as an offset into a segment. Each segment has a *segment descriptor*, which holds its base address and size limit. If the offset does not exceed the limit, and no other condition exists which would prevent reading the segment, the offset and base address are added together to form the linear address.

The linear address produced by segmentation is used directly as the physical address if bit 31 of the CR0 register is clear (the CR0 register is discussed in Chapter 10). This register bit controls whether paging is used or not used. If the bit is set, the paging hardware is used to translate the linear address into the physical address.

The paging hardware gives another level of organization to memory. It breaks the linear address space into fixed blocks called *pages*. The logical address space is mapped into the linear address space, which is mapped into some number of pages. A page can be in memory or on disk. When a logical address is issued, it is translated into an address for a page in memory, or an exception is issued. An exception gives the operating system a chance to read the page from disk and update the page mapping. The program which generated the exception then can be restarted without generating an exception.

If multiple segments are used, they are part of the programming environment seen by application programmers. Paging, however, is invisible to the application programmer and is not discussed in this chapter. See Chapter 11 for details on this subject.

### 3.1.1. Unsegmented or "Flat" Model

The simplest memory model is the flat model. Although there isn't a mode bit or control register which turns off the segmentation mechanism, the same effect can be achieved by mapping all segments to the same linear addresses. This will cause all memory operations to refer to the same memory space.

In a flat model, segments can cover the entire range of physical addresses, or they can cover only those addresses which are mapped to physical memory. The advantage of the smaller address space is it provides a minimum level of hardware protection against software bugs; an exception will occur if any logical address refers to an address for which no memory exists.



### 3.1.2. Segmented Model

In a segmented model of memory organization, the logical address space consists of as many as 16,383 segments of up to 4 gigabytes each, or a total as large as  $2^{46}$  bytes (64 terabytes). The processor maps this 64 terabyte logical address space onto the physical address space by the address translation mechanism described in Chapter 11. Application programmers can ignore the details of this mapping. The advantage of the segmented model is that offsets within each address space are separately checked and access to each segment can be individually controlled.

A pointer into a segmented address space consists of two parts (see Figure 3-1).

1. A *segment selector*, which is a 16-bit field which identifies a segment.
2. An *offset*, which is a 32-bit byte address within a segment.

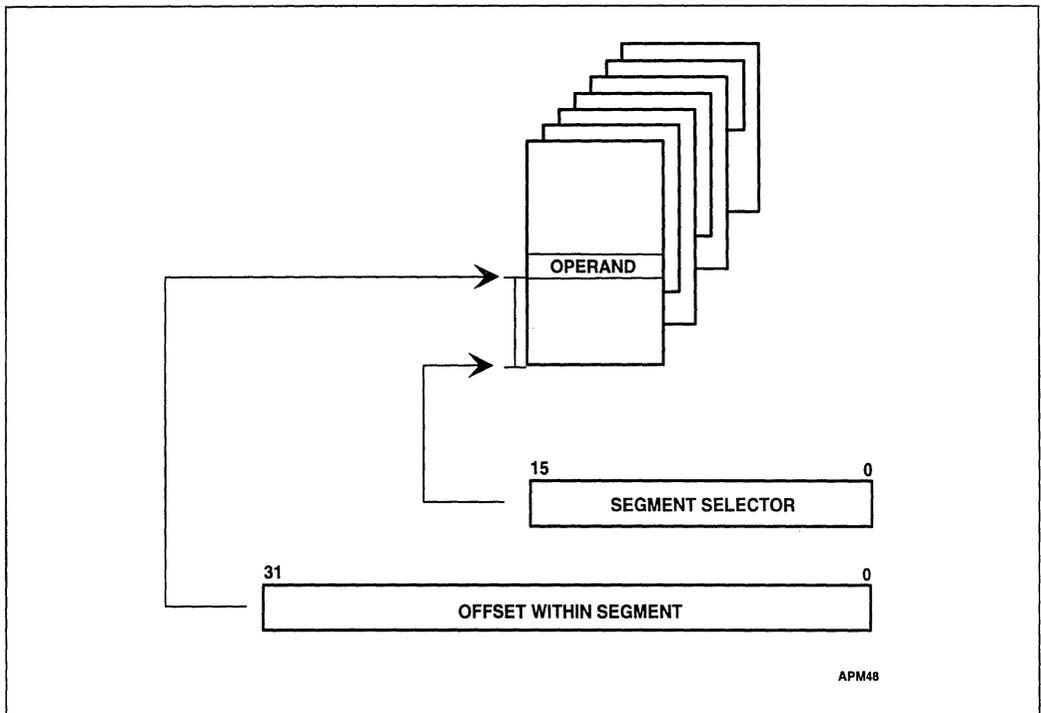


Figure 3-1. Segmented Addressing

The processor uses the segment selector to find the linear address of the beginning of the segment, called the *base address*. Programs access memory using fixed offsets from this base address, so an object-code module can be loaded into memory and run without changing the addresses it uses (dynamic linking). The size of a segment is defined by the programmer, so a segment can be exactly the size of the module it contains.

### 3.2. DATA TYPES

Bytes, words, doublewords, and quadwords are the principal data types (see Figure 3-2). A byte is eight bits. The bits are numbered 0 through 7, bit 0 being the least significant bit (LSB).

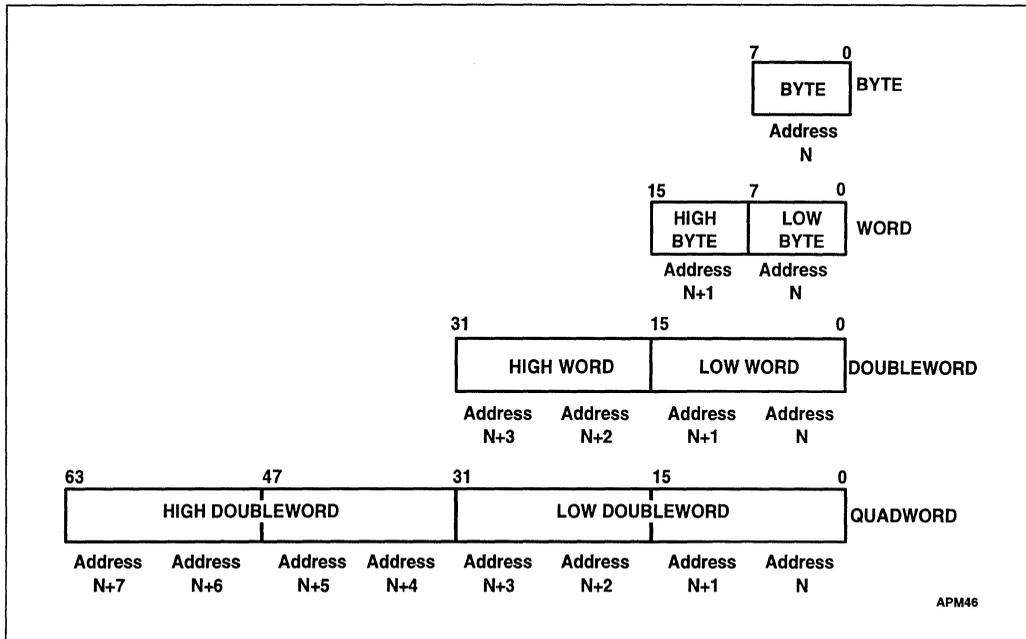


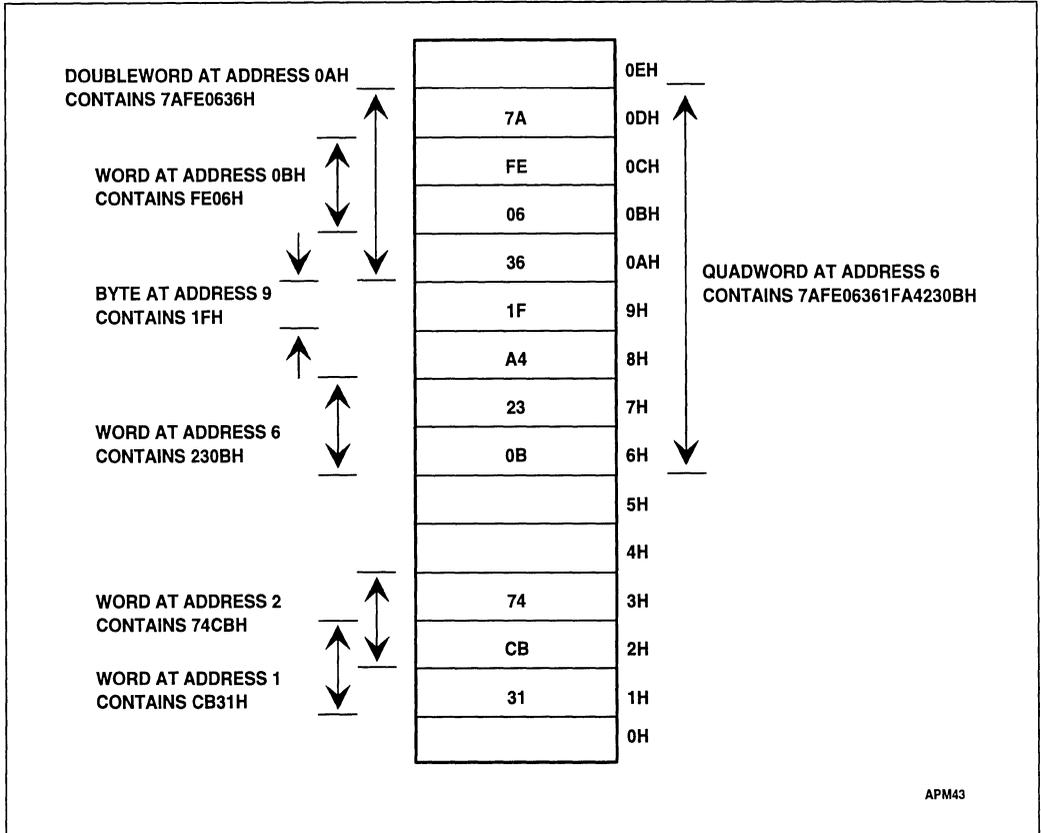
Figure 3-2. Fundamental Data Types

A word is two bytes occupying any two consecutive addresses. A word contains 16 bits. The bits of a word are numbered from 0 through 15, bit 0 again being the least significant bit. The byte containing bits 0-7 of the word is called the *low byte*; the byte containing bits 8-15 is called the *high byte*. The low byte is stored in the byte with the lower address. The address of the low byte also is the address of the word. The address of the high byte is used only when the upper half of the word is being accessed separately from the lower half.

A doubleword is four bytes occupying any four consecutive addresses. A doubleword contains 32 bits. The bits of a doubleword are numbered from 0 through 31, bit 0 again being the least significant bit. The word containing bits 0-15 of the doubleword is called the *low word*; the word containing bits 16-31 is called the *high word*. The low word is stored in the two bytes with the lower addresses. The address of the lowest byte is the address of the doubleword. The higher addresses are used only when the upper word is being accessed separately from the lower word, or when individual bytes are being accessed.

A quadword is eight bytes occupying any eight consecutive addresses. A quadword contains 64 bits. The bits of a quadword are numbered from 0 to 64 with bit 0 being the least significant bit. The doubleword containing bits 0-31 is called the low doubleword and the doubleword containing bits 32-63 is called the high doubleword. The low doubleword is

stored in the four bytes with the lower addresses. The higher addresses are used only when the upper doubleword is being accessed separately from the lower doubleword, or when individual bytes are being accessed. Figure 3-3 illustrates the arrangement of bytes within words, doublewords and quadwords.



**Figure 3-3. Bytes, Words, Doublewords and Quadwords in Memory**

Note that words do not need to be aligned at even-numbered addresses, doublewords do not need to be aligned at addresses evenly divisible by four, and quadwords do not need to be aligned at addresses evenly divisible by eight. This allows maximum flexibility in data structures (e.g., records containing mixed byte, word, and doubleword items) and efficiency in memory utilization. Because the Pentium processor has a 64-bit data bus, communication between processor and memory takes place as byte, word, doubleword and quadword transfers. Data can be accessed at any byte boundary, but multiple cycles can be required for unaligned transfers. The Pentium processor considers a 2-byte or 4-byte operand that crosses a 4-byte boundary and an 8-byte operand that crosses an 8-byte boundary to be misaligned. For maximum performance, data structures (especially stacks) should be designed so, whenever possible, word operands are aligned to even addresses, doubleword operands are

aligned to addresses evenly divisible by four, and quadwords are aligned to addresses evenly divisible by eight.

Although bytes, words, and doublewords are the fundamental types of operands, the processor also supports additional interpretations of these operands. Specialized instructions recognize the following data types (shown in Figure 3-4):

- *Integer*: A signed binary number held in a 32-bit doubleword, 16-bit word, or 8-bit byte. All operations assume a two's complement representation. The sign bit is located in bit 7 in a byte, bit 15 in a word, and bit 31 in a doubleword. The sign bit is set for negative integers, clear for positive integers and zero. The value of an 8-bit integer is from  $-128$  to  $+127$ ; a 16-bit integer from  $-32,768$  to  $+32,767$ ; a 32-bit integer from  $-2^{31}$  to  $+2^{31} - 1$ .
- *Ordinal*: An unsigned binary number contained in a 32-bit doubleword, 16-bit word, or 8-bit byte. The value of an 8-bit ordinal is from 0 to 255; a 16-bit ordinal from 0 to 65,535; a 32-bit ordinal from 0 to  $2^{32} - 1$ . This is sometimes referred to as an unsigned integer.
- *BCD Integer*: A representation of a binary-coded decimal (BCD) digit in the range 0 through 9. Unpacked decimal numbers are stored as unsigned byte quantities. One digit is stored in each byte. The magnitude of the number is the binary value of the low-order half-byte; values 0 to 9 are valid and are interpreted as the value of a digit. The high-order half-byte must be zero during multiplication and division; it can contain any value during addition and subtraction.
- *Packed BCD Integer*: A representation of binary-coded decimal digits, each in the range 0 to 9. One digit is stored in each half-byte, two digits in each byte. The digit in bits 4 to 7 is more significant than the digit in bits 0 to 3. Values 0 to 9 are valid for a digit.
- *Near Pointer*: A 32-bit effective address. A near pointer is an offset within a segment. Near pointers are used for all pointers in a flat memory model, or for references within a segment in a segmented model.
- *Far Pointer*: A 48-bit logical address consisting of a 16-bit segment selector and a 32-bit offset. Far pointers are used in a segmented memory model to access other segments.
- *Bit Field*: A contiguous sequence of bits. A bit field can begin at any bit position of any byte and can contain up to 32 bits.
- *Bit String*: A contiguous sequence of bits. A bit string can begin at any bit position of any byte and can contain up to  $2^{32} - 1$  bits.
- *Byte String*: A contiguous sequence of bytes, words, or doublewords. A string can contain from zero to  $2^{32} - 1$  bytes (4 gigabytes).
- *Floating-Point Types*: For a discussion of the data types used by floating-point instructions, see Chapter 6.

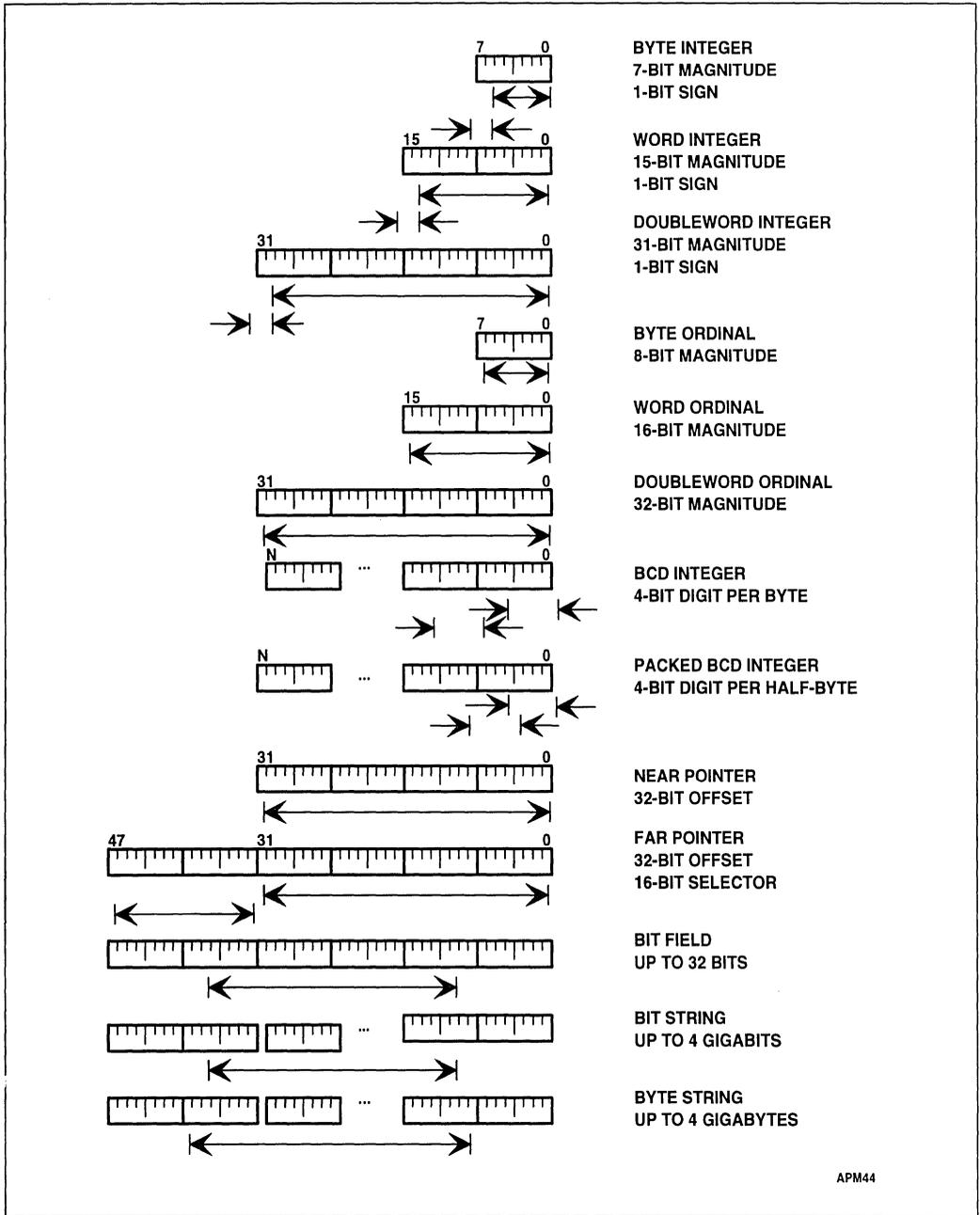


Figure 3-4. Data Types

### 3.3. REGISTERS

The processor contains sixteen registers which can be used by an application programmer. As Figure 3-5 shows, these registers can be grouped as:

1. General registers. These eight 32-bit registers are free for use by the programmer.
2. Segment registers. These registers hold segment selectors associated with different forms of memory access. For example, there are separate segment registers for access to code and stack space. These six registers determine, at any given time, which segments of memory are currently available.
3. Status and control registers. These registers report and allow modification of the state of the processor.

#### 3.3.1. General Registers

The general registers are the 32-bit registers EAX, EBX, ECX, EDX, EBP, ESP, ESI, and EDI. These registers hold operands for logical and arithmetic operations. They also can hold operands for address calculations (except the ESP register cannot be used as an index operand). The names of these registers are derived from the names of the general registers on the 8086 processor, the AX, BX, CX, DX, BP, SP, SI, and DI registers. As Table 3-1 shows, the low 16 bits of the general registers can be referenced using these names.

Each byte of the 16-bit registers AX, BX, CX, and DX also has another name. The byte registers are named AH, BH, CH, and DH (high bytes) and AL, BL, CL, and DL (low bytes).

All of the general-purpose registers are available for address calculations and for the results of most arithmetic and logical operations; however, a few instructions assign specific registers to hold operands. For example, string instructions use the contents of the ECX, ESI, and EDI registers as operands. By assigning specific registers for these functions, the instruction set can be encoded more compactly. The instructions that use specific registers include: double-precision multiply and divide, I/O, strings, translate, loop, variable shift and rotate, and stack operations.



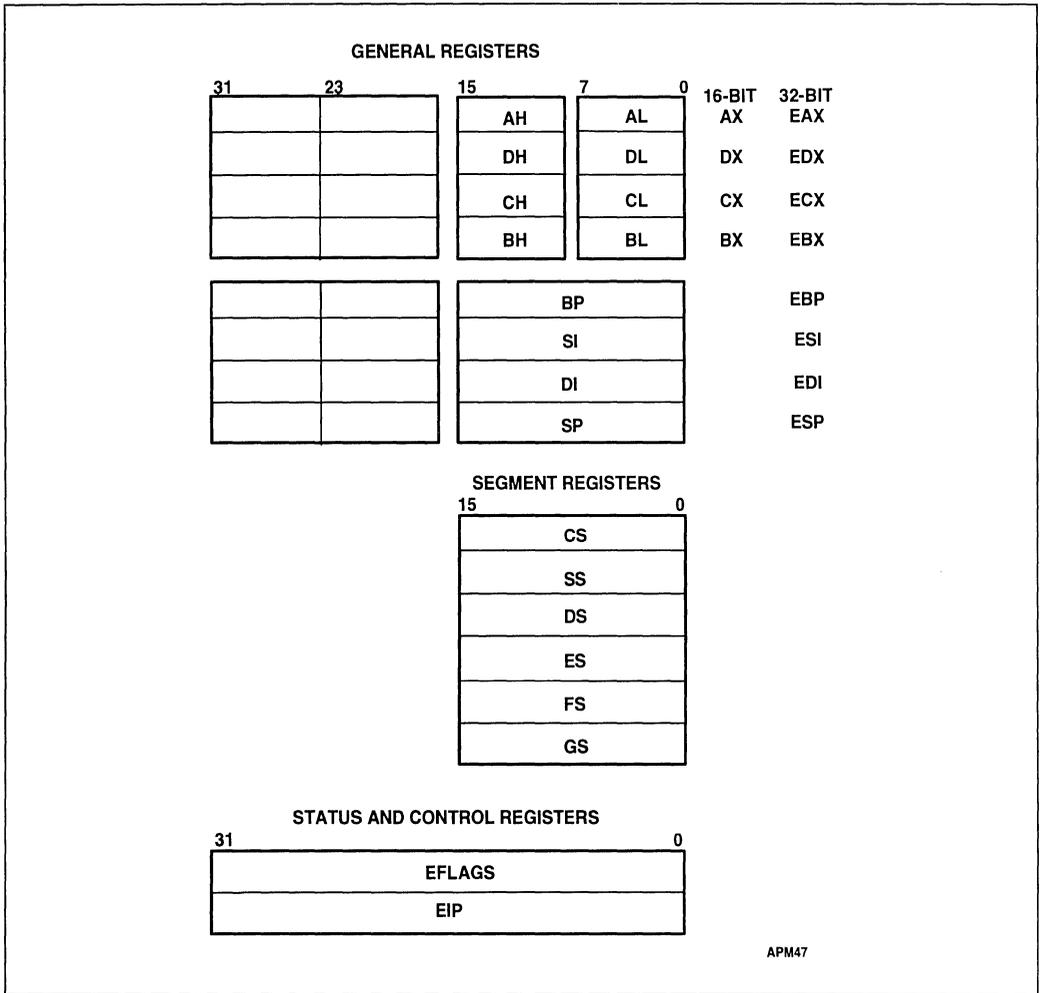


Figure 3-5. Application Register Set

Table 3-1. Register Names

8-Bit	16-Bit	32-Bit
AL	AX	EAX
AH		
BL	BX	EBX
BH		
CL	CX	ECX
CH		
DL	DX	EDX
DH		
	SI	ESI
	DI	EDI
	BP	EBP
	SP	ESP

### 3.3.2. Segment Registers

Segmentation gives system designers the flexibility to choose among various models of memory organization. Implementation of memory models is the subject of Chapter 11.

The segment registers contain 16-bit segment selectors, which index into tables in memory. The tables hold the base address for each segment, as well as other information regarding memory access. An unsegmented model is created by mapping each segment to the same place in physical memory, as shown in Figure 3-6.

At any instant, up to six segments of memory are immediately available. The segment registers CS, DS, SS, ES, FS, and GS hold the segment selectors for these six segments. Each register is associated with a particular kind of memory access (code, data, or stack). Each register specifies a segment, from among the segments used by the program (see Figure 3-7). Other segments can be used by loading their segment selectors into the segment registers.

The segment containing the instructions being executed is called the *code segment*. Its segment selector is held in the CS register. The processor fetches instructions from the code segment, using the contents of the EIP register as an offset into the segment. The CS register is loaded as the result of interrupts, exceptions, and instructions which transfer control between segments (e.g., the CALL, RET and JMP instructions).

Before a procedure is called, a region of memory needs to be allocated for a stack. The stack holds the return address, parameters passed by the calling routine, and temporary variables allocated by the procedure. All stack operations use the SS register to find the stack segment. Unlike the CS register, the SS register can be loaded explicitly, which permits application programs to set up stacks.

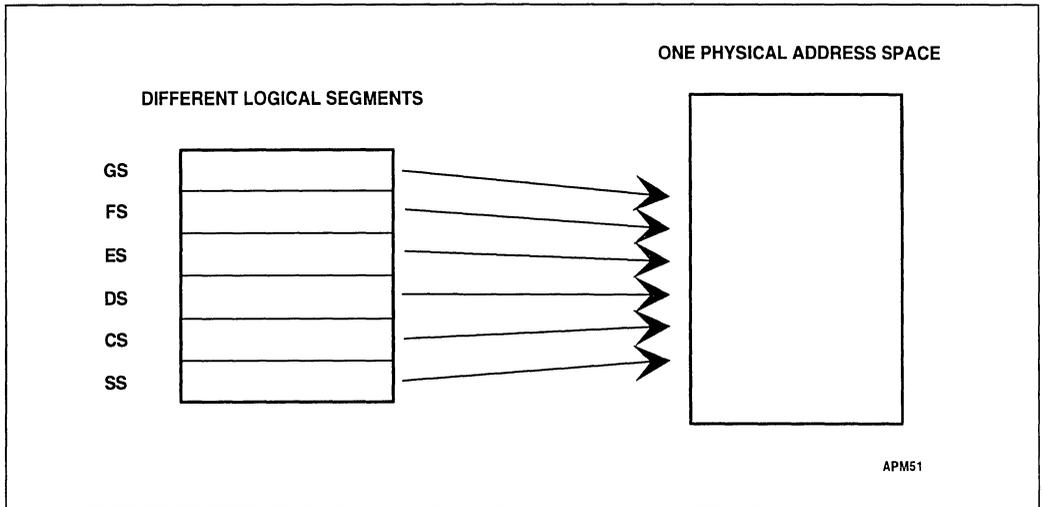


Figure 3-6. An Unsegmented Memory

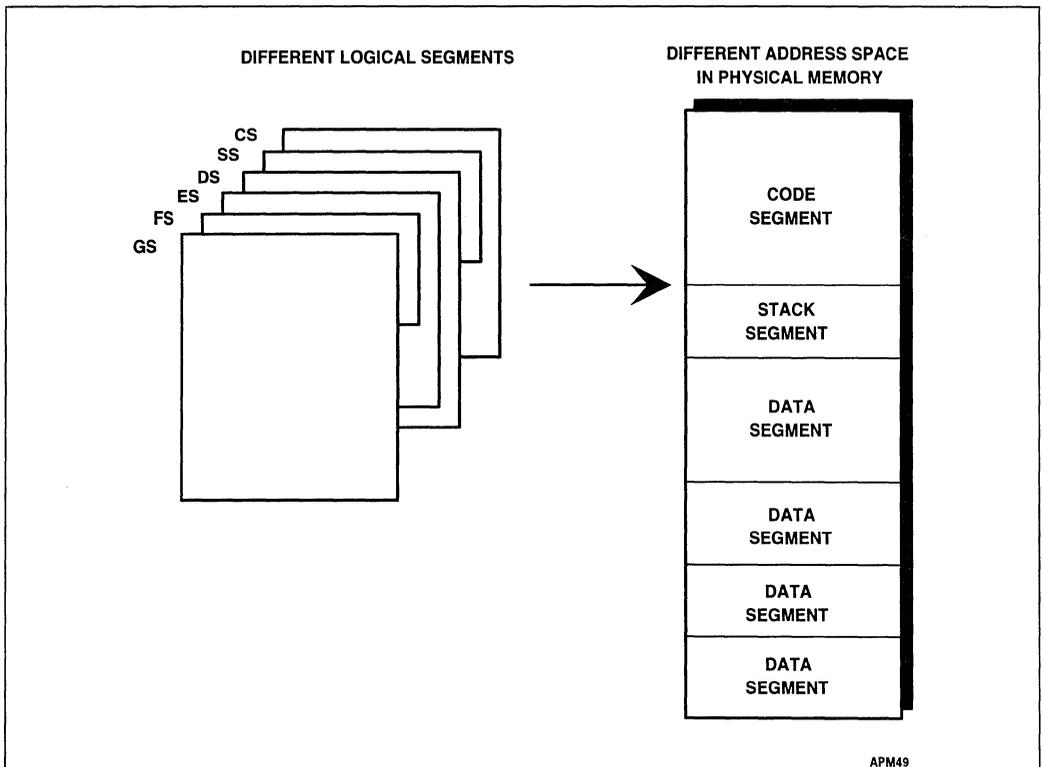


Figure 3-7. A Segmented Memory

The DS, ES, FS, and GS registers allow as many as four data segments to be available simultaneously. Four data segments give efficient and secure access to different types of data structures. For example, separate data segments can be created for the data structures of the current module, data exported from a higher-level module, a dynamically-created data structure, and data shared with another program. If a bug causes a program to run wild, the segmentation mechanism can limit the damage to only those segments allocated to the program.

Depending on the structure of data (i.e., the way data is partitioned into segments), a program can require access to more than four data segments. To access additional segments, the DS, ES, FS, and GS registers can be loaded by an application program during execution. The only requirement is to load the appropriate segment register before accessing data in its segment.

A base address is kept for each segment. To address data within a segment, a 32-bit offset is added to the segment's base address. Once a segment is selected (by loading the segment selector into a segment register), an instruction only needs to specify the offset. An operand within a data segment is addressed by specifying its offset either in an instruction or a general register. Simple rules define which segment register is used to form an address when only an offset is specified.

### 3.3.3. Stack Implementation

Stack operations are supported by three registers:

1. **Stack Segment (SS) Register.** Stacks reside in memory. The number of stacks in a system is limited only by the maximum number of segments. A stack can be up to 4 gigabytes long, the maximum size of a segment. One stack is available at a time—the stack whose segment selector is held in the SS register. This is the current stack, often referred to simply as "the" stack. The SS register is used automatically by the processor for all stack operations.
2. **Stack Pointer (ESP) Register.** The ESP register holds an offset to the top-of-stack (TOS) in the current stack segment. It is used by PUSH and POP operations, subroutine calls and returns, exceptions, and interrupts. When an item is pushed onto the stack (see Figure 3-8), the processor decrements the ESP register, then writes the item at the new TOS. When an item is popped off the stack, the processor copies it from the TOS, then increments the ESP register. In other words, the stack grows *down* in memory toward lesser addresses.
3. **Stack-Frame Base Pointer (EBP) Register.** The EBP register typically is used to access data structures passed on the stack. For example, on entering a subroutine the stack contains the return address and some number of data structures passed to the subroutine. The subroutine adds to the stack whenever it needs to create space for temporary local variables. As a result, the stack pointer gets incremented and decremented as temporary variables are pushed and popped. If the stack pointer is copied into the base pointer before anything is pushed on the stack, the base pointer can be used to reference data



structures with fixed offsets. If this is not done, the offset to access a particular data structure would change whenever a temporary variable is allocated or de-allocated.

When the EBP register is used to address memory, the current stack segment is referenced (i.e., the SS segment). Because the stack segment does not have to be specified, instruction encoding is more compact. The EBP register also can be used to address other segments.

Instructions, such as the ENTER and LEAVE instructions, are provided which automatically set up the EBP register for convenient access to variables.

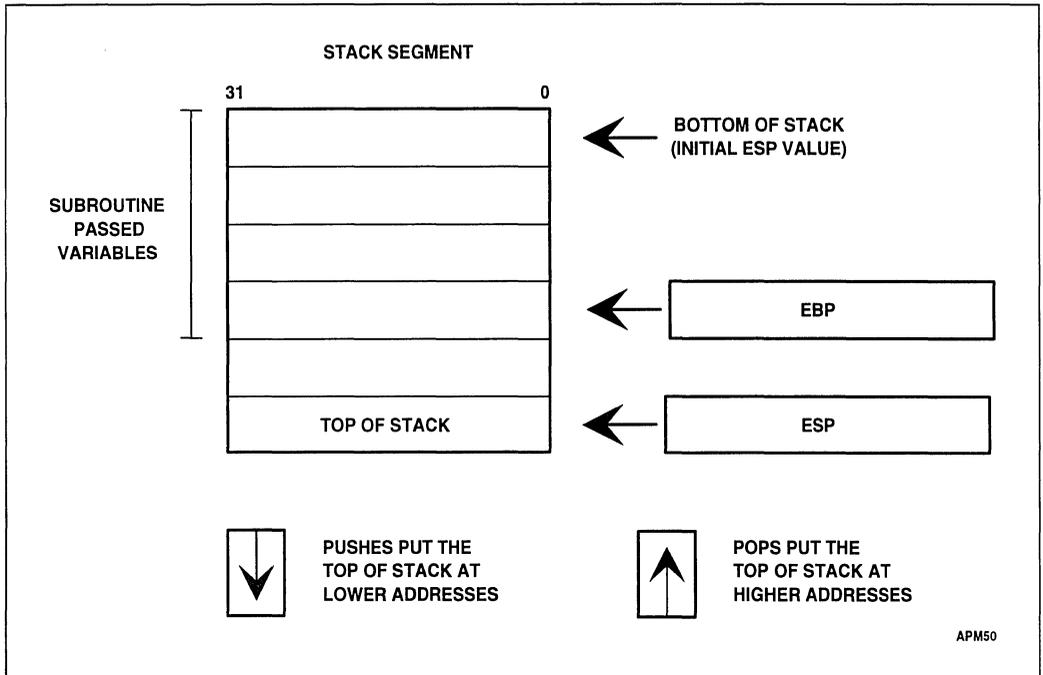


Figure 3-8. Stacks

### 3.3.4. Flags Register

Condition codes (e.g., carry, sign, overflow) and mode bits are kept in a 32-bit register named EFLAGS. Figure 3-9 defines the bits within this register.

The flags control certain operations and indicate the status of the Pentium processor. Besides status and control flag bits, the flag register also contains system flags. See Chapter 10 for a description of the system and control flags.

### 3.3.4.1. STATUS FLAGS

The status flags of the EFLAGS register report the kind of result produced from the execution of arithmetic instructions, such as ADD, SUB, MUL, and DIV. The MOV instruction does not affect these flags. Conditional jumps and subroutine calls allow a program to sense the state of the status flags and respond to them. For example, when the counter controlling a loop is decremented to zero, the state of the ZF flag changes, and this change can be used to suppress the conditional jump to the start of the loop. The status flags are shown in Table 3-2.

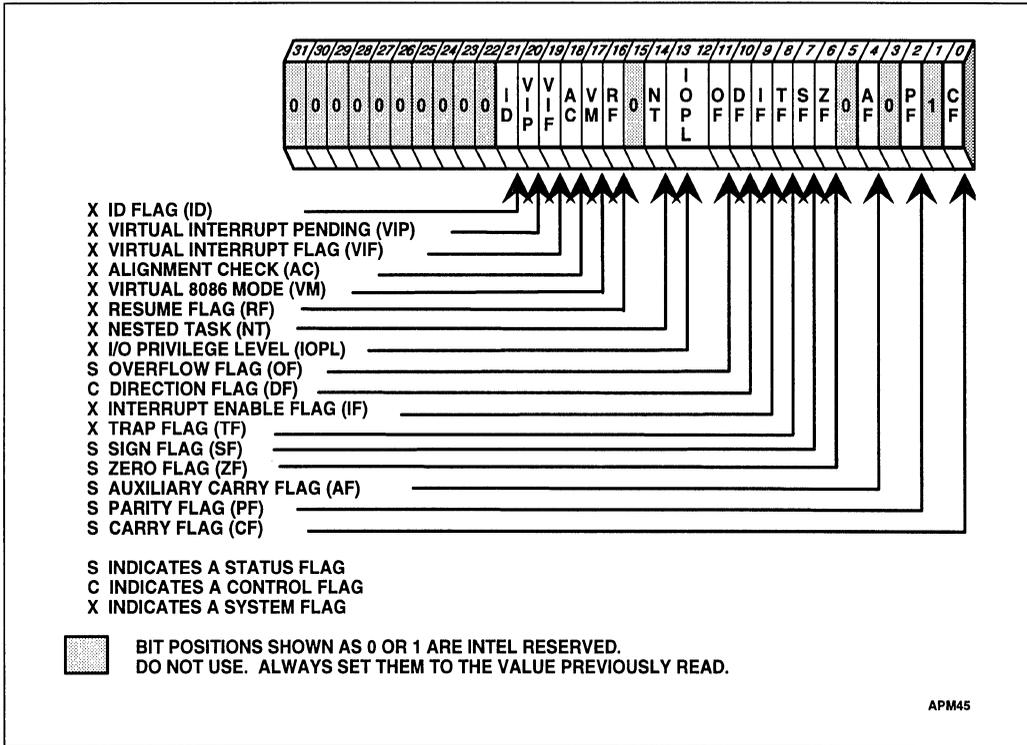


Figure 3-9. EFLAGS Register

Table 3-2. Status Flags

Name	Purpose	Condition Reported
OF	Overflow	Result exceeds positive or negative limit of number range
SF	Sign	Result is negative (less than zero)
ZF	Zero	Result is zero
AF	Auxiliary carry	Carry out of bit position 3 (used for BCD)
PF	Parity	Low byte of result has even parity (even number of set bits)
CF	Carry flag	Carry out of most significant bit of result

### 3.3.4.2. CONTROL FLAG

The control flag DF of the EFLAGS register controls string instructions.

DF (Direction Flag, bit 10)

Setting the DF flag causes string instructions to auto-decrement, that is, to process strings from high addresses to low addresses. Clearing the DF flag causes string instructions to auto-increment, or to process strings from low addresses to high addresses.

### 3.3.5. Instruction Pointer

The instruction pointer (EIP) register contains the offset in the current code segment for the next instruction to execute. The instruction pointer is not directly available to the programmer; it is controlled implicitly by control-transfer instructions (jumps, returns, etc.), interrupts, and exceptions.

The EIP register is advanced from one instruction boundary to the next. Because of instruction prefetching, it is only an approximate indication of the bus activity which loads instructions into the processor. See Chapter 18 for detailed information on prefetching.

## 3.4. INSTRUCTION FORMAT

The information encoded in an instruction includes a specification of the operation to be performed, the type of the operands to be manipulated, and the location of these operands. If an operand is located in memory, the instruction also must select, explicitly or implicitly, the segment which contains the operand.

An instruction can have various parts and formats. The exact format of instructions is shown in Appendix A; the parts of an instruction are described below. Of these parts, only the opcode is always present. The other parts may or may not be present, depending on the operation involved and the location and type of the operands. The parts of an instruction, in order of occurrence, are listed below:

- **Prefixes:** one or more bytes preceding an instruction which modify the operation of the instruction. The following prefixes can be used by application programs:
  1. Segment override—explicitly specifies which segment register an instruction should use, instead of the default segment register. The segment override prefixes include:

2EH	CS segment override prefix
36H	SS segment override prefix
26H	ES segment override prefix
65H	GS segment override prefix
  2. Address size (67H)—switches between 16- and 32-bit addressing. Either size can be the default; this prefix selects the non-default size.

3. Operand size (66H)—switches between 16- and 32-bit data size. Either size can be the default; this prefix selects the non-default size.
4. Repeat—used with a string instruction to cause the instruction to be repeated for each element of the string. The repeat prefixes include:
  - F3H REP prefix (used only with string instructions)
  - F3H REPE/REPZ prefix (used only with string instructions)
  - F2h REPNE/REPZ prefix (used only with string instructions)
5. Lock (0F0H)—used to ensure exclusive use of shared memory in multiprocessor environments. This prefix can only be used with the following instructions: BTS, BTR, BTC, XCHG, ADD, OR, ADC, SBB, AND, SUB, XOR, NOT, NEG, INC, DEC, CMPXCHG, CMPXCH8B, XADD

Zero or one bytes are reserved for each group of prefixes. The prefixes are grouped as follows:

- Instruction Prefixes: REP, REPE/REPZ, REPNE/REPZ, LOCK
- Segment Override Prefixes: CS, SS, DS, ES, FS, GS
- Operand Size Override
- Address Size Override

For each instruction, one prefix may be used from each group. The effect of redundant prefixes (more than one prefix from a group) is undefined and may vary from processor to processor.

- **Opcode:** specifies the operation performed by the instruction. Some operations have several different opcodes, each specifying a different form of the operation.
- **Register specifier:** an instruction can specify one or two register operands. Register specifiers occur either in the same byte as the opcode or in the same byte as the addressing-mode specifier.
- **Addressing-mode specifier:** when present, specifies whether an operand is a register or memory location; if in memory, specifies whether a displacement, a base register, an index register, and scaling are to be used.
- **SIB (scale, index, base) byte:** when the addressing-mode specifier indicates the use of an index register to calculate the address of an operand, an SIB byte is included in the instruction to encode the base register, the index register, and a scaling factor.
- **Displacement:** when the addressing-mode specifier indicates a displacement will be used to compute the address of an operand, the displacement is encoded in the instruction. A displacement is a signed integer of 32, 16, or 8 bits. The 8-bit form is used in the common case when the displacement is sufficiently small. The processor extends an 8-bit displacement to 16 or 32 bits, taking into account the sign.

- **Immediate operand:** when present, directly provides the value of an operand. Immediate operands can be bytes, words, or doublewords. In cases where an 8-bit immediate operand is used with a 16- or 32-bit operand, the processor extends the eight-bit operand to an integer of the same sign and magnitude in the larger size. In the same way, a 16-bit operand is extended to 32 bits.

### 3.5. OPERAND SELECTION

An instruction acts on zero or more operands. An example of a zero-operand instruction is the NOP instruction (no operation). An operand can be held in any of these places:

- In the instruction itself (an immediate operand).
- In a register (in the case of 32-bit operands, EAX, EBX, ECX, EDX, ESI, EDI, ESP, or EBP; in the case of 16-bit operands AX, BX, CX, DX, SI, DI, SP, or BP; in the case of 8-bit operands AH, AL, BH, BL, CH, CL, DH, or DL; the segment registers; or the EFLAGS register for flag operations). Use of 16-bit register operands requires use of the 16-bit operand size prefix if the current default operand size is 32 bits. (See Chapter 11 for information on setting the D-bit in the code segment descriptor to control default operand size.)
- In memory.
- At an I/O port. See Chapter 15 for information on I/O.

Register and immediate operands are available on-chip—the latter because they are prefetched as part of interpreting the instruction. Memory operands residing in the on-chip cache can be accessed just as fast for most instructions.

Of the instructions which have operands, some specify operands implicitly; others specify operands explicitly; still others use a combination of both. For example:

Implicit operand: `AAM`

By definition, AAM (ASCII adjust for multiplication) operates on the contents of the AX register.

Explicit operand: `XCHG EAX, EBX`

The operands to be exchanged are encoded in the instruction with the opcode.

Implicit and explicit operands: `PUSH COUNTER`

The memory variable COUNTER (the explicit operand) is copied to the top of the stack (the implicit operand).

Note that most instructions have implicit operands. All arithmetic instructions, for example, update the EFLAGS register.

An instruction can *explicitly* reference one or two operands. Two-operand instructions, such as MOV, ADD, and XOR, generally overwrite one of the two participating operands with the

result. This is one difference between the *source operand* (the one unaffected by the operation) and the *destination operand* (the one overwritten by the result).

For most instructions, one of the two explicitly specified operands—either the source or the destination—can be either in a register or in memory. The other operand must be in a register or it must be an immediate source operand. This puts the explicit two-operand instructions into the following groups:

- Register to register
- Register to memory
- Memory to register
- Immediate to register
- Immediate to memory

Certain string instructions and stack manipulation instructions, however, transfer data from memory to memory. Both operands of some string instructions are in memory and are specified implicitly. Push and pop stack operations allow transfer between memory operands and the memory-based stack.

Several three-operand instructions are provided, such as the `IMUL`, `SHRD`, and `SHLD` instructions. Two of the three operands are specified explicitly, as for the two-operand instructions, while a third is taken from the `CL` register or supplied as an immediate. Other three-operand instructions, such as the string instructions when used with a repeat prefix, take all their operands from registers.

### 3.5.1. Immediate Operands

Certain instructions use data from the instruction itself as one (and sometimes two) of the operands. Such an operand is called an *immediate* operand. It can be a byte, word, or doubleword. For example:

```
SHR PATTERN, 2
```

One byte of the instruction holds the value 2, the number of bits by which to shift the variable `PATTERN`.

```
TEST PATTERN, 0FFFF00FH
```

A doubleword of the instruction holds the mask which is used to test the variable `PATTERN`.

```
IMUL CX, MEMWORD, 3
```

A word in memory is multiplied by an immediate 3 and stored into the `CX` register.

All arithmetic instructions (except divide) allow the source operand to be an immediate value. When the destination is the `EAX` or `AL` register, the instruction encoding is one byte shorter than with the other general registers.



### 3.5.2. Register Operands

Operands can be located in one of the 32-bit general registers (EAX, EBX, ECX, EDX, ESI, EDI, ESP, or EBP), in one of the 16-bit general registers (AX, BX, CX, DX, SI, DI, SP, or BP), or in one of the 8-bit general registers (AH, BH, CH, DH, AL, BL, CL, or DL). Sixty-four bit operands are also used in 32-bit register pairs for operations such as DIV and MUL. Register pairs are represented with a colon separating them. For example, in the register pair EDX:EAX, EDX contains the high order bits and EAX contains the low order bits of the 64-bit operand.

The Pentium processor has instructions for referencing the segment registers (CS, DS, ES, SS, FS, and GS). These instructions are used by application programs only if system designers have chosen a segmented memory model.

The Pentium processor also has instructions for changing the state of individual flags in the EFLAGS register. Instructions have been provided for setting and clearing flags which often need to be accessed. The other flags, which are not accessed so often, can be changed by pushing the contents of the EFLAGS register on the stack, making changes to it while it's on the stack, and popping it back into the register.

### 3.5.3. Memory Operands

Instructions with explicit operands in memory must reference the segment containing the operand and the offset from the beginning of the segment to the operand. Segments are specified using a segment-override prefix, which is a byte placed at the beginning of an instruction. If no segment is specified, simple rules assign the segment by default. The offset is specified in one of the following ways:

1. Most instructions which access memory contain a byte for specifying the addressing method of the operand. The byte, called the *modR/M* byte, comes after the opcode and specifies whether the operand is in a register or in memory. If the operand is in memory, the address is calculated from a segment register and any of the following values: a base register, an index register, a scaling factor, and a displacement. When an index register is used, the *modR/M* byte also is followed by another byte to specify the index register and scaling factor. This form of addressing is the most flexible.
2. A few instructions use implied address modes:

A MOV instruction with the AL, AX, or EAX register as either source or destination can address memory with a doubleword encoded in the instruction. This special form of the MOV instruction allows no base register, index register, or scaling factor to be used. This form is one byte shorter than the general-purpose form.

String operations address memory in the DS segment using the ESI register, (the MOVS, CMPS, OUTS, and LODS instructions) or using the ES segment and EDI register (the MOVS, CMPS, INS, SCAS, and STOS instructions).

Stack operations address memory in the SS segment using the ESP register (the PUSH, POP, PUSHA, PUSHAD, POPA, POPAD, PUSHF, PUSHFD, POPF, POPFD, CALL, LEAVE, ENTER, INT, RET, IRET, and IRETD instructions, exceptions, and interrupts).

### 3.5.3.1. SEGMENT SELECTION

Explicit specification of a segment is optional. If a segment is not specified using a segment-override prefix, the processor automatically chooses a segment according to the rules of Table 3-3.

**Table 3-3. Default Segment Selection Rules**

Type of Reference	Segment Used Register Used	Default Selection Rule
Instructions	Code Segment CS register	Automatic with instruction fetch.
Stack	Stack Segment SS register	All stack pushes and pops. Any memory reference which uses ESP or EBP as a base register.
Local Data	Data Segment DS register	All data references except when relative to stack or string destination.
Destination Strings	E-Space Segment ES register	Destination of string instructions.

Different kinds of memory access have different default segments. Data operands usually use the main data segment (the DS segment). However, the ESP and EBP registers are used for addressing the stack, so when either register is used, the stack segment (the SS segment) is selected.

Segment-override prefixes are provided for each of the segment registers. Only the following special cases have a default segment selection which is not affected by a segment-override prefix:

- Destination strings in string instructions use the ES segment
- Destination of a push or source of a pop uses the SS segment
- Instruction fetches use the CS segment

### 3.5.3.2. EFFECTIVE-ADDRESS COMPUTATION

The modR/M byte provides the most flexible form of addressing. Instructions which have a modR/M byte after the opcode are the most common in the instruction set. For memory operands specified by a modR/M byte, the offset within the selected segment is the sum of four components:

- A displacement
- A base register
- An index register
- A scaling factor (the index register can be multiplied by a factor of 2, 4, or 8)

The offset which results from adding these components is called an *effective address*. Each of these components can have either a positive or negative value, with the exception of the scaling factor. Figure 3-10 illustrates the full set of possibilities for modR/M addressing.

The displacement component, because it is encoded in the instruction, is useful for relative addressing by fixed amounts, such as:

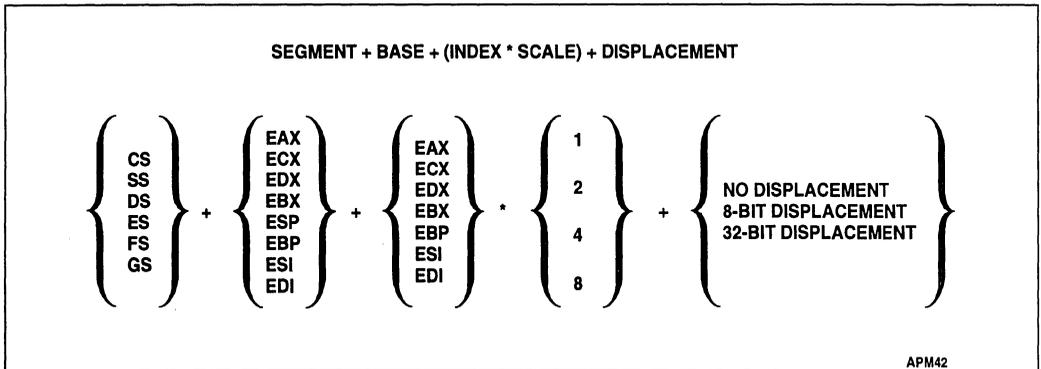
- Location of simple scalar operands.
- Beginning of a statically allocated array.
- Offset to a field within a record.

The base and index components have similar functions. Both use the same set of general registers. Both can be used for addressing which changes during program execution, such as:

- Location of procedure parameters and local variables on the stack.
- The beginning of one record among several occurrences of the same record type or in an array of records.
- The beginning of one dimension of multiple dimension array.
- The beginning of a dynamically allocated array.

The uses of general registers as base or index components differ in the following respects:

- The ESP register cannot be used as an index register.
- When the ESP or EBP register is used as the base, the SS segment is the default selection. In all other cases, the DS segment is the default selection.



**Figure 3-10. Effective Address Computation**

The scaling factor permits efficient indexing into an array when the array elements are 2, 4, or 8 bytes. The scaling of the index register is done in hardware at the time the address is evaluated. This eliminates an extra shift or multiply instruction.

The base, index, and displacement components can be used in any combination; any of these components can be null. A scale factor can be used only when an index also is used. Each possible combination is useful for data structures commonly used by programmers in high-level languages and assembly language. Suggested uses for some combinations of address components are described below.

## DISPLACEMENT

The displacement alone indicates the offset of the operand. This form of addressing is used to access a statically allocated scalar operand. A byte, word, or doubleword displacement can be used.

## BASE

The offset to the operand is specified indirectly in one of the general registers, as for "based" variables.

## BASE + DISPLACEMENT

A register and a displacement can be used together for two distinct purposes:

1. Index into an array when the element size is not 2, 4, or 8 bytes. The displacement component encodes the offset of the beginning of the array. The register holds the results of a calculation to determine the offset to a specific element within the array.
2. Access a field of a record. The base register holds the address of the beginning of the record, while the displacement is an offset to the field.

An important special case of this combination is access to parameters in a procedure activation record. A procedure activation record is the stack frame created when a subroutine is entered. In this case, the EBP register is the best choice for the base register, because it automatically selects the stack segment. This is a compact encoding for this common function.

## (INDEX \* SCALE) + DISPLACEMENT

This combination is an efficient way to index into a static array when the element size is 2, 4, or 8 bytes. The displacement addresses the beginning of the array, the index register holds the subscript of the desired array element, and the processor automatically converts the subscript into an index by applying the scaling factor.

## BASE + INDEX + DISPLACEMENT

Two registers used together support either a two-dimensional array (the displacement holds the address of the beginning of the array) or one of several instances of an array of records (the displacement is an offset to a field within the record).

## BASE + (INDEX \* SCALE) + DISPLACEMENT

This combination provides efficient indexing of a two-dimensional array when the elements of the array are 2, 4, or 8 bytes in size.



### 3.6. INTERRUPTS AND EXCEPTIONS

The processor has two mechanisms for interrupting program execution:

1. *Exceptions* are synchronous events which are responses of the processor to certain conditions detected during the execution of an instruction.
2. *Interrupts* are asynchronous events typically triggered by external devices needing attention.

Interrupts and exceptions are alike in that both cause the processor to temporarily suspend the program being run in order to run a program of higher priority. The major distinction between these two kinds of interrupts is their origin. An exception is always reproducible by re-executing the program which caused the exception, while an interrupt can have a complex, timing-dependent relationship with programs.

Application programmers normally are not concerned with handling exceptions or interrupts. The operating system, monitor, or device driver handles them. More information on interrupts for system programmers can be found in Chapter 14. Certain kinds of exceptions, however, are relevant to application programming, and many operating systems give application programs the opportunity to service these exceptions. However, the operating system defines the interface between the application program and the exception mechanism of the processor. Table 3-4 lists the interrupts and exceptions.

- A divide-error exception results when the DIV or IDIV instruction is executed with a zero denominator or when the quotient is too large for the destination operand. (See Chapter 3 for more information on the DIV and IDIV instructions.)
- A debug exception can be sent back to an application program if it results from the TF (trap) flag.
- A breakpoint exception results when an INT3 instruction is executed. This instruction is used by some debuggers to stop program execution at specific points.
- An overflow exception results when the INTO instruction is executed and the OF (overflow) flag is set. See Chapter 3 for a discussion of the INTO instruction.
- A bounds-check exception results when the BOUND instruction is executed with an array index which falls outside the bounds of the array. See Chapter 3 for a discussion of the BOUND instruction.
- The device-not-available exception occurs whenever the processor encounters an escape instruction and either the TS (task switched) or the EM (emulate coprocessor) bit of the CR0 control register is set.
- An alignment-check exception is generated for unaligned memory operations in user mode (privilege level 3), provided both AM and AC are set. Memory operations at supervisor mode (privilege levels 0, 1, and 2), or memory operations which default to supervisor mode, do not generate this exception.

The INT instruction generates an interrupt whenever it is executed; the processor treats this interrupt as an exception. Its effects (and the effects of all other exceptions) are determined

by exception handler routines in the application program or the operating system. The INT instruction itself is discussed in Chapter 25. See Chapter 14 for a more complete description of exceptions.

**Table 3-4. Exceptions and Interrupts**

Vector Number	Description
0	Divide Error
1	Debugger Call
2	NMI Interrupt
3	Breakpoint
4	INTO-detected Overflow
5	BOUND Range Exceeded
6	Invalid Opcode
7	Device Not Available
8	Double Fault
9	(Intel reserved. Do not use. Not used by Pentium® processor.)
10	Invalid Task State Segment
11	Segment Not Present
12	Stack Exception
13	General Protection
14	Page Fault
15	(Intel reserved. Do not use.)
16	Floating-Point Error
17	Alignment Check
18	Machine Check Exception
19-31	(Intel reserved. Do not use.)
32-255	Maskable Interrupts

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**4**

**Application  
Programming**





# CHAPTER 4

## APPLICATION PROGRAMMING

This chapter is an overview of the integer instructions which programmers can use to write application software for the Pentium processor. The instructions are grouped by categories of related functions. Additional application instructions for operating on floating-point operands are described in Chapter 6.

The instructions not discussed in this chapter or Chapter 6 normally are used only by operating-system programmers. System-level instructions are discussed in Part II.

The instruction set descriptions in Chapter 25 contain more detailed information on all instructions, including encoding, operation, timing, effect on flags, and exceptions which may be generated.

For information on the introduction of new instructions which may not be supported on earlier versions of Intel architecture, see Chapter 23.

### 4.1. DATA MOVEMENT INSTRUCTIONS

These instructions provide convenient methods for moving bytes, words, doublewords, or quadwords between memory and the processor registers. They come in three types:

1. General-purpose data movement instructions.
2. Stack manipulation instructions.
3. Type-conversion instructions.

#### 4.1.1. General-Purpose Data Movement Instructions

**MOV (Move)** transfers a byte, word, or doubleword from the source operand to the destination operand. The **MOV** instruction is useful for transferring data along any of these paths:

- To a register from memory.
- To memory from a register.
- Between general registers.
- Immediate data to a register.
- Immediate data to memory.

The **MOV** instruction cannot move from memory to memory or from a segment register to a segment register. Memory-to-memory moves can be performed, however, by the string move

instruction **MOVS**. A special form of the **MOV** instruction is provided for transferring data between the **AL**, **AX**, or **EAX** registers and a location in memory specified by a 32-bit offset encoded in the instruction. This form of the instruction does not allow a segment override, index register, or scaling factor to be used. The encoding of this form is one byte shorter than the encoding of the general-purpose **MOV** instruction. A similar encoding is provided for moving an 8-, 16-, or 32-bit immediate into any of the general registers.

**XCHG (Exchange)** swaps the contents of two operands. This instruction takes the place of three **MOV** instructions. It does not require a temporary location to save the contents of one operand while the other is being loaded. The **XCHG** instruction is especially useful for implementing semaphores or similar data structures for process synchronization.

The **XCHG** instruction can swap two byte operands, two word operands, or two doubleword operands. The operands for the **XCHG** instruction may be two register operands, or a register operand and a memory operand. When used with a memory operand, **XCHG** automatically activates the **LOCK** signal. (See Chapter 16 for more information on bus locking.)

#### 4.1.2. Stack Manipulation Instructions

**PUSH (Push)** decrements the stack pointer (**ESP** register), then copies the source operand to the top of stack (see Figure 4-1). The **PUSH** instruction often is used to place parameters on the stack before calling a procedure. Inside a procedure, it can be used to reserve space on the stack for temporary variables. The **PUSH** instruction operates on memory operands, immediate operands, and register operands (including segment registers). A special form of the **PUSH** instruction is available for pushing a 32-bit general register on the stack. This form has an encoding which is one byte shorter than the general-purpose form.

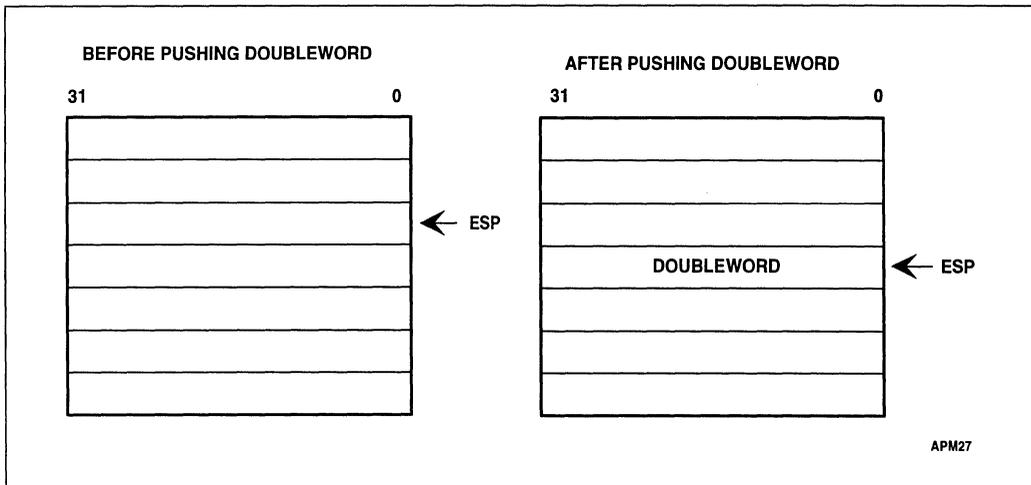


Figure 4-1. **PUSH** Instruction



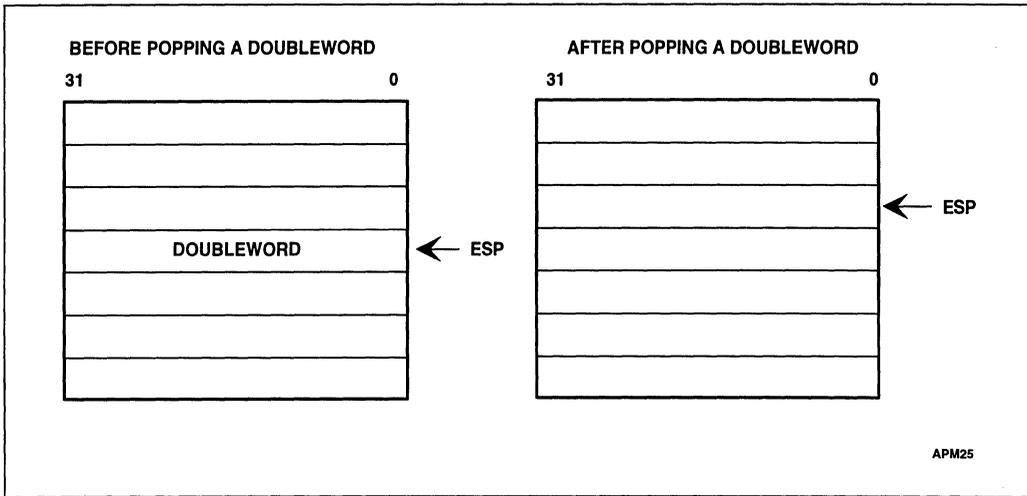


Figure 4-3. POP Instruction

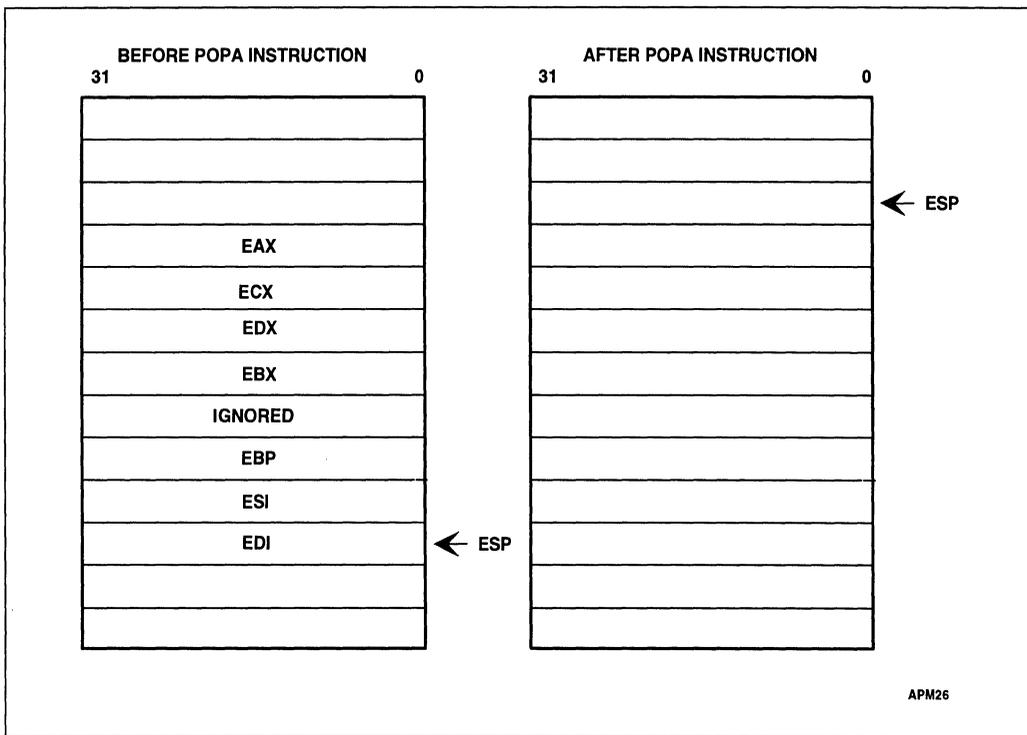


Figure 4-4. POPA Instruction



### 4.1.3. Type Conversion Instructions

The type conversion instructions convert bytes into words, words into doublewords, and doublewords into 64-bit quantities (called quadwords). These instructions are especially useful for converting signed integers, because they automatically fill the extra bits of the larger item with the value of the sign bit of the smaller item. This results in an integer of the same sign and magnitude, but a larger format. This kind of conversion, shown in Figure 4-5, is called sign extension.

There are two kinds of type conversion instructions:

- The CWD, CDQ, CBW, and CWDE instructions which only operate on data in the EAX register.
- The MOVSX and MOVZX instructions, which permit one operand to be in a general register while letting the other operand be in memory or a register.

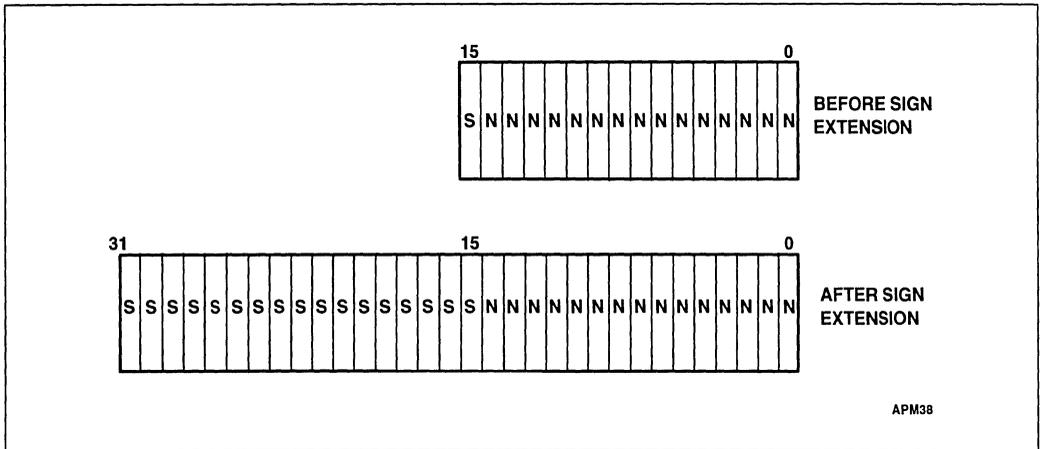


Figure 4-5. Sign Extension

**CWD (Convert Word to Doubleword)** and **CDQ (Convert Doubleword to Quad-Word)** double the size of the source operand. The CWD instruction copies the sign (bit 15) of the word in the AX register into every bit position in the DX register. The CDQ instruction copies the sign (bit 31) of the doubleword in the EAX register into every bit position in the EDX register. The CWD instruction can be used to produce a doubleword dividend from a word before a word division, and the CDQ instruction can be used to produce a quadword dividend from a doubleword before doubleword division. The CWD and CDQ instructions are different mnemonics for the same opcode. Which one gets executed is determined by whether it is in a 16- or 32-bit segment and the presence of any operand-size override prefixes. See Chapter 25 for a detailed description of these instructions.

**CBW (Convert Byte to Word)** copies the sign (bit 7) of the byte in the AL register into every bit position of the upper byte of the AX register.

**CWDE (Convert Word to Doubleword Extended)** copies the sign (bit 15) of the word in the AX register into every bit position of the high word of the EAX register.

**MOVSX (Move with Sign Extension)** extends an 8-bit value to a 16-bit value or an 8- or 16-bit value to 32-bit value by using the value of the sign to fill empty positions.

**MOVZX (Move with Zero Extension)** extends an 8-bit value to a 16-bit value or an 8- or 16-bit value to 32-bit value by clearing the empty bit positions.

## 4.2. BINARY ARITHMETIC INSTRUCTIONS

The arithmetic instructions operate on numeric data encoded in binary. Operations include the add, subtract, multiply, and divide as well as increment, decrement, compare, and change sign (negate). Both signed and unsigned binary integers are supported. The binary arithmetic instructions may also be used as steps in arithmetic on decimal integers. Source operands can be immediate values, general registers, or memory. Destination operands can be general registers or memory (except when the source operand is in memory). The basic arithmetic instructions have special forms for using an immediate value as the source operand and the AL, AX, or EAX registers as the destination operand. These forms are one byte shorter than the general-purpose arithmetic instructions.

The arithmetic instructions update the ZF, CF, SF, and OF flags to report the kind of result which was produced. The kind of instruction used to test the flags depends on whether the data is being interpreted as signed or unsigned. The CF flag contains information relevant to unsigned integers; the SF and OF flags contain information relevant to signed integers. The ZF flag is relevant to both signed and unsigned integers; the ZF flag is set when all bits of the result are clear.

Arithmetic instructions operate on 8-, 16-, or 32-bit data. The flags are updated to reflect the size of the operation. For example, an 8-bit ADD instruction sets the CF flag if the sum of the operands exceeds 255 (decimal).

If the integer is unsigned, the CF flag may be tested after one of these arithmetic operations to determine whether the operation required a carry or borrow to be propagated to the next stage of the operation. The CF flag is set if a carry occurs (addition instructions ADD, ADC, AAA, and DAA) or borrow occurs (subtraction instructions SUB, SBB, AAS, DAS, CMP, and NEG).

The INC and DEC instructions do not change the state of the CF flag. This allows the instructions to be used to update counters used for loop control without changing the reported state of arithmetic results. To test the arithmetic state of the counter, the ZF flag can be tested to detect loop termination, or the ADD and SUB instructions can be used to update the value held by the counter.

The SF and OF flags support signed integer arithmetic. The SF flag has the value of the sign bit of the result. The most significant bit (MSB) of the magnitude of a signed integer is the bit next to the sign—bit 6 of a byte, bit 14 of a word, or bit 30 of a doubleword. The OF flag is set in either of these cases:



- A carry was generated from the MSB into the sign bit but no carry was generated out of the sign bit (addition instructions ADD, ADC, INC, AAA, and DAA). In other words, the result was greater than the greatest positive number which could be represented in two's complement form.
- A carry was generated from the sign bit into the MSB but no carry was generated into the sign bit (subtraction instructions SUB, SBB, DEC, AAS, DAS, CMP, and NEG). In other words, the result was smaller than the smallest negative number which could be represented in two's complement form.

These status flags are tested by either kind of conditional instruction: Jcc (jump on condition cc) or SETcc (byte set on condition).

### 4.2.1. Addition and Subtraction Instructions

**ADD (Add Integers)** replaces the destination operand with the sum of the source and destination operands. The OF, SF, ZF, AF, PF, and CF flags are affected.

**ADC (Add Integers with Carry)** replaces the destination operand with the sum of the source and destination operands, plus 1 if the CF flag is set. If the CF flag is clear, the ADC instruction performs the same operation as the ADD instruction. An ADC instruction is used to propagate carry when adding numbers in stages, for example when using 32-bit ADD instructions to sum quadword operands. The OF, SF, ZF, AF, PF, and CF flags are affected.

**INC (Increment)** adds 1 to the destination operand. The INC instruction preserves the state of the CF flag. This allows the use of INC instructions to update counters in loops without disturbing the status flags resulting from an arithmetic operation used for loop control. The ZF flag can be used to detect when carry would have occurred. Use an ADD instruction with an immediate value of 1 to perform an increment which updates the CF flag. A one-byte form of this instruction is available when the operand is a general register. The OF, SF, ZF, AF, and PF flags are affected.

**SUB (Subtract Integers)** subtracts the source operand from the destination operand and replaces the destination operand with the result. If a borrow is required, the CF flag is set. The operands may be signed or unsigned bytes, words, or doublewords. The OF, SF, ZF, AF, PF, and CF flags are affected.

**SBB (Subtract Integers with Borrow)** subtracts the source operand from the destination operand and replaces the destination operand with the result, minus 1 if the CF flag is set. If the CF flag is clear, the SBB instruction performs the same operation as the SUB instruction. An SBB instruction is used to propagate borrow when subtracting numbers in stages, for example when using 32-bit SUB instructions to subtract one quadword operand from another. The OF, SF, ZF, AF, PF, and CF flags are affected.

**DEC (Decrement)** subtracts 1 from the destination operand. The DEC instruction preserves the state of the CF flag. This allows the use of the DEC instruction to update counters in loops without disturbing the status flags resulting from an arithmetic operation used for loop control. Use a SUB instruction with an immediate value of 1 to perform a decrement which

updates the CF flag. A one-byte form of this instruction is available when the operand is a general register. The OF, SF, ZF, AF, and PF flags are affected.

## 4.2.2. Comparison and Sign Change Instruction

**CMP (Compare)** subtracts the source operand from the destination operand. It updates the OF, SF, ZF, AF, PF, and CF flags, but does not modify the source or destination operands. A subsequent *Jcc* or *SETcc* instruction can test the flags.

**NEG (Negate)** subtracts a signed integer operand from zero. The effect of the NEG instruction is to change the sign of a two's complement operand while keeping its magnitude. The OF, SF, ZF, AF, PF, and CF flags are affected.

## 4.2.3. Multiplication Instructions

The processor has separate multiply instructions for unsigned and signed operands. The MUL instruction operates on unsigned integers, while the IMUL instruction operates on signed integers as well as unsigned.

**MUL (Unsigned Integer Multiply)** performs an unsigned multiplication of the source operand and the AL, AX, or EAX register. If the source is a byte, the processor multiplies it by the value held in the AL register and returns the double-length result in the AH and AL registers. If the source operand is a word, the processor multiplies it by the value held in the AX register and returns the double-length result in the DX and AX registers. If the source operand is a doubleword, the processor multiplies it by the value held in the EAX register and returns the quadword result in the EDX and EAX registers. The MUL instruction sets the CF and OF flags when the upper half of the result is non-zero; otherwise, the flags are cleared. The state of the SF, ZF, AF, and PF flags is undefined.

**IMUL (Signed Integer Multiply)** performs a signed multiplication operation. The IMUL instruction has three forms:

1. A one-operand form. The operand may be a byte, word, or doubleword located in memory or in a general register. This instruction uses the EAX and EDX (or AX and DX) registers as implicit operands in the same way as the MUL instruction.
2. A two-operand form. One of the source operands is in a general register while the other may be in a general register or memory. The result replaces the general-register operand.
3. A three-operand form; two are source operands and one is the destination. One of the source operands is an immediate value supplied by the instruction; the second may be in memory or in a general register. The result is stored in a general register. The immediate operand is a two's complement signed integer. If the immediate operand is a byte, the processor automatically sign-extends it to the size of the second operand before performing the multiplication.

The three forms are similar in most respects:



- The length of the product is calculated to twice the length of the operands.
- The CF and OF flags are set when significant bits are carried into the upper half of the result. The CF and OF flags are cleared when the upper half of the result is the sign-extension of the lower half. The state of the SF, ZF, AF, and PF flags is undefined.

However, forms 2 and 3 differ from 1 because the product is truncated to the length of the operands before it is stored in the destination register. Because of this truncation, the OF flag should be tested to ensure that no significant bits are lost. (For ways to test the OF flag, see the JO, INTO, and PUSHF instructions.)

Forms 2 and 3 of IMUL also may be used with unsigned operands because, whether the operands are signed or unsigned, the lower half of the product is the same. The CF and OF flags, however, cannot be used to determine if the upper half of the result is non-zero.

#### 4.2.4. Division Instructions

The Pentium processor has separate division instructions for unsigned and signed operands. The DIV instruction operates on unsigned integers, while the IDIV instruction operates on both signed and unsigned integers. In either case, a divide-error exception is generated if the divisor is zero or if the quotient is too large for the AL, AX, or EAX register.

**DIV (Unsigned Integer Divide)** performs an unsigned division of the AL, AX, or EAX register by the source operand. The dividend (the accumulator) is twice the size of the divisor (the source operand); the quotient and remainder have the same size as the divisor, as shown in Table 4-1.

Non-integral results are truncated toward 0. The remainder is always smaller than the divisor. For unsigned byte division, the largest quotient is 255. For unsigned word division, the largest quotient is 65,535. For unsigned doubleword division the largest quotient is  $2^{32}-1$ . The state of the OF, SF, ZF, AF, PF, and CF flags is undefined.

**IDIV (Signed Integer Divide)** performs a signed division of the accumulator by the source operand. The IDIV instruction uses the same registers as the DIV instruction.

For signed byte division, the maximum positive quotient is +127, and the minimum negative quotient is -128. For signed word division, the maximum positive quotient is +32,767, and the minimum negative quotient is -32,768. For signed doubleword division the maximum positive quotient is  $2^{31}-1$ , the minimum negative quotient is  $-2^{31}$ . Non-integral results are truncated towards 0. The remainder always has the same sign as the dividend and is less than the divisor in magnitude. The state of the OF, SF, ZF, AF, PF, and CF flags is undefined.

Table 4-1. Operands for Division

Operand Size (Divisor)	Dividend	Quotient	Remainder
Byte	AX register	AL register	AH register
Word	DX and AX	AX register	DX register
Doubleword	EDX and EAX	EAX register	EDX register

### 4.3. DECIMAL ARITHMETIC INSTRUCTIONS

Decimal arithmetic is performed by combining the binary arithmetic instructions (already discussed in the prior section) with the decimal arithmetic instructions. The decimal arithmetic instructions are used in one of the following ways:

- To adjust the results of a previous binary arithmetic operation to produce a valid packed or unpacked decimal result.
- To adjust the inputs to a subsequent binary arithmetic operation so that the operation will produce a valid packed or unpacked decimal result.

These instructions operate only on the AL or AH registers. Most use the AF flag.

#### 4.3.1. Packed BCD Adjustment Instructions

**DAA (Decimal Adjust after Addition)** adjusts the result of adding two valid packed decimal operands in the AL register. A DAA instruction must follow the addition of two pairs of packed decimal numbers (one digit in each half-byte) to obtain a pair of valid packed decimal digits as results. The CF flag is set if a carry occurs. The SF, ZF, AF, PF, and CF flags are affected. The state of the OF flag is undefined.

**DAS (Decimal Adjust after Subtraction)** adjusts the result of subtracting two valid packed decimal operands in the AL register. A DAS instruction must always follow the subtraction of one pair of packed decimal numbers (one digit in each half-byte) from another to obtain a pair of valid packed decimal digits as results. The CF flag is set if a borrow is needed. The SF, ZF, AF, PF, and CF flags are affected. The state of the OF flag is undefined.

#### 4.3.2. Unpacked BCD Adjustment Instructions

**AAA (ASCII Adjust after Addition)** changes the contents of the AL register to a valid unpacked decimal number, and clears the upper 4 bits. An AAA instruction must follow the addition of two unpacked decimal operands in the AL register. The CF flag is set and the contents of the AH register are incremented if a carry occurs. The AF and CF flags are affected. The state of the OF, SF, ZF, and PF flags is undefined.

**AAS (ASCII Adjust after Subtraction)** changes the contents of the AL register to a valid unpacked decimal number, and clears the upper 4 bits. An AAS instruction must follow the subtraction of one unpacked decimal operand from another in the AL register. The CF flag is set and the contents of the AH register are decremented if a borrow is needed. The AF and CF flags are affected. The state of the OF, SF, ZF, and PF flags is undefined.

**AAM (ASCII Adjust after Multiplication)** corrects the result of a multiplication of two valid unpacked decimal numbers. An AAM instruction must follow the multiplication of two decimal numbers to produce a valid decimal result. The upper digit is left in the AH register, the lower digit in the AL register. The SF, ZF, and PF flags are affected. The state of the AF, OF, and CF flags is undefined.

**AAD (ASCII Adjust before Division)** modifies the numerator in the AH and AL registers to prepare for the division of two valid unpacked decimal operands, so that the quotient produced by the division will be a valid unpacked decimal number. The AH register should contain the upper digit and the AL register should contain the lower digit. This instruction adjusts the value and places the result in the AL register. The AH register will be clear. The SF, ZF, and PF flags are affected. The state of the AF, OF, and CF flags is undefined.

## 4.4. LOGICAL INSTRUCTIONS

The logical instructions have two operands. Source operands can be immediate values, general registers, or memory. Destination operands can be general registers or memory (except when the source operand is in memory). The logical instructions modify the state of the flags. Short forms of the instructions are available when an immediate source operand is applied to a destination operand in the AL, AX, or EAX registers. The group of logical instructions includes:

- Boolean operation instructions.
- Bit test and modify instructions.
- Bit scan instructions.
- Rotate and shift instructions.
- Byte set on condition.

### 4.4.1. Boolean Operation Instructions

The logical operations are performed by the AND, OR, XOR, and NOT instructions.

**NOT (Not)** inverts the bits in the specified operand to form a one's complement of the operand. The NOT instruction is a unary operation which uses a single operand in a register or memory. NOT has no effect on the flags.

The AND, OR, and XOR instructions perform the standard logical operations "and," "or," and "exclusive or." These instructions can use the following combinations of operands:

- Two register operands.
- A general register operand with a memory operand.
- An immediate operand with either a general register operand or a memory operand.

The AND, OR, and XOR instructions clear the OF and CF flags, leave the AF flag undefined, and update the SF, ZF, and PF flags.

### 4.4.2. Bit Test and Modify Instructions

This group of instructions operates on a single bit which can be in memory or in a general register. The location of the bit is specified as an offset from the low end of the operand. The value of the offset either may be given by an immediate byte in the instruction or may be contained in a general register.

These instructions first assign the value of the selected bit to the CF flag. Then a new value is assigned to the selected bit, as determined by the operation. The state of the OF, SF, ZF, AF, and PF flags is undefined. Table 4-2 defines these instructions.

**Table 4-2. Bit Test and Modify Instructions**

Instruction	Effect on CF Flag	Effect on Selected Bit
BT (Bit Test)	CF flag ← Selected Bit	No effect
BTS (Bit Test and Set)	CF flag ← Selected Bit	Selected Bit ← 1
BTR (Bit Test and Reset)	CF flag ← Selected Bit	Selected Bit ← 0
BTC (Bit Test and Complement)	CF flag ← Selected Bit	Selected Bit ← – (Selected Bit)

### 4.4.3. Bit Scan Instructions

These instructions scan a word or doubleword for a set bit and store the bit index (an integer representing the bit position) of the first set bit into a register. The bit string being scanned may be in a register or in memory. The ZF flag is set if the entire word is clear, otherwise the ZF flag is cleared. In the former case, the value of the destination register is left undefined. The state of the OF, SF, AF, PF, and CF flags is undefined.

**BSF (Bit Scan Forward)** scans low-to-high (from bit 0 toward the upper bit positions).

**BSR (Bit Scan Reverse)** scans high-to-low (from the uppermost bit toward bit 0).

#### 4.4.4. Shift and Rotate Instructions

The shift and rotate instructions rearrange the bits within an operand.

These instructions fall into the following classes:

- Shift instructions.
- Double shift instructions.
- Rotate instructions.

##### 4.4.4.1. SHIFT INSTRUCTIONS

Shift instructions apply an arithmetic or logical shift to bytes, words, and doublewords. An arithmetic shift right copies the sign bit into empty bit positions on the upper end of the operand, while a logical shift right fills high order empty bit positions with zeros. An arithmetic shift is a fast way to perform a simple calculation. For example, an arithmetic shift right by one bit position divides an integer by two. A logical shift right divides an unsigned integer or a positive integer, but a signed negative integer loses its sign bit.

The arithmetic and logical shift right instructions, SAR and SHR, differ only in their treatment of the bit positions emptied by shifting the contents of the operand. Note that there is no difference between an arithmetic shift left and a logical shift left. Two names, SAL and SHL, are supported for this instruction in the assembler.

A count specifies the number of bit positions to shift an operand. Bits can be shifted up to 31 places. A shift instruction can give the count in any of three ways. One form of shift instruction always shifts by one bit position. The second form gives the count as an immediate operand. The third form gives the count as the value contained in the CL register. This last form allows the count to be a result from a calculation. Only the low five bits of the CL register are used.

When the number of bit positions to shift is zero, no flags are affected. Otherwise, the CF flag is left with the value of the last bit shifted out of the operand. In a single-bit shift, the OF flag is set if the value of the uppermost bit (sign bit) was changed by the operation. Otherwise, the OF flag is cleared. After a shift of more than one bit position, the state of the OF flag is undefined. On a shift of one or more bit positions, the SF, ZF, PF, and CF flags are affected. On a shift of one or more bit positions the state of the AF flag is undefined. If the count length is greater than or equal to the size of the operand, the value of the CF flag is undefined.

**SAL (Shift Arithmetic Left)** shifts the destination byte, word, or doubleword operand left by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register). Empty bit positions are cleared. See Figure 4-6.

**SHL (Shift Logical Left)** is another name for the SAL instruction. It is supported in the assembler.

**SHR (Shift Logical Right)** shifts the destination byte, word, or doubleword operand right by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register). Empty bit positions are cleared. See Figure 4-7.

**SAR (Shift Arithmetic Right)** shifts the destination byte, word, or doubleword operand to the right by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register). The sign of the operand is preserved by clearing empty bit positions if the operand is positive, or setting the empty bits if the operand is negative. See Figure 4-8.

Even though this instruction can be used to divide integers by an integer power of two, **the type of division is not the same as that produced by the IDIV instruction**. The quotient from the IDIV instruction is rounded toward zero, whereas the "quotient" of the SAR instruction is rounded toward negative infinity. This difference is apparent only for negative numbers. For example, when the IDIV instruction is used to divide  $-9$  by  $4$ , the result is  $-2$  with a remainder of  $-1$ . If the SAR instruction is used to shift  $-9$  right by two bits, the result is  $-3$ . The "remainder" of this kind of division is  $+3$ ; however, the SAR instruction stores only the high-order bit of the remainder (in the CF flag).

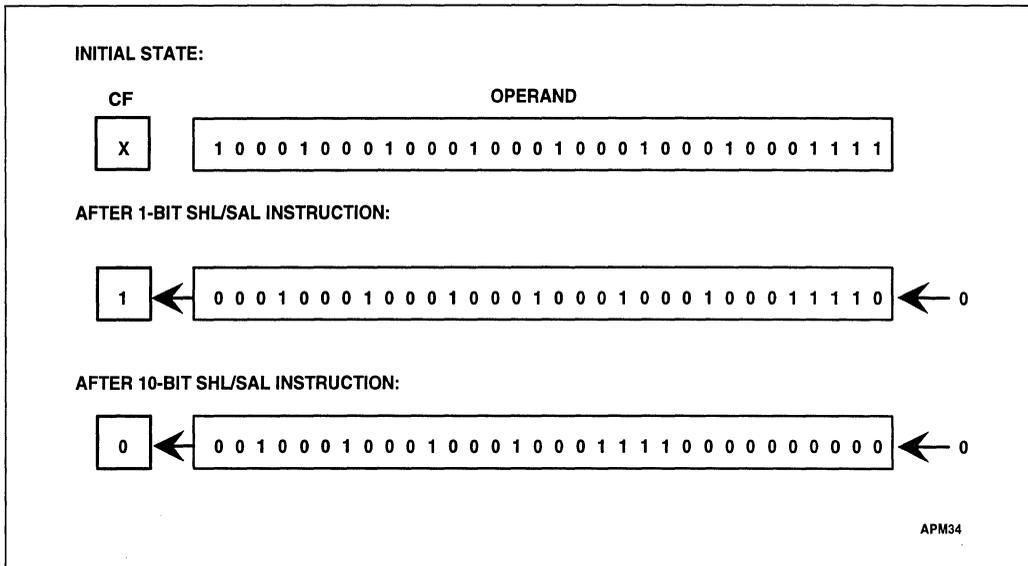


Figure 4-6. SHL/SAL Instruction

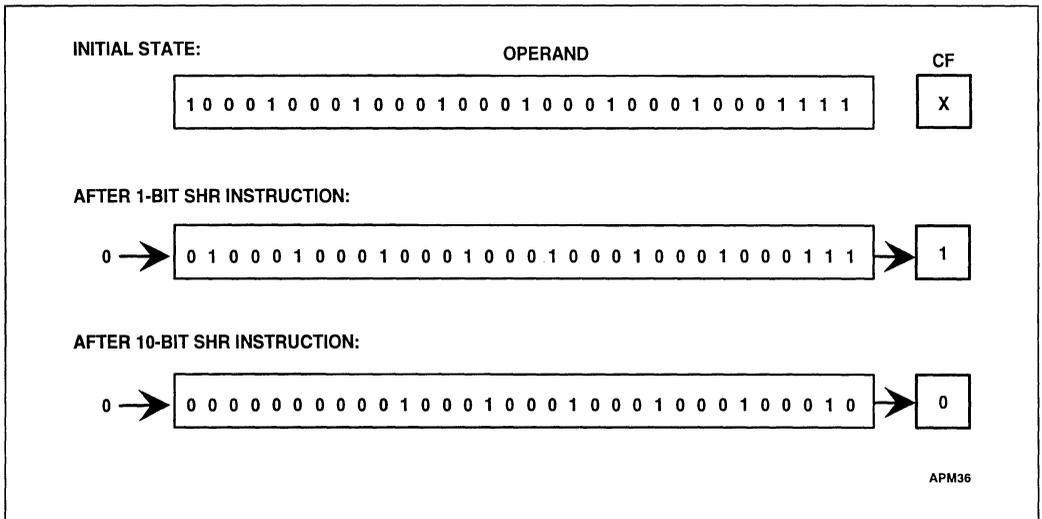


Figure 4-7. SHR Instruction

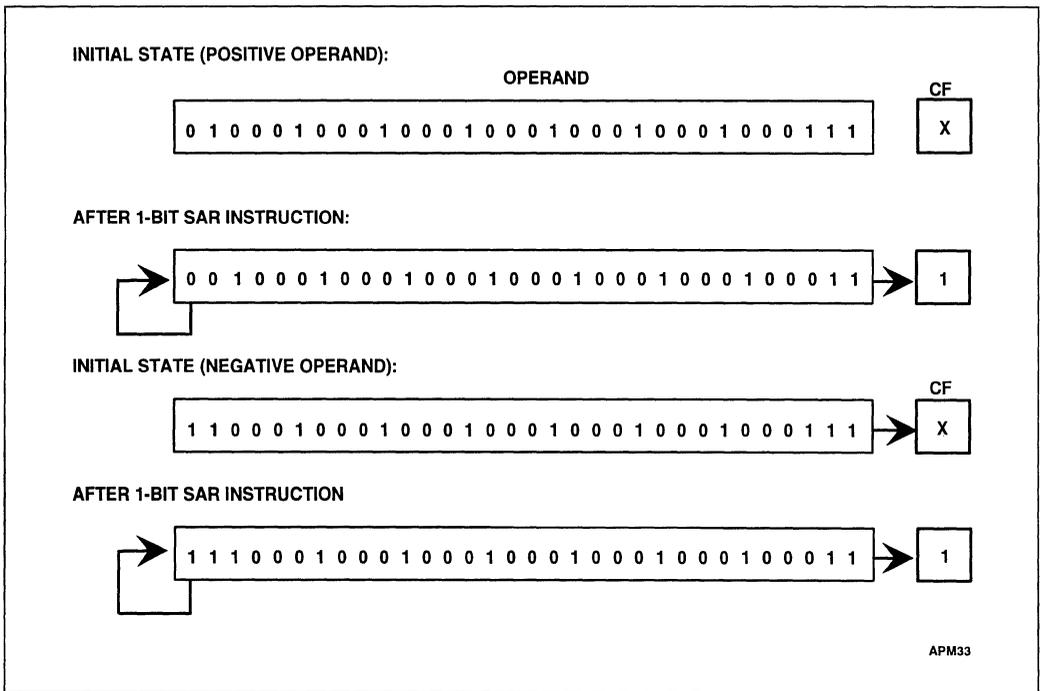


Figure 4-8. SAR Instruction

#### 4.4.4.2. DOUBLE-SHIFT INSTRUCTIONS

These instructions provide the basic operations needed to implement operations on long unaligned bit strings. The double shifts operate either on word or doubleword operands, as follows:

- Take two word operands and produce a one-word result (32-bit shift).
- Take two doubleword operands and produce a doubleword result (64-bit shift).

Of the two operands, the source operand must be in a register while the destination operand may be in a register or in memory. The number of bits to be shifted is specified either in the CL register or in an immediate byte in the instruction. Bits shifted out of the source operand fill empty bit positions in the destination operand, which also is shifted. Only the destination operand is stored.

When the number of bit positions to shift is zero, no flags are affected. Otherwise, the CF flag is set to the value of the last bit shifted out of the destination operand, and the SF, ZF, and PF flags are affected. On a shift of one bit position, the OF flag is set if the sign of the operand changed, otherwise it is cleared. For shifts of more than one bit position, the state of the OF flag is undefined. For shifts of one or more bit positions, the state of AF flag is undefined.

**SHLD (Shift Left Double)** shifts bits of the destination operand to the left, while filling empty bit positions with bits shifted out of the source operand (see Figure 4-9). The result is stored back into the destination operand. The source operand is not modified.

**SHRD (Shift Right Double)** shifts bits of the destination operand to the right, while filling empty bit positions with bits shifted out of the source operand (see Figure 4-10). The result is stored back into the destination operand. The source operand is not modified.

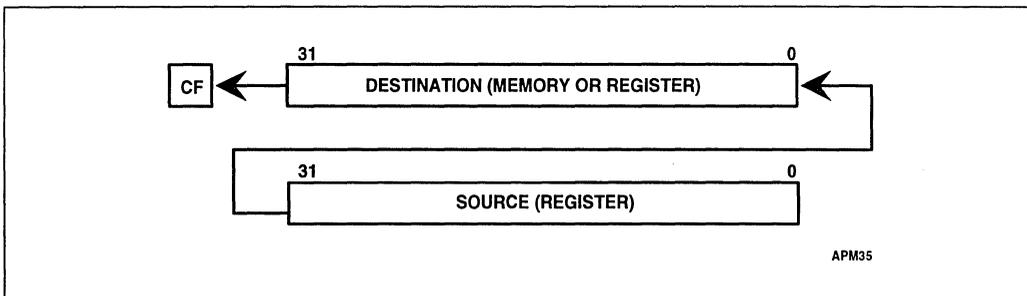


Figure 4-9. SHLD Instruction

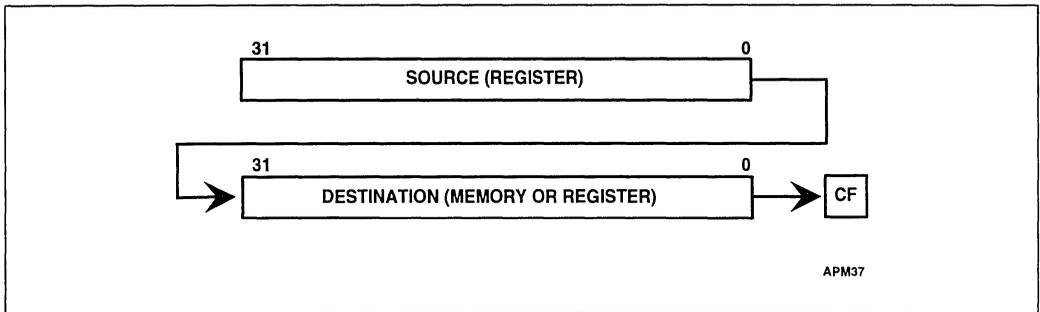


Figure 4-10. SHRD Instruction

#### 4.4.4.3. ROTATE INSTRUCTIONS

Rotate instructions apply a circular permutation to bytes, words, and doublewords. Bits rotated out of one end of an operand enter through the other end. Unlike a shift, no bits are emptied during a rotation.

Rotate instructions use only the CF and OF flags. The CF flag may act as an extension of the operand in two of the rotate instructions, allowing a bit to be isolated and then tested by a conditional jump instruction (JC or JNC). The CF flag always contains the value of the last bit rotated out of the operand, even if the instruction does not use the CF flag as an extension of the operand. The state of the SF, ZF, AF, and PF flags is not affected.

In a single-bit rotation, the OF flag is set if the operation changes the uppermost bit (sign bit) of the destination operand. If the sign bit retains its original value, the OF flag is cleared. After a rotate of more than one bit position, the value of the OF flag is undefined.

**ROL (Rotate Left)** rotates the byte, word, or doubleword destination operand left by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register). For each bit position of the rotation, the bit which exits from the left of the operand returns at the right. See Figure 4-11.

**ROR (Rotate Right)** rotates the byte, word, or doubleword destination operand right by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register). For each bit position of the rotation, the bit which exits from the right of the operand returns at the left. See Figure 4-12.

**RCL (Rotate Through Carry Left)** rotates bits in the byte, word, or doubleword destination operand left by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register).

This instruction differs from ROL in that it treats the CF flag as a one-bit extension on the upper end of the destination operand. Each bit which exits from the left side of the operand moves into the CF flag. At the same time, the bit in the CF flag enters the right side. See Figure 4-13.

**RCR (Rotate Through Carry Right)** rotates bits in the byte, word, or doubleword destination operand right by one bit position or by the number of bits specified in the count operand (an immediate value or a value contained in the CL register).

This instruction differs from ROR in that it treats CF as a one-bit extension on the lower end of the destination operand. Each bit which exits from the right side of the operand moves into the CF flag. At the same time, the bit in the CF flag enters the left side. See Figure 4-14.

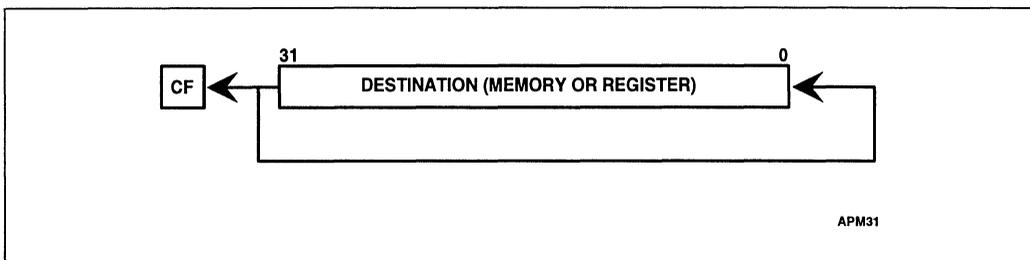


Figure 4-11. ROL Instruction

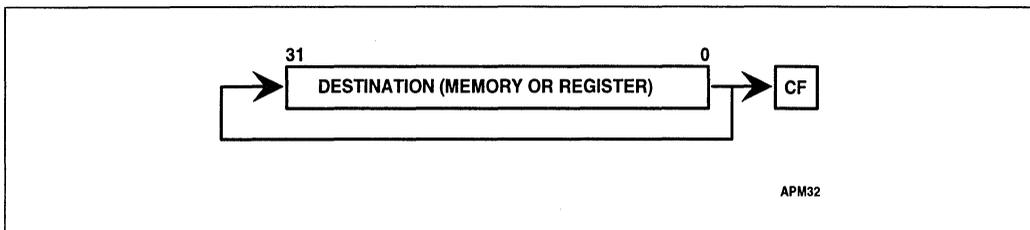


Figure 4-12. ROR Instruction

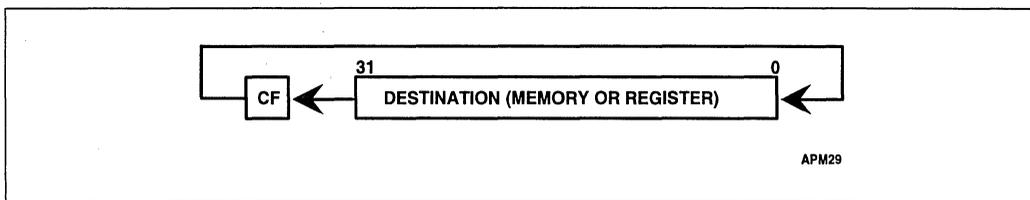


Figure 4-13. RCL Instruction

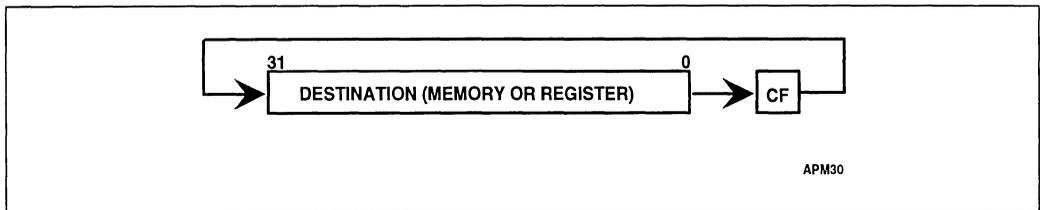


Figure 4-14. RCR Instruction

#### 4.4.4.4. FAST "bit bit" USING DOUBLE-SHIFT INSTRUCTIONS

One purpose of the double shift instructions is to implement a bit string move, with arbitrary misalignment of the bit strings. This is called a "bit blt" (BIT BLock Transfer). A simple example is to move a bit string from an arbitrary offset into a doubleword-aligned byte string. A left-to-right string is moved 32 bits at a time if a double shift is used inside the move loop.

```

MOV     ESI,ScrAddr
MOV     EDI,DestAddr
MOV     EBX,DWordCnt
MOV     CL,RelOffset ; relative offset Dest-Src
MOV     EDX,[ESI]    ; load first dword of source
ADD     ESI,4        ; bump source address

BltLoop:
  LODSD                ; new low order part in EAX
  SHLD  EDX,EAX,CL     ; EDX overwritten with aligned stuff
  XCHG  EDX,EAX       ; Swap high and low dwords
  STOSD                ; Write out next aligned chunk
  DEC   EBX            ; Decrement loop count
  JNZ   BltLoop

```

This loop is simple, yet allows the data to be moved in 32-bit chunks for the highest possible performance. Without a double shift, the best which can be achieved is 16 bits per loop iteration by using a 32-bit shift, and replacing the XCHG instruction with a ROR instruction by 16 to swap the high and low words of registers. A more general loop than shown above would require some extra masking on the first doubleword moved (before the main loop), and on the last doubleword moved (after the main loop), but would have the same 32 bits per loop iteration as the code above.

#### 4.4.4.5. FAST BIT STRING INSERT AND EXTRACT

The double shift instructions also make possible:

- Fast insertion of a bit string from a register into an arbitrary bit location in a larger bit string in memory, without disturbing the bits on either side of the inserted bits

- Fast extraction of a bit string into a register from an arbitrary bit location in a larger bit string in memory, without disturbing the bits on either side of the extracted bits

The following coded examples illustrate bit insertion and extraction under various conditions:

1. Bit String Insertion into Memory (when the bit string is 1-25 bits long, i.e., spans four bytes or less):

```

; Insert a right-justified bit string from a register into
; a bit string in memory.
;
; Assumptions:
; 1. The base of the string array is doubleword aligned.
; 2. The length of the bit string is an immediate value
;    and the bit offset is held in a register.
;
; The ESI register holds the right-justified bit string
; to be inserted.
; The EDI register holds the bit offset of the start of the
; substring.
; The EAX register and ECX are also used.
;
MOV   ECX,EDI           ; save original offset
SHR   EDI,3            ; divide offset by 8 (byte addr)
AND   CL,7H            ; get low three bits of offset
MOV   EAX,[EDI]strg_base ; move string dword into EAX
ROR   EAX,CL           ; right justify old bit field
SHRD  EAX,ESI,length   ; bring in new bits
ROL   EAX,length       ; right justify new bit field
ROL   EAX,CL           ; bring to final position
MOV   [EDI]strg_base,EAX ; replace doubleword in memory

```

2. Bit String Insertion into Memory (when the bit string is 1-31 bits long, i.e., spans five bytes or less):

```

; Insert a right-justified bit string from a register into
; a bit string in memory.
;
; Assumptions:
; 1. The base of the string array is doubleword aligned.
; 2. The length of the bit string is an immediate value
;    and the bit offset is held in a register.
;
; The ESI register holds the right-justified bit string
; to be inserted.
; The EDI register holds the bit offset of the start of the
; substring.
; The EAX, EBX, ECX, and EDI registers also are used.

```

```

;
MOV    ECX,EDI                    ; temp storage for offset
SHR    EDI,5                      ; divide offset by 32 (dwords)
SHL    EDI,2                      ; multiply by 4 (byte address)
AND    CL,1FH                    ; get low five bits of offset
MOV    EAX,[EDI]strg_base        ; move low string dword into EAX
MOV    EDX,[EDI]strg_base+4      ; other string dword into EDX
MOV    EBX,EAX                   ; temp storage for part of string
SHRD   EAX,EDX,CL                ; shift by offset within dword
SHRD   EAX,EBX,CL                ; shift by offset within dword
SHRD   EAX,ESI,length           ; bring in new bits
ROL    EAX,length                ; right justify new bit field
MOV    EBX,EAX                   ; temp storage for string
SHLD   EAX,EDX,CL                ; shift by offset within dword
SHLD   EDX,EBX,CL                ; shift by offset within dword
MOV    [EDI]strg_base,EAX        ; replace dword in memory
MOV    [EDI]strg_base+4,EDX      ; replace dword in memory

```

### 3. Bit String Insertion into Memory (when the bit string is exactly 32 bits long, i.e., spans four or five bytes):

```

; Insert right-justified bit string from a register into
; a bit string in memory.
;
; Assumptions:
; 1. The base of the string array is doubleword aligned.
; 2. The length of the bit string is 32 bits
;    and the bit offset is held in a register.
;
; The ESI register holds the 32-bit string to be inserted.
; The EDI register holds the bit offset to the start of the
; substring.
; The EAX, EBX, ECX, and EDI registers also are used.
;
MOV    EDX,EDI                    ; save original offset
SHR    EDI,5                      ; divide offset by 32 (dwords)
SHL    EDI,2                      ; multiply by 4 (byte address)
AND    CL,1FH                    ; isolate low five bits of offset
MOV    EAX,[EDI]strg_base        ; move low string dword into EAX
MOV    EDX,[EDI]strg_base+4      ; other string dword into EDX
MOV    EBX,EAX                   ; temp storage for part of string
SHRD   EAX,EDX                   ; shift by offset within dword
SHRD   EDX,EBX                   ; shift by offset within dword
MOV    EAX,ESI                   ; move 32-bit field into position
MOV    EBX,EAX                   ; temp storage for part of string
SHLD   EAX,EDX                   ; shift by offset within dword
SHLD   EDX,EBX                   ; shift by offset within dword

```

```
MOV    [EDI]strg_base,EAX    ; replace dword in memory
MOV    [EDI]strg_base,+4,EDX ; replace dword in memory
```

#### 4. Bit string Extraction from Memory (when the bit string is 1-25 bits long, i.e., spans four bytes or less):

```
; Extract a right-justified bit string into a register from
; a bit string in memory.
;
; Assumptions:
; 1) The base of the string array is doubleword aligned.
; 2) The length of the bit string is an immediate value
;    and the bit offset is held in a register.
;
; The EAX register hold the right-justified, zero-padded
; bit string that was extracted.
; The EDI register holds the bit offset of the start of the
; substring.
; The EDI, and ECX registers also are used.
;
MOV    ECX,EDI                ; temp storage for offset
SHR    EDI,3                  ; divide offset by 8 (byte addr)
AND    CL,7H                  ; get low three bits of offset
MOV    EAX,[EDI]strg_base     ; move string dword into EAX
SHR    EAX,CL                 ; shift by offset within dword
AND    EAX,mask               ; extracted bit field in EAX
```

#### 5. Bit string Extraction from Memory (when bit string is 1-32 bits long, i.e., spans five bytes or less):

```
; Extract a right-justified bit string into a register from
; bit string in memory.
;
; Assumptions:
; 1) The base of the string array is doubleword aligned.
; 2) The length of the bit string is an immediate
;    value and the bit offset is held in a register.
;
; The EAX register holds the right-justified, zero-padded
; bit string that was extracted.
; The EDI register holds the bit offset of the start of the
; substring.
; The EAX, EBX, and ECX registers also are used.
;
MOV    ECX,EDI                ; temp storage for offset
SHR    EDI,5                  ; divide offset by 32 (dwords)
SHL    EDI,2                  ; multiply by 4 (byte address)
AND    CL,1FH                 ; get low five bits of offset in
MOV    EAX,[EDI]strg_base     ; move low string dword into EAX
```

```
MOV    EDX,[EDI]strg_base +4    ; other string dword into EDX
SHRD   EAX,EDX,CL              ; shift right by offset in dword
AND    EAX,mask                ; extracted bit field in EAX
```

#### 4.4.5. Byte-Set-On-Condition Instructions

This group of instructions sets a byte to the value of zero or one, depending on any of the 16 conditions defined by the status flags. The byte may be in a register or in memory. These instructions are especially useful for implementing Boolean expressions in high-level languages such as Pascal.

Some languages represent a logical one as an integer with all bits set. This can be done by using the SETcc instruction with the mutually exclusive condition, then decrementing the result.

SETcc (Set Byte on Condition cc) loads the value 1 into a byte if condition cc is true; clears the byte otherwise. See Appendix D for a definition of the possible conditions.

#### 4.4.6. Test Instruction

TEST (Test) performs the logical "and" of the two operands, clears the OF and CF flags, leaves the AF flag undefined, and updates the SF, ZF, and PF flags. The flags can be tested by conditional control transfer instructions or the byte-set-on-condition instructions. The operands may be bytes, words, or doublewords.

The difference between the TEST and AND instructions is that the TEST instruction does not alter the destination operand. The difference between the TEST and BT instructions is that the TEST instruction can test the value of multiple bits in one operation, while the BT instruction tests a single bit.

### 4.5. CONTROL TRANSFER INSTRUCTIONS

The processor provides both conditional and unconditional control transfer instructions to direct the flow of execution. Conditional transfers are taken only for certain combinations of the state of the flags. Unconditional control transfers are always executed.

#### 4.5.1. Unconditional Transfer Instructions

The JMP, CALL, RET, INT, and IRET instructions transfer execution to a destination in a code segment. The destination can be within the same code segment (near transfer) or in a different code segment (far transfer). The forms of these instructions which transfer execution to other segments are discussed in a later section of this chapter. If the model of memory organization used in a particular application does not make segments visible to application programmers, far transfers are not used.

#### 4.5.1.1. JUMP INSTRUCTION

**JMP (Jump)** unconditionally transfers execution to the destination. The JMP instruction is a one-way transfer of execution; it does not save a return address on the stack.

The JMP instruction transfers execution from the current routine to a different routine. The address of the routine is specified in the instruction, in a register, or in memory. The location of the address determines whether it is interpreted as a relative address or an absolute address.

**Relative Address.** A relative jump uses a displacement (immediate mode constant used for address calculation) held in the instruction. The displacement is signed and variable-length (byte or doubleword). The destination address is formed by adding the displacement to the address held in the EIP register. The EIP register then contains the address of the next instruction to be executed.

**Absolute Address.** An absolute jump is used with a 32-bit segment offset in either of the following ways:

1. The program can jump to an address in a general register. This 32-bit value is copied into the EIP register and execution continues.
2. The destination address can be a memory operand specified using the standard addressing modes. The operand is copied into the EIP register and execution continues.

#### 4.5.1.2. CALL INSTRUCTIONS

**CALL (Call Procedure)** transfers execution and saves the address of the instruction following the CALL instruction for later use by a RET (Return) instruction. CALL pushes the current contents of the EIP register on the stack. The RET instruction in the called procedure uses this address to transfer execution back to the calling program.

CALL instructions, like JMP instructions, have relative and absolute forms.

Indirect CALL instructions specify an absolute address in one of the following ways:

1. The program can jump to an address in a general register. This 32-bit value is copied into the EIP register, the return address is pushed on the stack, and execution continues.
2. The destination address can be a memory operand specified using the standard addressing modes. The operand is copied into the EIP register, the return address is pushed on the stack, and execution continues.

#### 4.5.1.3. RETURN AND RETURN-FROM-INTERRUPT INSTRUCTIONS

**RET (Return From Procedure)** terminates a procedure and transfers execution to the instruction following the CALL instruction which originally invoked the procedure. The RET instruction restores the contents of the EIP register which were pushed on the stack when the procedure was called.



The RET instructions have an optional immediate operand. When present, this constant is added to the contents of the ESP register, which has the effect of removing any parameters pushed on the stack before the procedure call.

**IRET (Return From Interrupt)** returns control to an interrupted procedure. The IRET instruction differs from the RET instruction in that it restores the EFLAGS register from the stack. The contents of the EFLAGS register are stored on the stack when an interrupt occurs.

## 4.5.2. Conditional Transfer Instructions

The conditional transfer instructions are jumps which transfer execution if the states in the EFLAGS register match conditions specified in the instruction.

### 4.5.2.1. CONDITIONAL JUMP INSTRUCTIONS

Table 4-3 shows the mnemonics for the jump instructions. The instructions listed as pairs are alternate names for the same instruction. The assembler provides these names for greater clarity in program listings.

A form of conditional jump instruction is available which uses a displacement added to the contents of the EIP register if the specified condition is true. The displacement may be a byte or doubleword. The displacement is signed; it can be used to jump forward or backward.

Table 4-3. Conditional Jump Instructions

Mnemonic	Flag States	Description
<b>Unsigned Conditional Jumps</b>		
JNBE	(CF or ZF)=0	Above/not below nor equal
JAE/JNB	CF=0	Above or equal/not below
JBE/JNAE	CF=1	Below/not above nor equal
JBE/JNA	(CF or ZF)=1	Below or equal/not above
JC	CF=1	Carry
JE/JZ	ZF=1	Equal/zero
JNC	CF=0	Not carry
JNE/JNZ	ZF=0	Not equal/not zero
JNP/JPO	PF=0	Not parity/parity odd
JP/JPE	PF=1	Parity/parity even
<b>Signed Conditional Jumps</b>		
JG/JNLE	((SF xor OF) or ZF) =0	Greater/not less nor equal
JGE/JNL	(SF xor OF)=0	Greater or equal/not less
JL/JNGE	(SF xor OF)=1	Less/not greater nor equal
JLE/JNG	((SF xor OF) or ZF)=1	Less or equal/not greater
JNO	OF=0	Not overflow
JNS	SF=0	Not sign (non-negative)
JO	OF=1	Overflow
JS	SF=1	Sign (negative)

#### 4.5.2.2. LOOP INSTRUCTIONS

The loop instructions are conditional jumps which use the value of the ECX register as a count for the number of times to run a loop. All loop instructions decrement the contents of the ECX register on each reposition and terminate when zero is reached. Four of the five loop instructions accept the ZF flag as a condition for terminating the loop before the count reaches zero.

**LOOP (Loop While ECX Not Zero)** is a conditional jump instruction which decrements the contents of the ECX register before testing for the loop-terminating condition. If the contents of the ECX register are non-zero, the program jumps to the destination specified in the instruction. The LOOP instruction causes the execution of a block of code to be repeated until the count reaches zero. When zero is reached, execution is transferred to the instruction immediately following the LOOP instruction. If the value in the ECX register is zero when

the instruction is first called, the count is pre-decremented to 0FFFFFFFH and the LOOP runs  $2^{32}$  times.

**LOOPE (Loop While Equal) and LOOPZ (Loop While Zero)** are synonyms for the same instruction. These instructions are conditional jumps which decrement the contents of the ECX register before testing for the loop-terminating condition. If the contents of the ECX register are non-zero and the ZF flag is set, the program jumps to the destination specified in the instruction. When zero is reached or the ZF flag is clear, execution is transferred to the instruction immediately following the LOOPE/LOOPZ instruction.

**LOOPNE (Loop While Not Equal) and LOOPNZ (Loop While Not Zero)** are synonyms for the same instruction. These instructions are conditional jumps which decrement the contents of the ECX register before testing for the loop-terminating condition. If the contents of the ECX register are non-zero and the ZF flag is clear, the program jumps to the destination specified in the instruction. When zero is reached or the ZF flag is set, execution is transferred to the instruction immediately following the LOOPE/LOOPZ instruction.

#### 4.5.2.3. EXECUTING A LOOP OR REPEAT ZERO TIMES

**JECXZ (Jump if ECX Zero)** jumps to the destination specified in the instruction if the ECX register holds a value of zero. The JECXZ instruction is used in combination with the LOOP instruction and with the string scan and compare instructions. Because these instructions decrement the contents of the ECX register before testing for zero, a loop will run  $2^{32}$  times if the loop is entered with a zero value in the ECX register. The JECXZ instruction is used to create loops which fall through without executing when the initial value is zero. A JECXZ instruction at the beginning of a loop can be used to jump out of the loop if the count is zero. When used with repeated string scan and compare instructions, the JECXZ instruction can determine whether the loop terminated due to the count or due to satisfaction of the scan or compare conditions.

### 4.5.3. Software Interrupts

The INT, INTO, and BOUND instructions allow the programmer to specify a transfer of execution to an exception or interrupt handler.

**INTn (Software Interrupt)** calls the handler specified by an interrupt vector encoded in the instruction. The INT instruction may specify any interrupt type. This instruction is used to support multiple types of software interrupts or to test the operation of interrupt service routines. The interrupt service routine terminates with an IRET instruction, which returns execution to the instruction following the INT instruction.

**INTO (Interrupt on Overflow)** calls the handler for the overflow exception, if the OF flag is set. If the flag is clear, execution continues without calling the handler. The OF flag is set by arithmetic, logical, and string instructions. This instruction causes a software interrupt for handling error conditions, such as arithmetic overflow.

**BOUND (Detect Value Out of Range)** compares the signed value held in a general register against an upper and lower limit. The handler for the bounds-check exception is called if the

value held in the register is less than the lower bound or greater than the upper bound. This instruction causes a software interrupt for bounds checking, such as checking an array index to make sure it falls within the range defined for the array.

The **BOUND** instruction has two operands. The first operand specifies the general register being tested. The second operand is the base address of two words or doublewords at adjacent locations in memory. The lower limit is the word or doubleword with the lower address; the upper limit has the higher address. The **BOUND** instruction assumes that the upper limit and lower limit are in adjacent memory locations. These limit values cannot be register operands; if they are, an invalid-opcode exception occurs.

The upper and lower limits of an array can reside just before the array itself. This puts the array bounds at a constant offset from the beginning of the array. Because the address of the array already will be present in a register, this practice avoids extra bus cycles to obtain the effective address of the array bounds.

## 4.6. STRING OPERATIONS

String operations manipulate large data structures in memory, such as alphanumeric character strings. See also the section on I/O for information about the string I/O instructions (also known as block I/O instructions).

The string operations are made by putting string instructions (which execute only one iteration of an operation) together with other features of the instruction set, such as repeat prefixes. The string instructions include:

- **MOVS**—Move String
- **CMPS**—Compare string
- **SCAS**—Scan string
- **LODS**—Load string
- **STOS**—Store string

After a string instruction executes, the string source and destination registers point to the next elements in their strings. The string instructions automatically increment or decrement the contents of these registers by the number of bytes occupied by each string element. A string element can be a byte, word, or doubleword. The string registers include:

- **ESI**—Source index register
- **EDI**—Destination index register

String operations can begin at higher addresses and work toward lower ones, or they can begin at lower addresses and work toward higher ones. The direction is controlled by:

- **DF**—Direction flag

If the **DF** flag is clear, the registers are incremented. If the flag is set, the registers are decremented. These instructions set and clear the flag:

- STD—Set direction flag
- CLD—Clear direction flag

To operate on more than one element of a string, a repeat prefix must be used, such as:

- REP—Repeat while the ECX register not zero
- REPE/REPZ—Repeat while the ECX register not zero and the ZF flag is set
- REPNE/REPZ—Repeat while the ECX register not zero and the ZF flag is clear

Exceptions or interrupts that occur during a string instruction leave the registers in a state which allows the string instruction to be restarted. The source and destination registers point to the next string elements, the EIP register points to the string instruction, and the ECX register has the value it held following the last successful iteration. All that is necessary to restart the operation is to service the interrupt or fix the source of the exception, then execute an IRET instruction.

### 4.6.1. Repeat Prefixes

The repeat prefixes **REP (Repeat While ECX Not Zero)**, **REPE/REPZ (Repeat While Equal/Zero)**, and **REPNE/REPZ (Repeat While Not Equal/Not Zero)** specify repeated operation of a string instruction.

When a string instruction has a repeat prefix, the operation executes until one of the termination conditions specified by the prefix is satisfied.

For each repetition of the instruction, the string operation may be suspended by an exception or interrupt. After the exception or interrupt has been serviced, the string operation can restart where it left off. This mechanism allows long string operations to proceed without affecting the interrupt response time of the system.

All three prefixes shown in Table 4-4 cause the instruction to repeat until the ECX register is decremented to zero, if no other termination condition is satisfied. The repeat prefixes differ in their other termination condition. The REP prefix has no other termination condition. The REPE/REPZ and REPNE/REPZ prefixes are used exclusively with the SCAS (Scan String) and CMPS (Compare String) instructions. The REPE/REPZ prefix terminates if the ZF flag is clear. The REPNE/REPZ prefix terminates if the ZF flag is set. The ZF flag does not require initialization before execution of a repeated string instruction, because both the SCAS and CMPS instructions affect the ZF flag according to the results of the comparisons they make.

**Table 4-4. Repeat Instructions**

Repeat Prefix	Termination Condition 1	Termination Condition 2
REP	ECX=0	None
REPE/REPZ	ECX=0	ZF=0
REPNE/REPZ	ECX=0	ZF=1

## 4.6.2. Indexing and Direction Flag Control

Although the general registers are completely interchangeable under most conditions, the string instructions require the use of two specific registers. The source and destination strings are in memory addressed by the ESI and EDI registers. The ESI register points to source operands. By default, the ESI register is used with the DS segment register. A segment-override prefix allows the ESI register to be used with the CS, SS, ES, FS, or GS segment registers. The EDI register points to destination operands. It uses the segment indicated by the ES segment register; no segment override is allowed. The use of two different segment registers in one instruction permits operations between strings in different segments.

When ESI and EDI are used in string instructions, they automatically are incremented or decremented after each iteration. String operations can begin at higher addresses and work toward lower ones, or they can begin at lower addresses and work toward higher ones. The direction is controlled by the DF flag. If the flag is clear, the registers are incremented. If the flag is set, the registers are decremented. The STD and CLD instructions set and clear this flag. Programmers should always put a known value in the DF flag before using a string instruction.

## 4.6.3. String Instructions

**MOVS (Move String)** moves the string element addressed by the ESI register to the location addressed by the EDI register. The MOVSB instruction moves bytes, the MOVSW instruction moves words, and the MOVSD instruction moves doublewords. The MOVS instruction, when accompanied by the REP prefix, operates as a memory-to-memory block transfer. To set up this operation, the program must initialize the ECX, ESI, and EDI registers. The ECX register specifies the number of elements in the block.

**CMPS (Compare Strings)** subtracts the destination string element from the source string element and updates the AF, SF, PF, CF and OF flags. Neither string element is written back to memory. If the string elements are equal, the ZF flag is set; otherwise, it is cleared. CMPSB compares bytes, CMPSW compares words, and CMPSD compares doublewords.

**SCAS (Scan String)** subtracts the destination string element from the EAX, AX, or AL register (depending on operand length) and updates the AF, SF, ZF, PF, CF and OF flags. The string and the register are not modified. If the values are equal, the ZF flag is set; otherwise, it is cleared. The SCASB instruction scans bytes; the SCASW instruction scans words; the SCASD instruction scans doublewords.

When the REPE/REPZ or REPNE/REPZ prefix modifies either the SCAS or CMPS instructions, the loop which is formed is terminated by the loop counter or the effect the SCAS or CMPS instruction has on the ZF flag.

**LODS (Load String)** places the source string element addressed by the ESI register into the EAX register for doubleword strings, into the AX register for word strings, or into the AL register for byte strings. This instruction usually is used in a loop, where other instructions process each element of the string as they appear in the register.

**STOS (Store String)** places the source string element from the EAX, AX, or AL register into the string addressed by the EDI register. This instruction usually is used in a loop, where it writes to memory the result of processing a string element read from memory with the LODS instruction. A REP STOS instruction is the fastest way to initialize a large block of memory.

## 4.7. INSTRUCTIONS FOR BLOCK-STRUCTURED LANGUAGES

These instructions provide machine-language support for implementing block-structured languages, such as C and Pascal. They include ENTER and LEAVE, which simplify procedure entry and exit in compiler-generated code. They support a structure of pointers and local variables on the stack called a stack frame.

**ENTER (Enter Procedure)** creates a stack frame compatible with the scope rules of block-structured languages. In these languages, a procedure has access to its own variables and some number of other variables defined elsewhere in the program. The scope of a procedure is the set of variables to which it has access. The rules for scope vary among languages; they may be based on the nesting of procedures, the division of the program into separately-compiled files, or some other modularization scheme.

The ENTER instruction has two operands. The first specifies the number of bytes to be reserved on the stack for dynamic storage in the procedure being entered. Dynamic storage is the memory allocated for variables created when the procedure is called, also known as automatic variables. The second parameter is the lexical nesting level (from 0 to 31) of the procedure. The nesting level is the depth of a procedure in the hierarchy of a block-structured program. The lexical level has no particular relationship to either the protection privilege level or to the I/O privilege level.

The lexical nesting level determines the number of stack frame pointers to copy into the new stack frame from the preceding frame. A stack frame pointer is a doubleword used to access the variables of a procedure. The set of stack frame pointers used by a procedure to access the variables of other procedures is called the display. The first doubleword in the display is a pointer to the previous stack frame. This pointer is used by a LEAVE instruction to undo the effect of an ENTER instruction by discarding the current stack frame.

Example: `ENTER 2048,3`

Allocates 2K bytes of dynamic storage on the stack and sets up pointers to two previous stack frames in the stack frame for this procedure.

After the ENTER instruction creates the display for a procedure, it allocates the dynamic (automatic) local variables for the procedure by decrementing the contents of the ESP register by the number of bytes specified in the first parameter. This new value in the ESP register serves as the initial top-of-stack for all PUSH and POP operations within the procedure.

To allow a procedure to address its display, the ENTER instruction leaves the EBP register pointing to the first doubleword in the display. Because stacks grow down, this is actually the doubleword with the highest address in the display. Data manipulation instructions which

specify the EBP register as a base register automatically address locations within the stack segment instead of the data segment.

The ENTER instruction can be used in two ways: nested and non-nested. If the lexical level is 0, the non-nested form is used. The non-nested form pushes the contents of the EBP register on the stack, copies the contents of the ESP register into the EBP register, and subtracts the first operand from the contents of the ESP register to allocate dynamic storage. The non-nested form differs from the nested form in that no stack frame pointers are copied. The nested form of the ENTER instruction occurs when the second parameter (lexical level) is not zero.

The psuedo code in Example 4-1 shows the formal definition of the ENTER instruction. STORAGE is the number of bytes of dynamic storage to allocate for local variables, and LEVEL is the lexical nesting level.

#### Example 4-1. ENTER Definition

```
Push EBP
Set a temporary value FRAME_PTR := ESP
If LEVEL > 0 then
  Repeat LEVEL-1 times
    EBP := EBP-4
    Push the doubleword pointed to by EBP
  End Repeat
  Push FRAME_PTR
End if
EBP := FRAME_PTR
ESP := ESP-STORAGE
```

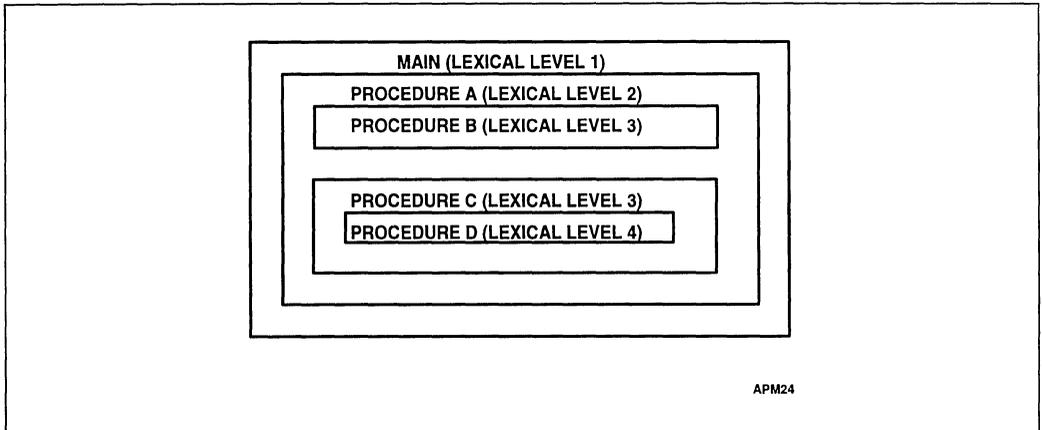
The main procedure (in which all other procedures are nested) operates at the highest lexical level, level 1. The first procedure it calls operates at the next deeper lexical level, level 2. A level 2 procedure can access the variables of the main program, which are at fixed locations specified by the compiler. In the case of level 1, the ENTER instruction allocates only the requested dynamic storage on the stack because there is no previous display to copy.

A procedure which calls another procedure at a lower lexical level gives the called procedure access to the variables of the caller. The ENTER instruction provides this access by placing a pointer to the calling procedure's stack frame in the display.

A procedure which calls another procedure at the same lexical level should not give access to its variables. In this case, the ENTER instruction copies only that part of the display from the calling procedure which refers to previously nested procedures operating at higher lexical levels. The new stack frame does not include the pointer for addressing the calling procedure's stack frame.

The ENTER instruction treats a re-entrant procedure as a call to a procedure at the same lexical level. In this case, each succeeding iteration of the re-entrant procedure can address only its own variables and the variables of the procedures within which it is nested. A re-entrant procedure always can address its own variables; it does not require pointers to the stack frames of previous iterations.

By copying only the stack frame pointers of procedures at higher lexical levels, the ENTER instruction makes certain that procedures access only those variables of higher lexical levels, not those at parallel lexical levels (see Figure 4-15).

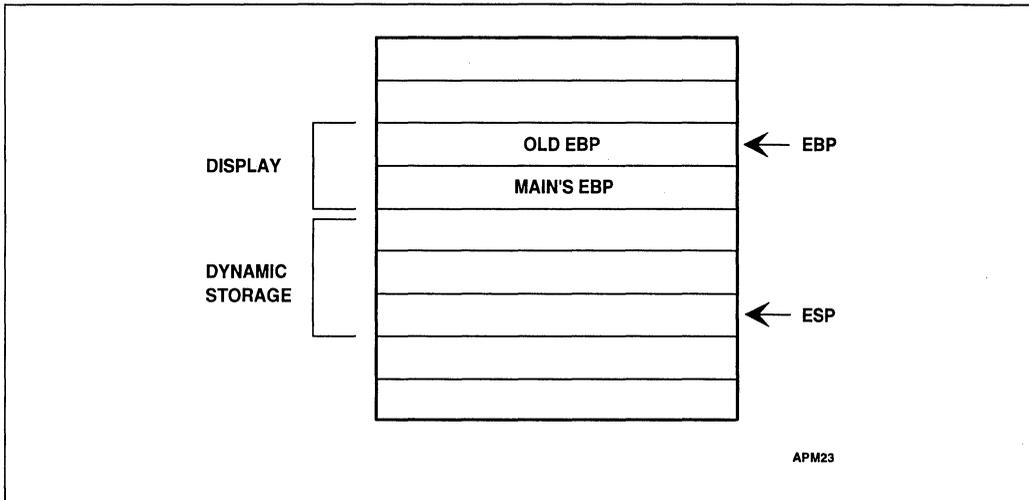


**Figure 4-15. Nested Procedures**

Block-structured languages can use the lexical levels defined by ENTER to control access to the variables of nested procedures. In the figure, for example, if PROCEDURE A calls PROCEDURE B which, in turn, calls PROCEDURE C, then PROCEDURE C will have access to the variables of MAIN and PROCEDURE A, but not those of PROCEDURE B because they are at the same lexical level. The following definition describes the access to variables for the nested procedures in Figure 4-15.

1. MAIN has variables at fixed locations.
2. PROCEDURE A can access only the variables of MAIN.
3. PROCEDURE B can access only the variables of PROCEDURE A and MAIN. PROCEDURE B cannot access the variables of PROCEDURE C or PROCEDURE D.
4. PROCEDURE C can access only the variables of PROCEDURE A and MAIN. PROCEDURE C cannot access the variables of PROCEDURE B or PROCEDURE D.
5. PROCEDURE D can access the variables of PROCEDURE C, PROCEDURE A, and MAIN. PROCEDURE D cannot access the variables of PROCEDURE B.

In Figure 4-16, an ENTER instruction at the beginning of the MAIN program creates three doublewords of dynamic storage for MAIN, but copies no pointers from other stack frames. The first doubleword in the display holds a copy of the last value in the EBP register before the ENTER instruction was executed. The second doubleword (which, because stacks grow down, is stored at a lower address) holds a copy of the contents of the EBP register following the ENTER instruction. After the instruction is executed, the EBP register points to the first doubleword pushed on the stack, and the ESP register points to the last doubleword in the stack frame.



**Figure 4-16. Stack Frame after Entering MAIN**

When MAIN calls PROCEDURE A, the ENTER instruction creates a new display (see Figure 4-17). The first doubleword is the last value held in MAIN's EBP register. The second doubleword is a pointer to MAIN's stack frame which is copied from the second doubleword in MAIN's display. This happens to be another copy of the last value held in MAIN's EBP register. PROCEDURE A can access variables in MAIN because MAIN is at level 1. Therefore the base address for the dynamic storage used in MAIN is the current address in the EBP register, plus four bytes to account for the saved contents of MAIN's EBP register. All dynamic variables for MAIN are at fixed, positive offsets from this value.

When PROCEDURE A calls PROCEDURE B, the ENTER instruction creates a new display. (See Figure 4-18). The first doubleword holds a copy of the last value in PROCEDURE A's EBP register. The second and third doublewords are copies of the two stack frame pointers in PROCEDURE A's display. PROCEDURE B can access variables in PROCEDURE A and MAIN by using the stack frame pointers in its display.

When PROCEDURE B calls PROCEDURE C, the ENTER instruction creates a new display for PROCEDURE C. (See Figure 4-19). The first doubleword holds a copy of the last value in PROCEDURE B's EBP register. This is used by the LEAVE instruction to restore PROCEDURE B's stack frame. The second and third doublewords are copies of the two stack frame pointers in PROCEDURE A's display. If PROCEDURE C were at the next deeper lexical level from PROCEDURE B, a fourth doubleword would be copied, which would be the stack frame pointer to PROCEDURE B's local variables.

Note that PROCEDURE B and PROCEDURE C are at the same level, so PROCEDURE C is not intended to access PROCEDURE B's variables. This does not mean that PROCEDURE C is completely isolated from PROCEDURE B; PROCEDURE C is called by PROCEDURE B, so the pointer to the returning stack frame is a pointer to PROCEDURE B's stack frame. In addition, PROCEDURE B can pass parameters to PROCEDURE C either on the stack or through variables global to both procedures (i.e., variables in the scope of both procedures).

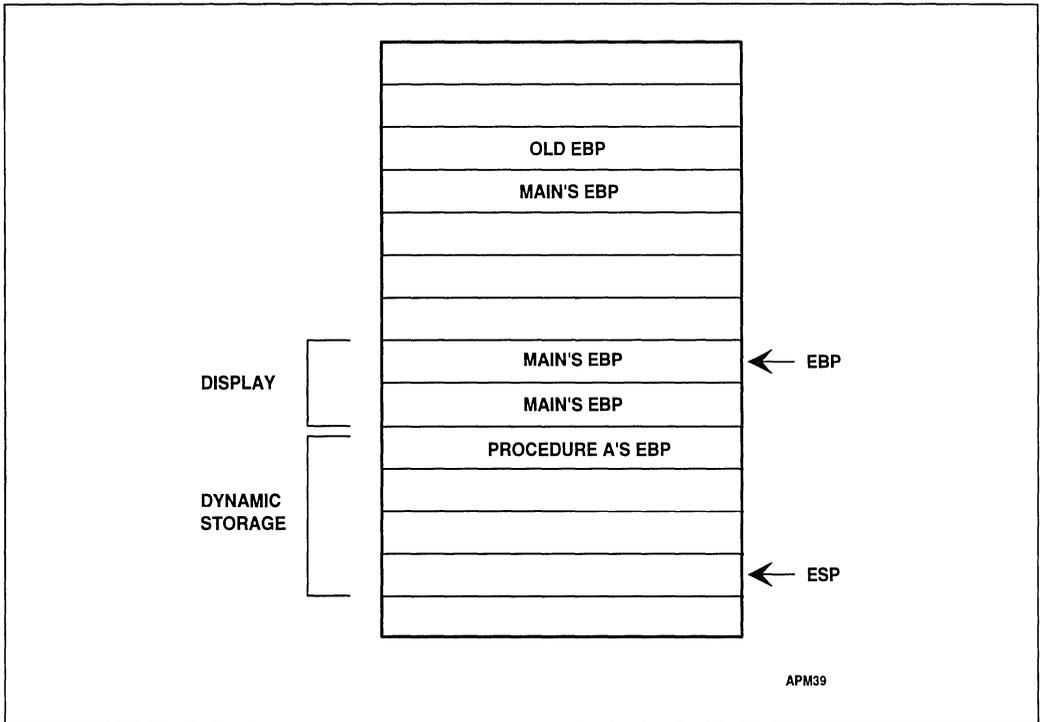


Figure 4-17. Stack Frame after Entering PROCEDURE A

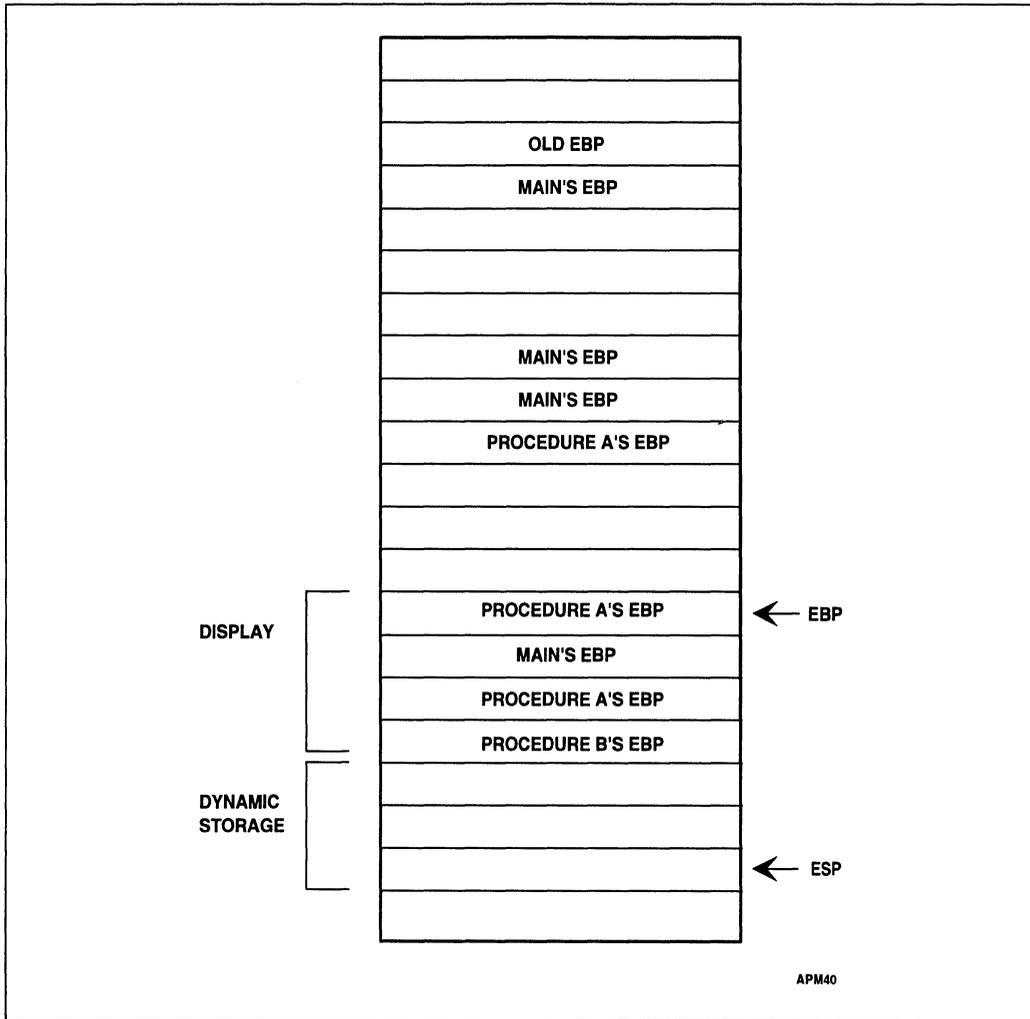


Figure 4-18. Stack Frame after Entering PROCEDURE B

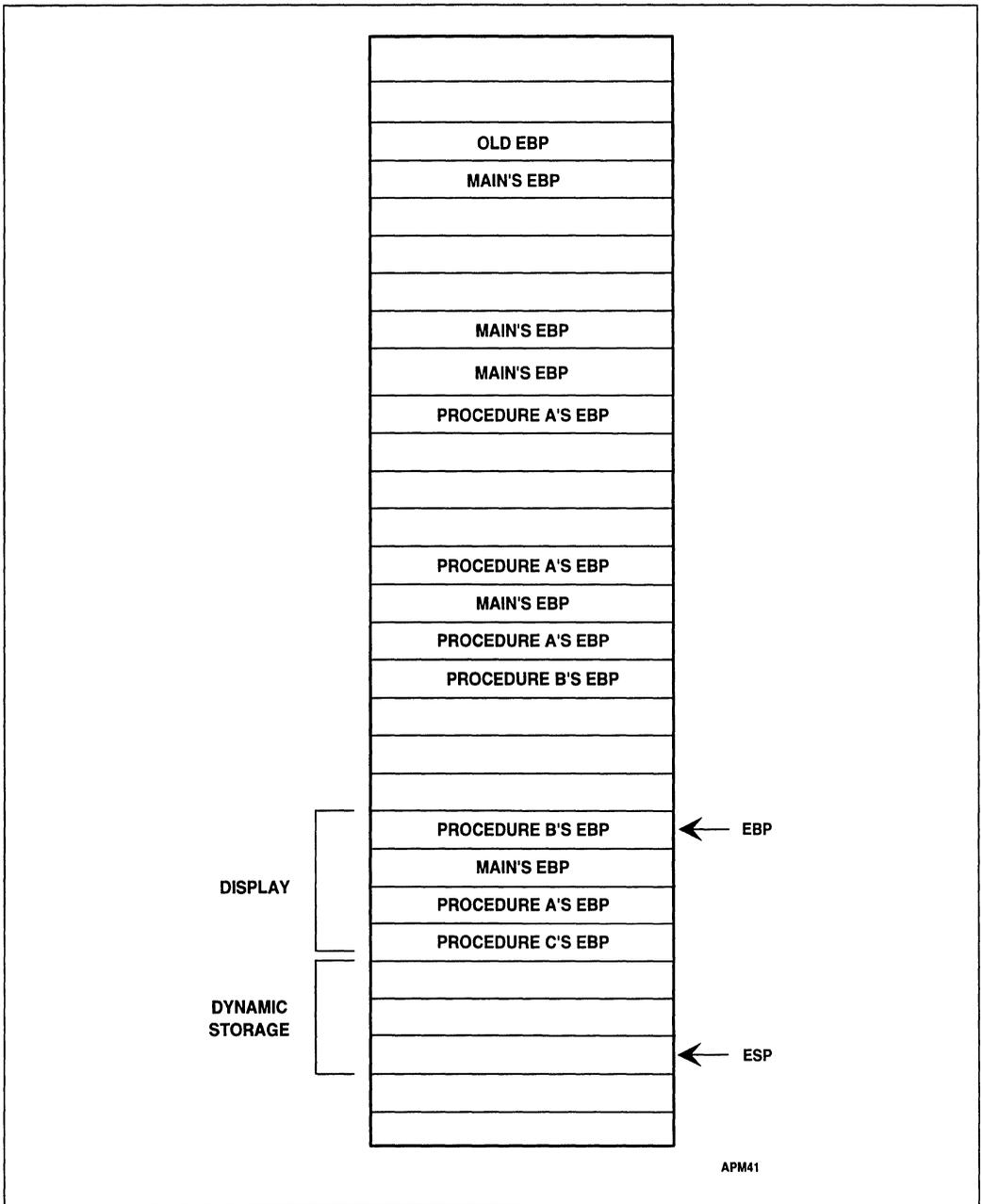


Figure 4-19. Stack Frame after Entering PROCEDURE C

**LEAVE (Leave Procedure)** reverses the action of the previous ENTER instruction. The LEAVE instruction does not have any operands. The LEAVE instruction copies the contents of the EBP register into the ESP register to release all stack space allocated to the procedure. Then the LEAVE instruction restores the old value of the EBP register from the stack. This simultaneously restores the ESP register to its original value. A subsequent RET instruction then can remove any arguments and the return address pushed on the stack by the calling program for use by the procedure.

## 4.8. FLAG CONTROL INSTRUCTIONS

The flag control instructions change the state of bits in the EFLAGS register, as shown in Table 4-5.

**Table 4-5. Flag Control Instructions**

Instruction	Effect
STC (Set Carry Flag)	CF ← 1
CLC (Clear Carry Flag)	CF ← 0
CMC (Complement Carry Flag)	CF ← $\neg$ CF
CLD (Clear Direction Flag)	DF ← 0
STD (Set Direction Flag)	DF ← 1

### 4.8.1. Carry and Direction Flag Control Instructions

The carry flag instructions are useful with instructions like the rotate-with-carry instructions RCL and RCR. They can initialize the carry flag, CF, to a known state before execution of an instruction which copies the flag into an operand.

The direction flag control instructions set or clear the direction flag, DF, which controls the direction of string processing. If the DF flag is clear, the processor increments the string index registers, ESI and EDI, after each iteration of a string instruction. If the DF flag is set, the processor decrements these index registers.

### 4.8.2. Flag Transfer Instructions

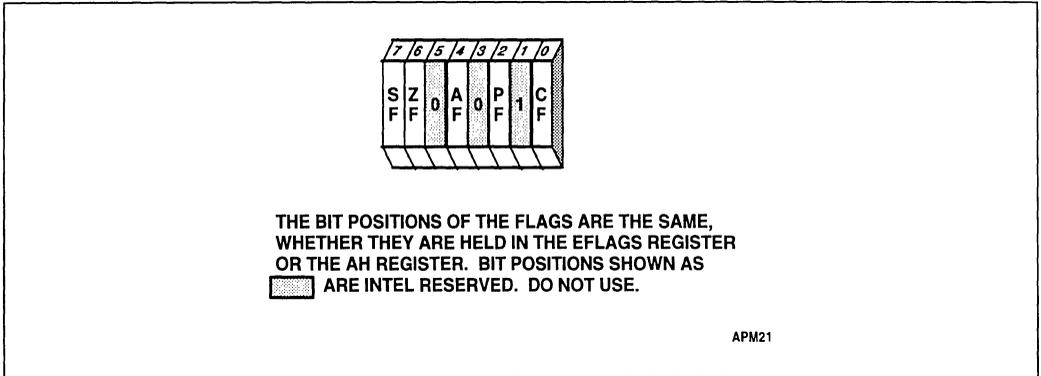
Though specific instructions exist to alter the CF and DF flags, there is no direct method of altering the other application-oriented flags. The flag transfer instructions allow a program to change the state of the other flag bits using the bit manipulation instructions once these flags have been moved to the stack or the AH register.

The LAHF and SAHF instructions deal with five of the status flags, which are used primarily by the arithmetic and logical instructions.



**LAHF (Load AH from Flags)** copies the SF, ZF, AF, PF, and CF flags to the AH register bits 7, 6, 4, 2, and 0, respectively (see Figure 4-20). The contents of the remaining bits 5, 3, and 1 are left undefined. The contents of the EFLAGS register remain unchanged.

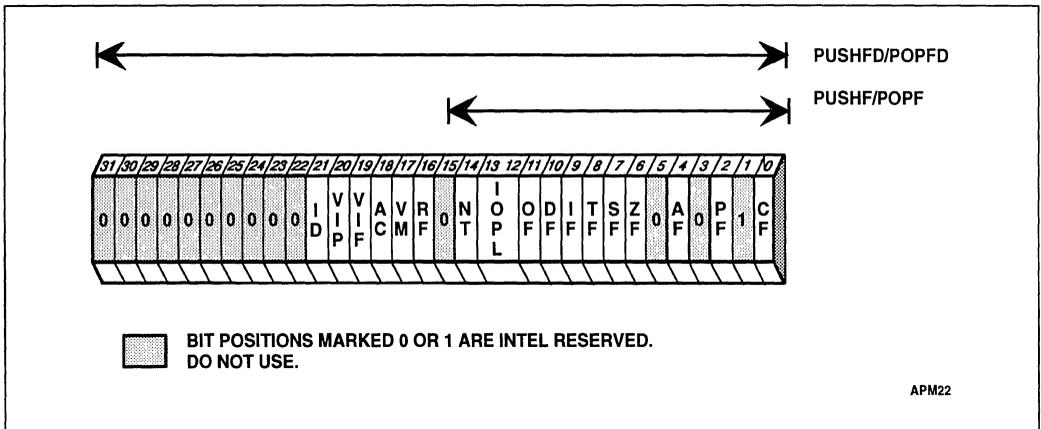
**SAHF (Store AH into Flags)** copies bits 7, 6, 4, 2, and 0 from the AH register into the SF, ZF, AF, PF, and CF flags, respectively (see Figure 4-20).



**Figure 4-20. Low Byte of EFLAGS Register**

The PUSHF and POPF instructions are not only useful for storing the flags in memory where they can be examined and modified, but also are useful for preserving the state of the EFLAGS register while executing a subroutine.

**PUSHF (Push Flags)** pushes the lower word of the EFLAGS register onto the stack (see Figure 4-21). The PUSHFD instruction pushes the entire EFLAGS register onto the stack (the RF and VM flags read as clear, however).



**Figure 4-21. Flags Used with PUSHF and POPF**

**POPF (Pop Flags)** pops a word from the stack into the EFLAGS register. Only bits 11, 10, 8, 7, 6, 4, 2, and 0 are affected with all uses of this instruction. If the privilege level of the current code segment is 0 (most privileged), the IOPL bits (bits 13 and 12) also are affected. If the I/O privilege level (IOPL) is 0, the IF flag (bit 9) also is affected. The POPFD instruction pops a doubleword into the EFLAGS register, and it can change the state of the AC bit (bit 18) and the ID bit (bit 21), as well as the bits affected by a POPF instruction.

## 4.9. NUMERIC INSTRUCTIONS

The Pentium processor includes hardware and instructions for high-precision numeric operations on a variety of numeric data types, including 80-bit extended real and 64-bit long integer. Arithmetic, comparison, transcendental, and data transfer instructions are available. Frequently-used constants are also provided, to enhance the speed of numeric calculations.

The numeric instructions are embedded in the instruction stream of the Pentium processor, as though they were being executed by a single device having both integer and floating-point capabilities. But the floating-point unit of the Pentium processor actually works in parallel with the integer unit, resulting in higher performance.

Refer to Chapter 5 to confirm the presence of a Pentium processor floating-point unit.

Chapter 6 describes the numeric instructions in more detail.

## 4.10. SEGMENT REGISTER INSTRUCTIONS

There are several distinct types of instructions which use segment registers. They are grouped together here because, if system designers choose an unsegmented model of memory organization, none of these instructions are used. The instructions which deal with segment registers include the following:

1. Segment-register transfer instructions.

```
MOV      SegReg, ...
MOV      ..., SegReg
PUSH    SegReg
POP     SegReg
```

2. Control transfers to another executable segment.

```
JMP     far
CALL    far
RET     far
```

3. Data pointer instructions.

```
LDS    reg, 48-bit memory operand
LES    reg, 48-bit memory operand
LFS    reg, 48-bit memory operand
```



```
LGS    reg, 48-bit memory operand
LSS    reg, 48-bit memory operand
```

- Note that the following interrupt-related instructions also are used in unsegmented systems. Although they can transfer execution between segments when segmentation is used, this is transparent to the application programmer.

```
INT    n
INTO
BOUND
IRET
```

### 4.10.1. Segment-Register Transfer Instructions

Forms of the MOV, POP, and PUSH instructions also are used to load and store segment registers. These forms operate like the general-register forms, except that one operand is a segment register. The MOV instruction cannot copy the contents of a segment register into another segment register.

The POP and MOV instructions cannot place a value in the CS register (code segment); only the far control-transfer instructions affect the CS register. When the destination is the SS register (stack segment), interrupts are disabled until after the next instruction.

No 16-bit operand size prefix is needed when transferring data between a segment register and a 32-bit general register.

### 4.10.2. Far Control Transfer Instructions

The far control-transfer instructions transfer execution to a destination in another segment by replacing the contents of the CS register. The destination is specified by a far pointer, which is a 16-bit segment selector and a 32-bit offset into the segment. The far pointer can be an immediate operand or an operand in memory.

**Far CALL.** An intersegment CALL instruction places the values held in the EIP and CS registers on the stack.

**Far RET.** An intersegment RET instruction restores the values of the CS and EIP registers from the stack.

### 4.10.3. Data Pointer Instructions

The data pointer instructions load a far pointer into the processor registers. A far pointer consists of a 16-bit segment selector, which is loaded into a segment register, and a 32-bit offset into the segment, which is loaded into a general register.

**LDS (Load Pointer Using DS)** copies a far pointer from the source operand into the DS register and a general register. The source operand must be a memory operand, and the destination operand must be a general register.

**Example:** `LDS ESI, STRING_X`

Loads the DS register with the segment selector for the segment addressed by `STRING_X`, and loads the offset within the segment to `STRING_X` into the ESI register. Specifying the ESI register as the destination operand is a convenient way to prepare for a string operation, when the source string is not in the current data segment.

**LES (Load Pointer Using ES)** has the same effect as the LDS instruction, except the segment selector is loaded into the ES register rather than the DS register.

**Example:** `LES EDI, DESTINATION_X`

Loads the ES register with the segment selector for the segment addressed by `DESTINATION_X`, and loads the offset within the segment to `DESTINATION_X` into the EDI register. This instruction is a convenient way to select a destination for string operation if the desired location is not in the current E-data segment.

**LFS (Load Pointer Using FS)** has the same effect as the LDS instruction, except the FS register receives the segment selector rather than the DS register.

**LGS (Load Pointer Using GS)** has the same effect as the LDS instruction, except the GS register receives the segment selector rather than the DS register.

**LSS (Load Pointer Using SS)** has the same effect as the LDS instruction, except the SS register receives the segment selector rather than the DS register. This instruction is especially important, because it allows the two registers which identify the stack (the SS and ESP registers) to be changed in one uninterruptible operation. Unlike the other instructions which can load the SS register, interrupts are not inhibited at the end of the LSS instruction. The other instructions, such as `POP SS`, turn off interrupts to permit the following instruction to load the ESP register without an intervening interrupt. Since both the SS and ESP registers can be loaded by the LSS instruction, there is no need to disable or re-enable interrupts.

## 4.11. MISCELLANEOUS INSTRUCTIONS

The following instructions do not fit in any of the previous categories, but are no less important.

The `CMPXCHG8B` and `CPUID` instructions are new instructions on the Pentium processor and bring improved functionality by providing a single instruction to accomplish what previously took multiple instructions on earlier microprocessors.

The `BSWAP`, `XADD`, and `CMPXCHG` instructions are not available on Intel386 DX or SX microprocessors. An Intel386 CPU can perform the same operations in multiple instructions. To use these instructions, always include functionally-equivalent code for Intel386 CPUs.



To determine whether these new instructions can be used, the type of processor in a system needs to be determined. See Chapter 5 for code examples and information on determining the type of the different processors.

### 4.11.1. Address Calculation Instruction

**LEA (Load Effective Address)** puts the 32-bit offset to a source operand in memory (rather than its contents) into the destination operand. The source operand must be in memory, and the destination operand must be a general register. This instruction is especially useful for initializing the ESI or EDI registers before the execution of string instructions or initializing the EBX register before an XLAT instruction. The LEA instruction can perform any indexing or scaling which may be needed.

**Example:** `LEA EBX, EBCDIC_TABLE`

Causes the processor to place the address of the starting location of the table labeled EBCDIC\_TABLE into EBX.

### 4.11.2. No-Operation Instruction

**NOP (No Operation)** occupies a byte of code space. When executed, it increments the EIP register to point at the next instruction, but affects nothing else.

### 4.11.3. Translate Instruction

**XLATB (Translate)** replaces the contents of the AL register with a byte read from a translation table in memory. The contents of the AL register are interpreted as an unsigned index into this table, with the contents of the EBX register used as the base address. The XLAT instruction does the same operation and loads its result into the same register, but it gets the byte operand from memory. This function is used to convert character codes from one alphabet into another. For example, an ASCII code could be used to look up its EBCDIC equivalent.

### 4.11.4. Byte Swap Instruction

**BSWAP (Byte Swap)** reverses the byte order in a 32-bit register operand. Bit positions 7..0 are exchanged with 31..24, and bit positions 15..8 are exchanged with 23..16. This instruction is useful for converting between "big-endian" and "little-endian" data formats. Executing this instruction twice in a row leaves the register in the same value as before. This instruction also speeds execution of decimal arithmetic by operating on four digits at a time as shown in Example 4-2.

**Example 4-2. ASCII Arithmetic Using BSWAP**

```

$title('ASCII Add/Subtract with BSWAP')

        name ASCII_arith

code segment      er public use32
;
;   Add a string of 4 ASCII decimal digits together.
;   The upper nibble MUST be 3.
;   DS:[ESI] points at operand 1
;   DS:[EBX] points at operand 2
;   DS:[EDI] points at the destination
;

add10proc near
;
;   Perform ASCII add using BSWAP instruction
;

        mov  eax, [esi]      ; Get low four digits of first operand
        bswapeax           ; Put into big-endian form
        add  eax, 96969696H ; Adjust for addition so carries work
        mov  ecx, [ebx]     ; Get low four digits of second operand
        bswapecx           ; Put into big-endian form
        add  eax, ecx       ; Do the add with inter-digit carry
        rcr  ch, 1          ; Save the carr flag
        mov  edx, eax       ; Save the value
        and  eax, 0F0F0F0FH ; Extract the uppernibble
        sub  eax, eax       ; Zero out uppernibble of each byte
        shr  eax, 4         ; Prepare for fixup
        and  eax, 0A0A0A0AH ; If non-zero upper nibble then form
                                ; as adjustment value to lower nibble
        add  eax, edx       ; Form adjusted lower nibble value
                                ; Upper nibbles may be 1 from adjustment
        or   eax, 30303030H ; Convert back to ASCII
        bswapeax           ; Back to little-endien
        mov  [edi], eax     ; Set destination
        rcl  ch, 1         ; Restore carry
        ret

add10      endp

;   Subtract a string of 4 ASCII decimal digits together.
;   The upper nibble must be 3.
;   DS:[ESI] points at operand 1
;   DS:[EBX] points at operand 2
;   DS:[EDI] points at the destination

```

```

;
sub10proc near
;
;   Perform ASCII subtract using BSWAP instruction.

    mov  eax, [esi]      ; Get low four digits of first operand
    bswap  eax          ; Put into big-endian form
    mov  ecx, [ebx]     ; get low four digits of second operand
    bswap  ecx          ; Put into big-endian form
    sub  eax,ecx        ; Do the subtraction with inter-digit
borrow
    rcr  ch, 1          ; Save the carry flag
    mov  edx, eax       ; Save the value
    and  eax, 0F0F0F0F0H ; Extract upper nibble, F if borrow
happened
    sub  edx, eax       ; Zero out upper nibble of each byte
    shr  eax, 4         ; Prepare for fixup
    and  eax,0A0A0A0AH ; If non-zero upper nibble then form
                        ; 10 as adjustment value to lower nibble
    add  eax, edx       ; Form adjusted lower nibble value
                        ; upper nibbles may be 1 from adjustment
    or   eax, 30303030H ; Convert back to ASCII
    bswapeax           ; Convert to little-endian
    mov  [edi], eax    ; Set to destination
    rcl  ch, 1         ; Restore borrow
    ret

sub10endp

code ends
end

```

#### 4.11.5. Exchange-and-Add Instruction

**XADD (Exchange and Add)** takes two operands: a source operand in a register and a destination operand in a register or memory. The source operand is replaced with the destination operand, and the destination operand is replaced with the sum of the source and destination operands. The flags reflect the result of the addition. This instruction can be combined with **LOCK** in a multiprocessing system to allow multiple processors to execute one do loop.

#### 4.11.6. Compare-and-Exchange Instructions

**CMPXCHG (Compare and Exchange)** takes three operands: a source operand in a register, a destination operand in a register or memory, and the accumulator (i.e., the AL, AX, or

EAX register, depending on operand size). If the values in the destination operand and the accumulator are equal, the destination operand is replaced with the source operand. Otherwise, the original value of the destination operand is loaded into the accumulator. The flags reflect the result which would have been obtained by subtracting the destination operand from the accumulator. The ZF flag is set if the values in the destination operand and the accumulator were equal, otherwise it is cleared.

The CMPXCHG instruction is useful for testing and modifying semaphores. It performs a check to see if a semaphore is free. If the semaphore is free it is marked allocated, otherwise it gets the ID of the current owner. This is all done in one uninterruptible operation. In a single processor system, it eliminates the need to switch to level 0 to disable interrupts to execute multiple instructions. For multiple processor systems, CMPXCHG can be combined with LOCK to perform all bus cycles atomically.

**CMPXCHG8B (Compare and Exchange 8 Bytes)** takes three operands: a destination operand in memory, a 64-bit value in EDX:EAX and a 64-bit value in ECX:EBX. CMPXCHG8B compares the 64-bit value in EDX:EAX with the destination. If they are equal, the 64-bit value in ECX:EBX is stored in the destination. If EDX:EAX and the destination are not equal, the destination is loaded into EDX:EAX. The ZF flag is set if the values in the destination and EDX:EAX are equal, otherwise it is cleared. The CF, PF, AF, SF, and OF flags are unaffected. CMPXCHG8B can be combined with LOCK to perform all bus cycles in one uninterruptible operation.

#### 4.11.7. CPUID Instruction

**CPUID** provides information to software about the the vendor and model of microprocessor on which it is executing. By loading a zero into EAX and then executing the CPUID instruction, the ECX, EDX, and EBX registers will contain a vendor identification string. The EAX register will contain the highest input value understood by the CPUID instruction. Software can then obtain additional information regarding which features are present by moving a one (or up to the highest value returned in EAX previously) into EAX and executing the CPUID instruction again.

When a one is loaded into the EAX register before executing the CPUID instruction, the EAX register contains information regarding the family, model and stepping of the processor as shown in Figure 4-22. Bits 8-11 of the EAX register indicate what family the processor belongs to and will be 5 for the Pentium microprocessor. Bits 4-7 of the EAX register indicate the model and will be 0 to indicate the first model in the Pentium processor family. Bits 0-3 of the EAX register indicate the Stepping ID which is a unique identifier for each revision level.

The EBX and ECX registers are reserved following execution of this instruction with an input value of one, and the EDX register will contain information on which features are present on a particular processor. For more information on the feature bits of EDX, see Appendix H.

The ability to set and clear the ID flag in the EFLAGS register indicates whether the processor supports the CPUID instruction. The CPUID instruction can be executed at any



privilege level to serialize instruction execution. Serializing instruction execution guarantees that any modifications to flags, registers, and memory for previous instructions are completed before the next instruction is fetched and executed. For more information on serializing operations, see Chapter 18.

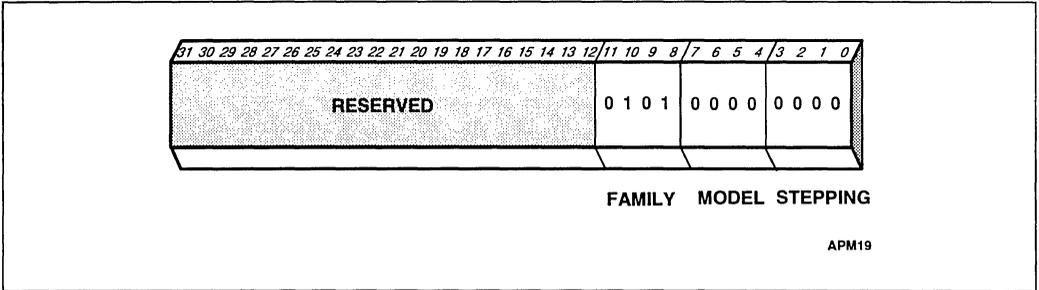


Figure 4-22. EAX Following the CPUID Instruction



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**5**

# **Feature Determination**





## CHAPTER 5

# FEATURE DETERMINATION

Identifying the type of processor present in a system may be necessary in order to determine which features are available to an application. Chapter 23 contains a complete list of which features are available for the different Intel architectures. The absence of an integrated floating-point unit (FPU) or numeric processor extension (NPX) may also need to be determined if software needs to emulate the floating-point instructions.

This chapter discusses processor identification, as well as on-chip FPU and NPX presence detection and identification. Sample code is provided in Example 5-1.

### 5.1. CPU IDENTIFICATION

The setting of the flags stored by the PUSHF instruction, by interrupts, and by exceptions is different on the 32-bit processors than that stored by the 8086 and Intel 286 processors in bits 12 and 13 (IOPL), 14 (NT), and 15 (reserved). These differences can be used to distinguish what type of processor is present in a system while an application is running.

- 8086 processor — bits 12 through 15 are always set.
- Intel 286 processor — bits 12 through 15 are always clear in real-address mode.
- 32-bit processors — in real-address mode, bit 15 is always clear and bits 14 through 12 have the last value loaded into them. In , bit 14 has the last value loaded into it, bit 15 is always clear, and IOPL depends on the CPL (if  $CPL \neq 0$ , the IOPL is unchanged, otherwise it is updated).

Other EFLAG register bits that can be used to differentiate between the 32-bit processors include:

- Bit 18 (AC), implemented on the Intel486 and Pentium processors, can be used to distinguish an Intel386 processor from the Intel486 and Pentium processors as it will always be clear on an Intel386 processor.
- Bit 21 (ID) can be used to determine if an application can execute the CPUID instruction. This instruction supplies information to applications at runtime that identifies Intel as the vendor, including family, model, stepping, and what features are implemented on the processor in the system an application is running on. The ability to set and clear this bit indicates that the CPUID instruction is supported by the processor. See Chapter 25 for details on this instruction.

## 5.2. FPU DETECTION

To determine whether an FPU or NPX is present in a system, applications can write to the status and control word registers using the FNINIT instruction and then verify the correct values are read back. Once an FPU or NPX is determined to be present, its type can then be determined. In most cases, the processor type will determine the type of FPU or NPX, however, an Intel386 microprocessor may work with either an Intel287™ or Intel387 math coprocessor. To determine which of these is present, the infinity of the coprocessor must be checked. On the Intel287 math coprocessor, positive infinity is equal to negative infinity. On the Intel387 math coprocessor, however, positive infinity is not equal to negative infinity.

## 5.3. SAMPLE CPUID IDENTIFICATION/FPU DETECTION CODE

Example 5-1 is the Intel recommended method of determining the processor type as well as the presence and type of NPX or integrated FPU. This code has been modified from previous versions of Intel's recommended CPU identification code by modularizing the printing functions so that applications not running in a DOS environment can remove or change the print function to conform to the appropriate environment. Note that this code (and previous versions) is supported on the Intel 286 in real-address mode only. This example was created using Microsoft's assembler directives.

### Example 5-1. CPU Identification and FPU Detection

```

;      Filename:          cpuid32.msm
;
;      This program has been developed by Intel Corporation.
;      Software developers have Intel's permission to incorporate
;      this source code into your software royalty free.
;
;      Intel specifically disclaims all warranties, express or
;      implied, and all liability, including consequential and other
;      indirect damages, for the use of this code, including
;      liability for infringement of any proprietary rights. Intel
;      does not assume any responsibility for any errors which may
;      appear in this code nor any responsibility to update it.
;
;      This program contains three parts:
;      Part 1: Identifies CPU type in the variable cpu_type:
;              0=8086 processor
;              2=Intel 286 processor
;              3=Intel386(TM) processor
;              4=Intel486(TM) processor
;              5=Pentium(R) processor
;
;      Part 2: Identifies FPU type in the variable fpu_type:

```

```

;           0=FPU not present
;           1=FPU present
;           2=287 present (only if cpu_type=3)
;           3=387 present (only if cpu_type=3)
;
; Part 3: Prints out the appropriate message. This part can
;         be removed if this program is not used in a DOS-based
;         system. Portions affected are at the end of the
;         data segment and the print procedure in the code
;         segment.
;
; This program was assembled with Microsoft's Assembler MASM
; 6.0. While this program mostly uses 16-bit operands, some
; 32-bit operands are required to check the 32-bit EFLAGS
; register once it has been determined that the processor is at
; least an Intel386 processor. 32-bit operations are invoked by
; using the macro OPND32.

        TITLE    CPUID
        DOSSEG
        .model   small
        .stack   100h
        .186

; The OPND32 macro takes either zero or two parameters.
; With zero parameters, it generates the 32-bit operand-size prefix.
; With two parameters, it generates the 32-bit operand-size prefix,
; followed by an opcode and a 32-bit immediate value. These
parameters
; are used to generate XOR AX,imm32 instructions.

OPND32 MACRO op_code, op_erand
        db      66h          ; Force 32-bit operand size
        IFNB <op_code>
            db      op_code  ; Optional opcode
        IFNB <op_erand>
            dd      op_erand ; Optional 32-bit immediate value
        ENDIF
    ENDF
ENDIF
ENDM

CPUID MACRO
        db      0fh          ; Opcode for CPUID instruction
        db      0a2h
    ENDM

TRUE      equ      1

```

```

FAMILY_MASK      equ      0f00h
FAMILY_SHIFT     equ      8
MODEL_MASK       equ      0f0h
MODEL_SHIFT      equ      4
STEPPING_MASK    equ      0fh
FPU_FLAG         equ      1h
MCE_FLAG         equ      80h
CMPXCHG8B_FLAG  equ      100h

```

```

        .data
fp_status      dw      ?
vendor_id      db      12 dup (?)
cpu_type       db      ?
model          db      ?
stepping       db      ?
id_flag        db      0
fpu_type       db      0
intel_proc     db      0
feature_flags  dw      2 dup (0)
;
; Remove the remaining data declarations if not using the DOS-based
; print procedure
;
id_msg         db      "This system has a$"
fp_8087        db      " and an 8087 math coprocessor$"
fp_80287       db      " and an 80287 math coprocessor$"
fp_80387       db      " and an 80387 math coprocessor$"
c8086          db      "n 8086/8088 processor$"
c286           db      "n 80286 processor$"
c386           db      "n 80386 processor$"
c486           db      "n 80486 DX processor or 80487 SX math coprocessor$"
c486nfp        db      "n 80486 SX processor$"
Intel486_msg   db      13,10,"This system contains a Genuine "
               db      "Intel486(TM) processor",13,10,"$"
Pentium_msg    db      13,10,"This system contains a Genuine "
               db      "Intel Pentium(R) processor",13,10,"$"
modelmsg       db      "Model:          $"
steppingmsg    db      "Stepping:         $"
familymsg      db      13,10,"Processor Family: $"
period         db      ". ",13,10,"$"
dataCR         db      ?,13,10,"$"
intel_id       db      "GenuineIntel"
fpu_msg        db      13,10,"This processor contains a FPU",13,10,"$"
mce_msg        db      "This processor supports the "
               db      "Machine Check Exception",13,10,"$"
cmp_msg        db      "This processor supports the "
               db      "CMPXCHG8B instruction",13,10,"$"

```

```

not_intel    db "t least an 80486 processor.",13,10
             db "It does not contain a Genuine Intel part and as a "
             db "result,",13,10,"the CPUID detection information "
             db "cannot be determined at this time.",13,10,"$"

;
;   This code identifies the processor and coprocessor
;   that are currently in the system.  The program first
;   determines the processor id.  When that is accomplished,
;   the program then determines whether a coprocessor
;   exists in the system.  If a coprocessor or integrated
;   coprocessor exists, the program identifies
;   the coprocessor id.  The program then prints out
;   the CPU and floating point presence and type.
;
.code
start:  mov     ax, @data
        mov     ds, ax           ; set segment register
        mov     es, ax           ; set segment register
        pushf                    ; save for restoration at end
        call    get_cpuid
        call    get_fpuid
        call    print
        popf
        mov     ax, 4c00h        ; terminate program
        int     21h

get_cpuid proc
;
;   This procedure determines the type of CPU in a system
;   and sets the cpu_type variable with the appropriate value.
;   All registers are used by this procedure, none are preserved.
;
;   Intel 8086 CPU check
;   Bits 12-15 of the FLAGS register are always set on the
;   8086 processor.
;
check_8086:
        pushf                    ; push original FLAGS
        pop     ax                ; get original FLAGS
        mov     cx, ax            ; save original FLAGS
        and     ax, 0fffh        ; clear bits 12-15 in FLAGS
        push   ax                ; save new FLAGS value on stack
        popf                    ; replace current FLAGS value
        pushf                    ; get new FLAGS
        pop     ax                ; store new FLAGS in AX
        and     ax, 0f000h       ; if bits 12-15 are set, then CPU

```

```

    cmp     ax, 0f000h      ; is an 8086/8088
    mov     cpu_type, 0     ; turn on 8086/8088 flag
    je     end_get_cpuid   ; jump if CPU is 8086/8088

; Intel 286 CPU check
; Bits 12-15 of the FLAGS register are always clear on the
; Intel 286 processor in real-address mode.
;
check_80286:
    or     cx, 0f000h      ; try to set bits 12-15
    push   cx              ; save new FLAGS value on stack
    popf                   ; replace current FLAGS value
    pushf                  ; get new FLAGS
    pop    ax              ; store new FLAGS in AX
    and    ax, 0f000h      ; if bits 12-15 clear, CPU=80286
    mov    cpu_type, 2     ; turn on 80286 flag
    jz    end_get_cpuid   ; if no bits set, CPU is 80286

; Intel386 CPU check
; The AC bit, bit #18, is a new bit introduced in the EFLAGS
; register on the Intel486 DX CPU to generate alignment faults.
; This bit cannot be set on the Intel386 CPU.
;
check_80386:
; It is now safe to use 32-bit opcode/operands
    mov    bx, sp          ; save current stack pointer to align
    and    sp, not 3       ; align stack to avoid AC fault
    OPND32
    pushf                  ; push original EFLAGS
    OPND32
    pop    ax              ; get original EFLAGS
    OPND32
    mov    cx, ax          ; save original EFLAGS
    OPND32 35h, 40000h     ; flip (XOR) AC bit in EFLAGS
    OPND32
    push   ax              ; save new EFLAGS value on stack
    OPND32
    popf                   ; replace current EFLAGS value
    OPND32
    pushf                  ; get new EFLAGS
    OPND32
    pop    ax              ; store new EFLAGS in EAX
    OPND32
    xor    ax, cx          ; can't toggle AC bit, CPU=80386
    mov    cpu_type, 3     ; turn on 80386 CPU flag
    mov    sp, bx          ; restore original stack pointer
    jz    end_get_cpuid   ; jump if 80386 CPU

```

```

    and     sp, not 3           ; align stack to avoid AC fault
    OPND32
    push   cx
    OPND32
    popf                                ; restore AC bit in EFLAGS first
    mov    sp, bx                ; restore original stack pointer

;   Intel486 DX CPU, Intel487 SX NDP, and Intel486 SX CPU check
;   Checking for ability to set/clear ID flag (Bit 21) in EFLAGS
;   which indicates the presence of a processor
;   with the ability to use the CPUID instruction.
;
check_80486:
    mov    cpu_type, 4          ; turn on 80486 CPU flag
    OPND32
    mov    ax, cx              ; get original EFLAGS
    OPND32 35h, 200000h        ; flip (XOR) ID bit in EFLAGS
    OPND32
    push  ax                   ; save new EFLAGS value on stack
    OPND32
    popf                        ; replace current EFLAGS value
    OPND32
    pushf                       ; get new EFLAGS
    OPND32
    pop    ax                   ; store new EFLAGS in EAX
    OPND32
    xor    ax, cx              ; can't toggle ID bit,
    je     end_get_cpuid       ; CPU=80486

;   Execute CPUID instruction to identify Intel as the vendor,
;   including family, model and stepping.
;
check_vendor:
    mov    id_flag, 1          ; set flag indicating use of CPUID
    ;                               ; inst.
    OPND32
    xor    ax, ax              ; set up input for CPUID instruction
    CPUID                               ; macro for CPUID instruction
    OPND32
    mov    word ptr vendor_id, bx ; setup to test for vendor id
    OPND32
    mov    word ptr vendor_id[+4], dx
    OPND32
    mov    word ptr vendor_id[+8], cx
    mov    si, offset vendor_id
    mov    di, offset intel_id
    mov    cx, length intel_id

```

```
compare:
    repe    cmpsb          ; compare vendor id to "GenuineIntel"
    or     cx, cx
    jnz    end_get_cpuid  ; if not zero, not an Intel CPU,
```

```
intel_processor:
    mov    intel_proc, 1
```

```
cpuid_data:
    OPND32
    cmp    ax, 1          ; make sure 1 is a valid input
                          ; value for CPUID
    jl    end_get_cpuid  ; if not, jump to end
    OPND32
    xor    ax, ax        ; otherwise, use as input to CPUID
    OPND32
    inc    ax            ; and get stepping, model and family
    CPUID
    mov    stepping, al
    and    stepping, STEPPING_MASK ; isolate stepping info

    and    al, MODEL_MASK ; isolate model info
    shr    al, MODEL_SHIFT
    mov    model, al

    and    ax, FAMILY_MASK ; mask everything but family
    shr    ax, FAMILY_SHIFT
    mov    cpu_type, al    ; set cpu_type with family

    OPND32
    mov    feature_flags, dx ; save feature flag data

end_get_cpuid:
    ret
get_cpuid endp
```

```
*****
```

```
get_fpuid proc
;
; This procedure determines the type of FPU in a system
; and sets the fpu_type variable with the appropriate value.
; All registers are used by this procedure, none are preserved.

; Coprocessor check
; The algorithm is to determine whether the floating-point
```

```

;      status and control words can be written to.  If not, no
;      coprocessor exists.  If the status and control words can be
;      written to, the correct coprocessor is then determined
;      depending on the processor id.  The Intel386 CPU can
;      work with either an Intel287 NDP or an Intel387 NDP.
;      The infinity of the coprocessor must be
;      checked to determine the correct coprocessor id.

      fninit                ; reset FP status word
      mov     fp_status, 5a5ah; initialize temp word to
                                ; non-zero value
      fnstsw  fp_status     ; save FP status word
      mov     ax, fp_status  ; check FP status word
      cmp     al, 0         ; see if correct status with
                                ; written
      mov     fpu_type, 0   ; no fpu present
      jne     end_get_fpuid

check_control_word:
      fnstcw  fp_status     ; save FP control word
      mov     ax, fp_status  ; check FP control word
      and     ax, 103fh     ; see if selected parts
                                ; looks OK
      cmp     ax, 3fh       ; check that 1's & 0's
                                ; correctly read

      mov     fpu_type, 0
      jne     end_get_fpuid
      mov     fpu_type, 1

;
;      80287/80387 check for the Intel386 CPU
;
check_infinity:
      cmp     cpu_type, 3
      jne     end_get_fpuid
      fld1                    ; must use default control from
FNINIT
      fldz                    ; form infinity
      fdiv                    ; 8087 and Intel287 NDP say +inf = -
inf
      fld     st              ; form negative infinity
      fchs                    ; Intel387 NDP says +inf <> -inf
      fcompp                   ; see if they are the same and remove
them
      fstsw  fp_status       ; look at status from FCOMPP
      mov     ax, fp_status
      mov     fpu_type, 2   ; store Intel287 NDP for fpu type

```

```

        sahf                ; see if infinities matched
        jz      end_get_fpuid ; jump if 8087 or Intel287 is present
        mov     fpu_type, 3   ; store Intel387 NDP for fpu type
end_get_fpuid:
        ret
get_fpuid endp

```

```

;*****
*

```

```
print proc
```

```

;
;   This procedure prints the appropriate cpuid string and
;   numeric processor presence status.  If the CPUID instruction
;   was supported, this procedure prints out cpuid info.
;   All registers are used by this procedure, none are preserved.

```

```

        cmp     id_flag, 1      ; if set to 1, cpu supports
                                ;   CPUID instruction
                                ;   print detailed CPUID

```

```
information
```

```
        je     print_cpuid_data
```

```

        mov     dx, offset id_msg ; print initial message
        mov     ah, 9h
        int     21h

```

```
print_86:
```

```

        cmp     cpu_type, 0
        jne     print_286
        mov     dx, offset c8086
        mov     ah, 9h
        int     21h
        cmp     fpu_type, 0
        je     end_print
        mov     dx, offset fp_8087
        mov     ah, 9h
        int     21h
        jmp     end_print

```

```
print_286:
```

```

        cmp     cpu_type, 2
        jne     print_386
        mov     dx, offset c286
        mov     ah, 9h
        int     21h

```

```
        cmp     fpu_type, 0
        je      end_print
        mov     dx, offset fp_80287
        mov     ah, 9h
        int     21h
        jmp     end_print

print_386:
        cmp     cpu_type, 3
        jne     print_486
        mov     dx, offset c386
        mov     ah, 9h
        int     21h
        cmp     fpu_type, 0
        je      end_print
        cmp     fpu_type, 2
        jne     print_387
        mov     dx, offset fp_80287
        mov     ah, 9h
        int     21h
        jmp     end_print

print_387:
        mov     dx, offset fp_80387
        mov     ah, 9h
        int     21h
        jmp     end_print

print_486:
        cmp     fpu_type, 0
        je      print_Intel486sx
        mov     dx, offset c486
        mov     ah, 9h
        int     21h
        jmp     end_print

print_Intel486sx:
        mov     dx, offset c486nfp
        mov     ah, 9h
        int     21h
        jmp     end_print

print_cpuid_data:

cmp_vendor:
        cmp     intel_proc, 1
        jne     not_GenuineIntel
```

```

        cmp     cpu_type, 4                ; if cpu_type=4, print
                                           ; Intel486 CPU message
    jne     check_Pentium
    mov     dx, offset Intel486_msg
    mov     ah, 9h
    int     21h
    jmp     print_family

check_Pentium:
    cmp     cpu_type, 5                ; if cpu_type=5, print
    jne     print_features            ; Pentium processor
message
    mov     dx, offset Pentium_msg
    mov     ah, 9h
    int     21h

print_family:
    mov     dx, offset familymsg      ; print family msg
    mov     ah, 9h
    int     21h
    mov     al, cpu_type
    mov     byte ptr dataCR, al
    add     byte ptr dataCR, 30h      ; convert to ASCII
    mov     dx, offset dataCR        ; print family info
    mov     ah, 9h
    int     21h

print_model:
    mov     dx, offset modelmsg      ; print model msg
    mov     ah, 9h
    int     21h
    mov     al, model
    mov     byte ptr dataCR, al
    add     byte ptr dataCR, 30h      ; convert to ASCII
    mov     dx, offset dataCR        ; print model info
    mov     ah, 9h
    int     21h

print_stepping:
    mov     dx, offset steppingmsg    ; print stepping msg
    mov     ah, 9h
    int     21h
    mov     al, stepping
    mov     byte ptr dataCR, al
    add     byte ptr dataCR, 30h      ; convert to ASCII
    mov     dx, offset dataCR        ; print stepping info

```

```
        mov     ah, 9h
        int     21h

print_features:
        mov     ax, feature_flags
        and     ax, FPU_FLAG                ; check for FPU
        jz     check_MCE
        mov     dx, offset fpu_msg
        mov     ah, 9h
        int     21h

check_MCE:
        mov     ax, feature_flags
        and     ax, MCE_FLAG                ; check for MCE
        jz     check_CMPXCHG8B
        mov     dx, offset mce_msg
        mov     ah, 9h
        int     21h

check_CMPXCHG8B:
        mov     ax, feature_flags
        and     ax, CMPXCHG8B_FLAG          ; check for CMPXCHG8B
        jz     end_print
        mov     dx, offset cmp_msg
        mov     ah, 9h
        int     21h
        jmp    end_print

not_GenuineIntel:
        mov     dx, offset not_Intel
        mov     ah, 9h
        int     21h

end_print:
        ret
print endp

        end     start
.
```



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**6**

**Numeric  
Applications**





## CHAPTER 6 NUMERIC APPLICATIONS

The Pentium processor contains a high-performance numerics processing element that provides significant numeric capabilities and direct support for floating-point, extended-integer, and BCD data types. The Pentium processor Floating-Point Unit (FPU) easily supports powerful and accurate numeric applications through its implementation, with radix 2, of the IEEE Standard 754 for Floating-Point Arithmetic. The Pentium processor FPU provides floating-point performance comparable to that of large minicomputers while offering compatibility with object code for 8087, Intel287, Intel387 DX, Intel387 SX, and Intel487 DX math coprocessors and the Intel486 DX processor.

### 6.1. INTRODUCTION TO NUMERIC APPLICATIONS

#### 6.1.1. History

The 8087 numeric processor extension (NPX) was designed for use in 8086-family systems. The 8086 was the first microprocessor family to partition the processing unit to permit high-performance numeric capabilities. The 8087 NPX for this processor family implemented a complete numeric processing environment in compliance with an early proposal for IEEE Standard 754 for Binary Floating-Point Arithmetic.

With the Intel287 coprocessor NPX, high-speed numeric computations were extended to 80286 high-performance multitasking and multiuser systems. Multiple tasks using the numeric processor extension were afforded the full protection of the 80286 memory management and protection features.

The Intel387 DX and SX math coprocessors are Intel's third generation numerics processors. They implement the final IEEE Std 754, adding new trigonometric instructions, and using a new design and CHMOS-III process to allow higher clock rates and require fewer clocks per instruction. Together, the Intel387 math coprocessor with additional instructions and the improved standard brought even more convenience and reliability to numerics programming and made this convenience and reliability available to applications that need the high-speed and large memory capacity of the 32-bit environment of the Intel386 microprocessor.

The Intel486 processor FPU is an on-chip equivalent of the Intel387 DX math coprocessor conforming to both IEEE Std 754 and the more recent, generalized IEEE Std 854. Having the FPU on chip results in a considerable performance improvement in numerics-intensive computation.

The Pentium processor FPU has been completely redesigned over the Intel486 processor FPU while maintaining conformance to both the IEEE Std 754 and 854. Faster algorithms provide at least three times the performance over the Intel486 processor FPU for common operations



including ADD, MUL, and LOAD. Many applications can achieve five times the performance of the Intel486 processor FPU or more with instruction scheduling and pipelined execution.

### 6.1.2. Performance

Today, floating-point performance is more important than ever. Applications of personal computer workstations, no longer limited to simple spreadsheets and business applications, now include sophisticated algorithms such as lab data analysis and three-dimensional graphics.

Table 6-1 compares the execution times of several Pentium processor numeric instructions with the equivalent operations executed on a 66-MHz Intel486 DX2 processor. As indicated in the table, the 66-MHz Pentium processor provides about three times the floating-point performance of a 66-MHz Intel486 DX2 CPU. A 66-MHz Pentium processor multiplies 32-bit and 64-bit floating-point numbers in about 45 nanoseconds. Of course, the actual performance of the processor in a given system depends on the characteristics of the individual application.

**Table 6-1. Numeric Processing Speed Comparisons**

Floating-Point Instruction			Approximate Performance Ratio: 66-MHz Pentium® Processor ÷ 66-MHz Intel486™ DX2 CPU
FADD	ST, ST(i)	Addition	3.8
FDIV	dword_var	Division	2.2
FYL2X	ST(0),ST(1) assumed	Logarithm	3.1
FPATAN	ST(0) assumed	Arctangent	2.6
F2XM1	ST(0) assumed	Exponentiation	4.8
FLD	ST(0), ST(i)	Data Transfer	4.0

The processor coordinates its integer and floating-point activities in a manner transparent to software. Moreover, built-in coordination facilities allow the integer pipe(s) to proceed with other instructions while the FPU is simultaneously executing numeric instructions. See AP-500, *Optimizations for Intel's 32-Bit Processors*, order number 241799, on how to obtain more information on floating-point instruction pairing as programs can exploit this concurrency of execution to further increase system performance and throughput.

### 6.1.3. Ease of Use

The 32-bit Intel architectures, with their on-chip FPU (such as the Pentium and Intel486 processors) or NPX's (such as the Intel386 CPU with an Intel387 math coprocessor) are explicitly designed to deliver stable, accurate results when programmed using straightforward



"pencil and paper" algorithms, bringing the functionality and power of accurate numeric computation into the hands of the general user. IEEE Std 754 specifically addresses this issue, recognizing the fundamental importance of making numeric computations both easy and safe to use.

These NPX's and FPU's provide more than raw execution speed for computation-intensive tasks; bringing the functionality and power of accurate numeric computation into the hands of the general user. These features are available in most high-level languages available for these processors.

For example, most computers can overflow when two single-precision floating-point numbers are multiplied together and then divided by a third, even if the final result is a perfectly valid 32-bit number. The FPU delivers the correctly rounded result. Other typical examples of undesirable machine behavior in straightforward calculations occur when computing financial rate of return, which involves the expression  $(1 + i)^n$  or when solving for roots of a quadratic equation:

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

If  $a$  does not equal 0, the formula is numerically unstable when the roots are nearly coincident or when their magnitudes are wildly different. The formula is also vulnerable to spurious over/underflows when the coefficients  $a$ ,  $b$ , and  $c$  are all very big or all very tiny. When single-precision (4-byte) floating-point coefficients are given as data and the formula is evaluated in the FPU's normal way, keeping all intermediate results in its stack, the FPU produces impeccable single-precision roots. This happens because, by default and with no effort on the programmer's part, the FPU evaluates all those subexpressions with so much extra precision and range as to overwhelm almost any threat to numerical integrity.

If double-precision data and results were at issue, a better formula would have to be used, and once again the FPU's default evaluation of that formula would provide substantially enhanced numerical integrity over mere double-precision evaluation.

On most machines, straightforward algorithms will not deliver consistently correct results (and will not indicate when they are incorrect). To obtain correct results on traditional machines under all conditions usually requires sophisticated numerical techniques that go beyond typical programming practice. General application programmers using straightforward algorithms will produce much more reliable programs using the Intel architectures. This simple fact greatly reduces the software investment required to develop safe, accurate computation-based products.

Beyond traditional numerics support for scientific applications, the Intel architectures have built-in facilities for commercial computing. They can process decimal numbers of up to 18 digits without round-off errors, performing *exact arithmetic* on integers as large as  $2^{64}$  or  $10^{18}$ . Exact arithmetic is vital in accounting applications where rounding errors may introduce monetary losses that cannot be reconciled.

The Intel FPU's contain a number of optional numerical facilities that can be invoked by sophisticated users. These advanced features include directed rounding, gradual underflow, and programmed exception-handling facilities.

These automatic exception-handling facilities permit a high degree of flexibility in numeric processing software, without burdening the programmer. While performing numeric calculations, the processor automatically detects exception conditions that can potentially damage a calculation (for example,  $X \div 0$  or  $\sqrt{X}$  when  $X < 0$ ). By default, on-chip exception logic handles these exceptions so that a reasonable result is produced and execution may proceed without program interruption. Alternatively, the processor can invoke a software exception handler to provide special results whenever various types of exceptions are detected.

#### 6.1.4. Applications

The Pentium processor FPU's versatility and performance make it appropriate for a broad array of numeric applications. In general, applications that exhibit any of the following characteristics can benefit by implementing numeric processing:

- Numeric data vary over a wide range of values, or include nonintegral values.
- Algorithms produce very large or very small intermediate results.
- Computations must be very precise; i.e., a large number of significant digits must be maintained.
- Performance requirements exceed the capacity of traditional microprocessors.
- Consistently safe, reliable results must be delivered using a programming staff that is not expert in numerical techniques.

Note also that the software development costs can be reduced and performance of systems improved that use not only real numbers, but operate on multiprecision binary or decimal integer values as well.

A few examples, which show how the Pentium processor might be used in specific numerics applications, are described below.

- Business data processing—The FPU's ability to accept decimal operands and produce *exact* decimal results of up to 18 digits greatly simplifies accounting programming. Financial calculations that use power functions can take advantage of the Intel architecture's exponentiation and logarithmic instructions. Many business software packages can benefit from the speed and accuracy of the FPU.
- Simulation—The large (32-bit) memory space and raw speed of the processor make it suitable for attacking large simulation problems, which heretofore could only be executed on expensive mini and mainframe computers. For example, complex electronic circuit simulations using SPICE can be performed. Simulation of mechanical systems using finite element analysis can employ more elements, resulting in more detailed analysis or simulation of larger systems.
- Graphics transformations—The FPU can be used in graphics applications such as computer-aided design (CAD), with the FPU performing many functions concurrently



with the execution of integer instructions; these functions include rotation, scaling, and interpolation.

- Process control—The FPU solves dynamic range problems automatically, and its extended precision allows control functions to be fine-tuned for more accurate and efficient performance. Using the Pentium processor to implement control algorithms also contributes to improved reliability and safety, while the processor's speed can be exploited in real-time operations.
- Computer numerical control (CNC)—The FPU can move and position machine tool heads with accuracy in real time. Axis positioning also benefits from the hardware trigonometric support provided by the FPU.
- Robotics—The powerful computational abilities of the Pentium processor FPU are ideal for on-board six-axis positioning.
- Navigation—Very small, lightweight, and accurate inertial guidance systems can be implemented with the FPU. Its built-in trigonometric functions can speed and simplify the calculation of position from bearing data.
- Data acquisition—The FPU can be used to scan, scale, and reduce large quantities of data as it is collected, thereby lowering storage requirements and time required to process the data for analysis.
- Digital Signal Processing (DSP)—All DSP-related applications, such as matrix multiplication and convolution, can benefit from the pipelined instruction implementation of the Pentium processor.

The preceding examples are oriented toward traditional numerics applications. There are, in addition, many other types of systems that do not appear to the end user as computational, but can employ the 32-bit Intel architecture's numerical capabilities to advantage. The imaginative system designer has an opportunity similar to that created by the introduction of the microprocessor itself. Many applications can be viewed as numerically-based if sufficient computational power is available to support this view (e.g., character generation for a laser printer). This is analogous to the thousands of successful products that have been built around "buried" microprocessors, even though the products themselves bear little resemblance to computers.

### 6.1.5. Programming Interface

The Intel architectures have a class of instructions known as ESCAPE instructions, all having a common format. These ESC instructions are numeric instructions for the FPU. These numeric instructions are part of a single integrated instruction set.

Numeric processing centers around the floating-point register stack. Programmers can treat these eight 80-bit registers either as a fixed register set, with instructions operating on explicitly-designated registers, or as a classical stack, with instructions operating on the top one or two stack elements.

Internally, the FPU holds all numbers in a uniform 80-bit extended format. Operands that may be represented in memory as 16-, 32-, or 64-bit integers, 32-, 64-, or 80-bit floating-point numbers, or 18-digit packed BCD numbers, are automatically converted into extended format as they are loaded into the FPU registers. Computation results are subsequently converted back into one of these destination data formats when they are stored into memory from the FPU registers.

Table 6-2 lists each of the seven numeric data types supported by the FPU, showing the data format for each type. The table also shows the approximate range of normalized values that can be represented with each type. Denormal values are also supported in each of the real types, as required by IEEE Std 854. Denormals are discussed later in this chapter.

**Table 6-2. Numeric Data Types**

Data Type	Bits	Significant Digits (Decimal)	Approximate Normalized Range (Decimal)
Word integer	16	4	$-32,768 \leq x \leq +32,767$
Short integer	32	9	$-2 \times 10^9 \leq x \leq +2 \times 10^9$
Long integer	64	18	$-9 \times 10^{18} \leq x \leq +9 \times 10^{18}$
Packed decimal	80	18	$-99...99 \leq x \leq +99...99$ (18 digits)
Single real	32	7	$1.18 \times 10^{-38} <  x  < 3.40 \times 10^{38}$
Double real	64	15-16	$2.23 \times 10^{-308} <  x  < 1.79 \times 10^{308}$
Extended real*	80	19	$3.37 \times 10^{-4932} <  x  < 1.18 \times 10^{4932}$

\* Equivalent to *double extended* format of IEEE Std 854.

All operands are stored in memory with the least significant digits starting at the initial (lowest) memory address. Numeric instructions access and store memory operands using only this initial address. See Chapter 24 for alignment strategies for the different processors.

Table 6-3 lists the numeric instructions by class. No special programming tools are necessary to use the numerical capabilities, because all of the numeric instructions and data types are directly supported by the Intel ASM386/ASM486 Assembler, by high-level languages from Intel, and by assemblers and compilers produced by many independent software vendors. Numeric routines can be written in assembly language or any of the following higher-level languages from Intel:

- PL/M-386/486
- C-386/486
- FORTRAN-386/486
- ADA-386/486

**Table 6-3. Principal Numeric Instructions**

Class	Instruction Types
Data Transfer	Load (all data types), Store (all data types), Exchange
Arithmetic	Add, Subtract, Multiply, Divide, Subtract Reversed, Divide Reversed, Square Root, Scale, Extract, Remainder, Integer Part, Change Sign, Absolute Value
Comparison	Compare, Examine, Test
Transcendental	Tangent, Arctangent, Sine, Cosine, Sine and Cosine, $2^X - 1$ , $Y \cdot \text{Log}_2(X)$ , $Y \cdot \text{Log}_2(X+1)$
Constants	0, 1, $\pi$ , $\text{Log}_{10}2$ , $\text{Log}_e2$ , $\text{Log}_210$ , $\text{Log}_2e$
Processor Control	Load Control Word, Store Control Word, Store Status Word, Load Environment, Store Environment, Save, Restore, Clear Exceptions, Initialize

All of these high-level languages provide programmers with access to the computational power and speed of the 32-bit Intel architectures without requiring an understanding of its architecture. Such architectural considerations as concurrency and synchronization are handled automatically by these high-level languages. For the assembly language programmer, specific rules for handling these issues are discussed in a later section of this manual.

## 6.2. ARCHITECTURE OF THE FLOATING-POINT UNIT

To the programmer, the FPU appears as a set of additional registers, data types, and instructions. Refer to Chapter 25 for detailed explanations of the numerical instruction set. This section explains the numerical registers and data types of the FPU architecture.

### 6.2.1. Numerical Registers

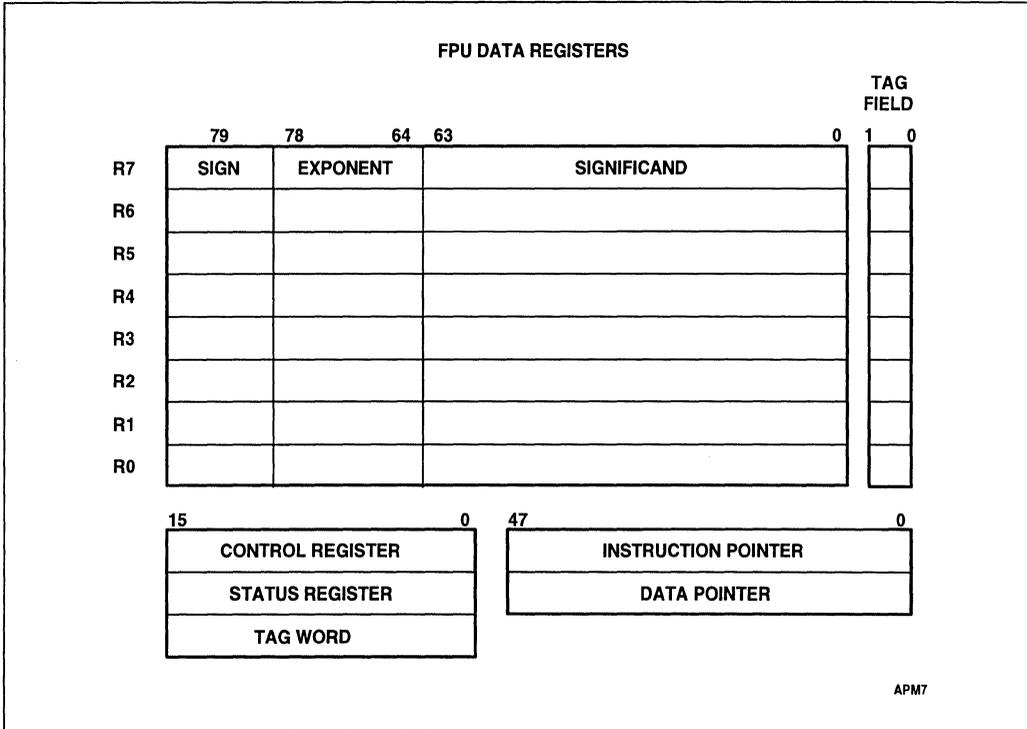
The numerical registers consist of:

- Eight individually-addressable 80-bit numeric registers, organized as a register stack.
- Three 16-bit registers containing:
  - The FPU status word.
  - The FPU control word.
  - The tag word.
- Error pointers, consisting of:
  - Two 16-bit registers containing selectors for the last instruction and operand.
  - Two 32-bit registers containing offsets for the last instruction and operand.
  - One 11-bit register containing the opcode of the last non-control FPU instruction.

All of the numeric instructions focus on the contents of these FPU registers.

### 6.2.1.1. THE FPU REGISTER STACK

The FPU register stack is shown in Figure 6-1. Each of the eight numeric registers in the stack is 80 bits wide and is divided into fields corresponding to the processor's extended real data type.



**Figure 6-1. Floating-Point Unit Register Set**

Numeric instructions address the data registers relative to the register on the top of the stack. At any point in time, this top-of-stack register is indicated by the TOP (stack TOP) field in the FPU status word. Load or push operations decrement TOP by one and load a value into the new top register. A store-and-pop operation stores the value from the current TOP register and then increments TOP by one. Like stacks in memory, the FPU register stack grows *down* toward lower-addressed registers.

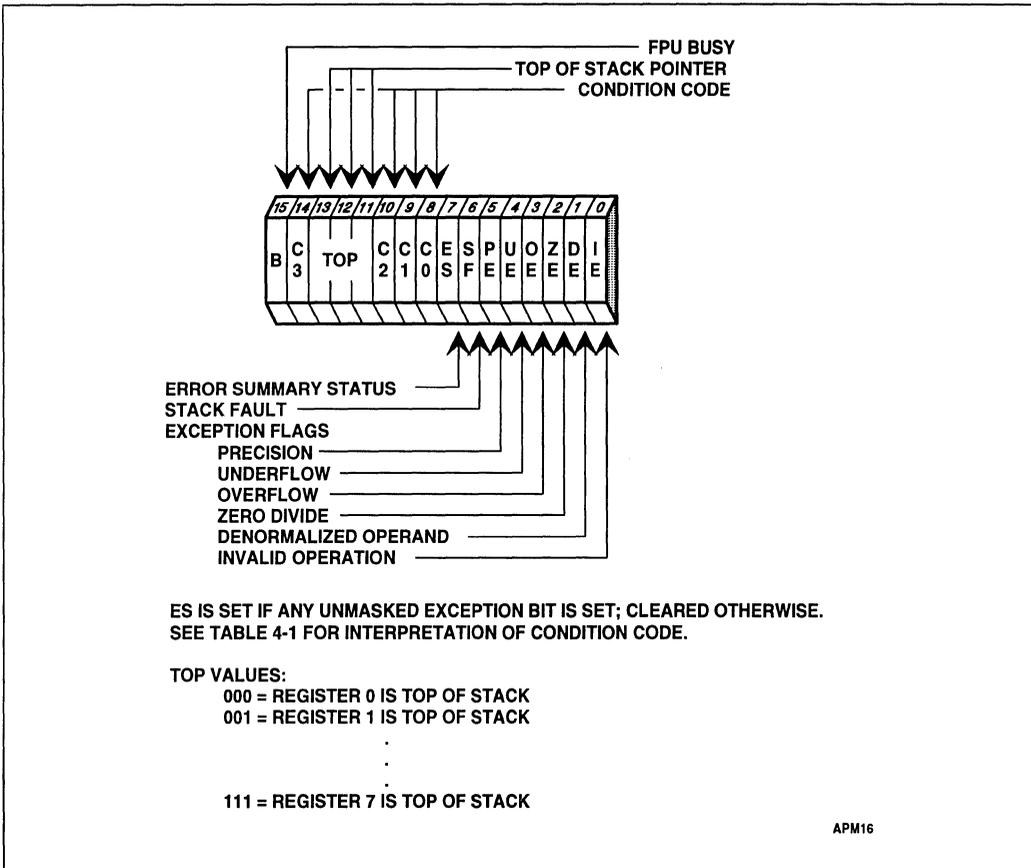
Many numeric instructions have several addressing modes that permit the programmer to implicitly operate on the top of the stack, or to explicitly operate on specific registers relative to the TOP. The ASM386/486 Assembler supports these register addressing modes, using the expression ST(0), or simply ST, to represent the current Stack Top and ST(*i*) to specify the *i*th register from TOP in the stack ( $0 \leq i \leq 7$ ). For example, if TOP contains 011B (register 3 is the top of the stack), the following statement would add the contents of two registers in the stack (registers 3 and 5):

```
FADD ST, ST(2)
```

The stack organization and top-relative addressing of the numeric registers can simplify subroutine programming by allowing routines to pass parameters on the register stack. By using the stack to pass parameters rather than using "dedicated" registers, calling routines gain flexibility in how they use the stack. As long as the stack is not full, each routine simply loads the parameters onto the stack before calling a particular subroutine to perform a numeric calculation. The subroutine then addresses its parameters as ST, ST(1), etc., even though TOP may, for example, refer to physical register 3 in one invocation and physical register 5 in another. Programmers can use the numeric registers like a conventional stack as described herein, or by using the pipelined architecture of the Pentium processor in conjunction with the FXCH instruction, reduce stack bottleneck and move towards a random register machine.

### **6.2.1.2. THE FPU STATUS WORD**

The 16-bit status word shown in Figure 6-2 reflects the overall state of the FPU. This status word may be stored into memory using the FSTSW/FNSTSW, FSTENV/FNSTENV, and FSAVE/FNSAVE instructions, and can be transferred into the AX register with the FSTSW AX/FNSTSW AX instructions, allowing the FPU status to be inspected by the Integer Unit.



**Figure 6-2. FPU Status Word**

The four FPU condition code bits ( $C_3-C_0$ ) are similar to the flags in a CPU: the processor updates these bits to reflect the outcome of arithmetic operations. The effect of these instructions on the condition code bits is summarized in Table 6-4. These condition code bits are used principally for conditional branching. The FSTSW AX instruction stores the FPU status word directly into the AX register, allowing these condition codes to be inspected efficiently. The SAHF instruction can copy  $C_3-C_0$  directly to the CPU's flag bits to simplify conditional branching. Table 6-5 shows the mapping of these bits to the CPU flag bits.

Bits 11-13 of the status word point to the FPU register that is the current Top of Stack (TOP). The significance of the stack top has been described in the prior section on the register stack.

Figure 6-2 shows the six exception flags in bits 0-5 of the status word. Bit 7 is the exception summary status (ES) bit. ES is set if any unmasked exception bits are set, and is cleared otherwise. Bits 0-5 indicate whether the FPU has detected one of six possible exception conditions since these status bits were last cleared or reset. (For definitions of exceptions,

refer to Chapter 7.) They are "sticky" bits, and can only be cleared by the instructions FINIT, FCLEX, FLDENV, FSAVE, and FRSTOR.

The B-bit (bit 15) is included for 8087 compatibility only. It reflects the contents of the ES bit (bit 7 of the status word).

Bit 6 is the stack fault (SF) bit. This bit distinguishes invalid operations due to stack overflow or underflow from other kinds of invalid operations. When SF is set, bit 9 ( $C_1$ ) distinguishes between stack overflow ( $C_1 = 1$ ) and underflow ( $C_1 = 0$ ).

### 6.2.1.3. CONTROL WORD

The FPU provides the programmer with several processing options, which are selected by loading a word from memory into the control word. Figure 6-3 shows the format and encoding of the fields in the control word.

The low-order byte of this control word configures the numerical exception masking. Bits 0–5 of the control word contain individual masks for each of the six floating-point exception conditions recognized by the processor. The high-order byte of the control word configures the FPU processing options, including

- Precision control
- Rounding control

The precision-control bits (bits 8–9) can be used to set the FPU internal operating precision at less than the default precision (64-bit significand). These control bits can be used to provide compatibility with the earlier-generation arithmetic processors having less precision than the Intel 32-bit FPU's. The precision-control bits affect the results of only the following five arithmetic instructions: ADD, SUB(R), MUL, DIV(R), and SQRT. No other operations are affected by PC.

The rounding-control bits (bits 10–11) provide for the common round-to-nearest mode, as well as directed rounding and true chop. Rounding control affects the arithmetic instructions (refer to Section 6.3. in this chapter for lists of arithmetic and nonarithmetic instructions) and certain nonarithmetic instructions, namely (FLD constant) and (FST(P)mem) instructions.

**Table 6-4. Condition Code Interpretation**

Instruction	C0	C3	C2	C1
FCOM, FCOMP, FCOMPP, FTST, FUCOMPP, FICOM, FICOMP	Result of Comparison		Operands is not Comparable	Zero or O/U#
FXAM	Operand class			Sign or O/U#
FPREM, FPREM1	Q2	Q1	0=reduction complete 1=reduction incomplete	Q0 or O/U#
FIST, FBSTP, FRINDINT, FST, FSTP, FADD, FMUL, FDIV, FDIVR, FSUB, FSUBR, FSCALE, FSQRT, FPATAN, F2XM1, FYL2X, FYL2XP1	UNDEFINED			Roundup or O/U#
FPTAN, FSIN, FCOS, FSINCOS	UNDEFINED		0=reduction complete 1=reduction incomplete	Roundup or O/U# (UNDEFINED) if C2=1)
FCHS, FABS, FXCH, FINCSTP, FDECSTP, Constant Loads, FXTRACT, FLD, FILD, FBLD, FSTP (ext. real)	UNDEFINED			Zero or O/U#
FLDENV, FRSTOR	Each bit loaded from memory			
FLDCW, FSTENV, FSTCW, FSTSW, FCLEX	UNDEFINED			
FINIT, FSAVE	Zero	Zero	Zero	Zero

**NOTES:**

O/U# — When both IE and SF bits of status word are set, indicating a stack exception, this bit distinguishes between stack overflow (C1=1) and underflow (C1=0).

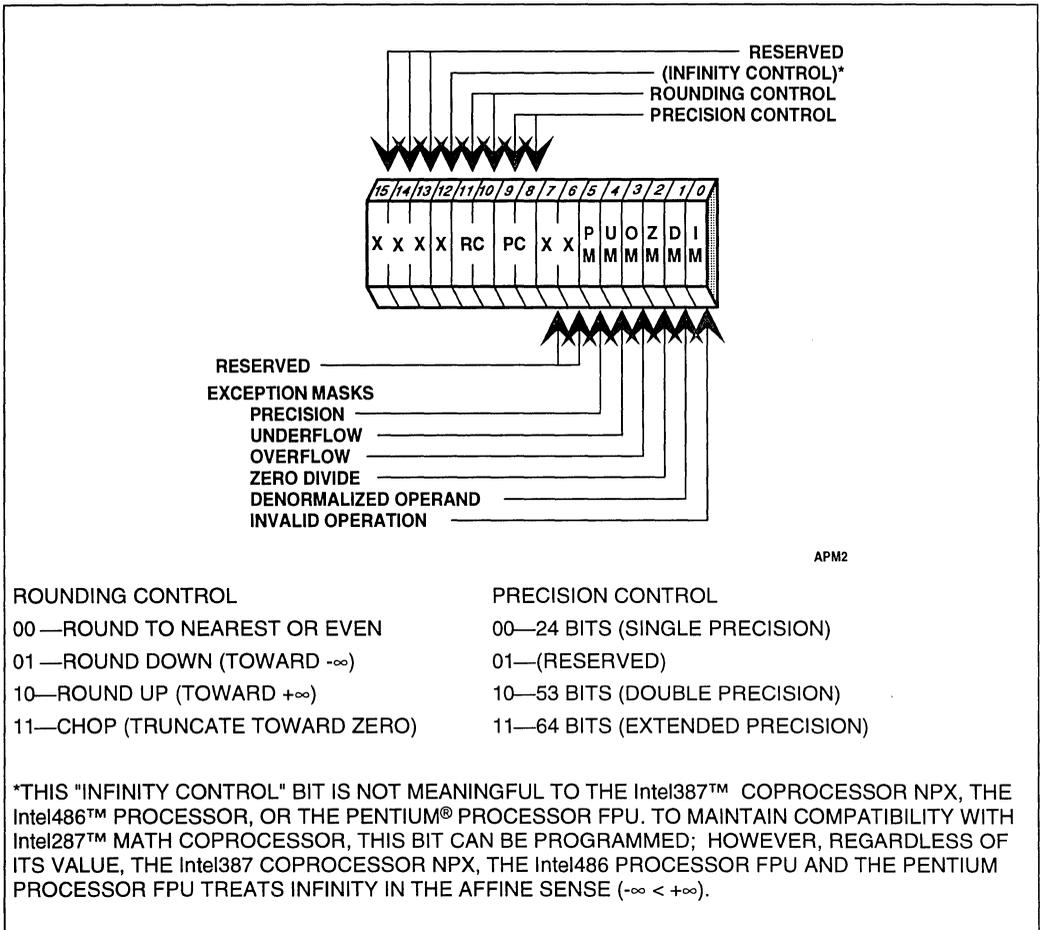
Reduction — If FPREM and FPREM1 produces a remainder that is less than the modulus, reduction is complete. When reduction is incomplete the value at the top of the stack is a partial remainder, which can be used as input to further reduction. For FPTAN, FSIN, FCOS and FSINCOS, the reduction bit is set if the operand at the top of the stack is too large. In this case, the original operand remains at the top of the stack.

Roundup — When the PE bit of the status word is set, this bit indicates whether the last rounding in the instruction was upward.

UNDEFINED — Do not rely on any specific value in these bits.

**Table 6-5. Correspondence Between FPU and IU Flag Bits**

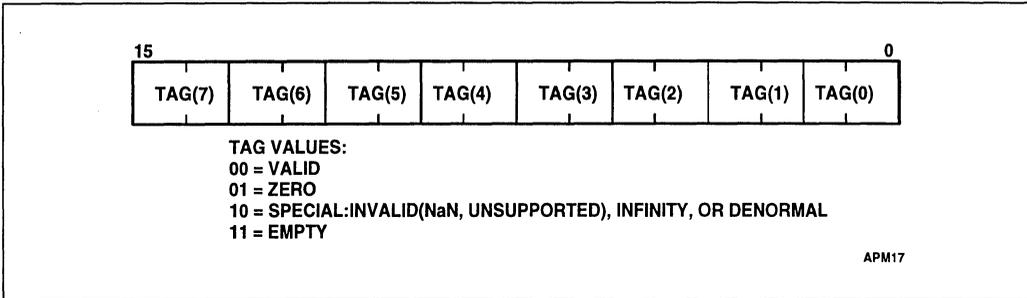
FPU Flag	IU Flag
C0	CF
C1	(none)
C2	PF
C3	ZF



**Figure 6-3. FPU Control Word Format**

### 6.2.1.4. THE FPU TAG WORD

The tag word (TW) indicates the contents of each register in the register stack, as shown in Figure 6-4. The TW is used by the FPU itself to distinguish between empty and nonempty register locations. Programmers of exception handlers may use this tag information to check the contents of a numeric register without performing complex decoding of the actual data in the register. The tag values from the TW correspond to physical registers 0–7. Programmers must use the current top-of-stack (TOP) pointer stored in the FPU status word to associate these tag values with the relative stack registers ST(0) through ST(7).



**Figure 6-4. Tag Word Format**

The exact values of the tags are generated during execution of the FSTENV and FSAVE instructions according to the actual contents of the nonempty stack locations. During execution of other instructions, the processor updates the TW only to indicate whether a stack location is empty or nonempty. As a result, the FPU tag word may not be the same as previously written when saving the FPU state, modifying the tag word, and reloading the FPU state. This can be demonstrated using the following steps to modify the FPU tag word. This example assumes FPU register 0 has the value 0 and tag(0)=11 (empty). Example 6-1 contains the actual assembly code to perform these steps.

1. FSAVE/FSTENV stores FPU state to memory M. M[tag(0)]=11 (empty).
2. Modify memory such that M[tag(0)]=10 (i.e., special, infinity, or denormal).
3. FLDENV loads fp state from memory M to FPU.
4. FSAVE/FSTENV stores FPU state to memory M again. The value of M[tag(0)] will be 01 (i.e., indicates zero because FPU register 0 has the value of 0).

**Example 6-1. Modifying the Tag Word**

```
name tagword

stack stackseg 100

data segment rw use16
fpstate dw 7 dup (?)
fpstate2 dw 7 dup (?)
```

```

data ends

code segment er public use16
    assume ds:data, ss:stack
start:
mov     ax,data
mov     ds,ax                ; set segment register

finit                    ; initialize FPU
fldz                    ; load zero
mov     bx, offset fpstate
fsave  [bx]              ; save FPU state

mov     ax,[bx+4]         ; tag word, AX should be 7FFFh,
                        ; top of the fp stack has
                        ; zero value and the rest are empty

mov     word ptr [bx+4], 3FFFh ; now change the zero tag (01) to
                        ; the valid tag (00)

fldenv [bx]
mov     bx, offset fpstate2 ; now the tag word is 3FFFh
fsave  [bx]              ; but we are saving 7FFFh to tag
                        ; word

code     ends
end start, ds:data, ss:stack

```

### 6.2.1.5. OPCODE FIELD OF LAST INSTRUCTION

The opcode field in Figure 6-5 describes the 11-bit format of the last non-control FPU instruction executed. The first and second instruction bytes (after all prefixes) are combined to form the opcode field. Since all floating-point instructions share the same five upper bits in the first instruction byte (following prefixes), they are not stored in the opcode field. Note that the second instruction byte is actually located in the low-order byte of the stored opcode field.

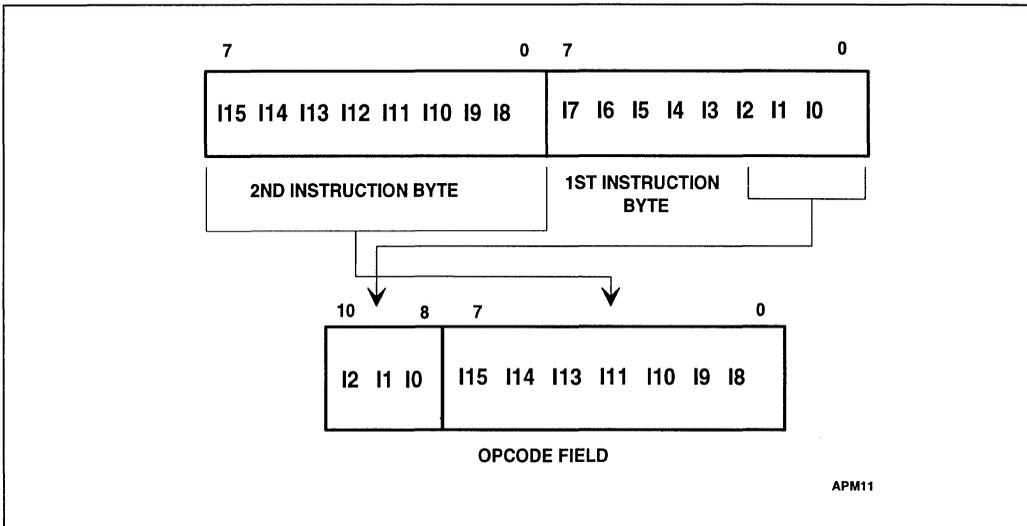


Figure 6-5. Opcode Field

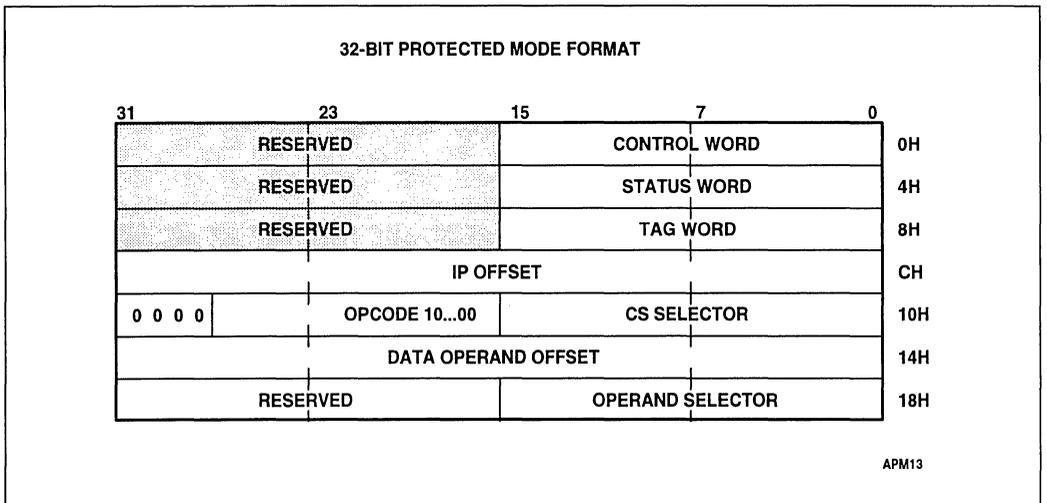
### 6.2.1.6. THE NUMERIC INSTRUCTION AND DATA POINTERS

The instruction and data pointers provide support for programmed exception-handlers. Whenever the processor decodes an ESC instruction other than FINIT, FCLEX, FLDCW, FSTCW, FSTSW, FSTSWAX, FSTENV, FLDENV, FSAVE, FRSTOR, and FWAIT, it saves the instruction address opcode and the operand address (if present) in registers that can be accessed by the user. Contents of these registers remain unchanged when any of the control instructions listed above is executed. Contents of the operand address register are undefined if the prior ESC instruction (which is not one of the above) did not have a memory operand.

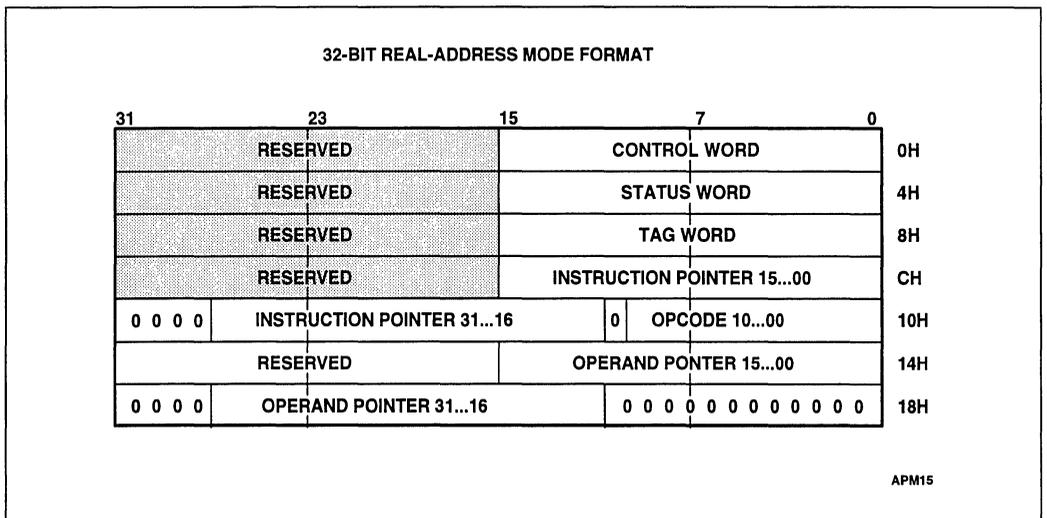
These registers can be accessed by the ESC instructions FSTENV, FLDENV, FSAVE and FRSTOR. The FINIT and FSAVE instructions clear these registers after writing them to memory.

When stored in memory, the instruction and data pointers appear in one of four formats, depending on the operating mode of the processor (protected mode or real-address mode) and depending on the operand-size attribute in effect (32-bit operand or 16-bit operand). In virtual-8086 mode, the real-address mode formats are used. Figures 6-6 through Figure 6-9 show these pointers as they are stored following an FSTENV instruction. The FSTENV and FSAVE instructions store this data into memory, allowing exception handlers to determine the precise nature of any numeric exceptions that may be encountered.

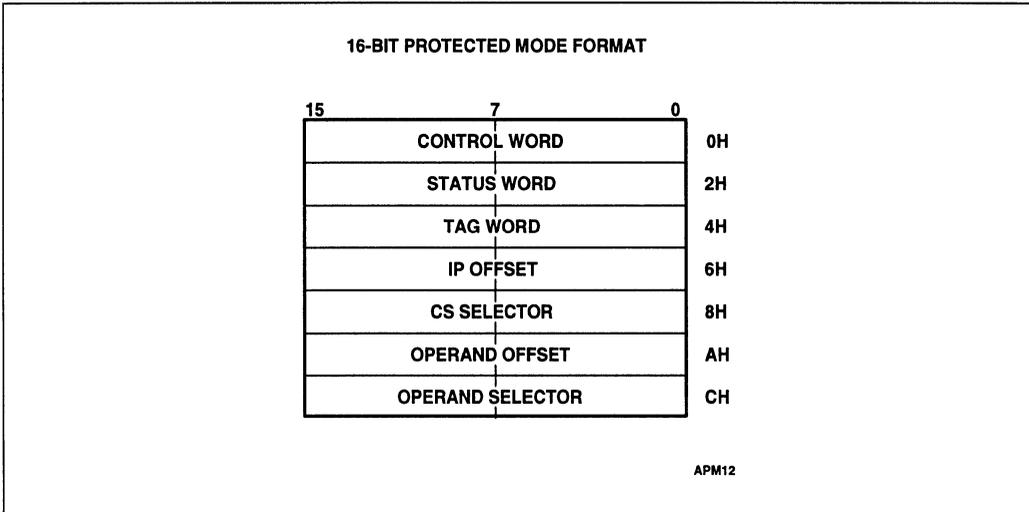
For all the Intel FPU and NPX architectures, the instruction address saved points to any prefixes that preceded the instruction, except the 8087, for which the instruction address points only to the ESC instruction opcode.



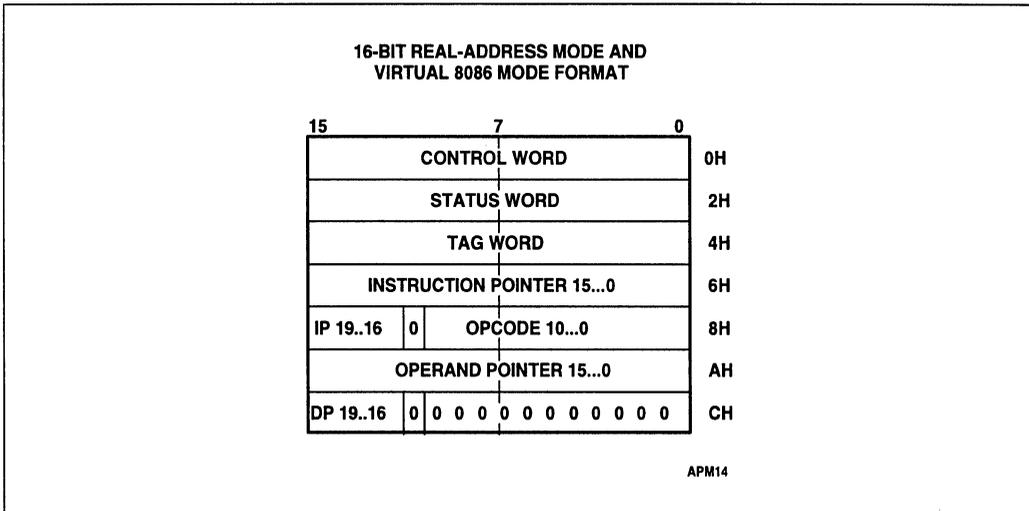
**Figure 6-6. Protected-Mode Numeric Instruction and Data Pointer Image in Memory, 32-Bit Format**



**Figure 6-7. Real Mode Numeric Instruction and Data Pointer Image in Memory, 32-Bit Format**



**Figure 6-8. Protected-Mode Numeric Instruction and Data Pointer Image in Memory, 16-Bit Format**



**Figure 6-9. Real Mode Numeric Instruction and Data Pointer Image in Memory, 16-Bit Format**



## 6.2.2. Computation Fundamentals

This section covers numeric programming concepts that are common to all applications. It describes the FPU's internal number system and the various types of numbers that can be employed in numeric programs. The most commonly used options for rounding and precision (selected by fields in the control word) are described, with exhaustive coverage of less frequently used facilities deferred to later sections. Exception conditions that may arise during execution of floating-point instructions are also described along with the options that are available for responding to these exceptions.

### 6.2.2.1. NUMBER SYSTEM

The system of real numbers that people use for pencil and paper calculations is conceptually infinite and continuous. There is no upper or lower limit to the magnitude of the numbers one can employ in a calculation, or to the precision (number of significant digits) that may be required to represent them. For any given real number, there are always arbitrarily many numbers both larger and smaller. There are also arbitrarily many numbers between any two real numbers. For example, between 2.5 and 2.6 are 2.51, 2.5897, 2.500001, etc.

While ideally it would be desirable for a computer to be able to operate on the entire real number system, in practice this is not possible. Computers, no matter how large, ultimately have fixed-size registers and memories that limit the system of numbers that can be accommodated. These limitations determine both the range and the precision of numbers. The result is a set of numbers that is finite and discrete, rather than infinite and continuous. This sequence is a subset of the real numbers that is designed to form a useful approximation of the real number system.

Figure 6-10 superimposes the basic floating-point number system on a real number line (decimal numbers are shown for clarity, although the processor actually represents numbers in binary). The dots indicate the subset of real numbers the processor can represent as data and final results of calculations. The range of double-precision, normalized numbers is approximately  $\pm 2.23 \times 10^{-308}$  to  $\pm 1.79 \times 10^{308}$ . Applications that are required to deal with data and final results outside this range are rare.

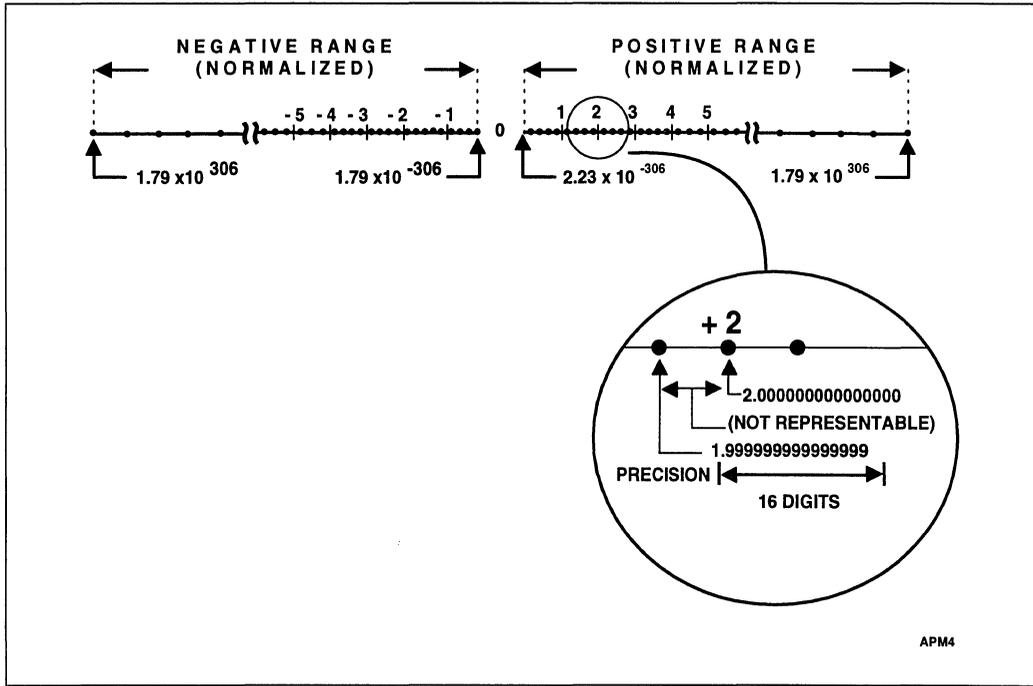


Figure 6-10. Double-Precision Number System

The finite spacing in Figure 6-10 illustrates that the FPU can represent a great many, but not all, of the real numbers in its range. There is always a gap between two adjacent floating-point numbers, and it is possible for the result of a calculation to fall in this space. When this occurs, the FPU rounds the true result to a number that it can represent. Thus, a real number that requires more digits than the FPU can accommodate (e.g., a 20-digit number) is represented with some loss of accuracy. Notice also that the representable numbers are not distributed evenly along the real number line. In fact, the same number of representable numbers exists between any two successive powers of 2 (i.e., as many representable numbers exist between 2 and 4 as between 65,536 and 131,072). Therefore, the gaps between representable numbers are larger as the numbers increase in magnitude. All integers in the range  $\pm 2^{64}$  (approximately  $\pm 10^{19}$ ), however, are exactly representable.

In its internal operations, the FPU actually employs a number system that is a substantial superset of that shown in Figure 6-10. The internal format (called extended real) extends the representable (normalized) range to about  $\pm 3.37 \times 10^{-4932}$  to  $\pm 1.18 \times 10^{4932}$ , and its precision to about 19 (equivalent decimal) digits. This format is designed to provide extra range and precision for constants and intermediate results, and is not normally intended for data or final results.

From a practical standpoint, the processor's set of real numbers is sufficiently large and dense so as not to limit the vast majority of applications. Compared to most computers, including mainframes, the processor provides a very good approximation of the real number system. It

is important to remember, however, that it is not an exact representation, and that computer arithmetic on real numbers is inherently approximate.

### 6.2.2.2. DATA TYPES AND FORMATS

The processor recognizes seven numeric data types for memory-based values, divided into three classes: binary integers, packed decimal integers, and binary reals. How these formats are stored in memory are discussed later in this section (the sign is always located in the highest-addressed byte).

Figure 6-11 summarizes the format of each data type. In the figure, the most significant digits of all numbers (and fields within numbers) are the leftmost digits.

#### 6.2.2.2.1. Binary Integers

The three binary integer formats are identical except for length, which governs the range that can be accommodated in each format. The leftmost bit is interpreted as the number's sign: 0=positive and 1=negative. Negative numbers are represented in standard two's complement notation (the binary integers are the only format to use two's complement). The quantity zero is represented with a positive sign (all bits are 0). The word integer format is identical to the 16-bit signed integer data type; the short integer format is identical to the 32-bit signed integer data type.

The binary integer formats exist in memory only. When used by the FPU, they are automatically converted to the 80-bit extended real format. All binary integers are exactly representable in the extended real format.

#### 6.2.2.2.2. Decimal Integers

Decimal integers are stored in packed decimal notation, with two decimal digits "packed" into each byte, except the leftmost byte, which carries the sign bit (0=positive, 1=negative). Negative numbers are not stored in two's complement form and are distinguished from positive numbers only by the sign bit. The most significant digit of the number is the leftmost digit. All digits must be in the range 0–9.

DATA FORMATS	RANGE	PRECISION	MOST SIGNIFICANT BYTE				LOWEST ADDRESSED BYTE																
			7	0	7	0	7	0	7	0	7	0	7	0	7	0	7	0					
WORD INTEGER	$10^4$	16 BITS																					
SHORT INTEGER	$10^9$	32 BITS																					
LONG INTEGER	$10^{18}$	64 BITS																					
PACKED BCD	$10^{18}$	18 DIGITS	S	X	d <sub>17</sub>	d <sub>16</sub>	d <sub>15</sub>	d <sub>14</sub>	d <sub>13</sub>	d <sub>12</sub>	d <sub>11</sub>	d <sub>10</sub>	d <sub>9</sub>	d <sub>8</sub>	d <sub>7</sub>	d <sub>6</sub>	d <sub>5</sub>	d <sub>4</sub>	d <sub>3</sub>	d <sub>2</sub>	d <sub>1</sub>	d <sub>0</sub>	
SINGLE PRECISION	$10^{\pm 38}$	24 BITS	S	BIASED EXPONENT			SIGNIFICAND																
DOUBLE PRECISION	$10^{\pm 308}$	53 BITS	S	BIASED EXPONENT			SIGNIFICAND																
EXTENDED PRECISION	$10^{\pm 4932}$	64 BITS	S	BIASED EXPONENT			1	SIGNIFICAND															

- (1) S = SIGN BIT (0 = positive, 1 = negative)
- (2) dn = DECIMAL DIGIT (TWO PER BYTE)
- (3) X = BITS HAVE NO SIGNIFICANCE; IGNORES WHEN LOADING, ZEROS WHEN STORING
- (4) D = POSITION OF IMPLICIT BINARY POINT
- (5) I = INTEGER BIT OF SIGNIFICAND; STORED IN TEMPORARY REAL, IMPLICIT IN SINGLE AND DOUBLE PRECISION
- (6) EXPONENT BIAS (NORMALIZED VALUES):  
 SINGLE: 127 (7FH)  
 DOUBLE: 1023 (3FFH)  
 EXTENDED REAL: 16383 (3FFFH)
- (7) PACKED BCD: (-1) (D ... D)
- (8) REAL: (-1) (2E-BIAS) (F F ...)

APM3

Figure 6-11. Numerical Data Formats

The decimal integer format exists in memory only. When used by the FPU, it is automatically converted to the 80-bit extended real format. All decimal integers are exactly representable in the extended real format.

**6.2.2.2.3. Real Numbers**

The processor represents real numbers of the form:

$$(-1)^s 2^E (b_0 \Delta b_1 b_2 b_3 \dots b_{p-1})$$

where:

s = 0 or 1

E = any integer between Emin and Emax, inclusive

b<sub>i</sub> = 0 or 1

p = number of bits of precision

Table 6-6 summarizes the parameters for each of the three real-number formats.

The Pentium processor stores real numbers in a three-field binary format that resembles scientific, or exponential, notation. The format consists of the following fields:

- The *significand* field,  $b_0 \Delta b_1 b_2 b_3 \dots b_{p-1}$ , is the number's significant digits. (The term "significand" is analogous to the term "mantissa" used to describe floating-point numbers on some computers.)
- The *exponent* field,  $e = E + \text{bias}$ , locates the binary point within the significant digits (and therefore determines the number's magnitude). (The term "exponent" is analogous to the term "characteristic" used to describe floating-point numbers on some computers.)
- The 1-bit *sign* field, which indicates whether the number is positive or negative. Negative numbers differ from positive numbers only in the sign bits of their significands.

**Table 6-6. Summary of Format Parameters**

Parameter	Format		
	Single	Double	Extended
Format width in bits	32	64	80
p (bits of precision)	24	53	64
Exponent width in bits	8	11	15
Emax	+127	+1023	+16383
Emin	-126	-1022	-16382
Exponent bias	+127	+1023	+16383

Table 6-7 shows how the real number 178.125 (decimal) is stored in the single real format. The table lists a progression of equivalent notations that express the same value to show how a number can be converted from one form to another. (The ASM386/486 and PL/M386/486 language translators perform a similar process when they encounter programmer-defined real number constants.) Note that not every decimal fraction has an exact binary equivalent. The decimal number 1/10, for example, cannot be expressed exactly in binary (just as the number

1/3 cannot be expressed exactly in decimal). When a translator encounters such a value, it produces a rounded binary approximation of the decimal value.

**Table 6-7. Real Number Notation**

Notation	Value		
Ordinary Decimal	178.125		
Scientific Decimal	1 <sub>Δ</sub> 78125E2		
Scientific Binary	1 <sub>Δ</sub> 0110010001E111		
Scientific Binary (Biased Exponent)	1 <sub>Δ</sub> 0110010001E10000110		
Single Format (Normalized)	Sign	Biased Exponent	Significand
	0	10000110	01100100010000000000000 1 <sub>Δ</sub> (implicit)

The FPU usually carries the digits of the significand in normalized form. This means that, except for the value zero, the significand contains an *integer* bit and fraction bits as follows:

$$1_{\Delta} \text{fff} \dots \text{ff}$$

where  $\Delta$  indicates an assumed binary point. The number of fraction bits varies according to the real format: 23 for single, 52 for double, and 63 for extended real. By normalizing real numbers so that their integer bit is always a 1, the processor eliminates leading zeros in small values ( $|X| < 1$ ). This technique maximizes the number of significant digits that can be accommodated in a significand of a given width. Note that, in the single and double formats, the integer bit is *implicit* and is not actually stored; the integer bit is physically present in the extended format only.

If one were to examine only the significand with its assumed binary point, all normalized real numbers would have values greater than or equal to one and less than two. The exponent field locates the *actual* binary point in the significant digits. Just as in decimal scientific notation, a positive exponent has the effect of moving the binary point to the right, and a negative exponent effectively moves the binary point to the left, inserting leading zeros as necessary. An unbiased exponent of zero indicates that the position of the assumed binary point is also the position of the actual binary point. The exponent field, then, determines a real number's magnitude.

In order to simplify comparing real numbers (e.g., for sorting), the processor stores exponents in a biased form. This means that a constant, called a bias, is added to the *true exponent* described above. As Table 6-6 shows, the value of this *bias* is different for each real format. It has been chosen so as to force the *biased exponent* to be a positive value. This allows two real numbers (of the same format and sign) to be compared as if they are unsigned binary integers. That is, when comparing them bitwise from left to right (beginning with the leftmost exponent bit), the first bit position that differs orders the numbers; there is no need to proceed further with the comparison. A number's true exponent can be determined simply by subtracting the bias value of its format.



The single and double real formats exist in memory only. If a number in one of these formats is loaded into an FPU register, it is automatically converted to extended format, the format used for all internal operations. Likewise, data in registers can be converted to single or double real for storage in memory. The extended real format may be used in memory also, typically to store intermediate results that cannot be held in registers.

Most applications should use the double format to store real-number data and results; it provides sufficient range and precision to return correct results with a minimum of programmer attention. The single real format is appropriate for applications that are constrained by memory, but it should be recognized that this format provides a smaller margin of safety. It is also useful for the debugging of algorithms, because roundoff problems will manifest themselves more quickly in this format. The extended real format should normally be reserved for holding intermediate results, loop accumulations, and constants. Its extra length is designed to shield final results from the effects of rounding and overflow/underflow in intermediate calculations. However, the range and precision of the double format are adequate for most microcomputer applications.

### 6.2.2.3. ROUNDING CONTROL

Internally, the FPU employs three extra bits (guard, round, and sticky bits) that enable it to round numbers in accord with the infinitely precise true result of a computation; these bits are not accessible to programmers. Whenever the destination can represent the infinitely precise true result, the FPU delivers it. Rounding occurs in arithmetic and store operations when the format of the destination cannot exactly represent the infinitely precise true result. For example, a real number may be rounded if it is stored in a shorter real format, or in an integer format. Or, the infinitely precise true result may be rounded when it is returned to a register.

The FPU has four rounding modes, selectable by the RC field in the control word (see Figure 6-3). Given a true result  $b$  that cannot be represented by the target data type, the FPU determines the two representable numbers  $a$  and  $c$  that most closely bracket  $b$  in value ( $a < b < c$ ). The processor then rounds (changes)  $b$  to  $a$  or to  $c$  according to the mode selected by the RC field as shown in Table 6-8. Rounding introduces an error in a result that is less than one unit in the last place to which the result is rounded.

- "Round to nearest" is the default mode and is suitable for most applications; it provides the most accurate and statistically unbiased estimate of the true result.
- The "chop" or "round toward zero" mode is provided for integer arithmetic applications.
- "Round up" and "round down" are termed *directed rounding* and can be used to implement interval arithmetic. Interval arithmetic is used to determine upper and lower bounds for the true result of a multistep computation, when the intermediate results of the computation are subject to rounding.

Rounding control affects only the arithmetic instructions (refer to Section 6.3. in this chapter for lists of arithmetic and nonarithmetic instructions).

**Table 6-8. Rounding Modes**

RC Field	Rounding Mode	Rounding Action
00	Round to Nearest	Closer to <i>b</i> of <i>a</i> or <i>c</i> ; if equally close, select even number (the one whose least significant bit is zero).
01	Round Down (toward $-\infty$ )	<i>a</i>
10	Round up (toward $+\infty$ )	<i>c</i>
11	Chop (toward 0)	Smaller in magnitude of <i>a</i> or <i>c</i> .

**NOTE:**  $a < b < c$ ; *a* and *c* are successive representable numbers; *b* is not representable

### 6.2.2.4. PRECISION CONTROL

The FPU allows results to be calculated with either 64, 53, or 24 bits of precision in the significand as selected by the precision control (PC) field of the control word. The default setting (following FINIT), and the one that is best suited for most applications, is the full 64 bits of significance provided by the extended real format. The other settings are required by the IEEE standard and are provided to obtain compatibility with the specifications of certain existing programming languages. Specifying less precision nullifies the advantages of the extended format's extended fraction length. When reduced precision is specified, the rounding of the fractional value clears the unused bits on the right to zeros. Precision Control affects only the instructions FADD, FSUB, FMUL, FDIV, and FSQRT.

## 6.3. FLOATING-POINT INSTRUCTION SET

The floating-point instructions available on the Pentium processor can be grouped into six functional classes:

- Data Transfer Instructions
- Nontranscendental Instructions
- Comparison Instructions
- Transcendental Instructions
- Constant Instructions
- Control Instructions

In this chapter, the instruction classes are described as a collection of resources available to programmers. For details of format, encoding, and execution times, see the instruction reference pages in Chapter 25.

The Intel387 math coprocessors and the Intel486 and Pentium processors FPU's have more instructions than the 8087/Intel287 math coprocessors. Some Intel386 DX microprocessor systems use an Intel287 math coprocessor. See Chapter 5 for examples of how to identify the processor type and determine what instructions are available.

### 6.3.1. Source and Destination Operands

The typical floating-point instruction takes one or two operands, which can come from the FPU register stack or from memory. Many instructions, such as FSIN, automatically operate on the top FPU stack element. Others allow, or require, the programmer to code the operand(s) explicitly along with the instruction mnemonic. Still others accept one explicit operand and one implicit operand (usually the top FPU stack element).

Whether specified by the programmer or supplied by default, floating-point operands are of two basic types, *sources* and *destinations*. A source operand provides an input to an instruction, but is not altered by its execution. Even when an instruction converts the source operand from one format to another (e.g., real to integer), the conversion is performed in an internal work area to avoid altering the source operand. A destination operand may also provide an input to an instruction; on execution, however, the instruction returns a result to the destination, overwriting its previous contents.

Many instructions allow their operands to be coded in more than one way. For example, FADD (add real) may be written without operands, with only a source, or with a destination and a source. When both destination and source operands are specified, the destination must precede the source on the command line, and both must come from the FPU stack.

Memory operands can be coded with any of the memory-addressing methods provided by the ModR/M byte. To review these methods (BASE = (INDEX X SCALE) + DISPLACEMENT), refer to Chapter 3. Floating-point instructions with memory operands either read from memory or write to it; no floating-point instruction does both. For a detailed description of each instruction, including its range of possible encodings, see the reference pages in Chapter 25.

### 6.3.2. Data Transfer Instructions

These instructions (summarized in Table 6-9) move operands among elements of the register stack, and between the stack top and memory. Any of the seven data types can be converted to extended-real and loaded (pushed) onto the stack in a single operation; they can be stored to memory in the same manner. The data transfer instructions automatically update the FPU tag word to reflect whether the register is empty or full following the instruction.

**Table 6-9. Data Transfer Instructions**

Real		Integer		Packed Decimal	
FLD	Load Real	FILD	Load Integer	FBLD	Load Packed Decimal
FST	Store Real	FIST	Store Integer		
FSTP	Store Real and Pop	FISTP	Store Integer and Pop	FBSTP	Store Packed Decimal and Pop
FXCH	Exchange register Contents				

### 6.3.3. Nontranscendental Instructions

The nontranscendental instruction set provides a wealth of variations on the basic add, subtract, multiply, and divide operations, and a number of other useful functions. These range from a simple absolute value instruction to instructions which perform exact modulo division, round real numbers to integers, and scale values by powers of two. Table 6-10 shows the nontranscendental operations provided, apart from basic arithmetic.

**Table 6-10. Nontranscendental Instructions (Besides Arithmetic)**

Mnemonic	Operation
FSQRT	Square Root
FSCALE	Scale
FEXTRACT	Extract Exponent and Significand
FPREM	Partial Remainder
FPREM1*	IEEE Standard Partial Remainder
FRNDINT	Round to Integer
FABS	Absolute Value
FCHS	Change Sign

\* Not available on 8087 or Intel287™ math coprocessor.

The basic arithmetic instructions (addition, subtraction, multiplication and division) are designed to encourage the development of very efficient algorithms. In particular, they allow the programmer to reference memory as easily as the FPU register stack. Table 6-11 summarizes the available operation/operand forms that are provided for basic arithmetic. In addition to the four normal operations, there are "reversed" subtraction and division instructions which eliminate the need for many exchanges between ST(0) and ST(1). The variety of instruction and operand forms give the programmer unusual flexibility:

- Operands can be located in registers or memory.
- Results can be deposited in a choice of registers.
- Operands can be a variety of numerical data types: extended real, double real, single real, short integer or word integer, with automatic conversion to extended real performed by the FPU.



**Table 6-11. Basic Arithmetic Instructions and Operands**

Instruction Form	Mnemonic Form	Operand Forms: Destination, Source
Classical Stack	<i>Fop</i>	{ST(1), ST}
Classical Stack, extra pop	<i>FopP</i>	{ST(1), ST}
Register	<i>Fop</i>	ST(i), ST or ST, ST(i)
Register, pop	<i>FopP</i>	ST(i), ST
Real Memory	<i>Fop</i>	{ST} single-real/double-real
Integer Memory	<i>Flop</i>	{ST} word-integer/short-integer

**NOTES:**

Braces ( { } ) surround implicit operands; these are not coded, but are supplied by the assembler.

*op* =    ADD     DEST ← DEST + SRC  
           SUB     DEST ← ST – Other Operand  
           SUBR    DEST ← Other Operand – ST  
           MUL     DEST ← DEST × SRC  
           DIV     DEST ← DEST ÷ SRC  
           DIVR    DEST ← SRC ÷ DEST

Five basic instruction forms can be used across all six operations, as shown in Table 6-11. The classical stack form can be used to make the FPU operate like a classical stack machine. No operands are coded in this form, only the instruction mnemonic. The FPU picks the source operand from the stack top (ST) and the destination from the next stack element (ST(1)). After performing its calculation, it returns the result to ST(1) and then pops ST, effectively replacing the operands by the result.

The register form is a generalization of the classical stack form; the programmer specifies the stack top as one operand and any register on the stack as the other operand. Coding the stack top as the destination provides a convenient way to access a constant, held elsewhere in the stack, from the top stack. The destination need not always be ST, however. The basic two-operand instructions allow the use of another register as the destination. Using ST as the source allows, for example, adding the stack top into a register used as an accumulator.

Often the operand in the stack top is needed for one operation but then is of no further use in the computation. The register pop form can be used to pick up the stack top as the source operand, and then discard it by popping the stack. Coding operands of ST(1), ST with a register pop mnemonic is equivalent to a classical stack operation: the top is popped and the result is left at the new top.

The two memory forms increase the flexibility of the nontranscendental instructions. They permit a real number or a binary integer in memory to be used directly as a source operand. This is useful in situations where operands are not used frequently enough to justify holding them in registers. Note that any memory-addressing method can be used to define these operands, so they can be elements in arrays, structures, or other data organizations, as well as simple scalars.

### 6.3.4. Comparison Instructions

The instructions of this class allow numbers of all supported real and integer data types to be compared. Each of these instructions (Table 6-12) analyzes the top stack element, often in relationship to another operand, and reports the result as a condition code (flags C0, C2, and C3) in the status word.

**Table 6-12. Comparison Instructions**

Mnemonic	Operation
FCOM	Compare Real
FCOMP	Compare Real and Pop
FCOMPP	Compare Real and Pop Twice
FICOM	Compare Integer
FICOMP	Compare Integer and Pop
FTST	Test
FUCOM*	Unordered Compare Real
FUCOMP*	Unordered Compare Real and Pop
FUCOMPP*	Unordered Compare Real and Pop Twice
FXAM	Examine

\*Not available on 8087 and Intel287™ math coprocessors.

The basic operations are compare, test (compare with zero), and examine (report type, sign, and normalization). Special forms of the compare operation are provided to optimize algorithms by allowing direct comparisons with binary integers and real numbers in memory, as well as popping the stack after a comparison.

The FSTSW AX (store status word) instruction can be used after a comparison to transfer the condition code to the AX register for inspection. The TEST instruction is recommended for using the FPU flags (once they are in the AX register) to control conditional branching. First check to see if the comparison resulted in *unordered*. This can happen, for instance, if one of the operands is a NaN. TEST the contents of the AX register against the constant 0400H; this will clear ZF (the Zero Flag of the EFLAGS register) if the original comparison was unordered, and set ZF otherwise. The JNZ instruction can then be used to transfer control (if necessary) to code that handles the case of unordered operands. With the unordered case now filtered out, TEST the contents of the AX register against the appropriate constant from Table 6-13, and then use the corresponding conditional branch.

**Table 6-13. TEST Constants for Conditional Branching**

Order	Constant	Branch
ST > Operand	4500H	JZ
ST < Operand	0100H	JNZ
ST = Operand	4000H	JNZ
Unordered	0400H	JNZ

It is not always necessary to filter out the unordered case when using this algorithm for conditional jumps. If the software has been thoroughly tested, and incorporates periodic checks for QNaN results (as recommended previously), then it is not necessary to check for *unordered* every time a comparison is made.

Instructions other than those in the comparison group can update the condition code. To ensure that the status word is not altered inadvertently, store it immediately following a comparison operation.

### 6.3.5. Transcendental Instructions

The instructions in this group (Table 6-14) perform the time-consuming core calculations for all common trigonometric, inverse trigonometric, hyperbolic, inverse hyperbolic, logarithmic, and exponential functions. The transcendentals operate on the top one or two stack elements, and they return their results to the stack. The trigonometric operations assume their arguments are expressed in radians. The logarithmic and exponential operations work in base 2.

**Table 6-14. Transcendental Instructions**

Mnemonic	Operation
FSIN*	Sine
FCOS*	Cosine
FSINCOS*	Sine and Cosine
FPTAN**	Tangent
FPATAN	Arctangent of ST(1) ÷ ST
F2XM1**	$2^X - 1$ ; X is in ST
FYL2X	$Y \times \log_2 X$ ; Y is in ST(1), X is in ST
FYL2XP1	$Y \times \log_2(X + 1)$ ; Y is in ST(1), X is in ST

\*Not available on 8087 and Intel287™ math coprocessors.

\*\*Operand range extended over 8087 and Intel287 math coprocessors.

The Pentium processor uses new algorithms for transcendental instructions, achieving a higher level of accuracy for the same instructions than the Intel486 processor. Accuracy is

measured in terms of units in the last place (ulp). For a given argument  $x$ , let  $f(x)$  and  $F(x)$  be the correct and computed (approximate) function values respectively. The error in ulps is defined to be

$$\left| \frac{f(x) - F(x)}{2^{k-63}} \right|$$

where  $k$  is an integer such that  $1 \leq 2^{-k}f(x) < 2$ .

On the Pentium processor, the worst case error on functions is less than 1 ulp when rounding to the nearest-even and less than 1.5 ulps when rounding in other modes. The functions are guaranteed to be monotonic, with respect to the input operands, throughout the domain supported by the instruction. See Appendix G for detailed information on transcendental accuracy.

The trigonometric functions accept a practically unrestricted range of operands, whereas the other transcendental instructions require that arguments be more restricted in range. FPREM or FPREM1 can be used to bring the otherwise valid operand of a periodic function into range. Prologue and epilogue software can be used to reduce arguments for other instructions to the expected range and to adjust the result to correspond to the original arguments if necessary. The instruction descriptions in the reference pages of Chapter 25 document the allowed operand range for each instruction.

When the argument of a trigonometric function is in range, it is automatically reduced by the appropriate multiple of  $2\pi$  (in 66-bit precision), by means of the same mechanism used in the FPREM and FPREM1 instructions. The value of  $\pi$  used in the automatic reduction has been chosen so as to guarantee no loss of significance in the operand, provided it is within the specified range. The internal value of  $\pi$  in hexadecimal is:

$$4 * 0.C90FDAA22168C234C$$

A program may use an explicit value for  $\pi$  in computations whose results later appear as arguments to trigonometric functions. In such a case (in explicit reduction of a trigonometric operand outside the specified range, for example), the value used for  $\pi$  should be the same as the full 66-bit internal  $\pi$ . This will insure that the results are consistent with the automatic argument reduction performed by the trigonometric functions. The 66-bit  $\pi$  cannot be represented as an extended-real value, so it must be encoded as two or more numbers. A common solution is to represent  $\pi$  as the sum of a  $high\pi$  which contains the 33 most-significant bits and a  $low\pi$  which contains the 33 least-significant bits. When using this two-part  $\pi$ , all computations should be performed separately on each part, with the results added only at the end.

The complications of maintaining a consistent value of  $\pi$  for argument reduction can be avoided, either by applying the trigonometric functions only to arguments within the range of the automatic reduction mechanism, or by performing all argument reductions (down to a magnitude less than  $\pi/4$ ) explicitly in software.



### 6.3.6. Constant Instructions

Each of these instructions, shown in Table 6-15, pushes a commonly used constant onto the stack. (ST(7) must be empty to avoid an invalid exception.) The values have full extended real precision (64 bits) and are accurate to approximately 19 decimal digits. Because an external real constant occupies 10 memory bytes, the constant instructions, which are only two bytes long, save storage and improve execution speed, in addition to simplifying programming.

**Table 6-15. Constant Instructions**

Mnemonic	Operation
FLDZ	Load +0.0
FLD1	Load +1.0
FLDPI	Load $\pi$
FLDL2T	Load $\log_2 10$
FLDL2E	Load $\log_2 e$
FLDLG2	Load $\log_{10} 2$
FLDLN2	Load $\log_e 2$

The constants used by these instructions are stored internally in a format more precise than extended real. When loading the constant, the FPU rounds the more precise internal constant according to the RC (rounding control) bit of the control word. However, in spite of this rounding, the precision exception is not raised (to maintain compatibility). When the rounding control is set to round to nearest, the FPU produces the same constant that is produced by the 8087 and Intel287 numeric coprocessors.

### 6.3.7. Control Instructions

The FPU control instructions are shown in Table 6-16. The FSTSW instruction is commonly used for conditional branching. The remaining instructions are not typically used in calculations; they provide control over the FPU for system-level activities. These activities include initialization of the FPU, numeric exception handling, and task switching.

As shown in Table 6-16, certain instructions have alternative mnemonics. The instructions which initialize the FPU, clear exceptions, or store (all or part of) the FPU environment come in two forms:

- *Wait*—the mnemonic is prefixed only with an F, such as FSTSW. This form checks for unmasked numeric exceptions.
- *No-wait*—the mnemonic is prefixed with an FN, such as FNSTSW. This form ignores unmasked numeric exceptions.

When a control instruction is coded using the no-wait form of the mnemonic, the ASM386/Intel486 processor assembler does not precede the ESC instruction with a WAIT instruction. The processor does not test for a floating-point error condition before executing a control instruction.

The only no-wait instructions are those shown in Table 6-16. All other floating-point instructions are automatically synchronized by the processor; all operands are transferred before the next instruction is initiated. Because of this automatic synchronization, non-control floating-point instructions need not be preceded by a WAIT instruction in order to execute correctly.

Exception synchronization relies on the WAIT instruction. Since the Integer Unit and the FPU operate in parallel, it is possible in the case of a floating-point exception for the processor to disturb information vital to exception recovery before the exception-handler can be invoked. Coding a WAIT or FWAIT instruction in the proper place can prevent this. See the next section for details.

**Table 6-16. Control Instructions**

Mnemonic	Operation
FINIT / FNINIT	Initialize FPU
FLDCW	Load Control Word
FSTCW/FNSTCW	Store Control Word
FSTSW/FNSTSW	Store Status Word
FSTSW AX/FNSTSW AX*	Store Status Word to AX Register
FCLEX/FNCLEX	Clear Exceptions
FSTENV/FNSTENV	Store Environment
FLDENV	Load Environment
FSAVE/FNSAVE	Save State
FRSTOR	Restore State
FINCSTP	Increment Stack Top Pointer
FDECSTP	Decrement Stack Top Pointer
FFREE	Free Register
FNOP	No Operation
FWAIT	Report FPU Error

\*Not available on 8087 math coprocessor.

It should also be noted that the 8087 instructions FENI and FDISI and the Intel287 math coprocessor instruction FSETPM perform no function in the Pentium, Intel486 and Intel386 processors and Intel387 coprocessors. If these opcodes are detected in the instruction stream, the 32-bit processors perform no specific operation and no internal states are affected. Chapter 23 contains a more complete description of the differences between floating-point operations on the Pentium and Intel486 processors and on the 8087, Intel287, and Intel387 DX numeric coprocessors.

## 6.4. NUMERIC APPLICATIONS

This section describes how programmers in assembly language and in a variety of higher-level languages can make use of the Intel486 processor's numerics capabilities.

The level of detail in this section is intended to give programmers a basic understanding of the software tools that can be used for numeric programming, but this information does not document the full capabilities of these facilities. Complete documentation is available with each program development product.

### 6.4.1. High-Level Languages

A variety of Intel high-level languages are available that automatically make use of the numeric instruction set when appropriate. These languages include C-386/486 and PL/M-386/486. In addition, many high-level language compilers optimized for the Pentium processor are available from independent software vendors.

Each of these high-level languages has special numeric libraries allowing programs to take advantage of the capabilities of the FPU. No special programming conventions are necessary to make use of the FPU when programming numeric applications in any of these languages.

Programmers in PL/M-386/486 and ASM386/486 can also make use of many of these library routines by using routines contained in the Support Library. These libraries implement many of the functions provided by higher-level languages, including exception handlers, ASCII-to-floating-point conversions, and a more complete set of transcendental functions than that provided by the processor's numeric instruction set.

#### 6.4.1.1. C PROGRAMS

C programmers automatically cause the C compiler to generate Intel486 processor numeric instructions when they use the **double** and **float** data types. The **float** type corresponds to the single real format; the **double** type corresponds to the double real format. The statement **#include <math.h>** causes mathematical functions such as **sin** and **sqrt** to return values of type **double**. Example 6-2 illustrates the ease with which C programs can make use of the processor's numerics capabilities.

#### 6.4.1.2. PL/M-386/486

Programmers in PL/M-386/486 can access a very useful subset of the FPU's numeric capabilities. The PL/M-386/486 **REAL** data type corresponds to the single real (32-bit) format. This data type provides a range of about  $8.43 \times 10^{-37} \leq |X| \leq 3.38 \times 10^{38}$ , with about seven significant decimal digits. This representation is adequate for the data manipulated by many microcomputer applications.



## Example 6-2. Sample C Program

```

/*****
 *
 *          SAMPLE C PROGRAM          *
 *
 *****/

/** Include stdio.h if necessary **/
/** Include math declarations for transcendentals and others **/

#include <math.h>
#define PI 3.1415926535897943

main()
double sin_result, cos_result;
double angle_deg = 0.0, angle_rad;
int i, no_of_trial=4;

for (i = 1; i <= no_of_trial; i++) {
    angle_rad = angle_deg * PI / 180.0;
    sin_result = sin (angle_rad);
    cos_result = cos (angle_rad);
    printf("sine of %f degrees equals %f\n", angle_deg, sin_result);
    printf("cosine of %f degrees equals %f\n\n", angle_deg,
cos_result);
    angle_deg = angle_deg + 30.0;
}
/** etc. **/
}

```

The utility of the REAL data type is extended by the PL/M-386/486 compiler's practice of holding intermediate results in the extended real format. This means that the full range and precision of the processor are utilized for intermediate results. Underflow, overflow, and rounding exceptions are most likely to occur during intermediate computations rather than during calculation of an expression's final result. Holding intermediate results in extended-precision real format greatly reduces the likelihood of overflow and underflow and eliminates roundoff as a serious source of error until the final assignment of the result is performed.

The compiler generates floating-point instructions to evaluate expressions that contain REAL data types, whether variables or constants or both. This means that addition, subtraction, multiplication, division, comparison, and assignment of REALs will be performed by the FPU. INTEGER expressions, on the other hand, are evaluated by the Integer Unit.

Five built-in procedures (Table 6-17) give the PL/M-386/486 programmer access to FPU control instructions. Prior to any arithmetic operations, a typical PL/M-386/486 program will set up the FPU using the INIT\$REAL\$MATH\$UNIT procedure and then issue SET\$REAL\$MODE to configure the FPU. SET\$REAL\$MODE loads the FPU control word, and its 16-bit parameter has the format shown previously for the control word. The

recommended value of this parameter is 033EH (round to nearest, 64-bit precision, all exceptions masked except invalid operation). Other settings may be used at the programmer's discretion.

**Table 6-17. PL/M-386/486 Built-In Procedures**

Procedure	FPU Control Instruction	Description
INIT\$REAL\$MATH\$UNIT	FINIT	Initialize FPU
SET\$REAL\$MODE	FLDCW	Set exception masks, rounding precision, and infinity controls.
GET\$REAL\$ERROR	FNSTSW& FNCLEX	Store, then clear, exception flags.
SAVE\$REAL\$STATUS	FNSAVE	Save FPU state.
RESTORE\$REAL\$STATUS	FRSTOR	Restore FPU state.

If any exceptions are unmasked, an exception handler must be provided in the form of an interrupt procedure that is designated to be invoked via interrupt vector number 16. The exception handler can use the GET\$REAL\$ERROR procedure to obtain the low-order byte of the FPU status word and to then clear the exception flags. The byte returned by GET\$REAL\$ERROR contains the exception flags; these can be examined to determine the source of the exception.

The SAVE\$REAL\$STATUS and RESTORE\$REAL\$STATUS procedures are provided for multitasking environments where a running task that uses the FPU may be preempted by another task that also uses the FPU. It is the responsibility of the operating system to issue SAVE\$REAL\$STATUS before it executes any statements that affect the FPU; these include the INIT\$REAL\$MATH\$UNIT and SET\$REAL\$MODE procedures as well as arithmetic expressions. SAVE\$REAL\$STATUS saves the FPU state (registers, status, and control words, etc.) on the memory stack. RESTORE\$REAL\$STATUS reloads the state information; the preempting task must invoke this procedure before terminating in order to restore the FPU to its state at the time the running task was preempted. This enables the preempted task to resume execution from the point of its preemption.

**6.4.1.3. ASM386/486**

The ASM386/486 assembly language provides programmers with complete access to all of the facilities of the processor.

**6.4.1.3.1. Defining Data**

The ASM386/486 directives shown in Table 6-18 allocate storage for numeric variables and constants. As with other storage allocation directives, the assembler associates a type with any variable defined with these directives. The type value is equal to the length of the storage unit in bytes (10 for DT, 8 for DQ, etc.). The assembler checks the type of any variable coded in an instruction to be certain that it is compatible with the instruction. For example,

the coding `FIADD ALPHA` will be flagged as an error if `ALPHA`'s type is not 2 or 4, because integer addition is only available for word and short integer (doubleword) data types. The operand's type also tells the assembler which machine instruction to produce; although to the programmer there is only an `FIADD` instruction, a different machine instruction is required for each operand type.

**Table 6-18. ASM386/486 Storage Allocation Directives**

Directives	Interpretation	Data Types
DW	Define Word	Word integer
DD	Define Doubleword	Short integer, short real
DQ	Define Quadword	Long integer, long real
DT	Define Tenbyte	Packed decimal, temporary real

On occasion it is desirable to use an instruction with an operand that has no declared type. For example, if register `BX` points to a short integer variable, a programmer may want to code `FIADD [BX]`. This can be done by informing the assembler of the operand's type in the instruction, coding `FIADD DWORD PTR [BX]`. The corresponding overrides for the other storage allocations are `WORD PTR`, `QWORD PTR`, and `TBYTE PTR`.

The assembler does not, however, check the types of operands used in processor control instructions. Coding `FRSTOR [BP]` implies that the programmer has set up register `BP` to point to the location (probably in the stack) where the processor's 94-byte state record has been previously saved.

The initial values for numeric constants may be coded in several different ways. Binary integer constants may be specified as bit strings, decimal integers, octal integers, or hexadecimal strings. Packed decimal values are normally written as decimal integers, although the assembler will accept and convert other representations of integers. Real values may be written as ordinary decimal real numbers (decimal point required), as decimal numbers in scientific notation, or as hexadecimal strings. Using hexadecimal strings is primarily intended for defining special values such as infinities, NaNs, and denormalized numbers. Most programmers will find that ordinary decimal and scientific decimal provide the simplest way to initialize numeric constants. Example 6-3 compares several ways of setting the various numeric data types to the same initial value.

**Example 6-3. Sample Numeric Constants**

```

; THE FOLLOWING ALL ALLOCATE THE CONSTANT: -126
; NOTE TWO'S COMPLEMENT STORAGE OF NEGATIVE BINARY INTEGERS.
;
EVEN                ;FORCE WORD ALIGNMENT
WORD_INTEGER        DW 1111111110000010b        ;BIT STRING
SHORT_INTEGER       DD 0FFFFFF82H                ;HEX STRING MUST START
                                                            ;WITH DIGIT
LONG_INTEGER        DQ -126                      ;ORDINAL DECIMAL

```

```

SINGLE_REAL      DD -126.0                ;NOTE PRESENCE OF .
DOUBLE_REAL     DD -1.26e2              ;SCIENTIFIC
PACKED_DECIMAL  DT -126                ;ORDINARY DECIMAL INTEGER
;
; IN THE FOLLOWING, SIGN AND EXPONENT IS 'C005'
; SIGNIFICAND IS '7300...00', 'R' INFORMS ASSEMBLER THAT
; THE STRING REPRESENTS A REAL DATA TYPE.
;
EXTENDED_REAL   DT 0C0057E000000000000000R ;HEX STRING
    
```

Note that preceding numeric variables and constants with the ASM386/486 EVEN directive ensures that the operands will be word-aligned in memory. The best performance is obtained when data transfers are aligned. See Chapter 24 for alignment strategies for the different processors. All numeric data types occupy integral numbers of words so that no storage is "wasted" if blocks of variables are defined together and preceded by a single EVEN declarative.

#### 6.4.1.3.2. Records and Structures

The ASM386/486 RECORD and STRUC (structure) declaratives can be very useful in numeric programming. The record facility can be used to define the bit fields of the control, status, and tag words. Example 6-4 shows one definition of the status word and how it might be used in a routine that polls the FPU until it has completed an instruction.

#### Example 6-4. Status Word Record Definition

```

; RESERVE SPACE FOR STATUS WORD
STATUS_WORD
; LAY OUT STATUS WORD FIELDS
STATUS_RECORD
&   BUSY:           1,
&   COND_CODE3:    1,
&   STACK_TOP: 3,
&   COND_CODE2:    1,
&   COND_CODE1:    1,
&   COND_CODE0:    1,
&   INT_REQ:       1,
&   S_FLAG:        1,
&   P_FLAG:        1,
&   U_FLAG:        1,
&   O_FLAG:        1,
&   Z_FLAG:        1,
&   D_FLAG:        1,
&   I_FLAG:        1
; REDUCE UNTIL COMPLETE
REDUCE:
    FPREM1
    
```

```
FNSTSW    STATUS_WORD
TEST     STATUS_WORD, MASK_COND_CODE2
JNZ     REDUCE
```

Because structures allow different but related data types to be grouped together, they often provide a natural way to represent "real world" data organizations. The fact that the structure template may be "moved" about in memory adds to its flexibility. Example 6-5 shows a simple structure that might be used to represent data consisting of a series of test score samples. This sample structure can be reorganized, if necessary, for the sake of more efficient execution. If the two double real fields were listed before the integer fields, then (provided that the structure is instantiated only at addresses divisible by eight) all the fields would be optimally aligned for efficient memory access and caching. A structure could also be used to define the organization of the information stored and loaded by the FSTENV and FLDENV instructions.

#### Example 6-5. Structure Definition

```
SAMPLE STRUC
    N_OBSDD ?      ; SHORT INTEGER
    MEAN DQ ?     ; DOUBLE REAL
    MODE DW ?     ; WORD INTEGER
    STD_DEV  DQ ? ; DOUBLE REAL
    ; ARRAY OF OBSERVATIONS -- WORD INTEGER
    TEST_SCORES DW 1000 DUP (?)
SAMPLE ENDS
```

#### 6.4.1.3.3. Addressing Methods

Numeric data in memory can be accessed with any of the memory addressing methods provided by the ModR/M byte and (optionally) the SIB byte. This means that numeric data types can be incorporated in data aggregates ranging from simple to complex according to the needs of the application. The addressing methods and the ASM386/486 notation used to specify them in instructions make the accessing of structures, arrays, arrays of structures, and other organizations direct and straightforward. Table 6-19 gives several examples of numeric instructions coded with operands that illustrate different addressing methods.

**Table 6-19. Addressing Method Examples**

Coding	Interpretation
FIADD ALPHA	ALPHA is a simple scalar (mode is direct).
FDIVR ALPHA.BETA	BETA is a field in a structure that is "overlaid" on ALPHA (mode is direct).
FMUL QWORD PTR [BX]	BX contains the address of a long real variable (mode is register indirect).
FSUB ALPHA [SI]	ALPHA is an array and SI contains the offset of an array element from the start of the array (mode is indexed).
FILD [BP].BETA	BP contains the address of a structure on the CPU stack and BETA is a field in the structure (mode is based).
FBLD TBYTE PTR [BX] [DI]	BX contains the address of a packed decimal array and DI contains the offset of an array element (mode is based indexed).

**6.4.1.4. COMPARATIVE PROGRAMMING EXAMPLE**

Examples 6-6 and 6-7 show the PL/M-386/486 and ASM386/486 code for a simple numeric program, called ARRSUM. The program references an array (X\$ARRAY), which contains 0–00 single real values; the integer variable N\$OF\$X indicates the number of array elements the program is to consider. ARRSUM steps through X\$ARRAY accumulating three sums:

- SUM\$X, the sum of the array values
- SUM\$INDEXES, the sum of each array value times its index, where the index of the first element is 1, the second is 2, etc.
- SUM\$SQUARES, the sum of each array element squared

**Example 6-6. Sample PL/M-386/486 Program**

```

/*****
*
*           ARRYSUM MODULE
*
***** /

array$sum:  do;
    declare (sum$x, sum$indexes, sum$squares) real;
    declare x$array(100) real;
    declare (n$of$x, i) integer;
    declare control $ FPU literally '033eh';

    / *Assume x$array and n$of$x are initialized */
    call init$real$math$unit;
    
```

```

call set$real$mode(control $ FPU);
/* Clear sums */
sum$x, sum$indexes, sum$squares = 0.0;
/* Loop through array, accumulating sums */
do i = 0 to n$of$x - 1;
    sum$x = sum$x + x$array(i);
    sum$indexes = sum$indexes + (x$array(i)*float(i+1));
    sum$squares = sum$squares + (x$array(i)*x$array(i));
end;
/* etc. */
end array$sum;

```

### Example 6-7. Sample ASM386/486 Program

```

name arraysum
; Define initialization routine
extrn initFPU:far
; Allocate space for data
data segment rw public
    control_FPU    dw 033eh
    n_of_x         dd ?
    x_array        dd 100 dup(?)
    sum_squares    dd ?
    sum_indexes    dd ?
    sum_x          dd ?
data ends
; Allocate CPU stack space
stack stackseg 400
; Begin code
code segment er public
    assume ds:data, ss:stack
start:
    mov ax, data
    mov ds, ax
    mov ax, stack
    mov ss, ax
    mov esp, stackstart stack
; Assume x_array and n_of_x have been initialized
; Prepare the FPU or its emulator
    call initFPU
    fldcwcontrol_FPU

```

```

; Clear three registers to hold running sums
    fldz
    fldz
    fldz
; Setup ECX as loop counter and ESI as index into x_array
    mov ecx, n_of_x
    imul ecx
    mov esi, eax
; ESI now contains index of last element + 1
; Loop through x_array and accumulate sum
sum_next:
; Back up one element and push on the stack
    sub esi, type x_array
    fld x_array[esi]
; Add to the sum and duplicate x on the stack
    fadd st(3), st
    fld st
; Square it and add into the sum of (index+1) and discard
    fmul st, st
    faddpst(2), st
    fmul n_of_x
    faddpst(2), st
; Reduce index for next iteration
    loop sum_next
; Pop sums into memory
pop_results:
    fstp sum_squares
    fstp sum_indexes
    fstp sum_x
    fwait
;
; Etc.
;
code ends
end start, ds:data, ss:stack

```

(A true program, of course, would go beyond these steps to store and use the results of these calculations.) The control word is set with the recommended values: round to nearest, 64-bit precision, interrupts enabled, and all exceptions masked except invalid operation. It is assumed that an exception handler has been written to field the invalid operation if it occurs, and that it is invoked by interrupt pointer 16.

The PL/M-386/486 version of ARRAYSUM is very straightforward and illustrates how easily the numerics capabilities of the Intel486 processor can be used in this language. After declaring variables, the program calls built-in procedures to initialize the FPU and to load to the control word. The program clears the sum variables and then steps through X\$ARRAY with a DO-loop. The loop control takes into account PL/M-386/486's practice of considering the index of the first element of an array to be 0. In the computation of SUM\$INDEXES, the built-in procedure FLOAT converts I+1 from integer to real because the language does not support "mixed mode" arithmetic. One of the strengths of the Intel486 processor FPU, of course, is that it *does* support arithmetic on mixed data types (because all values are converted internally to the 80-bit extended-precision real format).

The ASM386/486 version defines the external procedure INITFPU, which makes the different initialization requirements of the processor and its emulator transparent to the source code. After defining the data and setting up the segment registers and stack pointer, the program calls INITFPU and loads the control word. The computation begins with the next three instructions, which clear three registers by loading (pushing) zeros onto the stack. As shown in Figure 6-12, these registers remain at the bottom of the stack throughout the computation while temporary values are pushed on and popped off the stack above them.

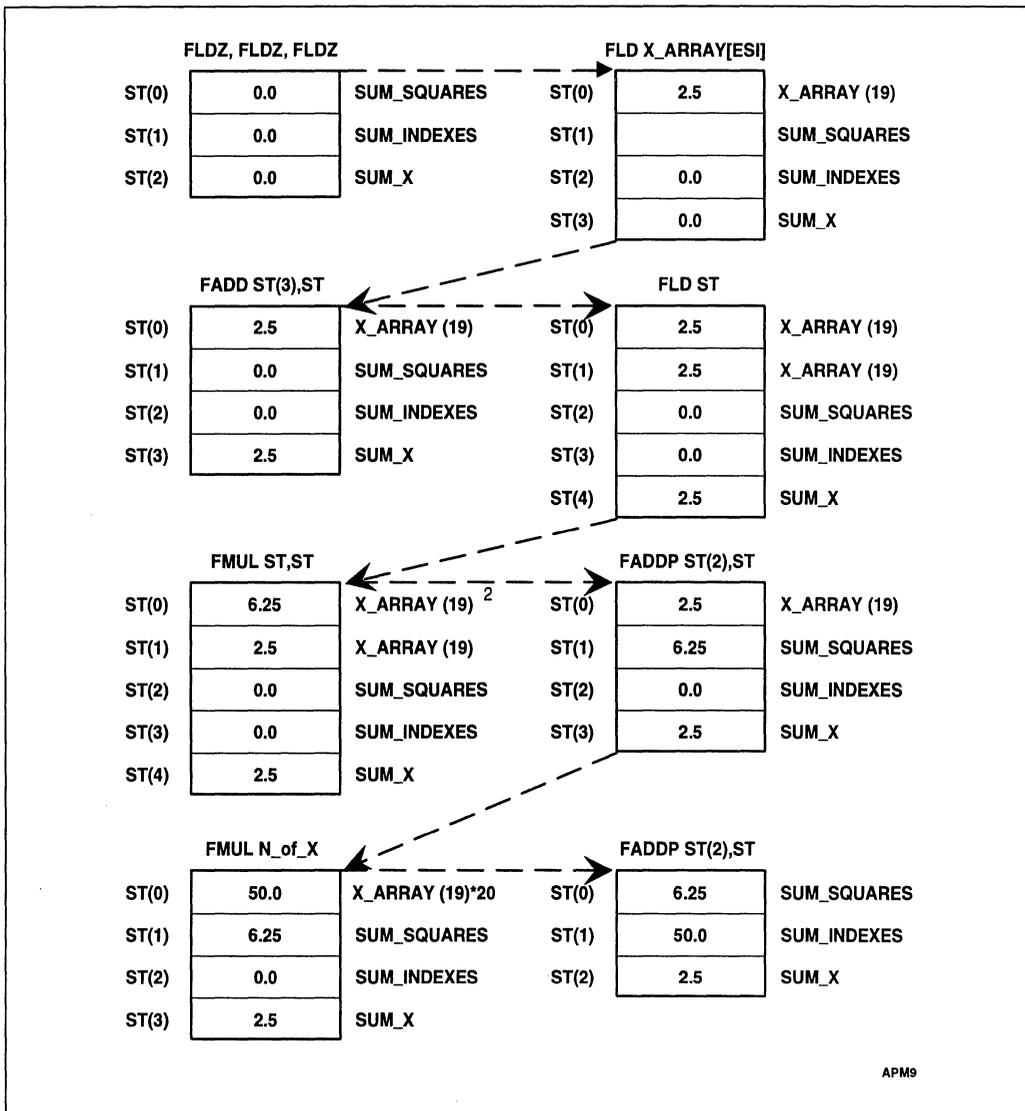


Figure 6-12. Instructions and Register Stack

The program uses the LOOP instruction to control its iteration through X\_ARRAY; register ECX, which LOOP automatically decrements, is loaded with n\_of\_x the number of array elements to be summed. Register ESI is used to select (index) the array elements. The program steps through X\_ARRAY from back to front, so ESI is initialized to point at the element just beyond the first element to be processed. The ASM386/486 TYPE operator is used to determine the number of bytes in each array element. This permits changing

X\_ARRAY to a double-precision real array by simply changing its definition (DD to DQ) and reassembling.

Figure 6-12 shows the effect of the instructions in the program loop on the FPU register stack. The figure assumes that the program is in its first iteration, that N\_OF\_X is 20, and that X\_ARRAY(19) (the 20th element) contains the value 2.5. When the loop terminates, the three sums are left as the top stack elements so that the program ends by simply popping them into memory variables.

#### 6.4.1.5. CONCURRENT PROCESSING

Because the Intel Pentium Processor Integer Unit (IU) and FPU execution units are separate, it is possible for the FPU to execute numeric instructions in parallel with integer instructions. This simultaneous execution of different instructions is called concurrency.

No special programming techniques are required to gain the advantages of concurrent execution; numeric instructions are simply placed in line with the integer instructions. Integer and numeric instructions are initiated in the same order as they are encountered in the instruction stream. However, because numeric operations performed by the FPU generally require more time than integer operations, the IU can often execute several instructions before the FPU completes a numeric instruction previously initiated.

This concurrency offers obvious advantages in terms of execution performance, but concurrency also imposes several rules that must be observed in order to assure proper synchronization of the IU and FPU.

All Intel high-level languages automatically provide for and manage concurrency in the FPU. Assembly-language programmers, however, must understand and manage some areas of concurrency in exchange for the flexibility and performance of programming in assembly language. This section is for the assembly-language programmer or well-informed high-level-language programmer.

#### 6.4.1.6. MANAGING CONCURRENCY

The activities of numeric programs can be split into two major areas: program control and arithmetic. The program control part performs activities such as deciding what functions to perform, calculating addresses of numeric operands, and loop control. The arithmetic part simply adds, subtracts, multiplies, and performs other operations on the numeric operands. The processor is designed to handle these two parts separately and efficiently.

Concurrency management is required to check for an exception before letting the processor change a value just used by the FPU. Almost any numeric instruction can, under the wrong circumstances, produce a numeric exception. For programmers in higher-level languages, all required synchronization is automatically provided by the appropriate compiler. For assembly-language programmers exception synchronization remains the responsibility of the programmer.

A complication is that a programmer may not expect their numeric program to cause numeric exceptions, but in some systems, they may regularly happen. To better understand these points, consider what can happen when the FPU detects an exception.

Depending on options determined by the software system designer, the processor can perform one of two things when a numeric exception occurs:

- The FPU can provide a default fix-up for selected numeric exceptions. Programs can mask individual exception types to indicate that the FPU should generate a safe, reasonable result whenever that exception occurs. The default exception fix-up activity is treated by the FPU as part of the instruction causing the exception; no external indication of the exception is given. When exceptions are detected, a flag is set in the numeric status register, but no information regarding where or when is available. If the FPU performs its default action for all exceptions, then the need for exception synchronization is not manifest. However, as will be shown later, this is not sufficient reason to ignore exception synchronization when designing programs that use the FPU.
- As an alternative to the default fix-up of numeric exceptions, the IU can be notified whenever an exception occurs. When a numeric exception is unmasked and the exception occurs, the FPU stops further execution of the numeric instruction and signals this event. On the next occurrence of an ESC or WAIT instruction, the processor traps to a software exception handler. The exception handler can then implement any sort of recovery procedures desired for any numeric exception detectable by the FPU. Some ESC instructions do not check for exceptions. These are the nonwaiting forms FNINIT, FNSTENV, FNSAVE, FNSTSW, FNSTCW, and FNCLEX.

When the FPU signals an unmasked exception condition, it is requesting help. The fact that the exception was unmasked indicates that further numeric program execution under the arithmetic and programming rules of the FPU is unreasonable.

If concurrent execution is allowed, the state of the processor when it recognizes the exception is undefined. It may have changed many of its internal registers and be executing a totally different program by the time the exception occurs. To handle this situation, the FPU has special registers updated at the start of each numeric instruction to describe the state of the numeric program when the failed instruction was attempted.

Exception synchronization ensures that the FPU is in a well-defined state after an unmasked numeric exception occurs. Without a well-defined state, it would be impossible for exception recovery routines to determine why the numeric exception occurred, or to recover successfully from the exception.

The following two sections illustrate the need to always consider exception synchronization when writing numeric code, even when the code is initially intended for execution with exceptions masked. If the code is later moved to an environment where exceptions are unmasked, the same code may not work correctly. An example of how some instructions written without exception synchronization will work initially, but fail when moved into a new environment, is shown in the following section.



### 6.4.1.7. EXCEPTION SYNCHRONIZATION

In the following examples, three instructions are shown to load an integer, calculate its square root, then increment the integer. The synchronous execution of the FPU will allow this program to execute correctly when no exceptions occur on the FILD instruction.

#### Incorrect Error Synchronization:

```
FILD COUNT      ; FPU instruction
INC  COUNT      ; integer instruction alters operand
FSQRT          ; subsequent FPU instruction -- error
                ; from previous FPU
                ; instruction detected here
```

#### Proper Error Synchronization:

```
FILD COUNT      ; FPU instruction
FSQRT          ; subsequent FPU instruction -- error from
                ; previous FPU
                ; instruction detected here
INC  COUNT      ; integer instruction alters operand
```

This situation changes if the numeric register stack is extended to memory. To extend the FPU stack to memory, the invalid exception is unmasked. A push to a full register or pop from an empty register sets SF and causes an invalid exception.

The recovery routine for the exception must recognize this situation, fix up the stack, then perform the original operation. The recovery routine will not work correctly in the first example shown in the figure. The problem is that the value of COUNT is incremented before the exception handler is invoked, so that the recovery routine will load an incorrect value of COUNT, causing the program to fail or behave unreliably.

### 6.4.1.8. PROPER EXCEPTION SYNCHRONIZATION

Exception synchronization relies on the WAIT instruction. Whenever an unmasked numerical exception occurs, the FPU asserts an error-condition signal internal to the processor. When the next WAIT instruction (or an ESC instruction other than FNINIT, FNCLEX, FNSTSW, FNSTSW AX, FNSTCW, FNSTENV, FNSAVE) is encountered, the error-condition signal is acknowledged and a software exception handler is invoked. (See Chapter 7 and section 23.3.7 for a more detailed discussion of the various floating-point error-reporting mechanisms and Pentium processor implementation specifics respectively.) If this WAIT or ESC instruction is properly placed, the processor will not yet have disturbed any information vital to recovery from the exception. A WAIT instruction should also be placed after the last floating-point instruction in an application so that any unmasked exceptions will be serviced before the task completes.



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**7**

**Special  
Computational  
Situations**

**I**



# CHAPTER 7

## SPECIAL COMPUTATIONAL SITUATIONS

Besides being able to represent positive and negative numbers, the numerical data formats may be used to describe other entities. These special values provide extra flexibility, but most users will not need to understand them in order to use the numerics capabilities of the processor successfully. This section describes the special values that may occur in certain cases and the significance of each. The numeric exceptions are also described, for writers of exception handlers and for those interested in probing the limits of numeric computation.

The material presented in this section is mainly of interest to programmers concerned with writing exception handlers. Many readers will only need to skim this section.

When discussing these special computational situations, it is useful to distinguish between *arithmetic instructions* and *nonarithmetic instructions*. Nonarithmetic instructions are those that have no operands or transfer their operands without substantial change; arithmetic instructions are those that make significant changes to their operands. Table 7-1 defines these two classes of instructions.

### 7.1. SPECIAL NUMERIC VALUES

The numerical data formats encompass encodings for a variety of special values in addition to the typical real or integer data values that result from normal calculations. These special values have significance and can express relevant information about the computations or operations that produced them. The various types of special values are:

- Denormal real numbers
- Zeros
- Positive and negative infinity
- NaN (Not-a-Number)
- Indefinite
- Unsupported formats

The following sections explain the origins and significance of each of these special values. Tables 7-2 through Tables 7-6 show how each of these special values is encoded for each of the numeric data types.

Table 7-1. Arithmetic and Nonarithmetic Instructions

Nonarithmetic Instructions	Arithmetic Instructions
FABS	F2XM1
FCHS	FADD (P)
FCLEX	FBLD
FDECSTP	FBSTP
FFREE	FCOMP(P)(P)
FINCSTP	FCOS
FINIT	FDIV(R)(P)
FLD (register-to-register)	FIADD
FLD (extended format from memory)	FICOM(P)
FLD constant	FIDIV(R)
FLDCW	FILD
FLDENV	FIMUL
FNOP	FIST(P)
FRSTOR	FISUB(R)
FSAVE	FLD (conversion)
FST(P) (register-to-register)	FMUL(P)
FSTP (extended format to memory)	FPATAN
FSTCW	FPREM
FSTENV	FPREM1
FSTSW	FPTAN
FWAIT	FRNDINT
FXAM	FSCALE
FXCH	FSIN
	FSINCOS
	FSQRT
	FST(P) (conversion)
	FSUB(R)(P)
	FTST
	FUCOM(P)(P)
	FXTRACT
	FYL2X
	FYL2XP1

**Table 7-2. Binary Integer Encodings**

Class	Sign	Magnitude
<b>Positives</b>		
(Largest)	0	11..11
	.	.
	.	.
	.	.
(Smallest)	0	00..01
Zero	0	00..00
<b>Negatives</b>		
(Smallest)	1	11..11
	.	.
	.	.
	.	.
	.	.
(Largest/Indefinite*)	1	00..00
	Word:	15 bits
	Short:	31 bits
	Long:	63 bits

**NOTES:**

\*If this encoding is used as a source operand (as in an integer load or integer arithmetic instruction), the FPU interprets it as the largest negative number representable in the format...  $-2^{15}$ ,  $-2^{31}$ , or  $-2^{63}$ . The FPU delivers this encoding to an integer destination in two cases:

1. If the result is the largest negative number.
2. As the response to a masked invalid operation exception, in which case it represents the special value *integer indefinite*.

**Table 7-3. Packed Decimal Encodings**

Class	Sign		Magnitude					
			digit	digit	digit	digit	...	digit
<b>Positives</b>								
Largest	0	0000000	1001	1001	1001	1001	...	1001
	.	.			.			
	.	.			.			
	.	.			.			
Smallest	0	0000000	0000	0000	0000	0000	...	0001
Zero	0	0000000	0000	0000	0000	0000	...	0000
<b>Negatives</b>								
Zero	1	0000000	0000	0000	0000	0000	...	0000
Smallest	1	0000000	0000	0000	0000	0000	...	0000
	.	.			.			
	.	.			.			
	.	.			.			
Largest	1	0000000	1001	1001	1001	1001	...	1001
<b>Indefinite*</b>	1	1111111	1111	1111	UUUU**	UUUU	...	UUUU
	—1 byte—		—9 bytes—					

\* The packed decimal indefinite is stored by FBSTP in response to a masked invalid operation exception. Attempting to load this value via FBLD produces an undefined result.

\*\* UUUU means bit values are undefined and may contain any value.



**Table 7-4. Single and Double Real Encodings**

Class	Sign	Biased Exponent	Significand ff-ff*
<b>Positive NaNs</b>			
Quiet	0	11..11	11..11
	.	.	.
	0	11..11	10..00
Signaling	0	11..11	01..11
	.	.	.
	0	11..11	00..01
Infinity	0	11..11	00..00
<b>Positive Reals</b>			
Normals	0	11..10	11..11
	.	.	.
	0	00..01	00..00
Denormals	0	00..00	11..11
	.	.	.
	0	00..00	00..01
Zero	0	00..00	00..00
<b>Negative Reals</b>			
Zero	1	00..00	00..00
Denormals	1	00..00	00..01
	.	.	.
	1	00..00	11..11
Normals	1	00..01	00..00
	.	.	.
	1	11..10	11..11
Infinity	1	11..11	00..00
<b>Negative NaNs</b>			
Signaling	1	11..11	00..01
	.	.	.
	1	11..11	01..11
Quiet	1 (Indefinite)	11..11	10..00
	.	.	.
	1	11..11	11..11
	Single: Double:	—8 bits— —11 bits—	—23 bits— —52 bits—

\*Integer bit is implied and not stored.

Table 7-5. Extended Real Encodings

Class	Sign	Biased Exponent	Significand ff-ff*
<b>Positive NaNs</b>			
Quiet	0	11..11	1 11..11
	.	.	.
	0	11..11	1 10..00
Signaling	0	11..11	1 01..11
	.	.	.
	0	11..11	1 00..01
Infinity	0	11..11	1 00..00
<b>Positive Reals</b>			
Normals	0	11..10	1 11..11
	.	.	.
	.	.	.
	0	00..01	1 00..00
Pseudodenormals	0	00..00	1 11..11
	.	.	.
	0	00..00	1 00..01
Denormals	0	00..00	0 11..11
	.	.	.
	.	.	.
	0	00..00	0 00..01
Zero	0	00..00	0 00..00
<b>Negative Reals</b>			
Zero	1	00..00	0 00..00
Denormals	1	00..00	0 00..01
	.	.	.
	1	00..00	0 11..11
Pseudodenormals	1	00..00	1 11..11
	.	.	.
	1	00..00	1 00..00
Normals	1	00..01	1 00..00
	.	.	.
	1	11..10	1 11..11
Infinity	1	11..11	1 00..00
<b>Negative NaNs</b>			
Signaling	1	11..11	1 00..01
	.	.	.
	1	11..11	1 01..11
Quiet	1 (Indefinite)	11..11	1 10..00
	.	.	.
	1	11..11	1 11..11
		—15 bits—	—64 bits—

\*Integer bit is implied and not stored.

**Table 7-6. Unsupported Formats**

Class	Sign	Biased Exponent	Significand f <sub>Δ</sub> ff-ff*
<b>Positive Pseudo-NaNs</b>			
Quiet	0	11..11	0 <sub>Δ</sub> 11..11
	.	.	.
	0	11..11	0 10..00
Signaling	0	11..11	0 01..11
	.	.	.
	0	11..11	0 00..01
Pseudoinfinity	0	11..11	0 00..00
<b>Positive Reals</b>			
Unnormals	0	11..10	0 11..11
	.	.	.
	.	.	.
	0	00..01	0 00..00
<b>Negative Reals</b>			
Unnormals	1	11..10	0 11..01
	.	.	.
	.	.	.
	1	00..01	0 00..00
Pseudoinfinity	1	11..11	0 00..00
<b>Negative Pseudo NaNs</b>			
Signaling	1	11..11	0 01..11
	.	.	.
	1	11..11	0 00..01
Quiet	1	11..11	0 11..11
	.	.	.
	1	11..11	0 10..00
		—15 bits—	—64 bits—

\*Integer bit is implied and not stored.

### 7.1.1. Denormal Real Numbers

The processor generally stores nonzero real numbers in normalized floating-point form; that is, the integer (leading) bit of the significand is always a one. (Refer to the previous section for a review of operand formats.) This bit is explicitly stored in the extended format, and is implicitly assumed to be a one (1<sub>Δ</sub>) in the single and double formats. Since leading zeros are eliminated, normalized storage allows the maximum number of significant digits to be held in a significand of a given width.

When a numeric value becomes very close to zero, normalized floating-point storage cannot be used to express the value accurately. The term *tiny* is used here to precisely define what values require special handling. A number R is said to be *tiny* when  $-2^{E_{min}} < R < 0$  or  $0 < R$

$< +2^{E_{min}}$ . (As defined in the previous section,  $E_{min}$  is  $-126$  for single format,  $-1022$  for double format, and  $-16382$  for extended format.) In other words, a nonzero number is *tiny* if its exponent would be too negative to store in the destination format.

To accommodate these instances, the processor can store and operate on reals that are not normalized, i.e., whose significands contain one or more leading zeros. Denormals typically arise when the result of a calculation yields a value that is *tiny*.

Denormal values have the following properties:

- The biased floating-point exponent is stored at its smallest value (zero)
- The integer bit of the significand (whether explicit or implicit) is zero

The leading zeros of denormals permit smaller numbers to be represented, at the possible cost of some lost precision (the number of significant bits is reduced by the leading zeros). In typical algorithms, extremely small values are most likely to be generated as intermediate, rather than final, results. By using the extended real format for holding intermediate values, quantities as small as  $\pm 3.37 \times 10^{-4932}$  can be represented; this makes the occurrence of denormal numbers a rare phenomenon in numerical applications. Nevertheless, the processor can load, store, and operate on denormalized real numbers when they do occur.

Denormals receive special treatment by the processor in three respects:

- The processor avoids creating denormals whenever possible. In other words, it always normalizes real numbers except in the case of tiny numbers.
- The processor provides the unmasked underflow exception to permit programmers to detect cases when denormals would be created.
- The processor provides the denormal operand exception to permit programmers to detect cases when denormals enter into calculations.

Denormalizing means incrementing the true result's exponent and inserting a corresponding leading zero in the significand, shifting the rest of the significand one place to the right. Denormal values may occur in any of the single, double, or extended formats. Table 7-7 shows the range of denormalized values in each format.

**Table 7-7. Denormalized Values**

Format	Smallest Magnitude		Largest Magnitude	
	(Exact)	(Approx.)	(Exact)	(Approx.)
Single Precision	$2^{-149}$	$10^{-46}$	$2^{-126}_2$ - $2^{-150}$	$10^{-38}$
Double Precision	$2^{-1074}$	$10^{-324}$	$2^{-1022}_2$ - $2^{-1075}$	$10^{-308}$
Extended	$2^{-16445}$	$10^{-4951}$	$2^{-16382}_2$ - $2^{-16445}$	$10^{-4932}$

Denormalization produces either a denormal or a zero. Denormals are readily identified by their exponents, which are always the minimum for their formats; in biased form, this is always the bit string: 00..00. This same exponent value is also assigned to the zeros, but a

denormal has a nonzero significand. A denormal in a register is tagged *special*. Tables 7-2 through Table 7-6 show how denormal values are encoded in each of the real data formats.

The denormalization process causes loss of significance if low-order one-bits are shifted off the right of the significand. In a severe case, *all* the significand bits of the true result are shifted out and replaced by the leading zeros. In this case, the result of denormalization is a true zero, and, if the value is in a register, it is tagged as a zero.

Denormals are rarely encountered in most applications. Typical debugged algorithms generate extremely small results only during the evaluation of intermediate subexpressions; the final result is usually of an appropriate magnitude for its single or double format real destination. If intermediate results are held in temporary real, as is recommended, the greater range of this format makes underflow very unlikely. Denormals are likely to arise only when an application generates a great many intermediates, so many that they cannot be held on the register stack or in extended format memory variables. If storage limitations force the use of single or double format reals for intermediates, and small values are produced, underflow may occur, and, if masked, may generate denormals.

When a denormal number in single or double format is used as a source operand and the denormal exception is masked, the FPU automatically *normalizes* the number when it is converted to extended format.

### 7.1.2. Zeros

The value *zero* in the real and decimal integer formats may be signed either positive or negative, although the sign of a binary integer zero is always positive. For computational purposes, the value of zero always behaves identically, regardless of sign, and typically the fact that a zero may be signed is transparent to the programmer. If necessary, the FXAM instruction may be used to determine a zero's sign.

A programmer can code a zero, or it can be created by the FPU as its masked response to an underflow exception. If a zero is loaded or generated in a register, the register is tagged *zero*. Table 7-8 lists the results of instructions executed with zero operands and also shows how a zero may be created from nonzero operands.

### 7.1.3. Infinity

The real formats support signed representations of infinities. These values are encoded with a biased exponent of all ones and a significand of  $1_{\Delta}00..00$ ; if the infinity is in a register, it is tagged *special*.

A programmer can code an infinity, or it can be created by the FPU as its masked response to an overflow or a zero divide exception. Note that depending on rounding mode, the masked response may create the largest valid value representable in the destination rather than infinity.

The signs of the infinities are observed, and comparisons are possible. Infinities are always interpreted in the affine sense; that is,  $-\infty < (\text{any finite number}) < +\infty$ . Arithmetic on infinities is always exact and, therefore, signals no exceptions, except for the invalid operations specified in Table 7-9.

Table 7-8. Zero Operands and Results

Operation	Operands	Result
FLD, FLBD	$\pm 0$	*0
FILD	+0	+0
FST, FSTP, FRNDINT	$\pm 0$ +X -X	*0 $+0^1$ $-0^1$
FBSTP	$\pm 0$	*0
FIST, FISTP	$\pm 0$ +X -X	*0 $-0^3$ $-0^4$
FCHS	+0 -0	-0 +0
FABS	$\pm 0$	+0
Addition	+0 plus +0 -0 plus -0 $\pm 0$ plus -0, -0 plus +0 -X plus +X, +X plus -X $\pm 0$ plus $\pm X$ , $\pm X$ plus $\pm 0$	+0 -0 $+0^2$ $\pm 0$ #X
Subtraction	+0 minus -0 -0 minus +0 +0 minus +0, -0 minus -0 +X minus +X, -X minus -X $\pm 0$ minus $\pm X$ $\pm X$ minus $\pm 0$	+0 -0 $\pm 0^2$ $\pm 0^2$ -#X #X

Table 7-8. Zero Operands and Results (Contd.)

Operation	Operands	Result
Multiplication	$\pm 0 \times \pm 0$	0
	$\pm 0 \times \pm X, \pm X \times \pm 0$	0
	$+X \times +Y, -X \times -Y$	$+0^1$
	$+X \times -Y, -X \times +Y$	$-0^1$
Division	$\pm 0 \div \pm 0$	Invalid Operation
	$\pm X \div \pm 0$	$\infty$ (Zero Divide)
	$\pm X \div \pm \infty$	0
	$+0 \div +X, -0 \div -X$	+0
	$+0 \div -X, -0 \div +X$	-0
	$-X \div -Y, +X \div +Y$	$+0^1$
	$-X \div -Y, +X \div +Y$	$-0^1$
FPREM, FPREM1	$\pm 0 \text{ rem } \pm 0$	Invalid Operation
	$\pm X \text{ rem } \pm 0$	Invalid Operation
	$+0 \text{ rem } \pm X$	+0
	$-0 \text{ rem } \pm X$	-0
	$+X \text{ rem } \pm Y$	+0 Y exactly divides X
	$-X \text{ rem } \pm Y$	-0 Y exactly divides X
FSQRT	$\pm 0$	*0
Compare	$\pm 0 : +X$	$\pm 0 < +X$
	$\pm 0 : \pm 0$	$\pm 0 = \pm 0$
	$\pm 0 : -X$	$\pm 0 > -X$
FTST	$\pm 0$	$\pm 0 = 0$
FXAM	+0	$C_3 = 1; C_2 = C_1 = C_0 = 0$
	-0	$C_3 = C_1 = 1; C_2 = C_0 = 0$
FSCALE	$\pm 0$ scaled by $-\infty$	*0
	$\pm 0$ scaled by $+\infty$	Invalid Operation
	$\pm 0$ scaled by X	*0
FEXTRACT	+0	$ST = +0, ST(1) = \infty,$
	-0	Zero divide $ST = -0, ST(1) = -\infty,$

Table 7-8. Zero Operands and Results (Contd.)

Operation	Operands	Result
		Zero divide
FPTAN	$\pm 0$	*0
FSIN (or SIN result of FSINCOS)	$\pm 0$	*0
FCOS (or COS result of FSINCOS)	$\pm 0$	+1
FPATAN	$\pm 0 \div + X$	*0
	$\pm 0 \div - X$	* $\pi$
	$\pm X \div \pm 0$	# $\pi/2$
	$\pm 0 \div + 0$	*0
	$\pm 0 \div - 0$	* $\pi$
	$+\infty \div \pm 0$	$+\pi/2$
	$-\infty \div \pm 0$	$-\pi/2$
	$\pm 0 \div + \infty$	*0
	$\pm 0 \div - \infty$	* $\pi$
F2XM1	+0	+0
	-0	-0
FYL2X	$\pm Y \times \log(\pm 0)$	Zero Divide
	$\pm 0 \times \log(\pm 0)$	Invalid Operation
FYL2XP1	$+ Y \times \log(\pm 0+1)$	*0
	$- Y \times \log(\pm 0+1)$	-*0

**NOTES:**

X and Y denote nonzero positive operands

- 1 When extreme underflow denormalizes the result to zero.
  - 2 Sign determined by rounding mode: + for nearest, up, or chop, - for down
  - 3 When  $0 < X < 1$  and rounding mode is not up.
  - 4 When  $-1 < X < 0$  and rounding mode is not down.
- \* Sign of original zero operand.  
# Sign of original X operand.  
-# Complement of sign of original X operand.

**Table 7-9. Infinity Operands and Results**

Operation	Operands	Result
FLD,FBLD	$\pm\infty$	$*\infty$
FST,FSTP,FRNDINT	$\pm\infty$	$*\infty$
FCHS	$+\infty$ $-\infty$	$-\infty$ $+\infty$
FABS	$\pm\infty$	$+\infty$
Addition	$+\infty$ plus $+\infty$ $-\infty$ plus $-\infty$ $+\infty$ plus $-\infty$ $-\infty$ plus $+\infty$ $\pm\infty$ plus $\pm X$ $\pm X$ plus $\pm\infty$	$+\infty$ $-\infty$ Invalid Operation Invalid Operation $*\infty$ $*\infty$
Subtraction	$+\infty$ minus $-\infty$ $-\infty$ minus $+\infty$ $+\infty$ minus $+\infty$ $-\infty$ minus $-\infty$ $\pm\infty$ minus $\pm X$ $\pm X$ minus $\pm\infty$	$+\infty$ $-\infty$ Invalid Operation Invalid Operation $*\infty$ $-\infty$
Multiplication	$\pm\infty \times \pm\infty$ $\pm\infty \times \pm Y, \pm Y \times \pm\infty$ $\pm\infty \times \pm Y, \pm Y \times \pm\infty$ $\pm 0 \times \pm\infty, \pm\infty \times \pm 0$	$\infty$ $\infty$ $\infty$ Invalid Operation
Division	$\pm\infty \div \pm\infty$ $+\infty \div \pm X$ $\pm X \div \pm\infty$	Invalid Operation $\infty$ 0
FPREM,FPREM1	$+\infty$ rem $\pm\infty$ $\pm\infty$ rem $\pm X$ $\pm X$ rem $\pm\infty$	Invalid Operation Invalid Operation \$X, Q = 0
FSQRT	$-\infty$ $+\infty$	Invalid Operation $+\infty$

Table 7-9. Infinity Operands and Results (Contd.)

Operation	Operands	Result
Compare	$+\infty : +\infty$	$+\infty = +\infty$
	$-\infty : -\infty$	$-\infty = -\infty$
	$+\infty : -\infty$	$+\infty > -\infty$
	$-\infty : +\infty$	$-\infty < +\infty$
	$+\infty : \pm X$	$+\infty > X$
	$-\infty : \pm X$	$-\infty < X$
	$\pm X : +\infty$	$X < +\infty$
	$\pm X : -\infty$	$X > +\infty$
	$+\infty$	$+\infty > 0$
FTST	$-\infty$	$-\infty < 0$
FSCALE	$\pm\infty$ scaled by $-\infty$	Invalid Operation
	$\pm\infty$ scaled by $+\infty$	$*\infty$
	$\pm\infty$ scaled by $\pm X$	$*\infty$
	$\pm 0$ scaled by $-\infty$	$\pm 0$
	$\pm 0$ scaled by $\infty$	Invalid Operation
	$\pm Y$ scaled by $+\infty$	$\#\infty$
	$\pm Y$ scaled by $-\infty$	$\#0$
FXTRACT	$\pm\infty$	ST = $*\infty$ , ST(1) = $+\infty$
FXAM	$+\infty$	C0 = C2 = 1; C1 = C3 = 0
	$-\infty$	C0 = C1 = C2 = 1; C3 = 0
FPATAN	$\pm\infty \div \pm X$	$*\pi/2$
	$\pm Y \div +\infty$	$\#0$
	$\pm Y \div -\infty$	$\#\pi$
	$\pm\infty \div +\infty$	$*\pi/4$
	$\pm\infty \div -\infty$	$*3\pi/4$
	$\pm\infty \div \pm 0$	$*\pi/2$
	$+0 \div +\infty$	$+0$
	$+0 \div -\infty$	$+\pi$
	$-0 \div +\infty$	$-0$
	$-0 \div -\infty$	$-\pi$

**Table 7-9. Operands and Results (Contd.)**

Operation	Operands	Result
F2XM1	$+\infty$ $-\infty$	$+\infty$ $-1$
FYL2X	$\pm\infty \times \log(1)$ $\pm\infty \times \log(X>1)$ $\pm\infty \times \log(0<X<1)$ $\pm Y \times \log(+\infty)$ $\pm 0 \times \log(+\infty)$ $\pm Y \times \log(-\infty)$	Invalid Operation $*\infty$ $-\infty$ $\#\infty$ Invalid Operation Invalid Operation
FYL2XP1	$\pm\infty \times \log(1)$ $\pm\infty \times \log(X>0)$ $\pm\infty \times \log$ $(-1<X<0)$ $\pm Y \times \log(+\infty)$ $\pm 0 \times \log(+\infty)$ $\pm Y \times \log(-\infty)$	Invalid Operation $*\infty$ $-\infty$ $\#\infty$ Invalid Operation Invalid Operation

**NOTES:**

- X Zero or nonzero, positive, finite operand
- Y Nonzero positive, finite operand
- \* Sign of original infinity operand.
- \* Complement of sign of original infinity operand
- \$ Sign of original operand.
- # Sign of the original Y operand.
- 1 Sign of original zero operand.

### 7.1.4. NaN (Not-a-Number)

A NaN (Not a Number) is a member of a class of special values that exists in the real formats only. A NaN has an exponent of 11..11B, may have either sign, and may have any significand except 1<sub>Δ</sub>00..00B, which is assigned to the infinities. A NaN in a register is tagged *special*.

There are two classes of NaN: signaling (SNaN) and quiet (QNaN). Among the QNaNs, the value *real indefinite* is of special interest.

#### 7.1.4.1. SIGNALING NaNs

A signaling NaN is a NaN that has a zero as the most significant bit of its fraction. The rest of the significand may be set to any value. The FPU never generates a signaling NaN as a result; however, it recognizes signaling NaNs when they appear as operands. Arithmetic operations (as defined at the beginning of this chapter) on a signaling NaN cause an invalid-operation exception (except for load operations from the stack, FXCH, FCHS, and FABS).

By unmasking the invalid operation exception, the programmer can use signaling NaNs to trap to the exception handler. The generality of this approach and the large number of NaN values that are available provide the sophisticated programmer with a tool that can be applied to a variety of special situations.

For example, a compiler could use signaling NaNs as references to uninitialized (real) array elements. The compiler could preinitialize each array element with a signaling NaN whose significand contained the index (relative position) of the element. If an application program attempted to access an element that it had not initialized, it would use the NaN placed there by the compiler. If the invalid operation exception were unmasked, an interrupt would occur, and the exception handler would be invoked. The exception handler could determine which element had been accessed, since the operand address field of the exception pointers would point to the NaN, and the NaN would contain the index number of the array element.

#### 7.1.4.2. QUIET NaNs

A quiet NaN is a NaN that has a one as the most significant bit of its significand. The processor creates the quiet NaN *real indefinite* (defined below) as its default response to certain exceptional conditions. The processor may derive other QNaNs by converting an SNaN. The processor converts a SNaN by setting the most significant bit of its significand to one, thereby generating a QNaN. The remaining bits of the significand are not changed; therefore, diagnostic information that may be stored in these bits of the SNaN is propagated into the QNaN.

The processor will generate the special QNaN, *real indefinite*, as its masked response to an invalid operation exception. This NaN is signed negative; its significand is encoded  $1_{\Delta}100.00$ . All other NaNs represent values created by programmers or derived from values created by programmers.

Both quiet and signaling NaNs are supported in all operations. A QNaN is generated as the masked response for invalid-operation exceptions and as the result of an operation in which at least one of the operands is a QNaN. The processor applies the rules shown in Table 7-10 when generating a QNaN.



Table 7-10. Rules for Generating QNaNs

Operation	Action
Real operation on an SNaN and a QNaN.	Deliver the QNaN operand.
Real operation on two SNaNs.	Deliver the QNaN that results from converting the SNaN that has the larger significand.
Real operation on two QNaNs.	Deliver the QNaN that has the larger significand.
Real operation on an SNaN and another number.	Deliver the QNaN that results from converting the SNaN.
Real operation on a QNaN and another number.	Deliver the QNaN.
Invalid operation that does not involve NaNs.	Deliver the default QNaN <i>real indefinite</i> .

Note that handling of a QNaN operand has greater priority than all exceptions except certain invalid-operation exceptions (refer to the section "Exception Priority" in this chapter).

Quiet NaNs could be used, for example, to speed up debugging. In its early testing phase, a program often contains multiple errors. An exception handler could be written to save diagnostic information in memory whenever it was invoked. After storing the diagnostic data, it could supply a quiet NaN as the result of the erroneous instruction, and that NaN could point to its associated diagnostic area in memory. The program would then continue, creating a different NaN for each error. When the program ended, the NaN results could be used to access the diagnostic data saved at the time the errors occurred. Many errors could thus be diagnosed and corrected in one test run.

In embedded applications which use computed results in further computations, an undetected QNaN can invalidate all subsequent results. Such applications should therefore periodically check for QNaNs and provide a recovery mechanism to be used if a QNaN result is detected.

### 7.1.5. Indefinite

For each numeric data type, one unique encoding is reserved for representing the special value *indefinite*. The processor produces this encoding as its response to a masked invalid-operation exception.

In the case of reals, the *indefinite* value is a QNaN as discussed in the prior section.

Packed decimal *indefinite* may be stored with a FBSTP instruction; attempting to use this encoding in a FBLD instruction, however, will have an undefined result; thus *indefinite* cannot be loaded from a packed decimal integer.

In the binary integers, the same encoding may represent either *indefinite* or the largest negative number supported by the format ( $-2^{15}$ ,  $-2^{31}$ , or  $-2^{63}$ ). The processor will store this encoding as its masked response to an invalid operation, or when the value in a source register represents or rounds to the largest negative integer representable by the destination. In situations where its origin may be ambiguous, the invalid-operation exception flag can be examined to see if the value was produced by an exception response. When this encoding is loaded or used by an integer arithmetic or compare operation, it is always interpreted as a negative number; thus, *indefinite* cannot be loaded from a binary integer.

## 7.1.6. Encoding of Data Types

Table 7-2 through Table 7-5 show how each of the special values just described is encoded for each of the numeric data types. In these tables, the least-significant bits are shown to the right and are stored in the lowest memory addresses. The sign bit is always the left-most bit of the highest-addressed byte.

### 7.1.6.1. UNSUPPORTED FORMATS

The extended format permits many bit patterns that do not fall into any of the previously mentioned categories. Table 7-6 shows these unsupported formats. Some of these encodings were supported by the Intel287 math coprocessor; however, most of them are not supported by the Intel387 math coprocessor, Intel486 processor, and Pentium processor FPUs. These changes are required due to changes made in the final version of IEEE Std 754 that eliminated these data types.

The categories of encodings formerly known as pseudo-NaNs, pseudoinfinities, and unnormal numbers are not supported. The Intel387 math coprocessor, Intel486 processor and Pentium processor FPU's raise the invalid-operation exception when they are encountered as operands.

The encodings formerly known as pseudodenormal numbers are not generated by the Pentium processor; however, they are correctly utilized when encountered as operands. The exponent is treated as if it were 00.01 and the mantissa is unchanged. The denormal exception is raised.

## 7.1.7. Numeric Exceptions

The FPU can recognize six classes of numeric exception conditions while executing numeric instructions:

1. I — Invalid operation
  - Stack fault
  - IEEE standard invalid operation
2. Z—Divide-by-zero

3. D—Denormalized operand
4. O—Numeric overflow
5. U—Numeric underflow
6. P—Inexact result (precision)

### 7.1.8. Handling Numeric Exceptions

When numeric exceptions occur, the processor takes one of two possible courses of action:

- The FPU can itself handle the exception, producing the most reasonable result and allowing numeric program execution to continue undisturbed.
- A software exception handler can be invoked to handle the exception.

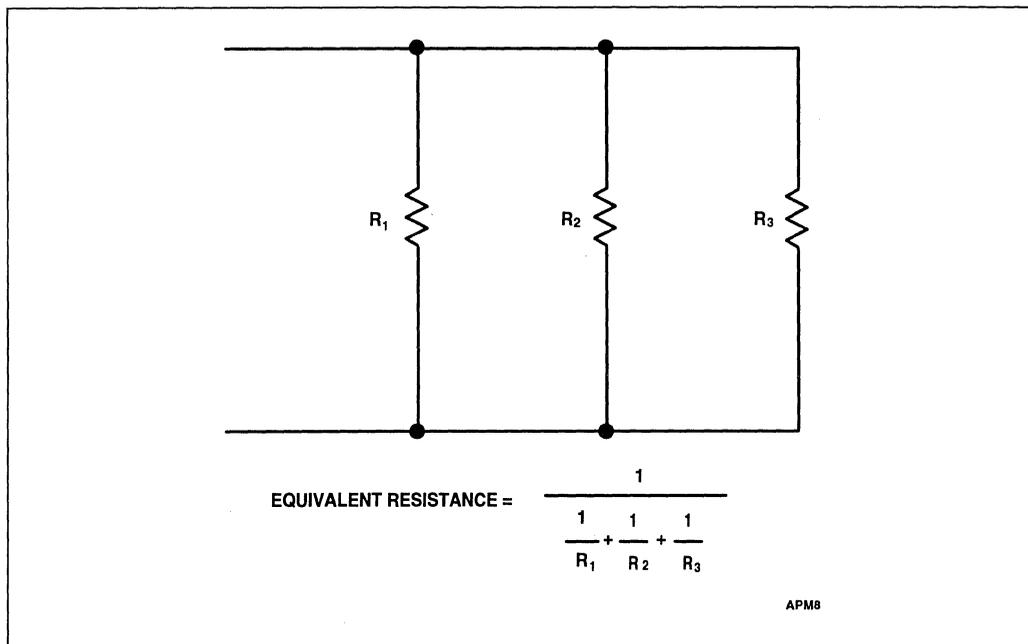
Each of the six exception conditions described above has a corresponding flag bit in the FPU status word and a mask bit in the FPU control word. If an exception is masked (the corresponding mask bit in the control word = 1), the processor takes an appropriate default action and continues with the computation. If the exception is unmasked (mask = 0), a software exception handler is invoked immediately before execution of the next WAIT or a floating-point instruction other than FNINIT, FNCLEX, FNSTSW, FNSTSW AX, FNSTCW, FNSTENV, FNSAVE. Depending on the value of the NE bit of the CR0 control register, the exception handler is invoked either (NE = 1) through interrupt vector 16 or (NE = 0) through an external interrupt.

Note that when exceptions are masked, the FPU may detect multiple exceptions in a single instruction, because it continues executing the instruction after performing its masked response. For example, the FPU could detect a denormalized operand, perform its masked response to this exception, and then detect an underflow.

#### 7.1.8.1. AUTOMATIC EXCEPTION HANDLING

The processor has a default fix-up activity for every possible exception condition it may encounter. These masked-exception responses are designed to be safe and are generally acceptable for most numeric applications.

As an example of how even severe exceptions can be handled safely and automatically using the default exception responses, consider a calculation of the parallel resistance of several values using only the standard formula (Figure 7-1). If R1 becomes zero, the circuit resistance becomes zero. With the divide-by-zero and precision exceptions masked, the processor will produce the correct result.



**Figure 7-1. Arithmetic Example Using Infinity**

By masking or unmasking specific numeric exceptions in the FPU control word, programmers can delegate responsibility for most exceptions to the processor, reserving the most severe exceptions for programmed exception handlers. Exception-handling software is often difficult to write, and the masked responses have been tailored to deliver the most reasonable result for each condition. For the majority of applications, masking all exceptions yields satisfactory results with the least programming effort. Certain exceptions can usefully be left unmasked during the debugging phase of software development, and then masked when the clean software is actually run. An invalid-operation exception for example, typically indicates a program error that must be corrected.

The exception flags in the FPU status word provide a cumulative record of exceptions that have occurred since these flags were last cleared. Once set, these flags can be cleared only by executing the FCLEX (clear exceptions) instruction, by reinitializing the FPU with FINIT, or by overwriting the flags with an FRSTOR or FLDENV instruction. This allows a programmer to mask all exceptions, run a calculation, and then inspect the status word to see if any exceptions were detected at any point in the calculation.

### 7.1.8.2. SOFTWARE EXCEPTION HANDLING

If the Pentium processor and Intel486 processor FPU encounters an unmasked exception condition, a software exception handler is invoked immediately before execution of the next WAIT or non-control floating-point instruction. The exception handler is invoked either

through interrupt vector 16 or through an external interrupt, depending on the value of the NE bit of the CR0 control register.

If NE = 1, an unmasked floating-point exception results in interrupt 16, immediately before the execution of the next non-control floating-point or WAIT instruction. Interrupt 16 is an operating-system call that invokes the exception handler. Chapter 14 contains a general discussion of exceptions and interrupts.

If NE = 0 (and the IGNNE# input is inactive), an unmasked floating-point exception causes the processor to freeze immediately before executing the next non-control floating-point or WAIT instruction. The frozen processor waits for an external interrupt, which must be supplied by external hardware in response to the FERR# output of the processor. (Regardless of the value of NE, an unmasked numerical exception causes the FERR# output to be activated.) In this case, the external interrupt invokes the exception-handling routine. If NE = 0 but the IGNNE# input is active, the processor disregards the exception and continues. Error reporting via external interrupt is supported for DOS compatibility. Chapter 23 contains further discussion of compatibility issues.

If the Intel387 math coprocessor NPX encounters an unmasked exception condition, it signals the exception to the Intel386 CPU using the ERROR# status line between the two processors. See Chapter 23 for differences in FPU exception handling.

The exception-handling routine is normally a part of the systems software. The routine must clear (or disable) the active exception flags in the FPU status word before executing any FP instructions that cannot complete execution when there is a pending FP exception. Otherwise, the FP instruction will trigger the FPU interrupt again, and the system will be caught in an endless loop. In any event, the routine must clear (or disable) the active exception flags in the FPU status word after handling them, and before IRET(D). Typical exception responses may include:

- Incrementing an exception counter for later display or printing
- Printing or displaying diagnostic information (e.g., the FPU environment and registers)
- Aborting further execution, or using the exception pointers to build an instruction that will run without exception and executing it

Applications programmers should consult their operating system's reference manuals for the appropriate system response to numerical exceptions. For systems programmers, some details on writing software exception handlers are provided in Chapter 14.

### 7.1.9. Invalid Operation

This exception may occur in response to two general classes of operations:

1. Stack operations
2. Arithmetic operations

The stack flag (SF) of the status word indicates which class of operation caused the exception. When SF is 1 a stack operation has resulted in stack overflow or underflow; when SF is 0, an arithmetic instruction has encountered an invalid operand.

### 7.1.9.1. STACK EXCEPTION

When SF is 1, indicating a stack operation, the O/U# bit of the condition code (bit C1) distinguishes between stack overflow and underflow as follows:

- O/U# = 1      Stack overflow—an instruction attempted to push down a nonempty stack location.
- O/U# = 0      Stack underflow—an instruction attempted to read an operand from an empty stack location.

When the invalid-operation exception is masked, the FPU returns the QNaN *indefinite*. This value overwrites the destination register, destroying its original contents.

When the invalid-operation exception is not masked, an exception handler is invoked. TOP is not changed, and the source operands remain unaffected.

### 7.1.9.2. INVALID ARITHMETIC OPERATION

This class includes the invalid operations defined in IEEE Std 854. The FPU reports an invalid operation in any of the cases shown in Table 7-11. Also shown in this table are the FPU's responses when the invalid exception is masked. When unmasked, an exception handler is invoked, and the operands remain unaltered. An invalid operation generally indicates a program error.

**Table 7-11. Masked Responses to Invalid Operations**

Condition	Masked Response
Any arithmetic operation on an unsupported format.	Return the QNaN <i>indefinite</i> .
Any arithmetic operation on a signaling NaN.	Return a QNaN (refer to the section "Rules for Generating QNaNs").
Compare and test operations: one or both operands is a NaN.	Set condition codes "not comparable."
Addition of opposite-signed infinities or subtraction of like-signed infinities.	Return the QNaN <i>indefinite</i> .
Multiplication: $\infty \times 0$ ; or $0 \times \infty$ .	Return the QNaN <i>indefinite</i> .
Division: $\infty \div \infty$ ; or $0 \div 0$ .	Return the QNaN <i>indefinite</i> .
Remainder instructions FPREM, FPREM1 when modulus (divisor) is zero or dividend is $\infty$ .	Return the QNaN <i>indefinite</i> ; set $C_2 = 0$ .
Trigonometric instructions FCOS, FPTAN, FSIN, FSINCOS when argument is $\infty$ .	Return the QNaN <i>indefinite</i> ; set $C_2 = 0$ .

**Table 7-11. Masked Responses to Invalid Operations (Contd.)**

Condition	Masked Response
FSQRT of negative operand (except FSQRT $(-0) = -0$ ), FYL2X of negative operand (except FYL2X $(-0) = -\infty$ ), FYL2XP1 of operand more negative than $-1$ .	Return the QNaN <i>indefinite</i> .
FBSTP instruction when source register is empty, a NaN, $\infty$ , or exceeds 18 decimal digits.	Store packed decimal <i>indefinite</i> .
FXCH instruction when one or both registers are tagged empty.	Change empty registers to the QNaN <i>indefinite</i> and then perform exchange.

### 7.1.10. Division by Zero

If an instruction attempts to divide a finite nonzero operand by zero, the FPU will report a zero-divide exception. This is possible for F(I)DIV(R)(P) as well as the other instructions that perform division internally: FYL2X and FXTRACT. The masked response for FDIV is to return an infinity signed with the exclusive OR of the sign of the two operands. FYL2X returns an infinity signed with the opposite sign of the non-zero operand. For FXTRACT, ST(1) is set to  $-\infty$ ; ST is set to zero with the same sign as the original operand. If the divide-by-zero exception is unmasked, an exception handler is invoked; the operands remain unaltered.

### 7.1.11. Denormal Operand

If an arithmetic instruction attempts to operate on a denormal operand, the FPU reports the denormal-operand exception. Denormal operands may have reduced significance due to lost low-order bits, therefore it may be advisable in certain applications to preclude operations on these operands. This can be accomplished by an exception handler that responds to unmasked denormal operand exceptions. Most users will mask this exception so that computation may proceed; any loss of accuracy will be analyzed by the user when the final result is delivered.

When this exception is masked, the FPU sets the DE-bit in the status word, then proceeds with the instruction. Gradual underflow and denormal numbers will produce results at least as good as, and often better than what could be obtained from a machine that flushes underflows to zero. In fact, a denormal operand in single- or double-precision format will be normalized to the extended-real format when loaded into the FPU. Subsequent operations will benefit from the additional precision of the extended-real format used internally.

When this exception is not masked, the DE-bit is set and the exception handler is invoked. The operands are not changed by the instruction and are available for inspection by the exception handler.

The Pentium processor FPU, Intel486 processor FPU, and Intel387 math coprocessors handle denormal values differently than the 8087 and Intel287 math coprocessors. This change is due to revisions in the IEEE standard before being approved. The difference in operation occurs when the denormal exception is masked. The Pentium processor FPU, Intel486 processor FPU, and Intel387 math coprocessors will automatically normalize denormals. The 8087 and Intel287 math coprocessors will generate a denormal result.

The difference in denormal handling is usually not an issue. The denormal operand exception is normally masked for the Intel387 math coprocessor, Intel486 processor, and Pentium processor FPUs. For programs that also run on an Intel287 math coprocessor, the denormal exception is often unmasked and an exception handler is provided to normalize any denormal values. Such an exception handler is redundant for the Pentium processor, Intel486 processor and Intel387 DX math coprocessor FPUs. The default exception handler should be used. See Chapter 23 for more information on the handling of exceptions by the various Intel architectures.

A program can detect at run time whether it is running on a Pentium processor, Intel486 processor, or Intel387 math coprocessor FPU or the older 8087/Intel287 math coprocessors. See Chapter 5 for example code sequences to determine the presence of 8087/Intel287 and Intel387 math coprocessors, as well as processor type. This example can be used to selectively mask the denormal exception for Intel387 DX math coprocessor, Intel486 processor or Pentium processor FPUs. A denormal exception handler should also be provided to support 8087/Intel287 math coprocessors. This code example can also be used to set a flag to allow use of new instructions added to the Intel387 math coprocessor, Intel486 processor, and Pentium processor FPUs beyond the instructions of the 8087/Intel287 math coprocessors.

## 7.1.12. Numeric Overflow and Underflow

If the exponent of a numeric result is too large for the destination real format, the FPU signals a numeric overflow. Conversely, if the exponent of a result is too small to be represented in the destination format, a numeric underflow is signaled. If either of these exceptions occur, the result of the operation is outside the range of the destination real format.

Typical algorithms are most likely to produce extremely large and small numbers in the calculation of intermediate, rather than final, results. Because of the great range of the extended-precision format, overflow and underflow are relatively rare events in most numerical applications.

### 7.1.12.1. OVERFLOW

The overflow exception can occur whenever the rounded true result would exceed in magnitude the largest finite number in the destination format. The exception can occur in the execution of most of the arithmetic instructions and in some of the conversion instructions; namely, FST(P), F(I)ADD(P), F(I)SUB(R)(P), F(I)MUL(P), FDIV(R)(P), FSCALE, FYL2X, and FYL2XP1.

The response to an overflow condition depends on whether the overflow exception is masked:

- Overflow exception masked. The value returned depends on the rounding mode as Table 7-12 illustrates.
- Overflow exception not masked. The unmasked response depends on whether the instruction is supposed to store the result on the stack or in memory:
  - If the destination is the stack, then true result is divided by  $2^{24,576}$  and rounded. (The bias 24,576 is equal to  $3 \times 2^{13}$ .) The significand is rounded to the appropriate precision (according to the precision control (PC) bit of the control word, for those instructions controlled by PC, otherwise to extended precision). The roundup bit (C1) of the status word is set if the significand was rounded upward. The biasing of the exponent by 24,576 normally translates the number as nearly as possible to the middle of the exponent range so that, if desired, it can be used in subsequent scaled operations with less risk of causing further exceptions. With the instruction FSCALE, however, it can happen that the result is too large and overflows even after biasing. In this case, the unmasked response is exactly the same as the masked round-to-nearest response, namely  $\pm$  infinity. The intention of this feature is to ensure the trap handler will discover that a translation of the exponent by  $-24574$  would not work correctly without obliging the programmer of Decimal-to-Binary or Exponential functions to determine which trap handler, if any, should be invoked.
  - If the destination is memory (this can occur only with the store instructions), then no result is stored in memory. Instead, the operand is left intact in the stack. Because the data in the stack is in extended-precision format, the exception handler has the option either of reexecuting the store instruction after proper adjustment of the operand or of rounding the significand on the stack to the destination's precision as the standard requires. The exception handler should ultimately store a value into the destination location in memory if the program is to continue.

**Table 7-12. Masked Overflow Results**

Rounding Mode	Sign of True Result	Result
To nearest	+	$+\infty$
	-	$-\infty$
Toward $-\infty$	+	Largest finite positive number
	-	$-\infty$
Toward $+\infty$	+	$+\infty$
	-	Largest finite negative number
Toward zero	+	Largest finite positive number
	-	Largest finite negative number

### 7.1.12.2. UNDERFLOW

Underflow can occur in the execution of the instructions FST(P), FADD(P), FSUB(RP), FMUL(P), F(I)DIV(RP), FSCALE, FPREM(1), FPTAN, FSIN, FSINCOS, FPATAN, F2XM1, FYL2X, and FYL2XP1.

Two related events contribute to underflow:

1. Creation of a tiny (denormal) result which, because it is so small, may cause some other exception later (such as overflow upon division).
2. Creation of an inexact result; i.e., the delivered result differs from what would have been computed were both the exponent range and precision unbounded.

Which of these events triggers the underflow exception depends on whether the underflow exception is masked:

1. Underflow exception masked. The underflow exception is signaled when the result is both tiny and inexact.
2. Underflow exception not masked. The underflow exception is signaled when the result is tiny, regardless of inexactness.

The response to an underflow exception also depends on whether the exception is masked:

1. Masked response. The result is denormal or zero. The precision exception is also triggered.
2. Unmasked response. The unmasked response depends on whether the instruction is supposed to store the result on the stack or in memory.

— If the destination is the stack, then the true result is multiplied by  $2^{24,576}$  and rounded. (The bias 24,576 is equal to  $3 \times 2^{13}$ .) The significand is rounded to the appropriate precision (according to the precision control (PC) bit of the control word, for those instructions controlled by PC, otherwise to extended precision). The roundup bit (C1) of the status word is set if the significand was rounded upward.

The biasing of the exponent by 24,576 normally translates the number as nearly as possible to the middle of the exponent range so that, if desired, it can be used in subsequent scaled operations with less risk of causing further exceptions. With the instruction FSCALE, however, it can happen that the result is too tiny and underflows even after biasing. In this case, the unmasked response is exactly the same as the masked round-to-nearest response, namely  $\pm 0$ . The intention of this feature is to ensure the trap handler will discover that a translation by +24576 would not work correctly without obliging the programmer of Decimal-to-Binary or Exponential functions to determine which trap handler, if any, should be invoked.

— If the destination is memory (this can occur only with the store instructions), then no result is stored in memory. Instead, the operand is left intact in the stack. Because the data in the stack is in extended-precision format, the exception handler has the option either of reexecuting the store instruction after proper adjustment of the operand or of rounding the significand on the stack to the destination's precision as

the standard requires. The exception handler should ultimately store a value into the destination location in memory if the program is to continue.

### 7.1.13. Inexact (Precision)

This exception condition occurs if the result of an operation is not exactly representable in the destination format. For example, the fraction 1/3 cannot be precisely represented in binary form. This exception occurs frequently and indicates that some (generally acceptable) accuracy has been lost.

By their nature, the transcendental instructions cause the inexact exception for their core cases. This means that some special cases where results are represented exactly will nonetheless cause the inexact exception, e.g. arguments into  $\log_2$  which are integer powers of 2. Table 7-13 lists the core cases for each of the transcendental instructions.

**Table 7-13. Transcendental Core Ranges**

Instruction	Core Range
FSIN	$  \theta   < 2^{63}$
FCOS	$  \theta   < 2^{63}$
FSINCOS	$  \theta   < 2^{63}$
FPTAN	$  \theta   < 2^{63}$
FPATAN	no restriction
F2XM1	$-1 < X < 1$
FYL2X*	$X > 0$
FYL2XP1*	$-(1-(\sqrt{2}/2)) \leq ST \leq \sqrt{2}-1$

**NOTES:** For these 2-operand instructions, Y should be normal for the core cases.

The C1 (roundup) bit of the status word indicates whether the inexact result was rounded up (C1 = 1) or chopped (C1 = 0).

The inexact exception accompanies the underflow exception when there is also a loss of accuracy. When underflow is masked, the underflow exception is signaled only when there is a loss of accuracy; therefore the precision flag is always set as well. When underflow is unmasked, there may or may not have been a loss of accuracy; the precision bit indicates which is the case.

This exception is provided for applications that need to perform exact arithmetic only. Most applications will mask this exception. The FPU delivers the rounded or over/underflowed result to the destination, regardless of whether a trap occurs.

### 7.1.14. Exception Priority

The processor deals with exceptions according to a predetermined precedence. Precedence in exception handling means that higher-priority exceptions are flagged and results are delivered according to the requirements of that exception. Lower-priority exceptions may not be flagged even if they occur. For example, dividing an SNaN by zero causes an invalid-operand exception (due to the SNaN) and not a zero-divide exception; the masked result is the QNaN *real indefinite*, not  $\infty$ . A denormal or inexact (precision) exception, however, can accompany a numeric underflow or overflow exception.

The precedence among numeric exceptions is as follows:

1. Invalid operation exception, subdivided as follows:
  - a. Stack underflow.
  - b. Stack overflow.
  - c. Operand of unsupported format.
  - d. SNaN operand.
2. QNaN operand. Though this is not an exception, if one operand is a QNaN, dealing with it has precedence over lower-priority exceptions. For example, a QNaN divided by zero results in a QNaN, not a zero-divide exception.
3. Any other invalid-operation exception not mentioned above or zero divide.
4. Denormal operand. If masked, then instruction execution continues, and a lower-priority exception can occur as well.
5. Numeric overflow and underflow. Inexact result (precision) can be flagged as well.
6. Inexact result (precision).

### 7.1.15. Standard Underflow/Overflow Exception Handler

As long as the underflow and overflow exceptions are masked, no additional software is required to cause the output of the processor to conform to the requirements of IEEE Std 854. When unmasked, these exceptions give the exception handler an additional option in the case of store instructions. No result is stored in memory; instead, the operand is left intact on the stack. The handler may round the significand of the operand on the stack to the destination's precision as the standard requires, or it may adjust the operand and reexecute the faulting instruction.





8

**Numeric  
Programming  
Examples**





## CHAPTER 8

# NUMERIC PROGRAMMING EXAMPLES

The following sections contain examples of numeric programs written in ASM386/486. These examples are intended to illustrate some of the techniques useful for programming numeric applications.

### 8.1. CONDITIONAL BRANCHING EXAMPLE

As discussed earlier, several numeric instructions post their results to the condition code bits of the FPU status word. Although there are many ways to implement conditional branching following a comparison, the basic approach is as follows:

- Execute the comparison.
- Store the status word. (The FPU status word can be stored directly into AX register.)
- Inspect the condition code bits.
- Jump on the result.

Example 8-1 is a code fragment that illustrates how two memory-resident double-format real numbers might be compared (similar code could be used with the FTST instruction). The numbers are called A and B, and the comparison is A to B.

#### Example 8-1. Conditional Branching for Compares

```

      .
      .
A     DQ     ?
B     DQ     ?
      .
      .
      .
      FLD     A      ; LOAD A ONTO TOP OF FPU STACK
      FCOMPB          ; COMPARE A;B POP A
      FSTSWAX        ; STORE RESULT TO AX REGISTER
;
; CPU AX REGISTER CONTAINS CONDITION CODES
; (RESULTS OF COMPARE)
; LOAD CONDITION CODES INTO FLAGS
;
      SAHF
;
; USE CONDITONAL JUMPS TO DETERMINE ORDERING OF A TO B

```

```

;
    JP    A_B_UNORDERED    ; TEST C2 (PF)
    JB    A_LESS           ; TEST C0 (CF)
    JE    A_EQUAL         ; TEST C3 (ZF)
A_GREATER:                ; C0 (CF) = 0, C3 (ZF) = 0
    .
    .
A_EQUAL :                 ; C0 (CF) 1, C3 (ZF) = 0
    .
    .
A_LESS                ; CD (CF) = 1, C3 (ZF) = 0
    .
    .
A_B_UNORDERED:        ; C2 (PF) = 1
    .
    .

```

The comparison itself requires loading A onto the top of the FPU register stack and then comparing it to B, while popping the stack with the same instruction. The status word is then written into the AX register.

A and B have four possible orderings, and bits C3, C2, and C0 of the condition code indicate which ordering holds. These bits are positioned in the upper byte of the FPU status word so as to correspond to the zero, parity, and carry flags (ZF, PF, and CF), when the byte is written into the flags. The code fragment sets ZF, PF, and CF of the EFLAGS register to the values of C3, C2, and C0 of the FPU status word, and then uses the conditional jump instructions to test the flags. The resulting code is extremely compact, requiring only seven instructions.

The FXAM instruction updates all four condition code bits. Example 8-2 shows how a jump table can be used to determine the characteristics of the value examined. The jump table (FXAM\_TBL) is initialized to contain the 32-bit displacement of 16 labels, one for each possible condition code setting. Note that four of the table entries contain the same value, "EMPTY." The first two condition code settings correspond to "EMPTY." The two other table entries that contain "EMPTY" will never be used on the 32-bit processors with integrated FPU or the Intel387 math coprocessor, but may be used if the code is executed with an Intel287 math coprocessor.

**Example 8-2. Conditional Branching for FXAM**

```

;    JUMP TABLE FOR EXAMINE ROUTINE
;
FXAM-TBL DD POSS_UNNORM, POS NAN, NEG_UNNORN, NEG_NAN,
&        POS_NORM, POS_INFINITY, NEG_NORM,
&        NEG_NFINITY, POS_ZERO, EMPTY, NEG_ZERO
&        EMPTY, POS_DENORM, EMPTY, NEG_DENORM, EMPTY
    .
    .

```



```

; EXAMINE ST AND STORE RESULT (CONDITION CODES)
FXAM
XOR     EAX, EAX           ; CLEAR EAX
FSTSWAX

; CALCULATE OFFSET INTO JUMP TABLE

AND     AX, 0100011100000000B ; CLEAR ALL BITS EXCEPT C3,
C2-C0
SHR     EAX, 6             ; SHIFT C2-C0 INTO PLACE
(000XXX00)
SAL     AH, 5              ; POSITION C3 (00X00000)
OR      AL, AH             ; DROP C3 IN ADJACENT TO C2
(00XXXX00)
XOR     AH, AH            ; CLEAR OUT THE OLD COPY OF
C3

; JUMP TO THE ROUTINE ' ADDRESSED' BY CONDITION CODE

JMP     FXAM_TBL[EAX]

; HERE ARE THE JUMP TARGETS, ONE TO HANDLE
; EACH POSSIBLE RESULT OF FXAM

POS_UNNORM:
.
POS_NAM:
.
NEG_UNNOM:
.
NEG_NAM:
.
POS_NORM:
.
POS_INFINITY:
.
NEG_NORM:
.
NEG_INFINITY:
.
POS_ZERO:
.
EMPTY:
.
NEG_ZERO:

```

```
POS_DENORM:
```

```
NEG_DENORM:
```

The program fragment performs the FXAM and stores the status word. It then manipulates the condition code bits to finally produce a number in register AX that equals the condition code times 2. This involves zeroing the unused bits in the byte that contains the code, shifting C3 to the right so that it is adjacent to C2, and then shifting the code to multiply it by 2. The resulting value is used as an index that selects one of the displacements from FXAM\_TBL (the multiplication of the condition code is required because of the 2-byte length of each value in FXAM\_TBL). The unconditional JMP instruction effectively vectors through the jump table to the labeled routine that contains code (not shown in the example) to process each possible result of the FXAM instruction.

## 8.2. EXCEPTION HANDLING EXAMPLES

There are many approaches to writing exception handlers. One useful technique is to consider the exception handler procedure as consisting of "prologue," "body," and "epilogue" sections of code. This procedure is invoked via interrupt number 16.

In the transfer of control to the exception handler due to an INTR, NMI, or SMI, interrupts have been disabled by hardware. The prologue performs all functions that must be protected from possible interruption by higher-priority sources. Typically, this involves saving registers and transferring diagnostic information from the FPU to memory. When the critical processing has been completed, the prologue may re-enable interrupts to allow higher-priority interrupt handlers to preempt the exception handler. The standard "prologue" not only saves the registers and transfers diagnostic information from the FPU to memory but also clears the FP exception flags in the status word. Alternatively, when it is not necessary for the handler to be re-entrant, another technique may also be used. In this technique, the exception flags are not cleared in the "prologue" and the body of the handler must not contain any FP instructions that cannot complete execution when there is a pending FP exception. Please refer to section 6.3.7 where these instructions are classified. Note that the handler must still clear the exception flag(s) before executing the IRET. If the exception handler uses neither of these techniques the system will be caught in an endless loop.

The body of the exception handler examines the diagnostic information and makes a response that is necessarily application-dependent. This response may range from halting execution, to displaying a message, to attempting to repair the problem and proceed with normal execution.

The epilogue essentially reverses the actions of the prologue, restoring the processor so that normal execution can be resumed. The epilogue must *not* load an unmasked exception flag into the FPU or another exception will be requested immediately.

The following code examples show the ASM386/486 coding of three skeleton exception handlers. They show how prologues and epilogues can be written for various situations, but

provide comments indicating only where the application dependent exception handling body should be placed.

The first two are very similar; their only substantial difference is their choice of instructions to save and restore the FPU. The tradeoff here is between the increased diagnostic information provided by FNSAVE and the faster execution of FNSTENV. For applications that are sensitive to interrupt latency or that do not need to examine register contents, FNSTENV reduces the duration of the "critical region," during which the processor does not recognize another interrupt request.

After the exception handler body, the epilogues prepare the processor to resume execution from the point of interruption (i.e., the instruction following the one that generated the unmasked exception). Notice that the exception flags in the memory image that is loaded into the FPU are cleared to zero prior to reloading (in fact, in these examples, the entire status word image is cleared).

Example 8-3 and Example 8-4 assume that the exception handler itself will not cause an unmasked exception. Where this is a possibility, the general approach shown in Example 8-5 can be employed. The basic technique is to save the full FPU state and then to load a new control word in the prologue. Note that considerable care should be taken when designing an exception handler of this type to prevent the handler from being reentered endlessly.

### Example 8-3. Full-State Exception Handler

```
SAVE_ALL PROC
;
; SAVE REGISTERS, ALLOCATE STACK SPACE
; FOR FPU STATE IMAGE
    PUSH EBP
    .
    .
    MOV EBP, ESP
    SUB ESP, 108
;SAVE FULL FPU STATE, ENABLE INTERRUPTS
    FNSAVE [EBP-108]
    STI
;
; APPLICATION-DEPENDENT EXCEPTION HANDLING
; CODE GOES HERE
;
; CLEAR EXCEPTION FLAGS IN STATUS WORD
; (WHICH IS IN MEMORY)
; RESTORE MODIFIED STATE IMAGE
    MOV BYTE PTR [EBP-104], 0H
    FRSTOR [EBP-108]
; DEALLOCATE STACK SPACE, RESTORE REGISTERS
    MOV ESP, EBP
```

```

        .
        POP        EBP
;
; RETURN TO INTERRUPTED CALCULATION
        IRET
SAVE_ALL  ENDP

```

#### Example 8-4. Reduced-Latency Exception Handler

```

SAVE_ENVIRONMENT  PROC
;
; SAVE REGISTERS, ALLOCATE STACK SPACE
; FOR FPU ENVIRONMENT
        PUSH        EBP
        .
        .
        MOV         EBP, ESP
        SUB         ESP, 28
;SAVE ENVIRONMENT, ENABLE INTERRUPTS
        FNSTENV    ..[EBP-28]
        STI
;
; APPLICATION-DEPENDENT EXCEPTION HANDLING
; CODE GOES HERE
;
; CLEAR EXCEPTION FLAGS IN STATUS WORD
; (WHICH IS IN MEMORY)
; RESTORE MODIFIED ENVIRONEMNT IMAGE
        MOV         BYTE PTR [EBP-24], 0H
        FLDENV     [EBP-28]
; DEALLOCATE STACK SPACE, RESTORE REGISTERS
        MOV         ESP, EBP
        .
        .
        POP        EBP
;
; RETURN TO INTERRUPTED CALCULATION
        IRET
SAVE_ENVIRONMENT  ENDP

```

#### Example 8-5. Reentrant Exception Handler

```

        .
        .
LOCAL_CONTROL DW ? ; ASSUME INITIALIZED
        .

```

```

.
REENTRANT PROC
;
; SAVE REGISTERS, ALLOCATE STACK SPACE
; FOR FPU STATE IMAGE
    PUSH EBP
.
    MOV     EBP, ESP
    SUB     ESP, 108
; SAVE STATE, LOAD NEW CONTROL WORD,
; ENABLE INTERRUPTS
    FNSAVE [EBP-108]
    FLDCW  LOCAL_CONTROL
    STI
.
.
;
; APPLICATION-DEPENDENT EXCEPTION HANDLING
; CODE GOES HERE
; AN UNMASKED EXCEPTION GENERATED HERE WILL
; CAUSE THE EXCEPTION HANDLER TO BE REENTERED.
; IF LOCAL STORAGE IS NEEDED, IT MUST BE ALLOCATED
; ON THE STACK.
;
.
.
; CLEAR EXCEPTION FLAGS IN STATUS WORD
; (WHICH IS IN MEMORY)
; RESTORE MODIFIED STATE IMAGE
    MOV     BYTE PTR [EBP-104], 0H
    FRSTOR [EBP-108]
; DEALLOCATE STACK SPACE, RESTORE REGISTERS
    MOV     ESP, EBP
.
.
    POP     EBP
;
; RETURN TO POINT OF INTERRUPTION
    IRET
REENTRANT ENDP

```

### 8.3. FLOATING POINT TO ASCII CONVERSION EXAMPLES

Numeric programs must typically format their results at some point for presentation and inspection by the program user. In many cases, numeric results are formatted as ASCII

strings for printing or display. This example shows how floating-point values can be converted to decimal ASCII character strings. Example 8-6 was developed using Intel's assemblers. Modification will need to be made to meet the requirements of other vendor's assemblers or their interface to high level languages.

Shortness, speed, and accuracy were chosen rather than providing the maximum number of significant digits possible. An attempt is made to keep integers in their own domain to avoid unnecessary conversion errors.

Using the extended precision real number format, this routine achieves a worst case accuracy of three units in the 16th decimal position for a noninteger value or integers greater than  $10^{18}$ . This is double precision accuracy. With values having decimal exponents less than 100 in magnitude, the accuracy is one unit in the 17th decimal position.

Higher precision can be achieved with greater care in programming, larger program size, and lower performance.

**Example 8-6. Floating Point to ASCII Conversion Routine**

SOURCE

```
+1 $title ('Convert a floating point number to ASCII')

        name      floating_to_ascil

        public    floating_to_ascii
        extrn     get_power_10:near, tos_status:near

;
; This subroutine will convert the floating point
; number in the top of the NPX stack to an ASCII
; string and separate power of 10 scaling value
; (in binary). The maximum width of the ASCII string
; formed is controlled by a parameter which must be
; >1. Unnormal values, denormal values, and pseudo
; zeros will be correctly converted. However,
; unnormals and pseudo zeros are no longer supported
; formats on the Intel486 processor in conformance with
; the IEEE floating point standard) and hence
; not generated internally. A returned value will
; indicate how many binary bits of precision were lost
; in an unnormal or denormal value. The magnitude
; (in terms of binary power) of a psuedo zero will also
; be indicated. Integers less than 10**18 in magnitude
; are accurately converted if the destination ASCII
; string field is wide enough to hold all the digits.
; Otherwise the value is converted to scientific notation.
```

```
;
; The status of the conversion is indentified by the
; return value, it can be:
;
; 0 Conversion complete, string size is defined
; 1 invalid arguments
; 2 exact integer conversion, string_size is defined
; 3 indefinite
; 4 + NAN (Not A Number)
; 5 - NAN
; 6 + Infinity
; 7 - Infinity
; 8 pseudo zero found, string_size is defined

; The PLM-386/486 calling convention is:
;
; floating_to_ascii:
;     procedure (number, denormal_ptr, string_ptr, size_ptr,
; field_size, power_ptr) word external:
; declare (denormal_ptr, string_ptr, size_ptr)
; pointer;
; declare field_size word,
; string_size based size_ptr word;
; declare number real;
; declare denormal integer based denormal_ptr;
; declare power integer based power_ptr;
; end floating_to_ascii;
;
; The floating point value is expected to be
; on the top of the FPU stack. This subroutine
; expects 3 free entries on the FPU stack and
; will pop the passed value off when done. The
; generated ASCII string will have a leading
; character either '-' or '+' indicating the sign
; of the value. The ASCII decimal digits will
; immediately follow. The numeric value of the
; ASCII string is (ASCII STRING.)*10 power. If
; the given number was zero, the ASCII string will
; contain a sign and a single zero character. The
; value string_size indicates the total length of
; ASCII string including the sign character.
; String(0) will always hold the sign. It is
; possible for string_size to be less than
; field_size. This occurs for zeroes of integer
; values. A psuedo zero will return a special
; return code. The denormal count will indicate
; the power of two originally associated with the
```

```

; value. The power of ten and ASCII string will
; be as if the value was an ordinary zero.
;
; This subroutine is accurate up to a maximum of
; 18 decimal digits for integers. Integer values
; will have a decimal power of zero associated
; with the item. For non-integers, the result will be
; accurate to within 2 decimal digits of the 16th
; decimal place(double precision). The exponentiate
; instruction is also used for scaling the value into
; the range acceptable for the BCD data type. The
; rounding mode in effect on entry to the
; subroutine is used for the conversion.
;
; The following registers are not transparent:
;
;     eax ebx edx esi edi eflags
;
; Define the stack layout.
;
ebp_save      equ  dword ptr [ebp]
es_save       equ  ebp_save + size ebp_save
return_ptr    equ  es_save + size es_save
power_ptr     equ  return_ptr + size return_ptr
field_size    equ  power_ptr + size power_ptr
size_ptr      equ  field_size + size field_size
string_ptr    equ  size_ptr + size size_ptr
denormal_ptr  equ  string_ptr + size string_ptr

parms_size    equ  size power_ptr + size field_size +
&              size size_ptr + size string_ptr +
&              size denormal_ptr
;
; Define Constants used
;
BCD DIGITS    equ  18    ; number of digits in bcd_value
WORD_SIZE    equ  4
BCD_SIZE     equ  10
MINUS        equ  1     ; Define return values
NAN          equ  4     ; The exact values chosen
INFINITY     equ  6     ; here are important. They must
INDEFINITE   equ  3     ; correspond to the possible return
PSUDO-ZERO   equ  8     ; values and be in the same numeric
INVALID      equ  -2    ; order as tested by the program.
ZERO         equ  -4

```



```

DENORMAL      equ   -6
UNNORMAL     equ   -8
NORMAL       equ   0
EXACT        equ   2
;
; Define layout of temporary storage area.
;
power_two    equ   word ptr [EBP - WORD_SIZE]
bcd_value    equ   tbyte ptr power_two - BCD_SIZE
bcd_byte     equ   byte ptr bcd_value
fraction     equ   bcd_value

local_size   equ   size power_two + size bcd_value
;
; Allocate stack space for the temporaries so
; the stack will be big enough
;
stack stackseg (local_size+6) ; allocate stack
; space for locals

code segment public er
    extrn power_table:qword
;
; Constants used by this function
;
                even                ; Optimize for 16 bits
const10        dw                    ; Adjustment value for
                ; too big BCD

; Convert the C3,C2, C1, C0 encoding from tos_status
; into meaningful bit flags and values.
;
status_table   db   UNNORMAL, NAN, UNNORMAL + MINUS,
&   NAN + MINUS, NORMAL, INFINITY,
&   NORMAL + MINUS, INFINITY + MINUS,
&   ZERO, INVALID, ZERO + MINUS, INVALID,
&   DENORMAL, INVALID, DENORMAL + MINUS, INVALID
floating_to_ascii proc

                call tos_status      ; Look at status of ST(0)

; Get descriptor from table
                movzx eax, staus_table[eax]
                cmp     al, INVALID   ; Look for empty ST(0)
                jne     not_empty
;

```

```

; ST(0) is empty! Return the status value.
    ret     parms_size
;
; Remove infinity from stack and exit.
;
found_infinity:
    fstp st(0)           ; OK to leave fstp running
    jmp  short exit_proc
;
; String space is too small
; Return invalid code.
;
small_string:
    mov     al,INVALID
exit_proc:
    leave                    ; Restore stack setup

    pop     es
    ret     parms_size
;
; ST(0) is NAN or indefinite. Store the
; value in memory and look at the fraction
; field to separate indefinite from an ordinary NAN.
;
NAN_or_indefinite:
    fstp fraction           ; remove value from stack
                                ; for examination
    test al, MINUS         ; Look at sign bit
    fwait                    ; Insure store is done
    jz  exit_proc          ; Can't be indefinite if positive

    mov  ebx,0C0000000H ; Match against upper 32 bits of fraction

; Compare bits 63-32
    sub  ebx, dword ptr fraction + 4

; Bits 31-0 must be zero
    or   ebx, dword ptr fraction
    jnz  exit_proc

; Set return value for indefinite value
    mov  al, INDEFINITE
    jmp  exit_proc
;
; Allocate stack space for local variables
; and establish parameter addressability.
;

```

```

not_empty:
    push es                                ; Save working register
    enter local_size, 0                    ; Setup stack addressing

; check for enough string space
    mov ecx, field_size
    cmp ecx, 2
    jl  small_string

    dec ecx                                ;adjust for sign character

; See if string is too large for BCD
    cmp ecx,BCD_DIGITS
    jbe size_ok

; Else set maximum string size
    mov ecx, BCD_DIGITS
size_ok:
    cmp al,INFINITY                        ;Look for infinity

; Return status value for + or - inf
    jge found_infinity
    cmp al, NAN                            ; Look for NAN INDEFINITE
    jge NAN_or_indefinite

;
; Set default return values and check that
; the number is normalized.
;
    fabs                                  ;use positive value
only
; sign bit in al

has true sign of
; value
    xor edx,edx                            ; form 0 constant
    mov edi, denormal_ptr                  ; zero denormal count
    mov [edi], dx
    mov ebx, power_ptr                    ; zero power of ten value
    mov [ebx], dx
    mov dl, al
    and dl, 1
    add dl, EXACT
    cmp al, ZERO                          ; Test for zero
    jae convert_integer                   ; skip power code if value is zero
    fstp fraction
    fwait
    mov al, bcd_byte +7

```

```

    or             byte ptr bcd_byte +7, 80h
    fld fraction
    fextract
    test al, 80h
    jnz normal_value

    fld1
    fsub
    ftst
    fstswax
    sahf
    jnz set_unnormal_count
;
; Found a psuedo zero
;
    fldlg2                               ; Develop power of ten
estimate
    add dl, PSUEDO_ZERO - EXACT
    fmulpst(2), st
    fxch                                   ; Get power of ten
    fistpword ptr [ebx]                   ; set power of ten
    jmp convert_integer

set_unnormal_count:
    fextract                               ; Get original fraction,
                                           ; now normalized
    fxch                                   ; Get unnormal count
    fchs
    fistpword ptr [edi] ; set unnormal count

; Calculate the decimal magnitude associated
; with this number to within one order. This
; error will always be inevitable due to
; rounding and lost precision. As a result,
; we will deliberately fail to consider the
; LOG10 of the fraction value in calculating
; the order. Since the fraction will always
; be 1 <= f < 2, its LOG10 will not change
; the basic accuracy of the function. To
; get the decimal order of magnitude, simply
; multiply the power of two by LOG10(2) and
; truncate the result to an integer.
;
normal_value:
    fstp fraction                           ; Save the fraction field
                                           ; for later use

```



```

        fist power_two           ; Save power of two
        fldlg2                   ; Get LOG10(2)
                                   ; Power_two is now safe
to use
        fmul                     ; Form LOG10(of exponent of
number)
        fistpword ptr [ebx] ; Any rounding mode will work here
;
; Check if the magnitude of the number rules
; out treating it is an integer.
;
; CX has the maximum number of decimal digits
; allowed.
;
        fwait                   ; Wait for power-ten to be
valid

; Get power of ten of value
        movsxi, word ptr [ebx]
        sub esi, ecx           ; Form scaling factor necessary in ax
        ja     adjust_result  ; Jump if number will not fit
;
; The number is between 1 and 10**(field_size).
; Test if it is an integer.
;
        field power_two ; Restore original number
        sub dl, NORMAL_EXACT ; Convert to exact return value
        fld fraction
        fscale                ; Form full value, this
                                   ; is safe here
        fst st(1)             ; Copy value for compare
        frndint                ; Test if its an integer
        fcomp                  ; Compare values
        fstswax                ; Save status
        sahf                    ; C3=1 implies it was an integer
        jnz convert_integer

        fstp st(0)            ; Remove non integer value
        add dl, NORMAL_EXACT ; Restore original return

; Scale the number to within the range allowed
; by the BCD format. The scaling operation should
; produce a number within one decimal order of
; magnitude of the largest decimal number
; representative within the given string width.
;
; The scaling power of ten value is in si.

```

```

;
adjust_result:
    mov  eax,esi                ; Setup for pow10
    mov  word ptr [ebx], ax    ; Set initial power
                                ; of ten
return value
    neg  eax                    ; Subtract one for each
order of                        ; magnitude
the value is scaled by
    call get_power_10          ; Scaling factor is returned
as                                ; exponent
and fraction
    fld  fraction              ; Get fraction
    fmul                                ; Combine
fractions
    mov  esi, ecx              ; Form power of ten of the
maximum
    shl  esi, 3                ; BCD value to fit in
                                ; the string
    fild power_two             ; combine powers of two
    faddpst(2),st
    fscale                      ; Form full value
                                ; exponent
was safe
    fstp st(1)                 ; remove exponent
;
; Test the adjusted value against a table
; of exact powers of ten. The combined errors
; of the magnitude estimate and power function
; can result in a value one order of magnitude
; too small or too large to fit correctly in
; the BCD field. To handle this problem, pretest
; the adjusted value, if it is too small or
; large, then adjust it by ten and adjust the
; power of ten value.
;
test_power:
; compare against exact power entry. Use the next
; entry since cx has been decremented by one
;
    fcom power_table[esi]+type power_table
    fstswax                      ; No wait is necessary
    sahf                          ; If C3 = C0 = 0 then
    jb  test_for_small ; too big

```

```

        fdiv const10                ; Else adjust value
        and dl, not EXACT          ; Remove exact flag
        inc word ptr [ebx]         ; Adjust power of ten value
        jmp short in_range         ; Convert the value to a BCD
                                     ; integer
test_for_small:
        fcom power_table[esi]; Test relative size
        fstswax                    ; no wait is necessary
        sahf                       ; If C0 = 0 then
                                     ; st (0) >=
lower_bound
        jc          in_range        ; Convert the value to a
                                     ; BCD integer
        fimulconst10               ; Adjust value into range
        dec word ptr [ebx]         ; Adjust power of ten value
in_range:
        frndint                    ; Form integer value
;
; Assert: 0 <= TOS <= 999,999,999,999,999,999
; The TOS number will be exactly representable
; in 18 digit BCD format.
;
convert_integer:
        fbstpbcd_value             ; Store as BCD format number
;
; While the store BCD runs, setup registers
; for the conversion to ASCII.
;
        mov esi, BCD_SIZE-2       ; Initial BCD index value
        mov cx, 0F04h              ; Set shift count and mask
        mov ebx, 1                 ; Set initial size of ASCII
; Field for sign
        mov edi, string_ptr; Get address of start of
                                     ; ASCII string
        mov ax, ds                 ; Copy ds to es
        mov es, ax
        cld                        ; Set autoincrement mode
        mov al, '+'                ; Clear sign field
        test dl, MINUS             ; Look for negative value
        jz          positive_result

        mov al, '-'
positive_result:
        stosb                      ; Bump string pointer
                                     ; past sign
        and dl, not MINUS         ; Turn off sign bit

```

```

        fwait                                ; Wait for fbstp to finish
;
;Register usage:
; ah:      BCD byte value in use
; al:      ASCII character value
; dx:      Return value
; ch:      BCD mask = 0Fh
; cl:      BCD shift count = 4
; ebx:     ASCII string field width
; esi:     BCD field index
; edi:     ASCII string field pointer
; ds,es:   ASCII string segment base
;
;Remove leading zeroes from the number.
;
skip_leading_zeroes:
    mov     ah, bcd_byte[esi]    ; Get BCD byte
    mov     al, ah                ; Copy value
    shr     al, cl                ; Get high order digit
    and     al, 0Fh              ; Set zero flag
    jnz     enter_odd            ; Exit loop if leading
                                   ; non zero found

    mov     al, ah                ; Get BCD byte again
    and     al, 0fh              ; Get low order digit
    jnz     enter_even          ; Exit loop if non zero
                                   ; digit found

    dec     esi                    ; Decrement BCD index
    jns     skip_leading_zeroes
;
; The significand was all zeroes.
;
    mov     al, '0'                ; Set initial zero
    stosb
    inc     ebx                    ; Bump string length
    jmp     short exit_with_value
;
; Now expand the BCD string into digit
; per byte values 0-9.
;
digit_loop:
    mov     ah, bcd_byte[esi]    ; Get BCD byte
    mov     al, ah
    shr     al, cl                ; Get high order digit

enter_odd:

```

```

        add  al, '0'                ; Convert to ASCII
        stosb                       ; Put digit into ASCII
                                   ; string area
        mov  al,ah                   ; Get low order digit
        and  al,0Fh
        inc  ebx                     ; Bump field size counter
enter_even:
        add  al, '0'                ; Convert to ASCII
        stosb                       ; Put digit into ASCII
area
        inc  ebx                     ; Bump field size counter
        dec  esi                     ; Go to next BCD byte
        jns  digit_loop
;
; Conversion complete. set the string
; size and remainder.
;
exit_with_value:
        mov  edi,size_ptr
        mov  word ptr [edi],bx
        mov  eax,edx                 ; set return value
        jmp  exit_proc

floating_to_ascii  endp
                    code ends
                    end

+ 1 $title(calculate the value of 10**eax)
; This subroutine will calculate the
; value of 10**eax. For values of
; 0 <= eax <19, the result will exact.
; All registers are transparent
; and results are returned on the TOS
; as two numbers, exponent in st(1) and
; fraction is st(0). The exponent value
; can be larger than the largest
; exponent of an extended real format
; number. Three stack entries are used.
;

        name      get_power 10
        public    get_power_10, power_table

stack stackseg 8

code  segment public er
;

```

```

; Use exact values from 1.0 to 1e18.
;
;           even                ; optimize 16 bit access
power_table dq 1.0,1e,1e2,1e3
             dq 1e4,1e5,1e6,1e7
             dq 1e8,1e9,1e10,1e11
             dq 1e12, 1e13, 1e14,1e15
             dq 1e16,1e17, 1e18

get_power_10 proc

    cmp     eax,18                ; Test for 0 <=
ax < 19
    ja     out_of_range

    fld     power_table[eax*8]    ; Get exact value
    fxtract                ; Separate
power                                ; and
                                ;
fraction
    ret                        ; OK to
leave fxtract running
;
; Calculate the value using the
; exponentiate instruction. The following
; relations are used:
; 10**x= 2**(log2(10)*x)
; 2**(I+F) = 2**I * 2**F
; if st(1) - I and st(0) = 2**F then
; fscale produces 2**(I+F)
;
out_of-range:
    fld12t                ; TOS =
LOG2(10)
    enter4,0

; Save power of 10 value, P
    mov     [edx-4], eax

; TOS,X= LOG2(10)*P = LOG2(10**P)
    fimul dword ptr[edx-4]
    fld1                ; Set TOS =
1.0
    fchs
    fld     st(1)        ; Copy power
value

```



```

; in
base two
    frndint
inf < I <= x
; TOS = I: -

I is an integer
; where

Rounding mode does
; not

matter
    fxch st(2)
st(1) = 1.0
; TOS = x,
; st(2)

= I
    fsub st,st(2)
; TOS,F = x - I:
; -1.0

< TOS <= 1.0

; Restore original rounding control
    pop  eax
    fx2m1
; TOS =
2**(F) - 1.0
    leave
; Restore

stack
    fsubr
; Form
2**(F)
    ret
; OK to
leave fsubr running

get_power_10    endp

code            ends
                end

```

```

+1 $Title(Determine TOS register contents)
;
; This subroutine will return a value
; from 0-15 in eax corresponding
; to the contents of FPU TOS. All
; registers are transparent and no
; errors are possible. The return
; value corresponds to c3,c2,c1,c0
; of FXAM instruction.
;
    name      tos_status
    public   tos_status

```

```

stackstackseg 6

code segment public er

tos_statusproc

    fxam                                ; Get status of TOS register
    fstswax                             ; Get current status
    mov  al,ah                          ; Put bits 10-8 into bits 2-0
    and  eax,4007h                      ; Mask out bits c3,c2,c1,c0
    shr  ah, 3                          ; Put bits c3 into bit 11
    or   al, ah                          ; Put c3 into bit 3
    mov  ah, 0                          ; Clear return value
    ret

tos_statusendp

code      ends
          end

```

### 8.3.1. Function Partitioning

Three separate modules implement the conversion. Most of the work of the conversion is done in the module `FLOATING__TO_ASCII`. The other modules are provided separately, because they have a more general use. One of them, `GET_POWER_10`, is also used by the ASCII to floating-point conversion routine. The other small module, `TOS_STATUS`, identifies what, if anything, is in the top of the numeric register stack.

### 8.3.2. Exception Considerations

Care is taken inside the function to avoid generating exceptions. Any possible numeric value is accepted. The only possible exception is insufficient space on the numeric register stack.

The value passed in the numeric stack is checked for existence, type (NaN or infinity), and status (denormal, zero, sign). The string size is tested for a minimum and maximum value. If the top of the register stack is empty, or the string size is too small, the function returns with an error code.

Overflow and underflow is avoided inside the function for very large or very small numbers.

### 8.3.3. Special Instructions

The functions demonstrate the operation of several numeric instructions, different data types, and precision control. Shown are instructions for automatic conversion to BCD, calculating



the value of 10 raised to an integer value, establishing and maintaining concurrency, data synchronization, and use of directed rounding on the FPU.

Without the extended precision data type and built-in exponential function, the double precision accuracy of this function could not be attained with the size and speed of the shown example.

The function relies on the numeric BCD data type for conversion from binary floating-point to decimal. It is not difficult to unpack the BCD digits into separate ASCII decimal digits. The major work involves scaling the floating-point value to the comparatively limited range of BCD values. To print a 9-digit result requires accurately scaling the given value to an integer between  $10^8$  and  $10^9$ . For example, the number +0.123456789 requires a scaling factor of  $10^9$  to produce the value +123456789.0, which can be stored in 9 BCD digits. The scale factor must be an exact power of 10 to avoid changing any of the printed digit values.

These routines should exactly convert all values exactly representable in decimal in the field size given. Integer values that fit in the given string size are not be scaled, but directly stored into the BCD form. Noninteger values exactly representable in decimal within the string size limits are also exactly converted. For example, 0.125 is exactly representable in binary or decimal. To convert this floating-point value to decimal, the scaling factor is 1000, resulting in 125. When scaling a value, the function must keep track of where the decimal point lies in the final decimal value.

### 8.3.4. Description of Operation

Converting a floating-point number to decimal ASCII takes three major steps: identifying the magnitude of the number, scaling it for the BCD data type, and converting the BCD data type to a decimal ASCII string.

Identifying the magnitude of the result requires finding the value  $X$  such that the number is represented by  $I \times 10^X$ , where  $1.0 \leq I < 10.0$ . Scaling the number requires multiplying it by a scaling factor  $10^S$ , so that the result is an integer requiring no more decimal digits than provided for in the ASCII string.

Once scaled, the numeric rounding modes and BCD conversion put the number in a form easy to convert to decimal ASCII by host software.

Implementing each of these three steps requires attention to detail. To begin with, not all floating-point values have a numeric meaning. Values such as infinity, indefinite, or NaN may be encountered by the conversion routine. The conversion routine should recognize these values and identify them uniquely.

Special cases of numeric values also exist. Denormals have numeric values, but should be recognized because they indicate that precision was lost during some earlier calculations.

Once it has been determined that the number has a numeric value, and it is normalized (setting appropriate denormal flags, if necessary, to indicate this to the calling program), the value must be scaled to the BCD range.

### 8.3.5. Scaling the Value

To scale the number, its magnitude must be determined. It is sufficient to calculate the magnitude to an accuracy of 1 unit, or within a factor of 10 of the required value. After scaling the number, a check is made to see if the result falls in the range expected. If not, the result can be adjusted one decimal order of magnitude up or down. The adjustment test after the scaling is necessary due to inevitable inaccuracies in the scaling value.

Because the magnitude estimate for the scale factor need only be close, a fast technique is used. The magnitude is estimated by multiplying the power of 2, the unbiased floating-point exponent, associated with the number by  $\log_{10}2$ . Rounding the result to an integer produces an estimate of sufficient accuracy. Ignoring the fraction value can introduce a maximum error of 0.32 in the result.

Using the magnitude of the value and size of the number string, the scaling factor can be calculated. Calculating the scaling factor is the most inaccurate operation of the conversion process. The relation  $10^X = 2^{(X \cdot \log_2 10)}$  is used for this function. The exponentiate instruction F2XM1 is used.

Due to restrictions on the range of values allowed by the F2XM1 instruction, the power of 2 value is split into integer and fraction components. The relation  $2^{(I+F)} = 2^I \times 2^F$  allows using the FSCALE instruction to recombine the  $2^F$  value, calculated through F2XM1, and the  $2^I$  part.

#### 8.3.5.1. INACCURACY IN SCALING

The inaccuracy in calculating the scale factor arises because of the trailing zeros placed into the fraction value of the power of two when stripping off the integer valued bits. For each integer valued bit in the power of 2 value separated from the fraction bits, one bit of precision is lost in the fraction field due to the zero fill occurring in the least significant bits.

Up to 14 bits may be lost in the fraction because the largest allowed floating-point exponent value is  $2^{14}-1$ . These bits directly reduce the accuracy of the calculated scale factor, thereby reducing the accuracy of the scaled value. For numbers in the range of  $10^{\pm 30}$ , a maximum of 8 bits of precision are lost in the scaling process.

#### 8.3.5.2. AVOIDING UNDERFLOW AND OVERFLOW

The fraction and exponent fields of the number are separated to avoid underflow and overflow in calculating the scaling values. For example, to scale  $10^{-4932}$  to  $10^8$  requires a scaling factor of  $10^{4950}$ , which cannot be represented by the the Intel FPU's.

By separating the exponent and fraction, the scaling operation involves adding the exponents separate from multiplying the fractions. The exponent arithmetic involves small integers, all easily represented by the Intel FPU's.

### 8.3.5.3. FINAL ADJUSTMENTS

It is possible that the power function (Get\_Power\_10) could produce a scaling value such that it forms a scaled result larger than the ASCII field could allow. For example, scaling  $9.9999999999999999 \times 10^{4900}$  by  $1.00000000000000010 \times 10^{-4883}$  produces  $1.00000000000000009 \times 10^{18}$ . The scale factor is within the accuracy of the FPU and the result is within the conversion accuracy, but it cannot be represented in BCD format. This is why there is a post-scaling test on the magnitude of the result. The result can be multiplied or divided by 10, depending on whether the result was too small or too large, respectively.

### 8.3.6. Output Format

For maximum flexibility in output formats, the position of the decimal point is indicated by a binary integer called the power value. If the power value is zero, then the decimal point is assumed to be at the right of the rightmost digit. Power values greater than zero indicate how many trailing zeros are not shown. For each unit below zero, move the decimal point to the left in the string.

The last step of the conversion is storing the result in BCD and indicating where the decimal point lies. The BCD string is then unpacked into ASCII decimal characters. The ASCII sign is set corresponding to the sign of the original value.

## 8.4. TRIGONOMETRIC CALCULATION EXAMPLES

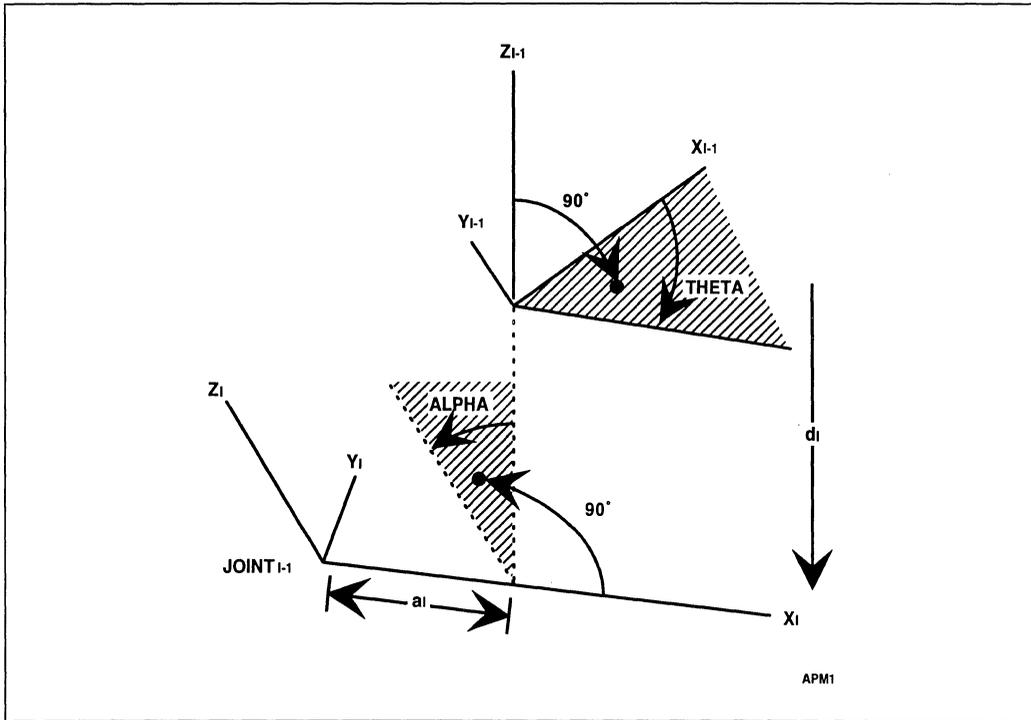
In this example, the kinematics of a robot arm is modeled with the  $4 \times 4$  homogeneous transformation matrices proposed by Denavit and Hartenberg<sup>1,2</sup>. The translational and rotational relationships between adjacent links are described with these matrices using the D-H matrix method. For each link, there is a  $4 \times 4$  homogeneous transformation matrix that represents the link's coordinate system ( $\mathbf{L}_i$ ) at the joint ( $\mathbf{J}_i$ ) with respect to the previous link's coordinate system ( $\mathbf{J}_{i-1}$ ,  $\mathbf{L}_{i-1}$ ). The following four geometric quantities completely describe the motion of any rigid joint/link pair ( $\mathbf{J}_i$ ,  $\mathbf{L}_i$ ), as Figure 8-1 illustrates.

- $\theta_i$  = The angular displacement of the  $\mathbf{x}_i$  axis from the  $\mathbf{x}_{i-1}$  axis by rotating around the  $\mathbf{z}_{i-1}$  axis (anticlockwise).
- $d_i$  = The distance from the origin of the  $(i-1)^{\text{th}}$  coordinate system along the  $\mathbf{z}_{i-1}$  axis to the  $\mathbf{x}_i$  axis.
- $a_i$  = The distance of the origin of the  $i^{\text{th}}$  coordinate system from the  $\mathbf{z}_{i-1}$  axis along the  $-\mathbf{x}_i$  axis.
- $\alpha_i$  = The angular displacement of the  $\mathbf{z}_i$  axis from the  $\mathbf{z}_{i-1}$  about the  $\mathbf{x}_i$  axis (anticlockwise).

---

<sup>1</sup> J. Denavit and R.S. Hartenberg, "A Kinematic Notation for Lower-Pair Mechanisms Based on Matrices", *J. Applied Mechanics*, June 1955, pp. 215-221.

<sup>2</sup> C.S. George Lee, "Robot Arm Kinematics, Dynamics, and Control," *IEEE Computer*, Dec. 1982.



**Figure 8-1. Relationships Between Adjacent Joints**

The D-H transformation matrix  $A_{i-1}^i$  for adjacent coordinate frames (from joint<sub>*i-1*</sub> to joint<sub>*i*</sub>) is calculated as follows:

$$A_{i-1}^i = T_{z,d} \times T_{z,\theta} \times T_{x,a} \times T_{x,\alpha}$$

where:

- $T_{z,d}$  represents a translation along the  $z_{i-1}$  axis
- $T_{z,\theta}$  represents a rotation of angle  $\theta$  about the  $z_{i-1}$  axis
- $T_{x,a}$  represents a translation along the  $x_i$  axis
- $T_{x,\alpha}$  represents a rotation of angle  $\alpha$  about the  $x_i$  axis



$$A_{i-1}^i = \begin{bmatrix} \cos \theta_i & -\cos \alpha_i \sin \theta_i & \sin \alpha_i \sin \theta_i & \cos \theta_i \\ \sin \theta_i & \cos \alpha_i \cos \theta_i & -\sin \alpha_i \cos \theta_i & \sin \theta_i \\ 0 & \sin \alpha_i & \cos \alpha_i & d_i \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

The composite homogeneous matrix  $\mathbf{T}$  which represents the position and orientation of the joint/link pair with respect to the base system is obtained by successively multiplying the D-H transformation matrices for adjacent coordinate frames.

Example 8-7 illustrates how the transformation process can be accomplished using the floating-point capabilities of the Intel architectures. The program consists of two major procedures. The first procedure TRANS\_PROC is used to calculate the elements in each D-H matrix,  $A_{i-1}^i$ . The second procedure MATRIXMUL\_PROC finds the product of two successive D-H matrices.

$$\mathbf{T}_0^i = \mathbf{A}_0^1 \times \mathbf{A}_1^2 \times \dots \times \mathbf{A}_{i-1}^i$$

### Example 8-7. Robot Arm Kinematics Example

```

NAME ROT_MATRIX_CAL
; This example illustrates the use
; of the Intel486™ floating point
; instructions, in particular, the
; FSINCOS function which gives both
; the SIN and COS values.
; The program calculates the
; composite matrix for base to end-
; effector transformation.
;
; Only the kinematics is considered in
; this example.
;
; If the composite matrix mentioned above
; is given by:
; t1n = A1 x A2 ... x An
; T1n is found by successively calling
; trans_proc and matrixmul_proc until
; all matrices have been exhausted.
;
; trans_proc calculates entries in each
; A(A1,...,An) while matrixmul_proc
; performs the matrix multiplication for

```

```
; Ai and Ai+1. matrixmul_proc in turn
; calls matrix_row and matrix_elem to
; do the multiplication.
```

```
; Define stack space
```

```
trans_stack stackseg 400
```

```
; Define the matrix structure for
; 4x4 transformational matrices
```

```
a_matrix struc
    a11 dq ?
    a12 dq ?
    a13 dq ?
    a14 dq ?
    a21 dq ?
    a22 dq ?
    a23 dq ?
    a24 dq ?
    a31 dq 0h
    a32 dq ?
    a33 dq ?
    a34 dq ?
    a41 dq 0h
    a42 dq 0h
    a43 dq 0h
    a44 dq 1h
```

```
a_matrix ends
```

```
; Assume One joint in the storage
; allocation and hence for
; two seats of parameters; however,
; more joints are possible
```

```
;
alp_deg struc
    alpha_deg1 dd ?
    alpha_deg2 dd ?
alp_deg ends
```

```
tht_deg struc
    theta_deg dd ?
tht_deg ends
```



```

a_array struc
    A1    dd    ?
    A2    dd    ?
A_array ends

D_array struc
    D1    dq    ?
    D2    dq    ?
D_array ends

; trans-data is the data segment
;

trans_data segment rw public

    Amx                a_matrix<>
    Bmx                a_matrix<>
    Tmx                a_marix<>
    ALPHA_DEG         alp_deg<>
    THETA_DEG         tht_deg<>
    A_VECTOR          A_array<>
    D_VECTOR          D_array<>
    ZERO              dd    0
    d180              dd    180
    NUM_JOINT         equ    1
    NUM_ROW           equ    4
    NUM_COL           equ    4
    REVERSE           db    1h
trans_data ends

assume ds:trans_data, es:trans_data

; Trans code contains the procedures
; for calculating matrix elements and
; matrix multiplications

trans_code segment er public
trans_proc proc far

; Calculate alpha and theta in radians
; from their values in degrees

    fldpi
    fdiv d180

```

```

; Duplicate pi/180
    fld  st(0)

    fmul qword ptr ALPHA_DEG[ecx*8]
    fxch st(1)
    fmul qword ptr THETA_DEG[ecx*8]

; theta(radians) in ST and
; alpha(radians) in ST(1)

; Calculate matrix elements
; a11 = cos theta
; a12 = -cos alpha * sin thet
; a13 = sin alpha * sin theta
; a14 = A *cos theta
; a21 = sin theta
; a22 = cos alpha * cos theta
; a23 = sin alpha * cos theta
; a24 = A * sin theta
; a32 = sin alpha
; a33 = cos alpha
; a34 = D
; a31 = a41 = a2 = a43 = 0.0
; a44 = 1

; ebx contains the offset for the matrix

    fsincos                                ; cos theta in ST
                                           ; sin theta inst(1)
    fld  st(0)                             ; duplicate cos theta
    fst  [ebx].a11                          ; cos theta in a11
    fmul qword ptr A_VECTOR[ecx*8]
    fstp [ebx].a14                          ; A* cos theta in a14
    fxch st(1)                             ; sin theta in ST
    fst  [ebx].a21                          ; sin theta in a21
    fld  st                                ; duplicate sin theta
    fmul qword ptr A_VECTOR[ecx*8]
    fstp [ebx].a24                          ; A * sin theta in a24
    fld  st(2)                             ; alpha in ST
    fsincos                                ; cos alpha in ST
                                           ; sin alpha in ST(1)
                                           ; sin theta in ST(2)
                                           ; cos theta in ST (3)

    fst  [ebx].a33                          ; cos alpha in a33
    fxch st(1)                             ; sin alpha in ST
    fst  [ebx].a32                          ; sin sin alpha in a32

```

```

fld  st(2)                ;sin theta in ST
                           ;sin alpha in ST (1)
fmul st,st(1)            ;sin alpha * sin theta
fstp [ebx].a13           ;stored in a13a
fmul st,st(3)            ;costheta * sin alpha
fchs                     ;cos theta * sin alpha
fstp [ebx].a23           ;stored in a23
fld  st(2)                ;cos theta in ST
                           ;cos alpha in ST(1)
                           ;sin theta in ST(2)
                           ;cos theta in ST(3)

fmul st,st(1)            ;cos theta * cos alpha
fstp [ebx].a22           ;stored in a22
fmul st,st(1)            ;cos alpha * sin theta
;
; To take advantage of parallel operations
; between the IU and FPU
  push eax                ;save eax
;
; also move D into a34 in a faster way
  mov  eax, dword ptr D_VECTOR[ecx*8]
  mov  dword ptr [ebx + 88], eax
  mov  eax, dword ptr D_VECTOR[ecx * 8 + 4]
  mov  dword ptr [ebx + 92], eax
  pop  eax                ;restore eax
  fchs                     ;cos alpha * sin theta
  fstp [ebx].a12         ;stored in a12
                           ;and all nonzero
elements                ;have been calculated

  ret

trans_proc endp

matrix_elem proc far

; This procedure calculates the dot product of the ith row
; of the first matrix and the jth column of the second
; matrix:

; TIJ where TIJ = sum of Aik x Bkj over k
;
; parameters passed from the calling routine,
; matrix_row:
; ESI = (i-1)*8
; EDI = (j-1)*8

```

```

; local register, EBP = (k-1)*8

    push ebp                ; save ebp
    push ecx                ; ecx to be used as a tmp reg
    mov  ecx, esi           ; save it for later indexing

; locating the element in the first matrix, A
    imul ecx, NUM_COL      ; ecx contains offset due
                                ; to preceding rows; the
                                ; offset is from the
beginning
                                ; of the matrix

    xor  ebp, ebp          ; clear ebp, which will be
                                ; used as a temp reg to
index(k)
                                ; across the ith row of the
first
                                ; matrix as well as down the
jth
                                ; column of the second
matrix

; clear Tij for accumulating Aik*Bkj
    mov  dword ptr [edx][edi], ebp
    mov  dword ptr [edx][edi+4], ebp

    push ecx                ; save on stack: esi * num_col =
                                ; the offset of the
beginning of
                                ; the ith row from the
                                ; beginning of the A matrix

NXT_k:
    add  ecx, ebp           ; get to the kth column entry
                                ; of the ith row of the A
matrix

; load Aik into FPU
    fld  qword ptr [eax][ecx]

```

```

; locating Bkj
    mov  ecx, ebp
    imul ecx, NUM_ROW           ; ecx contains the offset of the
                                ; beginning of
the kth row from
                                ; the beginning
of the B matrix
    add  ecx, edi               ; get to the jth column
                                ; of the kth row
of the B matrix
    fmul qword ptr [ebx][ecx] ;Aik & Bkj
    pop  ecx                   ;esi * num_col in ecx again
    push ecx                   ;also at top of program
stack
; add to the result in the output matrix, Tij
    add  ecx, edi

; accumulating the sum of Aik * Bkj
    fadd qword ptr [edx][ecx]
    fstp qword ptr [edx][ecx]

; increment k by 1, i.e., ebp by 8
    add  ebp, 8

; Has k reached the width of the matrix yet?
    cmp  ebp, NUM_COL*8
    jl   NXT_k

; Restore registers
    pop  ecx                   ;clear esi_num_col from stack
    pop  ecx                   ;restore ecx
    pop  ebp                   ;restore ebp
    ret

matrix_elem endp

matrix_row proc far
    xor  edi, edi
    ;scan across a row

NXT_COL:
    call matrix_elem
    add  edi, 8
    cmp  edi, NUM_COL*8
    jl   NXT_COL
    ret

```

matrix\_row endp

matrixmul\_proc proc far

; This procedure does the matrix multiplication by calling  
; matrix\_row to calculate entries in each row.

; ;  
; The matrix multiplication is performed in the following  
; manner,  
;  $T_{ij} = A_{ik} \times B_{kj}$

; where i and j denote the row and column  
; respectively and k is the index for scanning  
; across the ith row of the first matrix and  
; the jth column of the second matrix.

mov ebp, esp ; use base pointer for  
indexing

mov edx, dword ptr [ebp+4] ; offset Tmx in edx  
mov ebx, dword ptr [ebp+8] ; offset Bmx in ebx  
mov eax, dword ptr [ebp+12] ; offset Amx in eax

; setup esi and edi  
; edi points to the column  
; esi points to the row

xor esi, esi ; clear esi

NXT\_ROW:

call matrix\_row  
add esi, 8  
cmp esi, NUM\_ROW\*8  
jl NXT\_ROW  
ret 12 ;pop off matrix

pointers

matrixmul\_proc endp

trans\_code ends

```
;*****
;
;           ;
;           Main Program
;
;
;           ;
;*****
```

```
main_code segment er
```

```
START:
```

```
    mov     esp, stackstart trans_stack
```

```
        pushad                                ;save all registers
```

```
; ECX denotes the number of joints where
; number of matrices = NUM_JOINT + 1
; Find the first matrix (from the base of the
; system to the first joint) and call it Bmx
    xor     ecx, ecx                            ;1st matrix
    mov     ebx, offset Bmx
    call   trans_proc                          ; is Bmx
    inc     ecx
```

```
NXT_MATRIX:
```

```
; From the 2nd matrix and on, it will be stored in Amx.
; The result from the first matrix mult. is stored in
; Tmx but will be accessed as Bmx in the next multiplication.
; As a matter of fact, the roles of Bmx and Tmx alternate in
; successive multiplications. This is achieved by reversing
; the order of the Bmx and Tmx pointers being passed onto the
; program stack. Thus, this is invislbe to the matrix
; mutliplication procedure.
; REVERSE serves as the indicator
; REVERSE = 0 means that the result is to be placed in Tmx
```

```
    mov     ebx, offset Amx                    ;find Amx
    call   trans_proc
    inc     ecx
    xor     REVERSE, 1h
    jnz    Bmx_as_Tmx
```

```
; No reversing. Bms as the second input
; matrix while Tmx as the output matrix.
    push offset Amx
    push offset Bmx
    push offset Tmx
    jmp    CONTINUE
```

```
; Reversing. Tmx as the second input
; matrix while Bms as the output matrix.
```

```

Bmx_as_Tmx:
    push offset Amx
    push offset Tmx                ;reversing the
    push offset Bmx                ;pointers passed

CONTINUE:
    call matrixmul_proc
    cmp  ecx, NUM_JOINT
    jle  NXT_MATRIX

; if REVERSE = 1 then the final answer
; will be in Bmx, otherwise in Tmx.

    popad

main_code ends

end START, ds:trans_data, ss:trans_stack

```



# **Part II**

## **System Programming**





# 9

## **Real-Address Mode System Architecture**





# CHAPTER 9

## REAL-ADDRESS MODE SYSTEM ARCHITECTURE

The real-address mode of the Pentium processor runs programs written for the 8086, 8088, 80186, or 80188 processors, or for the real-address mode of Intel 286, Intel386, or Intel486 processors.

The architecture of the processor in this mode is almost identical to that of the 8086, 8088, 80186, and 80188 processors. To a programmer, a 32-bit processor in real-address mode appears as a high-speed 8086 processor or real-mode Intel 286 processor with extensions to the instruction set and registers. The principal features of this architecture are defined in Chapter 3 and Chapter 4.

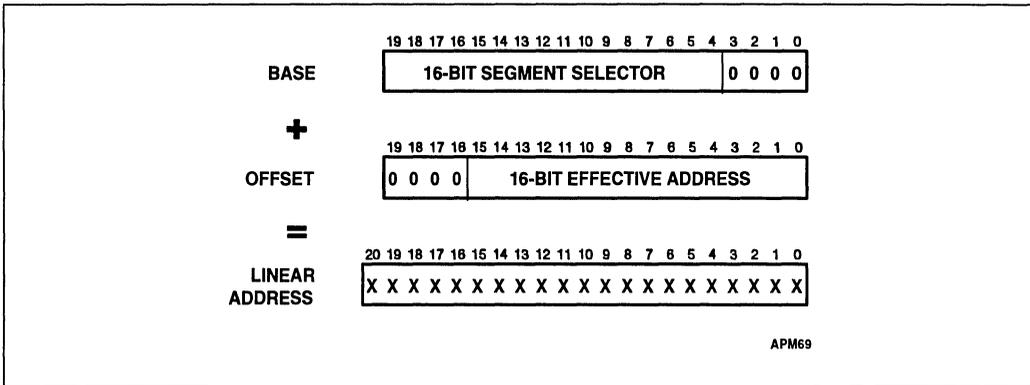
This chapter discusses certain additional topics which complete the system programmer's view of real-address mode:

- Address formation.
- Interrupt and exception handling.
- Real-address mode exceptions.

For information on input and output both in real-address mode and protected mode, refer to Chapter 15.

### 9.1. ADDRESS TRANSLATION

In real-address mode, the processor does not interpret selectors by referring to descriptors; instead, it forms linear addresses as an 8086 processor would. It shifts the selector left by four bits to form a 20-bit base address. The effective address is extended with four clear bits in the upper bit positions and added to the base address to create a linear address, as shown in Figure 9-1.



**Figure 9-1. 8086 Address Translation**

Because of the possibility of a carry, the resulting linear address may have as many as 21 significant bits. An 8086 program may generate linear addresses anywhere in the range 0 to 10\_FFEFH (1 megabyte plus approximately 64K bytes) of the linear address space. (Note, however, that on the Intel486 and Pentium processors, the A20M# signal can be used in real-address mode to mask address signal A20, thereby mimicking the 20-bit wrap-around behavior of the 8086 processor.) Because paging is not available in real-address mode, the linear address is used as the physical address.

Unlike the 8086 and Intel 286 processors, but like the Intel386 and Intel486 processors, the Pentium processor can generate 32-bit effective addresses using an address override prefix; however in real-address mode, the value of a 32-bit address may not exceed 65,535 without causing an exception. For full compatibility with Intel 286 real-address mode, pseudo-protection faults (interrupt 12 or 13 with no error code) occur if an effective address is generated outside the range 0 through 65,535.

## 9.2. REGISTERS AND INSTRUCTIONS

The register set available in real-address mode includes all the registers defined for the 8086 processor plus the new registers introduced with the Intel386 processor and Intel387 coprocessor: FS, GS, debug registers, control registers, test registers, and floating-point unit registers. New instructions which explicitly operate on the segment registers FS and GS are available, and the new segment-override prefixes can be used to cause instructions to use the FS and GS registers for address calculations.

The instruction codes which generate invalid-opcode exceptions include instructions from protected mode which move or test protected-mode segment selectors and segment descriptors, i.e., the VERR, VERW, LAR, LSL, LTR, STR, LLDT, and SLDT instructions. Programs executing in real-address mode are able to take advantage of the new application-oriented instructions added to the architecture with the introduction of the 80186, 80188, Intel 286, Intel386, Intel486, and Pentium processors.

Unlike the 8086 and Intel 286 processors, but like the Intel386 and Intel486 processors, the Pentium processor offers an operand-size override prefix which enables access to 32-bit operands. This prefix should not be used, however, if compatibility with the 8086 or Intel 286 processors is desired.

### 9.3. INTERRUPT AND EXCEPTION HANDLING

Interrupts and exceptions in real-address mode work much as they do on an 8086 processor. Interrupts and exceptions call interrupt procedures through an interrupt table. The processor scales the interrupt or exception identifier by four to obtain an index into the interrupt table. The entries of the interrupt table are far pointers to the entry points of interrupt or exception handler procedures. When an interrupt occurs, the processor pushes the current values of the CS and IP registers onto the stack, disables interrupts, clears the TF flag, and transfers control to the location specified in the interrupt table. An IRET instruction at the end of the handler procedure reverses these steps before returning control to the interrupted procedure. Exceptions do not return error codes in real-address mode.

The primary difference in the interrupt handling of the 32-bit processors in real-address mode compared to the 8086 processor is that the location and size of the interrupt table depend on the contents of the IDTR register. Ordinarily, this fact is not apparent to programmers, because, after reset initialization, the IDTR register contains a base address of 0 and a limit of 3FFH, which is compatible with the 8086 processor. However, the LIDT instruction can be used in real-address mode to change the base and limit values in the IDTR register. See Chapter 9 for details on the IDTR register, and the LIDT and SIDT instructions. If an interrupt occurs and its entry in the interrupt table is beyond the limit stored in the IDTR register, a double-fault exception is generated.

### 9.4. REAL-ADDRESS MODE EXCEPTIONS

The processor reports some exceptions differently when executing in real-address mode than when executing in protected mode. Table 9-1 details the real-address-mode exceptions.

**Table 9-1. Exceptions and Interrupts**

Description	Vector	Source of the Exception	Does the Return Address Point to the Instruction Which Caused the Exception?
Divide Error	0	DIV and IDIV instructions	yes
Debug	1	Any	1
NMI	2	Nonmaskable Interrupt	yes
Breakpoint	3	INT instruction	no
Overflow	4	INTO instruction	no
Bounds Check	5	BOUND instruction	yes
Invalid Opcode	6	Reserved opcodes and improper use of LOCK prefix	yes
Device not available	7	ESC or WAIT instructions	yes
Double Fault	8	Interrupt table limit too small, fault occurring while handling another fault	yes
Reserved	9		
Invalid Task State Segment <sup>3</sup>	10	JMP, CALL, IRET instructions, interrupts and exceptions	yes
Segment not present <sup>3</sup>	11	Any instruction which changes segments	yes
Stack Exception	12	Stack operation crosses address limit (beyond offset FFFFH)	yes
CS, DS, ES, FS, GS Segment Overrun	13	Word memory reference beyond offset FFFFH. An attempt to execute past the end of CS segment.	yes
Page Fault <sup>3</sup>	14	Any instruction that references memory	yes
Reserved	15		
Floating-Point Error	16	ESC or WAIT instructions	yes <sup>2</sup>
Alignment Check <sup>3</sup>	17	Any data reference	no
Intel Reserved	18–31		
Software Interrupt	0–255	INT <i>n</i> instructions	no
Maskable Interrupt	32–255		yes

**NOTES:**

1. Some debug exceptions point to the faulting instruction, others point to the following instruction. The exception handler can test the DR6 register to determine which has occurred.
2. Floating-point errors are reported on the first ESC or WAIT instruction after the ESC instruction which generated the error.
3. Exceptions 10, 11, 14 and 17 do not occur in Real Mode, but are possible in virtual 8086 mode.



# 10

## **Protected-Mode System Architecture Overview**





# CHAPTER 10

## PROTECTED-MODE SYSTEM ARCHITECTURE OVERVIEW

Many of the architectural features of the processor are used only by system programmers. This chapter presents an overview of these features. Application programmers may need to read this chapter, and the following chapters which describe the use of these features, in order to understand the hardware facilities used by system programmers to create a reliable and secure environment for application programs. The system-level architecture also supports powerful debugging features which application programmers may wish to use during program development.

The system-level features of the architecture include:

- Memory Management
- Protection
- Multitasking
- Exceptions and Interrupts
- Input/Output
- Initialization and Mode Switching
- FPU Management
- Debugging
- Cache Management
- Multiprocessing

These features are supported by registers and instructions, all of which are introduced in the following sections. The purpose of this chapter is not to explain each feature in detail, but rather to place the remaining chapters about protected mode and systems programming in perspective. When a register or instruction is mentioned, it is accompanied by an explanation or a reference to a following chapter.

### 10.1. SYSTEM REGISTERS

The registers intended for use by system programmers fall into these categories:

- EFLAGS Register
- Memory-Management Registers
- Control Registers
- Debug Registers

The system registers control the execution environment of application programs. Most systems restrict access to these facilities by application programs (although systems can be built where all programs run at the most privileged level, in which case application programs are allowed to modify these facilities).

### 10.1.1. System Flags

The system flags of the EFLAGS register control I/O, maskable interrupts, debugging, task switching, and the virtual-8086 mode. An application program should ignore these system flags, and should not attempt to change their state. In some systems, an attempt to change the state of a system flag by an application program results in an exception. These flags are shown in Figure 10-1.

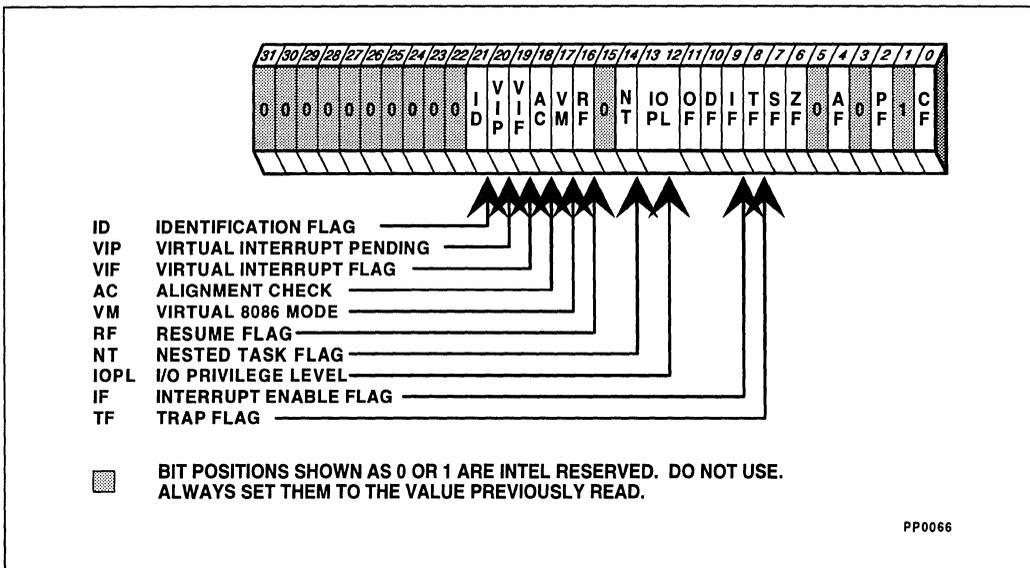


Figure 10-1. System Flags

#### ID (Identification Flag, bit 21)

The ability of a program to set and clear the ID flag indicates that the processor supports the CPUID instruction. Refer to Chapter 25 for details about CPUID.

#### VIP (Virtual Interrupt Pending Flag, bit 20)

The VIP flag together with the VIF enable each applications program in a multitasking environment to have virtualized versions of the system's IF flag. For more on the use of these flags in virtual-8086 mode and in protected mode, refer to Appendix H.

**VIF (Virtual Interrupt Flag, bit 19)**

The VIF is a virtual image of IF (the interrupt flag) used with VIP.

**AC (Alignment Check Mode, bit 18)**

Setting the AC flag and the AM bit in the CR0 register enables alignment checking on memory references. An alignment-check exception is generated when reference is made to an unaligned operand, such as a word at an odd byte address or a doubleword at an address which is not an integral multiple of four. Alignment-check exceptions are generated only in user mode (privilege level 3). Memory references which default to privilege level 0, such as segment descriptor loads, do not generate this exception even when caused by a memory reference in user-mode.

The alignment-check exception can be used to check alignment of data. This is useful when exchanging data with other processors, such as the i860™ microprocessor, which require all data to be aligned. The alignment-check exception can also be used by interpreters to flag some pointers as special by misaligning the pointer. This eliminates overhead of checking each pointer and only handles the special pointer when used.

**VM (Virtual-8086 Mode, bit 17)**

Setting the VM flag places the processor in virtual-8086 mode, which is an emulation of the programming environment of an 8086 processor. See Chapter 22 for more information.

**RF (Resume Flag, bit 16)**

The RF flag temporarily disables debug faults so that an instruction can be restarted after a debug fault without immediately causing another debug fault. The debugger sets this flag with the IRETD instruction when returning to the interrupted program. The RF flag is not affected by the POPF, POPFD or IRET instructions. See Chapter 14 and Chapter 17 for details.

**NT (Nested Task, bit 14)**

The processor sets and tests the nested task flag to control chaining of interrupted and called tasks. The NT flag affects the operation of the IRET instruction. The NT flag is affected by the POPF, POPFD, and IRET instructions. Improper changes to the state of this flag can generate unexpected exceptions in application programs. See Chapter 13 and Chapter 14 for more information on nested tasks.

**IOPL (I/O Privilege Level, bits 12 and 13)**

The I/O privilege level is used by the protection mechanism to control access to the I/O address space. The privilege level of the code segment currently executing (CPL) and the IOPL determine whether this field can be modified by the POPF, POPFD, and IRET instructions. See Chapter 15 for more information.

**IF (Interrupt-Enable Flag, bit 9)**

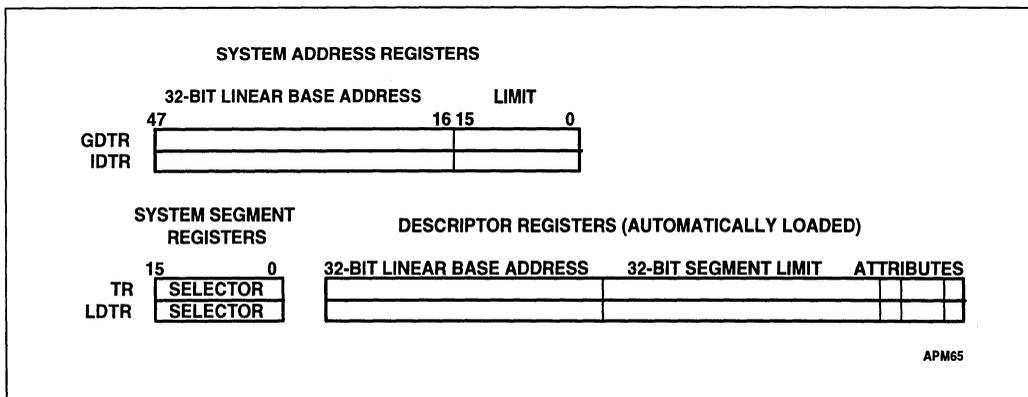
Setting the IF flag puts the processor in a mode in which it responds to maskable interrupt requests (INTR interrupts). Clearing the IF flag disables these interrupts. The IF flag has no effect on either exceptions or nonmaskable interrupts (NMI interrupts). The CPL and IOPL determine whether this field can be modified by the CLI, STI, POPF, POPFD, and IRET instructions. See Chapter 14 for more details about interrupts.

**TF (Trap Flag, bit 8)**

Setting the TF flag puts the processor into single-step mode for debugging. In this mode, the processor generates a debug exception after each instruction, which allows a program to be inspected as it executes each instruction. Single-stepping is just one of several debugging features of the processor. If an application program sets the TF flag using the POPF, POPFD, or IRET instructions, a debug exception is generated. See Chapter 14 and Chapter 17 for more information.

**10.1.2. Memory-Management Registers**

Four registers of the processor specify the locations of the data structures which control segmented memory management, as shown in Figure 10-2. Special instructions are provided for loading and storing these registers. The GDTR and IDTR registers can be loaded with instructions which get a six-byte block of data from memory. The LDTR and TR registers can be loaded with instructions which take a 16-bit segment selector as an operand. The remaining bytes of these registers are then loaded automatically by the processor from the descriptor referenced by the operand.



**Figure 10-2. Memory Management Registers**

Most systems protect the instructions which load memory-management registers from use by application programs (although a system in which no protection is used is possible).

### **GDTR Global Descriptor Table Register**

This register holds the 32-bit base address and 16-bit segment limit for the global descriptor table (GDT). When a reference is made to data in memory, a segment selector is used to find a segment descriptor in the GDT or LDT. A segment descriptor contains the base address for a segment. See Chapter 11 for an explanation of segmentation.

### **LDTR Local Descriptor Table Register**

This register holds the 32-bit base address, 32-bit segment limit, descriptor attributes, and 16-bit segment selector for the local descriptor table (LDT). The segment which contains the LDT has a segment descriptor in the GDT. There is no segment selector for the GDT. When a reference is made to data in memory, a segment selector is used to find a segment descriptor in the GDT or LDT. A segment descriptor contains the base address for a segment. See Chapter 11 for an explanation of segmentation.

### **IDTR Interrupt Descriptor Table Register**

This register holds the 32-bit base address and 16-bit segment limit for the interrupt descriptor table (IDT). When an interrupt occurs, the interrupt vector is used as an index to get a gate descriptor from this table. The gate descriptor contains a pointer used to start up the interrupt handler. See Chapter 14 for details of the interrupt mechanism.

### **TR Task Register**

This register holds the 32-bit base address, 32-bit segment limit, descriptor attributes, and 16-bit segment selector for the task currently being executed. It references a task state segment (TSS) descriptor in the global descriptor table. See Chapter 13 for a description of the multitasking features of the processor.

## **10.1.3. Control Registers**

Figure 10-3 shows the format of the control registers CR0, CR1, CR2, CR3, and CR4. Most systems prevent application programs from loading the control registers (although an unprotected system would allow this). Application programs can read these registers; for example, reading CR0 to determine if a numerics coprocessor is present. Forms of the MOV instruction allow these registers to be loaded from or stored in general registers. For example:

```
MOV    EAX,  CR0
MOV    CR3,  EBX
```

Refer to Chapter 16 for a list of the initial values of all these registers.

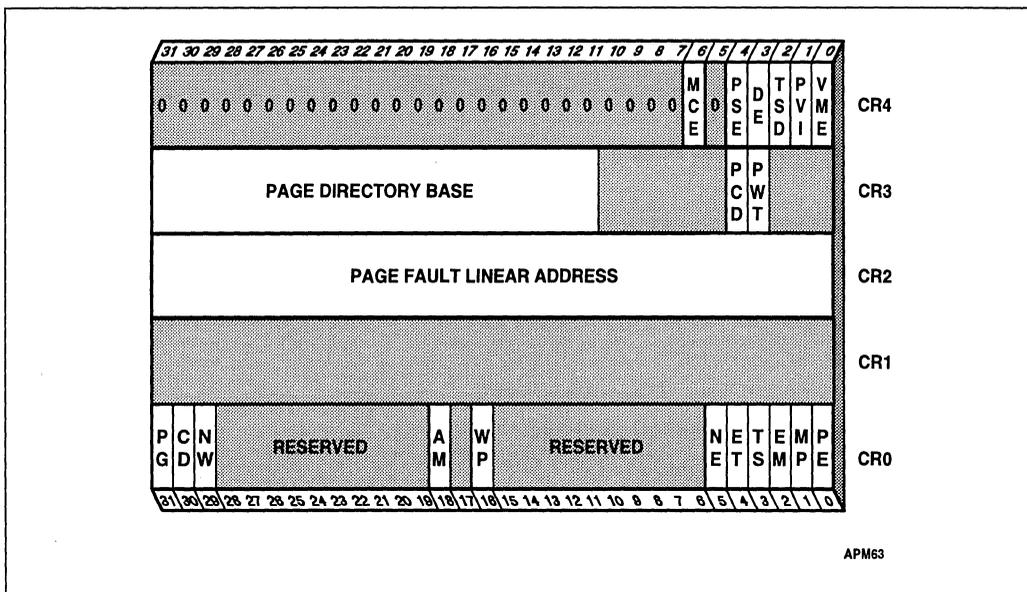


Figure 10-3. Control Registers

The CR0 register contains system control flags, which control modes or indicate states which apply generally to the processor, rather than to the execution of an individual task. A program should not attempt to change any of the reserved bit positions. Reserved bits should always be set to the value previously read.

**PG (Paging, bit 31 of CR0)**

This bit enables paging when set and disables paging when clear. See Chapter 11 for more information about paging. See Chapter 16 for information on how to enable paging.

When an exception is generated during paging, the CR2 register has the 32-bit linear address which caused the exception. See Chapter 14 for more information about handling exceptions generated during paging (page faults).

When paging is used, the CR3 register has the 20 most-significant bits of the address of the page directory (the first-level page table). The CR3 register is also known as the page-directory base register (PDBR). Note that the page directory must be aligned to a page boundary, so the low 12 bits of the register are not used as address bits. Unlike the Intel386 DX processor, the Intel486 and Pentium processors assign functions to two of these bits. These are:

- PCD (Page-Level Cache Disable, bit 4 of CR3)  
The state of this bit is driven on the PCD pin during bus cycles which are not paged, such as interrupt acknowledge cycles, when paging is enabled. It is driven during all bus cycles when paging is not enabled. The PCD pin is used to control caching in an external cache on a cycle-by-cycle basis.

- **PWT (Page-Level Writes Transparent, bit 3 of CR3)**

The state of this bit is driven on the PWT pin during bus cycles which are not paged, such as interrupt acknowledge cycles, when paging is enabled. It is driven low during all bus cycles when paging is not enabled. The PWT pin is used to control write through in an external cache on a cycle-by-cycle basis.

**CD (Cache Disable, bit 30 of CR0)**

This bit enables the internal cache fill mechanism when clear and disables it when set. Cache misses do not cause cache line fills when the bit is set. Note that cache hits are not disabled; to completely disable the cache, the cache must be invalidated. See Chapter 18 for information on caching.

**NW (Not Writethrough, bit 29 of CR0)**

This bit enables writethroughs and cache invalidation cycles when clear and disables invalidation cycles and writethroughs which hit in the cache when set. See Chapter 18 for information on caching.

**AM (Alignment Mask, bit 18 of CR0)**

This bit allows alignment checking when set and disables alignment checking when clear. Alignment checking is performed only when the AM bit is set, the AC flag is set, and the CPL is 3 (user mode).

**WP (Write Protect, bit 16 of CR0)**

When set, this bit write-protects pages against supervisor-level writes. When this bit is clear, read-only pages can be written by a supervisor process. This feature is useful for implementing the copy-on-write method of creating a new process (forking) used by some operating systems, such as UNIX\*.

**NE (Numeric Error, bit 5 of CR0)**

This bit enables the standard mechanism for reporting floating-point numeric errors when set. When NE is clear and the IGNNE# input is active, numeric errors are ignored. When the NE bit is clear and the IGNNE# input is inactive, a numeric error causes the processor to stop and wait for an interrupt. The interrupt is generated by using the FERR# pin to drive an input to the interrupt controller (the FERR# pin emulates the ERROR# pin of the Intel287 and Intel387 DX math coprocessors). The NE bit, IGNNE# pin, and FERR# pin are used with external logic to implement PC-style error reporting.

**ET (Extension Type, bit 4 of CR0)**

This bit is one to indicate support of Intel387 DX math coprocessor instructions (on the Pentium microprocessor, this bit is reserved).

**TS (Task Switched, bit 3 of CR0)**

The processor sets the TS bit with every task switch and tests it when interpreting floating-point arithmetic instructions. This bit allows delaying save/restore of numeric context until the numeric data is actually used. The CLTS instruction clears this bit.

**EM (Emulation, bit 2 of CR0)**

When the EM bit is set, execution of a numeric instruction generates the device-not-available exception. The EM bit must be set when the processor does not have a floating-point unit.

**MP (Monitor coProcessor, bit 1 of CR0)**

On the Intel 286 and Intel386 DX processors, the MP bit controls the function of the WAIT instruction, which is used to synchronize with a coprocessor. When running Intel 286 and Intel386 DX CPU programs on processors with the Intel486 processor and Pentium processor FPU's, this bit should be set. The MP bit should be reset in the Intel486 SX CPU.

**PE (Protection Enable, bit 0 of CR0)**

Setting the PE bit enables segment-level protection. See Chapter 12 for more information about protection. See Chapter 16 for information on how to enable paging.

The CR4 register contains bits that enable certain architectural extensions. This register is new with the Pentium microprocessor.

**VME (Virtual-8086 Mode Extensions, bit 0 of CR4)**

Setting this bit to 1 enables support for a virtual interrupt flag in virtual-8086 mode. This feature can improve the performance of virtual-8086 applications by eliminating the overhead of faulting to a virtual-8086 monitor for emulation of certain operations. Refer to Appendix H for more information on this feature.

**PVI (Protected-Mode Virtual Interrupts, bit 1 of CR4)**

Setting this bit to 1 enables support for a virtual interrupt flag in protected mode. This feature can enable some programs designed for execution at privilege level 0 to execute at privilege level 3. Refer to Appendix H for more information on this feature.

**TSD (Time Stamp Disable, bit 2 of CR4)**

Setting this bit to 1 makes RDTSC (read from time stamp counter) a privileged instruction. Refer to Chapter 25 for details on the RDTSC instruction.

**DE (Debugging Extensions, bit 3 of CR4)**

Setting this bit to 1 enables I/O breakpoints. Refer to Chapter 17 for more information on debugging.

**PSE (Page Size Extensions, bit 4 of CR4)**

Setting this bit to 1 enables four-megabyte pages. Refer to Appendix H for information about this feature.

**MCE (Machine Check Enable, bit 6 of CR4)**

Setting this bit to 1 enables the machine check exception.

**Notes**

All new features (VME, PVI, TSD, DE and PSE) in the CPUID feature flag should be qualified with the CPUID instruction and are model specific.

**10.1.4. Debug Registers**

The debug registers bring advanced debugging abilities to the processor, including data breakpoints and the ability to set instruction breakpoints without modifying code segments (useful in debugging ROM-based software). Only programs executing at the highest privilege level can access these registers. See Chapter 17 for a complete description of their formats and use. The debug registers are shown in Figure 10-4.

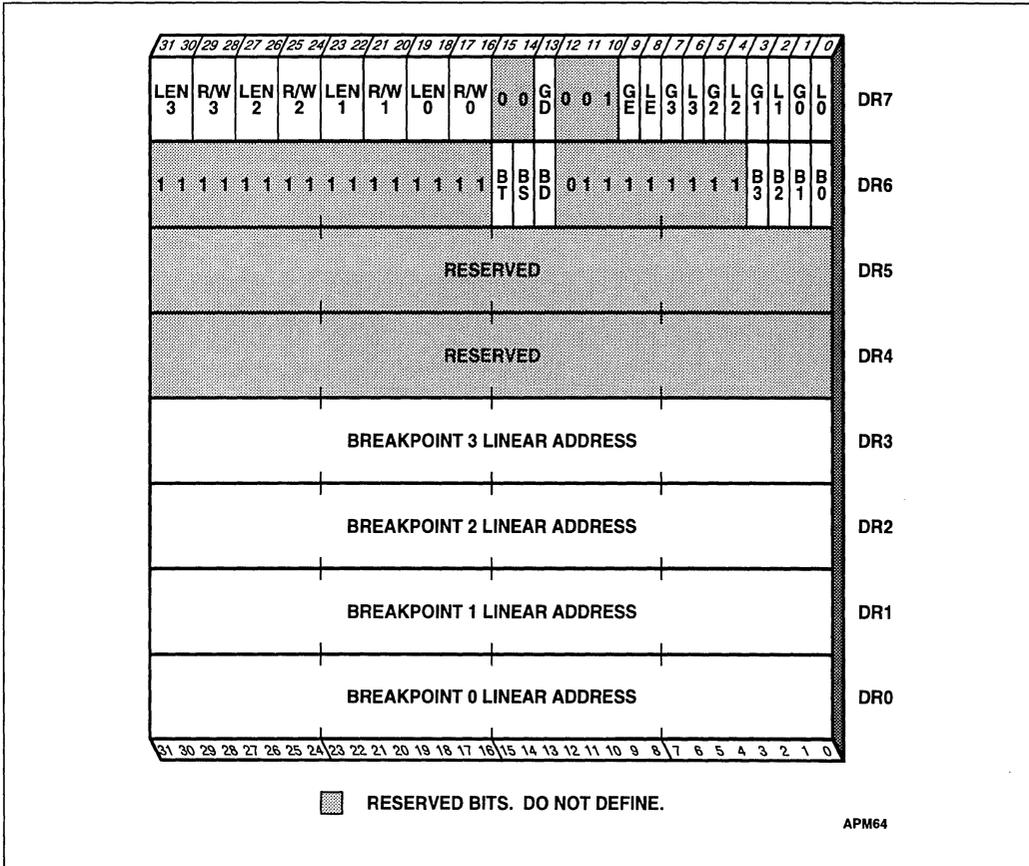


Figure 10-4. Debug Registers

## 10.2. SYSTEM INSTRUCTIONS

System instructions deal with functions such as:

1. Verification of pointer parameters (see Chapter 12):

Instruction	Description	Useful to Application?	Protected from Application?
ARPL	Adjust RPL	No	No
LAR	Load Access Rights	Yes	No
LSL	Load Segment Limit	Yes	No
VERR	Verify for Reading	Yes	No
VERW	Verify for Writing	Yes	No

2. Addressing descriptor tables (see Chapter 11):

Instruction	Description	Useful to Application?	Protected from Application?
LLDT	Load LDT Register	No	Yes
SLDT	Store LDT Register	Yes	No
LGDT	Load GDT Register	No	Yes
SGDT	Store GDT Register	No	No

3. Multitasking (see Chapter 13):

Instruction	Description	Useful to Application?	Protected from Application?
LTR	Load Task Register	No	Yes
STR	Store Task Register	Yes	No

4. Floating-point numerics (see Chapter 6):

Instruction	Description	Useful to Application?	Protected from Application?
CLTS	Clear TS bit in CR0	No	Yes
ESC	Escape Instructions	Yes	No
WAIT	Wait Until Coprocessor Not Busy	Yes	No

5. Input and output (see Chapter 15):

Instruction	Description	Useful to Application?	Protected from Application?
IN	Input	Yes	Can be
OUT	Output	Yes	Can be
INS	Input String	Yes	Can be
OUTS	Output String	Yes	Can be

6. Interrupt control (see Chapter 14):

Instruction	Description	Useful to Application?	Protected from Application?
CLI	Clear IF flag	Can be	Can be
STI	Set IF flag	Can be	Can be
LIDT	Load IDT Register	No	Yes
SIDT	Store IDT Register	No	No

7. Debugging (see Chapter 17):

Instruction	Description	Useful to Application?	Protected from Application?
MOV	Load and store debug registers	No	Yes

8. Cache Management (see Chapter 18):

Instruction	Description	Useful to Application?	Protected from Application?
INVD	Invalidate cache, no writeback	No	Yes
WBINVD	Invalidate cache, with writeback	No	Yes
INVLPG	Invalidate TLB entry	No	Yes



9. System Control:

Instruction	Description	Useful to Application?	Protected from Application?
SMSW	Store MSW	Yes	No
LMSW	Load MSW	No	Yes
MOV	Load And Store Control Register	No	Yes
HLT	Halt Processor	No	Yes
LOCK	Bus Lock	No	No
RSM	Return from system management mode	No	Yes

The SMSW and LMSW instructions are provided for compatibility with the 16-bit Intel 286 processor. Programs for 32-bit processors such as the Pentium microprocessor should not use these instructions. Instead, they should access the Control Registers using forms of the MOV instruction. The LMSW instruction does not affect the PG, CD, NW, AM, WP, NE or ET bits, and it cannot be used to clear the PE bit.

The HLT instruction stops the processor until an enabled interrupt or RESET signal is received. (Note that the NMI and SMI interrupts are always enabled.) A special bus cycle is generated by the processor to indicate halt mode has been entered. Hardware may respond to this signal in a number of ways. An indicator light on the front panel may be turned on. An NMI interrupt for recording diagnostic information may be generated. Reset initialization may be invoked. Software designers may need to be aware of the response of hardware to halt mode.

The LOCK instruction prefix is used to invoke a locked (atomic) read-modify-write operation when modifying a memory operand. The LOCK# signal is asserted and the processor does not respond to requests for bus control during a locked operation. This mechanism is used to allow reliable communications between processors in multiprocessor systems.

In addition to the chapters mentioned above, detailed information about each of these instructions can be found in the instruction reference chapter, Chapter 25.





**11**

**Protected-Mode  
Memory  
Management**





## CHAPTER 11

# PROTECTED-MODE MEMORY MANAGEMENT

Memory management is a hardware mechanism which lets operating systems create simplified environments for running programs. For example, when several programs are running at the same time, they must each be given an independent address space. If they all had to share the same address space, each would have to perform difficult and time-consuming checks to avoid interfering with the others.

Memory management consists of segmentation and paging. Segmentation is used to give each program several independent, protected address spaces. Paging is used to support an environment where large address spaces are simulated using a small amount of RAM and some disk storage. System designers can choose to use either or both of these mechanisms. When several programs are running at the same time, either mechanism can be used to protect programs against interference from other programs.

Segmentation allows memory to be completely unstructured and simple, like the memory model of an 8-bit processor, or highly structured with address translation and protection. The memory management features apply to units called segments. Each segment is an independent, protected address space. Access to segments is controlled by data which describes its size, the privilege level required to access it, the kinds of memory references which can be made to it (instruction fetch, stack push or pop, read operation, write operation, etc.), and whether it is present in memory.

Segmentation is used to control memory access, which is useful for catching bugs during program development and for increasing the reliability of the final product. It also is used to simplify the linkage of object code modules. There is no reason to write position-independent code when full use is made of the segmentation mechanism, because all memory references can be made relative to the base addresses of a module's code and data segments. Segmentation can be used to create ROM-based software modules, in which fixed addresses (fixed, in the sense that they cannot be changed) are offsets from a segment's base address. Different software systems can have the ROM modules at different physical addresses because the segmentation mechanism will direct all memory references to the right place.

In a simple memory architecture, all addresses refer to the same address space. This is the memory model used by 8-bit microprocessors, such as the 8080 processor, where the logical address is the physical address. The 32-bit processors in protected mode can be used in this way by mapping all segments into the same address space and keeping paging disabled. This might be done where an older design is being updated to 32-bit technology without also adopting the new architectural features.

An application also could make partial use of segmentation. A frequent cause of software failures is the growth of the stack into the instruction code or data of a program. Segmentation can be used to prevent this. The stack can be put in an address space separate from the address space for either code or data. Stack addresses always would refer to the memory in the stack segment, while data addresses always would refer to memory in the data

segment. The stack segment would have a maximum size enforced by hardware. Any attempt to grow the stack beyond this size would generate an exception.

A complex system of programs can make full use of segmentation. For example, a system in which programs share data in real time can have precise control of access to that data. Program bugs appear as exceptions generated when a program makes improper access. This is useful as an aid to debugging during program development, and it also can be used to trigger error-recovery procedures in systems delivered to the end user.

Segmentation hardware translates a segmented (logical) address into an address for a continuous, unsegmented address space, called a linear address. If paging is enabled, paging hardware translates a linear address into a physical address. If paging is not enabled, the linear address is used as the physical address. The physical address appears on the address bus coming out of the processor.

Paging is a mechanism used to simulate a large, unsegmented address space using a small, fragmented address space and some disk storage. Paging provides access to data structures larger than the available memory space by keeping them partly in memory and partly on disk.

Paging is applied to units of 4 kilobytes called pages. When a program attempts to access a page which is on disk, the program is interrupted in a special way. Unlike other exceptions and interrupts, an exception generated due to address translation restores the contents of the processor registers to values which allow the exception-generating instruction to be re-executed. This special treatment enables instruction restart; that is, it allows the operating system to read the page from disk, update the mapping of linear addresses to physical addresses for that page, and restart the program. This process is transparent to the program.

Paging is optional. If an operating system never enables the paging mechanism, linear addresses will be used as physical addresses. This might be done where a design using a 16-bit processor is being updated to use a 32-bit processor. An operating system written for a 16-bit processor does not use paging because the size of its address space is so small (64K bytes) that it is more efficient to swap entire segments between RAM and disk, rather than individual pages.

Paging would be enabled for operating systems, such as UNIX, which can support demand-paged virtual memory. Paging is transparent to application software, so an operating system intended to support application programs written for 16-bit processors can run those programs with paging enabled. Unlike paging, segmentation is not transparent to application programs. Programs which use segmentation must be run with the segments they were designed to use.

## 11.1. SELECTING A SEGMENTATION MODEL

A model for the segmentation of memory is chosen on the basis of reliability and performance. For example, a system which has several programs sharing data in real time would get maximum performance from a model which checks memory references in hardware. This would be a multisegment model.



At the other extreme, a system which has just one program may get higher performance from an unsegmented or "flat" model. The elimination of "far" pointers and segment-override prefixes reduces code size and increases execution speed. Context switching is faster, because the contents of the segment registers no longer have to be saved or restored.

Some of the benefits of segmentation also can be provided by paging. For example, data can be shared by mapping the same pages onto the address space of each program.

### 11.1.1. Flat Model

The simplest model is the flat model. In this model, all segments are mapped to the entire physical address space. A segment offset can refer to either code or data areas. To the greatest extent possible, this model removes the segmentation mechanism from the architecture seen by either the system designer or the application programmer. This might be done for a programming environment like UNIX, which supports paging but does not support segmentation.

A segment is defined by a segment descriptor. At least two segment descriptors must be created for a flat model, one for code references and one for data references. Both descriptors have the same base address value. Whenever memory is accessed, the contents of one of the segment registers are used to select a segment descriptor. The segment descriptor provides the base address of the segment and its limit, as well as access control information (see Figure 11-1).

ROM usually is put at the top of the physical address space, because the processor begins execution at FFFF\_FFF0H. RAM is placed at the bottom of the address space because the initial base address for the DS data segment after reset initialization is 0.

For a flat model, each descriptor has a base address of 0 and a segment limit of 4 gigabytes. By setting the segment limit to 4 gigabytes, the segmentation mechanism is kept from generating exceptions for memory references which fall outside of a segment. Exceptions could still be generated by the paging or segmentation protection mechanisms, but these also can be removed from the memory model.

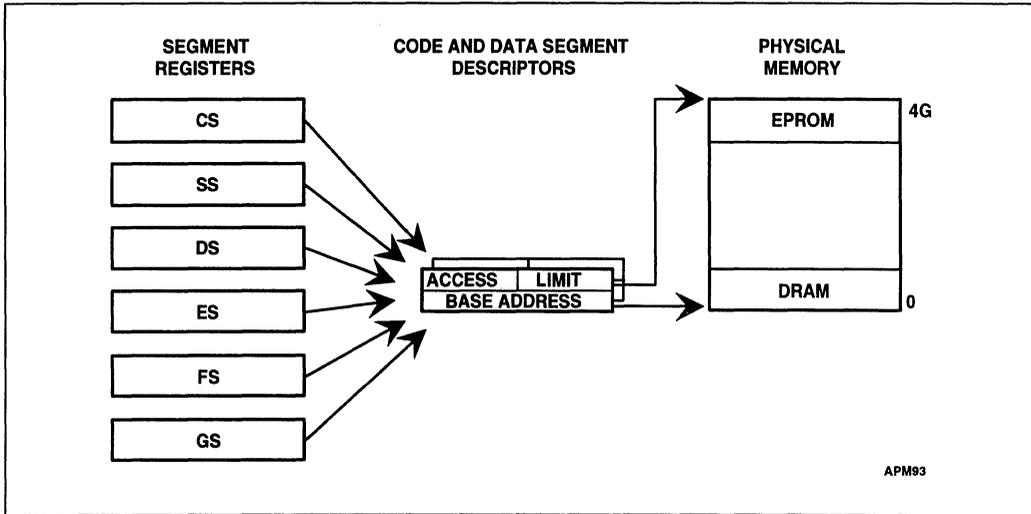


Figure 11-1. Flat Model

### 11.1.2. Protected Flat Model

The protected flat model is like the flat model, except the segment limits are set to include only the range of addresses for which memory actually exists. A general-protection exception will be generated on any attempt to access unimplemented memory. This might be used for systems in which the paging mechanism is disabled, because it provides a minimum level of hardware protection against some kinds of program bugs.

In this model, the segmentation hardware prevents programs from addressing nonexistent memory locations. The consequences of being allowed access to these memory locations are hardware-dependent. For example, if the processor does not receive a **READY#** signal (the signal used to acknowledge and terminate a bus cycle), the bus cycle does not terminate and program execution stops.

Although no program should make an attempt to access these memory locations, an attempt may occur as a result of program bugs. Without hardware checking of addresses, it is possible that a bug could suddenly stop program execution. With hardware checking, programs fail in a controlled way. A diagnostic message can appear and recovery procedures can be attempted.

An example of a protected flat model is shown in Figure 11-2. Here, segment descriptors have been set up to cover only those ranges of memory which exist. A code segment cover the EPROM and DRAM of physical memory. The code segment base and limit can optionally be set to allow access to DRAM area. The data segment limit must be set to the sum of EPROM and DRAM sizes. If memory-mapped I/O is used, it can be addressed just beyond the end of DRAM area.

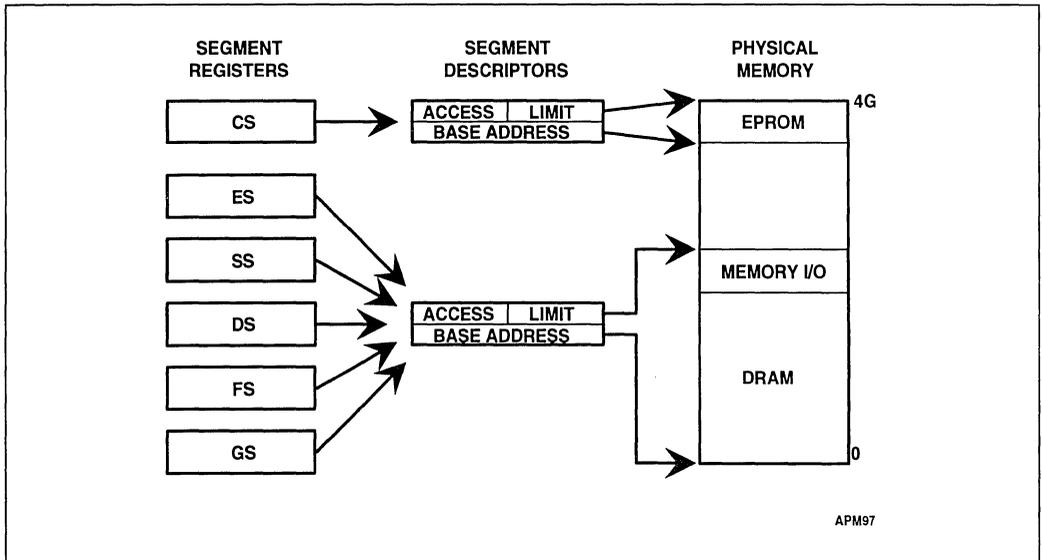


Figure 11-2. Protected Flat Model

### 11.1.3. Multisegment Model

The most sophisticated model is the multisegment model. Here, the full capabilities of the segmentation mechanism are used. Each program is given its own table of segment descriptors, and its own segments. The segments can be completely private to the program, or they can be shared with specific other programs. Access between programs and particular segments can be individually controlled.

Up to six segments can be ready for immediate use. These are the segments which have segment selectors loaded in the segment registers. Other segments are accessed by loading their segment selectors into the segment registers (see Figure 11-3).

Each segment is a separate address space. Even though they may be placed in adjacent blocks of physical memory, the segmentation mechanism prevents access to the contents of one segment by reading beyond the end of another. Every memory operation is checked against the limit specified for the segment it uses. An attempt to address memory beyond the end of the segment generates a general-protection exception.

The segmentation mechanism only enforces the address range specified in the segment descriptor. It is the responsibility of the operating system to allocate separate address ranges to each segment. There may be situations in which it is desirable to have segments which share the same range of addresses. For example, a system can have both code and data stored in a ROM. A code segment descriptor would be used when the ROM is accessed for instruction fetches. A data segment descriptor would be used when the ROM is accessed as data.

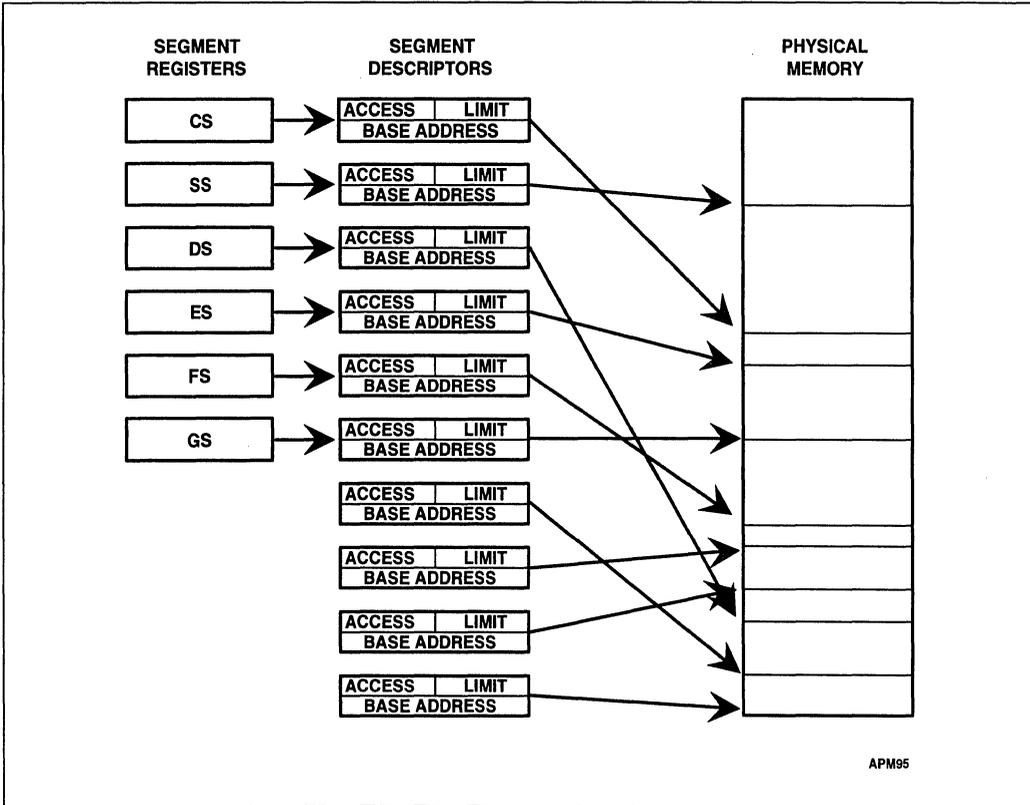


Figure 11-3. Multisegment Model

## 11.2. SEGMENT TRANSLATION

A logical address consists of the 16-bit segment selector for its segment and a 32-bit offset into the segment. The logical address is checked for access rights and range. If it passes these tests, the logical address is translated into a linear address by adding the offset to the base address of the segment. The base address comes from the segment descriptor, a data structure in memory which provides the size and location of a segment, as well as access control information. The segment descriptor comes from one of two tables; the global descriptor table (GDT) or the local descriptor table (LDT). There is one GDT for all programs in the system and one LDT for each separate program being run. If the operating system allows, different programs can share the same LDT. The system also can be set up with no LDTs; all programs will then use the GDT.

Every logical address is associated with a segment (even if the system maps all segments into the same linear address space). Although a program can have thousands of segments, only six can be available for immediate use. These are the six segments whose segment selectors are

loaded in the processor. The segment selector holds information used to translate the logical address into the corresponding linear address.

Separate segment registers exist in the processor for each kind of memory reference (code space, stack space, and data spaces). They hold the segment selectors for the segments currently in use. Access to other segments requires loading a segment register using a form of the MOV instruction. Up to four data spaces can be available at the same time, thus providing a total of six segment registers.

When a segment selector is loaded, the base address, segment limit, and access control information also are loaded into the segment register. The processor does not reference the descriptor tables in memory again until another segment selector is loaded. The information saved in the processor allows it to translate addresses without making extra bus cycles. In systems in which multiple processors have access to the same descriptor tables, it is the responsibility of software to reload the segment registers when the descriptor tables are modified. If this is not done, an old segment descriptor cached in a segment register might be used after its memory-resident version has been modified.

The segment selector contains a 13-bit index into one of the descriptor tables. The index is scaled by eight (the number of bytes in a segment descriptor) and added to the 32-bit base address of the descriptor table. The base address comes from either the global descriptor table register (GDTR) or the local descriptor table register (LDTR). These registers hold the linear address of the beginning of the descriptor tables. A bit in the segment selector specifies which table to use, as shown in Figure 11-4.

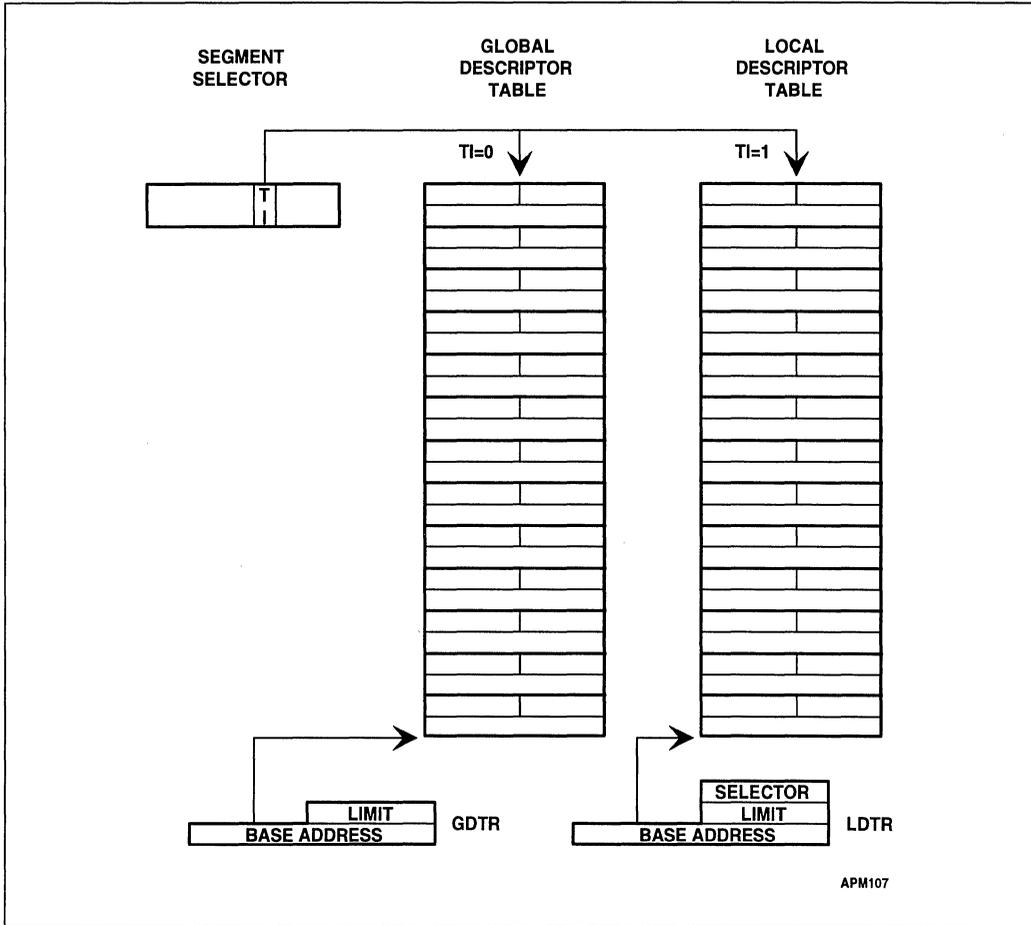


Figure 11-4. TI Bit Selects Descriptor Table

The translated address is the linear address, as shown in Figure 11-5. If paging is not used, it is also the physical address. If paging is used, a second level of address translation produces the physical address. This translation is described in Section 11.3.



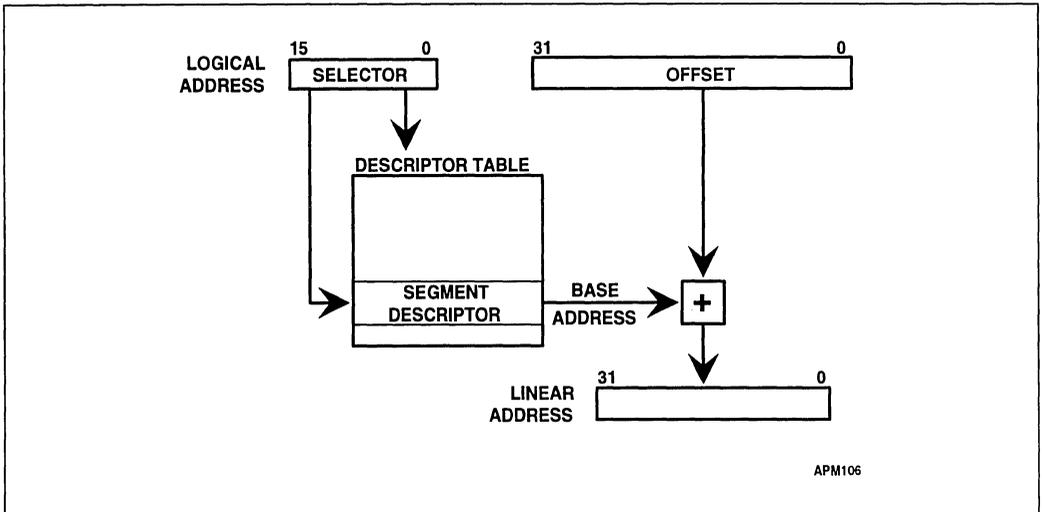


Figure 11-5. Segment Translation

### 11.2.1. Segment Registers

Each kind of memory reference is associated with a segment register. Code, data, and stack references each access the segments specified by the contents of their segment registers. More segments can be made available by loading their segment selectors into these registers during program execution.

Every segment register has a "visible" part and an "invisible" part, as shown in Figure 11-6. There are forms of the MOV instruction to load the visible part of these segment registers. The invisible part is loaded by the processor.

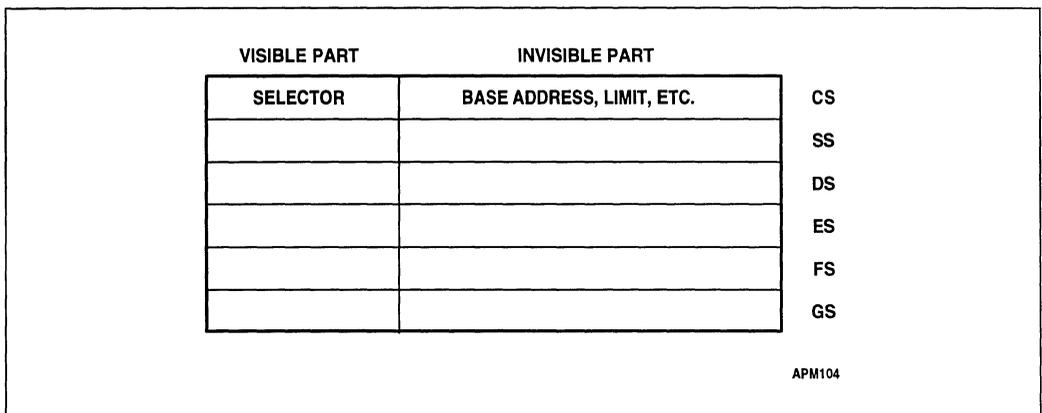


Figure 11-6. Segment Registers

The operations which load these registers are instructions for application programs (described in Chapter 4). There are two kinds of these instructions:

1. Direct load instructions such as the MOV, POP, LDS, LES, LSS, LGS, and LFS instructions. These instructions explicitly reference the segment registers.
2. Implied load instructions such as the far pointer versions of the CALL and JMP instructions. These instructions change the contents of the CS register as an incidental part of their function.

When one of these instructions is executed, the visible part of the segment register is loaded with a segment selector. The processor automatically loads the invisible part of the segment register with information (such as the base address) from the descriptor table. Because most instructions refer to segments whose selectors already have been loaded into segment registers, the processor can add the logical-address offset to the segment base address with no performance penalty.

### 11.2.2. Segment Selectors

A segment selector points to the information which defines a segment, called a segment descriptor. A program may have more segments than the six whose segment selectors occupy segment registers. When this is true, the program uses forms of the MOV instruction to change the contents of these registers when it needs to access a new segment.

A segment selector identifies a segment descriptor by specifying a descriptor table and a descriptor within that table. Segment selectors are visible to application programs as a part of a pointer variable, but the values of selectors are usually assigned or modified by link editors or linking loaders, not application programs. Figure 11-7 shows the format of a segment selector.

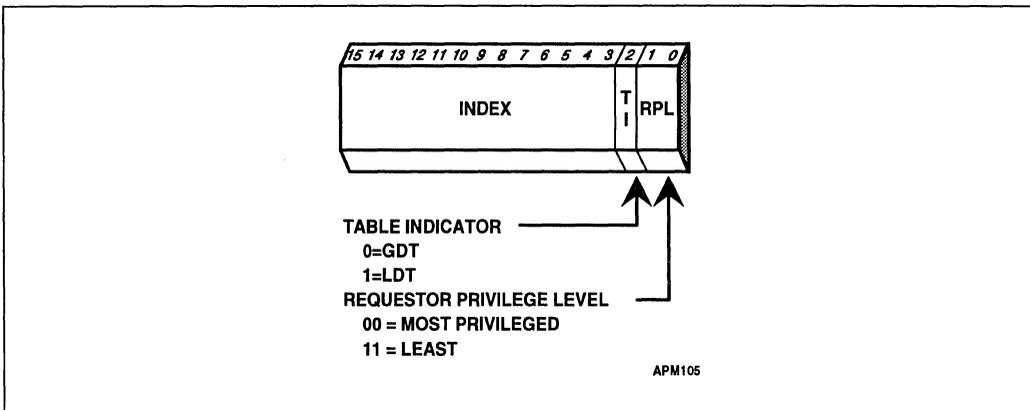


Figure 11-7. Segment Selector

**Index:** Selects one of 8192 descriptors in a descriptor table. The processor multiplies the index value by 8 (the number of bytes in a segment descriptor) and adds the result to the base address of the descriptor table (from the GDTR or LDTR register).

**Table Indicator bit:** Specifies the descriptor table to use. A clear bit selects the GDT; a set bit selects the current LDT.

**Requestor Privilege Level:** When this field of a selector contains a privilege level having a greater value (i.e., less privileged) than the program, it effectively overrides the program's privilege level for accesses that use that selector. When a program uses a less privileged segment selector, memory accesses take place at the lesser privilege level. This is used to guard against a security violation in which a less privileged program uses a more privileged program to access protected data.

For example, system utilities or device drivers must run with a high level of privilege in order to access protected facilities such as the control registers of peripheral interfaces. But they must not interfere with other protected facilities, even if a request to do so is received from a less privileged program. If a program requested reading a sector of disk into memory occupied by a more privileged program, such as the operating system, the RPL can be used to generate a general-protection exception when the less privileged segment selector is used. This exception occurs even though the program using the segment selector would have a sufficient privilege level to perform the operation on its own.

Because the first entry of the GDT is not used by the processor, a selector which has an index of 0 and a table indicator of 0 (i.e., a selector which points to the first entry of the GDT) is used as a "null selector." The processor does not generate an exception when a segment register (other than the CS or SS registers) is loaded with a null selector. It does, however, generate an exception when a segment register holding a null selector is used to access memory. This feature can be used to initialize unused segment registers.

### 11.2.3. Segment Descriptors

A segment descriptor is a data structure in memory which provides the processor with the size and location of a segment, as well as control and status information. Descriptors typically are created by compilers, linkers, loaders, or the operating system, but not application programs. Figure 11-8 illustrates the general descriptor format. All types of segment descriptors use a variation of this basic format.

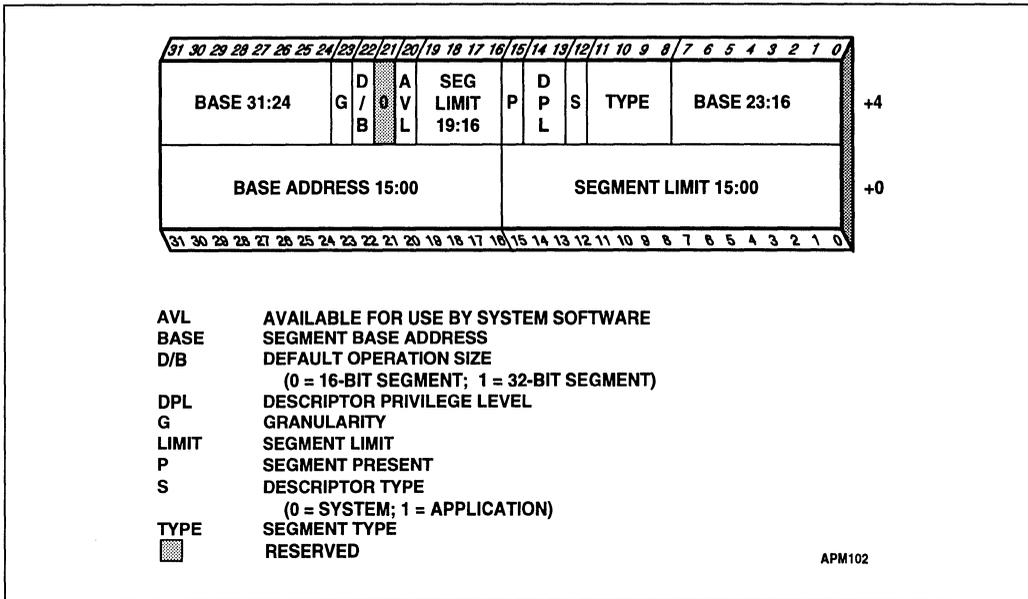


Figure 11-8. Segment Descriptors

**Base:** Defines the location of the segment within the 4-gigabyte physical address space. The processor puts together the three base address fields to form a single 32-bit value. Segment base values should be aligned to 16-byte boundaries to allow programs to maximize performance by aligning code/data on 16-byte boundaries.

**Granularity bit:** Turns on scaling of the Limit field by a factor of 4096 ( $2^{12}$ ). When the bit is clear, the segment limit is interpreted in units of one byte; when set, the segment limit is interpreted in units of 4K bytes. Note that the twelve least significant bits of the address are not tested when scaling is used. For example, a limit of 0 with the Granularity bit set results in valid offsets from 0 to 4095. Also note that only the Limit field is affected. The base address remains byte granular.

**Limit:** Defines the size of the segment. The processor puts together the two limit fields to form a 20-bit value. The processor interprets the segment size in one of two ways, depending on the setting of the Granularity bit:

1. If the Granularity bit is clear, the segment size is from 1 byte to 1 megabyte, in increments of 1 byte.
2. If the Granularity bit is set, the segment size is from 4 kilobytes to 4 gigabytes, in increments of 4K bytes.

For expand-up segments, a logical address can have an offset ranging from 0 to the limit. Other offsets generate exceptions. Expand-down segments reverse the sense of the Limit field; they can be addressed with any offset except those from 0 to the limit (see the Type field, below). This is done to allow segments to be created in which increasing the value held in the Limit field allocates new memory at the bottom of the segment's address space, rather than at the top. Expand-down segments are intended to hold stacks, but it is not necessary to use them. If a stack is going to be put in a segment which does not need to change size, it can be a normal data segment.

**S bit:** Determines whether a given segment is a system segment or a code or data segment. If the S bit is set, then the segment is either a code or a data segment. If it is clear, then the segment is a system segment.

**D bit/B bit:** In a code segment, this bit is called the D bit, and it indicates the default length for operands and effective addresses. If the D bit is set, then 32-bit operands and 32-bit effective addressing modes are assumed. If it is clear, then 16-bit operands and addressing modes are assumed. In a data segment, this bit is called the B bit, and it controls two aspects of stack operation:

1. The size of the stack pointer register. If B = 1, pushes, pops and calls all use 32-bit ESP register; if B = 0, stack operations use the 16-bit SP register.
2. The upper bound of an expand-down stack. In expand-down segments, the Limit field specifies the lower bound of the stack segment, while the upper bound is an address of all 1-bits. If B = 1, the upper bound is FFFF\_FFFFH; if B = 0, the upper bound is FFFFH.

**Type:** The interpretation of this field depends on whether the segment descriptor is for an application segment or a system segment. System segments have a slightly different descriptor format, discussed in Chapter 12. The Type field of a memory descriptor specifies the kind of access which may be made to a segment, and its direction of growth (see Table 11-1).

For data segments, the three lowest bits of the type field can be interpreted as expand-down (E), write enable (W), and accessed (A). For code segments, the three lowest bits of the type field can be interpreted as conforming (C), read enable (R), and accessed (A).

Data segments can be read-only or read/write. Stack segments are data segments which must be read/write. Loading the SS register with a segment selector for any other type of segment generates a general-protection exception. If the stack segment needs to be able to change size, it can be an expand-down data segment. The meaning of the segment limit is reversed for an expand-down segment. The valid offsets in an expand-down segment are those which generate exceptions in expand-up segments. Expand-up segments must be addressed by offsets which are equal or less than the segment limit. Offsets into expand-down segments always must be greater than the segment limit. This interpretation of the segment limit causes memory space to be allocated at the bottom of the segment when the segment limit is decreased, which is correct for stack segments because they grow toward lower addresses. If the stack is given a segment which does not change size, the segment does not need to be expand-down.

**Table 11-1. Application Segment Types**

Type	11	10 E	9 W	8 A	Descriptor Type	Description
0	0	0	0	0	Data	Read-Only
1	0	0	0	1	Data	Read-Only, accessed
2	0	0	1	0	Data	Read/Write
3	0	0	1	1	Data	Read/Write, accessed
4	0	1	0	0	Data	Read-Only, expand-down
5	0	1	0	1	Data	Read-Only, expand-down, accessed
6	0	1	1	0	Data	Read/Write, expand-down
7	0	1	1	1	Data	Read/Write, expand-down, accessed
Type	11	10 C	9 R	8 A	Descriptor Type	Description
8	1	0	0	0	Code	Execute-Only
9	1	0	0	1	Code	Execute-Only, accessed
10	1	0	1	0	Code	Execute/Read
11	1	0	1	1	Code	Execute/Read, accessed
12	1	1	0	0	Code	Execute-Only, conforming
13	1	1	0	1	Code	Execute-Only, conforming, accessed
14	1	1	1	0	Code	Execute/Read-Only, conforming
15	1	1	1	1	Code	Execute/Read-Only, conforming, accessed

Code segments can be execute-only or execute/read. An execute/read segment might be used, for example, when constants have been placed with instruction code in a ROM. In this case, the constants can be read either by using an instruction with a CS override prefix or by placing a segment selector for the code segment in a segment register for a data segment.

Code segments can be either conforming or non-conforming. A transfer of execution into a more privileged conforming segment keeps the current privilege level. A transfer into a non-conforming segment at a different privilege level results in a general-protection exception, unless a task gate is used (see Chapter 13 for a discussion of multitasking). System utilities which do not access protected facilities, such as data-conversion functions (e.g., EBCDIC/ASCII translation, Huffman encoding/decoding, math library) and some types of exceptions (e.g., Divide Error, INTO-detected overflow, and BOUND range exceeded) may be loaded in conforming code segments.

The A (accessed) bit of the Type field is set by the processor to indicate that a segment has been loaded into a segment register. By clearing the A-bit initially, then testing it later, software can monitor segment usage. For example, a program development system might clear all of the Accessed bits for the segments of an application. If the application crashes, the states of these bits can be used to generate a map of all the segments accessed by the application. Unlike the breakpoints provided by the debugging mechanism (Chapter 17), the usage information applies to segment usage rather than linear address matches.

The processor may update the Type field when a segment is accessed, even if the access is a read cycle. If the descriptor tables have been put in ROM, it may be necessary for hardware to prevent the ROM from being enabled onto the data bus during a write cycle. It also may be necessary to return the READY# signal to the processor when a write cycle to ROM occurs, otherwise the cycle does not terminate. These features of the hardware design are

necessary for using ROM-based descriptor tables with the Intel386 DX processor, which always sets the Accessed bit when a segment descriptor is loaded. The Intel486 and Pentium processors, however, only set the Accessed bit if it is not already set. Writes to descriptor tables in ROM can be avoided by setting the Accessed bits in every descriptor.

**DPL (Descriptor Privilege Level):** Defines the privilege level of the segment. This is used to control access to the segment, using the protection mechanism described in Chapter 12.

**Segment-Present bit:** If this bit is clear, the processor generates a segment-not-present exception when a selector for the descriptor is loaded into a segment register. This is used to detect access to segments which have become unavailable. A segment can become unavailable when the system needs to create free memory. Items in memory, such as character fonts or device drivers, which currently are not being used are deallocated. An item is deallocated by marking the segment "not present" (this is done by clearing the Segment-Present bit). The memory occupied by the segment then can be put to another use. The next time the deallocated item is needed, the segment-not-present exception will indicate the segment needs to be loaded into memory. When this kind of memory management is provided in a manner invisible to application programs, it is called virtual memory. A system can maintain a total amount of virtual memory far larger than physical memory by keeping only a few segments present in physical memory at any one time.

Figure 11-9 shows the format of a descriptor when the Segment-Present bit is clear. When this bit is clear, the operating system is free to use the locations marked Available to store its own data, such as information regarding the whereabouts of the missing segment.

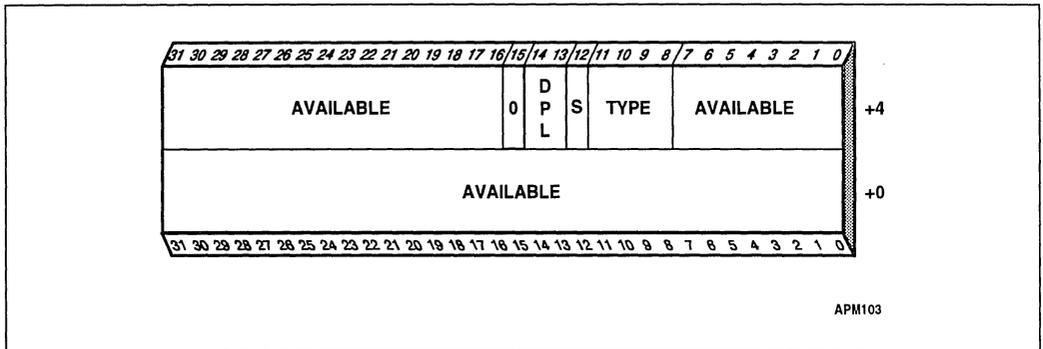


Figure 11-9. Segment Descriptor (Segment Not Present)

### 11.2.4. Segment Descriptor Tables

A segment descriptor table is an array of segment descriptors. There are two kinds of descriptor tables:

- The global descriptor table (GDT)
- The local descriptor tables (LDT)

There is one GDT for all tasks, and an LDT for each task being run. A descriptor table is an array of segment descriptors, as shown in Figure 11-10. A descriptor table is variable in length and can contain up to 8192 ( $2^{13}$ ) descriptors. The first descriptor in the GDT is not used by the processor. A segment selector to this "null descriptor" does not generate an exception when loaded into a data segment register (DS, ES, FS, or GS), but it always generates an exception when an attempt is made to access memory using the descriptor. By initializing the segment registers with this segment selector, accidental reference to unused segment registers can be guaranteed to generate an exception.

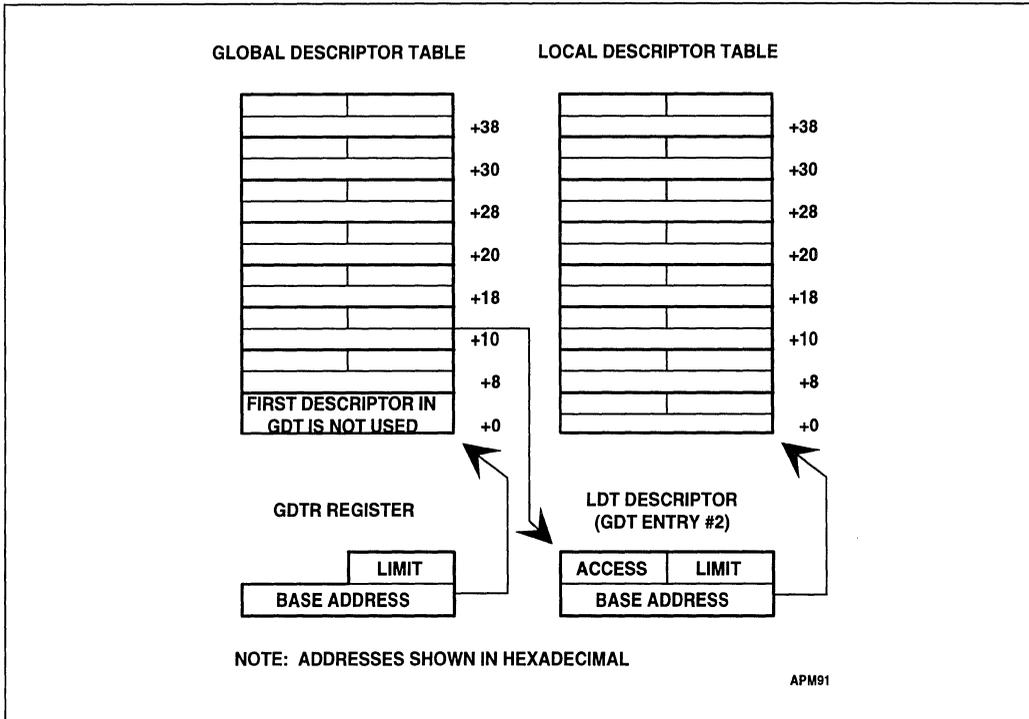


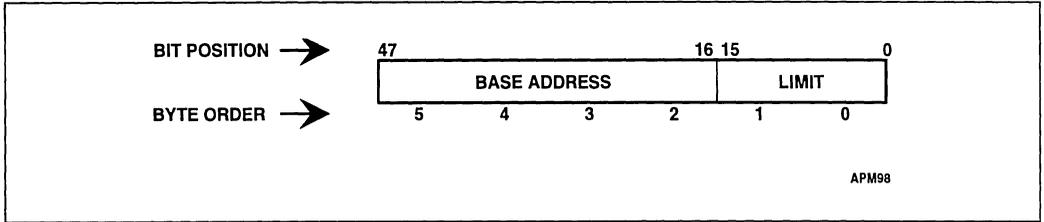
Figure 11-10. Descriptor Tables

### 11.2.5. Descriptor Table Base Registers

The processor finds the global descriptor table (GDT) and interrupt descriptor table (IDT) using the GDTR and IDTR registers. These registers hold 32-bit base addresses for tables in the linear address space. They also hold 16-bit limit values for the size of these tables.

When the IDTR and GDTR registers are loaded or stored, a 48-bit "pseudo-descriptor" is accessed in memory, as shown in Figure 11-11. To avoid alignment check faults in user mode (privilege level 3), the pseudo-descriptor should be located at an odd word address (i.e., an address which is 2 MOD 4). This causes the processor to store an aligned word,

followed by an aligned doubleword. User-mode programs normally do not store pseudo-descriptors, but the possibility of generating an alignment check fault can be avoided by aligning pseudo-descriptors in this way.



**Figure 11-11. Pseudo-Descriptor Format**

The base addresses of the GDT and IDT should be aligned on an eight-byte boundary to maximize performance of cache line fills.

The limit values for both the GDT and IDT are expressed in bytes. As with segments, the limit value is added to the base address to get the address of the last valid byte. A limit value of zero results in exactly one valid byte. Because segment descriptors are always eight bytes long, the limit should always be one less than an integral multiple of eight (i.e.,  $8N - 1$ ). The LGDT and SGDT instructions write and read the GDTR register; the LIDT and SIDT instructions write and read the IDTR register.

A third descriptor table is the local descriptor table (LDT). It is identified by a 16-bit segment selector held in the LDTR register. The LLDT and SLDT instructions write and read the segment selector in the LDTR register. The LDTR register also holds the base address and limit for the LDT, but these are loaded automatically by the processor from the segment descriptor for the LDT (which is taken from the GDT). The LDT should be aligned on an eight-byte boundary to maximize performance of cache line fills.

### 11.3. PAGE TRANSLATION

A linear address is a 32-bit address into a uniform, unsegmented address space. This address space can be a large physical address space (i.e., an address space composed of several gigabytes of RAM), or paging can be used to simulate this address space using a small amount of RAM and some disk storage. When paging is used, a linear address is translated into its corresponding physical address, or an exception is generated. The exception gives the operating system a chance to read the page from disk (perhaps sending a different page out to disk in the process), then restart the instruction which generated the exception.

Paging is different from segmentation through its use of fixed-size pages. Unlike segments, which usually are the same size as the code or data structures they hold, pages have a fixed size. If segmentation is the only form of address translation which is used, a data structure which is present in physical memory will have all of its parts in memory. If paging is used, a data structure can be partly in memory and partly in disk storage.

The information which either maps linear addresses into physical addresses or raises exceptions is held in data structures in memory called page tables. As with segmentation, this information is cached within the CPU to minimize the number of bus cycles required for address translation. Unlike segmentation, the address translation caches are completely invisible to application programs. The processor's caches for address translation information are called translation lookaside buffers (TLB). The TLBs satisfy most requests for reading the page tables. Extra bus cycles occur only when the TLBs cannot satisfy a request. This typically happens when a page has not been accessed for a long time.

### 11.3.1. Paging Options

Paging is enabled when bit 31 (the PG bit) of the CR0 register is set. This bit usually is set by the operating system during software initialization. (Refer to Chapter 16 for information on how to change PG.) When paging is enabled, a second stage of address translation is used to generate the physical address from the linear address. If paging is not enabled, the linear address is used as the physical address. The PG bit must be set if the operating system is running more than one program in virtual-8086 mode or if demand-paged virtual memory is used.

### 11.3.2. Linear Address

Figure 11-12 shows the format of a linear address for a 4K page.

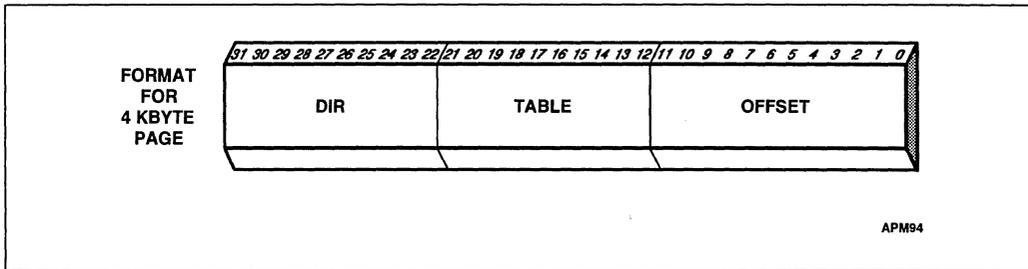


Figure 11-12. Format of a Linear Address

Figure 11-13 shows how the processor translates the DIRECTORY, TABLE, and OFFSET fields of a linear address into the physical address by consulting page tables. The addressing mechanism uses the DIRECTORY field as an index into a page directory. It uses the TABLE field as an index into the page table determined by the page directory. It uses the OFFSET field to address an operand within the page specified by the page table.

### 11.3.3. Page Tables

A page table is an array of 32-bit entries. A page table is itself a page, and contains 4096 bytes of data or at most 1K 32-bit entries. Four kilobyte pages, including page directories and page tables, are aligned to 4K-byte boundaries. Two levels of tables are used to address a page of memory. At the highest level is a page directory. A page directory holds up to 1K entries that address page tables of the second level. A page table of the second level addresses up to 1K pages in physical memory. All the tables addressed by one page directory, therefore, can address 1M ( $2^{20}$ ) four-Kbyte pages. If each page contains 4K ( $2^{12}$ ) bytes, the tables of one page directory can span a linear address space of four gigabytes ( $2^{20} \times 2^{12} = 2^{32}$ ). For information on support of page sizes larger than 4K, see Appendix H.

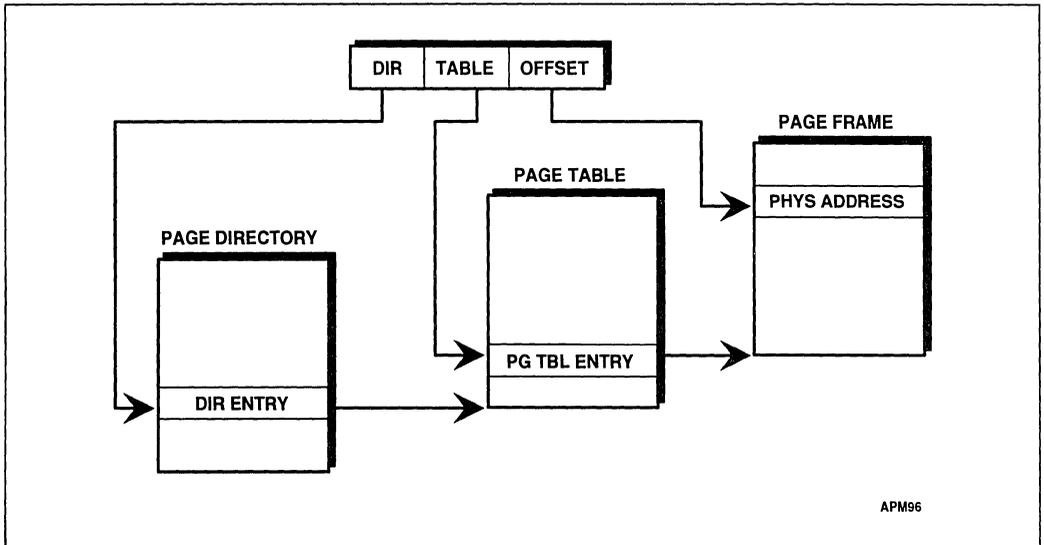


Figure 11-13. Page Translation

The physical address of the current page directory is stored in the CR3 register, also called the page directory base register (PDBR). Memory management software has the option of using one page directory for all tasks, one page directory for each task, or some combination of the two. See Chapter 16 for information on initialization of the CR3 register. See Chapter 13 for how the contents of the CR3 register can change for each task.

### 11.3.4. Page-Table Entries

Page-table and page-directory entries for 4K pages have one of the formats shown by Figure 11-14. For information on page-table and page-directory formats for pages larger than 4K, see Appendix H.

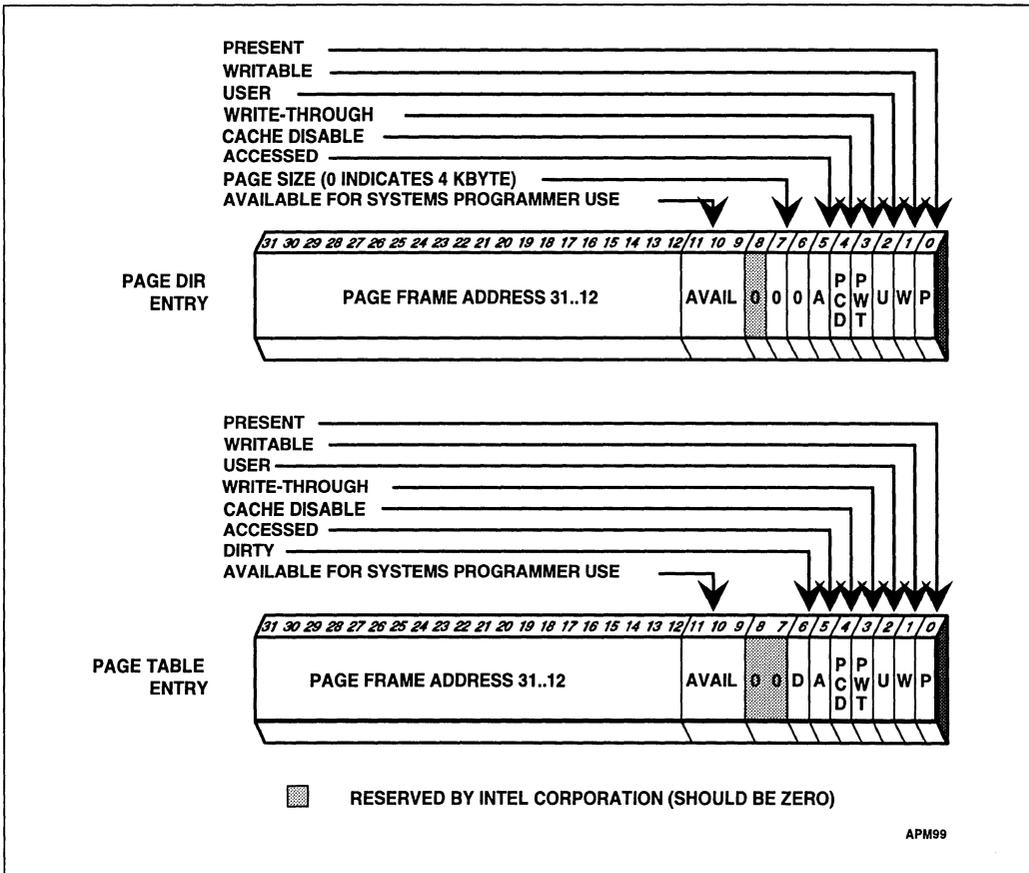


Figure 11-14. Format of Page Directory and Page Table Entries for 4K Pages

### 11.3.4.1. PAGE FRAME ADDRESS

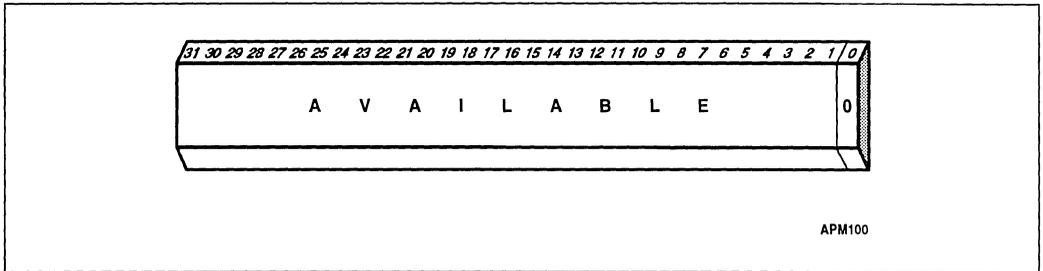
The page frame address specifies the physical starting address of a page. In a page directory, the page frame address is the address of a page table. In a second-level page table, the page frame address is the address of the four kilobyte page that contains the desired memory operand or instructions.

### 11.3.4.2. PRESENT BIT

The Present bit indicates whether the page frame address in a page table entry maps to a page in physical memory. When set, the page is in memory.

When the Present bit is clear, the page is not in memory, and the rest of the page table entry is available for the operating system, for example, to store information regarding the

whereabouts of the missing page. Figure 11-15 illustrates the format of a page table entry when the Present bit is clear.



**Figure 11-15. Format of a Page Table Entry for a Not-Present Page**

If the Present bit is clear in either level of page tables when an attempt is made to use a page table entry for address translation, a page-fault exception is generated. In systems which support demand-paged virtual memory, the following sequence of events then occurs:

1. The operating system copies the page from disk storage into physical memory.
2. The operating system loads the page frame address into the page table entry and sets its Present bit. Other bits, such as the dirty and accessed bits, may be set, too.
3. Because a copy of the old page table entry may still exist in a translation lookaside buffer (TLB), the operating system invalidates them. See Section 11.3.5. for a discussion of TLBs and how to invalidate them.
4. The program which caused the exception is then restarted.

Note that there is no Present bit in CR3 for the page directory itself. The page directory may be not-present while the associated task is suspended, but the operating system must ensure that the page directory indicated by the CR3 image in a process's TSS is present in physical memory before the process is dispatched. The page directory must also remain in memory as long as the task is active.

**11.3.4.3. ACCESSED AND DIRTY BITS**

These bits provide data about page usage in both levels of page tables. The Accessed bit is used to report read or write access to a page or to a second-level page table. The Dirty bit is used to report write access to a page. These bits are set by the hardware; however, the processor does not implicitly clear either of these bits.

The processor sets the Accessed bit in both levels of page table before a read or write operation to a page. The processor sets the Dirty bit before a write operation to an address mapped by that page table entry. Only the Dirty bit in the second-level page table is used; the processor does not use the Dirty bit of the page directory.

The operating system may use the Accessed bit when it needs to create some free memory by sending a page or second-level page table to disk storage. By periodically clearing the

Accessed bits in the page tables, it can see which pages have been used recently. Pages which have not been used are candidates for sending out to disk.

The operating system may use the Dirty bit when a page is sent back to disk. By clearing the Dirty bit when the page is brought into memory, the operating system can see if it has received any write access. If there is a copy of the page on disk and the copy in memory has not received any writes, there is no need to update disk from memory.

See Chapter 19 for how the processor updates the Accessed and Dirty bits in multiprocessor systems.

#### **11.3.4.4. READ/WRITE AND USER/SUPERVISOR BITS**

The Read/Write and User/Supervisor bits are used for protection checks applied to pages, which the processor performs at the same time as address translation. See Chapter 12 for more information on protection.

#### **11.3.4.5. PAGE-LEVEL CACHE CONTROL BITS**

The PCD and PWT bits are used for page-level cache management. Software can control the caching of individual pages or second-level page tables using these bits. See Chapter 18 for more information on caching.

### **11.3.5. Translation Lookaside Buffers**

The processor stores the most recently used page table entries in on-chip caches called translation lookaside buffers or TLBs. The Pentium microprocessor has separate TLB's for the data and instruction caches. Most paging is performed using the contents of the TLBs. Bus cycles to the page tables in memory are performed only when the TLBs do not contain the translation information for a requested page.

The TLBs are invisible to application programs (with  $PL > 0$ ), but not to operating systems ( $PL = 0$ ). Operating-system programmers must invalidate the TLBs (dispose of their page table entries) immediately following and every time there are changes to entries in the page tables (including when the present bit is set to zero). If this is not done, old data which has not received the changes might be used for address translation and as a result, subsequent page table references could be incorrect.

The operating system can invalidate the TLBs by loading the CR3 register. The CR3 register can be loaded in either of two ways:

1. Explicit loading using MOV instructions, such as:  
`MOV CR3, EAX`
2. Implicit loading by a task switch which changes the contents of the CR3 register. (See Chapter 13 for more information on task switching.)



When the mapping of an individual page is changed, the operating system should use the INVLPG instruction. Where possible, INVLPG invalidates only an individual TLB entry; however, in some cases, INVLPG invalidates the entire instruction-cache TLB.

## 11.4. COMBINING SEGMENT AND PAGE TRANSLATION

Figure 11-16 combines Figure 11-5 and Figure 11-13 to summarize both stages of translation from a logical address to a physical address when paging is enabled. Options available in both stages of address translation can be used to support several different styles of memory management.

### 11.4.1. Flat Model

When a 32-bit processor is used to run software written without segments, it may be desirable to remove the segmentation features of the processor. The 32-bit processors do not have a mode bit for disabling segmentation, but the same effect can be achieved by mapping the stack, code, and data spaces to the same range of linear addresses. The 32-bit offsets used by 32-bit processor instructions can cover a four-gigabyte linear address space.

When paging is used, the segments can be mapped to the entire linear address space. If more than one program is being run at the same time, the paging mechanism can be used to give each program a separate address space.

### 11.4.2. Segments Spanning Several Pages

The architecture allows segments which are larger than the size of a page. For example, a large data structure may span thousands of pages. If paging were not used, access to any part of the data structure would require the entire data structure to be present in physical memory. With paging, only the page containing the part being accessed needs to be in memory.

### 11.4.3. Pages Spanning Several Segments

Segments also can be smaller than the size of a page. If one of these segments is placed in a page which is not shared with another segment, the extra memory is wasted. For example, a small data structure, such as a 1-byte semaphore, occupies 4K bytes if it is placed in a page by itself. If many semaphores are used, it is more efficient to pack them into a single page.

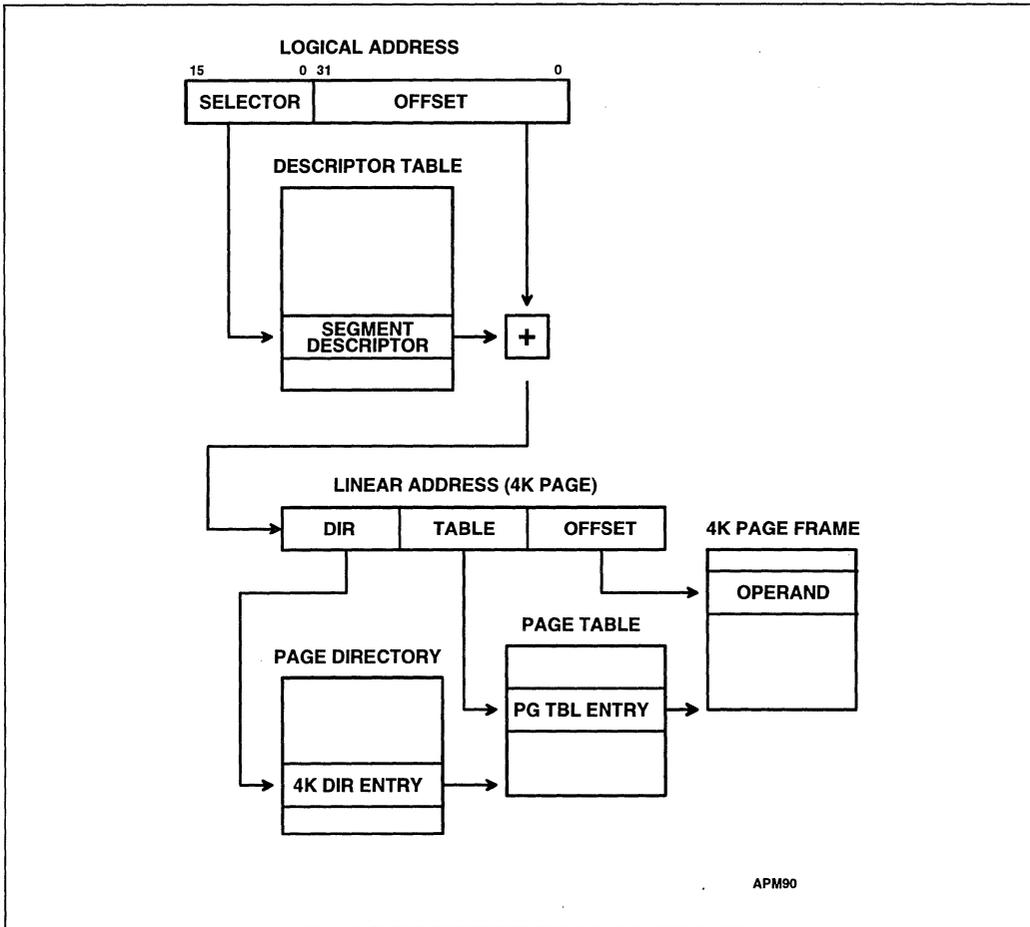


Figure 11-16. Combined Segment and Page Address Translation

### 11.4.4. Non-Aligned Page and Segment Boundaries

The architecture does not enforce any correspondence between the boundaries of pages and segments. A page can contain the end of one segment and the beginning of another. Likewise, a segment can contain the end of one page and the beginning of another.

### 11.4.5. Aligned Page and Segment Boundaries

Memory-management software may be simpler and more efficient if it enforces some alignment between page and segment boundaries. For example, if a segment which can fit in

one page is placed in two pages, there may be twice as much paging overhead to support access to that segment.

### 11.4.6. Page-Table Per Segment

An approach to combining paging and segmentation which simplifies memory-management software is to give each segment its own page table, as shown in Figure 11-17. This gives the segment a single entry in the page directory which provides the access control information for paging the segment.

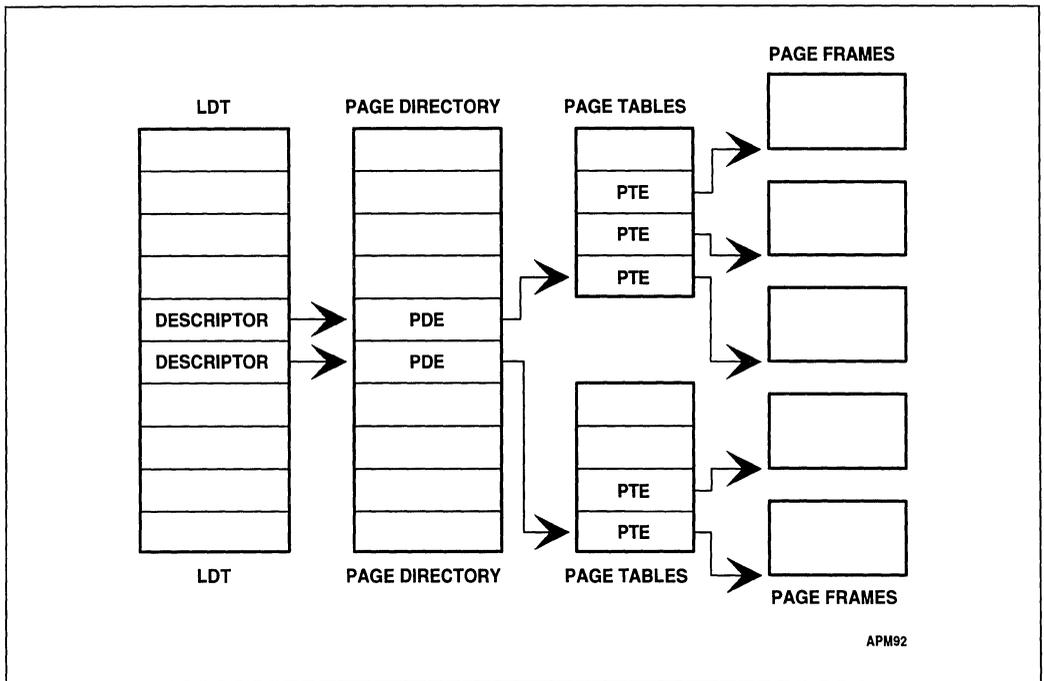


Figure 11-17. Each Segment Can Have Its Own Page Table



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**12**

**Protection**



## CHAPTER 12 PROTECTION

Protection is necessary for reliable multitasking. Protection can be used to prevent tasks from interfering with each other. For example, protection can keep one task from overwriting the instructions or data of another task.

During program development, the protection mechanism can give a clearer picture of program bugs. When a program makes an unexpected reference to the wrong memory space, the protection mechanism can block the event and report its occurrence.

In end-user systems, the protection mechanism can guard against the possibility of software failures caused by undetected program bugs. If a program fails, its effects can be confined to a limited domain. The operating system can be protected against damage, so diagnostic information can be recorded and automatic recovery attempted.

Protection can be applied to segments and pages. Two bits in a processor register define the privilege level of the program currently running (called the current privilege level or CPL). The CPL is checked during address translation for segmentation and paging.

Although there is no control register or mode bit for turning off the protection mechanism, the same effect can be achieved by assigning privilege level 0 (the highest level of privilege) to all segment selectors, segment descriptors, and page table entries.

### 12.1. SEGMENT-LEVEL PROTECTION

Protection provides the ability to limit the amount of interference a malfunctioning program can inflict on other programs and their data. Protection is a valuable aid in software development because it allows software tools (operating system, debugger, etc.) to survive in memory undamaged. When an application program fails, the software is available to report diagnostic messages, and the debugger is available for post-mortem analysis of memory and registers. In production, protection can make software more reliable by giving the system an opportunity to initiate recovery procedures.

Each memory reference is checked to verify that it satisfies the protection checks. All checks are made before the memory cycle is started; any violation prevents the cycle from starting and results in an exception. Because checks are performed in parallel with address translation, there is no performance penalty. There are five protection checks:

1. Type check
2. Limit check
3. Restriction of addressable domain
4. Restriction of procedure entry points
5. Restriction of instruction set

A protection violation results in an exception. See Chapter 14 for an explanation of the exception mechanism. This chapter describes the protection violations which lead to exceptions.

## 12.2. SEGMENT DESCRIPTORS AND PROTECTION

Figure 12-1 shows the fields of a segment descriptor which are used by the protection mechanism. Individual bits in the Type field also are referred to by the names of their functions.

When the operating system creates a descriptor, it sets the protection parameters. In general, application programmers do not need to be concerned about protection parameters.

When a program loads a segment selector into a segment register, the processor loads both the base address of the segment and the protection information. The invisible part of each segment register has storage for the base, limit, type, and privilege level. While this information is resident in the segment register, subsequent protection checks on the same segment can be performed with no performance penalty.

### 12.2.1. Type Checking

In addition to the descriptors for application code and data segments, the processor has descriptors for system segments and gates. These are data structures used for managing tasks (Chapter 13) and exceptions and interrupts (Chapter 14). Table 12-1 lists all the types defined for system segments and gates. Note that not all descriptors define segments; gate descriptors hold pointers to procedure entry points.



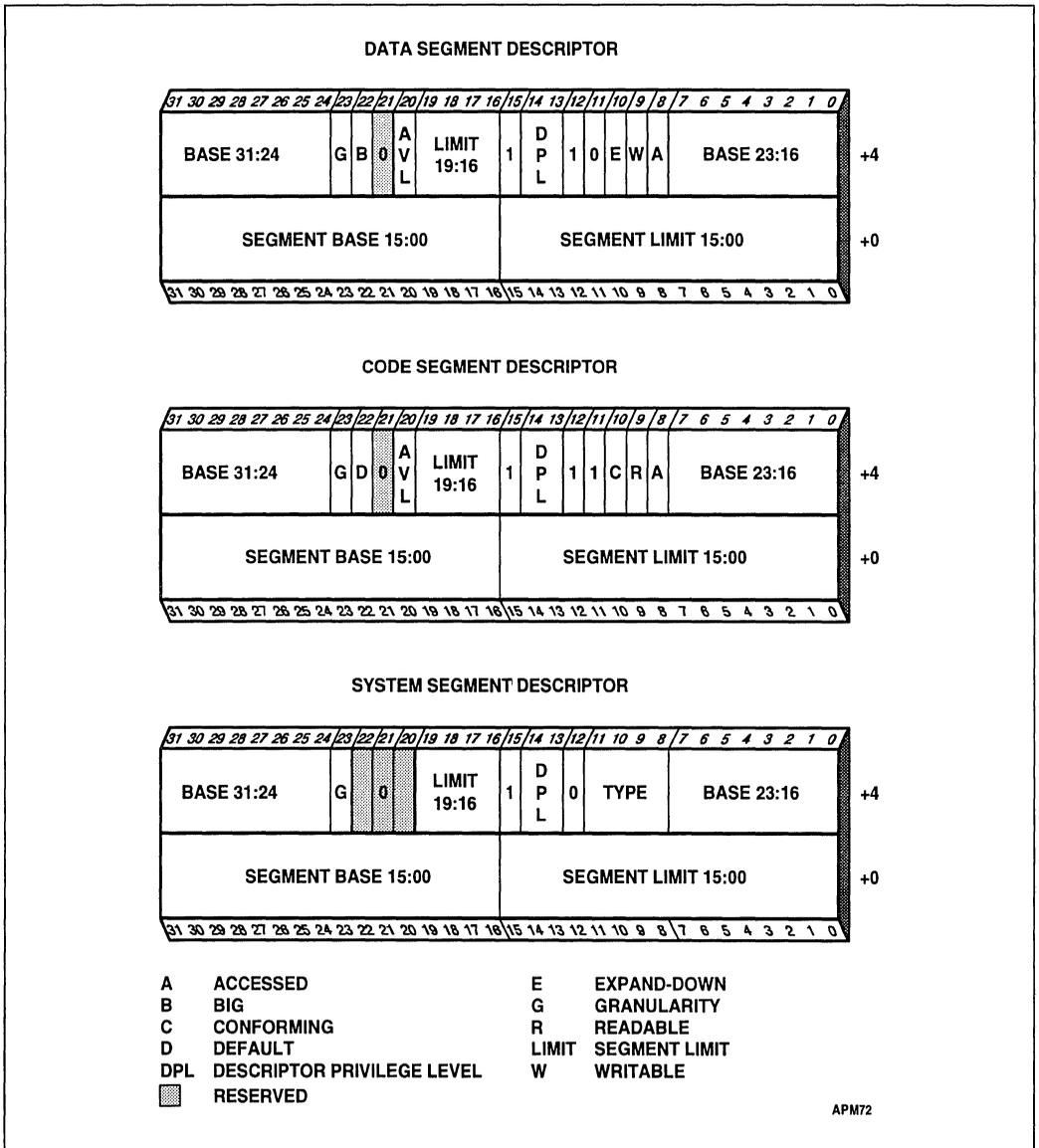


Figure 12-1. Descriptor Fields Used for Protection

**Table 12-1. System Segment and Gate Types**

Type		Description
Decimal	Binary	
0	0 0 0 0	Reserved
1	0 0 0 1	Available 16-Bit TSS
2	0 0 1 0	LDT
3	0 0 1 1	Busy 16-Bit TSS
4	0 1 0 0	16-Bit Call Gate
5	0 1 0 1	Task Gate
6	0 1 1 0	16-Bit Interrupt Gate
7	0 1 1 1	16-Bit Trap Gate
8	1 0 0 0	Reserved
9	1 0 0 1	Available 32-Bit TSS
10	1 0 1 0	Reserved
11	1 0 1 1	Busy 32-Bit TSS
12	1 1 0 0	32-Bit Call Gate
13	1 1 0 1	Reserved
14	1 1 1 0	32-Bit Interrupt Gate
15	1 1 1 1	32-Bit Trap Gate

The Type fields of code and data segment descriptors include bits which further define the purpose of the segment (see Figure 12-1):

- The Writable bit in a data-segment descriptor controls whether programs can write to the segment.
- The Readable bit in an executable-segment descriptor specifies whether programs can read from the segment (e.g., to access constants stored in the code space). A readable, executable segment may be read in two ways:
  1. With the CS register, by using a CS override prefix.
  2. By loading a selector for the descriptor into a data-segment register (the DS, ES, FS, or GS registers).

Type checking can be used to detect programming errors which would attempt to use segments in ways not intended by the programmer. The processor examines type information on two kinds of occasions:

1. When a selector for a descriptor is loaded into a segment register. Certain segment registers can contain only certain descriptor types; for example:
  - The CS register only can be loaded with a selector for an executable segment.
  - Selectors of executable segments which are not readable cannot be loaded into data-segment registers.
  - Only selectors of writable data segments can be loaded into the SS register.
2. When instructions access segments whose descriptors are already loaded into segment registers. Certain segments can be used by instructions only in certain predefined ways; for example:
  - No instruction may write into an executable segment.
  - No instruction may write into a data segment if the writable bit is not set.
  - No instruction may read an executable segment unless the readable bit is set.

### 12.2.2. Limit Checking

The Limit field of a segment descriptor prevents programs from addressing outside the segment. The effective value of the limit depends on the setting of the G bit (Granularity bit). For data segments, the limit also depends on the E bit (Expansion Direction bit). The E bit is a designation for one bit of the Type field, when referring to data segment descriptors.

When the G bit is clear, the limit is the value of the 20-bit Limit field in the descriptor. In this case, the limit ranges from 0 to F\_FFFFH ( $2^{20} - 1$  or 1 megabyte). When the G bit is set, the processor scales the value in the Limit field by a factor of  $2^{12}$ . In this case the limit ranges from 0FFFH ( $2^{12} - 1$  or 4K bytes) to FFFF\_FFFFH ( $2^{32} - 1$  or 4 gigabytes). Note that when scaling is used, the lower twelve bits of the address are not checked against the limit; when the G bit is set and the segment limit is 0, valid offsets within the segment are 0 through 4095.

For all types of segments except expand-down data segments, the value of the limit is one less than the size, in bytes, of the segment. The processor causes a general-protection exception in any of these cases:

- Attempt to access a memory byte at an address  $>$  limit
- Attempt to access a memory word at an address  $>$  (limit  $- 1$ )
- Attempt to access a memory doubleword at an address  $>$  (limit  $- 3$ )
- Attempt to access a memory quadword at an address  $>$  (limit  $- 7$ )

For expand-down data segments, the limit has the same function but is interpreted differently. In these cases the range of valid offsets is from (limit  $+ 1$ ) to  $2^{32} - 1$  if B-bit = 1 and  $2^{16} - 1$  if B-bit = 0. An expand-down segment has maximum size when the segment limit is 0.

Limit checking catches programming errors such as runaway subscripts and invalid pointer calculations. These errors are detected when they occur, so identification of the cause is

easier. Without limit checking, these errors could overwrite critical memory in another module, and the existence of these errors would not be discovered until the damaged module crashed, an event which may occur long after the actual error. Protection can block these errors and report their source.

In addition to limit checking on segments, there is limit checking on the descriptor tables. The GDTR, LDTR, and IDTR registers contain a 16-bit limit value. It is used by the processor to prevent programs from selecting a segment descriptor outside the descriptor table. The limit of a descriptor table identifies the last valid byte of the table. Because each descriptor is eight bytes long, a table which contains up to  $N$  descriptors should have a limit of  $8N - 1$ .

A selector may be given a zero value. Such a selector refers to the first descriptor in the GDT, which is not used. Although this descriptor can be loaded into a segment register, any attempt to reference memory using this descriptor will generate a general-protection exception.

### 12.2.3. Privilege Levels

The protection mechanism recognizes four privilege levels, numbered from 0 to 3. The greater numbers mean lesser privileges. If all other protection checks are satisfied, a general-protection exception is generated if a program attempts to access a segment using a less privileged level (greater privilege number) than that applied to the segment.

Although no control register or mode bit is provided for turning off the protection mechanism, the same effect can be achieved by assigning all privilege levels the value of 0. (The PE bit in the CR0 register is not an enabling bit for the protection mechanism alone; it is used to enable protected mode, the mode of program execution in which the full 32-bit architecture is available. When protected mode is disabled, the processor operates in real-address mode, where it appears as a fast, enhanced 8086 processor.)

Privilege levels can be used to improve the reliability of operating systems. By giving the operating system the greatest privilege (numerically lowest privilege level), it is protected from damage by bugs in other programs. If a program crashes, the operating system has a chance to generate a diagnostic message and attempt recovery procedures.

Another level of privilege can be established for other parts of the system software, such as the programs which handle peripheral devices. If a device driver crashes, the operating system should be able to report a diagnostic message, so it makes sense to protect the operating system against bugs in device drivers. A device driver, however, may service an important peripheral such as a disk drive. If the application program crashes, the device driver should not corrupt the directory structure of the disk, so it makes sense to protect device drivers against bugs in applications. Device drivers should be given an intermediate privilege level between the operating system and the application programs. Application programs are given the least privilege (numerically greatest level).

Figure 12-2 shows how these levels of privilege can be interpreted as rings of protection. The center is for the segments containing the most critical software, usually the kernel of an operating system. Outer rings are for less critical software.



The following data structures contain privilege levels:

- The lowest two bits of the CS segment register hold the current privilege level (CPL). This is the privilege level of the program being run. The lowest two bits of the SS register also hold a copy of the CPL. Normally, the CPL is equal to the privilege level of the code segment from which instructions are being fetched. The CPL changes when control is transferred to a code segment with a different privilege level.
- Segment descriptors contain a field called the descriptor privilege level (DPL). The DPL is the privilege level applied to a segment.
- Segment selectors contain a field called the requestor privilege level (RPL). The RPL is intended to represent the privilege level of the procedure which created the selector. If the RPL is a less privileged level than the CPL, it overrides the CPL. When a more privileged program receives a segment selector from a less privileged program, the RPL causes the memory access to take place at the less privileged level.

Privilege levels are checked when the selector of a descriptor is loaded into a segment register. The checks used for data access differ from those used for transfers of execution among executable segments; therefore, the two types of access are considered separately in the following sections.

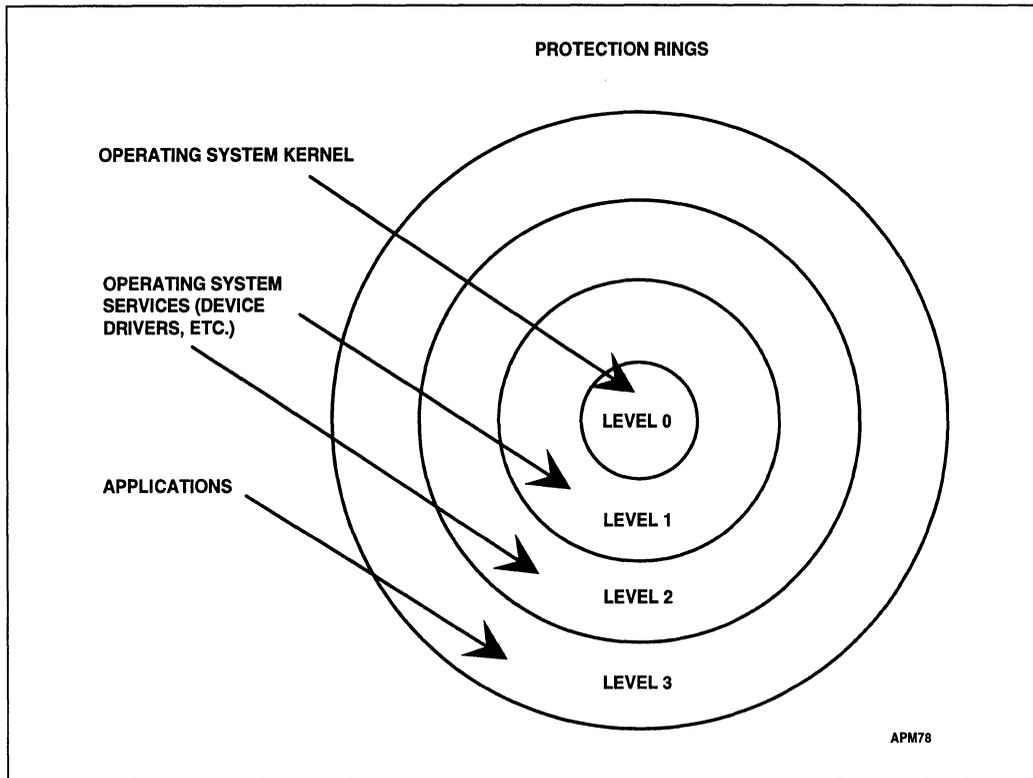


Figure 12-2. Protection Rings

### 12.3. RESTRICTING ACCESS TO DATA

To address operands in memory, a segment selector for a data segment must be loaded into a data-segment register (the DS, ES, FS, GS, or SS registers). The processor checks the segment's privilege levels. The check is performed when the segment selector is loaded. As Figure 12-3 shows, three different privilege levels enter into this type of privilege check.

The three privilege levels which are checked are:

1. The CPL (current privilege level) of the program. This is held in the two least-significant bit positions of the CS register.
2. The DPL (descriptor privilege level) of the segment descriptor of the segment containing the operand.
3. The RPL (requestor's privilege level) of the selector used to specify the segment containing the operand. This is held in the two lowest bit positions of the segment

register used to access the operand (the SS, DS, ES, FS, or GS registers). If the operand is in the stack segment, the RPL is the same as the CPL.

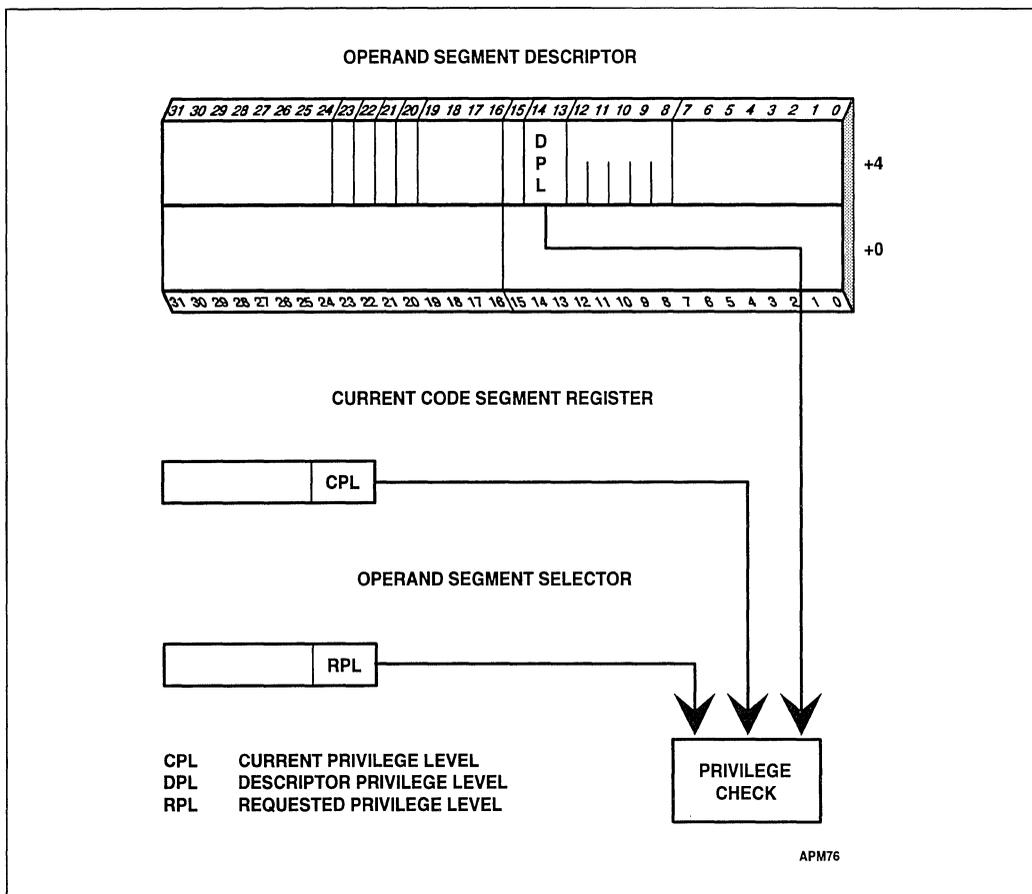


Figure 12-3. Privilege Check for Data Access

Instructions may load a segment register only if the DPL of the segment is the same or a less privileged level (greater privilege number) than the less privileged of the CPL and the selector's RPL.

The addressable domain of a task varies as its CPL changes. When the CPL is 0, data segments at all privilege levels are accessible; when the CPL is 1, only data segments at privilege levels 1 through 3 are accessible; when the CPL is 3, only data segments at privilege level 3 are accessible.

Systems that use only two of the four possible privilege levels should use levels 0 and 3.

### 12.3.1. Accessing Data in Code Segments

It may be desirable to store data in a code segment, for example, when both code and data are provided in ROM. Code segments may legitimately hold constants; it is not possible to write to a segment defined as a code segment, unless a data segment is mapped to the same address space. The following methods of accessing data in code segments are possible:

1. Load a data-segment register with a segment selector for a nonconforming, readable, executable segment.
2. Load a data-segment register with a segment selector for a conforming, readable, executable segment.
3. Use a code-segment override prefix to read a readable, executable segment whose selector already is loaded in the CS register.

The same rules for access to data segments apply to case 1. Case 2 is always valid because the privilege level of a code segment with a set Conforming bit is effectively the same as the CPL, regardless of its DPL. Case 3 is always valid because the DPL of the code segment selected by the CS register is the CPL.

## 12.4. RESTRICTING CONTROL TRANSFERS

Control transfers are provided by the JMP, CALL, RET, INT, and IRET instructions, as well as by the exception and interrupt mechanisms. Exceptions and interrupts are special cases discussed in Chapter 14. This chapter discusses only the JMP, CALL, and RET instructions.

The near forms of the JMP, CALL, and RET instructions transfer program control within the current code segment, and therefore are subject only to limit checking. The processor checks that the destination of the JMP, CALL, or RET instruction does not exceed the limit of the current code segment. This limit is cached in the CS register, so protection checks for near transfers do not degrade performance.

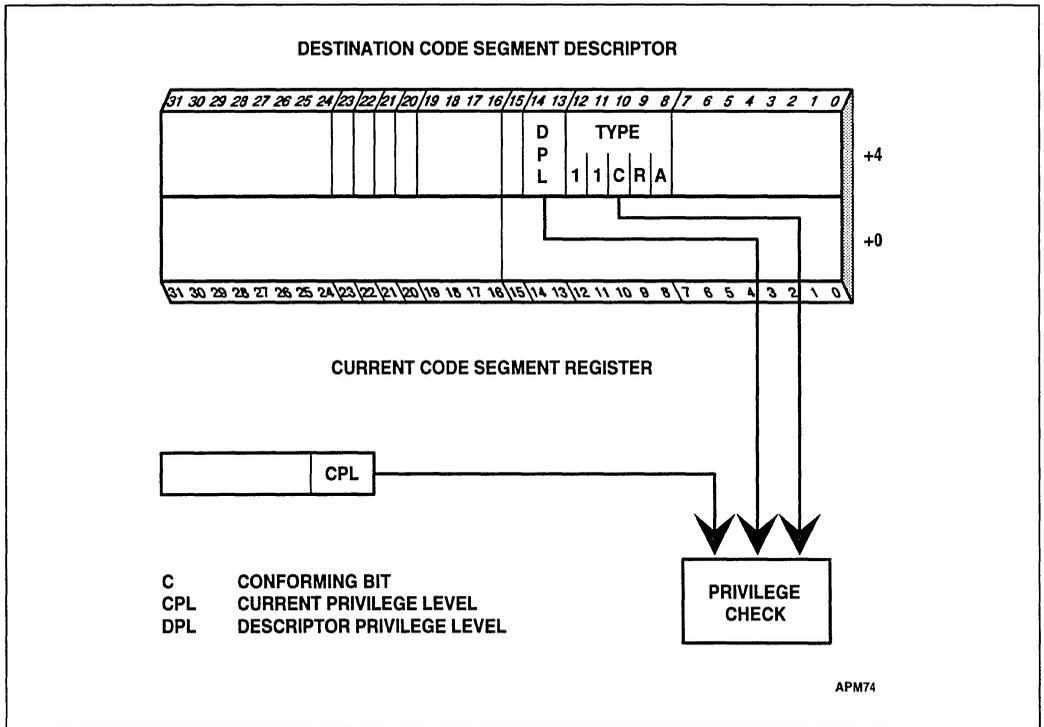
The operands of the far forms of the JMP and CALL instruction refer to other segments, so the processor performs privilege checking. There are two ways a JMP or CALL instruction can refer to another segment:

1. The operand selects the descriptor of another executable segment.
2. The operand selects a call gate descriptor.

As Figure 12-4 shows, two different privilege levels enter into a privilege check for a control transfer which does not use a call gate:

1. The CPL (current privilege level).
2. The DPL of the descriptor of the destination code segment.





**Figure 12-4. Privilege Check for Control Transfer Without Gate**

Normally the CPL is equal to the DPL of the segment which the processor is currently executing. The CPL may, however, be greater (less privileged) than the DPL if the current code segment is a conforming segment (as indicated by the Type field of its segment descriptor). A conforming segment runs at the privilege level of the calling procedure. The processor keeps a record of the CPL cached in the CS register; this value can be different from the DPL in the segment descriptor of the current code segment.

The processor only permits a JMP or CALL instruction directly into another segment if either of the following privilege rules is satisfied:

- The DPL of the segment is equal to the CPL.
- The segment is a conforming code segment, and its DPL is less (more privileged) than the CPL.

Conforming segments are used for programs, such as math libraries and some kinds of exception handlers, which support applications but do not require access to protected system facilities. When control is transferred to a conforming segment, the CPL does not change, even if the selector used to address the segment has a different RPL. This is the only condition in which the CPL may be different from the DPL of the current code segment.

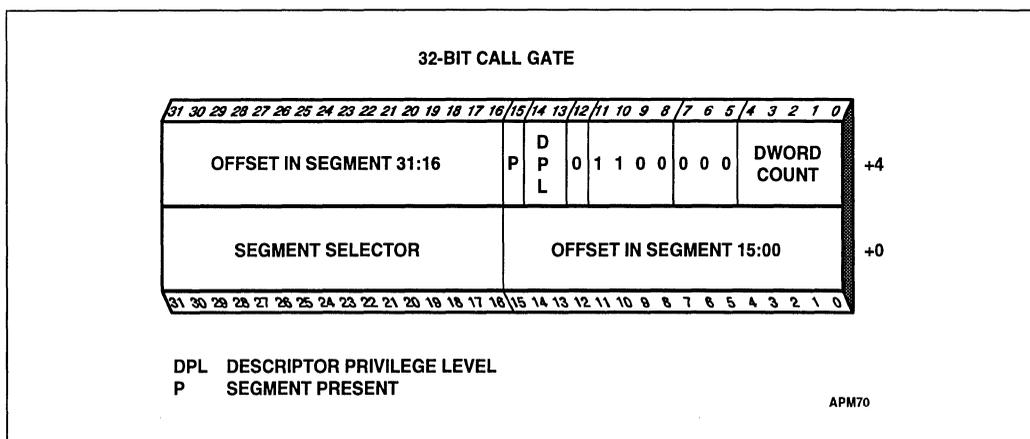
Most code segments are not conforming. For these segments, control can be transferred without a gate only to other code segments at the same level of privilege. It is sometimes necessary, however, to transfer control to higher privilege levels. This is accomplished with the CALL instruction using call-gate descriptors, which is explained in Chapter 13. The JMP instruction may never transfer control to a nonconforming segment whose DPL does not equal the CPL.

## 12.5. GATE DESCRIPTORS

To provide protection for control transfers among executable segments at different privilege levels, the processor uses gate descriptors. There are four kinds of gate descriptors:

- Call gates
- Trap gates
- Interrupt gates
- Task gates

Task gates are used for task switching and are discussed in Chapter 13. Chapter 14 explains how trap gates and interrupt gates are used by exceptions and interrupts. This chapter is concerned only with call gates. Call gates are a form of protected control transfer. They are used for control transfers between different privilege levels. They only need to be used in systems in which more than one privilege level is used. Figure 12-5 illustrates the format of a call gate.



**Figure 12-5. Call Gate**

A call gate has two main functions:

1. To define an entry point of a procedure.
2. To specify the privilege level required to enter a procedure.

CALL and JMP instructions use call gate descriptors in the same manner as code segment descriptors. When the hardware recognizes that the segment selector for the destination refers to a gate descriptor, the operation of the instruction is determined by the contents of the call gate. A call gate descriptor may reside in the GDT or in an LDT, but not in the interrupt descriptor table (IDT).

The selector and offset fields of a gate form a pointer to the entry point of a procedure. A call gate guarantees that all control transfers to other segments go to a valid entry point, rather than to the middle of a procedure (or worse, to the middle of an instruction). The operand of the control transfer instruction is not the segment selector and offset within the segment to the procedure's entry point. Instead, the segment selector points to a gate descriptor, and the offset is not used. Figure 12-6 shows this form of addressing.

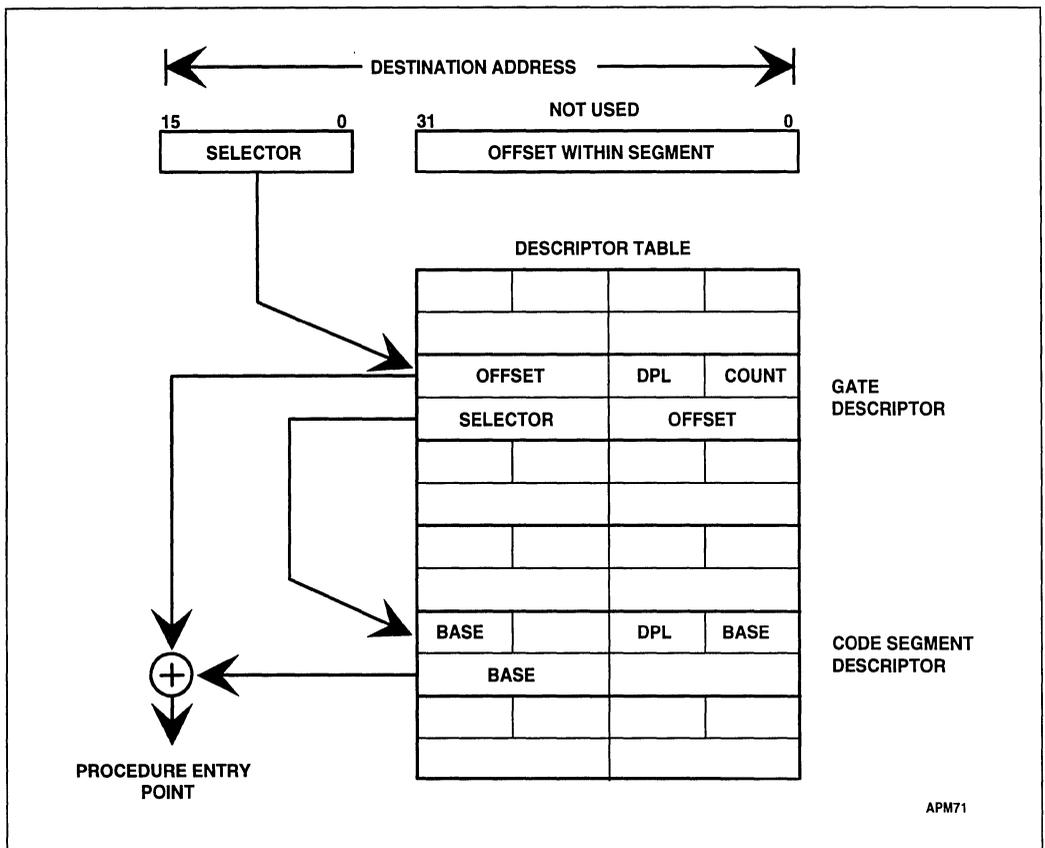


Figure 12-6. Call Gate Mechanism

As shown in Figure 12-7, four different privilege levels are used to check the validity of a control transfer through a call gate.

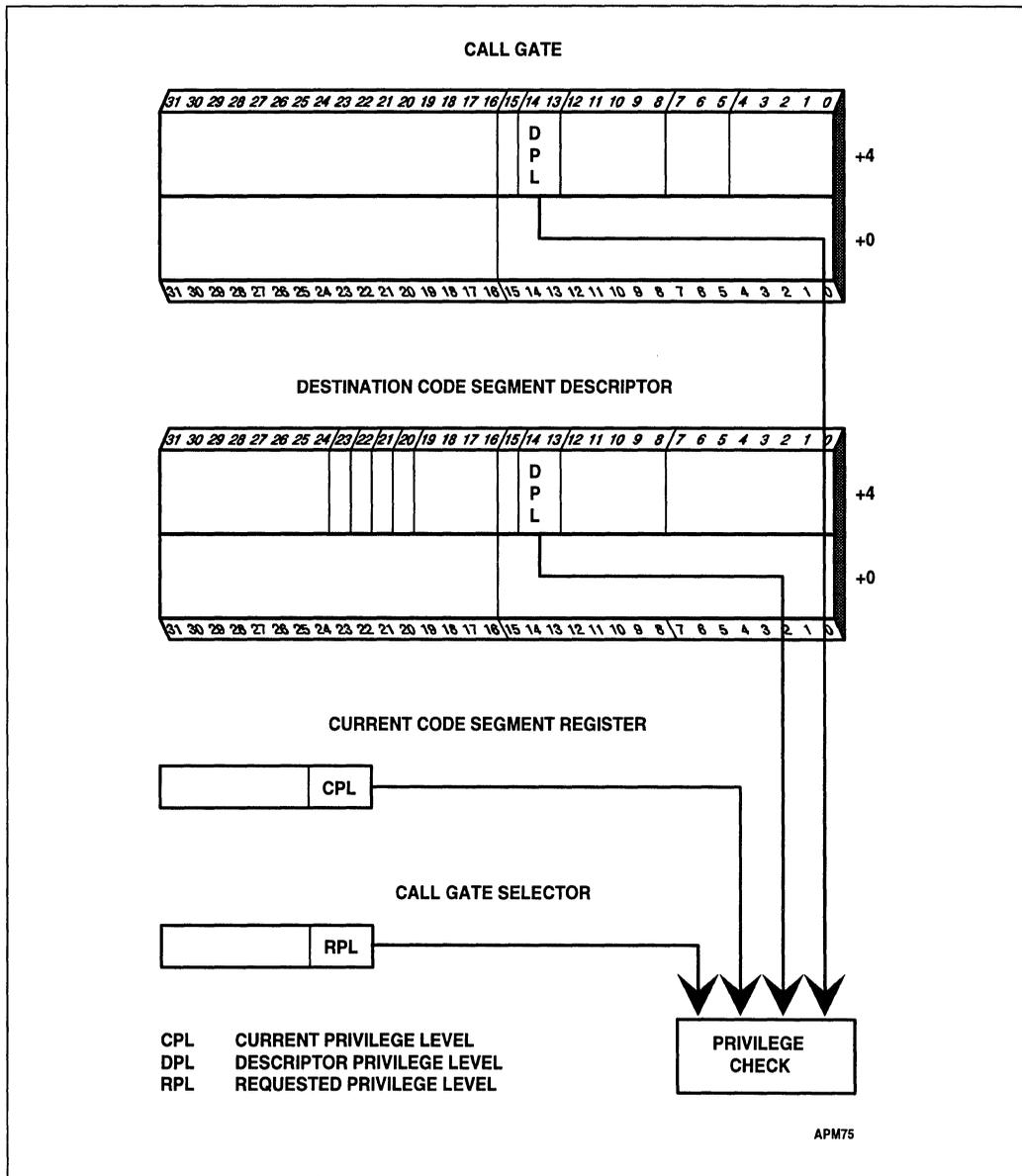


Figure 12-7. Privilege Check for Control Transfer with Call Gate

The privilege levels checked during a transfer of execution through a call gate are:

1. The CPL (current privilege level).
2. The RPL (requestor's privilege level) of the segment selector used to specify the call gate.
3. The DPL (descriptor privilege level) of the gate descriptor.
4. The DPL of the segment descriptor of the destination code segment.

The DPL field of the gate descriptor determines from which privilege levels the gate may be used. One code segment can have several procedures which are intended for use from different privilege levels. For example, an operating system may have some services which are intended to be used by both the operating system and application software, such as routines to handle character I/O, while other services may be intended only for use by operating system, such as routines which initialize device drivers.

Gates can be used for control transfers to more privileged levels or to the same privilege level (though they are not necessary for transfers to the same level). Only CALL instructions can use gates to transfer to more privileged levels. A JMP instruction can use a gate only to transfer control to a code segment with the same privilege level, or to a conforming code segment with the same or a more privileged level.

For a JMP instruction to a nonconforming segment, both of the following privilege rules must be satisfied; otherwise, a general-protection exception is generated.

- $\text{MAX}(\text{CPL}, \text{RPL}) \leq \text{gate DPL}$
- Destination code segment  $\text{DPL} = \text{CPL}$

For a CALL instruction (or for a JMP instruction to a conforming segment), both of the following privilege rules must be satisfied; otherwise, a general-protection exception is generated.

- $\text{MAX}(\text{CPL}, \text{RPL}) \leq \text{gate DPL}$
- Destination code segment  $\text{DPL} \leq \text{CPL}$

### 12.5.1. Stack Switching

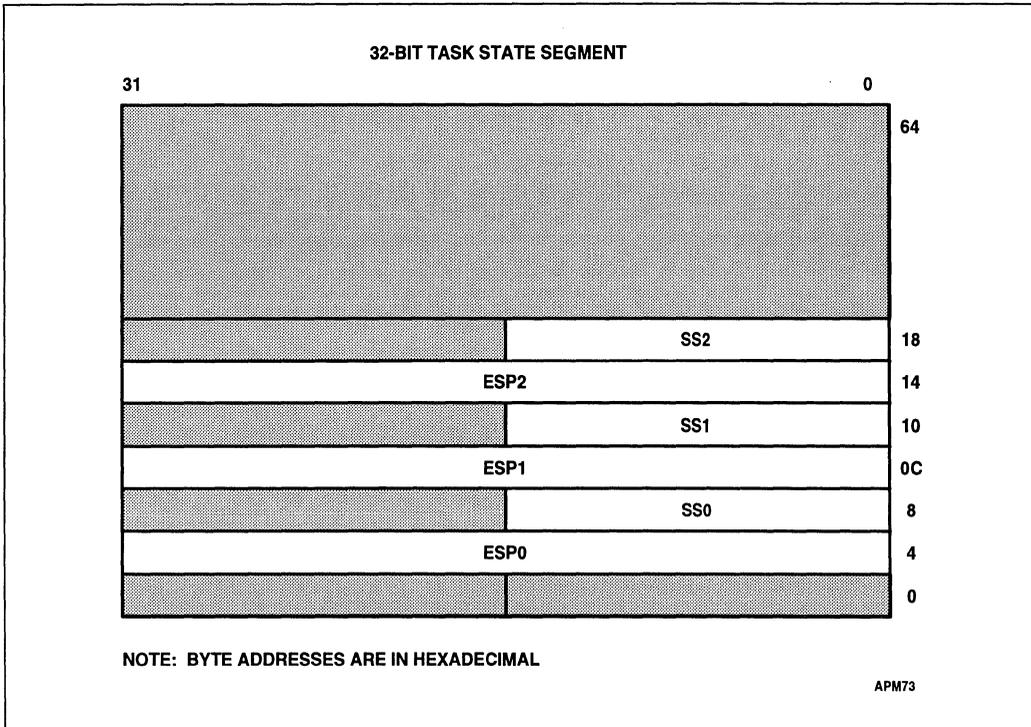
A procedure call to a more privileged level does the following:

1. Changes the CPL.
2. Transfers control (execution).
3. Switches stacks.

All inner protection rings (privilege levels 0, 1, and 2), have their own stacks for receiving calls from less privileged levels. If the caller were to provide the stack, and the stack was too small, the called procedure might crash as a result of insufficient stack space. Instead, the processor prevents less privileged programs from crashing more privileged programs by

creating a new stack when a call is made to a more privileged level. The new stack is created, parameters are copied from the old stack, the contents of registers are saved, and execution proceeds normally. When the procedure returns, the contents of the saved registers restore the original stack.

The processor finds the space to create new stacks using the task state segment (TSS), as shown in Figure 12-8. (Chapter 13 discusses the TSS in more detail.) Each task has its own TSS. The TSS contains initial stack pointers for the inner protection rings. The operating system is responsible for creating each TSS and initializing its stack pointers. (If the operating system does not use TSSs for multitasking, it still must allocate at least one TSS for this stack-related purpose.) An initial stack pointer consists of a segment selector and an initial value for the ESP register (an initial offset into the segment). The initial stack pointers are strictly read-only values. The processor does not change them while the task runs. These stack pointers are used only to create new stacks when calls are made to more privileged levels. These stacks disappear when the called procedure returns. The next time the procedure is called, a new stack is created using the initial stack pointer.



**Figure 12-8. Initial Stack Pointers in a TSS**

When a call gate is used to change privilege levels, a new stack is created by loading an address from the TSS. The processor uses the DPL of the destination code segment (the new CPL) to select the initial stack pointer for privilege level 0, 1, or 2.

The DPL of the new stack segment must equal the new CPL; if not, a TSS fault is generated. It is the responsibility of the operating system to create stacks and stack-segment descriptors for all privilege levels which are used. The stacks must be read/write as specified in the Type fields of their segment descriptors. They must contain enough space, as specified in the Limit fields, to hold the contents of the SS and ESP registers, the return address, and the parameters and temporary variables required by the called procedure.

As with calls within a privilege level, parameters for the procedure are placed on the stack. The parameters are copied to the new stack. The parameters can be accessed within the called procedure using the same relative addresses which would have been used if no stack switching had occurred. The count field of a call gate tells the processor how many doublewords (up to 31) to copy from the caller's stack to the stack of the called procedure. If the count is 0, no parameters are copied.

If more than 31 doublewords of data need to be passed to the called procedure, one of the parameters can be a pointer to a data structure, or the saved contents of the SS and ESP registers may be used to access parameters in the old stack space.

The processor performs the following stack-related steps in executing a procedure call between privilege levels.

1. The stack of the called procedure is checked to make certain it is large enough to hold the parameters and the saved contents of registers; if not, a stack exception is generated.
2. The old contents of the SS and ESP registers are pushed onto the stack of the called procedure as two doublewords (the 16-bit SS register is zero-extended to 32 bits; the zero-extended upper word is Intel reserved; do not use).
3. The parameters are copied from the stack of the caller to the stack of the called procedure.
4. A pointer to the instruction after the CALL instruction (the old contents of the CS and EIP registers) is pushed onto the new stack. The contents of the SS and ESP registers after the call point to this return pointer on the stack.

Figure 12-9 illustrates the stack frame before, during, and after a successful interlevel procedure call and return.

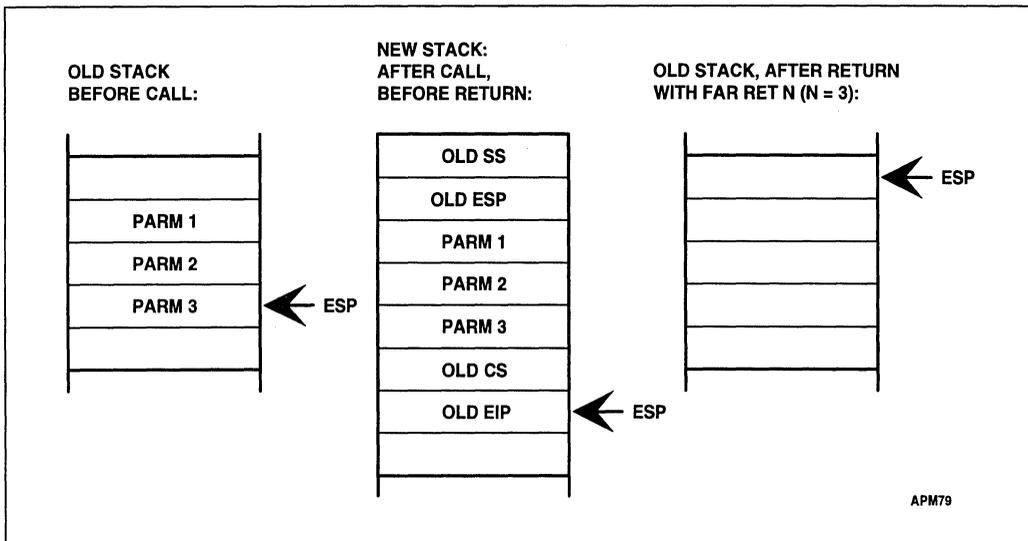


Figure 12-9. Stack Frame during Interlevel Call

The TSS does not have a stack pointer for a privilege level 3 stack, because a procedure at privilege level 3 cannot be called by a less privileged procedure. The stack for privilege level 3 is preserved by the contents of the SS and EIP registers which have been saved on the stack of the privilege level called from level 3.

A call using a call gate does not check the values of the words copied onto the new stack. The called procedure should check each parameter for validity. A later section discusses how the ARPL, VERR, VERW, LSL, and LAR instructions can be used to check pointer values.

### 12.5.2. Returning from a Procedure

The near forms of the RET instruction only transfer control within the current code segment, therefore are subject only to limit checking. The offset to the instruction following the CALL instruction is popped from the stack into the EIP register. The processor checks that this offset does not exceed the limit of the current code segment.

The far form of the RET instruction pops the return address which was pushed onto the stack by an earlier far CALL instruction. Under normal conditions, the return pointer is valid, because it was generated by a CALL or INT instruction. Nevertheless, the processor performs privilege checking because of the possibility that the current procedure altered the pointer or failed to maintain the stack properly. The RPL of the code-segment selector popped off the stack by the return instruction should have the privilege level of the calling procedure.

A return to another segment can change privilege levels, but only toward less privileged levels. When a RET instruction encounters a saved CS value whose RPL is numerically

greater (less privileged) than the CPL, a return across privilege levels occurs. A return of this kind performs these steps:

1. The checks shown in Table 12-2 are made, and the CS, EIP, SS, and ESP registers are loaded with their former values, which were saved on the stack.
2. The old contents of the SS and ESP registers (from the top of the current stack) are adjusted by the number of bytes indicated in the RET instruction. The resulting ESP value is not checked against the limit of the stack segment. If the ESP value is beyond the limit, that fact is not recognized until the next stack operation. (The contents of the SS and ESP registers for the returning procedure are not preserved; normally, their values are the same as those contained in the TSS.)
3. The contents of the DS, ES, FS, and GS segment registers are checked. If any of these registers refer to segments whose DPL is less than the new CPL (excluding conforming code segments), the segment register is loaded with the null selector (Index = 0, TI = 0). The RET instruction itself does not signal exceptions in these cases; however, any subsequent memory reference using a segment register containing the null selector will cause a general-protection exception. This prevents less privileged code from accessing more privileged segments using selectors left in the segment registers by a more privileged procedure.

**Table 12-2. Interlevel Return Checks**

Type of Check	Exception Type	Error Code
Top-of-stack + 7 must be within stack segment limit	Stack	0
RPL of return code segment must be greater than the CPL	Protection	Return CS
Return code segment selector must be non-null	Protection	Return CS
Return code segment descriptor must be within descriptor table limit	Protection	Return CS
Return segment descriptor must be a code segment	Protection	Return CS
Return code segment is present	Segment not present	Return CS
DPL of return non-conforming code segment must equal RPL of return code segment selector, or DPL of return conforming code segment must be less than or equal to RPL of return code segment selector	Protection	Return CS
ESP + N + 15* must be within the stack segment limit	Stack fault	0
Segment selector at ESP + N + 12* must be non-null	Protection	Return SS
Segment descriptor at ESP + N + 12* must be within descriptor table limit	Protection	Return SS
Stack segment descriptor must be read/write	Protection	Return SS
Stack segment must be present	Stack fault	Return SS
Old stack segment DPL must be equal to RPL of old code segment	Protection	Return SS
Old stack segment selector must have an RPL equal to the DPL of the old stack segment	Protection	Return SS

\* N is the value of the immediate operand supplied with the RET instruction.

## 12.6. INSTRUCTIONS RESERVED FOR THE OPERATING SYSTEM

Instructions which can affect the protection mechanism or influence general system performance can only be executed by trusted procedures. The processor has two classes of such instructions:

1. Privileged instructions—those used for system control.
2. Sensitive instructions—those used for I/O and I/O-related activities.

### 12.6.1. Privileged Instructions

The instructions which affect protected facilities can be executed only when the CPL is 0 (most privileged). If one of these instructions is executed when the CPL is not 0, a general-protection exception is generated. These instructions include:



CLTS	—Clear Task-Switched Flag
HLT	—Halt Processor
INVD	—Invalidate Cache
INVLPG	—Invalidate TLB Entry
LGDT	—Load GDT Register
LIDT	—Load IDT Register
LLDT	—Load LDT Register
LMSW	—Load Machine Status Word
LTR	—Load Task Register
MOV to/from CRn	—Move to Control Register n
MOV to/from DRn	—Move to Debug Register n
WBINVD	—Writeback and Invalidate Cache

### 12.6.2. Sensitive Instructions

Instructions which deal with I/O need to be protected, but they also need to be used by procedures executing at privilege levels other than 0 (the most privileged level). The mechanisms for protection of I/O operations are covered in detail in Chapter 15.

## 12.7. INSTRUCTIONS FOR POINTER VALIDATION

Pointer validation is necessary for maintaining isolation between privilege levels. It consists of the following steps:

1. Check whether the supplier of the pointer is allowed to access the segment.
2. Check whether the segment type is compatible with its use.
3. Check whether the pointer offset exceeds the segment limit.

Although the processor automatically performs checks 2 and 3 during instruction execution, software must assist in performing the first check. The ARPL instruction is provided for this purpose. Software also can use steps 2 and 3 to check for potential violations, rather than waiting for an exception to be generated. The LAR, LSL, VERR, and VERW instructions are provided for this purpose.

**LAR (Load Access Rights)** is used to verify that a pointer refers to a segment of a compatible privilege level and type. The LAR instruction has one operand: a segment selector for the descriptor whose access rights are to be checked. Conforming code segments may be accessed from any privilege level. Any other segment descriptor must be readable at a privilege level which is numerically greater (less privileged) than the CPL and the selector's RPL. If the descriptor is readable, the LAR instruction gets the second doubleword of the descriptor, masks this value with 00FxFF00H, stores the result into the specified 32-bit destination register, and sets the ZF flag. (The x indicates that the corresponding four bits of

the stored value are undefined.) Once loaded, the access rights can be tested. All valid descriptor types can be tested by the LAR instruction. If the RPL or CPL is greater than the DPL, or if the segment selector would exceed the limit for the descriptor table, zero is returned, and the ZF flag is cleared.

**LSL (Load Segment Limit)** allows software to test the limit of a segment descriptor. If the descriptor referenced by the segment selector (in memory or a register) is readable at the CPL, the LSL instruction loads the specified 32-bit register with a 32-bit, byte granular limit calculated from the concatenated limit fields and the G bit of the descriptor. This only can be done for descriptors which describe segments (data, code, task state, and local descriptor tables); gate descriptors are inaccessible. (Table 12-3 lists in detail which types are valid and which are not.) Interpreting the limit is a function of the segment type. For example, downward-expandable data segments (stack segments) treat the limit differently than other kinds of segments. For both the LAR and LSL instructions, the ZF flag is set if the load was successful; otherwise, the ZF flag is cleared.

**Table 12-3. Valid Descriptor Types for LSL Instruction**

Type Code	Descriptor Type	Valid?
0	Reserved	No
1	Reserved	No
2	LDT	Yes
3	Reserved	No
4	Reserved	No
5	Task Gate	No
6	Reserved	No
7	Reserved	No
8	Reserved	No
9	Available 32-bit TSS	Yes
A	Reserved	No
B	Busy 32-bit TSS	Yes
C	32-bit Call Gate	No
D	Reserved	No
E	32-bit Interrupt Gate	No
F	32-bit Trap Gate	No

An additional check, the alignment check, can be applied at CPL = 3. When both the AM bit in CR0 and the AC flag are set, unaligned memory references generate exceptions. This is useful for programs which use the low two bits of pointers to identify the type of data structure they address. For example, a subroutine in a math library may accept pointers to numeric data structures. If the type of this structure is assigned a code of 10 (binary) in the



lowest two bits of pointers to this type, math subroutines can correct for the type code by adding a displacement of  $-10$  (binary). If the subroutine should ever receive the wrong pointer type, an unaligned reference would be produced, which would generate an exception. Alignment checking accelerates the processing of programs written in symbolic-processing (i.e., Artificial Intelligence) languages such as Lisp, Prolog, Smalltalk, and C++. It can be used to speed up pointer tag type checking.

### 12.7.1. Descriptor Validation

The processor has two instructions, **VERR** and **VERW**, which determine whether a segment selector points to a segment which can be read or written using the CPL. Neither instruction causes a protection fault if the segment cannot be accessed.

**VERR (Verify for Reading)** verifies a segment for reading and sets the ZF flag if that segment is readable using the CPL. The **VERR** instruction checks the following:

- The segment selector points to a segment descriptor within the bounds of the GDT or an LDT.
- The segment selector indexes to a code or data segment descriptor.
- The segment is readable and has a compatible privilege level.

The privilege check for data segments and nonconforming code segments verifies that the DPL must be a less privileged level than either the CPL or the selector's RPL. Conforming segments are not checked for privilege level.

**VERW (Verify for Writing)** provides the same capability as the **VERR** instruction for verifying writability. Like the **VERR** instruction, the **VERW** instruction sets the ZF flag if the segment can be written. The instruction verifies the descriptor is within bounds, is a segment descriptor, is writable, and has a DPL which is a less privileged level than either the CPL or the selector's RPL. Code segments are never writable, whether conforming or not.

### 12.7.2. Pointer Integrity and RPL

The requestor's privilege level (RPL) can prevent accidental use of pointers which crash more privileged code from a less privileged level.

A common example is a file system procedure, **FREAD** (*file\_id*, *n\_bytes*, *buffer\_ptr*). This hypothetical procedure reads data from a disk file into a buffer, overwriting whatever is already there. It services requests from programs operating at the application level, but it must run in a privileged mode in order to read from the system I/O buffer. If the application program passed this procedure a bad buffer pointer, one which pointed at critical code or data in a privileged address space, the procedure could cause damage which would crash the system.

Use of the RPL can avoid this problem. The RPL allows a privilege override to be assigned to a selector. This privilege override is intended to be the privilege level of the code segment which generated the segment selector. In the above example, the RPL would be the CPL of

the application program which called the system level procedure. The processor automatically checks any segment selector loaded into a segment register to determine whether its RPL allows access.

To take advantage of the processor's checking of the RPL, the called procedure need only check that all segment selectors passed to it have an RPL for the same or a less privileged level as the original caller's CPL. This guarantees that the segment selectors are not more privileged than their source. If a selector is used to access a segment which the source would not be able to access directly, i.e. the RPL is less privileged than the segment's DPL, a general-protection exception is generated when the selector is loaded into a segment register.

**ARPL (Adjust Requested Privilege Level)** adjusts the RPL field of a segment selector to be the larger (less privileged) of its original value and the value of the RPL field for a segment selector stored in a general register. The RPL fields are the two least significant bits of the segment selector and the register. The latter normally is a copy of the caller's CS register on the stack. If the adjustment changes the selector's RPL, the ZF flag is set; otherwise, the ZF flag is cleared.

## 12.8. PAGE-LEVEL PROTECTION

Protection applies to both segments and pages. When the flat model for memory segmentation is used, page-level protection prevents programs from interfering with each other.

Each memory reference is checked to verify that it satisfies the protection checks. All checks are made before the memory cycle is started; any violation prevents the cycle from starting and results in an exception. Because checks are performed in parallel with address translation, there is no performance penalty. There are two page-level protection checks:

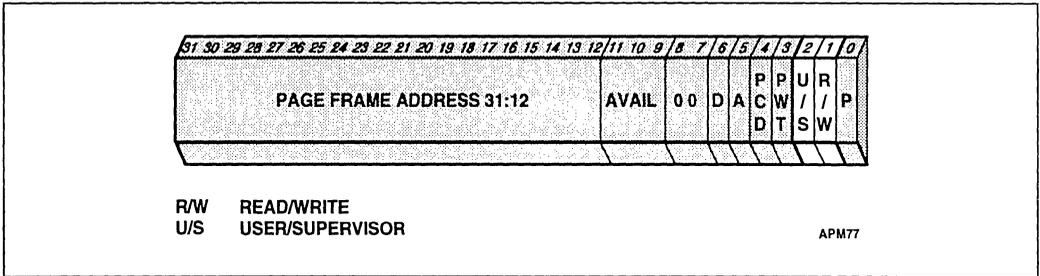
1. Restriction of addressable domain.
2. Type checking.

A protection violation results in an exception. See Chapter 14 for an explanation of the protected-mode exception mechanism. This chapter describes the protection violations which lead to exceptions.

### 12.8.1. Page-Table Entries Hold Protection Parameters

Figure 12-10 highlights the fields of a page table entry which control access to pages. The protection checks are applied for both first- and second-level page tables.





**Figure 12-10. Protection Fields of a Page Table Entry**

### 12.8.1.1. RESTRICTING ADDRESSABLE DOMAIN

Privilege is interpreted differently for pages than for segments. With segments, there are four privilege levels, ranging from 0 (most privileged) to 3 (least privileged). With pages, there are two levels of privilege:

1. Supervisor level (U/S=0)—for the operating system, other system software (such as device drivers), and protected system data (such as page tables).
2. User level (U/S=1)—for application code and data.

The privilege levels used for segmentation are mapped into the privilege levels used for paging. If the CPL is 0, 1, or 2, the processor is running at supervisor level. If the CPL is 3, the processor is running at user level. When the processor is running at supervisor level, all pages are accessible. When the processor is running at user level, only pages from the user level are accessible.

### 12.8.1.2. TYPE CHECKING

Only two types of pages are recognized by the protection mechanism:

1. Read-only access (R/W=0).
2. Read/write access (R/W=1).

When the processor is running at supervisor level with the WP bit in the CR0 register clear (its state following reset initialization), all pages are both readable and writable (write-protection is ignored). When the processor is running at user level, only pages which belong to user level and are marked for read/write access are writable. User-level pages which are read/write or read-only are readable. Pages from the supervisor level are neither readable nor writable from user level. A general-protection exception is generated on any attempt to violate the protection rules.

Setting the WP bit in the CR0 register enables supervisor-mode sensitivity to write-protected pages.

The supervisor write-protect feature is also useful for implementing the copy-on-write strategy used by some operating systems, such as UNIX, for task creation (also called forking or spawning). When a new task is created, it is possible to copy the entire address space of the parent task. This gives the child task a complete, duplicate set of the parent's segments and pages. An alternative strategy, copy-on-write, saves memory space and time by mapping the child's segments and pages to the same segments and pages used by the parent task. A private copy of a page gets created only when one of the tasks writes to the page. By using the WP bit, the supervisor can detect an attempt to write to a user- or supervisor-level page, and can copy the page at that time.

### 12.8.2. Combining Protection of Both Levels of Page Tables

For any one page, the protection attributes of its page directory entry (first-level page table) may differ from those of its second-level page table entry. The processor checks the protection for a page by examining the protection specified in both the page directory (first-level page table) and the second-level page table. Table 12-4 shows the protection provided by the possible combinations of protection attributes when the WP bit is clear.

### 12.8.3. Overrides to Page Protection

Certain accesses are checked as if they are privilege-level 0 accesses, for any value of CPL:

- Access to segment descriptors (LDT, GDT, TSS and IDT).
- Access to inner stack during a CALL instruction, or exceptions and interrupts, when a change of privilege level occurs.



**Table 12-4. Combined Page Directory and Page Table Protection**

Page Directory Entry		Page Table Entry		Combined Effect	
Privilege	Access Type	Privilege	Access Type	Privilege	Access Type
User	Read-Only	User	Read-Only	User	Read-Only
User	Read-Only	User	Read-Write	User	Read-Only
User	Read-Write	User	Read-Only	User	Read-Only
User	Read-Write	User	Read-Write	User	Read/Write
User	Read-Only	Supervisor	Read-Only	Supervisor	Read/Write*
User	Read-Only	Supervisor	Read-Write	Supervisor	Read/Write*
User	Read-Write	Supervisor	Read-Only	Supervisor	Read/Write*
User	Read-Write	Supervisor	Read-Write	Supervisor	Read/Write
Supervisor	Read-Only	User	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Only	User	Read-Write	Supervisor	Read/Write*
Supervisor	Read-Write	User	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Write	User	Read-Write	Supervisor	Read/Write
Supervisor	Read-Only	Supervisor	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Only	Supervisor	Read-Write	Supervisor	Read/Write*
Supervisor	Read-Write	Supervisor	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Write	Supervisor	Read-Write	Supervisor	Read/Write

\*If the WP bit of CR0 is set, the access type is determined by the R/W bits of the page directory and page table entries

## 12.9. COMBINING PAGE AND SEGMENT PROTECTION

When paging is enabled, the processor first evaluates segment protection, then evaluates page protection. If the processor detects a protection violation at either the segment level or the page level, the operation does not go through; an exception occurs instead. If an exception is generated by segmentation, no paging exception is generated for the operation.

For example, it is possible to define a large data segment which has some parts which are read-only and other parts which are read-write. In this case, the page directory (or page table) entries for the read-only parts would have the U/S and R/W bits specifying no write access for all the pages described by that directory entry (or for individual pages specified in the second-level page tables). This technique might be used, for example, to define a large data segment, part of which is read-only (for shared data or ROMmed constants). This defines a flat data space as one large segment, with flat pointers used to access this flat space, while protecting shared data, shared files mapped into the virtual space, and supervisor areas.





13

# Protected-Mode Multitasking





## CHAPTER 13

# PROTECTED-MODE MULTITASKING

The Pentium processor provides hardware support for multitasking. A task is a program which is running, or waiting to run while another program is running. A task is invoked by an interrupt, exception, jump, or call. When one of these forms of transferring execution is used with a destination specified by an entry in one of the descriptor tables, this descriptor can be a type which causes a new task to begin execution after saving the state of the current task. There are two types of task-related descriptors which can occur in a descriptor table: task state segment descriptors and task gates. When execution is passed to either kind of descriptor, a task switch occurs.

A task switch is like a procedure call, but it saves more processor state information. A task switch transfers execution to a completely new environment, the environment of a task. This requires saving the contents of nearly all the processor registers, including the EFLAGS register and the segment registers. Unlike procedures, tasks are not re-entrant. A task switch does not push anything on the stack. The processor state information is saved in a data structure in memory, called a task state segment.

The registers and data structures which support multitasking are:

- Task state segment.
- Task state segment descriptor.
- Task register.
- Task gate descriptor.

With these structures, the processor can switch execution from one task to another, saving the context of the original task to allow the task to be restarted. The processor also offers two other task-management features:

1. Interrupts and exceptions can cause task switches (if needed in the system design). The processor can not only perform a task switch to handle the interrupt or exception, but it can automatically switch back when the interrupt or exception returns. This mechanism can handle interrupts that occur during interrupt tasks.
2. With each switch to another task, the processor also can switch to another LDT. This can be used to give each task a different logical-to-physical address mapping. This is an additional protection feature, because tasks can be isolated and prevented from interfering with one another. The PDBR register also is reloaded. This allows the paging mechanism to be used to enforce the isolation between tasks.

Use of the multitasking mechanism is optional. In some applications, it may not be the best way to manage program execution. Where extremely fast response to interrupts is needed, the time required to save the processor state may be too great. A possible compromise in these situations is to use the task-related data structures, but perform task switching in software. This allows a smaller processor state to be saved. This technique can be one of the optimizations used to enhance system performance after the basic functions of a system have been implemented.

### 13.1. TASK STATE SEGMENT

The processor state information needed to restore a task is saved in a type of segment, called a task state segment or TSS. Figure 13-1 shows the format of a TSS for tasks designed for 32-bit CPUs (compatibility with 16-bit 80286 tasks is provided by a different kind of TSS; see Chapter 23). The fields of a TSS are divided into two main categories:

1. Dynamic fields the processor updates with each task switch. These fields store:
  - The general registers (EAX, ECX, EDX, EBX, ESP, EBP, ESI, and EDI).
  - The segment registers (ES, CS, SS, DS, FS, and GS).
  - The flags register (EFLAGS).
  - The instruction pointer (EIP).
  - The selector for the TSS of the previous task (updated only when a return is expected).
2. Static fields the processor reads, but does not change. These fields are set up when a task is created. These fields store:
  - The selector for the task's LDT.
  - The CR3 register.
  - The logical address of the stacks for privilege levels 0, 1, and 2.
  - The T-bit (debug trap bit) which, when set, causes the processor to raise a debug exception when a task switch occurs. (See Chapter 17 for more information on debugging.)
  - The base address for the I/O permission bit map and interrupt redirection bitmap. If present, these maps are stored in the TSS at higher addresses. The base address points to the beginning of the I/O map and the end of the 32-byte interrupt map. (See Chapter 15 for more information about the I/O permission bit map and Chapter 22 for more information about interrupt redirection.)



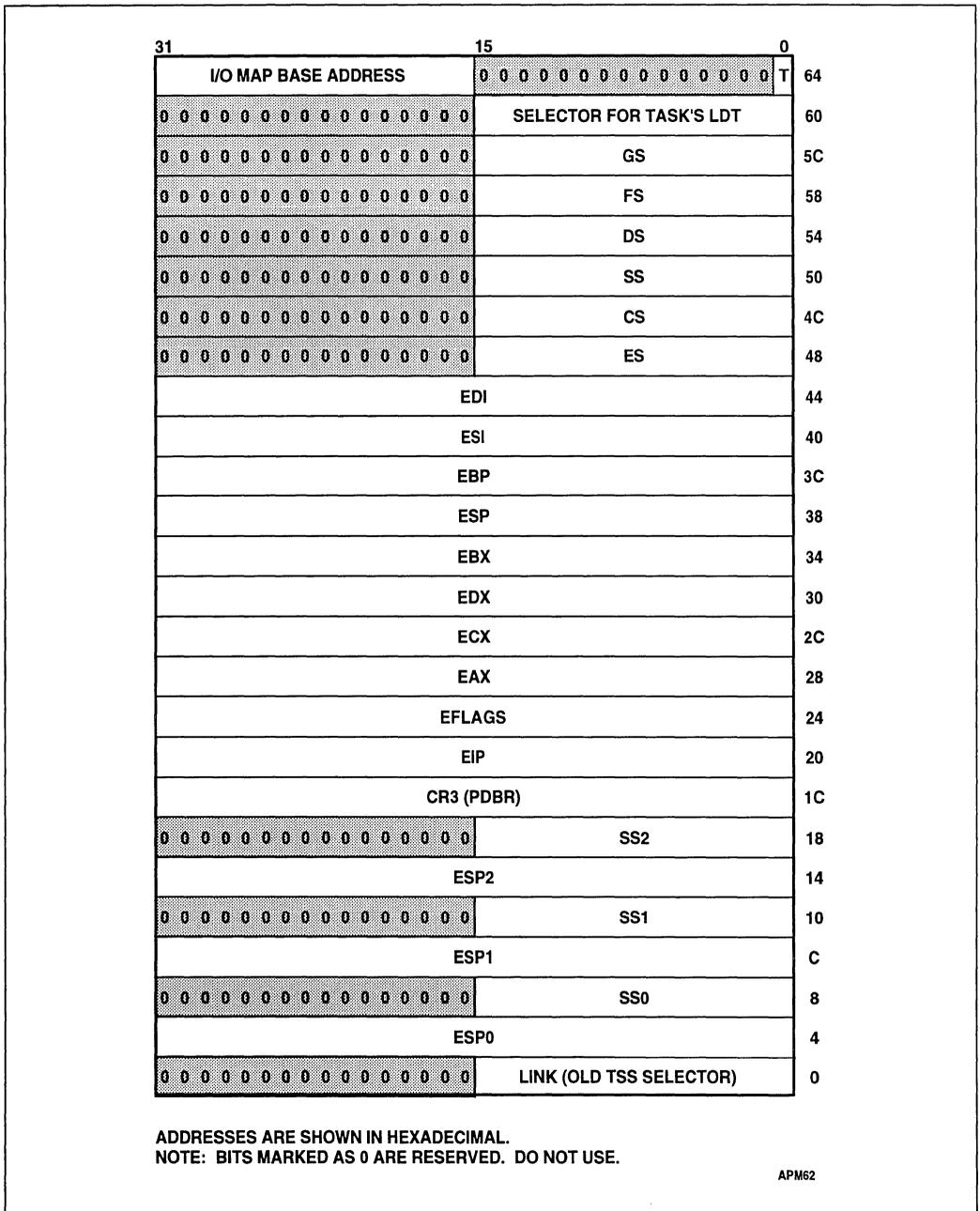
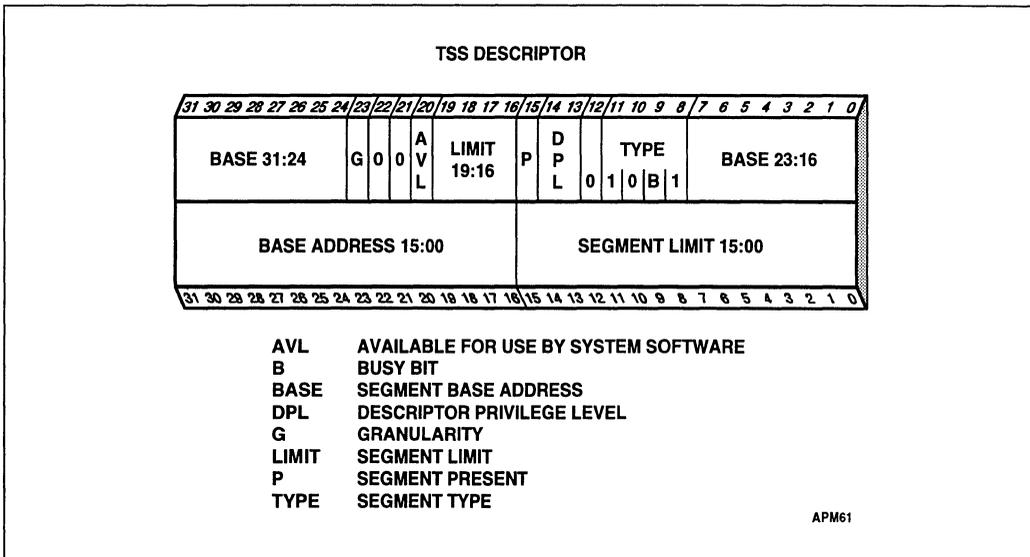


Figure 13-1. 32-Bit Task State Segment

If paging is used, it is important to avoid placing a page boundary within the part of the TSS which is read by the processor during a task switch (the first 104 bytes). If a page boundary is placed within this part of the TSS, the pages on either side of the boundary must be present at the same time. In addition, if paging is used, the pages corresponding to the old task's TSS, the new task's TSS, and the descriptor table entries for each should be marked as present and read/write. It is an unrecoverable error to receive a page fault or general-protection exception after the processor has started to read the TSS.

### 13.2. TSS DESCRIPTOR

The task state segment, like all other segments, is defined by a descriptor. Figure 13-2 shows the format of a TSS descriptor.



**Figure 13-2. TSS Descriptor**

The Busy bit in the Type field indicates whether the task is busy. A busy task is currently running or waiting to run. A Type field with a value of 9 indicates an inactive task; a value of 11 (decimal) indicates a busy task. Tasks are not recursive. The processor uses the Busy bit to detect an attempt to call a task whose execution has been interrupted.

The Base, Limit, and DPL fields and the Granularity bit and Present bit have functions similar to their use in data-segment descriptors. The Limit field must have a value equal to or greater than 67H, one byte less than the minimum size of a task state. An attempt to switch to a task whose TSS descriptor has a limit less than 67H generates an exception. A larger limit is required if an I/O permission map is used. A larger limit also may be required for the operating system, if the system stores additional data in the TSS.

A procedure with access to a TSS descriptor can cause a task switch. In most systems, the DPL fields of TSS descriptors should be less than 3, so only privileged software can perform task switching.

Access to a TSS descriptor does not give a procedure the ability to read or modify the descriptor. Reading and modification only can be done using a data descriptor mapped to the same location in memory. Loading a TSS descriptor into a segment register generates an exception. TSS descriptors only may reside in the GDT. An attempt to access a TSS using a selector with a set TI bit (which indicates the current LDT) generates an exception.

### 13.3. TASK REGISTER

The task register (TR) is used to find the current TSS. Figure 13-3 shows the path by which the processor accesses the TSS.

The task register has both a visible part (i.e., a part which can be read and changed by software) and an invisible part (i.e., a part maintained by the processor and inaccessible to software). The selector in the visible portion indexes to a TSS descriptor in the GDT. The processor uses the invisible portion of the TR register to retain the base and limit values from the TSS descriptor. Keeping these values in a register makes execution of the task more efficient, because the processor does not need to fetch these values from memory to reference the TSS of the current task.

The LTR and STR instructions are used to modify and read the visible portion of the task register. Both instructions take one operand, a 16-bit segment selector located in memory or a general register.

**LTR (Load task register)** loads the visible portion of the task register with the operand, which must index to a TSS descriptor in the GDT. The LTR instruction also loads the invisible portion with information from the TSS descriptor. The LTR instruction is a privileged instruction; it may be executed only when the CPL is 0. The LTR instruction generally is used during system initialization to put an initial value in the task register; afterwards, the contents of the TR register are changed by events which cause a task switch.

**STR (Store task register)** stores the visible portion of the task register in a general register or memory.

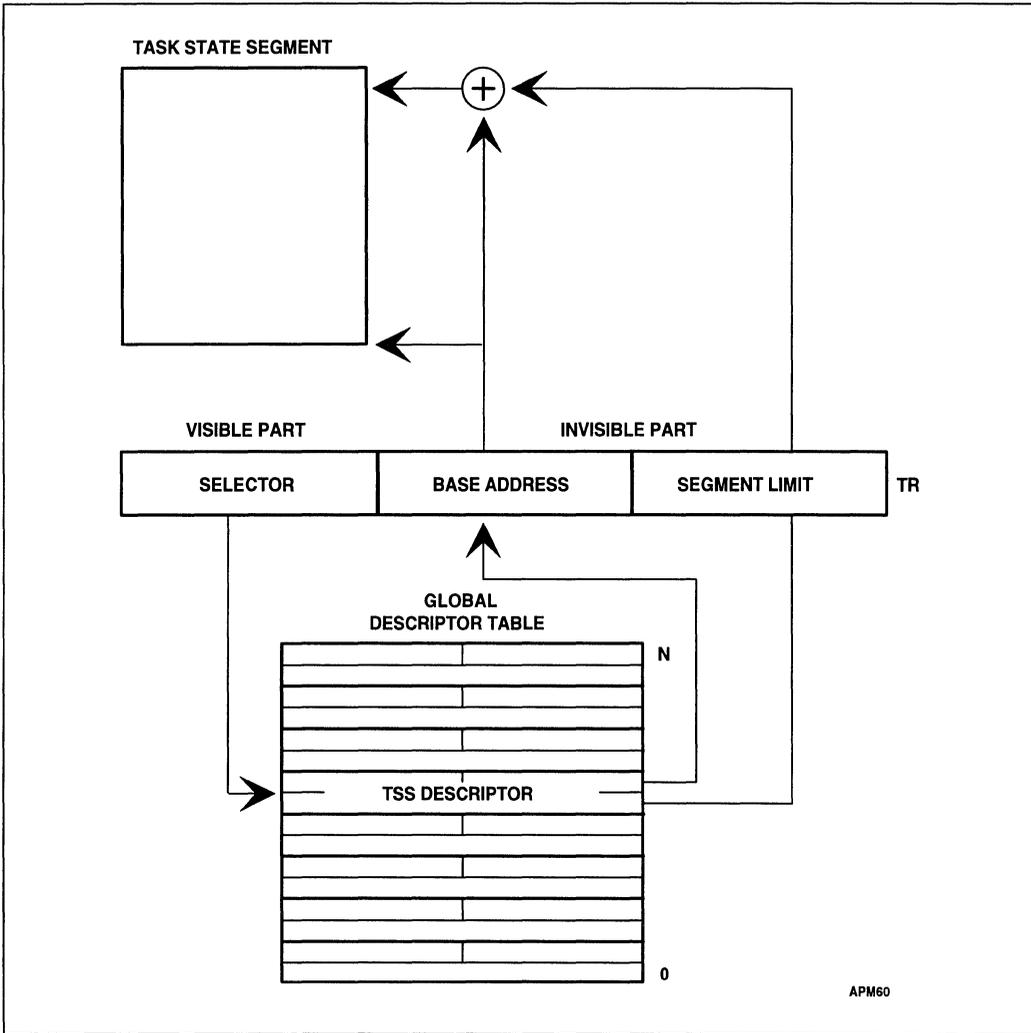
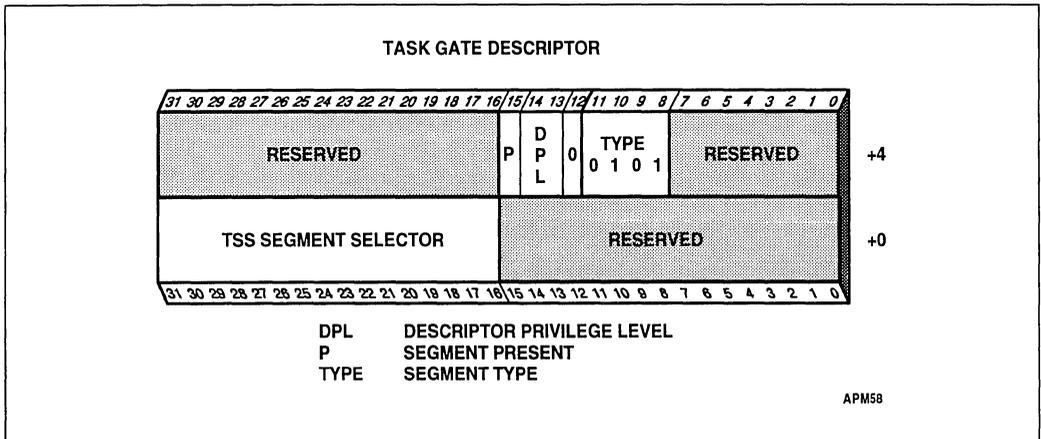


Figure 13-3. Task Register

### 13.4. TASK GATE DESCRIPTOR

A task gate descriptor provides an indirect, protected reference to a task. Figure 13-4 illustrates the format of a task gate.





**Figure 13-4. Task Gate Descriptor**

The Selector field of a task gate indexes to a TSS descriptor. The RPL in this selector is not used.

The DPL of a task gate controls access to the descriptor for a task switch. A procedure may not select a task gate descriptor unless the selector's RPL and the CPL of the procedure are numerically less than or equal to the DPL of the descriptor. This prevents less privileged procedures from causing a task switch. (Note that when a task gate is used, the DPL of the destination TSS descriptor is not used.)

A procedure with access to a task gate can cause a task switch, as can a procedure with access to a TSS descriptor. Both task gates and TSS descriptors are provided to satisfy three needs:

1. The need for a task to have only one Busy bit. Because the Busy bit is stored in the TSS descriptor, each task should have only one such descriptor. There may, however, be several task gates which select a single TSS descriptor.
2. The need to provide selective access to tasks. Task gates fill this need, because they can reside in an LDT and can have a DPL which is different from the TSS descriptor's DPL. A procedure which does not have sufficient privilege to use the TSS descriptor in the GDT (which usually has a DPL of 0) can still call another task if it has access to a task gate in its LDT. With task gates, the operating system can limit task switching to specific tasks.
3. The need for an interrupt or exception to cause a task switch. Task gates also may reside in the IDT, which allows interrupts and exceptions to cause task switching. When an interrupt or exception supplies a vector to a task gate, the processor switches to the indicated task.

Figure 13-5 illustrates how both a task gate in an LDT and a task gate in the IDT can identify the same task.

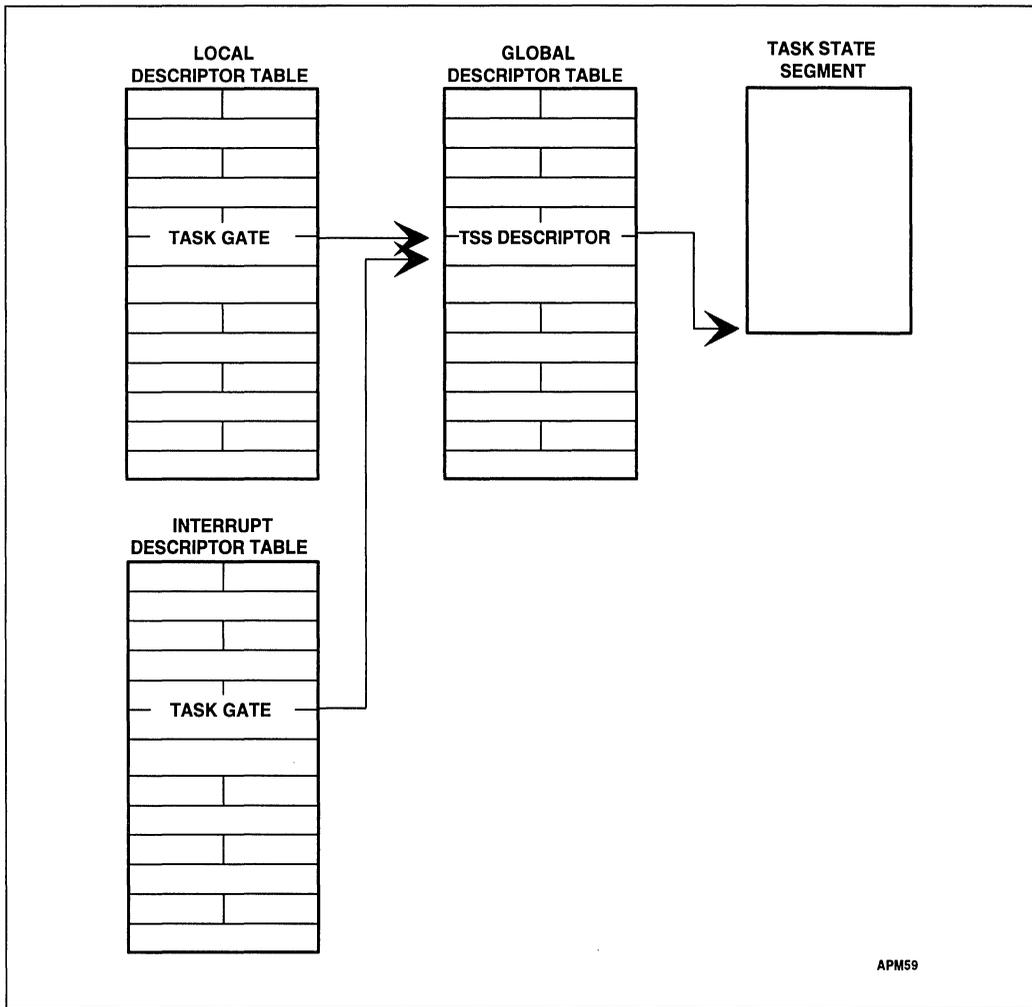


Figure 13-5. Task Gates Reference Tasks

### 13.5. TASK SWITCHING

The processor transfers execution to another task in any of four cases:

1. The current task executes a `JMP` or `CALL` to a TSS descriptor.
2. The current task executes a `JMP` or `CALL` to a task gate.
3. An interrupt or exception indexes to a task gate in the IDT.
4. The current task executes an `IRET` when the NT flag is set.

The JMP, CALL, and IRET instructions, as well as interrupts and exceptions, are all ordinary mechanisms of the processor which can be used in circumstances in which no task switch occurs. The descriptor type (when a task is called) or the NT flag (when the task returns) make the difference between the standard mechanism and the form which causes a task switch.

To cause a task switch, a JMP or CALL instruction can transfer execution to either a TSS descriptor or a task gate. The effect is the same in either case: the processor transfers execution to the specified task.

An exception or interrupt causes a task switch when it indexes to a task gate in the IDT. If it indexes to an interrupt or trap gate in the IDT, a task switch does not occur. See Chapter 14 for more information on the interrupt mechanism.

An interrupt service routine always returns execution to the interrupted procedure, which may be in another task. If the NT flag is clear, a normal return occurs. If the NT flag is set, a task switch occurs. The task receiving the task switch is specified by the TSS selector in the TSS of the interrupt service routine.

A task switch has these steps:

1. Check that the current task is allowed to switch to the new task. Data-access privilege rules apply to JMP and CALL instructions. The DPL of the TSS descriptor and the task gate must be numerically greater (e.g., lower privilege level) than or equal to both the CPL and the RPL of the gate selector. Exceptions, interrupts, and IRET instructions are permitted to switch tasks regardless of the DPL of the destination task gate or TSS descriptor.
2. Check that the TSS descriptor of the new task is marked present and has a valid limit (greater than or equal to 67H). Errors restore any changes made in the processor state when an attempt is made to execute the error-generating instruction. This lets the return address for the exception handler point to the error-generating instruction, rather than the instruction following the error-generating instruction. The exception handler can fix the condition which caused the error, and restart the task. The intervention of the exception handler can be completely transparent to the application program.
3. Save the state of the current task. The processor finds the base address of the current TSS in the task register. The processor registers are copied into the current TSS (the EAX, ECX, EDX, EBX, ESP, EBP, ESI, EDI, ES, CS, SS, DS, FS, GS, and EFLAGS registers, and the instruction pointer).
4. Load the TR register with the selector to the new task's TSS descriptor, set the new task's Busy bit, and set the TS bit in the CR0 register. The selector is either the operand of a JMP or CALL instruction, or it is taken from a task gate.
5. Load the new task's state from its TSS and continue execution. The registers loaded are the LDTR register; the PDBR (CR3); the EFLAGS register; the general registers EIP, EAX, ECX, EDX, EBX, ESP, EBP, ESI, EDI; and the segment registers ES, CS, SS, DS, FS, and GS. Any errors detected in this step occur in the context of the new task. To an exception handler, the first instruction of the new task appears not to have executed.

Note that the state of the old task is always saved when a task switch occurs. If the task is resumed, execution starts with the instruction which normally would have been next. The registers are restored to the values they held when the task stopped running.

Every task switch sets the TS (task switched) bit in the CR0 register. The TS bit is useful to system software for coordinating the operations of the integer unit with the floating-point unit. The TS bit indicates that the context of the floating-point unit may be different from that of the current task. Chapter 6 discusses the TS bit and the FPU in more detail.

Exception service routines for exceptions caused by task switching (exceptions resulting from steps 5 through 17 shown in Table 13-1 may be subject to recursive calls if they attempt to reload the segment selector which generated the exception. The cause of the exception (or the first of multiple causes) should be fixed before reloading the selector.

The privilege level at which the old task was running has no relation to the privilege level of the new task. Because the tasks are isolated by their separate address spaces and task state segments, and because privilege rules control access to a TSS, no privilege checks are needed to perform a task switch. The new task begins executing at the privilege level indicated by the RPL of the new contents of the CS register, which are loaded from the TSS.



**Table 13-1. Checks Made during a Task Switch**

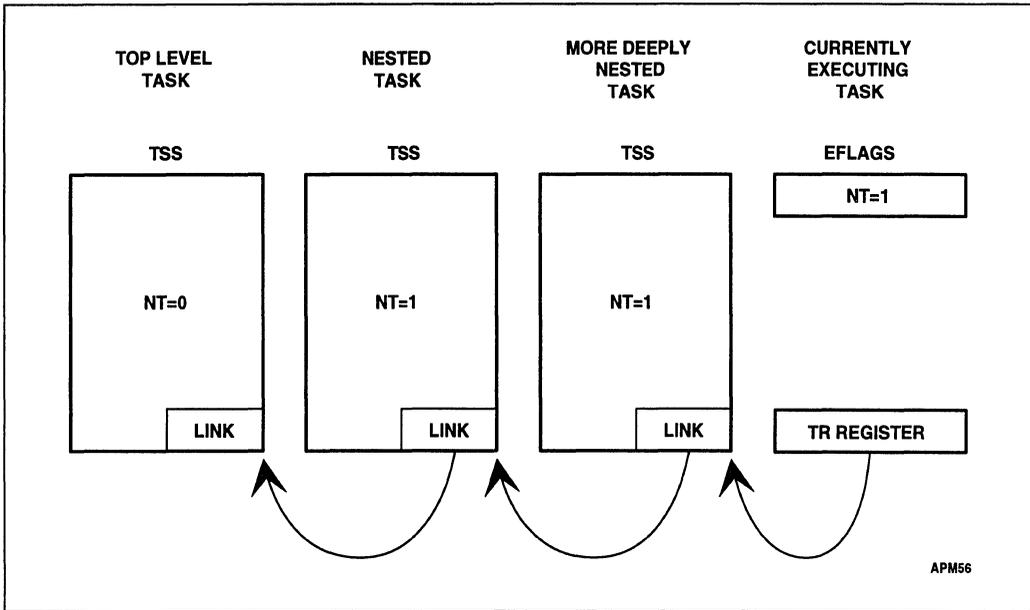
Step	Condition Checked	Exception <sup>1</sup>	Error Code Reference
1	TSS descriptor is present in memory	NP	New Task's TSS
2	TSS descriptor is not busy	TS (for IRET); GP (for JMP, CALL, INT)	Task's backlink TSS
3	TSS segment limit greater than or equal to 108	TS	New Task's TSS
4	Registers are loaded from the values in the TSS		
5	LDT selector of new task is valid <sup>2</sup>	TS	New Task's LDT
6	Code segment DPL matches selector RPL	TS	New Code Segment
7	SS selector is valid <sup>2</sup>	TS	New Stack Segment
8	Stack segment is present in memory	SF	New Stack Segment
9	Stack segment DPL matches CPL	TS	New stack segment
10	LDT of new task is present in memory	TS	New Task's LDT
11	CS selector is valid <sup>2</sup>	TS	New Code Segment
12	Code segment is present in memory	NP	New Code Segment
13	Stack segment DPL matches selector RPL	TS	New Stack Segment
14	DS, ES, FS, and GS selectors are valid <sup>2</sup>	TS	New Data Segment
15	DS, ES, FS, and GS segments are readable	TS	New Data Segment
16	DS, ES, FS, and GS segments are present in memory	NP	New Data Segment
17	DS, ES, FS, and GS segment DPL greater than or equal to CPL (unless these are conforming segments)	TS	New Data Segment

**NOTES: Future Intel processors may use a different order of checks.**

1. NP = Segment-not-present exception, GP = General-protection exception, TS = Invalid-TSS exception, SF = Stack exception.
2. A selector is valid if it is in a compatible type of table (e.g., an LDT selector may not be in any table except the GDT), occupies an address within the table's segment limit, and refers to a compatible type of descriptor (e.g., a selector in the CS register only is valid when it indexes to a descriptor for a code segment; the descriptor type is specified in its Type field).

## 13.6. TASK LINKING

The Link field of the TSS and the NT flag are used to return execution to the previous task. The NT flag indicates whether the currently executing task is nested within the execution of another task, and the Link field of the current task's TSS holds the TSS selector for the higher-level task, if there is one (see Figure 13-6).



**Figure 13-6. Nested Tasks**

When an interrupt, exception, jump, or call causes a task switch, the processor copies the segment selector for the current task state segment into the TSS for the new task and sets the NT flag. The NT flag indicates the Link field of the TSS has been loaded with a saved TSS selector. The new task releases control by executing an IRET instruction. When an IRET instruction is executed, the NT flag is checked. If it is set, the processor does a task switch to the previous task. Table 13-2 summarizes the uses of the fields in a TSS which are affected by task switching.

**Table 13-2. Effect of a Task Switch on Busy, NT and Link Fields**

Field	Effect of Jump	Effect of CALL Instruction or Interrupt	Effect of IRET Instruction
Busy bit of new task	Bit is set. Must have been clear before.	Bit is set. Must have been clear before.	No change. Must be set.
Busy bit of old task	Bit is cleared.	No change. Bit is currently set.	Bit is cleared.
NT flag of new task	No change.	Flag is set.	No change.
NT flag of old task	No change.	No change.	Flag is cleared.
Link field of new task.	No change.	Loaded with selector for old task's TSS.	No change.
Link field of old task.	No change.	No change.	No change.

Note that the NT flag may be modified by software executing at any privilege level. It is possible for a program to set its NT bit and execute an IRET instruction, which would have the effect of invoking the task specified in the Link field of the current task's TSS. To keep spurious task switches from succeeding, the operating system should initialize the Link field of every TSS it creates.

### 13.6.1. Busy Bit Prevents Loops

The Busy bit of the TSS descriptor prevents re-entrant task switching. There is only one saved task context, the context saved in the TSS, therefore a task only may be called once before it terminates. The chain of suspended tasks may grow to any length, due to multiple interrupts, exceptions, jumps, and calls. The Busy bit prevents a task from being called if it is in this chain. A re-entrant task switch would overwrite the old TSS for the task, which would break the chain.

The processor manages the Busy bit as follows:

1. When switching to a task, the processor sets the Busy bit of the new task.
2. When switching from a task, the processor clears the Busy bit of the old task if that task is not to be placed in the chain (i.e., the instruction causing the task switch is a JMP or IRET instruction). If the task is placed in the chain, its Busy bit remains set.
3. When switching to a task, the processor generates a general-protection exception if the Busy bit of the new task already is set.

In this way, the processor prevents a task from switching to itself or to any task in the chain, which prevents re-entrant task switching.

The Busy bit may be used in multiprocessor configurations, because the processor asserts a bus lock when it sets or clears the Busy bit. This keeps two processors from invoking the same task at the same time. (See Chapter 19 for more information on multiprocessing.)

### 13.6.2. Modifying Task Linkages

Modification of the chain of suspended tasks may be needed to resume an interrupted task before the task which interrupted it. A reliable way to do this is:

1. Disable interrupts.
2. First change the Link field in the TSS of the interrupting task, then clear the Busy bit in the TSS descriptor of the task being removed from the chain.
3. Re-enable interrupts.

## 13.7. TASK ADDRESS SPACE

The LDT selector and PDBR (CR3) field of the TSS can be used to give each task its own LDT and page tables. Because segment descriptors in the LDTs are the connections between tasks and segments, separate LDTs for each task can be used to set up individual control over these connections. Access to any particular segment can be given to any particular task by placing a segment descriptor for that segment in the LDT for that task. If paging is enabled, each task can have its own set of page tables for mapping linear addresses to physical addresses.

It also is possible for tasks to have the same LDT. This is a simple and memory-efficient way to allow some tasks to communicate with or control each other, without dropping the protection barriers for the entire system.

Because all tasks have access to the GDT, it also is possible to create shared segments accessed through segment descriptors in this table.

### 13.7.1. Task Linear-to-Physical Space Mapping

The choices for arranging the linear-to-physical mappings of tasks fall into two general classes:

1. One linear-to-physical mapping shared among all tasks. When paging is not enabled, this is the only choice. Without paging, all linear addresses map to the same physical addresses. When paging is enabled, this form of linear-to-physical mapping is obtained by using one page directory for all tasks. The linear space may exceed the available physical space if demand-paged virtual memory is supported.
2. Independent linear-to-physical mappings for each task. This form of mapping comes from using a different page directory for each task. Because the PDBR (page directory base register) is loaded from the TSS with each task switch, each task may have a different page directory.

The linear address spaces of different tasks may map to completely distinct physical addresses. If the entries of different page directories point to different page tables and the



page tables point to different pages of physical memory, then the tasks do not share any physical addresses.

The task state segments must lie in a space accessible to all tasks so that the mapping of TSS addresses does not change while the processor is reading and updating the TSSs during a task switch. The linear space mapped by the GDT also should be mapped to a shared physical space; otherwise, the purpose of the GDT is defeated. Figure 13-7 shows how the linear spaces of two tasks can overlap in the physical space by sharing page tables.

### 13.7.2. Task Logical Address Space

By itself, an overlapping linear-to-physical space mapping does not allow sharing of data among tasks. To share data, tasks must also have a common logical-to-linear space mapping; i.e., they also must have access to descriptors which point into a shared linear address space. There are three ways to create shared logical-to-physical address-space mappings:

1. Through the segment descriptors in the GDT. All tasks have access to the descriptors in the GDT. If those descriptors point into a linear-address space which is mapped to a common physical-address space for all tasks, then the tasks can share data and instructions.
2. Through shared LDTs. Two or more tasks can use the same LDT if the LDT selectors in their TSSs select the same LDT for use in address translation. Segment descriptors in the LDT addressing linear space mapped to overlapping physical space provide shared physical memory. This method of sharing is more selective than sharing by the GDT; the sharing can be limited to specific tasks. Other tasks in the system may have different LDTs which do not give them access to the shared areas.
3. Through segment descriptors in the LDTs which map to the same linear address space. If the linear address space is mapped to the same physical space by the page mapping of the tasks involved, these descriptors permit the tasks to share space. Such descriptors are commonly called aliases. This method of sharing is even more selective than those listed above; other descriptors in the LDTs may point to independent linear addresses which are not shared.

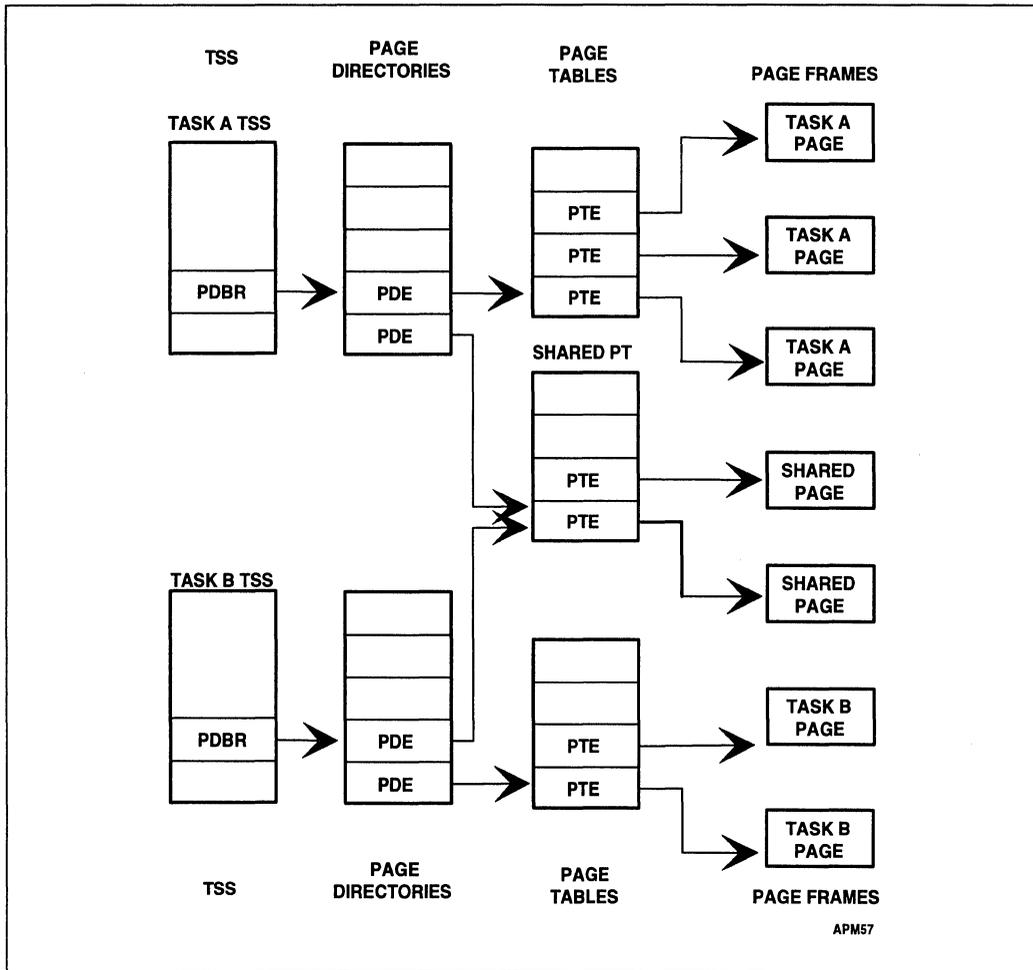


Figure 13-7. Overlapping Linear-to-Physical Mappings





**14**

# **Protected-Mode Exceptions and Interrupts**





# CHAPTER 14

## PROTECTED-MODE EXCEPTIONS AND INTERRUPTS

Exceptions and interrupts are forced transfers of execution to a task or a procedure. The task or procedure is called a *handler*. Interrupts occur at random times during the execution of a program, in response to signals from hardware. Exceptions occur when instructions are executed which provoke exceptions. Usually, the servicing of interrupts and exceptions is performed in a manner transparent to application programs. Interrupts are used to handle events external to the processor, such as requests to service peripheral devices. Exceptions handle conditions detected by the processor in the course of executing instructions, such as division by zero.

There are two sources for interrupts and two sources for exceptions:

### 1. Interrupts

- Maskable interrupts, which are received on the CPU's INTR input pin. Maskable interrupts do not occur unless the interrupt-enable flag (IF) is set.
- Nonmaskable interrupts, which are received on the NMI (Non-Maskable Interrupt) input of the processor. The processor does not provide a mechanism to prevent nonmaskable interrupts.

### 2. Exceptions

- Processor-detected exceptions. These are further classified as *faults*, *traps*, and *aborts*.
- Programmed exceptions. The INTO, INT 3, INT *n*, and BOUND instructions may trigger exceptions. These instructions often are called "software interrupts," but the processor handles them as exceptions.

This chapter explains the features of the processor which control and respond to interrupts.

## 14.1. EXCEPTION AND INTERRUPT VECTORS

The processor associates an identifying number with each different type of interrupt or exception. This number is called a *vector*.

The NMI interrupt and the exceptions are assigned vectors in the range 0 through 31. Not all of these vectors are currently used by the processor; unassigned vectors in this range are reserved for possible future uses. Do not use unassigned vectors.

The vectors for maskable interrupts are determined by hardware. External interrupt controllers (such as Intel's 8259A Programmable Interrupt Controller) put the vector on the

processor's bus during its interrupt-acknowledge cycle. Any vectors in the range 32 through 255 can be used. Table 14-1 shows the assignment of exception and interrupt vectors.

**Table 14-1. Exception and Interrupt Vectors**

Vector Number	Description
0	Divide Error
1	Debug Exception
2	NMI Interrupt
3	Breakpoint
4	INTO-detected Overflow
5	BOUND Range Exceeded
6	Invalid Opcode
7	Device Not Available
8	Double Fault
9	CoProcessor Segment Overrun (reserved)
10	Invalid Task State Segment
11	Segment Not Present
12	Stack Fault
13	General Protection
14	Page Fault
15	(Intel reserved. Do not use.)
16	Floating-Point Error
17	Alignment Check
18	Machine Check*
19-31	(Intel reserved. Do not use.)
32-255	Maskable Interrupts

\*Machine check is a model-specific exception, available on the Pentium® microprocessor only. It may not be continued or may not be continued with a compatible implementation in future processor generations.

Exceptions are classified as *faults*, *traps*, or *aborts* depending on the way they are reported and whether restart of the instruction which caused the exception is supported.

**Faults**—A fault is an exception which is reported at the instruction boundary prior to the instruction in which the exception was detected. The fault is reported with the machine restored to a state which permits the instruction to be restarted. The return address for the fault handler points to the instruction which generated the fault, rather than the instruction following the faulting instruction.

**Traps**—A trap is an exception which is reported at the instruction boundary immediately after the instruction in which the exception was detected.

**Aborts**—An abort is an exception which does not always report the location of the instruction causing the exception and does not allow restart of the program which caused the exception. Aborts are used to report severe errors, such as hardware errors and inconsistent or illegal values in system tables.

## 14.2. INSTRUCTION RESTART

For most exceptions and interrupts, transfer of execution does not take place until the end of the current instruction. This leaves the EIP register pointing at the instruction which comes after the instruction which was being executed when the exception or interrupt occurred. If the instruction has a repeat prefix, transfer takes place at the end of the current iteration with the registers set to execute the next iteration. But if the exception is a fault, the processor registers are restored to the state they held before execution of the instruction began. This permits *instruction restart*.

Instruction restart is used to handle exceptions which block access to operands. For example, an application program could make reference to data in a segment which is not present in memory. When the exception occurs, the exception handler must load the segment (probably from a hard disk) and resume execution beginning with the instruction which caused the exception. At the time the exception occurs, the instruction may have altered the contents of some of the processor registers. If the instruction read an operand from the stack, it is necessary to restore the stack pointer to its previous value. All of these restoring operations are performed by the processor in a manner completely transparent to the application program.

When a fault occurs, the EIP register is restored to point to the instruction which received the exception. When the exception handler returns, execution resumes with this instruction.

## 14.3. ENABLING AND DISABLING INTERRUPTS

Certain conditions and flag settings cause the processor to inhibit certain kinds of interrupts and exceptions.

### 14.3.1. NMI Masks Further NMIs

While an NMI interrupt handler is executing, the processor disables additional calls to the procedure or task which handles the interrupt until the next IRET instruction is executed. This prevents stacking up calls to the interrupt handler. It is recommended that interrupt gates be used for NMI's in order to disable nested maskable interrupts, since an IRET instruction from the maskable-interrupt handler would re-enable NMI.

### 14.3.2. IF Masks INTR

The IF flag can turn off servicing of interrupts received on the INTR pin of the processor. When the IF flag is clear, INTR interrupts are ignored; when the IF flag is set, INTR interrupts are serviced. As with the other flag bits, the processor clears the IF flag in response to a RESET signal. The STI and CLI instructions set and clear the IF flag.

**CLI (Clear Interrupt-Enable Flag)** and **STI (Set Interrupt-Enable Flag)** put the IF flag (bit 9 in the EFLAGS register) in a known state. These instructions may be executed only if the CPL is an equal or more privileged level than the IOPL. A general-protection exception is generated if they are executed with a lesser privileged level.

The IF flag also is affected by the following operations:

- The PUSHF instruction stores all flags on the stack, where they can be examined and modified. The POPF instruction can be used to load the modified form back into the EFLAGS register.
- Task switches and the POPF and IRET instructions load the EFLAGS register; therefore, they can be used to modify the setting of the IF flag.
- Interrupts through interrupt gates automatically clear the IF flag, which disables interrupts. (Interrupt gates are explained later in this chapter).

### 14.3.3. RF Masks Debug Faults

The RF flag in the EFLAGS register is used to prevent servicing an instruction breakpoint fault multiple times. RF works as follows:

- The processor does not set the RF bit in the EFLAGS image that it pushes onto the stack of the handler. Normally the RF image on the stack does not need to be changed by software.
- RF itself is set by the fault handler when it executes the IRETD instruction to return to the faulting instruction. IRETD transfers the EFLAGS image from the stack into the EFLAGS register. (POPF and POPFD do not transfer the RF image into the EFLAGS register.)
- RF is cleared by the processor at successful termination of every instruction, except after the IRET instruction and after JMP, CALL, or INT instructions that cause a task switch. Therefore, RF remains set for no more than one instruction — the one executed immediately after the IRET.
- When set, RF causes the processor to suppress reporting of instruction breakpoint faults.

Because instruction breakpoint faults are the highest priority faults, they are always reported before any other faults for the same instruction. RF is zero for the first attempt to execute the instruction and one for all attempts to restart the instruction after an instruction breakpoint or any other fault. This ensures that an instruction breakpoint fault is reported only once. (See Chapter 17 for more information on debugging.)



#### 14.3.4. MOV or POP to SS Masks Some Exceptions and Interrupts

Software which needs to change stack segments often uses a pair of instructions; for example:

```
MOV             SS, AX
MOV             ESP, StackTop
```

If an interrupt or exception occurs after the segment selector has been loaded but before the ESP register has been loaded, these two parts of the logical address into the stack space are inconsistent for the duration of the interrupt or exception handler.

To prevent this situation, the processor inhibits interrupts, debug exceptions, and single-step trap exceptions after either a MOV to SS instruction or a POP to SS instruction, until the instruction boundary following the next instruction is reached. General-protection faults may still be generated. If the LSS instruction is used to modify the contents of the SS register, the problem does not occur.

### 14.4. PRIORITY AMONG SIMULTANEOUS EXCEPTIONS AND INTERRUPTS

If more than one exception or interrupt is pending at an instruction boundary, the processor services them in a predictable order. The priority among classes of exception and interrupt sources is shown in Table 14-2. While priority among these classes is consistent throughout the architecture, exceptions within each class are implementation-dependent and may vary from processor to processor. The processor first services a pending exception or interrupt from the class which has the highest priority, transferring execution to the first instruction of the handler. Lower priority exceptions are discarded; lower priority interrupts are held pending. Discarded exceptions are re-issued when the interrupt handler returns execution to the point of interruption.

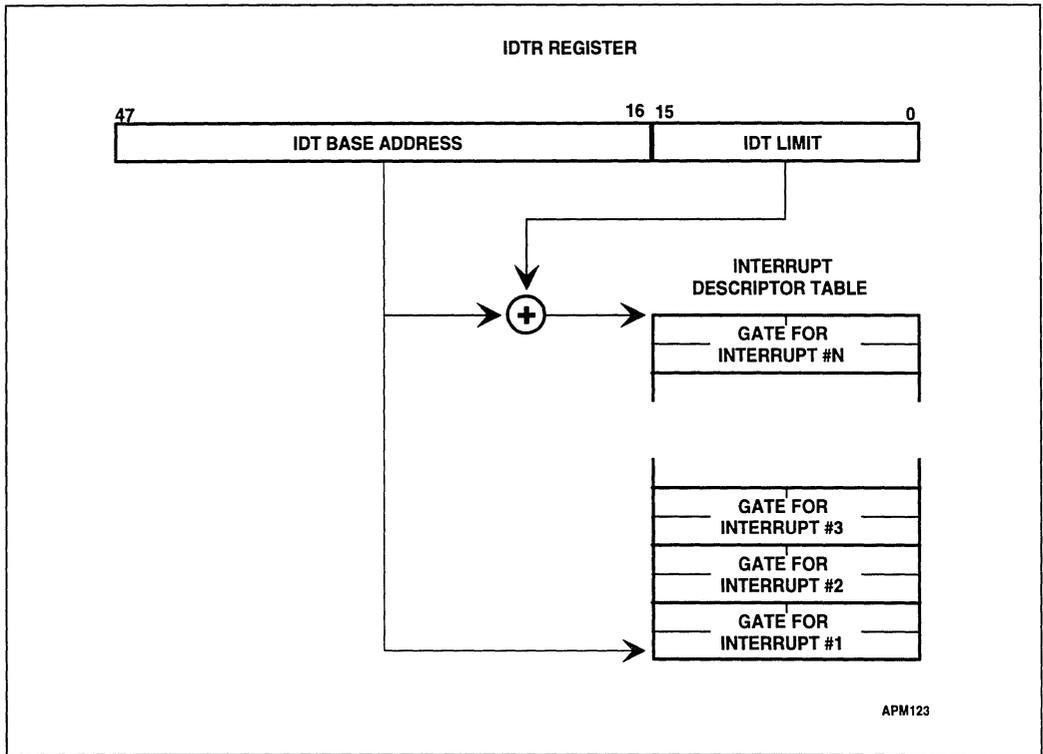
**Table 14-2. Priority Among Simultaneous Exceptions and Interrupts**

Priority	Class	Descriptions
Highest	Class 1	Traps on the Previous Instruction - Breakpoints - Debug Trap Exceptions (TF flag set, T bit in TSS set, or data/IO breakpoint)
	Class 2	External Interrupts - NMI Interrupts - Maskable Interrupts
	Class 3	Faults from fetching next instruction - Code Breakpoint Fault
	Class 4	Faults from fetching or decoding the next instruction - Code Segment Limit Violation - Page Fault on Prefetch - Illegal Opcode - Instruction length > 15 bytes - Coprocessor Not Available
Lowest	Class 5	Faults on Executing an Instruction - General Detection - FP error (from previous FP instruction) - Interrupt on Overflow - Bound - Invalid TSS - Segment Not Present - Stack Exception - General Protection - Data Page Fault - Alignment Check

## 14.5. INTERRUPT DESCRIPTOR TABLE

The interrupt descriptor table (IDT) associates each exception or interrupt vector with a descriptor for the procedure or task which services the associated event. Like the GDT and LDTs, the IDT is an array of 8-byte descriptors. Unlike the GDT, the first entry of the IDT may contain a descriptor. To form an index into the IDT, the processor scales the exception or interrupt vector by eight, the number of bytes in a descriptor. Because there are only 256 vectors, the IDT need not contain more than 256 descriptors. It can contain fewer than 256 descriptors; descriptors are required only for the interrupt vectors which may occur.

The IDT may reside anywhere in physical memory. As Figure 14-1 shows, the processor locates the IDT using the IDTR register. This register holds both a 32-bit base address and 16-bit limit for the IDT. The LIDT and SIDT instructions load and store the contents of the IDTR register. Both instructions have one operand, which is the address of six bytes in memory.



**Figure 14-1. IDTR Locates IDT in Memory**

If a vector references a descriptor beyond the limit, the processor enters shutdown mode. In this mode, the processor stops executing instructions until an NMI interrupt is received or reset initialization is invoked. The processor generates a special bus cycle to indicate it has entered shutdown mode. Software designers may need to be aware of the response of hardware to receiving this signal. For example, hardware may turn on an indicator light on the front panel, generate an NMI interrupt to record diagnostic information, or invoke reset initialization.

**LIDT (Load IDT register)** loads the IDTR register with the base address and limit held in the memory operand. This instruction can be executed only when the CPL is 0. It normally is used by the initialization code of an operating system when creating an IDT. An operating system also may use it to change from one IDT to another.

**SIDT (Store IDT register)** copies the base and limit value stored in IDTR to memory. This instruction can be executed at any privilege level.

## 14.6. IDT DESCRIPTORS

The IDT may contain any of three kinds of descriptors:

- Task gates
- Interrupt gates
- Trap gates

Figure 14-2 shows the format of task gates, interrupt gates, and trap gates. (The task gate in an IDT is the same as the task gate in the GDT or an LDT already discussed in Chapter 13.)



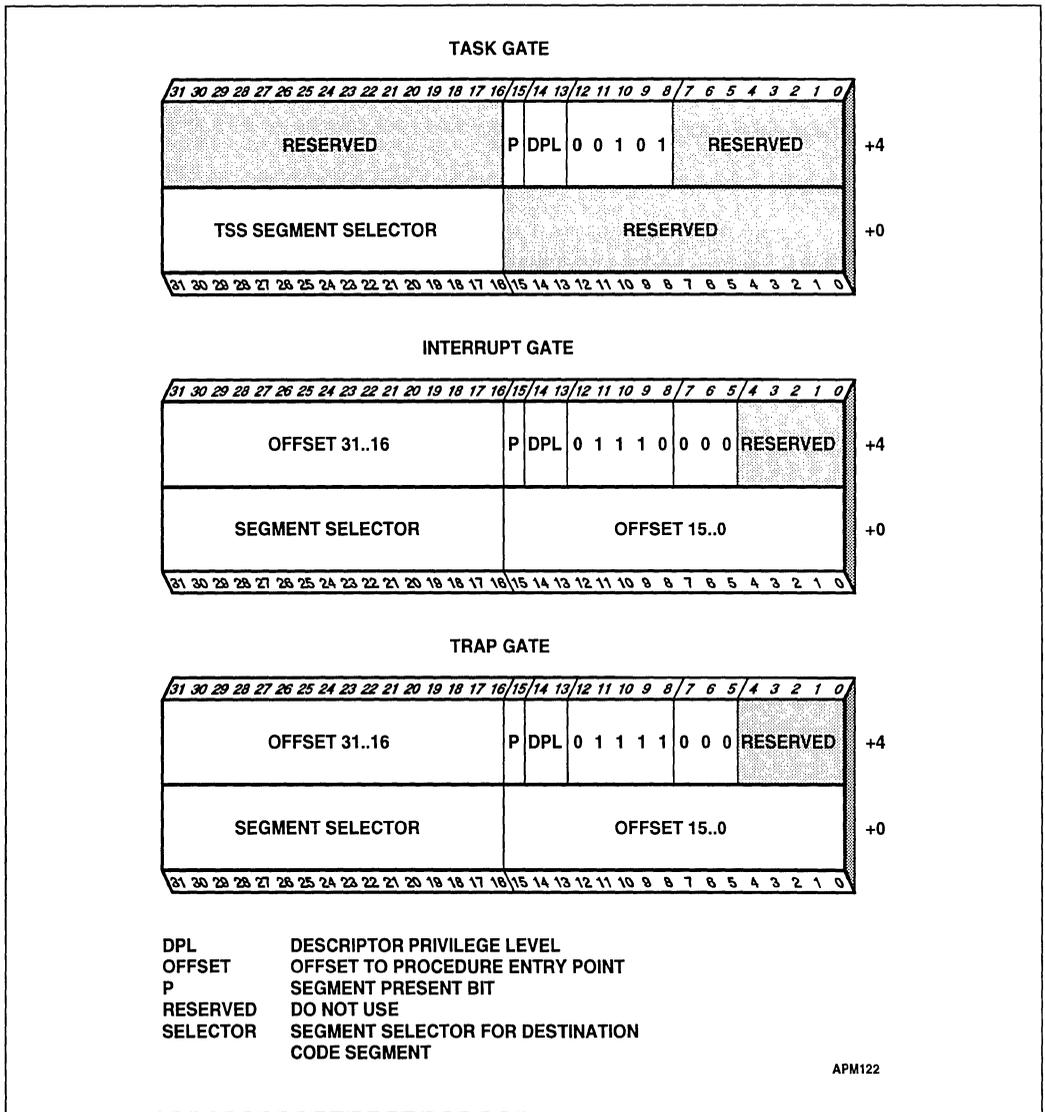


Figure 14-2. IDT Gate Descriptors

## 14.7. INTERRUPT TASKS AND INTERRUPT PROCEDURES

Just as a CALL instruction can call either a procedure or a task, so an exception or interrupt can "call" an interrupt handler as either a procedure or a task. When responding to an exception or interrupt, the processor uses the exception or interrupt vector to index to a

descriptor in the IDT. If the processor indexes to an interrupt gate or trap gate, it calls the handler in a manner similar to a CALL to a call gate. If the processor finds a task gate, it causes a task switch in a manner similar to a CALL to a task gate.

### 14.7.1. Interrupt Procedures

An interrupt gate or trap gate indirectly references a procedure which runs in the context of the currently executing task, as shown in Figure 14-3. The selector of the gate points to an executable-segment descriptor in either the GDT or the current LDT. The offset field of the gate descriptor points to the beginning of the exception or interrupt handling procedure.

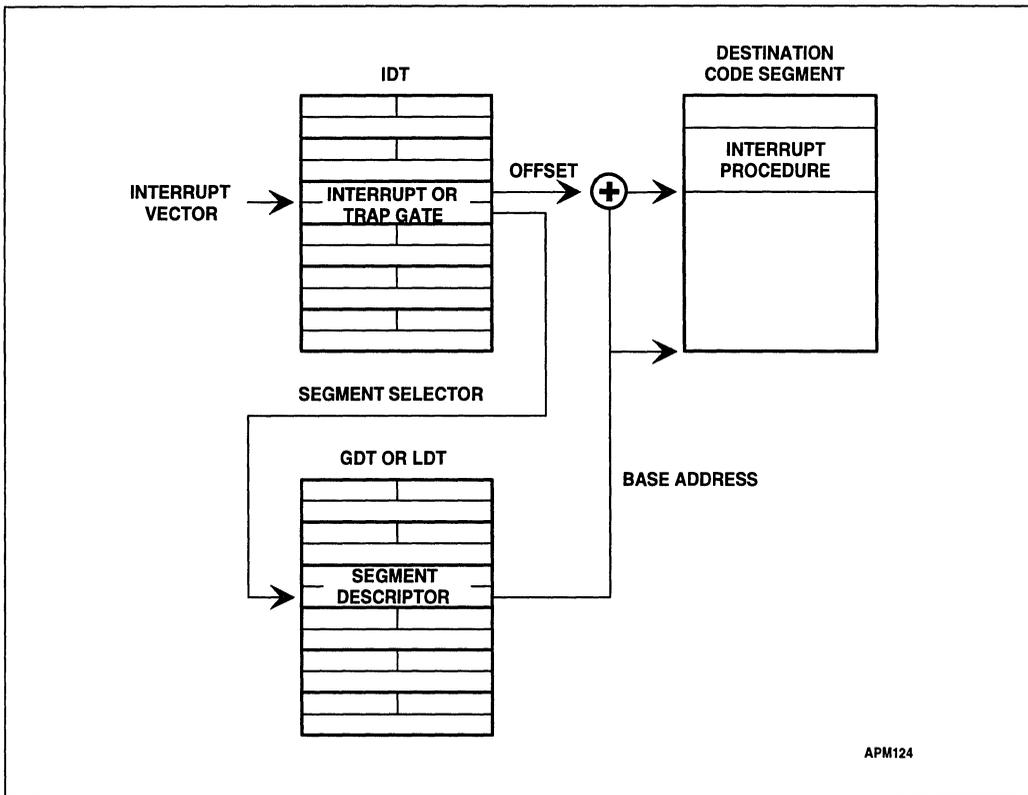


Figure 14-3. Interrupt Procedure Call

The processor calls an exception or interrupt handling procedure in much the same manner as a procedure call; the differences are explained in the following sections.

### 14.7.1.1. STACK OF INTERRUPT PROCEDURE

Just as with a transfer of execution using a CALL instruction, a transfer to an exception or interrupt handling procedure uses the stack to store the processor state. As Figure 14-4 shows, an interrupt pushes the contents of the EFLAGS register onto the stack before pushing the address of the interrupted instruction.

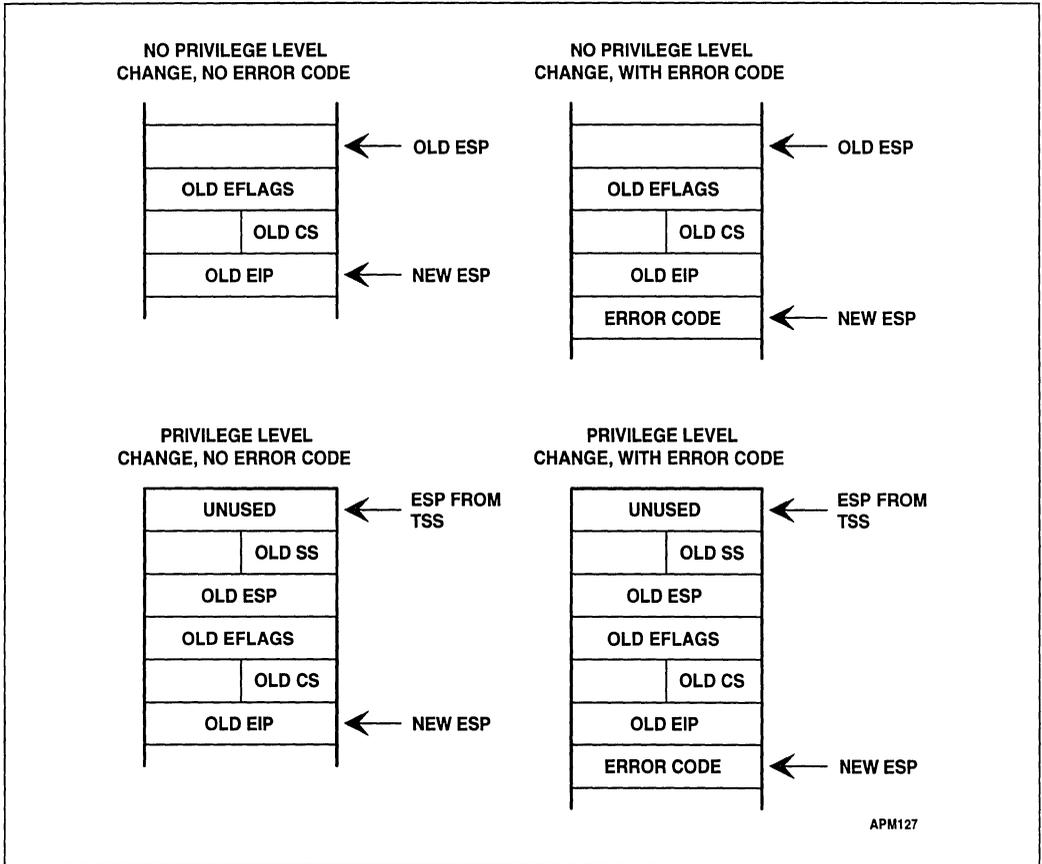


Figure 14-4. Stack Frame after Exception or Interrupt

Certain types of exceptions also push an error code on the stack. An exception handler can use the error code to help diagnose the exception.

### 14.7.1.2. RETURNING FROM AN INTERRUPT PROCEDURE

An interrupt procedure differs from a normal procedure in the method of leaving the procedure. The IRET instruction is used to exit from an interrupt procedure. The IRET instruction is similar to the RET instruction except that it increments the contents of the ESP

register by an extra four bytes and restores the saved flags into the EFLAGS register. The IOPL field of the EFLAGS register is restored only if the CPL is 0. The IF flag is changed only if  $CPL \leq IOPL$ .

#### 14.7.1.3. FLAG USAGE BY INTERRUPT PROCEDURE

Interrupts using either interrupt gates or trap gates cause the TF flag to be cleared after its current value is saved on the stack as part of the saved contents of the EFLAGS register. In so doing, the processor prevents instruction tracing from affecting interrupt response. A subsequent IRET instruction restores the TF flag to the value in the saved contents of the EFLAGS register on the stack.

The difference between an interrupt gate and a trap gate is its effect on the IF flag. An interrupt which uses an interrupt gate clears the IF flag, which prevents other interrupts from interfering with the current interrupt handler. A subsequent IRET instruction restores the IF flag to the value in the saved contents of the EFLAGS register on the stack. An interrupt through a trap gate does not change the IF flag.

#### 14.7.1.4. PROTECTION IN INTERRUPT PROCEDURES

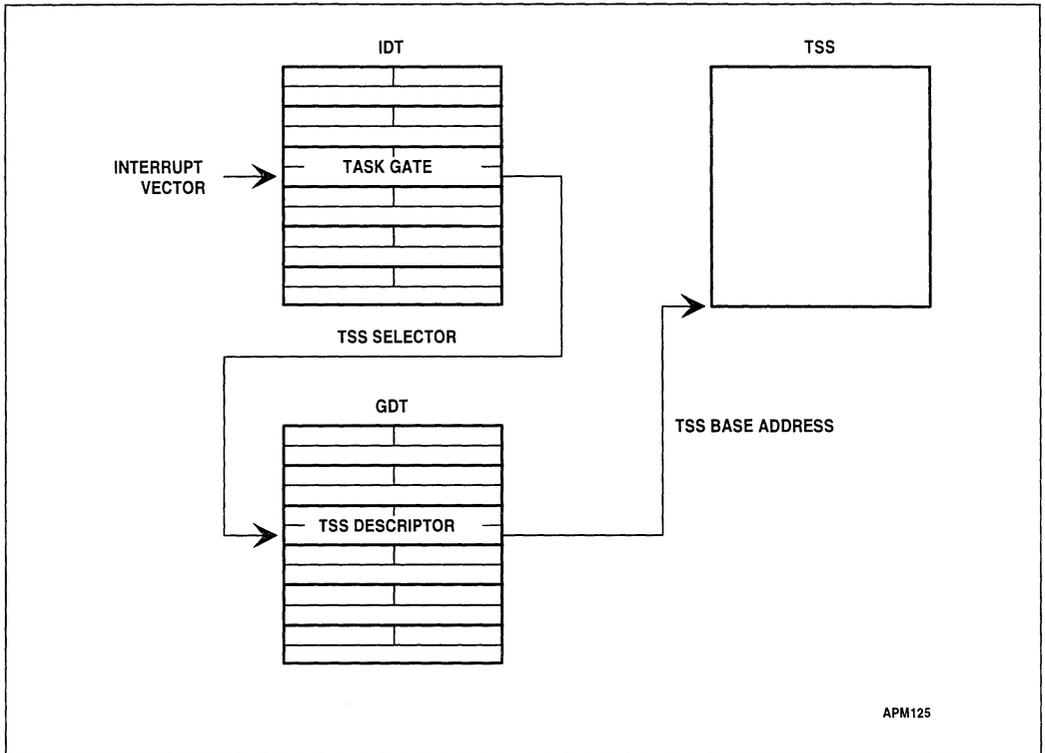
The privilege rule which governs interrupt procedures is similar to that for procedure calls: the processor does not permit an interrupt to transfer execution to a procedure in a less privileged segment (numerically greater privilege level). An attempt to violate this rule results in a general-protection exception.

Because interrupts generally do not occur at predictable times, this privilege rule effectively imposes restrictions on the privilege levels at which exception and interrupt handling procedures can run. Either of the following techniques can be used to keep the privilege rule from being violated.

- The exception or interrupt handler can be placed in a conforming code segment. This technique can be used by handlers for certain exceptions (divide error, for example). These handlers must use only the data available on the stack. If the handler needs data from a data segment, the data segment would have to have privilege level 3, which would make it unprotected.
- The handler can be placed in a code segment with privilege level 0. This handler would always run, no matter what CPL the program has.

### 14.7.2. Interrupt Tasks

A task gate in the IDT indirectly references a task, as Figure 14-5 illustrates. The segment selector in the task gate addresses a TSS descriptor in the GDT.



**Figure 14-5. Interrupt Task Switch**

When an exception or interrupt calls a task gate in the IDT, a task switch results. Handling an interrupt with a separate task offers two advantages:

- The entire context is saved automatically.
- The interrupt handler can be isolated from other tasks by giving it a separate address space. This is done by giving it a separate LDT.

A task switch caused by an interrupt operates in the same manner as the other task switches described in Chapter 13. The interrupt task returns to the interrupted task by executing an IRET instruction.

Some exceptions return an error code. If the task switch is caused by one of these, the processor pushes the code onto the stack corresponding to the privilege level of the interrupt handler.

When interrupt tasks are used in an operating system, there are actually two mechanisms which can dispatch tasks: the software scheduler (part of the operating system) and the hardware scheduler (part of the processor's interrupt mechanism). The software scheduler needs to accommodate interrupt tasks which may be dispatched when interrupts are enabled.

## 14.8. ERROR CODE

With exceptions related to a specific segment, the processor pushes an error code onto the stack of the exception handler (whether it is a procedure or task). The error code has the format shown in Figure 14-6. The error code resembles a segment selector; however instead of an RPL field, the error code contains two one-bit fields:

1. The processor sets the EXT bit if an event external to the program caused the exception.
2. The processor sets the IDT bit if the index portion of the error code refers to a gate descriptor in the IDT.

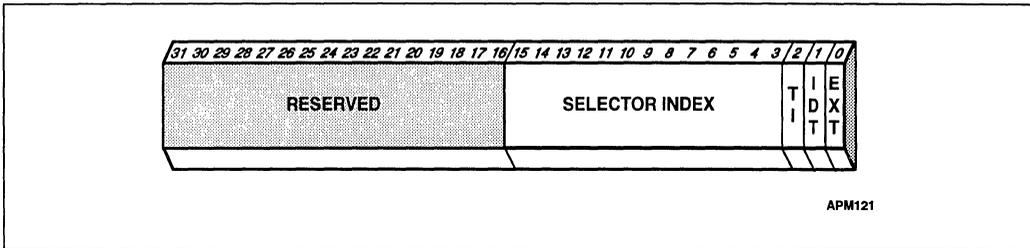


Figure 14-6. Error Code

If the IDT bit is not set, the TI bit indicates whether the error code refers to the GDT (TI bit clear) or to the LDT (TI bit set). The remaining 13 bits are the upper bits of the selector for the segment. In some cases the error code is *null* (i.e., all bits in the lower word are clear).

The error code is pushed on the stack as a doubleword or word, according to current default size. This is done to keep the stack aligned on addresses which are multiples of four. The upper half of the doubleword is reserved.

## 14.9. EXCEPTION CONDITIONS

The following sections describe conditions which generate exceptions. Each description classifies the exception as a *fault*, *trap*, or *abort*. This classification provides information needed by system programmers for restarting the procedure in which the exception occurred:

- **Faults**—The saved contents of the CS and EIP registers point to the instruction which generated the fault.
- **Traps**—The saved contents of the CS and EIP registers stored when the trap occurs point to the instruction to be executed after the instruction which generated the trap. If a trap is detected during an instruction which transfers execution, the saved contents of the CS and EIP registers reflect the transfer. For example, if a trap is detected in a JMP instruction, the saved contents of the CS and EIP registers point to the destination of the JMP instruction, not to the instruction at the next address above the JMP instruction.

- **Aborts**—An abort is an exception which permits neither precise location of the instruction causing the exception nor restart of the program which caused the exception. Aborts are used to report severe errors, such as hardware errors and inconsistent or illegal values in system tables.

### 14.9.1. Interrupt 0—Divide Error

The divide-error fault occurs during a DIV or an IDIV instruction when the divisor is zero.

### 14.9.2. Interrupt 1—Debug Exceptions

The processor generates a debug exception for a number of conditions; whether the exception is a fault or a trap depends on the condition, as shown below:

Instruction address breakpoint		fault
Data address breakpoint		trap
General detect	fault	
Single-step	trap	
Task-switch breakpoint		trap

The processor does not push an error code for this exception. An exception handler can examine the debug registers to determine which condition caused the exception. See Chapter 17 for more detailed information about debugging and the debug registers.

### 14.9.3. Interrupt 3—Breakpoint

The INT 3 instruction generates a breakpoint trap. The INT 3 instruction is one byte long, which makes it easy to replace an opcode in a code segment in RAM with the breakpoint opcode. The operating system or a debugging tool can use a data segment mapped to the same physical address space as the code segment to place an INT 3 instruction in places where it is desired to call the debugger. Debuggers use breakpoints as a way to suspend program execution in order to examine registers, variables, etc.

The saved contents of the CS and EIP registers point to the byte following the breakpoint. If a debugger allows the suspended program to resume execution, it replaces the INT 3 instruction with the original opcode at the location of the breakpoint, and it decrements the saved contents of the EIP register before returning. See Chapter 17 for more information on debugging.

#### 14.9.4. Interrupt 4—Overflow

The overflow trap occurs when the processor executes an INTO instruction with the OF flag set. Because signed and unsigned arithmetic both use some of the same instructions, the processor cannot determine when overflow actually occurs. Instead, it sets the OF flag when the results, if interpreted as signed numbers, would be out of range. When doing arithmetic on signed operands, the OF flag can be tested directly or the INTO instruction can be used.

#### 14.9.5. Interrupt 5—Bounds Check

The bounds-check fault is generated when the processor, while executing a BOUND instruction, finds that the operand exceeds the specified limits. A program can use the BOUND instruction to check a signed array index against signed limits defined in a block of memory.

#### 14.9.6. Interrupt 6—Invalid Opcode

The invalid-opcode fault is generated when an invalid opcode is detected by the execution unit. (The exception is not detected until an attempt is made to execute the invalid opcode; i.e., prefetching an invalid opcode does not cause this exception.) No error code is pushed on the stack. The exception can be handled within the same task.

This exception also occurs when the type of operand is invalid for the given opcode. Examples include an intersegment JMP instruction using a register operand, or an LES instruction with a register source operand.

A third condition which generates this exception is the use of the LOCK prefix with an instruction which may not be locked. Only certain instructions may be used with bus locking, and only forms of these instructions which write to a destination in memory may be used. All other uses of the LOCK prefix generate an invalid-opcode exception.

Following is a list of undefined opcodes that are reserved by Intel. These opcodes, even though undefined, do not generate interrupt 6.

- D6
- F1

#### 14.9.7. Interrupt 7—Device Not Available

The device-not-available fault is generated by either of two conditions:

- The processor executes an ESC instruction, and the EM bit of the CR0 register is set.
- The processor executes a WAIT instruction (with MP=1) or ESC instruction, and the TS bit of the CR0 register is set.



Interrupt 7 thus occurs when the programmer wants ESC instructions to be handled by software (EM set), or when a WAIT or ESC instruction is encountered and the context of the floating-point unit is different from that of the current task.

On the Intel 286 and Intel386 processors, the MP bit in the CR0 register is used with the TS bit to determine if WAIT instructions should generate exceptions. For programs running on the Pentium and Intel486 DX processors, and Intel487 SX coprocessors, the MP bit should always be set. For programs running on the Intel486 SX processor, MP should be clear.

### 14.9.8. Interrupt 8—Double Fault

Normally, when the processor detects an exception while trying to call the handler for a prior exception, the two exceptions can be handled serially. If, however, the processor cannot handle them serially, it signals the double-fault exception instead. To determine when two faults are to be signaled as a double fault, the processor divides the exceptions into three classes: benign exceptions, contributory exceptions, and page faults. Table 14-3 shows this classification. Then, comparing the classes of the first and second exception, the processor signals a double-fault in the cases indicated by Table 14-4.

**Table 14-3. Interrupt and Exception Classes**

Class	Vector Number	Description
Benign Exceptions and Interrupts	1	Debug Exceptions
	2	NMI Interrupt
	3	Breakpoint
	4	Overflow
	5	Bounds Check
	6	Invalid Opcode
	7	Device Not Available
Contributory Exceptions	16	Floating-Point Error
	0	Divide Error
	10	Invalid TSS
	11	Segment Not Present
	12	Stack Fault
Page Faults	13	General Protection
	14	Page Fault

**Table 14-4. Double Fault Conditions**

First Exception	Second Exception		
	Benign	Contributory	Page Fault
Benign	OK	OK	OK
Contributory	OK	Double Fault	OK
Page Fault	OK	Double Fault	Double Fault

An initial segment or page fault encountered while prefetching instructions is outside the domain of Table 14-4. Any further faults generated while the processor is attempting to transfer control to the appropriate fault handler could still lead to a double-fault sequence.

The processor always pushes an error code onto the stack of the double-fault handler; however, the error code is always 0. The faulting instruction may not be restarted. If any other exception occurs while attempting to call the double-fault handler, the processor enters shutdown mode. This mode is similar to the state following execution of an HLT instruction. No instructions are executed until an NMI interrupt or a RESET signal is received. If the shutdown occurs while the processor is executing an NMI interrupt handler, then only a RESET can restart the processor. The processor generates a special bus cycle to indicate it has entered shutdown mode.

#### **14.9.9. Interrupt 9—(Intel reserved. Do not use.)**

Interrupt 9, the coprocessor-segment overrun abort, is generated in Intel386 CPU-based systems with an Intel387 math coprocessor when the Intel386 CPU detects a page or segment violation while transferring the middle portion of an Intel387 math coprocessor operand. This interrupt is generated neither by the Pentium processor nor by the Intel486 processor; interrupt 13 occurs instead.

#### **14.9.10. Interrupt 10—Invalid TSS**

An invalid-TSS fault is generated if a task switch to a segment with an invalid TSS is attempted. A TSS is invalid in the cases shown in Table 14-5. An error code is pushed onto the stack of the exception handler to help identify the cause of the fault. The EXT bit indicates whether the exception was caused by a condition outside the control of the program (e.g., if an external interrupt using a task gate attempted a task switch to an invalid TSS).



**Table 14-5. Invalid TSS Conditions**

Error Code Index	Description
TSS segment	TSS segment limit less than 67H
LDT segment	Invalid LDT or LDT not present
Stack segment	Stack segment selector exceeds descriptor table limit
Stack segment	Stack segment is not writable
Stack segment	Stack segment DPL not compatible with CPL
Stack segment	Stack segment selector RPL not compatible with CPL
Code segment	Code segment selector exceeds descriptor table limit
Code segment	Code segment is not executable
Code segment	Non-conforming code segment DPL not equal to CPL
Code segment	Conforming code segment DPL greater than CPL
Data segment	Data segment selector exceeds descriptor table limit
Data segment	Data segment not readable

This fault can occur either in the context of the original task or in the context of the new task. Until the processor has completely verified the presence of the new TSS, the exception occurs in the context of the original task. Once the existence of the new TSS is verified, the task switch is considered complete; i.e., the TR register is loaded with a selector for the new TSS and, if the switch is due to a CALL or interrupt, the Link field of the new TSS references the old TSS. Any errors discovered by the processor after this point are handled in the context of the new task.

To ensure a TSS is available to process the exception, the handler for an invalid-TSS exception must be a task called using a task gate.

### 14.9.11. Interrupt 11—Segment Not Present

The segment-not-present fault is generated when the processor detects that the present bit of a descriptor is clear. The processor can generate this fault in any of these cases:

- While attempting to load the CS, DS, ES, FS, or GS registers; loading the SS register, however, causes a stack fault.
- While attempting to load the LDT register using an LLDT instruction; loading the LDT register during a task switch operation, however, causes an invalid-TSS exception.
- While attempting to use a gate descriptor which is marked segment-not-present.

This fault is restartable. If the exception handler loads the segment and returns, the interrupted program resumes execution.

If a segment-not-present exception occurs during a task switch, not all the steps of the task switch are complete. During a task switch, the processor first loads all the segment registers, then checks their contents for validity. If a segment-not-present exception is discovered, the remaining segment registers have not been checked and therefore may not be usable for referencing memory. The segment-not-present handler should not rely on being able to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. The exception handler should check all segment registers before trying to resume the new task; otherwise, general protection faults may result later under conditions which make diagnosis more difficult. There are three ways to handle this case:

1. Handle the segment-not-present fault with a task. The task switch back to the interrupted task causes the processor to check the registers as it loads them from the TSS.
2. Use the PUSH and POP instructions on all segment registers. Each POP instruction causes the processor to check the new contents of the segment register.
3. Check the saved contents of each segment register in the TSS, simulating the test which the processor makes when it loads a segment register.

This exception pushes an error code onto the stack. The EXT bit of the error code is set if an event external to the program caused an interrupt which subsequently referenced a not-present segment. The IDT bit is set if the error code refers to an IDT entry (e.g., an INT instruction referencing a not-present gate).

An operating system typically uses the segment-not-present exception to implement virtual memory at the segment level. A not-present indication in a gate descriptor, however, usually does not indicate that a segment is not present (because gates do not necessarily correspond to segments). Not-present gates may be used by an operating system to trigger exceptions of special significance to the operating system.

### 14.9.12. Interrupt 12—Stack Exception

A stack fault is generated under two conditions:

- As a result of a limit violation in any operation which refers to the SS register. This includes stack-oriented instructions such as POP, PUSH, ENTER, and LEAVE, as well as other memory references which implicitly or explicitly use the SS register (for example, MOV AX, [BP+6] or MOV AX, SS:[EAX+6]). The ENTER instruction generates this exception when there is too little space for allocating local variables.
- When attempting to load the SS register with a descriptor which is marked segment-not-present but is otherwise valid. This can occur in a task switch, a CALL instruction to a different privilege level, a return to a different privilege level, an LSS instruction, or a MOV or POP instruction to the SS register.

When the processor detects a stack exception, it pushes an error code onto the stack of the exception handler. If the exception is due to a not-present stack segment or to overflow of the new stack during an interlevel CALL, the error code contains a selector to the segment which



caused the exception (the exception handler can test the present bit in the descriptor to determine which exception occurred); otherwise, the error code is 0.

An instruction generating this fault is restartable in all cases. The return address pushed onto the exception handler's stack points to the instruction which needs to be restarted. This instruction usually is the one which caused the exception; however, in the case of a stack exception from loading a not-present stack-segment descriptor during a task switch, the indicated instruction is the first instruction of the new task.

When a stack exception occurs during a task switch, the segment registers may not be usable for addressing memory. During a task switch, the selector values are loaded before the descriptors are checked. If a stack exception is generated, the remaining segment registers have not been checked and may cause exceptions if they are used. The stack fault handler should not expect to use the segment selectors found in the CS, SS, DS, ES, FS, and GS registers without causing another exception. The exception handler should check all segment registers before trying to resume the new task; otherwise, general protection faults may result later under conditions where diagnosis is more difficult.

### 14.9.13. Interrupt 13—General Protection

All protection violations which do not cause another exception cause a general-protection exception. This includes (but is not limited to):

- Exceeding the segment limit when using the CS, DS, ES, FS, or GS segments.
- Exceeding the segment limit when referencing a descriptor table.
- Transferring execution to a segment which is not executable.
- Writing to a read-only data segment or a code segment.
- Reading from an execute-only code segment.
- Loading the SS register with a selector for a read-only segment (unless the selector comes from a TSS during a task switch, in which case an invalid-TSS exception occurs).
- Loading the SS, DS, ES, FS, or GS register with a selector for a system segment.
- Loading the DS, ES, FS, or GS register with a selector for an execute-only code segment.
- Loading the SS register with the selector of an executable segment.
- Accessing memory using the DS, ES, FS, or GS register when it contains a null selector.
- Switching to a busy task.
- Violating privilege rules.
- Exceeding the instruction length limit of 15 bytes (this only can occur when redundant prefixes are placed before an instruction).
- Loading the CR0 register with a set PG bit (paging enabled) and a clear PE bit (protection disabled).

- Interrupt or exception through an interrupt or trap gate from virtual-8086 mode to a handler at a privilege level other than 0.
- Attempting to write a one into a reserved bit of CR4.

The general-protection exception is a fault. In response to a general-protection exception, the processor pushes an error code onto the exception handler's stack. If loading a descriptor causes the exception, the error code contains a selector to the descriptor; otherwise, the error code is null. The source of the selector in an error code may be any of the following:

- An operand of the instruction.
- A selector from a gate which is the operand of the instruction.
- A selector from a TSS involved in a task switch.

#### 14.9.14. Interrupt 14—Page Fault

A page fault occurs when paging is enabled (the PG bit in the CR0 register is set) and the processor detects one of the following conditions while translating a linear address to a physical address:

- The page-directory or page-table entry needed for the address translation has a clear Present bit, which indicates that a page table or the page containing the operand is not present in physical memory.
- The procedure does not have sufficient privilege to access the indicated page.

If a page fault is caused by a page level protection violation, the access bits in the page-directory are set when the faults occur. The access bit in the page table is only set if there are no page level protection violations.

The processor provides the page fault handler two items of information which aid in diagnosing the exception and recovering from it:

- An error code on the stack. The error code for a page fault has a format different from that for other exceptions (see Figure 14-7). The error code tells the exception handler three things:
  - a. Whether the exception was due to a not-present page, to an access rights violation, or to use of a reserved bit.
  - b. Whether the processor was executing at user or supervisor level at the time of the exception.
  - c. Whether the memory access which caused the exception was a read or write.
- The contents of the CR2 register. The processor loads the CR2 register with the 32-bit linear address which generated the exception. The exception handler can use this address to locate the corresponding page directory and page table entries. If another page fault occurs during execution of the page fault handler, the handler will push the contents of the CR2 register onto the stack.



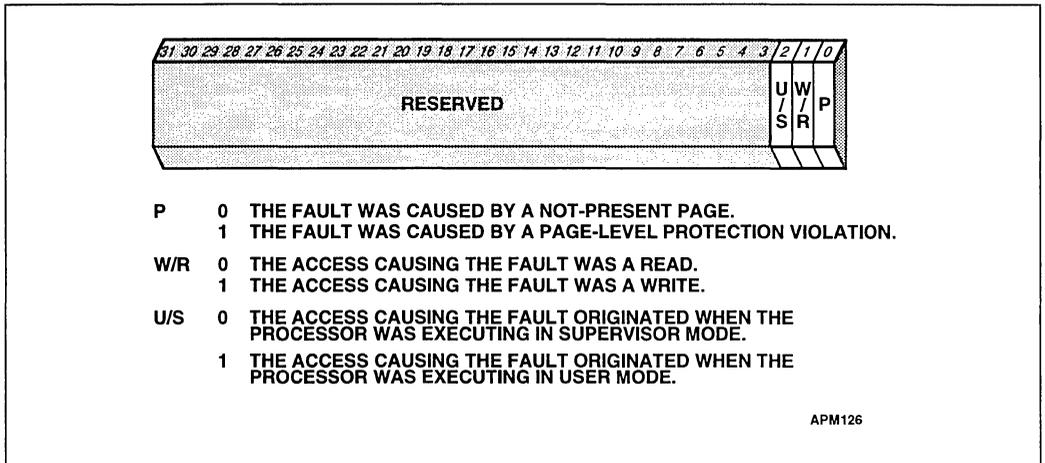


Figure 14-7. Page Fault Error Code

#### 14.9.14.1. PAGE FAULT DURING TASK SWITCH

These operations during a task switch cause access to memory:

1. Write the state of the original task in the TSS of that task.
2. Read the GDT to locate the TSS descriptor of the new task.
3. Read the TSS of the new task to check the types of segment descriptors from the TSS.
4. May read the LDT of the new task in order to verify the segment registers stored in the new TSS.

A page fault can result from accessing any of these operations. In the last two cases the exception occurs in the context of the new task. The instruction pointer refers to the next instruction of the new task, not to the instruction which caused the task switch (or the last instruction to be executed, in the case of an interrupt). If the design of the operating system permits page faults to occur during task-switches, the page-fault handler should be called through a task gate.

#### 14.9.14.2. PAGE FAULT WITH INCONSISTENT STACK POINTER

Special care should be taken to ensure that a page fault does not cause the processor to use an invalid stack pointer (SS:ESP). Software written for Intel 16-bit processors often uses a pair of instructions to change to a new stack; for example:

```
MOV SS, AX
MOV SP, StackTop
```

With the 32-bit processors, because the second instruction accesses memory, it is possible to get a page fault after the selector in the SS segment register has been changed but before the

contents of the SP register have received the corresponding change. At this point, the two parts of the stack pointer SS:SP (or, for 32-bit programs, SS:ESP) are inconsistent. The new stack segment is being used with the old stack pointer.

The processor does not use the inconsistent stack pointer if the handling of the page fault causes a stack switch to a well defined stack (i.e., the handler is a task or a more privileged procedure). However, if the page fault occurs at the same privilege level and in the same task as the page fault handler, the processor will attempt to use the stack indicated by the inconsistent stack pointer.

In systems which use paging and handle page faults within the faulting task (with trap or interrupt gates), software executing at the same privilege level as the page fault handler should initialize a new stack by using the LSS instruction rather than an instruction pair shown above. When the page fault handler is running at privilege level 0 (the normal case), the problem is limited to programs which run at privilege level 0, typically the kernel of the operating system.

### 14.9.15. Interrupt 16—Floating-Point Error

A floating-point-error fault signals an error generated by a floating-point arithmetic instruction. Interrupt 16 can occur only if the NE bit in the CR0 register is set. Numeric processing exceptions have already been introduced previously in Chapter 7.

If NE = 1, an unmasked floating-point exception results in interrupt 16, immediately before the execution of the next non-control floating-point or WAIT instruction. Interrupt 16 is an operating-system call that invokes the exception handler. Chapter 14 contains a general discussion of exceptions and interrupts.

If NE = 0 (and the IGNNE# input is inactive), an unmasked floating-point exception causes the processor to freeze immediately before executing the next non-control floating-point or WAIT instruction. The frozen processor waits for an external interrupt, which must be supplied by external hardware in response to the FERR# output of the Intel486 or Pentium processors (the FERR# is similar to the ERROR# pin of the Intel387 math coprocessor). Regardless of the value of NE, an unmasked numerical exception causes the FERR# output of the Intel486 and Pentium processors to be activated. In this case, the external interrupt invokes the exception-handling routine. If NE = 0 but the IGNNE# input is active, the processor disregards the exception and continues. Error reporting via external interrupt is supported for DOS compatibility. Chapter 23 contains further discussion of compatibility issues.

When handling numeric errors, the processor has two responsibilities:

- It must not disturb the numeric context when an error is detected.
- It must clear the error and attempt recovery from the error.

Although the manner in which programmers may treat these responsibilities varies from one implementation to the next, most exception handlers will include these basic steps:



- Store the FPU environment (control, status, and tag words, operand and instruction pointers) as it existed at the time of the exception.
- Clear the exception bits in the status word.
- Enable interrupts if disabled due to an INTR, NMI, or SMI exception.
- Identify the exception by examining the status and control words in the saved environment.
- Take some system-dependent action to rectify the exception.
- Return to the interrupted program and resume normal execution.

#### 14.9.15.1. NUMERICS EXCEPTION HANDLING

Recovery routines for numeric exceptions can take a variety of forms. They can change the arithmetic and programming rules of the FPU. These changes may redefine the default fix-up for an error, change the appearance of the FPU to the programmer, or change how arithmetic is defined on the FPU.

A change to an exception response might be to perform denormal arithmetic on denormals loaded from memory. A change in appearance might be extending the register stack into memory to provide an "infinite" number of numeric registers. The arithmetic of the FPU can be changed to automatically extend the precision and range of variables when exceeded. All these functions can be implemented on the processor via numeric exceptions and associated recovery routines in a manner transparent to the application programmer.

Some other possible application-dependent actions might include:

- Incrementing an exception counter for later display or printing
- Printing or displaying diagnostic information (e.g., the FPU environment and registers)
- Aborting further execution
- Storing a diagnostic value (a NaN) in the result and continuing with the computation

Notice that an exception may or may not constitute an error, depending on the application. Once the exception handler corrects the condition causing the exception, the floating-point instruction that caused the exception can be restarted, if appropriate. This cannot be accomplished using the IRET instruction, however, because the trap occurs at the ESC or WAIT instruction following the offending ESC instruction. The exception handler must obtain (using FSAVE or FSTENV) the address of the offending instruction in the task that initiated it, make a copy of it, execute the copy in the context of the offending task, and then return via IRET to the current instruction stream.

In order to correct the condition causing the numeric exception, exception handlers must recognize the precise state of the FPU at the time the exception handler was invoked, and be able to reconstruct the state of the FPU when the exception initially occurred. To reconstruct the state of the FPU, programmers must understand that different classes of exceptions are recognized at different times (before or after) execution of a numeric instruction.

Invalid operation, zero divide, and denormal operand exceptions are detected before an operation begins, whereas overflow, underflow, and precision exceptions are not raised until a true result has been computed. When a *before* exception is detected, the FPU register stack and memory have not yet been updated, and appear as if the offending instructions has not been executed.

When an *after* exception is detected, the register stack and memory appear as if the instruction has run to completion; i.e., they may be updated. (However, in a store or store-and-pop operation, unmasked over/underflow is handled like a *before* exception; memory is not updated and the stack is not popped.) The following programming examples include an outline of several exception handlers to process numeric exceptions.

#### 14.9.15.2. SIMULTANEOUS EXCEPTION RESPONSE

In cases where multiple exceptions arise simultaneously, the FPU signals one exception according to the precedence list below. This means, for example, that an SNaN divided by zero results in an invalid operation, not in a zero-divide exception; the masked result is the QNaN *real indefinite*, not  $\infty$ . A denormal or inexact (precision) exception, however, can accompany a numeric underflow or overflow exception.

The precedence among numeric exceptions is as follows:

1. Invalid operation exception, subdivided as follows:
  - Stack underflow.
  - Stack overflow.
  - Operand of unsupported format.
  - SNaN operand.
2. QNaN operand. Though this is not an exception, if one operand is a QNaN, dealing with it has precedence over lower-priority exceptions. For example, a QNaN divided by zero results in a QNaN, not a zero-divide exception.
3. Any other invalid-operation exception not mentioned above or zero divide.
4. Denormal operand. If masked, then instruction execution continues, and a lower-priority exception can occur as well.
5. Numeric overflow and underflow. Inexact result (precision) can be flagged as well.
6. Inexact result (precision).



### 14.9.16. Interrupt 17—Alignment Check

An alignment-check fault can be generated for access to unaligned operands. For example, a word stored at an odd byte address, or a doubleword stored at an address which is not an integer multiple of four. Table 14-6 lists the alignment requirements by data type. To enable alignment checking, the following conditions must be true:

- AM bit in the CR0 register is set
- AC flag is set
- CPL is 3 (user mode)

**Table 14-6. Alignment Requirements by Data Type**

Data Type	Address Must Be Divisible By
WORD	2
DWORD	4
Short REAL	4
Long REAL	8
TEMPREAL	8
Selector	2
48-bit Segmented Pointer	4
32-bit Flat Pointer	4
32-bit Segmented Pointer	2
48-bit "Pseudo-Descriptor"	4
FSTENV/FLDENV save area	4 or 2, depending on operand size
FSAVE/FRSTOR save area	4 or 2, depending on operand size
Bit String	4

Alignment checking is useful for programs which use the low two bits of pointers to identify the type of data structure they address. For example, a subroutine in a math library may accept pointers to numeric data structures. If the type of this structure is assigned a code of 10 (binary) in the lowest two bits of pointers to this type, math subroutines can correct for the type code by adding a displacement of -10 (binary). If the subroutine should ever receive the wrong pointer type, an unaligned reference would be produced, which would generate an exception.

Alignment-check faults are generated only in user mode (privilege level 3). Memory references which default to privilege level 0, such as segment descriptor loads, do not generate alignment-check faults, even when caused by a memory reference made in user mode.

Storing a 48-bit pseudo-descriptor (the memory image of the contents of a descriptor table base register) in user mode can generate an alignment-check fault. Although user-mode programs do not normally store pseudo-descriptors, the fault can be avoided by aligning the pseudo-descriptor to an odd word address (i.e., an address which is 2 MOD 4).

FSAVE and FRSTOR instructions generate unaligned references which can cause alignment-check faults. These instructions are rarely needed by application programs.

### **14.9.17. Interrupt 18—Machine Check**

Machine check is a model-specific exception, available only on the Pentium microprocessor. It may or may not be continued with a compatible implementation on future processor generations. Use the CPUID instruction feature flag register to determine the presence of this feature.

## **14.10. EXCEPTION SUMMARY**

Table 14-7 summarizes the exceptions recognized by the Pentium processor.



Table 14-7. Exception Summary

Description	Vector Number	Return Address Points to Faulting Instruction?	Exception Type	Source of the Exception
Division by Zero	0	Yes	FAULT	DIV and IDIV instructions
Debug Exceptions	1	1	1	Any code or data reference
Breakpoint	3	No	TRAP	INT 3 instruction
Overflow	4	No	TRAP	INTO instruction
Bounds Check	5	Yes	FAULT	BOUND instruction
Invalid Opcode	6	Yes	FAULT	Reserved Opcodes
Device Not Available	7	Yes	FAULT	ESC and WAIT instructions
Double Fault	8	Yes	ABORT	Any instruction
Invalid TSS	10	Yes <sup>2</sup>	FAULT	JMP, CALL, IRET instructions, interrupts, and exceptions
Segment Not Present	11	Yes <sup>2</sup>	FAULT	Any instruction which changes segments
Stack Fault	12	Yes	FAULT	Stack operations
General Protection	13	Yes	FAULT/TRAP <sup>3</sup>	Any code or data reference
Page Fault	14	Yes	FAULT	Any code or data reference
Floating-Point Error	16	Yes	FAULT <sup>4</sup>	ESC and WAIT instructions
Alignment Check	17	Yes	FAULT	Any data reference
Machine Check	18	–	–	( <i>model dependent</i> )
Software Interrupt	0 to 255	No	TRAP	INT n instructions

**NOTES:**

1. Debug exceptions are either traps or faults. The exception handler can distinguish between traps and faults by examining the contents of the DR6 register.
2. Restartability is conditional during task switches as documented in section 7.5.
3. All general-protection faults are restartable. If the fault occurs while attempting to call the handler, the interrupted program is restartable, but the interrupt may be lost.
4. Floating-point errors are not reported until the first ESC or WAIT instruction following the ESC instruction which generated the error.

## 14.11. ERROR CODE SUMMARY

Table 14-8 summarizes the error information that is available with each exception.

**Table 14-8. Error Code Summary**

Description	Vector Number	Is an Error Code Generated?
Divide Error	0	No
Debug Exceptions	1	No
Breakpoint	3	No
Overflow	4	No
Bounds Check	5	No
Invalid Opcode	6	No
Device Not Available	7	No
Double Fault	8	Yes (always zero)
Invalid TSS	10	Yes
Segment Not Present	11	Yes
Stack Fault	12	Yes
General Protection	13	Yes
Page Fault	14	Yes (special format)
Floating-Point Error	16	No
Alignment Check	17	Yes (always zero)
Machine Check	18	<i>(model dependent)</i>
Software Interrupt	0–255	No



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**15**

**Input/Output**





## CHAPTER 15 INPUT/OUTPUT

Input/output is accomplished through I/O ports, which are registers connected to peripheral devices. An I/O port can be an input port, an output port, or a bidirectional port. Some I/O ports are used for carrying data, such as the transmit and receive registers of a serial interface. Other I/O ports are used to control peripheral devices, such as the control registers of a disk controller.

The input/output architecture is the programmer's model of how these ports are accessed. The discussion of this model includes:

- Methods of addressing I/O ports.
- Instructions which perform I/O operations.
- The I/O protection mechanism.

### 15.1. I/O ADDRESSING

The processor allows I/O ports to be addressed in either of two ways:

- Through a separate I/O address space accessed using I/O instructions.
- Through memory-mapped I/O, where I/O ports appear in the address space of physical memory.

The use of a separate I/O address space is supported by special instructions and a hardware protection mechanism. When memory-mapped I/O is used, the general-purpose instruction set can be used to access I/O ports, and protection is provided using segmentation or paging. Some system designers may prefer to use the I/O facilities built into the processor, while others may prefer the simplicity of a single physical address space.

Hardware designers use these ways of mapping I/O ports into the address space when they design the address decoding circuits of a system. I/O ports can be mapped so that they appear in the I/O address space or the address space of physical memory (or both).

#### 15.1.1. I/O Address Space

The processor provides a separate I/O address space, distinct from the address space for physical memory, where I/O ports can be placed. The I/O address space consists of  $2^{16}$  (64K) individually addressable 8-bit ports; any two consecutive 8-bit ports can be treated as a 16-bit port, and any four consecutive ports can be a 32-bit port. Extra bus cycles are required if a port crosses the boundary between two doublewords in physical memory.

The M/IO# pin of the processor indicates when a bus cycle to the I/O address space occurs. When a separate I/O address space is used, it is the responsibility of the hardware designer to make use of this signal to select I/O ports rather than memory. In fact, the use of the separate I/O address space simplifies the hardware design because these ports can be selected by a single signal; unlike other processors, it is not necessary to decode a number of upper address lines in order to set up a separate I/O address space.

A program can specify the address of a port in two ways. With an immediate byte constant, the program can specify:

- 256 8-bit ports numbered 0 through 255.
- 128 16-bit ports numbered 0, 2, 4, . . . , 252, 254.
- 64 32-bit ports numbered 0, 4, 8, . . . , 248, 252.

Using a value in the DX register, the program can specify:

- 8-bit ports numbered 0 through 65535.
- 16-bit ports numbered 0, 2, 4, . . . , 65532, 65534.
- 32-bit ports numbered 0, 4, 8, . . . , 65528, 65532.

The processor can transfer 8, 16, or 32 bits to a device in the I/O space. Like words in memory, 16-bit ports should be aligned to even addresses so that all 16 bits can be transferred in a single bus cycle. Like doublewords in memory, 32-bit ports should be aligned to addresses which are multiples of four. The processor supports data transfers to unaligned ports, but there is a performance penalty because an extra bus cycle must be used.

The IN and OUT instructions move data between a register and a port in the I/O address space. The instructions INS and OUTS move strings of data between the memory address space and ports in the I/O address space.

I/O port addresses 0F8H through 0FFH are reserved for use by Intel Corporation. Do not assign I/O ports to these addresses.

The exact order of bus cycles used to access ports which require more than one bus cycle is undefined and is not guaranteed to remain the same in future Intel products. If software needs to produce a particular order of bus cycles, this order must be specified explicitly. For example, to load a word-length port at 4H followed by loading a word port at 2H, two word-length instructions must be used, rather than a single doubleword instruction at 2H.

Note that, although the processor automatically masks parity errors for certain types of bus cycles, such as interrupt acknowledge cycles, it does not mask parity for bus cycles to the I/O address space. Programmers may need to be aware of this behavior as a possible source of parity errors.

### 15.1.2. Memory-Mapped I/O

I/O devices may be placed in the address space for physical memory. This is called memory-mapped I/O. As long as the devices respond like memory components, they can be used with memory-mapped I/O.

Memory-mapped I/O provides additional programming flexibility. Any instruction which references memory may be used to access an I/O port located in the memory space. For example, the MOV instruction can transfer data between any register and a port. The AND, OR, and TEST instructions may be used to manipulate bits in the control and status registers of peripheral devices (see Figure 15-1). Memory-mapped I/O can use the full instruction set and the full complement of addressing modes to address I/O ports.

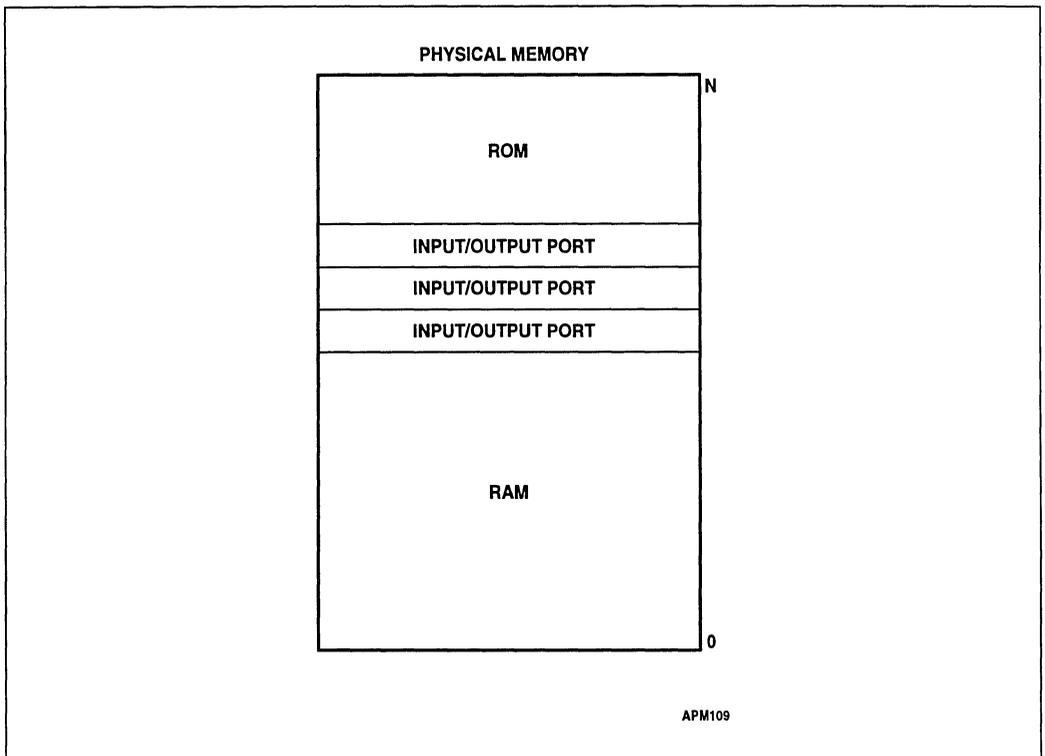


Figure 15-1. Memory-Mapped I/O

Using an I/O instruction for an I/O write can also be advantageous because it guarantees that the write will be completed before the next instruction begins execution. If I/O writes are used to control system hardware, then this sequence of events is desirable, since it guarantees that the next instruction will be executed in the new system hardware state. Refer to Section 15.4 for more information on serialization of I/O operations.

If caching is enabled in real-address mode, designers should consider if it is advantageous to prevent caching of I/O data, whether by using the PCD bit of page table entries or by using the KEN# signal.

## 15.2. I/O INSTRUCTIONS

The I/O instructions provide access to the processor's I/O ports for the transfer of data. These instructions have the address of a port in the I/O address space as an operand. There are two kinds of I/O instructions:

1. Those which transfer a single item (byte, word, or doubleword) to or from a register.
2. Those which transfer strings of items (strings of bytes, words, or doublewords) located in memory. These are known as "string I/O instructions" or "block I/O instructions."

These instructions cause the M/IO# signal to be driven low (logic 0) during a bus cycle, which indicates to external hardware that access to the I/O address space is taking place.

### 15.2.1. Register I/O Instructions

The I/O instructions IN and OUT move data between I/O ports and the EAX register (32-bit I/O), the AX register (16-bit I/O), or the AL (8-bit I/O) register. The IN and OUT instructions address I/O ports either directly, with the address of one of 256 port addresses coded in the instruction, or indirectly using an address in the DX register to select one of 64K port addresses.

**IN (Input from Port)** transfers a byte, word, or doubleword from an input port to the AL, AX, or EAX registers. A byte IN instruction transfers 8 bits from the selected port to the AL register. A word IN instruction transfers 16 bits from the port to the AX register. A doubleword IN instruction transfers 32 bits from the port to the EAX register.

**OUT (Output from Port)** transfers a byte, word, or doubleword from the AL, AX, or EAX registers to an output port. A byte OUT instruction transfers 8 bits from the AL register to the selected port. A word OUT instruction transfers 16 bits from the AX register to the port. A doubleword OUT instruction transfers 32 bits from the EAX register to the port.

### 15.2.2. Block I/O Instructions

The INS and OUTS instructions move blocks of data between I/O ports and memory. Block I/O instructions use an address in the DX register to address a port in the I/O address space. These instructions use the DX register to specify:

- 8-bit ports numbered 0 through 65535.
- 16-bit ports numbered 0, 2, 4, . . . , 65532, 65534.
- 32-bit ports numbered 0, 4, 8, . . . , 65528, 65532.



Block I/O instructions use either the (E)SI or (E)DI register to address memory. For each transfer, the (E)SI or (E)DI register is incremented or decremented, as specified by the DF flag.

The INS and OUTS instructions, when used with repeat prefixes, perform block input or output operations. The repeat prefix REP modifies the INS and OUTS instructions to transfer blocks of data between an I/O port and memory. These block I/O instructions are string instructions (see Chapter 3 for more on string instructions). They simplify programming and increase the speed of data transfer by eliminating the need to use a separate LOOP instruction or an intermediate register to hold the data.

The string I/O instructions operate on byte strings, word strings, or doubleword strings. After each transfer, the memory address in the ESI or EDI registers is incremented or decremented by 1 for byte operands, by 2 for word operands, or by 4 for doubleword operands. The DF flag controls whether the register is incremented (the DF flag is clear) or decremented (the DF flag is set).

**INS (Input String from Port)** transfers a byte, word, or doubleword string element from an input port to memory. The INSB instruction transfers a byte from the selected port to the memory location addressed by the ES and EDI registers. The INSW instruction transfers a word. The INSD instruction transfers a doubleword. A segment override prefix cannot be used to specify an alternate destination segment. Combined with a REP prefix, an INS instruction makes repeated read cycles to the port, and puts the data into consecutive locations in memory.

**OUTS (Output String from Port)** transfers a byte, word, or doubleword string element from memory to an output port. The OUTSB instruction transfers a byte from the memory location addressed by the DS and ESI registers to the selected port. The OUTSW instruction transfers a word. The OUTSD instruction transfers a doubleword. A segment override prefix can be used to specify an alternate source segment. Combined with a REP prefix, an OUTS instruction reads consecutive locations in memory, and writes the data to an output port.

### 15.3. PROTECTED-MODE I/O

When the processor is running in protected mode, I/O operates as in real-address mode, but with additional protection features:

- References to memory-mapped I/O ports, like any other memory reference, are subject to access protection and control by both the segmentation and the paging mechanism. Refer to Chapter 12 for a complete discussion of memory protection.
- The execution of I/O instructions is also subject to two protection mechanisms:
  - a. The IOPL field in the EFLAGS register controls access to the I/O instructions.
  - b. The I/O permission bit map of a TSS segment controls access to individual ports in the I/O address space.

These protection mechanisms are available only when a separate I/O address space is used.

### 15.3.1. I/O Privilege Level

In systems where I/O protection is used, access to I/O instructions is controlled by the IOPL field in the EFLAGS register. This permits the operating system to adjust the privilege level needed to perform I/O. In a typical protection ring model, privilege levels 0 and 1 have access to the I/O instructions. This lets the operating system and the device drivers perform I/O, but keeps applications and less privileged device drivers from accessing the I/O address space. Applications access I/O through the operating system.

The following instructions can be executed only if  $CPL \leq IOPL$ :

IN	— Input
INS	— Input String
OUT	— Output
OUTS	— Output String
CLI	— Clear Interrupt-Enable Flag
STI	— Set Interrupt-Enable Flag

These instructions are called "sensitive" instructions, because they are sensitive to the IOPL field. In virtual-8086 mode, the I/O permission bit map further limits access to I/O ports (see Chapter 23).

To use sensitive instructions, a procedure must run at a privilege level at least as privileged as that specified by the IOPL field. Any attempt by a less privileged procedure to use a sensitive instruction results in a general-protection exception. Because each task has its own copy of the EFLAGS register, each task can have a different IOPL.

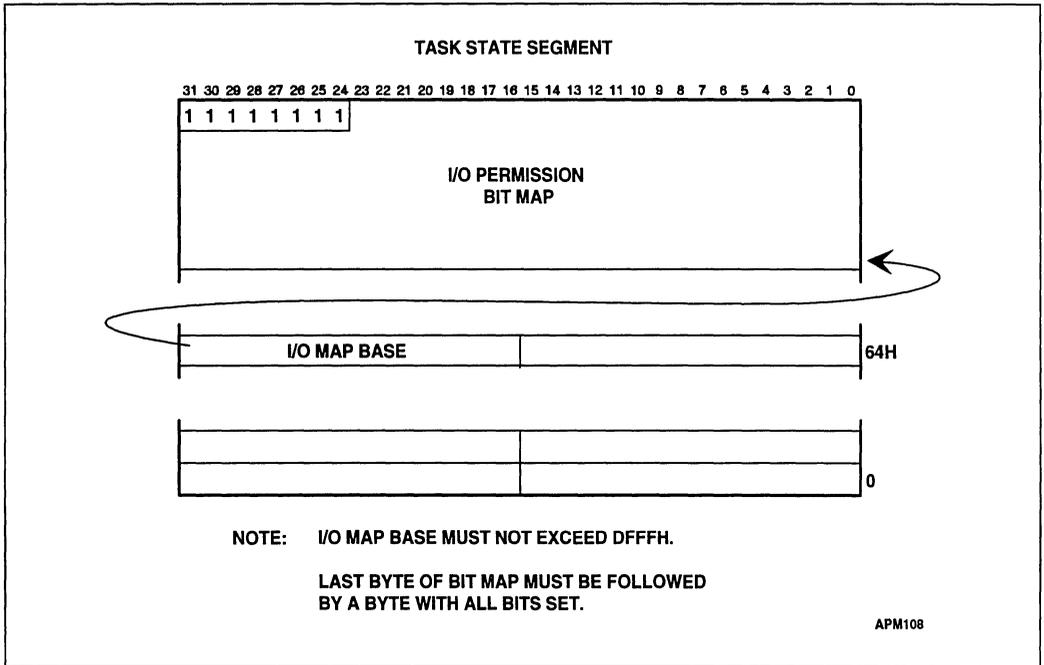
A task can change IOPL only with the POPF and IRET instructions; however, such changes are privileged. No procedure may change its IOPL unless it is running at privilege level 0. An attempt by a less privileged procedure to change the IOPL does not result in an exception; the IOPL simply remains unchanged.

The POPF instruction also may be used to change the state of the IF flag (as can the CLI and STI instructions); however, changes to the IF flag using the POPF instruction are IOPL-sensitive. A procedure may change the setting of the IF flag with a POPF instruction only if it runs with a CPL at least as privileged as the IOPL. An attempt by a less privileged procedure to change the IF flag does not result in an exception; the IF flag simply remains unchanged.

### 15.3.2. I/O Permission Bit Map

The processor can generate exceptions for references to specific I/O addresses. These addresses are specified in the I/O permission bit map in the TSS (see Figure 15-2). The size of the map and its location in the TSS are variable. The processor finds the I/O permission bit map with the I/O map base address in the TSS. The base address is a 16-bit offset into the TSS. This is an offset to the beginning of the bit map. The limit of the TSS is the limit on the size of the I/O permission bit map.





**Figure 15-2. I/O Permission Bit Map**

Because each task has its own TSS, each task has its own I/O permission bit map. Access to individual I/O ports can be granted to individual tasks.

If  $CPL \leq IOPL$  in protected mode, then the processor allows I/O operations to proceed. If  $CPL > IOPL$ , or if the processor is operating in virtual 8086 mode, then the processor checks the I/O permission map. Each bit in the map corresponds to an I/O port byte address; for example, the control bit for address 41 (decimal) in the I/O address space is found at bit position 1 of the sixth byte in the bit map. The processor tests all the bits corresponding to the I/O port being addressed; for example, a doubleword operation tests four bits corresponding to four adjacent byte addresses. If any tested bit is set, a general-protection exception is generated. If all tested bits are clear, the I/O operation proceeds.

Because I/O port addresses are not necessarily aligned to word and doubleword boundaries, it is possible that the processor may need to access two bytes in the bit map when I/O permission is checked. For maximum speed, the processor has been designed to read two bytes for every access to an I/O port. To prevent exceptions from being generated when the ports with the highest addresses are accessed, an extra byte needs to come after the table. This byte must have all of its bits set, and it must be within the segment limit.

It is not necessary for the I/O permission bit map to represent all the I/O addresses. I/O addresses not spanned by the map are treated as if they had set bits in the map. For example, if the TSS segment limit is 10 bytes past the bit map base address, the map has 11 bytes and

the first 80 I/O ports are mapped. Higher addresses in the I/O address space generate exceptions.

If the I/O bit map base address is greater than or equal to the TSS segment limit, there is no I/O permission map, and all I/O instructions generate exceptions. The base address must be less than or equal to 0DFFFH.

### 15.3.3. Paging and Caching

In protected mode, the paging mechanism can also help control cacheability of I/O buffers and memory-mapped I/O addresses. If caching is enabled, either external hardware or the paging mechanism (the PCD bit in the page table entry) must be used to prevent caching of I/O data.

The operating system can also use the segmentation or paging mechanism to manage the data space used by the operands of I/O instructions. The AVL (available) fields in segment descriptors or page table entries can be used by the operating system to mark pages containing I/O buffers as unrelocatable and unswappable.

## 15.4. ORDERING OF I/O

When controlling I/O devices it is often important that memory and I/O operations be carried out in precisely the order programmed. For example, a program may write a command to an I/O port, then read the status of the I/O device from another I/O port. It is important that the status returned be the status of the device *after* it receives the command, not *before*. Programmers should take care, because there are situations in which the programmed order is not preserved by the processor.

To optimize performance, the Pentium CPU allows memory reads to be reordered ahead of buffered writes in most situations. Internally, CPU reads (cache hits) can be reordered around buffered writes. Memory reordering does not occur externally at the pins, reads (cache miss) and writes appear in-order. The Intel486 CPU allows memory reads to be reordered ahead of buffered writes in certain precisely-defined circumstances. (See the *Intel486™ Microprocessor Hardware Reference Manual* for further details about the operation of the write buffer.) Using memory-mapped I/O, therefore, creates the possibility that an I/O read might be performed before the memory write of a previous instruction. To eliminate this possibility on the Intel486 CPU, use an I/O instruction for the read. To eliminate this possibility on the Pentium processor, insert one of the serializing instructions, such as CPUID, between operations.

When I/O instructions are used instead of memory-mapped I/O, the situation is different in two respects:

1. Some I/O writes are never buffered. The only I/O writes that the Intel486 CPU buffers are those from the OUTS instruction. The Pentium processor does not buffer any I/O writes. Therefore, strict ordering of I/O operations is enforced by the processor.

2. The processor synchronizes I/O instruction execution with external bus activity. Refer to Table 15-1.

**Table 15-1. I/O Serialization**

Current Instruction	Processor Holds Execution of ...		Awaiting for Completion of ...	
	Current Instruction?	Next Instruction?	Pending Stores?	Current Store?
IN	Yes		Yes	
INS	Yes		Yes	
REP INS	Yes		Yes	
OUT		Yes	Yes	Yes
OUTS		Yes	Yes	Yes
REP OUTS		Yes	Yes	Yes

Refer to Chapter 13 for more general information on memory access ordering and to Chapter 18 for information about other serializing instructions.





# 16

## **Initialization and Mode Switching**





# CHAPTER 16

## INITIALIZATION AND MODE SWITCHING

The processor is initialized to a known state following hardware reset in order for software execution to begin. When initialized, the processor provides model and stepping information to determine what features are available to software. For feature determination by applications at run-time, a code example and discussion is provided in Chapter 5. This chapter provides processor initialization state information and configuration requirements for both real-address and protected mode. This chapter also discusses the process of switching between real-address and protected modes which is normally part of the initialization process. A program example for switching to protected mode is provided.

The floating-point units (FPU's) of the Intel architectures (except the Intel287 math coprocessor NPX) operate the same regardless of whether the processor is operating in real-address mode, in protected mode, or in virtual 8086 mode.

To the numerics programmer, the operating mode affects only the manner in which the FPU instruction and data pointers are represented in memory following an FSAVE or FSTENV instruction. Each of these instructions produces one of four formats depending on both the operating mode and on the operand-size attribute in effect for the instruction. The differences are detailed in the discussion of the FSAVE and FSTENV instructions in Chapter 25.

### 16.1. PROCESSOR INITIALIZATION

The processor has an input, called the RESET pin, which invokes reset initialization. After RESET is asserted, some registers of the processor are set to known states. These known states, such as the contents of the EIP register, are sufficient to allow software to begin execution. Software then can build the data structures in memory, such as the GDT and IDT tables, which are used by system and application software. The internal caches, translation lookaside buffers (TLB's) and the branch target buffers (BTB's) are invalidated when RESET is asserted.

Hardware asserts the RESET signal at power-up. Hardware may assert this signal at other times. For example, a button may be provided for manually invoking reset initialization. Reset also may be the response of hardware to receiving a halt or shutdown indication.

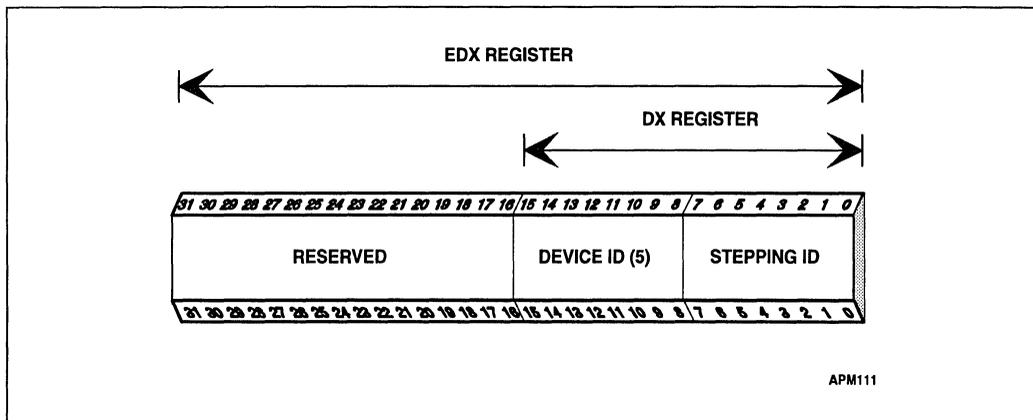
The Pentium processor also has an INIT input, which is similar to RESET except it does not disturb the internal caches, model specific registers, or floating point state. INIT provides a method for switching from protected to real-address mode while maintaining the contents of the internal caches. The TLB's and BTB are invalidated by INIT being asserted.

### 16.1.1. Processor State after Reset

A self test may be requested at power-up. It is the responsibility of the hardware designer to provide the request for self test, if desired. If the self test is selected, it takes about  $2^{19}$  clock periods to complete. (This clock count is model-specific and Intel reserves the right to change the exact number of periods without notification.)

The EAX register is clear (zero) if the processor passed the test. A non-zero value in the EAX register after self test indicates the processor is faulty. If the self test is not requested, the contents of the EAX register after reset initialization is zero.

The EDX register holds a component identifier and revision number after reset initialization, as shown in Figure 16-1. The DH register contains the value 3, 4, or 5 to indicate an Intel386 CPU, Intel486 CPU, or Pentium processor, respectively. Different values may be returned for the various proliferations of these families, for example the Intel386 SX CPU contains 23H. Binary object code can be made compatible with other Intel processors by using this number to select the correct initialization software. The DL register contains a unique identifier of the revision level. The upper word of EDX is reserved following reset.



**Figure 16-1. Contents of the EDX Register after Reset**

The state of the CR0 register for the Pentium processor following power-up is shown in Figure 16-2 (60000010H). This state puts the processor into real-address mode with paging disabled. The state of the flags and other registers following power-up is shown in Table 16-1.

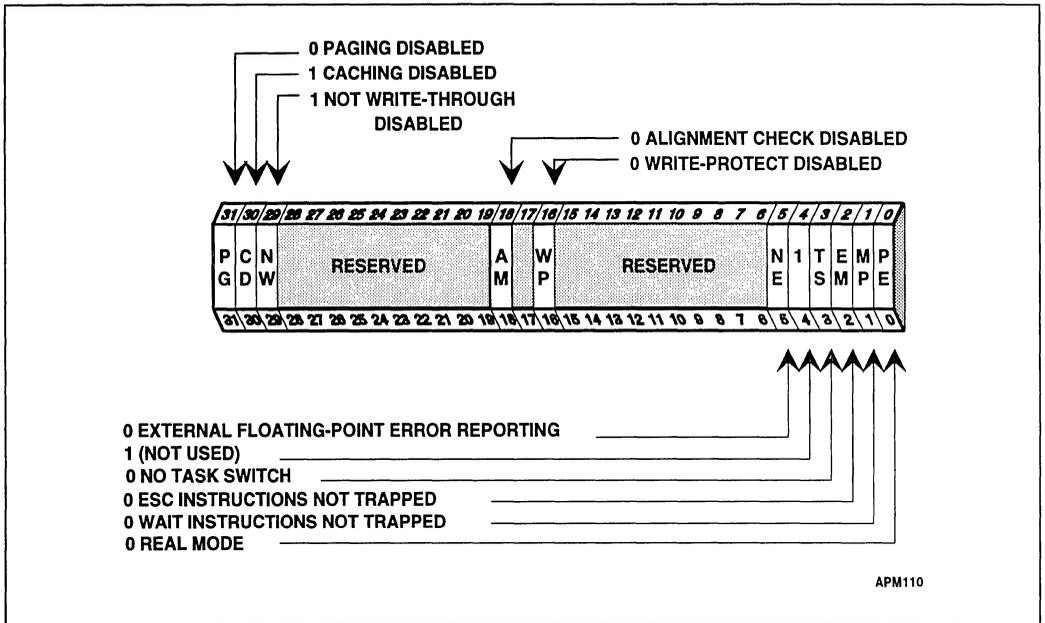


Figure 16-2. Contents of CR0 Register after Reset

Table 16-1. Processor State Following Reset

Register	RESET Without BIST	INIT
EFLAGS <sup>1</sup>	00000002H	00000002H
EIP	0000FFF0H	0000FFF0H
CR0	60000010H	Note 2
CR2/CR3/CR4	00000000H	00000000H
CS	selector=0F000H base=0FFFF000H limit=0FFFFH AR=Present, Read/Write,Accessed	selector=0F000H base=0FFFF000H limit=0FFFFH AR=Present, Read/Write, Accessed
SS, DS, ES, FS, GS	selector=0000 base=0000H limit=0FFFFH AR=Present, Read/Write, Accessed	selector=0000 base=0000H limit=0FFFFH AR=Present, Read/Write, Accessed
EDX	000005xxH	000005xxH
EAX	0 <sup>3</sup>	0
EBX, ECX, ESI, EDI, EBP, ESP	00000000H	00000000H
LDTR	selector=0000H base=00000000H limit=0FFFFH AR=Present,Read/Write	selector=0000H base=00000000H limit=0FFFFH AR=Present,Read/Write
GDTR,IDTR	base=00000000H limit=0FFFFH AR=Present,Read/Write	base=00000000H limit=0FFFFH AR=Present,Read/Write
DR0, DR1, DR2, DR3	00000000H	00000000H
DR6	FFF0FF0H	FFF0FF0H
DR7	00000400H	00000400H
Time Stamp Counter	0	Unchanged
Control and Event Select	0	Unchanged
TR12	0	Unchanged
All Other Model Specific Registers (MSR's)	Undefined	Unchanged
Data and Code Cache, TLB's	Invalid	Invalid

**NOTES:**

1. The high ten bits of the EFLAGS register are undefined following power-up. Undefined bits are reserved. Software should not depend on the states of any of these bits.
2. CD and NW are unchanged, bit 4 is set to 1, all other bits are cleared.
3. If Built-In Self Test is invoked, EAX is 0 only if all tests passed.

### 16.1.2. First Instruction Executed

To generate an address, the base part of a segment register is added to the effective address to form the linear address. This is true for all modes of operation, although the base address is calculated differently in protected and real-address modes. To fetch an instruction, the base portion of the CS register is added to EIP to form a linear address (see Chapter 9 and Chapter 11 for details on calculating addresses).

In real-address mode, when the value of the segment register selector is changed, the base portion will automatically be changed to this value multiplied by 16. However, immediately after reset, the base portion of the CS register behaves differently: It is not 16 times the selector value. Instead, the CS selector is 0F000H and the CS base is 0FFFF0000H. The first time the CS selector value is changed after reset, it will follow the above rule (base = selector \* 16). As a result, after reset, the first instruction that is being fetched and executed is at physical address: CS.base + EIP = 0FFFFFFF0H. This is the address to locate the EPROM with the initialization code. This address is located 16 bytes below the uppermost address of the physical memory of the Pentium processor.

Ensure that no far jump or far call is executed until the initialization is completed. If the first far jump/call is made during real mode, a new value enters the CS selector (16 bits) and sets the value of the CS base to 20 bits only, i.e., the destination address would be in the address space 0 to 1M. You might want to be sure that you have valid memory and code in this area.

The base address for the data segments are set to the bottom of the physical address space (address 0), where RAM is expected to be.

## 16.2. FPU INITIALIZATION

During system initialization, systems software can determine the absence or presence of a numeric processor extension. Systems software must then initialize the FPU or NPX and set flags in CR0 to reflect the state of the numeric environment. These activities can be quickly and easily performed as part of the overall system initialization. See Chapter 5 for determining the processor type and feature recognition.

A hardware reset leaves the Pentium processor FPU in a state that is different from the state that is obtained by executing the FNINIT instruction as shown in Table 16-2. See Chapter 23 for a complete list of initialization differences between these processors following RESET.

The state of the FPU registers following RESET or INIT is shown in Table 16-2. Following RESET, the Pentium processor FPU contains 0 in ST0-ST7 stack registers with the tags set to zero (01). However, the tags are only visible to the programmer by using the FSAVE/FSTENV instructions. When these instructions are used, they interpret the stack locations as zero, returning tag values of 01. The Pentium processor, in addition, has an INIT pin which, when asserted, causes the processor to reset without altering the FPU state. An FNINIT instruction should be executed after reset.

Initializing the FPU simply means placing the FPU in a known state unaffected by any activity performed earlier. A single FNINIT instruction performs this initialization. All the error masks are set, all registers are tagged empty, TOP is set to zero, and default rounding

and precision controls are set. Table 16-2 shows the state of the FPU following FINIT or FNINIT.

**Table 16-2. FPU State Following FINIT or FNINIT**

Field	Value	Interpretation
Control Word (Infinity Control)* Rounding Control Precision Control Exception Masks	037FH 0 00 00 111111	Affine Round to nearest Extended Exceptions masked
Status Word (Busy) Condition Code Stack Top Exception Summary Stack Flag Exception Flags	0000H 0 0000 000 0 0 000000	— — Register 0 is stack top No exceptions — No exceptions
Tag Word Tags	FFFFH 11	Empty
Registers	Not changed	Not changed
Exception Pointers Instruction Code Instruction Address Operand Address	0 0 0	Cleared Cleared Cleared

\*The Pentium®, Intel486™ and Intel386™ processors do not have infinity control. This value is listed to emphasize that programs written for the Intel287™ math coprocessor may not behave the same on the 32-bit processors if they depend on this bit.

### 16.2.1. Configuring the Numerics Environment

System software must load the appropriate values into the MP, EM, and NE bits of the control register 0 (CR0) to control emulation of floating-point instructions by software, synchronization between the FPU and CPU context, and software or external interrupt handling of floating-point exceptions. These bits are clear on hardware reset of the Pentium processor.

The MP (Monitor coProcessor) bit determines whether WAIT instructions trap when the context of the FPU is different from that of the currently executing task. If MP = 1 and TS = 1, then a WAIT instruction will cause a Device Not Available fault (interrupt vector 7). The MP bit is used on the Intel 286, Intel386 DX, Intel386 SX and Intel486 SX microprocessors to support the use of a WAIT instruction to wait on a device other than a numeric coprocessor. The device reports its status through the BUSY# pin. Generally, the MP bit should be set for processors with integrated FPU and clear in processors without an integrated FPU or numeric processor extension. However, an operating system can choose to save the floating-point context at every context switch, in which case there would be no need to set the MP bit.

The EM (EMulate coprocessor) bit determines whether ESC instructions are executed by the FPU (EM = 0) or trap via interrupt vector 7 to be handled by software (EM = 1). The EM bit is used on CPU/NPX systems so that numeric applications can be run in the absence of an NPX with a software emulator. For normal operation of Intel processors with an integrated FPU, the EM bit should be cleared to 0. The EM bit must be set in the Intel386 DX, Intel386 SX, or Intel486 SX CPUs if there is no NPX present. If the EM bit is set and no coprocessor or emulator is present, the system will hang.

The interpretation of different combinations of the EM and MP bits are shown in Table 16-3. Recommendations for the different processors is shown in Table 16-4.

**Table 16-3. EM and MP Bits Interpretations**

EM	MP	Interpretation
0	0	Numeric instructions are passed to FPU; WAIT ignores TS
0	1	Numeric instructions are passed to FPU; WAIT tests TS
1	0	Numeric instructions trap to emulator; WAIT ignores TS
1	1	Numeric instructions trap to emulator, WAIT tests TS

**Table 16-4. Recommended Values by Processor**

EM	MP	Interpretation
1	0	Intel386™ DX, Intel386 SX, and Intel486™ SX CPUs
0	1	Intel387™ DX, Intel387 SX, and Intel487™ SX math coprocessors, and Intel386 DX, Intel386 SX, Intel486 DX and Pentium® processors

The action taken for floating-point and wait instructions based on the value of these bits is shown in Table 16-5.

**Table 16-5. Action Taken for Different Combinations of EM, MP and TS**

CR0 Bits			Instruction Type	
EM	TS	MP	Floating Point	Wait
0	0	0	Execute	Execute
0	0	1	Execute	Execute
0	1	0	Exception 7	Execute
0	1	1	Exception 7	Exception 7
1	0	0	Exception 7	Execute
1	0	1	Exception 7	Execute
1	1	0	Exception 7	Execute
1	1	1	Exception 7	Exception 7

The NE (Numeric Exception) bit determines whether unmasked floating-point exceptions are handled through interrupt vector 16 (NE = 1) or through external interrupt (NE = 0). In systems using an external interrupt controller to invoke numeric exception handlers, the NE bit should be cleared to 0. This option is used for compatibility with the error reporting scheme used in DOS-based systems. Other systems can make use of the automatic error reporting through interrupt 16, and should set the NE bit to 1. Numeric exception handling is discussed in a later section.

### 16.2.2. FPU Software Emulation

Setting the EM bit to 1 causes the processor to trap via interrupt vector 7 (Device Not Available) to a software exception handler whenever it encounters an ESC instruction. Setting this bit has two uses:

1. The EM bit is used to run numeric applications on an Intel processor without an integrated FPU or NPX using a software Intel387 math coprocessor emulator.
2. Numeric applications designed to be run with a non-standard Intel387 math coprocessor emulator may not run successfully without the emulator. Setting the EM bit to 1 makes it possible to run such applications, or programs which use non-standard floating-point arithmetic.

If a math coprocessor is not present in the system, floating-point instructions can be emulated. The system is set up for software emulation as Table 16-6:

**Table 16-6. Software Emulation Settings**

CR0 Bit	Value
EM	1
MP	0
NE	1

The EM bit must be set in order for software emulation to function properly. Setting the EM bit to 1 will cause the processor to trap via interrupt vector 7 (Device Not Available) to a software exception handler whenever it encounters an ESC instruction. If the EM bit is set and no coprocessor or emulator is present, the system will hang.

The MP bit can be used during a task switch in protected-mode in conjunction with the TS bit to determine if WAIT instructions should trap when the context of the FPU is different from that of the currently executing task. When no FPU is present, this information may be irrelevant and therefore the bit should be set to 0.

Regardless of the value of the NE bit, the Intel486 SX processor generates an interrupt vector 7 (Device Not Available) upon encountering any floating point instruction. It is recommended that NE be set to 1 for normal operation. If a Floating-Point Unit is present, this bit follows the description described in Table 16-3.

### 16.3. CACHE ENABLING

The cache is enabled by clearing the CD and NW bits in the CR0 register (they are set upon hardware reset as indicated above). This enables caching (writethrough for the Intel486 processor and writeback for the Pentium processor) and cache invalidation cycles. Because all cache lines are invalid following reset initialization, it is unnecessary to invalidate the cache before enabling caching. See Chapter 18 for complete details of cache handling, including implementation of a writethrough cache on the Pentium processor using the PWT bit in the page table entry.

Under circumstances where cache lines may be marked as valid, the cache may need to be flushed or invalidated before the cache is enabled. This may occur as a result of using the test registers to run test patterns through the cache memory as part of confidence testing during software initialization. See the *Pentium® Processor Data Book* for model-specific details on cache testing.

### 16.4. SOFTWARE INITIALIZATION IN REAL-ADDRESS MODE

Note that the processor has several processing modes. It begins execution in a mode compatible with an 8086 processor, called real-address mode. After reset initialization, software must set up data structures needed for the processor to perform basic system functions, such as handling interrupts. If the processor remains in real-address mode, software must set up data structures in the form used by the 8086 processor. If the processor

is going to operate in protected mode, software must set up data structures in the form used by protected mode and then switch modes (see Section 16.6.).

### 16.4.1. System Tables

In real-address mode, no descriptor tables are used. The interrupt descriptor table (IDT), which starts at address 0 (unless the IDTR is changed), needs to be loaded with pointers to exception and interrupt handlers before interrupts can be enabled.

### 16.4.2. NMI Interrupt

The NMI interrupt is always enabled (except on nested NMI's). If the interrupt vector table and the NMI interrupt handler need to be loaded into RAM, there will be a period of time following reset initialization when an NMI interrupt cannot be handled. Hardware must provide a mechanism to prevent an NMI interrupt from being generated while software is unable to handle it. For example, the IDT and NMI interrupt handler can be provided in ROM. This allows an NMI interrupt to be handled immediately after reset initialization. Most systems enable/disable NMI by passing the NMI signal through an AND gate controlled by a bit in an I/O port. Hardware can clear the bit when the processor is reset, and software can set the bit when it is ready to handle NMI interrupts. System software designers should be aware of the mechanism used by hardware to protect software from NMI interrupts following reset.

## 16.5. SOFTWARE INITIALIZATION IN PROTECTED MODE

The data structures needed in protected mode are determined by the memory management features which are used. The processor supports segmentation models which range from a single, uniform address space (flat model) to a highly structured model with several independent, protected address spaces for each task (multisegmented model). Paging can be enabled for allowing access to large data structures which are partly in memory and partly on disk. Both of these forms of address translation require data structures which are set up by the operating system and used by the memory management hardware.

### 16.5.1. System Tables

A flat model without paging minimally requires a GDT with one code and one data segment descriptor. A null descriptor in the first GDT entry is also required. A flat model with paging may provide code and data descriptors for supervisor mode and another set of code and data descriptors for user mode. In addition, it requires a page directory and at least one second-level page table. (Note: the second-level page table can be eliminated if the page directory contains a directory entry pointing to itself, in which case the page directory and page table reside in the same page.) The stack can be placed in a normal read/write data segment, so no descriptor for the stack is required. Before the GDT can be used, the base address and limit for the GDT must be loaded into the GDTR register using an LGDT instruction.



A multi-segmented model may require additional segments for the operating system, as well as segments and LDTs for each application program. LDTs require segment descriptors in the GDT. Some operating systems allocate new segments and LDTs as they are needed. This provides maximum flexibility for handling a dynamic programming environment, such as an engineering workstation. However, many operating systems use a single LDT for all processes, allocating GDT entries in advance. An embedded system, such as a process controller, might pre-allocate a fixed number of segments and LDTs for a fixed number of application programs. This would be a simple and efficient way to structure the software environment of a system which requires real-time performance.

### 16.5.2. Interrupts

If hardware allows interrupts to be generated, the IDT and a gate for the interrupt handler need to be created. Before the IDT can be used, the base address and limit for the IDT must be loaded into the IDTR register using an LIDT instruction. See Chapter 14 for detailed information on this topic.

### 16.5.3. Paging

Unlike segmentation, paging is controlled by a mode bit. If the PG bit in the CR0 register is clear (its state following reset initialization), the paging mechanism is completely absent from the processor architecture seen by programmers.

If the PG bit is set, paging is enabled. The bit may be set using a MOV CR0 instruction. Before setting the PG bit, the following conditions must be true:

- Software has created at least two page tables, the page directory and at least one second-level page table if 4K pages are used. For information on 4M pages, see Appendix H.
- The PDDBR register (same as the CR3 register) is loaded with the physical base address of the page directory.
- The processor is in protected mode (paging is not available in real-address mode). If all other restrictions are met, the PG and PE bits can be set at the same time.

The following guidelines for setting the PG bit (as with the PE bit) should be adhered to maintain both upwards and downwards compatibility:

1. The instruction setting the PG bit should be followed immediately with a JMP instruction. A JMP instruction immediately after the MOV CR0 instruction changes the flow of execution, so it has the effect of emptying the Intel386 and Intel486 processor of instructions which have been fetched or decoded. The Pentium processor, however, uses a branch target buffer (BTB) for branch prediction, eliminating the need for branch instructions to flush the prefetch queue. For more information on the BTB, see the *Pentium® Processor Family Developer's Manual*, Volume 1, order number 241428.

2. The code from the instruction which sets the PG bit through the JMP instruction must come from a page which is identity mapped (i.e., the linear address before the jump is the same as the physical address after paging is enabled).

The 32-bit Intel architectures have different requirements for enabling paging and switching to protected mode. The Intel386 processor requires following steps 1 *or* 2 above. The Intel486 processor requires following both steps 1 *and* 2 above. The Pentium processor requires only step 2 but for upwards and downwards code compatibility with the Intel386 and Intel486 processors, it is recommended both steps 1 and 2 be taken.

See Chapter 11 for complete information on the paging mechanism.

#### 16.5.4. Tasks

If the multitasking mechanism is not used and changes to more privileged segments are not allowed, it is unnecessary to initialize the TR register.

If the multitasking mechanism is used or changes to more privileged segments are allowed (values for more privileged SS and ESP are obtained from the TSS), a TSS and a TSS descriptor for the initialization software must be created. TSS descriptors must not be marked as busy when they are created; TSS descriptors should be marked as busy by the CPU only as a side-effect of performing a task switch. As with descriptors for LDTs, TSS descriptors reside in the GDT. The LTR instruction is used to load a selector for the TSS descriptor of the initialization software into the TR register. This instruction marks the TSS descriptor as busy, but does not perform a task switch. The selector must be loaded before the software performs the first task switch, because a task switch copies the current task state into the TSS. After the LTR instruction has been used, further operations on the TR register are performed by task switching. As with segments and LDTs, TSSs and TSS descriptors can be either pre-allocated or allocated as needed.

If changes to more privileged segments are allowed, a TSS and TSS descriptor need to be created. The processor uses the TSS to obtain the values for the more privileged stack segment selector and stack pointer values when transferring control to more privileged segments.

#### 16.5.5. TLB, BTB and Cache Testing

As part of the process of switching into protected mode, system programmers may wish to perform TLB, BTB, and cache testing. For more information on testing, see the *Pentium® Processor Family Developer's Manual*, Volume 1, Chapter 33.

### 16.6. MODE SWITCHING

In order to take full advantage of the 32-bit address space and instruction set, the processor must switch from its native real-address mode to protected mode. A system may also find it necessary to switch back into real-address mode for system operations. This section identifies

the steps necessary for software to switch the processor from real-address mode to protected mode and from protected mode back into real-address mode.

### 16.6.1. Switching to Protected Mode

Before switching to protected mode, a minimum set of system data structures must be created, and the GDT, IDT, and TR registers must be initialized, as discussed in the previous section. Once these tables are created, system software can perform the steps to switch into protected mode.

Protected mode is entered by setting the PE bit in the CR0 register. The MOV CR0 instruction may be used to set this bit. The same two guidelines for setting the PG bit to enable paging in Section 16.5.3. apply for setting the PE bit to enable protected mode.

After entering protected mode, the segment registers continue to hold the contents they had in real address mode. Software should reload all the segment registers. Execution in protected mode begins with a CPL of 0.

### 16.6.2. Switching Back to Real-Address Mode

The processor re-enters real-address mode if software clears the PE bit in the CR0 register with a MOV CR0 instruction. A procedure which re-enters real-address mode should proceed as follows:

1. If paging is enabled, perform the following sequence:
  - Transfer control to linear addresses which have an identity mapping (i.e., linear addresses equal physical addresses). Ensure the GDT and IDT are identity mapped.
  - Clear the PG bit in the CR0 register.
  - Move zero into the CR3 register to flush the TLB.
2. Transfer control to a segment which has a limit of 64K (0FFFFH). This loads the CS register with the segment limit it needs to have in real mode. Ensure the GDT and IDT are in real-address memory (0-1Meg).
3. Load segment registers SS, DS, ES, FS, and GS with a selector for a descriptor containing the following values, which are appropriate for real mode:
  - Limit = 64K (0FFFFH)
  - Byte granular (G = 0)
  - Expand up (E = 0)
  - Writable (W = 1)
  - Present (P = 1)
  - Base = any value

Note that if the segment registers are not reloaded, execution continues using the descriptors loaded during protected mode.

4. Disable interrupts. A CLI instruction disables INTR interrupts. NMI interrupts can be disabled with external circuitry.
5. Clear the PE bit in the CR0 register.
6. Jump to the real mode program using a far JMP instruction. This flushes the instruction queue (of the Intel386 and Intel486 processors) and puts appropriate values in the access rights of the CS register. This step is not required on the Pentium processor, however, for downwards compatibility, a far JMP should be included as part of the switching back to real-address mode process.
7. Use the LIDT instruction to load the base and limit of the real-mode interrupt vector table.
8. Enable interrupts.
9. Load the segment registers as needed by the real-mode code.

## 16.7. INITIALIZATION AND MODE SWITCHING EXAMPLE

This section provides an initialization and mode switching example that can be incorporated into your application. Also provided are some assumptions about the Intel development tools that are used which include the ASM386/486 assembler and BLD386 builder.

### 16.7.1. Goal of this Example

The goal of this example is to move the CPU into protected mode right after reset using initialization code that resides in EPROM/Flash and run a simple application.

### 16.7.2. Memory Layout Following Reset

Based on the discussion in Section 16.1. and the values shown in Table 16-1, Figure 16-3 shows the memory layout following processor reset and the starting point of this example.



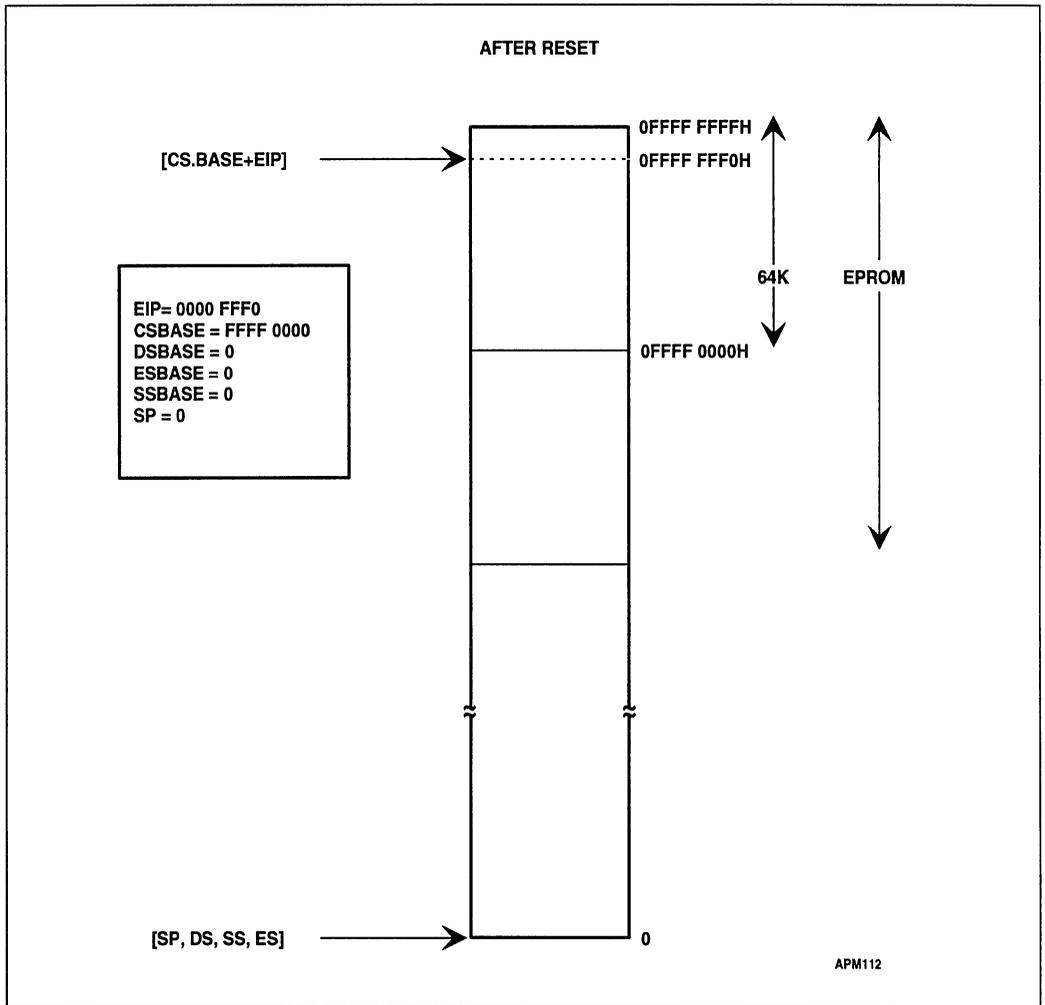


Figure 16-3. Processor State after Reset

### 16.7.3. The Algorithm

The main steps of this example are shown in Table 16-7 along with the line numbers from the source listing of STARTUP.ASM given in Example 16-1.

**Table 16-7. The Algorithm and Related Listing Line Numbers**

ASM Lines		Description
From	To	
157	157	Jump (short) to the entry code in the EPROM
162	169	Construct a temporary GDT in RAM with one entry: 0 - null 1 - R/W data segment, Base=0 limit = 4GB
171	172	Load the GDTR to point to the temp GDT
174	177	Load CR0 with protected mode bit - move to PM
179	181	Jump near to clear real mode queue
184	186	Load DS, ES registers with GDT[1] descriptor; now both point to the entire physical memory space.
188	195	Perform specific board initialization that is imposed by the new protected mode
196	218	Copy the application's GDT from ROM into RAM
220	238	Copy the application's IDT from ROM into RAM
241	243	Load application's GDTR
244	245	Load application's IDTR
247	261	Copy the application's TSS from ROM into RAM
263	267	Update TSS descriptor and other aliases in GDT (GDT alias or IDT alias)
277	277	Load the TR register (without task switch — using LTR instruction)
282	286	Load SS, ESP with the value found in the application's TSS
287	287	Push EFLAGS value found in the application's TSS
288	288	Push CS value found in the application's TSS
289	289	Push EIP value found in the application's TSS
290	293	Load DS, ES with the value found in the application's TSS
296	296	Perform IRET; pop the above values and enter the application code

**NOTES:**

If a switch into protected mode is made the CS selector is not changed (by far jump or far call) the original base value is retained (if there is no far jump after reset the base will stay 0FFFF000H; which is the location space of the EPROM).

Interrupts are disabled after reset and should stay that way, otherwise may impose far jump. NMI is not disabled and must not be active until the initialization is done.

The use of TEMP\_GDT allows simple transfer of tables from the EPROM to anywhere in the RAM area. A GDT entry is constructed with its base pointing to address 0 and a limit of 4GB. When the DS and ES registers are loaded with this descriptor, the TEMP\_GDT is no longer needed and can be replaced by the application GDT.

The assumption for this code is one TSS no LDTs. If more TSSs exist in the application, they must be copied into RAM. If there are LDTs they may be copied as well.

In some implementations, decoding of the address lines A20 - A31 is not done after reset to simulate the early 8086 chip behavior. In the process of moving into protected mode it may be desirable to set these decoders to decode the complete address lines.

## 16.7.4. Tool Usage

In this example, Intel software tools (ASM386 and BLD386) are used.

The following are assumptions that are used when using the Intel ASM386 and BLD386 to generate the initialization code.

- The ASM386 will generate the right operand size opcodes according to the code segment attribute. The attribute is assigned either by the ASM386 invocation controls or in the code segment definition.
- If a code segment that is going to run in real-address mode is defined, it must be set to a USE 16 attribute. If 32-bit operands (MOV EAX, EBX) are used in the segment, an operand prefix will automatically be generated which will force the CPU to execute a 32-bit operation for this instruction although its default code segment attribute is 16-bit.
- Intel's ASM386 assembler allows specific use of the 16- or 32-bit instructions, for example, LGDTW, LGDTD, IRETD. If you are using the generic instruction (LGDT) the default segment attribute will be used to generate the right opcode.

**Table 16-8. Relationship Between BLD Item and ASM Source File**

Item	ASM386 and Startup.A58	BLD386 Controls and BLD file	Effect
Bootstrap	public startup startup:	bootstrap start(startup)	Near jump at 0FFFFFF0H to start
GDT location	public GDT_EPROM GDT_EPROM TABLE_REG <>	TABLE GDT(location = GDT_EPROM)	The location of the GDT will be programmed into the GDT_EPROM location
IDT location	public IDT_EPROM IDT_EPROM TABLE_REG <>	TABLE IDT(location = IDT_EPROM)	The location of the IDT will be programmed into the IDT_EPROM location
RAM start	RAM_START equ 400H	memory( reserve = (0..3FFFH))	RAM_START is used as the ram destination for moving the tables. It must be excluded from the application's segment area.
Location of the application TSS in the GDT	TSS_INDEX EQU 10	TABLE GDT( ENTRY=( 10: PROTECTED_MODE_T ASK))	Put the descriptor of the application TSS in GDT entry 10
EPROM size and location	size and location of the initialization code	SEGMENT startup.code (base= 0FFFF000H) ...memory (RANGE( ROM_AREA = ROM(x..y))	Initialization code size must be less than 64K and resides at upper most 64K of the 4GB memory space.

### 16.7.5. STARTUP.ASM Listing

The source code listing to move the CPU into protected mode is provided in Example 16-1. This listing does not include any opcode and offset information.

#### Example 16-1. STARTUP.ASM

```
DOS 5.0 (045-N) 386(TM) MACRO ASSEMBLER STARTUP
                                09:44:51    08/19/92    PAGE    1

DOS 5.0 (045-N) 386(TM) MACRO ASSEMBLER V4.0, ASSEMBLY OF MODULE
                                STARTUP
OBJECT MODULE PLACED IN startup.obj
ASSEMBLER INVOKED BY: f:\386tools\ASM386.EXE startup.a58 pw (132 )
```

```

LINE      SOURCE

1          NAME      STARTUP
2
3          ;;;;;;;;;;;;;;
4          ;
5          ; ASSUMPTIONS:
6          ;
7          ;     1.  The bottom 64K of memory is ram, and can be used for
8          ;         scratch space by this module.
9          ;
10         ;     2.  The system has sufficient free usable ram to copy the
11         ;         initial GDT, IDT, and TSS
12         ;
13         ;;;;;;;;;;;;;;
14
15         ; configuration data - must match with build definition
16
17         CS_BASE      EQU      0FFFF000H
18
19         ; CS_BASE is the linear address of the segment STARTUP_CODE
20         ; - this is specified in the build language file
21
22         RAM_START    EQU      400H
23
24         ; RAM_START is the start of free, usable ram in the linear
25         ; memory space.  The GDT, IDT, and initial TSS will be
26         ; copied above this space, and a small data segment will be
27         ; discarded at this linear address.  The 32-bit word at
28         ; RAM_START will contain the linear address of the first
29         ; free byte above the copied tables - this may be useful if
30         ; a memory manager is used.
31
32         TSS_INDEX    EQU      10
33
34         ; TSS_INDEX is the index of the TSS of the first task to
35         ; run after startup
36
37
38         ;;;;;;;;;;;;;;
39
40         ; ----- STRUCTURES and EQU -----
41         ; structures for system data
42
43         ; TSS structure
44         TASK_STATE   STRUC

```

```

45     link           DW ?
46     link_h        DW ?
47     ESP0          DD ?
48     SS0           DW ?
49     SS0_h         DW ?
50     ESP1          DD ?
51     SS1           DW ?
52     SS1_h         DW ?
53     ESP2          DD ?
54     SS2           DW ?
55     SS2_h         DW ?
56     CR3_reg       DD ?
57     EIP_reg       DD ?
58     EFLAGS_reg    DD ?
59     EAX_reg       DD ?
60     ECX_reg       DD ?
61     EDX_reg       DD ?
62     EBX_reg       DD ?
63     ESP_reg       DD ?
64     EBP_reg       DD ?
65     ESI_reg       DD ?
66     EDI_reg       DD ?
67     ES_reg        DW ?
68     ES_h          DW ?
69     CS_reg        DW ?
70     CS_h          DW ?
71     SS_reg        DW ?
72     SS_h          DW ?
73     DS_reg        DW ?
74     DS_h          DW ?
75     FS_reg        DW ?
76     FS_h          DW ?
77     GS_reg        DW ?
78     GS_h          DW ?
79     LDT_reg       DW ?
80     LDT_h         DW ?
81     TRAP_reg      DW ?
82     IO_map_base   DW ?
83     TASK_STATE    ENDS
84
85     ; basic structure of a descriptor
86     DESC          STRUC
87         lim_0_15      DW ?
88         bas_0_15      DW ?
89         bas_16_23     DB ?
90         access        DB ?
91         gran          DB ?

```

```

92     bas_24_31      DB ?
93 DESC      ENDS
94
95 ; structure for use with LGDT and LIDT instructions
96 TABLE_REG  STRUC
97     table_lim      DW ?
98     table_linear   DD ?
99 TABLE_REG  ENDS
100
101 ; offset of GDT and IDT descriptors in builder generated GDT
102 GDT_DESC_OFF EQU 1*SIZE(DESC)
103 IDT_DESC_OFF EQU 2*SIZE(DESC)
104
105 ; equates for building temp GDT in ram
106 LINEAR_SEL      EQU      1*SIZE (DESC)
107 LINEAR_PROTO_LO EQU      0000FFFFH ; LINEAR_ALIAS
108 LINEAR_PROTO_HI EQU      000CF9200H
109
110 ; Protection Enable Bit in CR0
111 PE_BIT EQU 1B
112
113 ; -----
114
115 ; ----- DATA SEGMENT-----
116
117 ; Initially, this data segment starts at linear 0, due to
118 ; CPU powerup state.
119
120 STARTUP_DATA  SEGMENT RW
121
122 free_mem_linear_base LABEL  DWORD
123 TEMP_GDT       LABEL  BYTE   ; must be first in
segment
124 TEMP_GDT_NULL_DESC  DESC  <>
125 TEMP_GDT_LINEAR_DESC DESC  <>
126
127 ; scratch areas for LGDT and LIDT instructions
128 TEMP_GDT_SCRATCH TABLE_REG  <>
129 APP_GDT_RAM      TABLE_REG  <>
130 APP_IDT_RAM      TABLE_REG  <>
131     ; align end_data
132 fill      DW      ?
133
134 ; last thing in this segment - should be on a dword boundary
135 end_data LABEL  BYTE
136
137 STARTUP_DATA  ENDS

```

```

138 ; -----
139
140
141 ; ----- CODE SEGMENT-----
142 STARTUP_CODE SEGMENT ER PUBLIC USE16
143
144 ; filled in by builder
145     PUBLIC  GDT_EPROM
146 GDT_EPROM  TABLE_REG  <>
147
148 ; filled in by builder
149     PUBLIC  IDT_EPROM
150 IDT_EPROM  TABLE_REG  <>
151
152 ; entry point into startup code - the bootstrap will vector
153 ; here with a near JMP generated by the builder.  This
154 ; label must be in the top 64K of linear memory.
155
156     PUBLIC  STARTUP
157 STARTUP:
158
159 ; DS,ES address the bottom 64K of flat linear memory
160     ASSUME  DS:STARTUP_DATA, ES:STARTUP_DATA
161 ; See Figure 16-4
162 ; load GDTR with temporary GDT
163     LEA    EBX,TEMP_GDT  ; build the TEMP_GDT in low ram,
164     MOV    DWORD PTR [EBX],0  ; where we can address
165     MOV    DWORD PTR [EBX]+4,0
166     MOV    DWORD PTR [EBX]+8, LINEAR_PROTO_LO
167     MOV    DWORD PTR [EBX]+12, LINEAR_PROTO_HI
168     MOV    TEMP_GDT_scratch.table_linear,EBX
169     MOV    TEMP_GDT_scratch.table_lim,15
170
171     DB    66H          ; execute a 32 bit LGDT
172     LGDT  TEMP_GDT_scratch
173
174 ; enter protected mode
175     MOV    EBX,CR0
176     OR    EBX,PE_BIT
177     MOV    CR0,EBX
178
179 ; clear prefetch queue
180     JMP    CLEAR_LABEL
181 CLEAR_LABEL:
182
183 ; make DS and ES address 4G of linear memory
184     MOV    CX,LINEAR_SEL

```

```
185         MOV     DS,CX
186         MOV     ES,CX
187
188     ; do board specific initialization
189     ;
190         ;
191         ; .....
192         ;
193
194
195     ; See Figure 16-5
196     ; copy EPROM GDT to ram at:
197     ;             RAM_START + size (STARTUP_DATA)
198     MOV     EAX, RAM_START
199     ADD     EAX, OFFSET (end_data)
200     MOV     EBX, RAM_START
201     MOV     ECX, CS_BASE
202     ADD     ECX, OFFSET (GDT_EPROM)
203     MOV     ESI, [ECX].table_linear
204     MOV     EDI, EAX
205     MOVZX  ECX, [ECX].table_lim
206     MOV     APP_GDT_ram[EBX].table_lim, CX
207     INC     ECX
208     MOV     EDX, EAX
209     MOV     APP_GDT_ram[EBX].table_linear, EAX
210     ADD     EAX, ECX
211     REP MOVSB     BYTE PTR ES:[EDI], BYTE PTR DS:[ESI]
212
213     ; fixup GDT base in descriptor
214     MOV     ECX, EDX
215     MOV     [EDX].bas_0_15+GDT_DESC_OFF, CX
216     ROR     ECX, 16
217     MOV     [EDX].bas_16_23+GDT_DESC_OFF, CL
218     MOV     [EDX].bas_24_31+GDT_DESC_OFF, CH
219
220     ; copy EPROM IDT to ram at:
221     ; RAM_START+size(STARTUP_DATA)+SIZE (EPROM GDT)
222     MOV     ECX, CS_BASE
223     ADD     ECX, OFFSET (IDT_EPROM)
224     MOV     ESI, [ECX].table_linear
225     MOV     EDI, EAX
226     MOVZX  ECX, [ECX].table_lim
227     MOV     APP_IDT_ram[EBX].table_lim, CX
228     INC     ECX
229     MOV     APP_IDT_ram[EBX].table_linear, EAX
230     MOV     EBX, EAX
231     ADD     EAX, ECX
```

```

232     REP MOVSB     BYTE PTR ES:[EDI],BYTE PTR DS:[ESI]
233
234         ; fixup IDT pointer in GDT
235     MOV     [EDX].bas_0_15+IDT_DESC_OFF,BX
236     ROR     EBX,16
237     MOV     [EDX].bas_16_23+IDT_DESC_OFF,BL
238     MOV     [EDX].bas_24_31+IDT_DESC_OFF,BH
239
240         ; load GDTR and IDTR
241     MOV     EBX, RAM_START
242     DB     66H             ; execute a 32 bit LGDT
243     LGDT   APP_GDT_ram[EBX]
244     DB     66H             ; execute a 32 bit LIDT
245     LIDT   APP_IDT_ram[EBX]
246
247         ; move the TSS
248     MOV     EDI,EAX
249     MOV     EBX,TSS_INDEX*SIZE(DESC)
250     MOV     ECX,GDT_DESC_OFF ;build linear address for TSS
251     MOV     GS,CX
252     MOV     DH,GS:[EBX].bas_24_31
253     MOV     DL,GS:[EBX].bas_16_23
254     ROL     EDX,16
255     MOV     DX,GS:[EBX].bas_0_15
256     MOV     ESI,EDX
257     LSL     ECX,EBX
258     INC     ECX
259     MOV     EDX,EAX
260     ADD     EAX,ECX
261     REP MOVSB     BYTE PTR ES:[EDI],BYTE PTR DS:[ESI]
262
263         ; fixup TSS pointer
264     MOV     GS:[EBX].bas_0_15,DX
265     ROL     EDX,16
266     MOV     GS:[EBX].bas_24_31,DH
267     MOV     GS:[EBX].bas_16_23,DL
268     ROL     EDX,16
269     ;save start of free ram at linear location RAMSTART
270     MOV     free_mem_linear_base+RAM_START,EAX
271
272     ;assume no LDT used in the initial task - if necessary,
273     ;code to move the LDT could be added, and should resemble
274     ;that used to move the TSS
275
276     ; load TR
277     LTR     BX ; No task switch, only descriptor loading
278     ; See Figure 16-6

```

```
279      ; load minimal set of registers necessary to simulate task
280      ; switch
281
282
283      MOV     AX,[EDX].SS_reg      ; start loading registers
284      MOV     EDI,[EDX].ESP_reg
285      MOV     SS,AX
286      MOV     ESP,EDI             ; stack now valid
287      PUSH   DWORD PTR [EDX].EFLAGS_reg
288      PUSH   DWORD PTR [EDX].CS_reg
289      PUSH   DWORD PTR [EDX].EIP_reg
290      MOV     AX,[EDX].DS_reg
291      MOV     BX,[EDX].ES_reg
292      MOV     DS,AX              ; DS and ES no longer linear memory
293      MOV     ES,BX
294
295      ; simulate far jump to initial task
296      IRETD
297
298  STARTUP_CODE  ENDS
*** WARNING #377 IN 298, (PASS 2) SEGMENT CONTAINS PRIVILEGED
INSTRUCTION(S)
299
300  END STARTUP, DS:STARTUP_DATA, SS:STARTUP_DATA
301
302

ASSEMBLY COMPLETE,      1 WARNING,      NO ERRORS.
```

### 16.7.6. MAIN.ASM Source Code

The file MAIN.ASM shown in Example 16-2 defines the data and stack segments for this application and can be substituted with the main module task written in a high-level language that is invoked by the IRET instruction executed by STARTUP.ASM.

#### Example 16-2. MAIN.ASM

```
NAME    main_module
data    SEGMENT RW
        dw 1000 dup(?)
DATA    ENDS

stack  stackseg 800

CODE SEGMENT ER use32 PUBLIC
main_start:
        nop
        nop
        nop

CODE    ENDS

END main_start, ds:data, ss:stack
```

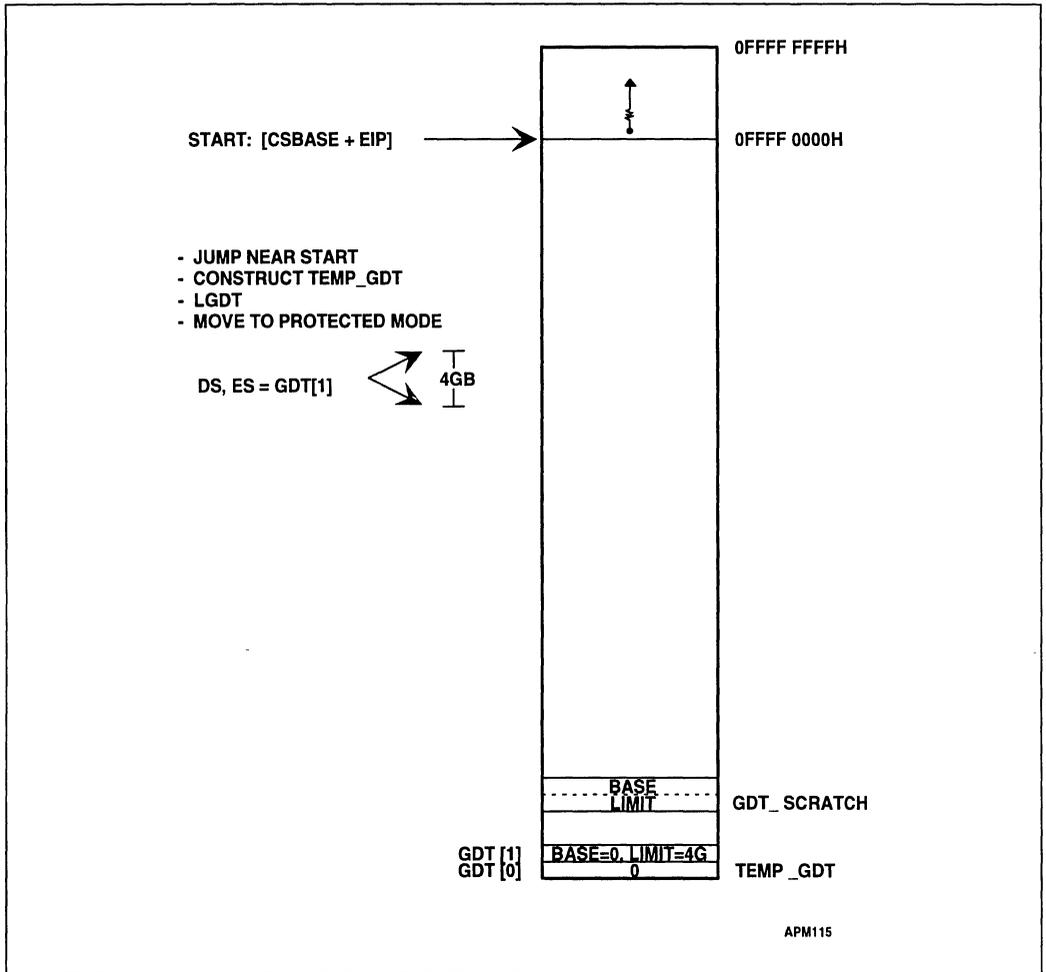


Figure 16-4. Constructing Temp\_GDT and Switching to Protected Mode (Lines 162-172 of List File)

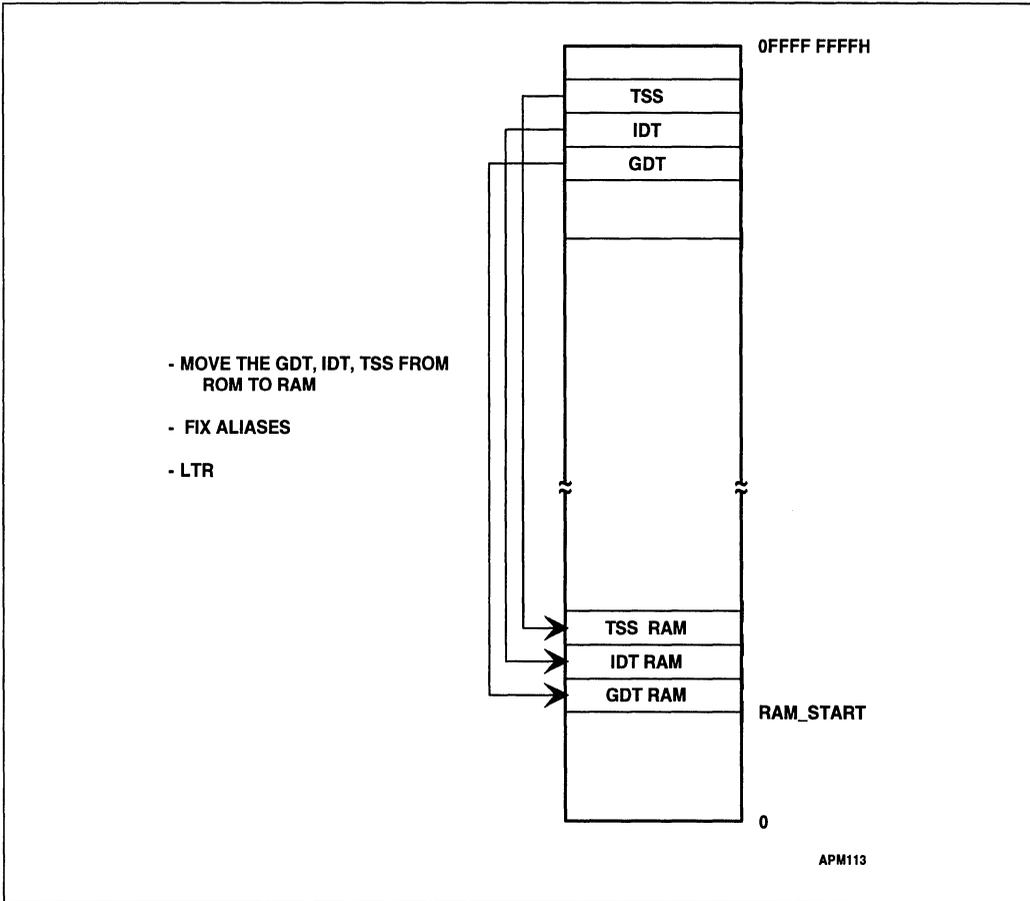
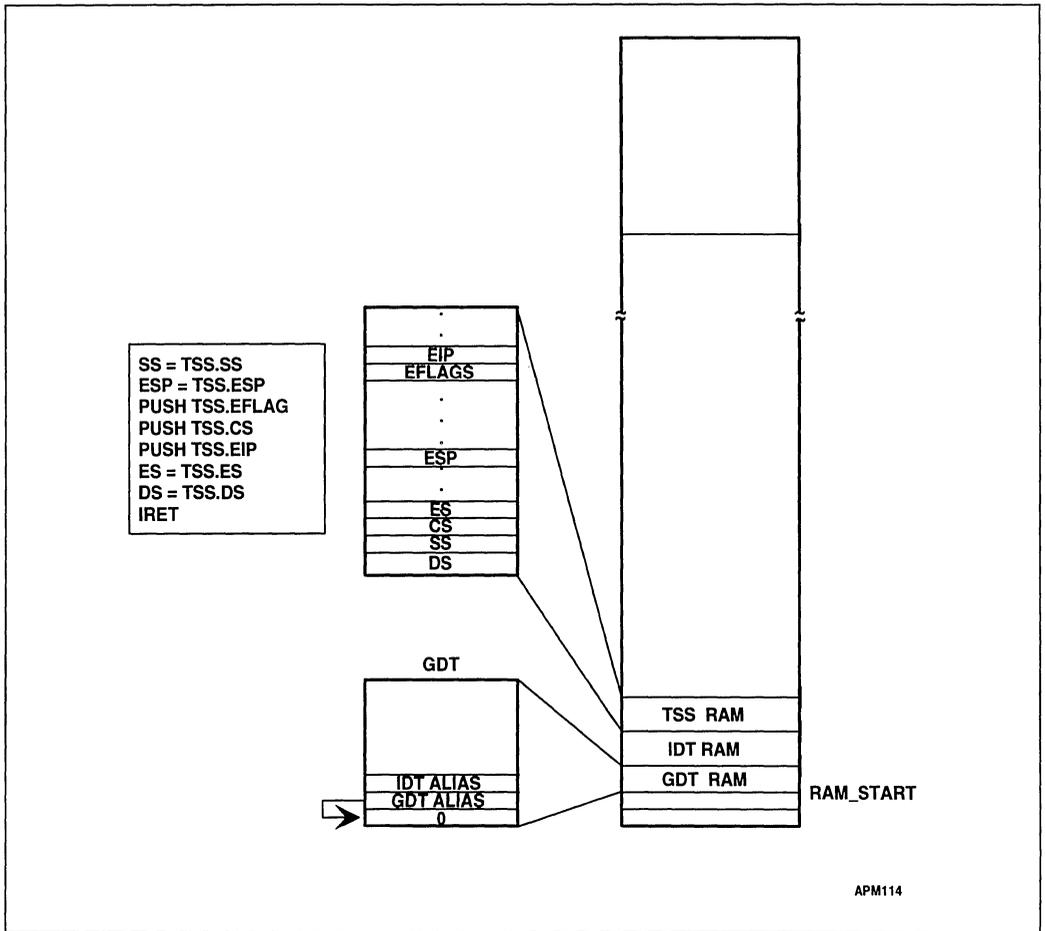


Figure 16-5. Moving the GDT, IDT and TSS from ROM to RAM  
(Lines 196-261 of List File)



**Figure 16-6. Task Switching**  
(Lines 282-296 of List File)

### 16.7.7. Supporting Files

The batch file shown in Example 16-3 can be used to assemble the source code files STARTUP.ASM and MAIN.ASM and build the final application.

#### Example 16-3. Batch File to Assemble, Compile and Build the Application

```
ASM386 STARTUP.ASM
ASM386 MAIN.ASM
```

```
BLD386 STARTUP.OBJ, MAIN.OBJ buildfile(EPROM.BLD) bootstrap(STARTUP)
Bootload
```

The BLD386 has several functions in this example:

- It allocates physical memory location to segments and tables.
- It generates tables using the build file and the input files.
- It links object files and resolves references.
- It generates bootloadable file to be programmed into the EPROM.

Example 16-4 shows the build file used as input to BLD386 to perform the above functions.

#### Example 16-4. Build File

```
INIT_BLD_EXAMPLE;

SEGMENT
    *SEGMENTS                (DPL = 0)
    , startup.startup_code    (BASE = 0FFFF0000H)
    ;

TASK
    BOOT_TASK                (OBJECT = startup, INITIAL,DPL = 0,
                             NOT INTENABLED)
    , PROTECTED_MODE_TASK    (OBJECT = main_module,DPL = 0,
                             NOT INTENABLED)
    ;

TABLE
    GDT (
        LOCATION = GDT_EPROM
        , ENTRY = (
            10:          PROTECTED_MODE_TASK
            ,          startup.startup_code
            ,          startup.startup_data
            ,          main_module.data
            ,          main_module.code
            ,          main_module.stack
            )
        ),
    IDT (
        LOCATION = IDT_EPROM
        );
```

```
MEMORY
(
    RESERVE = (0..3FFFH
                -- Area for the GDT, IDT, TSS copied from
ROM
                60000H..0FFFEFFFFH)
    ,
    RANGE = (ROM_AREA = ROM (0FFFF0000H..0FFFFFFFH))
            -- Eprom size 64K
    ,
    RANGE = (RAM_AREA = RAM (4000H..05FFFFH))
);

END
```



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17

**Debugging**



The Pentium processor has advanced debugging facilities which are particularly important for sophisticated software systems, such as multitasking operating systems. The failure conditions for these software systems can be very complex and time-dependent. The debugging features of the Pentium processor give the system programmer valuable tools for looking at the dynamic state of the processor.

The debugging support is accessed through the debug registers. The debug registers of the Pentium processor hold the addresses of memory and I/O locations, called breakpoints, which invoke debugging software (unlike the Intel386 and Intel486 processors which allowed debugging of memory accesses only). An exception is generated when a memory or I/O operation is made to one of these addresses. A breakpoint is specified for a particular form of memory or I/O access, such as an instruction fetch, doubleword memory write operation or a word I/O read operation. The debug registers support both instruction breakpoints and data breakpoints.

With other processors, instruction breakpoints are set by replacing normal instructions with breakpoint instructions. When the breakpoint instruction is executed, the debugger is called. But with the debug registers of the Pentium processor, this is not necessary. By eliminating the need to write into the code space, the debugging process is simplified (there is no need shadow the ROM code space in RAM) and breakpoints can be set in ROM-based software. In addition, breakpoints can be set on reads and writes to data which allows real-time monitoring of variables.

## 17.1. DEBUGGING SUPPORT

The features of the architecture which support debugging include:

- **Reserved debug interrupt vector**—Specifies a procedure or task to be called when an event for the debugger occurs.
- **Debug address registers**—Specifies the addresses of up to four breakpoints.
- **Debug control register**—Specifies the forms of memory or I/O access for the breakpoints.
- **Debug status register**—Reports conditions which were in effect at the time of the exception.
- **Trap bit of TSS (T-bit)**—Generates a debug exception when an attempt is made to perform a task switch to a task with this bit set in its TSS.
- **Resume flag (RF)**—Suppresses multiple exceptions to the same instruction.
- **Trap flag (TF)**—Generates a debug exception after every execution of an instruction.

- **Breakpoint instruction**—Calls the debugger (generates a debug exception). This instruction is an alternative way to set code breakpoints. It is especially useful when more than four breakpoints are desired, or when breakpoints are being placed in the source code.
- **Reserved interrupt vector for breakpoint exception**—Calls a procedure or task when a breakpoint instruction is executed.

These features allow a debugger to be called either as a separate task or as a procedure in the context of the current task. The following conditions can be used to call the debugger:

- Task switch to a specific task.
- Execution of the breakpoint instruction.
- Execution of any instruction.
- Execution of an instruction at a specified address.
- Read or write of a byte, word, or doubleword at a specified memory address.
- Write to a byte, word, or doubleword at a specified memory address.
- Input of a byte or word at a specified I/O address.
- Output of a byte, word, or doubleword at a specified I/O address.
- Attempt to change the contents of a debug register.

## 17.2. DEBUG REGISTERS

Six registers control debugging. These registers are accessed by forms of the MOV instruction. A debug register may be the source or destination operand for one of these instructions. The debug registers are privileged resources; the MOV instructions which access them may be executed only at privilege level 0. An attempt to read or write the debug registers from any other privilege level generates a general-protection exception. Figure 17-1 shows the format of the debug registers.



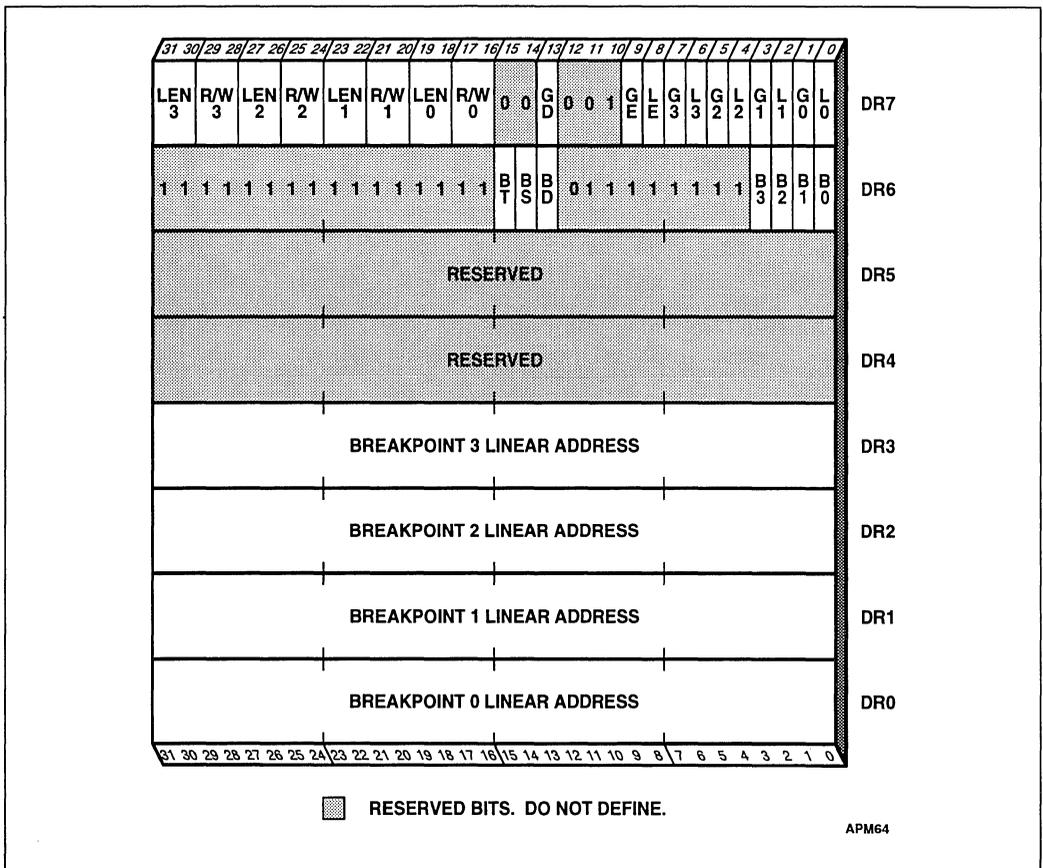


Figure 17-1. Debug Registers

### 17.2.1. Debug Address Registers (DR0-DR3)

Each of these registers holds the linear address for one of the four breakpoints. That is, breakpoint comparisons are made before physical address translation occurs. Each breakpoint condition is specified further by the contents of the DR7 register.

### 17.2.2. Debug Control Register (DR7)

The debug control register shown in Figure 17-1 specifies the type of memory or I/O access associated with each breakpoint. Each address in registers DR0 to DR3 corresponds to a field R/W0 to R/W3 in the DR7 register. The DE (Debug Extensions) bit in the CR4 register

determines how the R/W bits are interpreted. When the DE bit is set, the processor interprets these bits as follows:

- 00 — Break on instruction execution only
- 01 — Break on data writes only
- 10 — Break on I/O reads or writes
- 11 — Break on data reads or writes but not instruction fetches

When the DE bit is clear, the Pentium processor interprets the R/W bits the same as the Intel486 and Intel386 processors, which is as follows:

- 00 — Break on instruction execution only
- 01 — Break on data writes only
- 10 — undefined
- 11 — Break on data reads or writes but not instruction fetches

The LEN0 to LEN3 fields in the DR7 register specify the size of the breakpointed location. A size of 1, 2, or 4 bytes may be specified. The length fields are interpreted as follows:

- 00 — one-byte length
- 01 — two-byte length
- 10 — undefined
- 11 — four-byte length

If  $RW_n$  is 00 (instruction execution), then  $LEN_n$  should also be 00. The effect of using any other length is undefined.

The GD bit enables the debug register protection condition that is flagged by BD of DR6. Note that GD is cleared at entry to the debug exception handler by the processor. This allows the handler free access to the debug registers.

The low eight bits of the DR7 register (fields L0 to L3 and G0 to G3) individually enable the four address breakpoint conditions. There are two levels of enabling: the local (L0 through L3) and global (G0 through G3) levels. The local enable bits are automatically cleared by the processor with every task switch to avoid unwanted breakpoint conditions in the new task. They are used to set breakpoint conditions in a single task. The global enable bits are not cleared by a task switch. They are used to enable breakpoint conditions which apply to all tasks.

### 17.2.3. Debug Status Register (DR6)

The debug status register shown in Figure 11-1 reports conditions sampled at the time the debug exception was generated. Among other information, it reports which breakpoint triggered the exception. Update only occurs if the exception is taken, then all bits are updated.



When an enabled breakpoint generates a debug exception, it loads the low four bits of this register (B0 through B3) before entering the debug exception handler. The B bit is set if the condition described by the DR, LEN, and R/W bits is true, even if the breakpoint is not enabled by the L and G bits. The processor sets the B bits for all breakpoints which match the conditions present at the time the debug exception is generated, whether or not they are enabled.

The BT bit is associated with the T bit (debug trap bit) of the TSS (see Chapter 10 for the format of a TSS). The processor sets the BT bit before entering the debug handler if a task switch has occurred to a task with a set T bit in its TSS. There is no bit in the DR7 register to enable or disable this exception; the T bit of the TSS is the only enabling bit.

The BS bit is associated with the TF flag. The BS bit is set if the debug exception was triggered by the single-step execution mode (TF flag set). The single-step mode is the highest-priority debug exception; when the BS bit is set, any of the other debug status bits also may be set.

The BD bit is set if the next instruction will read or write one of the eight debug registers while they are being used by in-circuit emulation if the GD bit in DR7 is set to one.

Note that the contents of the DR6 register are never cleared by the processor. To avoid any confusion in identifying debug exceptions, the debug handler should clear the register before returning.

#### 17.2.4. Debug Registers DR4 and DR5

Although debug registers 4 and 5 have been documented as *reserved*, previous generations of processors aliased these registers to debug registers 6 and 7, respectively. When debug extensions are not enabled (CR4.DE=0), the Pentium processor remains compatible with existing software by aliasing these references. However, when debug extensions are enabled (CR4.DE=1), attempts to reference debug registers 4 or 5 will result in an Undefined Opcode Exception (#UD).

#### 17.2.5. Breakpoint Field Recognition

The address and LEN bits for each of the four breakpoint conditions define a range of sequential byte addresses for a data or I/O breakpoint. The LEN bits permit specification of a one-, two-, or four-byte range. Two-byte ranges must be aligned on word boundaries (addresses which are multiples of two) and four-byte ranges must be aligned on doubleword boundaries (addresses which are multiples of four). I/O breakpoint addresses are zero extended from 16 to 32 bits for purposes of comparison with the breakpoint address in the selected debug register. These requirements are enforced by the processor; it uses the LEN bits to mask the lower address bits in the debug registers. Unaligned data or I/O breakpoint addresses do not yield the expected results.

A data breakpoint for reading or writing is triggered if any of the bytes participating in an access is within the range defined by a breakpoint address register and its LEN bits. Table

17-1 gives some examples of combinations of addresses and fields with references which do and do not cause traps.

**Table 17-1. Breakpointing Examples**

Operation		Address (hex)	Length (in bytes)
Register Contents	DR0	A0001	1 (LEN0 = 00)
Register Contents	DR1	A0002	1 (LEN1 = 00)
Register Contents	DR2	B0002	2 (LEN2 = 01)
Register Contents	DR3	C0000	4 (LEN3 = 11)
Data Operations Which Trap		A0001	1
		A0002	1
		A0001	2
		A0002	2
		B0002	2
		B0001	4
		C0000	4
		C0001	2
Data Operations Which Do Not Trap		A0000	1
		A0003	4
		B0000	2
		C0004	4

A data breakpoint for an unaligned operand can be made from two sets of entries in the breakpoint registers where each entry is byte-aligned, and the two entries together cover the operand. This breakpoint generates exceptions only for the operand, not for any neighboring bytes.

Instruction breakpoint addresses must have a length specification of one byte (LEN = 00); the behavior of code breakpoints for other operand sizes is undefined. The processor recognizes an instruction breakpoint address only when it points to the first byte of an instruction. If the instruction has any prefixes, the breakpoint address must point to the first prefix.

It is recommended that debuggers execute the LGDT instruction before returning to the program being debugged to ensure that breakpoints are detected.

### 17.3. DEBUG EXCEPTIONS

Two of the interrupt vectors of the Pentium processor are reserved for debug exceptions. The debug exception is the usual way to invoke debuggers designed for the Pentium processor.

#### 17.3.1. Interrupt 1—Debug Exceptions

The handler for this exception usually is a debugger or part of a debugging system. The processor generates a debug exception for any of several conditions. The debugger can check flags in the DR6 and DR7 registers to determine which condition caused the exception and

which other conditions also might apply. Table 17-2 shows the states of these bits for each kind of breakpoint condition.

Instruction breakpoints are faults; other debug exceptions are traps. The debug exception may report either or both at one time. The following sections present details for each class of debug exception.

**Table 17-2. Debug Exception Conditions**

Flags Tested	Description
BS = 1	Single-step trap
B0 = 1 and (GE0 = 1 or LE0 = 1)	Breakpoint defined by DR0, LEN0, and R/W0
B1 = 1 and (GE1 = 1 or LE1 = 1)	Breakpoint defined by DR1, LEN1, and R/W1
B2 = 1 and (GE2 = 1 or LE2 = 1)	Breakpoint defined by DR2, LEN2, and R/W2
B3 = 1 and (GE3 = 1 or LE3 = 1)	Breakpoint defined by DR3, LEN3, and R/W3
BD = 1	Debug registers in use for in-circuit emulation
BT = 1	Task switch

### 17.3.1.1. INSTRUCTION-BREAKPOINT FAULT

The processor reports an instruction breakpoint before it executes the breakpointed instruction (i.e., a debug exception caused by an instruction breakpoint is a fault).

The RF flag permits the debug exception handler to restart instructions which cause faults other than debug faults. When a debug fault occurs, the system software must set the RF bit in the copy of the EFLAGS register which is pushed on the stack in the debug exception handler routine. This bit is set in preparation for resuming the program's execution at the breakpoint address without generating another breakpoint fault on the same instruction. (Note: The RF bit does not cause breakpoint traps to be ignored, nor other kinds of faults.) The RF flag is set by the IRETD instruction (but not by POPF or POPFD) to the value specified by the saved copy of the EFLAGS register in order to disable the generation of a code breakpoint exception on the instruction immediately following the IRETD.

The processor clears the RF flag at the successful completion of every instruction except after the IRET instruction and JMP, CALL, or INT instructions which cause a task switch.

The processor does not set the RF flag in the copy of the EFLAGS register pushed on the stack before entry into any fault handler. When the fault handler is entered for instruction breakpoints, for example, the debug handler should set the RF flag in the copy of the EFLAGS register pushed on the stack; so that when the IRET instruction is executed, returning control from the exception handler, the RF flag in the EFLAGS register will be set, and execution will resume at the breakpointed instruction without generating another breakpoint for the same instruction.

Code breakpoints are the highest priority faults and are therefore guaranteed to be serviced before any other faults which may be detected during the decoding or execution of an

instruction. If after a debug fault, the RF flag is set and the debug handler retries the faulting instruction, it is possible that retrying the instruction will generate other faults. The restart of the instruction after these faults also occurs with the RF flag set, so repeated debug faults continue to be suppressed. The processor clears the RF flag only after *successful* completion of the instruction.

### 17.3.1.2. DATA MEMORY AND I/O BREAKPOINTS

Data memory and I/O breakpoint exceptions are traps; i.e., the processor generates an exception for a breakpoint after executing the instruction which accesses the breakpointed memory or I/O location.

Because data breakpoints are traps, the original data is overwritten before the trap exception is generated. If a debugger needs to save the contents of a write breakpoint location, it should save the original contents before setting the breakpoint. The handler can report the saved value after the breakpoint is triggered. The data in the debug registers can be used to address the new value stored by the instruction which triggered the breakpoint.

The Pentium processor, like the Intel486 processor, ignores the GE and LE bits in DR7. If any of the *Ln/Gn* bits is set (or single stepping is enabled), instruction pairing is inhibited and the Pentium processor slows execution so that most breakpoints are reported exactly on the instruction that generated them. In the Intel386 DX processor, exact data breakpoint matching does not occur unless it is enabled by setting either the LE or the GE bit.

The Pentium processor, however, is unable to report data breakpoints exactly for the REP MOVS and REP STOS instructions until the completion of the iteration after the one in which the breakpoint occurs in order to be able to execute the load, store, updates to ESI, EDI and ECX and the check for completion on each iteration of these REpeated instructions in a single clock.

Repeated INS and OUTS instructions that generate an I/O breakpoint debug exception, trap after the completion of the first iteration. Repeated INS and OUTS instructions that generate a memory breakpoint debug exception trap after the iteration in which the memory address breakpoint location is accessed.

### 17.3.1.3. GENERAL-DETECT FAULT

The general-detect fault occurs when an attempt is made to use the debug registers at the same time they are being used by in-circuit emulation when the GD bit in DR7 is set to one. This additional protection feature guarantees that emulators can have full control over the debug registers when required. The exception handler can detect this condition by checking the state of the BD bit of the DR6 register.



#### 17.3.1.4. SINGLE-STEP TRAP

This trap occurs if the TF flag was set before the instruction was executed. Note that the exception does not occur after an instruction which sets the TF flag. For example, if the POPF instruction is used to set the TF flag, a single-step trap does not occur until after the instruction following the POPF instruction.

The processor clears the TF flag before calling the exception handler. If the TF flag was set in a TSS at the time of a task switch, the exception occurs after the first instruction is executed in the new task.

The single-step flag normally is not cleared by privilege changes inside a task. The INT instructions, however, do clear the TF flag. Therefore, software debuggers which single-step code must recognize and emulate INT *n* or INTO instructions rather than executing them directly. To maintain protection, the operating system should check the current execution privilege level after any single-step trap to see if single stepping should continue at the current privilege level.

The interrupt priorities guarantee that, if an external interrupt occurs, single stepping stops. When both an external interrupt and a single step interrupt occur together, the single step interrupt is processed first. This clears the TF flag. After saving the return address or switching tasks, the external interrupt input is examined before the first instruction of the single step handler executes. If the external interrupt is still pending, then it is serviced. The external interrupt handler does not run in single-step mode. To single step an interrupt handler, single step an INTn instruction which calls the interrupt handler.

#### 17.3.1.5. TASK-SWITCH TRAP

The debug exception also occurs after a task switch if the T bit of the new task's TSS is set. The exception occurs after control has passed to the new task, but before the first instruction of that task is executed. The exception handler can detect this condition by examining the BT bit of the DR6 register.

Note that, if the debug exception handler is a task, the T bit of its TSS should not be set. Failure to observe this rule will put the processor in a loop.

### 17.3.2. Interrupt 3—Breakpoint Instruction

The breakpoint trap is caused by execution of the INT 3 instruction. Typically, a debugger prepares a breakpoint by replacing the first opcode byte of an instruction with the opcode for the breakpoint instruction. When execution of the INT 3 instruction calls the exception handler, the return address points to the first byte of the instruction following the INT 3 instruction.

With older processors, this feature is used extensively for setting instruction breakpoints. With the Pentium, Intel486, and Intel386 processors, this use is more easily handled using the debug registers. However, the breakpoint exception still is useful for breakpointing debuggers, because the breakpoint exception can call another exception handler. The breakpoint exception also can be useful when it is necessary to set a greater number of breakpoints than permitted by the debug registers, or when breakpoints are being placed in the source code of a program under development.



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**Caching, Pipelining  
and Buffering**





## CHAPTER 18

# CACHING, PIPELINING AND BUFFERING

The Pentium processor has many features that work together to yield extremely high performance — features such as caches, buffers, and pipelining. In general, these features work behind the scenes; that is, programs automatically run faster without having to explicitly take these performance features into account. In spite of this transparent implementation, some programmers may wish to take maximum advantage of these features. This chapter provides the information necessary to do so. It also documents the few cases in which systems programmers must explicitly take these performance features into account. The features discussed are:

- Internal instruction and data caches.
- ⊗ Address translation caches.
- ⊗ Prefetch queues.
- ⊗ Write buffers.
- ⊗ Execution pipelining.

### 18.1. INTERNAL INSTRUCTION AND DATA CACHES

The Pentium microprocessor has separate data and instruction caches on-chip. Caches raise system performance by satisfying an internal read request more quickly than a bus cycle to memory. They also reduce the processor's use of the external bus when the same locations are accessed multiple times. Having separate caches for instructions and data allows simultaneous cache look-up. Up to two data references and up to 32 bytes of raw opcodes can be accessed in one clock. The caches are fully transparent to applications software.

Caching is available in all execution modes: real mode, protected mode, and virtual-8086 mode. For a properly designed, single-processor system, the caching does not require further control once it is enabled during system initialization.

The data and instruction caches hold 8K bytes each. The cache line width of the Pentium processor is 256 bits or 32 bytes. A line can be filled from memory with a four-transfer burst cycle. External caches are not likely to use cache lines smaller than those of the internal cache.

Cache lines can only be mapped to 32-byte aligned blocks of main memory. (A 32-byte aligned block begins at an address which is clear in its low-order five bits.) The caches do not support partially-filled cache lines, so caching even a single doubleword requires caching an entire line.

The processor allows any area of memory to be cached, although both software and hardware can disallow certain areas from being cached — software by setting the PCD bit in the

respective page table entries; hardware by deasserting the **KEN#** signal for bus cycles with addresses that fall within those areas. When both software and hardware agree that a requested datum is cacheable, the processor reads an entire 32-byte line into the appropriate cache. This operation is called a *cache line fill*. Cache line fills are generated only for read misses, not for write misses. A store that misses the cache does not copy the missed line into cache from memory, but rather posts the datum in a write buffer, then sends it to the external bus when the bus is available.

The CPU can use an external second-level cache outside of the processor chip. An external cache can improve performance by providing a larger cache or wider line, or by allowing the processor bus to run faster than the memory bus.

Caches require special consideration in multiprocessor systems. When one processor accesses data cached in another processor, it must not receive incorrect data. If it modifies data, all other processors which access that data must receive the modified data. This property is called *cache consistency*. The CPU provides mechanisms which maintain cache consistency in the presence of multiple processors and external caches.

The operation of internal and external caches is transparent to application software, but knowledge of the behavior of these caches may be useful in optimizing software performance. For example, knowledge of cache dimensions and replacement algorithms are an indication of how large of a data structure can be operated on at once without causing cache thrashing. In multiprocessor systems, maintenance of cache consistency may, in rare circumstances, require intervention by system software. For these rare cases, the Pentium microprocessor provides privileged cache control operations.

### 18.1.1. Data Cache

In the data cache, a cache protocol known as MESI maintains consistency with caches of other processors and with an external cache. The data cache has two status bits per tag; so, each line can be in one of the states defined in Table 18-1. The state of a cache line can change as the result of either internal or external activity related to that line. In general, the operation of the MESI protocol is transparent to programs.

**Table 18-1. MESI Cache Line States**

Cache Line State:	M Modified	E Exclusive	S Shared	I Invalid
This cache line is valid?	Yes	Yes	Yes	No
The memory copy is...	...out of date	...valid	...valid	—
Copies exist in caches of other processors?	No	No	Maybe	Maybe
A write to this line ...	...does not go to bus	...does not go to bus	...goes to bus and updates cache	...goes directly to bus

### 18.1.2. Data Cache Update Policies

A cache adheres to an *update policy* to determine when a write operation must update main memory. (The update policy does not affect read operations.) The update policies supported by the Pentium microprocessor data cache are:

- *Writethrough* — a write request to a line in the cache triggers updates to both cache memory and main memory. Writethrough is useful for applications such as a graphics frame buffer, where writes must update memory so that they can be seen on the graphics display.
- *Writeback* — a write request to a line in the cache updates only the cache memory. The writeback policy reduces bus traffic by eliminating many unnecessary writes to memory. Writes to a line in the cache are not immediately forwarded to main memory; instead, they are accumulated in the cache. The modified cache line is written to main memory later, when a writeback operation is performed. Writeback operations are triggered when cache lines need to be deallocated, such as when new cache lines are being allocated in a cache which is already full. Writeback operations also are triggered by the mechanisms used to maintain cache consistency.

The processor allows any area of memory to be subject to either policy. Both software and hardware have control over which policy is employed — software through the PWT bit of page table entries; hardware through the WB/WT# signal.

The internal caches of the Pentium microprocessor can be used with external caches which are writethrough, writeback, or a mixture of both.

### 18.1.3. Instruction Cache

The instruction cache implements only the "SI" part of the MESI protocol, because the instruction cache is not writable.

The instruction cache monitors changes in the data cache to maintain consistency between the caches when instructions are modified. For more information, refer to Section 18.2.3.

## 18.2. OPERATION OF THE INTERNAL CACHES

Software controls the operating mode of the caches by setting or clearing the CD and NW bits of CR0. These bits after RESET are set to one (cache disabled). Software can leave caching disabled, or software can enable caching by updating the CD bit and NW bits of CR0.

### 18.2.1. Cache Control Bits

Table 18-2 summarizes the modes controlled by the CD and NW bits of CR0. For normal operation and highest performance, these bits should be set to zero. To completely disable the cache, the following two steps must be performed:

1. CD and NW must be set to 1.
2. The caches must be flushed.

If the cache is not flushed, cache hits on reads will still occur and data will be read from the cache. In addition, the cache must be flushed after being disabled to prevent any inconsistencies with main memory.

**Table 18-2. Cache Operating Modes**

CD	NW	Purpose/Description
0	0	<p><b>Normal highest performance cache operation.</b></p> <p>Read hits access the cache.            Read misses may cause replacement.            Write hits update the cache.            Only writes to shared lines and write misses appear externally.            Write hits can change shared lines to exclusive under control of WB/WT#.            Invalidation is allowed.</p>
0	1	<p><b>Invalid setting.</b></p> <p>A general-protection exception with an error code of zero is generated.</p>
1	0	<p><b>Cache disabled. Memory consistency maintained. Existing contents locked in cache.</b></p> <p>Read hits access the cache.            Read misses do not cause replacement.            Write hits update cache.            Only write hits to shared lines and write misses update memory.            Write hits can change shared lines to exclusive under control of WB/WT#.            Invalidation is allowed.</p>
1	1	<p><b>Cache disabled. Memory consistency not maintained.</b></p> <p>Read hits access the cache.            Read misses do not cause replacement.            Write hits update cache but not memory.            Write hits change exclusive lines to modified.            Shared lines remain shared after write hit.            Write misses access memory.            Invalidation is inhibited.</p>

### 18.2.2. Cache Management Instructions

The INVD and WBINVD instructions are used to invalidate the contents of the internal and external caches. The INVD instruction invalidates all internal (data and instruction) cache

entries and generates a special bus cycle which indicates that external caches also should be invalidated. (The response of external hardware to receiving a cache invalidation bus cycle is dependent on system implementation.) INVD should be used with care. It does not writeback modified cache lines; therefore, it can cause the data cache to become inconsistent with other memories in the system. Unless there is a specific requirement or benefit to invalidate a cache without writing back the modified lines (i.e., testing or fault recovery where cache coherency with main memory is not a concern), software should use the WBINVD instruction.

The WBINVD instruction first writes back any modified lines in the data cache, then invalidates the contents of its instruction and data caches. It ensures that cache coherency with main memory will be maintained regardless of system configuration (i.e., writethrough or writeback). Following this, it generates special bus cycles to indicate that external caches should also writeback modified data and invalidate their contents.

### 18.2.3. Self-Modifying Code

Unlike the Intel486 microprocessor, the Pentium microprocessor has separate caches for data and instructions. In spite of this difference in implementation, the Pentium microprocessor supports updates to instructions in a manner that is completely compatible with the Intel486 microprocessor. See section 23.2.17.5 for further clarification.

A write to an instruction that is in the instruction cache causes the instruction to be invalidated in the instruction cache. This check is based on the physical address of the instruction. In addition, the Pentium microprocessor checks whether a write may modify an instruction that has been prefetched for execution; if so, it invalidates the prefetch queue. This check is based on the linear address of the instruction.

Because the linear address of the write is checked against the linear address of the instructions that have been prefetched, special care must be taken for self-modifying code to work correctly when the physical addresses of the instruction and the written data are the same, but the linear addresses differ. In such cases, it is necessary to execute a serializing operation after the write and before executing the modified instruction. See the section on serializing operations below for more information. (Note that the check on linear addresses described above is not in practice a concern for compatibility. Applications that include self-modifying code use the same linear address for modifying and fetching the instruction. Systems software, such as a debugger, that might possibly modify an instruction using a different linear address than that used to fetch the instruction, will execute a serializing operation, such as IRET, before the modified instruction is executed.)

## 18.3. PAGE-LEVEL CACHE MANAGEMENT

When paging is enabled, two bits in entries of the page directory and second-level page tables are used to manage the caching of pages and to drive processor output pins. (These bits are reserved on Intel386 processors.)

The PCD and PWT bits control caching on a page-by-page basis. The PCD bit (page-level cache disable) affects the operation of the internal cache. Both the PCD bit and the PWT bit (page-level writethrough) drive processor output pins (called PCD and PWT) for controlling external caches. The treatment of these signals by external hardware depends on system design; for example, some hardware systems may control the caching of pages by decoding some of the high address bits.

There are three potential sources of the bits used to drive the PCD and PWT outputs of the processor: the CR3 register, the page directory, and the second-level page tables. The processor outputs are driven by the CR3 register for bus cycles where paging is not used to generate the address, such as the loading of an entry in the page directory. The outputs are driven by a page directory entry when an entry from a second-level page table is accessed. The outputs are driven by a second-level page table entry when instructions or data in memory are accessed. When paging is disabled, these bits are ignored (that is, the CPU assumes PCD=1 and PWT=1). See Chapter 9 for descriptions of the PCD and PWT bits in CR3.

### 18.3.1. PCD Bit

When the PCD bit of a page table entry is set, caching of data from the page is disabled, even if hardware requests caching by asserting the KEN# input. When the PCD bit is clear, caching may be requested by hardware on a cycle-by-cycle basis.

The ability to disable caching is useful for pages which contain memory-mapped I/O ports and for pages which do not provide a performance benefit when cached, such as initialization software.

Regardless of the page-table entries, the processor ignores the PCD output (i.e., assumes PCD=1) whenever the CD (Cache Disable) bit in CR0 is set.

### 18.3.2. PWT Bit

When a page table entry has a set PWT bit (bit position 3), a writethrough caching policy is specified for data in the corresponding page. Clearing the PWT bit on the Pentium microprocessor enables a writeback policy for the page. External caches can also use the output signal driven by the PWT bit to control update policy on a page-by-page basis.

## 18.4. ADDRESS TRANSLATION CACHES

Refer to Chapter 11 for information on the address translation caches (TLBs).



## 18.5. CACHE REPLACEMENT ALGORITHM

The data, instruction caches use a least-recently-used (LRU) algorithm to choose which line of a set is overwritten when a miss causes a line fill and all lines in the set contain valid data. The address-translation cache uses a psuedo-LRU algorithm. These algorithms are controlled by LRU bits in the tags of each cache. The states of the valid bits take precedence over the LRU bits. If any of the lines in the set is invalid, an invalid line is used for the line fill, and the LRU bits are not used. RESET initializes the valid bits so that two Pentium processors executing the same code on identical boards have exactly the same series of cache hits, misses, and replacements.

## 18.6. EXECUTION PIPELINING AND PAIRING

The Pentium processor achieves approximately two times the integer execution speed of the Intel486 microprocessor through a superscalar architecture capable of executing two instructions in parallel. Two pipelines operate in parallel allowing integer instructions to execute in a single clock in each pipeline. The allocation of instructions to a pipeline is performed automatically by the processor. The processor preserves the appearance of strict sequential execution even in the presence of interrupts and exceptions.

## 18.7. WRITE BUFFERS

The Pentium processor utilizes write buffers for memory operands and for each pipeline. Write buffers improve performance by allowing the processor to proceed with the next pair of instructions even though one of the current instructions writes to memory when the bus is busy. The write buffers can be filled in parallel when instructions in both pipes write to memory during the same clock; however, they are always emptied in the same sequence in which the write requests were generated by software.

In general, the existence of these buffers is transparent to programmers. The Pentium processor ensures that memory read operations are never reordered ahead of prior pending write operations; however, for compatibility with future processors, programmers should follow the ordering guidelines presented in Chapter 19. Refer also to Chapter 15 for information about the interaction of I/O instructions with the memory write buffers.

## 18.8. SERIALIZING INSTRUCTIONS

After executing certain instructions the Pentium processor serializes instruction execution. This means that any modifications to flags, registers, and memory for previous instructions are completed before the next instruction is fetched and executed. For example, when a new value is loaded into CR0 to enable protected mode, the processor always fetches the next instruction with protection enabled.

When the processor serializes instruction execution, it ensures that it has completed any modifications to memory, including flushing any internally buffered stores; it then waits for

the EWBE# pin to go active before fetching and executing the next instruction. Pentium processor systems can use the EWBE# pin to indicate that a store is pending externally. In this manner, a system designer can ensure that all externally pending stores are complete before the processor begins to fetch and execute the next instruction.

The processor serializes instruction execution after executing any of the following instructions:

CPUID	LGDT	MOV to Debug Register
INVD	LIDT	MOV to Control Register
INVLPG	LLDT	RSM
IRET	LTR	WBINVD
IRETD		WRMSR

The CPUID instruction can be executed at any privilege level to serialize instruction execution.

With regard to serialization, note that:

1. The Pentium processor does not generally writeback the contents of modified data in its data cache to external memory when it serializes instruction execution. Software can force modified data to be written back by executing the instruction WBINVD.
2. Whenever an instruction is executed to enable/disable paging (that is, change the PG bit of CR0), this instruction must be followed with a jump. The instruction at the target of the branch is fetched with the new value of PG (i.e., paging enabled/disabled), however, the jump instruction itself is fetched with the previous value of PG. Intel386, Intel486 and Pentium processors have slightly different requirements in this regard. See Chapter 23 for more information. In all other respects a MOV to CR0 that changes PG is serializing. Any MOV to CR0 that does not change PG is completely serializing.
3. Whenever an instruction is executed to change the contents of CR3 while paging is enabled, the next instruction is fetched using the translation tables that correspond to the new value of CR3. Therefore the next instruction and the sequentially following instructions should have a mapping based upon the new value of CR3.
4. The Pentium processor implements branch-prediction techniques to improve performance by prefetching the destination of a branch instruction before the branch instruction is executed. Consequently, instruction execution is not generally serialized when a branch instruction is executed.
5. The I/O instructions are not completely serializing; the processor does not wait for these instructions to complete before it prefetches the next instruction. However, they do have some serializing properties that cause them to function in a manner that is compatible with processor generations prior to the Pentium processor. Refer to Chapter 15 for more information.

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# **Multiprocessing**



## CHAPTER 19 MULTIPROCESSING

The Pentium processor supports multiprocessing both on the processor bus and on a memory bus via secondary cache units. Due to the high bandwidth demands of multiprocessor systems Intel recommends the use of secondary cache.

Multiprocessors can increase particular aspects of system performance. For example, a computer graphics system may use an i860 CPU for fast rendering of raster images, while a Pentium processor is used to support a standard operating system, such as UNIX, IBM OS/2\*, or Microsoft Windows\*. Or alternatively, multiple Pentium microprocessors can be used in a symmetric system architecture with an operating system such as multiprocessor UNIX. Multiprocessing systems are sensitive to the following design issues:

- *Maintaining cache consistency*—When one processor accesses data cached in another processor, it must not receive incorrect data. If it modifies data, all other processors which access that data must receive the modified data.
- *Reliable communication*—Processors need to be able to communicate with each other in a way which eliminates interference when more than one processor simultaneously accesses the same area in memory.
- *Write ordering*—In some circumstances, it is important that memory writes be observed externally in precisely the same order as programmed.

Cache consistency is discussed in Chapter 18. Reliable communication and write ordering are discussed in the following sections.

### 19.1. LOCKED BUS CYCLES

While the system architecture of multiprocessor systems varies greatly, they generally have a need for reliable communication with memory. A processor in the act of updating the Accessed bit of a segment descriptor, for example, should reject other attempts to update the descriptor until the operation is complete.

It also is necessary to have reliable communication with other processors. Bus masters need to exchange data in a reliable way. For example, a bit in memory may be shared by several bus masters for use as a signal that some resource, such as a peripheral device, is idle. A bus master may test this bit, see that the resource is free, and change the state of the bit. The state would indicate to other potential bus masters that the resource is in use. A problem could arise if another bus master reads the bit between the time the first bus master reads the bit and the time the state of the bit is changed. This condition would indicate to both potential bus masters that the resource is free. They may interfere with each other as they both attempt to use the resource. The processor prevents this problem through support of locked bus cycles; requests for control of the bus are ignored during locked cycles.

The Pentium processor protects the integrity of certain critical memory operations by asserting an output signal called LOCK#. It is the responsibility of the hardware designer to use these signals to control memory access among processors.

The processor automatically asserts one of these signals during certain critical memory operations. Software can specify which other memory operations need to have LOCK# asserted.

The features of the general-purpose multiprocessing interface include:

- The LOCK# signal, which appears on a pin of the processor.
- The LOCK instruction prefix, which allows software to assert LOCK#.
- Automatic assertion of LOCK# for some kinds of memory operations.

### 19.1.1. LOCK Prefix and the LOCK# Signal

The LOCK prefix and its bus signal only should be used to prevent other bus masters from interrupting a data movement operation. The LOCK prefix can be used with the following Pentium processor instructions when they modify memory. An invalid-opcode exception results from using the LOCK prefix before any other instruction, or with these instructions when no write operation is made to memory (i.e., when the destination operand is in a register).

- Bit test and change: the BTS, BTR, and BTC instructions.
- Exchange: the XCHG, XADD, CMPXCHG, and CMPXCHG8B instructions (no LOCK prefix is needed for the XCHG instruction).
- One-operand arithmetic and logical: the INC, DEC, NOT, NEG instructions.
- Two-operand arithmetic and logical: the ADD, ADC, SUB, SBB, AND, OR, and XOR instructions.

A locked instruction is *guaranteed* to lock only the area of memory defined by the destination operand, but may lock a larger memory area. For example, typical 8086 and 80286 configurations lock the entire physical memory space.

Semaphores (shared memory used for signalling between multiple processors) should be accessed using identical address and length. For example, if one processor accesses a semaphore using word access, other processors should not access the semaphore using byte access.

The integrity of the lock is not affected by the alignment of the memory field. The LOCK# signal is asserted for as many bus cycles as necessary to update the entire operand.

### 19.1.2. Automatic Locking

There are some critical memory operations for which the processor automatically asserts the LOCK# signal. These operations are:



- Acknowledging interrupts. After an interrupt request, the interrupt controller uses the data bus to send the interrupt vector of the source of the interrupt to the processor. The processor asserts LOCK# to ensure no other data appears on the data bus during this time.
- Setting the Busy bit of a TSS descriptor. The processor tests and sets the Busy bit in the Type field of the TSS descriptor when switching to a task. To ensure that two different processors do not switch to the same task simultaneously, the processor asserts the LOCK# signal while testing and setting this bit.
- Updating segment descriptors. When loading a segment descriptor, the processor will set the Accessed bit if the bit is clear. During this operation, the processor asserts LOCK# so the descriptor will not be modified by another processor while it is being updated. For this action to be effective, operating-system procedures which update descriptors should use the following steps:
  - Use a locked operation when updating the access-rights byte to mark the descriptor not-present, and specify a value for the Type field which indicates the descriptor is being updated.
  - Update the fields of the descriptor. (This may require several memory accesses; therefore, LOCK cannot be used.)
  - Use a locked operation when updating the access-rights byte to mark the descriptor as valid and present.Note that the Intel386 DX processor always updates the Accessed bit, whether it is clear or not. The Intel486 and Pentium processors only update the Accessed bit if it is not already set.
- Updating page-directory and page-table entries. When updating page-directory and page-table entries, the processor uses locked cycles to set the Accessed and Dirty bits.
- Executing an XCHG instruction. The Pentium processor always asserts LOCK# during an XCHG instruction which references memory (even if the LOCK prefix is not used).

## 19.2. MEMORY ACCESS ORDERING

The Pentium microprocessor is a strongly ordered machine. "Strongly ordered" means that, in spite of parallel instruction execution, internal and external cache inquiry writebacks, and write buffering, the order in which writes are programmed is the order in which they are observed externally. In the case of I/O operations, both reads and writes always appear in programmed order. However, to optimize performance, the Pentium processor allows memory reads to be reordered ahead of buffered writes in most situations. Internally, CPU reads (cache hits) can be reordered around buffered writes. Memory reordering does not occur externally at the pins, reads (cache miss) and writes appear in-order.

Strong ordering helps software designed for execution by a uniprocessor system work correctly in a multiprocessor or multimaster environment. Such software does not necessarily

consider the possible effect of the reordering of memory writes. Strong ordering, however, exacts a performance penalty and therefore may not be implemented in future processors.

Software intended to operate correctly in future, high-performance, weakly-ordered systems should not depend on the strongly ordered properties of the Pentium microprocessor. Instead, it should ensure that those accesses to shared variables which are intended to control concurrent execution among processors are explicitly ordered through the use of appropriate ordering operations. The ordering operations available on the Pentium microprocessor include the locking operations discussed in section 19.1. and the serializing operations discussed in Chapter 18.

### **19.3. PENTIUM PROCESSOR (735\90, 815\100, 1000\120, 1110\133) INTEGRATED APIC**

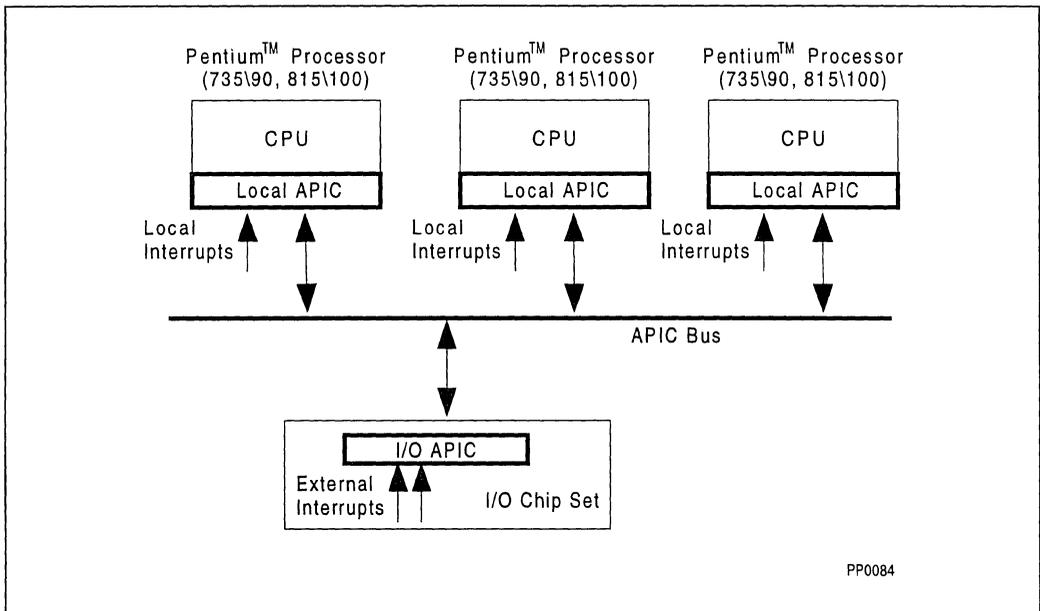
**APIC IS SUPPORTED ONLY ON PENTIUM PROCESSOR (735\90, 815\100, 1000\120, 1110\133) AND FUTURE PROLIFERATIONS AND UPGRADES.**

This section describes the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) Advanced Programmable Interrupt Controller (APIC). Within the Pentium processor family, the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) is the first microprocessor to provide an integrated APIC. The Pentium Processor (735\90, 815\100, 1000\120, 1110\133) APIC is software backward compatible with 82489DX, except for the differences described later in the chapter. The main features of the APIC architecture include:

- Multiprocessor interrupt management using static or dynamic distribution schemes.
- Dynamic distribution via interrupt routing to lowest priority processors.
- Inter-processor interrupts.
- Variety of addressing schemes.
- System-wide control functions such as NMI, INIT, System Management Interrupt (SMI) and Startup-Interprocessor Interrupt.
- 8259A-compatible mode.
- 32-bit counter generating *one-shot* or *periodic* interrupts.

For multiprocessor (MP) systems, the APIC architecture would generally have a decentralized implementation, consisting of two main components: a *Local APIC* and an *I/O APIC*. See Figure 19-1. The *I/O APIC* is part of the system chipset. It is responsible for capturing interrupts injected by I/O devices, and distributing them among Local APICs via the APIC Bus. The Local APICs control dispatching of interrupts to their corresponding processors.





**Figure 19-1. Local APIC Within a Pentium Processor (735\90, 815\100, 1000\120, 1110\133)-Based MP System**

The I/O APIC enables individual interrupt pins to be programmed by specifying the following information: a vector and its implied priority, the sensitivity to be recognized as an edge or as a level trigger, and the set of processors (one or more) to service the interrupt.

The Local APIC contains the necessary intelligence to determine whether it should accept interrupts broadcast on the APIC bus. The Local APIC provides functions such as queuing, nesting and masking of interrupts. It handles interrupt delivery protocol with its local processor and accesses to APIC registers, and also manages inter-processor interrupts and remote APIC register reads. In addition, each Local APIC includes a built-in Timer and local interrupt pins on which processor-specific interrupts can be injected. The local APIC can be disabled in hardware, or in software, and used in conjunction with a standard 8259A-style interrupt controller, as explained in Chapter 19 of *Pentium® Processor Family User's Manual*, Volume I.

#### NOTE

The focus of this chapter is on the Local APIC, and its implementation in the Pentium Processor (735\90, 815\100, 1000\120, 1110\133). Contact your chip set vendor for the information on I/O APIC.

In the register descriptions throughout this chapter, fields containing r's or <RESERVED> or <reserved> are reserved by the architecture. These bits are read as zeroes, unless specified

otherwise. For compatibility with future APIC implementations, the software must assign the last read values to all reserved bits when written.

### 19.3.1. Interrupt Control Mechanism

The following subsections present the major Local APIC elements and their role in the interrupt control mechanism. The description is built around APIC registers and functions associated with them.

#### 19.3.1.1. VALID INTERRUPTS

The APIC architecture supports 240 distinct vectors in the range of 16 to 255. Interrupt priority is implied by its vector, i.e.

$$\text{priority} = [\text{Vector} / 16]$$

where 1 is the lowest priority and 15 is the highest. Vectors 16 through 31 are reserved for exclusive use by the Pentium Processor (735\90, 815\100, 1000\120, 1110\133). The remaining vectors are for general use. The Pentium Processor (735\90, 815\100, 1000\120, 1110\133) Local APIC includes a 2-deep interrupt FIFO for each priority level. For best performance, the software is recommended to allocate up to two interrupt vectors belonging to the same priority.

#### 19.3.1.2. INTERRUPT SOURCES

Interrupts to the Local APIC arrive in one of the following manners:

- On local interrupt pins, from locally connected devices.
- As a bus message from the I/O APIC, originated by I/O devices, or
- As a bus message from another local APIC, originated as an interprocessor interrupt.
- Generated internally, by the local APIC programmable timer or the error register.
- As a software-generated self-interrupt.

The local APIC serves the I/O APIC and interprocessor interrupts according to the information included in the bus message (such as vector, trigger type, interrupt destination, etc.). The APIC Local pins and the timer interrupts interpretation is programmed via a structure called Local Vector Table (LVT). To generate an interprocessor interrupt, the source processor programs its Interrupt Command Register (ICR). The programming of the ICR causes generation of a corresponding interrupt bus message. The LVT and the ICR programming is explained in detail in sections 19.3.1.7 and 19.3.1.8, respectively.

#### 19.3.1.3. BUS ARBITRATION

Being connected on a common bus, the local and the I/O APICs have to arbitrate to get a grant for sending a message on the bus. Logically, the bus is a wired-OR connection, enabling more than one APIC to start sending its message. Each APIC issues its arbitration

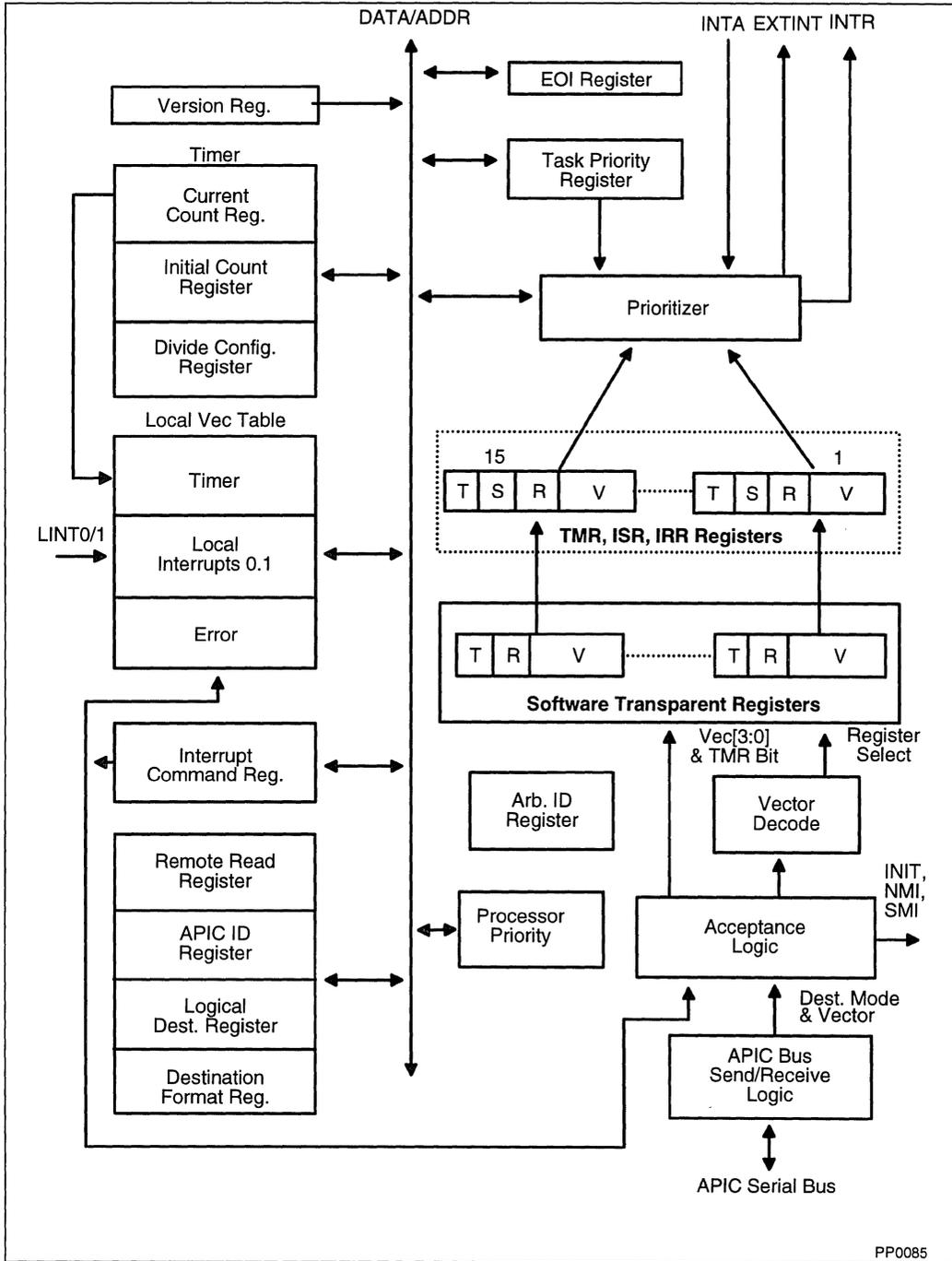


priority at the beginning of each message, and one winner is collectively selected. At any given time the arbitration priority (kept in a software-transparent 4-bit Arb ID register) is a unique value for every APIC agent. It is initially set after Reset. The arbitration priority is dynamically modified after each successfully transmitted message to preserve fairness.

Section 19.3.2 describes the existing arbitration protocols and bus message formats, while Section 19.3.1.8 includes a definition of an *INIT Level De-assert* message, used to resynchronize all APIC agents Arb IDs. Note that except for start-up and remote-read interprocessor interrupts (defined below), all bus messages failing during delivery are automatically retried. The software should be aware of situations in which interrupt messages are being "ignored" by disabled or nonexistent target APIC agents, and messages are resent again and again.

#### 19.3.1.4. THE LOCAL APIC STRUCTURE

Figure 19-2 depicts the Local APIC block diagram. Software interacts with the Local APIC by reading and writing its registers. The registers are memory-mapped, and for each processor they have an identical address space of 4Kbytes starting at address 0FEE0000 (hex). The register address allocation scheme is shown in table 19-6. Register offsets are aligned on 128-bit boundaries. All registers are accessed using 32-bit loads and stores. Wider registers (64-bit or 256-bit) are defined and accessed as independent multiple 32-bit registers.



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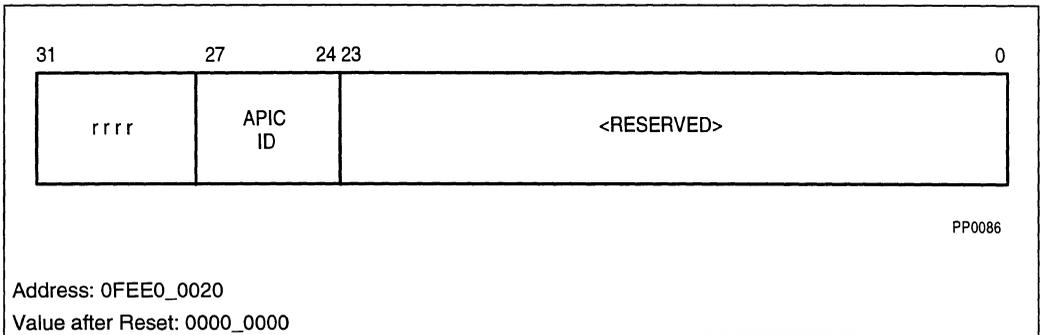
Figure 19-2. Local APIC Structure

### 19.3.1.5. INTERRUPT DESTINATION AND APIC ID

The destination of an interrupt can be *one*, *all* or a *subset* of processors in the system. The sender specifies the destination of an interrupt in one of two destination modes: *physical* or *logical*.

#### Physical Destination Mode

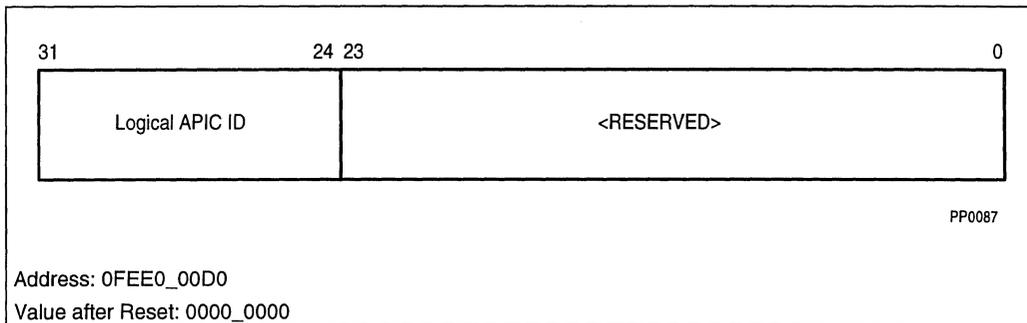
In the physical mode, the destination processor is specified by its APIC ID. This ID is matched against the APIC actual physical ID stored in the Local APIC ID register. See Figure 19-3. A single destination (ID = 0 through 14) or a broadcast to all (ID = 15) can be specified in the physical mode. Note that in this mode, the Pentium Processor (735\90, 815\100) APIC supports up to 15 agents. The APIC ID register is loaded at power up by sampling the values of four input pins. The ID portion can be read and modified by software.



**Figure 19-3. Local APIC ID Register**

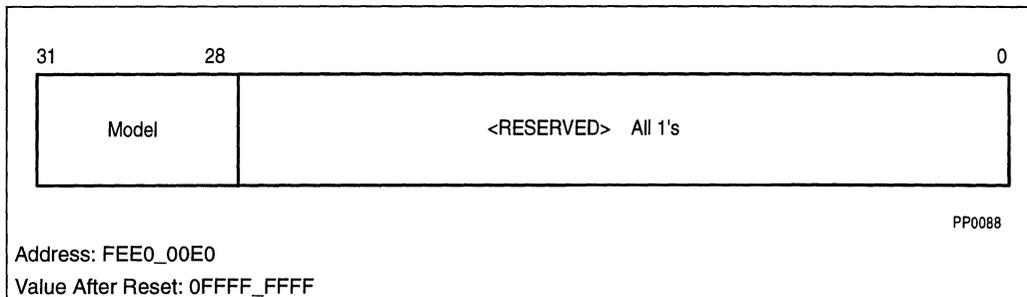
#### Logical Destination Mode

In the logical mode, message destinations are specified using an 8-bit message destination address (MDA). See section 19.3.2.2 for description of bus message formats. The MDA is compared against an 8-bit Logical APIC ID field of the APIC Logical Destination Register (LDR). See Figure 19-4.



**Figure 19-4. Logical Destination Register (LDR)**

Destination Format Register (DFR) defines the interpretation of the logical destination information. See Figure 19-5. The DFR and the LDR can be programmed to achieve a *Flat Model* or a *Cluster Model* interrupt delivery modes.



**Figure 19-5. Destination Format Register (DFR)**

**Flat Model**

For this model, bits 28 through 31 of the DFR must be programmed to 1111. The MDA is interpreted as a decoded address. This scheme allows the specification of arbitrary groups of APICs simply by setting the member’s bit to one in the corresponding LDR. In the Flat Model, up to 8 local APIC units can coexist in the system. Broadcast to all units is achieved by setting all 8 bits of the MDA to ones.

**Cluster Model**

For the Cluster Model, the DFR bits 28 through 31 should be programmed to 0000. There are two basic connection schemes: *flat cluster* and *hierarchical cluster*.

**Flat Cluster**

In the Flat Cluster model, all clusters are connected on a single APIC bus. MDA[31-28] contains the encoded address of the destination cluster. MDA[31-28] is compared against bits



LDR[31-28] to determine if the Local APIC is part of the cluster. MDA[27-24] is compared with LDR[27-24] to identify individual local APIC unit within the cluster. Arbitrary sets of processors within a cluster can be specified by writing the target cluster address in MDA[31-28] and setting selected bits in MDA[27-24], corresponding to the chosen members of the cluster. In this mode, 15 clusters (with cluster addresses of 0 through 14) each having 4 processors can be specified in the message. The APIC Arb ID, however, supports only 15 agents, and hence the total number of processors supported in this mode is limited to 15. Broadcast to all APICs is achieved by setting all destination bits to one. This guarantees a match on all clusters, and selects all APICs in each cluster.

### Hierarchical Network

An arbitrary hierarchical network can be created by connecting different flat clusters via independent APIC buses. This scheme requires a *cluster manager* within each cluster, responsible for handling message passing between APIC buses. One cluster contains up to 4 agents. Thus 15 cluster managers, each with 4 agents, can form a network of up to 60 APIC agents. Note that hierarchical APIC networks requires a special cluster manager device, which is not part of the local or the I/O APIC units.

#### 19.3.1.6. INTERRUPT DISTRIBUTION MODES

The APIC supports two schemes for selecting the destination processor: *Static* and *Dynamic*. The static scheme is used to access a specific processor in the network. The dynamic scheme enables the incoming interrupts to be assigned each time to a different, generally a less busy processor. The distribution scheme can be programmed in the LVT for local interrupt delivery, or the ICR for bus messages.

#### Static Scheme

Under this scheme, the interrupt is unconditionally delivered to all local APICs that match the destination information supplied with the interrupt. The following are delivery modes that fall into the static distribution category: *Fixed*, *SMI*, *NMI*, *ExtInt*, *Remote Read* and *StartUp*.

#### Dynamic Scheme

Under the dynamic scheme category, there is only one delivery mode called *Lowest Priority*. From all processors listed in the destination, the processor selected is the one whose current arbitration priority is the lowest. The latter is specified in the Arbitration Priority Register (APR), defined later in this chapter. If more than one processor share the lowest priority, the processor with the highest Arb ID (a unique value) is selected.

In the lowest priority mode, if there exists a *focus processor*, it will accept the interrupt, regardless of its priority. A processor is said to be a *focus* of an interrupt if it is currently servicing that interrupt, or if it has a pending request for that interrupt.

### 19.3.1.7. LOCAL VECTOR TABLE

The Local APIC contains a Local Vector Table (LVT), specifying interrupt delivery and status information for the locally interrupts. The information includes: the interrupt associated vector, delivery mode, status bits and other data as shown in Figure 19-6. The LVT incorporates four 32-bit entries. Entry 0 corresponds to the timer, entries 1 and 2 belong to the two local interrupt pins, and entry 3 is for the error interrupt.

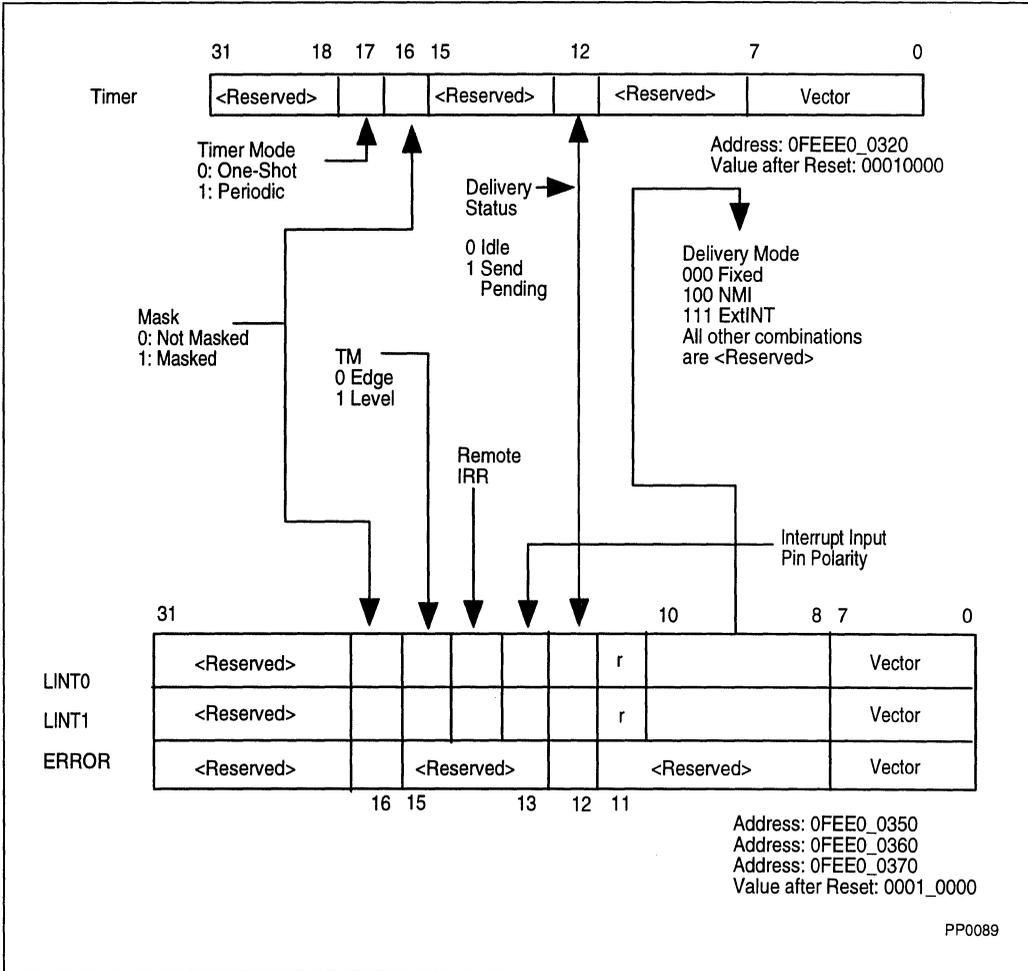


Figure 19-6. Local Vector Table (LVT)

- VECTOR

Interrupt vector number.

- DELIVERY MODE

This 3-bit field is defined only for the Local Interrupt entries 1 and 2. The timer and the Error Status Register (ESR) generate only edge triggered maskable interrupts to the local processor. The delivery Mode field does not exist for the timer and error interrupts. Note that certain delivery modes will only operate as intended when used in conjunction with a specific Trigger Mode.

**000 (Fixed):** deliver the interrupt, received on the local interrupt pin, to the processor as specified in the corresponding LVT entry. The Trigger Mode can be edge or level. Note, if the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) is not used in conjunction with an I/O APIC, the fixed delivery mode can be programmed for an edge-triggered interrupt only. This restriction may be relaxed in future implementations.

**100 (NMI):** deliver the interrupt, received on the local interrupt pin, to the processor as an NMI interrupt. The vector information is ignored. The NMI interrupt is treated as edge-triggered, even if programmed otherwise. Note that the NMI may be masked. It is the software's responsibility to program the LVT mask bit according to the desired behavior of NMI.

**111 (ExtINT):** deliver the interrupt, received on the local interrupt pin, to the processor and respond as if the interrupt originated in an externally connected (8259A-compatible) interrupt controller. A special INTA bus cycle corresponding to ExtINT, is routed to the external controller. The latter is expected to supply the vector information. "ExtINT" mode requires an edge-triggered interrupt. The APIC architecture supports only one ExtINT source in a system.

- DELIVERY STATUS

This is a 1-bit read-only field holding the current status of interrupt delivery. Two states are defined:

0 (Idle):                    There is currently no activity for this interrupt, or the previous interrupt from this source has been accepted.

1 (Send Pending):        Indicates that the interrupt has been injected, but the APIC has not yet completely accepted it.

- INTERRUPT INPUT PIN POLARITY

This bit specifies the polarity of the corresponding interrupt pin. A value of 0 means the signal is active-high and a value of 1 means the signal is active-low.

- REMOTE Interrupt Request Register (IRR) Bit

This bit is used for level triggered interrupts only, and its meaning is undefined for edge triggered interrupts. For level triggered interrupts, the bit is set when the logic of the Local APIC accepts the interrupt. The remote IRR bit is reset when an EOI command is received from the processor.

- **TRIGGER MODE**

- 0: edge sensitive,

- 1: level sensitive.

- Only the local interrupt pins can be programmed as edge or level triggered. The timer and error interrupts are always treated as edge triggered.

- **MASK**

- 0: enables injection of the interrupt,

- 1: inhibits injection of the interrupt.

- **TIMER MODE**

- 0: one-shot, 1: periodic. The timer is described in section 19.3.4.

### **19.3.1.8. INTER-PROCESSOR AND SELF INTERRUPTS**

A processor generates inter-processor interrupts by writing into the Interrupt Command Register (ICR) of its local APIC. See Figure 19-7.





The processor may use the ICR for self interrupts or for interrupting other processors (e.g., to forward device interrupts originally accepted by it to other processors for service). In addition, special inter-processor interrupts (IPI) such as the Start-Up message, can be delivered using the ICR mechanism. ICR-based interrupts are treated as edge triggered even if programmed otherwise.

All fields of the ICR are read-write by software with the exception of the Delivery Status and Remote Read Status fields which are read-only. Writing to the 32-bit word that contains the interrupt vector causes the interrupt message to be sent. The ICR consists of the following fields.

- **VECTOR**

The vector identifying the interrupt being sent. If the Delivery Mode is “Remote Read”, then the Vector field contains bits 11 through 4 (8 bits) of the register address to be read from the remote Local APIC unit. The Local APIC register addresses are summarized in Table 19-2.

- **DELIVERY MODE**

The Delivery Mode is a 3-bit field that specifies how the APICs listed in the destination field should act upon reception of the interrupt. Note that all interprocessor interrupts behave as edge triggered interrupts (except for INIT Level De-Assert message) even if they are programmed as level triggered interrupts.

**000 (Fixed):** Deliver the interrupt to all processors listed in the destination field according to the information provided in the ICR. The fixed interrupt is treated as an edge-triggered interrupt even if programmed otherwise.

**001 (Lowest Priority):** As above, except that the interrupt is delivered to the processor executing at the lowest priority among the set of processors listed in the destination.

**010 & Vector Field = 00(h) (SMI):** System Management Interrupt. Only the edge trigger mode is allowed. The vector field must be programmed to zero.

**011 (Remote Read):** Remote read interrupt is a request to a remote local APIC unit to send the value of one of its registers over the APIC bus. As explained above, the register is selected by setting its partial address (bits 11 through 4 of the register address) into the Vector field of the ICR. The register value is latched by the sending APIC and stored in the Remote Register where it can be read by the local processor. The Remote Read message must be sent to only one local APIC at a time. Only valid addresses can be used in the vector field. A value of 0FF(h) in the vector field is reserved for future use.

**100 (NMI):** Deliver the interrupt as an NMI interrupt to all processors listed in the destination field. The vector information is ignored. NMI is treated as an edge triggered interrupt even if programmed otherwise.

**101 (INIT):** Deliver the interrupt as an INIT signal to all processors listed in the destination field. As a result, all addressed APICs will assume their INIT state. As in the case of NMI, the vector information is ignored, and INIT is treated as an edge triggered interrupt even if programmed otherwise.

**101 & Trigger Mode = 1 & Level Mode = 0 (INIT Level De-Assert):** This special delivery mode is used as a synchronization message to **all APIC agents** to set their Arb IDs by the values of their APIC IDs. Note that the INIT interrupt is sent to all agents, regardless of the destination field value. However, at least one valid destination



processor should be specified. For future compatibility, the software is requested to use a broadcast-to-all ("all-incl-self" shorthand, as described below).

**110 (StartUp):** This delivery mode is used as a special message between two processors in the Dual-Processing configuration. For details refer to the *Pentium® Processor Family User's Manual*, Volume I. The Vector information contains the start-up address for the DP Boot-up protocol, as explained in Chapter 20 of the *Pentium® Processor Family Developer's Manual*, Volume 1. StartUp is treated as an edge triggered interrupt even if programmed otherwise.

#### NOTE

Remote Read and Start-Up interrupts are not automatically retried by the source APIC upon failure in delivery of the message. It is up to the software to decide whether a retry is needed in the case of failure, and issue a retry message accordingly.

- **DESTINATION MODE**
  - 0: Physical
  - 1: Logical
- **DELIVERY STATUS**
  - 0 (Idle): means that there is currently no activity for this interrupt.
  - 1 (Send Pending): indicates that the interrupt has been injected, but its delivery is temporarily delayed due to APIC bus being busy or the inability of the receiving APIC unit to accept the interrupt at that time.
- **LEVEL**

For *INIT Level De-Assert* delivery mode the level is 0. For all other modes the level is 1.
- **TRIGGER MODE**

This bit is used for the *INIT Level De-Assert* delivery mode only.
- **REMOTE READ STATUS**

This field indicates the status of the data contained in the Remote Read register. This field is read-only to software. Whenever software writes to the ICR using "Remote Read," the Remote Read status becomes "in-progress" (waiting for the remote data to arrive). The remote APIC is expected to respond at a specific APIC bus cycle, as explained in section 19.3.2. If the remote APIC is unable to do so, then the Remote Read status becomes "Invalid". If successful, the Remote Read status becomes "Valid". Software should poll the status bits to determine completion and success of the remote read message.
- **DESTINATION SHORTHAND:**

This field indicates whether a shorthand notation is used to specify the destination of the interrupt and if so, which shorthand is used. Destination shorthands do not use the 8-bit Destination field, and can be sent by software using a single write to the lower 32-bit part of the APIC Interrupt Command Register. Shorthands are defined for the following

cases: software self interrupt, interrupt to all processors in the system including the sender, interrupts to all processors in the system excluding the sender.

00: (dest field) No shorthand. The destination is specified in bits 56 to 63 of the ICR.

01: (self) The current APIC is the single destination of the interrupt. This is useful for software self interrupts. The destination field is ignored. See Table 19-7 for description of supported modes. Note that self interrupts do not generate bus messages.

10: (all incl self) The interrupt is sent to “all” processors in the system including the processor sending the interrupt. The APIC will broadcast a message with the destination field set to 0F(hex). See Table 19-7 for description of supported modes.

11: (all excl self) The interrupt is sent to “all” processors in the system with the exception of the processor sending the interrupt. The APIC will broadcast a message using the Physical Destination Mode and destination field set to 0F(hex).

- **DESTINATION**

This field is only used when the Destination Shorthand is set to “Dest Field”. If the destination mode is physical, then bits 56-59 contain the APIC ID. In logical mode, the interpretation of the 8-bit Destination field depends on the DFR and LDR of the Local APIC Units.

### 19.3.1.9. INTERRUPT ACCEPTANCE

Three 256-bit read-only registers are involved in the interrupt acceptance logic. See format in Figure 19-8. The 256 bits represents the 256 possible vectors. Because vectors 0-15 are reserved, so are bits 0-15 in these registers.

- **TMR (Trigger Mode Register)**

Upon acceptance of an interrupt, the corresponding TMR bit is cleared for edge triggered interrupts and set for level interrupts. If the TMR bit is set, the local APIC sends an EOI message to all I/O APICs as a result of software issuing an EOI command (see definition of EOI register in section 19.3.1.9.6).

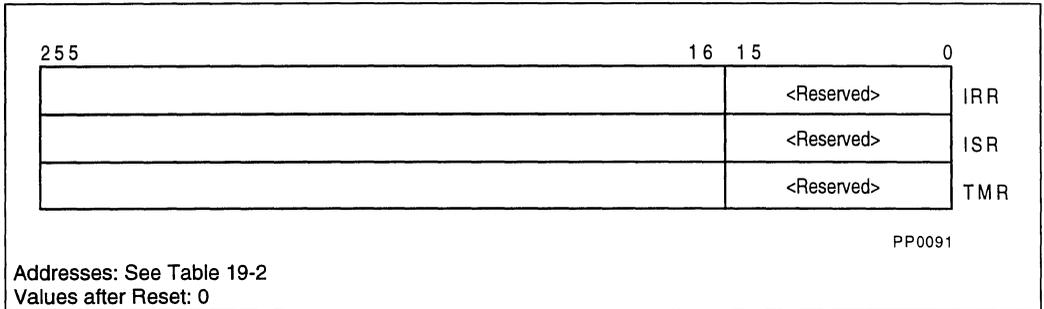
- **IRR (Interrupt Request Register)**

Contains the active interrupt requests that have been accepted, but not yet dispensed by the current Local APIC. A bit in IRR is set when the APIC accepts the interrupt. The IRR bit is cleared, and a corresponding ISR bit is set when the INTA cycle is issued.



- **ISR (In-Service Register)**

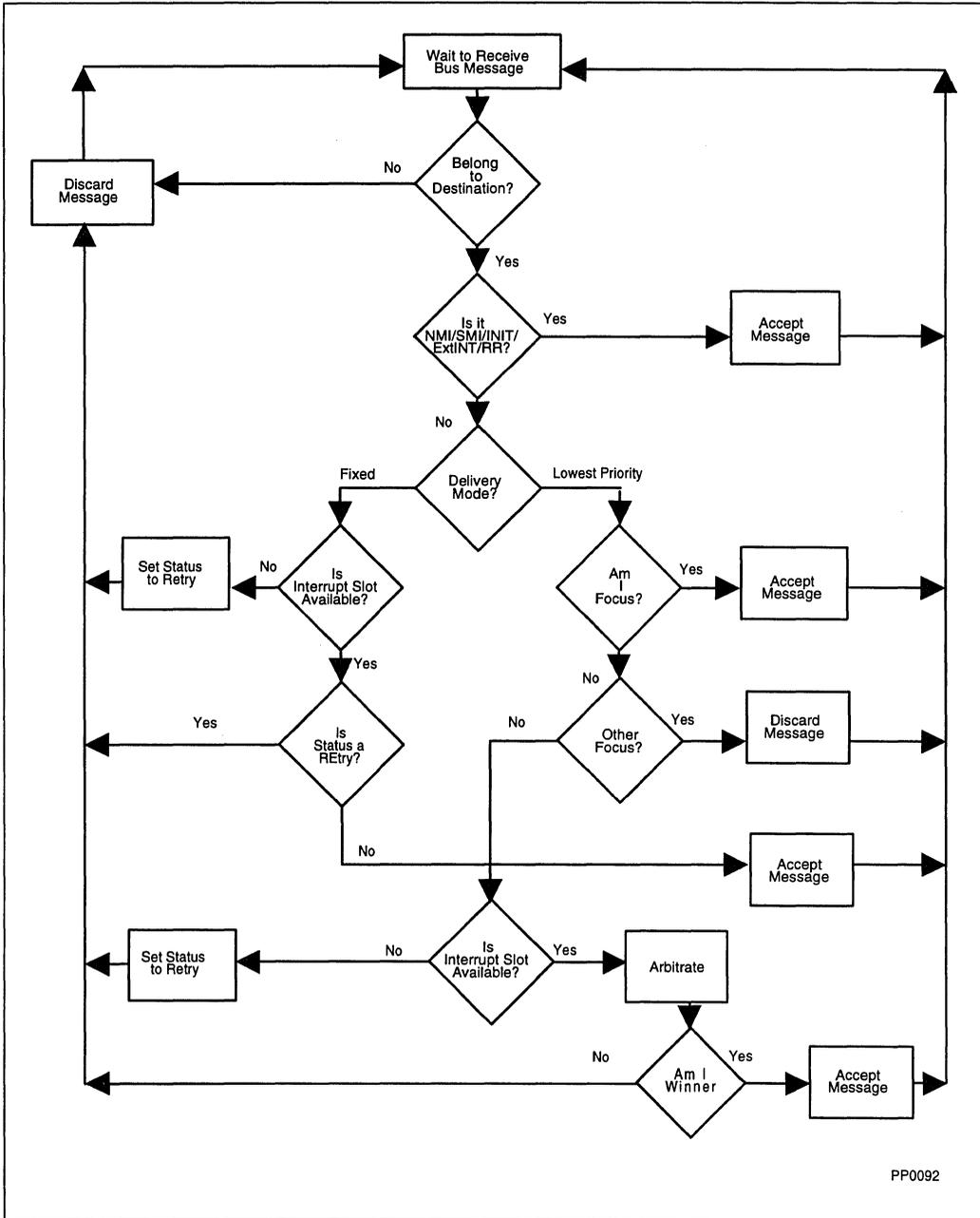
Marks the interrupts that have been delivered to the processor, but have not been fully serviced yet, as an EOI has not yet been received from the processor. The ISR reflects the current state of the processor interrupt queue. The ISR bit for the highest priority IRR is set during the INTA cycle. During the EOI cycle, the highest priority ISR bit is cleared, and if the corresponding TMR bit was set, an EOI message is sent to all I/O APICs.



**Figure 19-8. IRR, ISR and TMR Registers**

### 19.3.1.9.1. Interrupt Acceptance Decision Flow Chart

The acceptance decision process is illustrated in the following simplified flow chart.



PP0092

Figure 19-9. Interrupt Acceptance Flow Chart for Local APIC



Response of the Local APIC to the Start-Up IPI is explained in *Pentium® Processor Family User's Manual*, Volume I.

### 19.3.1.9.2. Task Priority Register

Task Priority Register (TPR) provides a "priority threshold" mechanism for interrupting the processor. Only interrupts whose priority is higher than that specified in the TPR will be serviced. Other interrupts are recorded and are serviced as soon as the TPR value is decreased enough to allow that. This enables the operating system to block temporarily specific interrupts (generally low priority) from disturbing high-priority tasks execution. The priority threshold mechanism is not applicable for delivery modes excluding the vector information, i.e. for ExtINT, NMI, SMI, INIT, INIT-Deassert, Start-Up and Remote Read.

The Task Priority is specified in the TPR, as illustrated in Figure 19-10. The 4 MSB of task priority correspond to 16 interrupt priorities, while the 4 LSB correspond to the sub-class priority. The TPR value is generally denoted as x:y, where x is the main priority while y provides more precision within a given priority class. When the x-value of the TPR is 15, the APIC will not accept any interrupts.

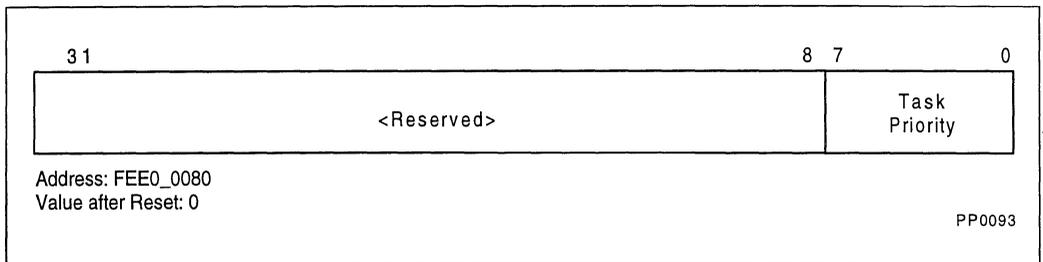


Figure 19-10. Task Priority Register (TPR)

### 19.3.1.9.3. Processor Priority Register (PPR)

The Processor Priority Register (PPR) is used to determine whether a pending interrupt can be dispensed to the processor. Its value is computed as the following.

*If* TPR[7:4] > ISRV[7:4] *then* PPR[7:0] = TPR[7:0]  
*else* PPR[7:4] = ISRV[7:4], PPR[3:0]=0.

Where ISRV is the vector of the highest priority ISR bit set, or zero if no ISR bit is set. The PPR format is identical to that of the TPR. The PPR address is 0FEE0\_00A0, and its value after Reset is zero.

### 19.3.1.9.4. Arbitration Priority Register (APR)

Arbitration Priority Register (APR) holds the current "lowest-priority" of the processor, a value used during Lowest Priority arbitration. See section 19.3.2. The APR format is identical to that of the TPR. The APR value is computed as the following.

*If (TPR[7:4] ≥ IRRV[7:4]) and (TPR[7:4] > ISRV[7:4]) then APR[7:0] = TPR[7:0]  
 else APR[7:4] = max(TPR[7:4], ISRV[7:4], IRRV[7:4]), APR[3:0]=0.*

Where IRRV is the vector of the highest priority IRR bit set, or zero if no IRR bit is set. The APR address is 0FEE0\_0090H, and its value after Reset is zero.

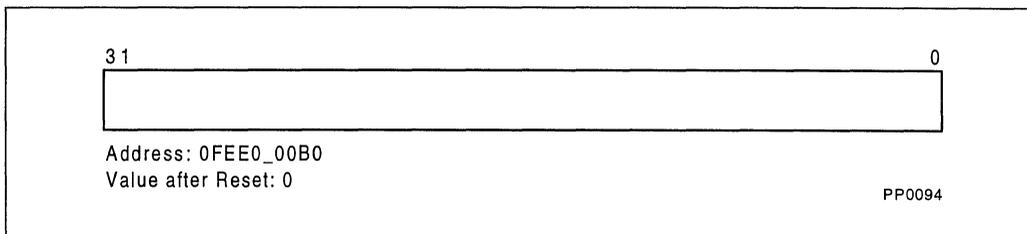
**19.3.1.9.5. Spurious Interrupt**

A special situation may occur when a processor raises its Task Priority to be greater than or equal to the level of the interrupt for which the Processor INTR signal is currently being asserted. If at the time the INTA cycle is issued, the interrupt that was to be dispensed has become masked (programmed by software), the Local APIC will return a spurious interrupt vector to the processor. Dispensing the spurious interrupt vector does not affect the ISR, so the handler for this vector should return without an EOI.

**19.3.1.9.6. End-Of-Interrupt (EOI)**

During the interrupt serving routine, the software should indicate acceptance of lowest-priority, fixed, timer and error interrupts by writing an arbitrary value into its local APIC End-Of-Interrupt (EOI) register. This is an indication for the local APIC it can issue the next interrupt, regardless of whether the current interrupt service has been terminated or not. Note that interrupts whose priority is higher than that currently in service, do not wait for the EOI command corresponding to the interrupt in service.

Upon receiving end-of-interrupt, the APIC clears the highest priority bit in the ISR and selects the next highest priority interrupt for posting to the CPU. If the terminated interrupt was a level-triggered interrupt, the local APIC sends an end-of-interrupt message to all I/O APICs. Note that EOI command is supplied for the above two interrupt delivery modes regardless of the interrupt source, i.e. as a result of either the I/O APIC interrupts or those issued on local pins or using the ICR. For future compatibility, the software is requested to issue the end-of-interrupt command by writing a value of 00000000h into the EOI register.

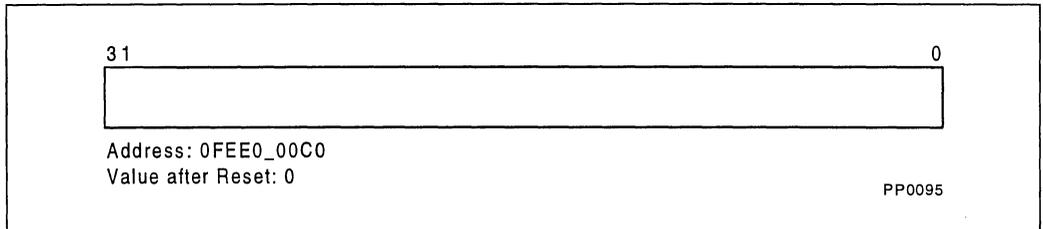


**Figure 19-11. EOI Register**

**19.3.1.10. READING REMOTE APIC REGISTERS**

Local APIC registers can only be accessed by the local processor. To read a register in a “remote” Local APIC unit, the processor writes to the ICR specifying a Delivery Mode of “Remote Read”. The remote APIC is specified in the Destination field of the ICR. Upon

receiving a “Remote Read,” the target APIC responds by placing a 32-bit content of the selected register on the APIC bus. This value is read by the sending APIC and placed in its Remote Read Register (RR), which can then be read by software. See Figure 19-12. The RR is software read-only, and is valid when the Delivery Status in the ICR becomes “Valid”. See “Remote Read Status” in section 19.3.1.8.



**Figure 19-12. Remote Register (RR)**

### 19.3.1.11. LOCAL APIC STATE

All Local Units are initialized in a software disabled state after power-up. A software disabled Local APIC unit responds only to self-interrupts and INIT, NMI, SMI, Remote Read and Start-Up messages arriving on the APIC Bus. The operation of local APICs during the disabled state is summarized below.

- For the above messages, the APIC behaves normally, as if fully enabled.
- Pending interrupts in the IRR and ISR registers will be held and will require masking or handling by the CPU.
- A disabled APIC does not affect the sending of APIC messages. It is software responsibility to avoid ICR commands if no sending of interrupts is desired.
- Disabling an APIC does not affect the message in progress. The local APIC will complete the reception/transmission of the current message and then enter the disabled state.
- A disabled APIC automatically sets all mask bits in the LVT entries. Trying to reset these bits in the local vector table will be ignored.
- A disabled APIC listens to all bus messages in order to keep its Arb ID synchronized with the rest of the system.

#### 19.3.1.11.1. Spurious Interrupt Vector Register

Software can enable or disable at any time the local unit by programming bit 8 of the Spurious interrupt Vector Register (SVR). See Figure 19-13.

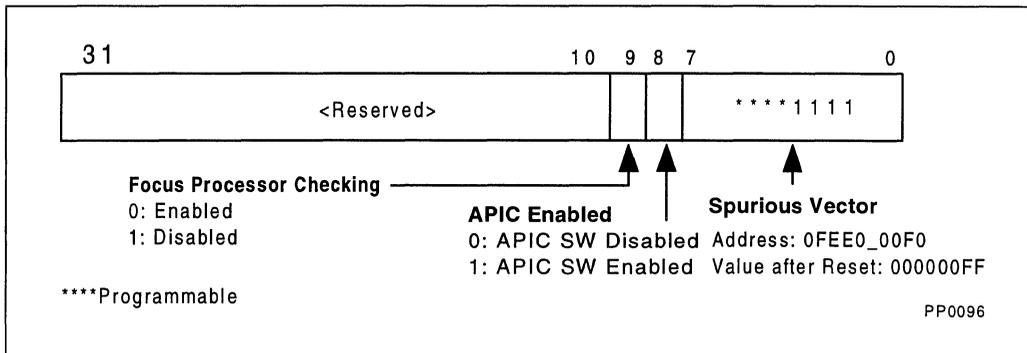


Figure 19-13. Spurious Interrupt Vector Register (SVR)

- **Spurious Vector:** The 8-bit interrupt vector is released during an INTA cycle when all pending interrupts are masked or when no interrupt is pending. Bits 4 to 7 of the Spurious Vector are programmable by software, and bits 0 to 3 are hardwired to logical ones. software writes to bits 0 to 3 have no effect.
- **Focus Processor Checking:** This bit defines if the focus processor checking is enabled during the lowest priority delivery. A value of 0 enables the focus checking mechanism, while a value of 1 disables it.

### 19.3.1.11.2. Local APIC Initialization

The Local APIC has a RESET input signal connected to its processor Reset line. On Reset, the Local APIC and its processor are initialized simultaneously. The local APIC obtains its physical ID at the falling edge of Reset by sampling four input pins and stores this value into the APIC ID register.

### 19.3.1.11.3. Local APIC State After Power-Up Reset and Init

#### Power-up Reset

The state of registers and state machines after a Power up Reset are as follows:

- IRR, ISR, TMR, ICR, TPR, Holding Registers, Timer Initial Count Register, Timer Current count register, Remote Register, LDR and Divide Configuration Register are all reset to 0.
- Destination Format Register is reset to all ones.
- Local Vector Table entries are reset to zero except for the Mask bits. The Mask bits are set to ones.
- Local APIC Version register is not affected.
- Local APIC ID and Arb ID registers are loaded from CPU pins.



- All internal state machines are reset.
- APIC is software disabled. Bit 8 of the SVR is set to 0.

**Initialization Reset (INIT)**

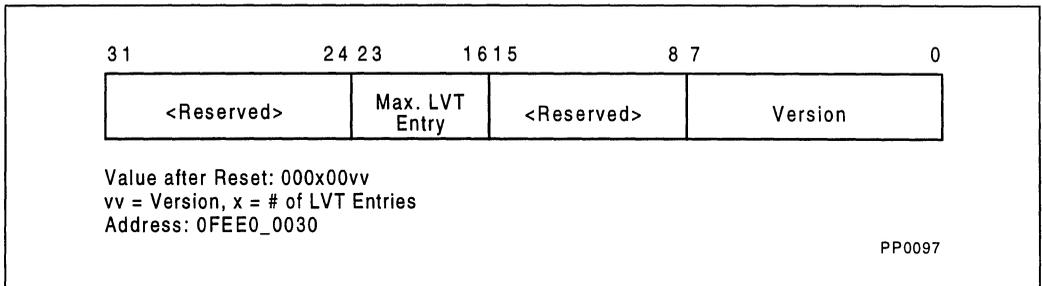
INIT is a Software Reset, and is delivered as a bus message. INIT has the same effect on the Local APIC as the power-up Reset, except that the APIC ID and Arb ID registers are not affected. The Local APIC asserts the INIT signal to its processor which begins the initialization process in the local APIC.

**Local APIC State After INIT Deassert Message**

All Local APICs, whether they are targeted or not, load their Arbitration ID register with values from their APIC ID registers. software is recommended to use broadcast-to-all-excluding-self destination mode when using the INIT deassert command, and at least one APIC must appear as a target.

**19.3.1.12. LOCAL APIC VERSION REGISTER**

The Local APIC contains a hardwired Version Register, used for identifying the APIC version by software. In addition, the version register specifies the size of LVT used in the specific implementation.



**Figure 19-14. Local APIC Version Register**

- **VERSION:** The version numbers are assigned for the 82489DX and Local APIC.  
0X(h) = 82489DX  
1X(h) = Pentium Processor (735\90, 815\100, 1000\120, 1110\133) Local APIC  
20 - 0FFh = Reserved
- **Max LVT Entry:** Shows the number of the highest order LVT entry. For the Pentium Processor (735\90, 815\100), having 4 entries LVT, the Max LVT number is 3.



## 19.3.2. APIC Bus And Inter-APIC Communication Protocol

All I/O and local APIC units communicate via a 3-wire inter-APIC bus. Two of the wires are open-drain (wired-OR) and are used for data transmission, and one wire is a clock. **The bus and its messages are invisible to software, and may change in future implementations without having any effect on software compatibility.** Note that electrical values of the bus are  $V_L$  for logical one and  $V_H$  for logical zero.

### 19.3.2.1. BUS ARBITRATION

Because only one message can be delivered at any time on the APIC bus, the APIC agents employ a "rotating priority" arbitration protocol to gain a grant for message delivery. One or more APIC agents may start sending their messages simultaneously. At the beginning of every message, each agent presents the type of the message it is willing to transmit and the agent's current arbitration priority (taken from internal Arb ID register) on the APIC bus. This information is used for arbitration. After each arbitration cycle, only potential winners keep driving the bus. By the time all arbitration cycles are completed, there will be only one agent left driving the bus (see message-specific information below). Once a winner is selected, it is granted exclusive use of the bus, and will continue driving the bus sending its actual message.

After each successfully transmitted message all agents increase their Arb ID (a 4-bit value) by one. The previous winner (i.e., the one that has just successfully transmitted its message) assumes a priority of zero (lowest). An agent whose Arb ID was 15 (highest) during arbitration, but did not send a message, adopts the previous winner Arb ID, incremented by one.

Note that the arbitration protocol described above is slightly different if one of the APIC agents issues a special message called End-Of-Interrupt (EOI), defined below. This high-priority message is granted the bus regardless of its agent Arb ID, unless more than one agent issues an EOI message simultaneously. In the latter case, EOI messages arbitrate using their Arb IDs.

Lowest-priority (LP) arbitration utilizes the APR appended with a 4-bit updated Arb ID to break ties if there are multiple APICs executing at the lowest priority. All 8 bits of the APR are used for the LP arbitration. Note that Arb ID is initialized after Reset to the value of APIC ID. Also, the INIT-deassert command resynchronizes the Arb-ID by setting it with APIC ID value.

### 19.3.2.2. BUS MESSAGE FORMATS

There are 4 types of messages: 14-cycle *EOI* message, 21-cycle *Short* message, 34-cycle *Non-Focused Lowest Priority* message and 39-cycle *Remote Read* message. The purpose of each type of message and its format are described below.



### EOI Message

The EOI message is an indication the local APIC sends to the I/O APIC that a level triggered interrupt has been accepted by the processor. This, in turn, is a result of software writing into the EOI register of the Local APIC.

**Table 19-1. 14-Cycle EOI Message**

Cycle	Bit1	Bit0	
1:	1	1	11 = EOI
2:	ArbID3	0	Arbitration ID bits 3 through 0
3:	ArbID2	0	
4:	ArbID1	0	
5:	ArbID0	0	
6:	V7	V6	Interrupt vector V7 - V0
7:	V5	V4	
8:	V3	V2	
9:	V1	V0	
10:	C	C	Checksum for cycles 6 - 9
11:	0	0	
12:	A	A	Status Cycle 0
13:	A1	A1	Status Cycle 1
14:	0	0	

The checksum is computed for cycles 6 through 9. It is a cumulative sum of the 2-bit (Bit1:Bit0) logical data values. The carry out of all but the last addition is added to the sum. If any APIC computes a different checksum than the one appearing on the bus in cycle 10, it signals an error, driving 11 on the APIC bus during cycle 12. In this case, the APICs disregard the message. The sending APIC will receive an appropriate error indication (see section 19.3.3), and will resend the message. The status cycles are defined in Table 19-5.

### Short Message

Short messages are used for delivery of Fixed, NMI, SMI, INIT, StartUp, ExtINT and Lowest Priority with Focus processor interrupts.

Table 19-2. 21-Cycle Short Message

Cycle	Bit1	Bit0	
1:	0	1	0 1 = normal
2:	ArbID3	0	Arbitration ID bits 3 through 0
3:	ArbID2	0	
4:	ArbID1	0	
5:	ArbID0	0	
6:	DM	M2	DM = Destination Mode
7:	M1	M0	M2-M0 = Delivery mode
8:	L	TM	L = Level, TM = Trigger Mode
9:	V7	V6	V7-V0 = Interrupt Vector
10:	V5	V4	
11:	V3	V2	
12:	V1	V0	
13:	D7	D6	D7-D0 = Destination
14:	D5	D4	
15:	D3	D2	
16:	D1	D0	
17:	C	C	Checksum for cycles 6-16
18:	0	0	
19:	A	A	Status cycle 0
20:	A1	A1	Status cycle 1
21:	0	0	

If DM = 0 (physical mode), then cycles 15 and 16 represent the APIC ID and cycles 13 and 14 are considered don't care by the receiver. If DM = 1 (logical mode), then cycles 13 through 16 are the 8-bit logical destination field. For *shorthands* of “all-incl-self” and “all-excl-self” DM=0 and D3-D0 = 1111. The agent sending the message is the only one required to distinguish between the two cases. It does so using internal information.

In the lowest priority delivery, if the focus processor exists, it identifies itself driving 10 during cycle 19 and accepts the interrupt. This is an indication to other agents to terminate arbitration. In case the focus processor has not been found, the short message is extended on-the-fly to the non-focused lowest-priority message, which continues as explained below. Note that except for the EOI message, messages generating a checksum or an acceptance error (see section 19.3.3) terminate after cycle 21.

**Non-Focused Lowest Priority Message**

This format is employed for the lowest priority delivery mode without a Focus Processor. Cycles 1 through 20 are same as for the short message. If status cycle AA = 10, then a Focus processor has been identified, and the short message format is used. AA = 00 indicates the need to start lowest priority arbitration, continuing the message using the 34-cycles format shown below. For other combinations of status bits, refer to Table 19-5.

**Table 19-3. 34-Cycle Non-Focused Lowest Priority Message**

Cycle	Bit0	Bit1	
1:	0	1	0 1 = normal
2:	ArbID3	0	Arbitration ID bits 3 through 0
3:	ArbID2	0	
4:	ArbID1	0	
5:	ArbID0	0	
6:	DM	M2	DM = Destination mode
7:	M1	M0	M2-M0 = Delivery mode
8:	L	TM	L = Level, TM = Trigger Mode
9:	V7	V6	V7-V0 = Interrupt Vector
10:	V5	V4	
11:	V3	V2	
12:	V1	V0	
13:	D7	D6	D7-D0 = Destination
14:	D5	D4	
15:	D3	D2	
16:	D1	D0	
17:	C	C	Checksum for cycles 6-16
18:	0	0	
19:	A	A	Status cycle 0
20:	A1	A1	Status cycle 1

**Table 19-3. 34-Cycle Non-Focused Lowest Priority Message (Contd.)**

Cycle	Bit0	Bit1	
21:	P7	0	P7 - P0 = Inverted Processor Priority
22:	P6	0	
23:	P5	0	
24:	P4	0	
25:	P3	0	
26:	P2	0	
27:	P1	0	
28:	P0	0	
29:	ArbID3	0	Arbitration ID 3 -0
30:	ArbID2	0	
31:	ArbID1	0	
32:	ArbID0	0	
33:	A2	A2	Status Cycle
34:	0	0	

Cycles 21 through 28 are used to arbitrate for the lowest priority processor. The processors participating in the arbitration drive their inverted processor priority on the bus. Only the local APICs having “free interrupt slots” will participate in the lowest priority arbitration. If no such APIC exists, the message will be rejected, and will have to be tried later.

Cycles 29 through 32 are also used for arbitration in case two or more processors have the same lowest priority. In the lowest delivery mode, all combinations of errors in cycle 33 (A2 A2) will set the “accept error” bit in the error status register (defined in section 19.3.3). Arb ID update is performed in cycle 20, and is not affected by errors detected in cycle 33. Only the local APIC that wins in the LP arbitration, drives cycle 33. An error in cycle 33 will force the sender to re-send the message.

### Remote Read Message

The remote read message is used for a local APIC to read a register located in another local APIC. The message format is the same as in the case of a short message for the first 20 cycles.

**Table 19-4. 39-Cycle Remote Read Message**

Cycle	Bit0	Bit1	
1:	0	1	0 1 = normal
2:	ArbID3	0	Arbitration ID bits 3 through 0
3:	ArbID2	0	
4:	ArbID1	0	
5:	ArbID0	0	
6:	DM	M2	DM = Destination mode
7:	M1	M0	M2-M0 = Delivery mode
8:	L	TM	L = Level, TM = Trigger Mode
9:	V7	V6	V7-V6 = Don't care
10:	V5	V4	V5-V0 = Register address (address bits 4 –11)
11:	V3	V2	
12:	V1	V0	
13:	D7	D6	Destination
14:	D5	D4	
15:	D3	D2	
16:	D1	D0	
17:	C	C	Checksum for cycles 6-16
18:	0	0	
19:	A	A	Status cycle 0
20:	A1	A1	Status cycle 1
21:	d31	d30	Remote register data 31-0
22:	d29	d28	
23:	d27	d26	
24:	d25	d24	

**Table 19-4. 39-Cycle Remote Read Message (Contd.)**

Cycle	Bit0	Bit1	
25:	d23	d22	
26:	d21	d20	
27:	d19	d18	
28:	d17	d16	
29:	d15	d14	
30:	d13	d12	
31:	d11	d10	
32:	d09	d08	
33:	d07	d06	
34:	d05	d04	
35:	d03	d02	
36:	d01	d00	
37:	S	S	Data Status: 11 = valid, 00 = invalid
38:	C	C	Checksum for cycles 21 - 36
39:	0	0	

Cycles 21 through 36 contain the remote register data. The status information in cycle 37 specifies the validity of the received data. The Remote read message is not retried, even if the data is invalid. A Remote Read to an invalid address results in an invalid data status bits, reported in cycle 37.



**Table 19-5. APIC Bus Status Cycles Interpretation**

Delivery Mode	Focus processor?	Status A A	Comments	Status A1 A1	Comments
Fixed, EOI	N/A	0 0	CS OK	1 0 1 1 0 x	Accepted Retry Accept Error
		1 1 1 0 0 1	CS Error Error Error	0 0 0 0 0 0	
NMI, SMI, INIT, ExtINT, Start-Up	N/A	0 0	CS OK	1 0 1 1 0 x	Accepted Error Error
		1 1 1 0 0 1	CS Error Error Error	0 0 0 0 0 0	
Lowest Priority	No	0 0	CS OK	1 1 1 0 0 x	Do LP Arb* End and Retry Error
	Yes	1 0 1 1 0 1	CS OK CS Error Error	0 0 0 0 0 0	
Remote Read	N/A	0 0 1 1 0 1 1 0	CS OK CS Error Error Error	0 0 0 0 0 0 0 0	

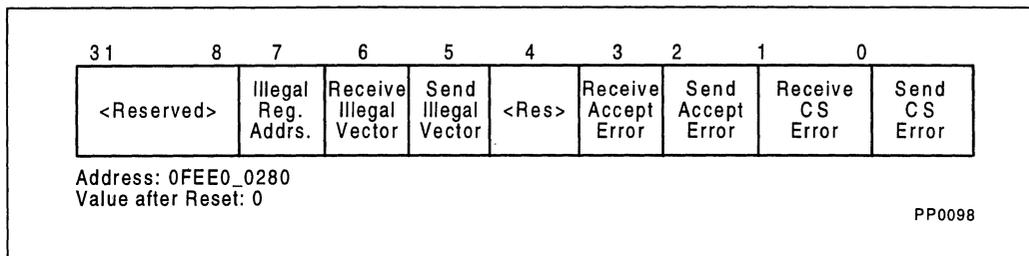
**NOTE:**

\***Status: A2 A2** (relevant for LP Arbitration only)

- 1 0 Accept
- 1 1 Error
- 0 x Error

### 19.3.3. Error Handling In APIC

The Local APIC incorporates an Error Status Register (ESR) to record all the errors detected by the APIC. The ESR is read only, and is reset after being read by either the CPU or through the Remote Read message. A write to the ESR has no side effects. ESR fields are shown in Fig 19-15. **For compatibility with future implementations, the software must perform a write into the ESR before reading.** An Error interrupt is generated when one of the error bits is set. Error bits are cumulative. The ESR must be cleared by software after unmasking of the error interrupt entry in the LVT is performed. If the software, however, wishes to handle errors set in the register prior to unmasking, it should read the ESR prior or immediately after the unmasking.



**Figure 19-15. Error Status Register (ESR)**

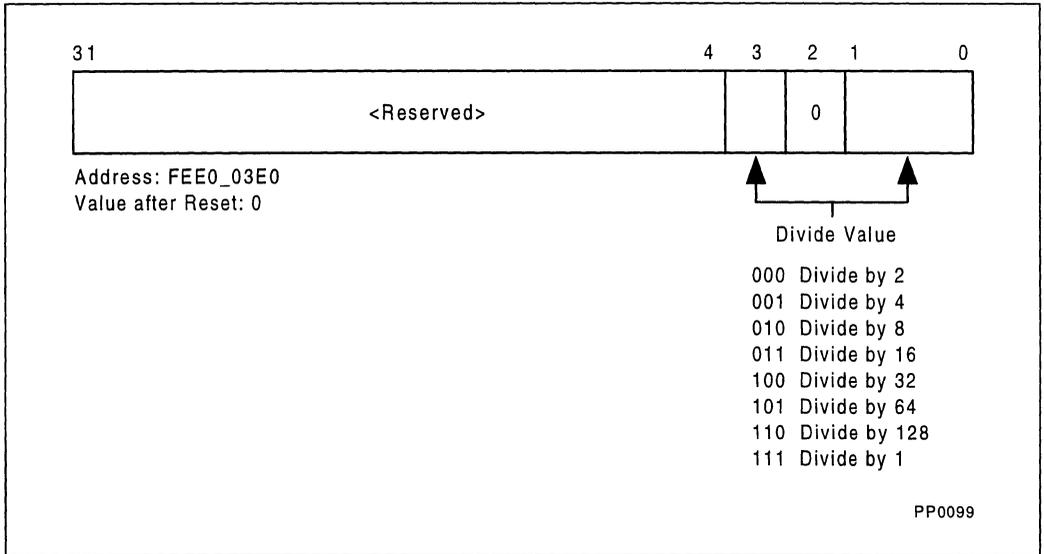
- **Send CS Error**  
Check Sum Error. The local APIC sets this bit when it detects a check sum error for a message that was sent by it.
- **Receive CS Error**  
Check Sum Error. The local APIC sets this bit when it detects a check sum error for a message that was received by it
- **Send Accept Error**  
The Local APIC sets this error bit when it detects that a message sent by it was not accepted by any agent on the bus.
- **Receive Accept Error**  
The Local APIC sets this error bit when it detects that the message which was received by it was not accepted by any agent on the bus, including itself.
- **Send Illegal Vector**  
Set when the local APIC detects an illegal vector in the message that it is sending on the bus.
- **Receive Illegal Vector**  
Set when the local APIC detects an illegal vector in the message received by it. This includes an illegal vector code in the local vector table interrupts and self interrupts from ICR.
- **Illegal Reg. Address**  
This bit is set when the processor is trying to access a register that is not implemented in the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) local APIC register address space, i.e., FEE0 0000 through FEE0 03FF.

## 19.3.4. Timer

### 19.3.4.1. OVERVIEW

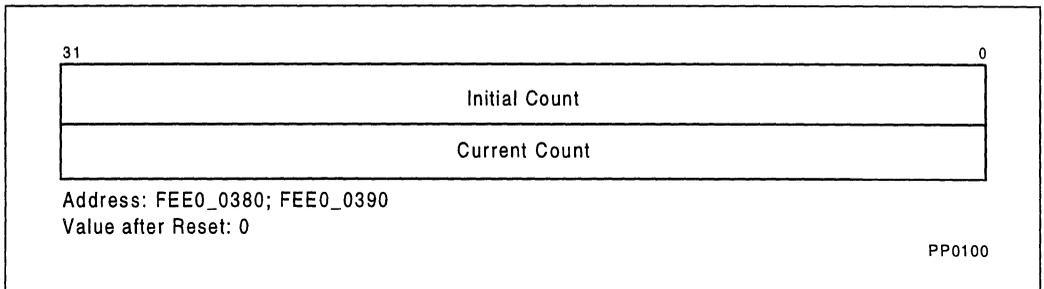
The Local APIC unit contains a 32-bit programmable timer for use by the local processor. The time base is derived from the CPU bus clock, divided by the “divide” value. After reset,

the timer is initialized to zero. The timer supports one-shot and periodic modes. The timer can be configured to interrupt the local processor with an arbitrary vector. Refer to Figure 19-16.



**Figure 19-16. Divide Configuration Register**

The timer is started by programming its Initial Count register (IC). The IC value is copied into the Current Count register (CC), and the counting down begins. After the timer reaches zero in One-Shot mode, an interrupt is generated and the timer remains at its zero value until reprogrammed. In Periodic mode, the CC is automatically reloaded from the IC and counting down is repeated. If the IC value is N, then the CC values are N, N-1, ..., 2, 1, N, N-1, .... , etc. If during the counting process the IC is set, the counting will restart and the new value will be used. The IC is read-write by software, while the CC is read only.



**Figure 19-17. Initial Count and Current Count Registers**

Table 19-6. APIC Registers Address Map

Address (hex)	Register Name	Software Read/Write
0FEE0 0000	Reserved	
0FEE0 0010	Reserved	
0FEE0 0020	Local APIC ID Register	Read/write
0FEE0 0030	Local APIC Version Register	Read only
0FEE0 0040	Reserved	
0FEE0 0050	Reserved	
0FEE0 0060	Reserved	
0FEE0 0070	Reserved	
0FEE0 0080	Task Priority Register	Read/Write
0FEE0 0090	Arbitration Priority Register	Read only
0FEE0 00A0	Processor Priority Register	Read only
0FEE0 00B0	EOI Register	Write only
0FEE0 00C0	Remote Read Register	Read only
0FEE0 00D0	Logical Destination Register	Read/Write
0FEE0 00E0	Destination Format Register	Bits 0-27 Read only. Bits 28-31 Read/Write
0FEE0 00F0	Spurious Interrupt Vector Reg.	Bits 0-3 Read only. Bits 4-9 Read/Write
0FEE0 0100 through 0FEE0 0170	ISR 0-255	Read only

**Table 19-6. APIC Registers Address Map (Contd.)**

Address (hex)	Register Name	Software Read/Write
0FEE0 0180 through 0FEE0 01F0	TMR 0-255	Read only
0FEE0 0200 through 0FEE0 0270	IRR 0-255	Read only
0FEE0 0280	Error Status Register	Read only
0FEE0 0290 through 0FEE0 02F0	Reserved	
0FEE0 0300	Interrupt Command Reg. 0-31	Read/Write
0FEE0 0310	Interrupt Command Reg. 32-63	Read/Write
0FEE0 0320	Local Vector Table (Timer)	Read/Write
0FEE0 0330	Reserved	
0FEE0 0340	Reserved	
0FEE0 0350	Local Vector Table (LINT0)	Read/Write
0FEE0 0360	Local Vector Table (LINT1)	Read/Write
0FEE0 0370	Local Vector Table (Error)	Read/Write
0FEE0 0380	Initial Count Register for Timer	Read/Write
0FEE0 0390	Current Count Register for Timer	Read only
0FEE0 03A0 through 0FEE0 03D0	Reserved	
0FEE0 03E0	Timer Divide Configuration Register	Read/Write
0FEE0 03F0	Reserved	

### 19.3.5. APIC Valid/Invalid Programming Combination

**Table 19-7. Interrupt Command Register**

Trigger Mode	Destination Mode	Delivery Mode	Valid/Invalid	Destination Shorthand
Edge	Physical or Logical	Fixed, Lowest Priority, NMI, SMI, INIT, StartUp	Valid	Dest. Field
Level	Physical or Logical	Fixed, Lowest Priority, NMI	(*)	Dest. field
Level	Physical or Logical	INIT	(**)	Dest. Field
Edge	Physical	Remote Read	Valid	Dest. field
Edge	Logical	Remote Read	Invalid	x
Level	x	Remote Read, SMI, StartUp	Invalid	x
Edge	x	Fixed	Valid	Self
Level	x	Fixed	(*)	Self
x	x	Lowest Priority, Remote Read, NMI, INIT, SMI, StartUp	Invalid	Self
Edge	x	Fixed	Valid	All inc Self
Level	x	Fixed	(*)	All inc Self
x	x	Lowest Priority, Remote Read, NMI, INIT, SMI, StartUp	Invalid	All inc Self
Edge	x	Fixed, Lowest Priority, NMI, INIT, SMI, StartUp	Valid	All excl Self
Level	x	Fixed, Lowest Priority, NMI	(*)	All excl Self
Level	x	SMI, StartUp	Invalid	All excl Self
Level	x	INIT	(**)	All excl Self



**Table 19-8. Local Vector Table**

Trigger Mode	Delivery Mode	Valid/Invalid
Edge or Level	Fixed	Valid
Edge	NMI	Valid
Level	NMI	(*)
Edge	ExtINT	Valid
Level	ExtINT	Invalid

**NOTES:**

\* Valid. Treated as Edge Triggered if Level = 1, otherwise ignored.

\*\* Valid. Treated as edge triggered when "level" = 1 (assert). When "level" = 0 (de-assert), treated as "INIT Level De-assert" message.

**NOTE**

Only INIT-deassert messages are allowed to have level = 'de-assert'. For all other messages the level must be "assert".

### 19.3.6. Software Visible Differences Between APIC and 82489DX

The following APIC features differ in their definitions from the 82489DX features.

In the 82489DX, when the local unit is disabled by resetting the bit 8 of the spurious vector register, all the internal registers including the IRR, ISR and TMR are cleared and the mask bits in the local vector tables are set to logical ones. In the disabled mode, 82489DX local unit will accept only the Reset Deassert message. In CPU, disabling the local APIC doesn't clear any registers. It sets the mask bits in the local vector tables and ceases accepting the buss messages except for INIT, SMI, NMI, Remote Read and Start-Up.

In the APIC, NMI and INIT (except for INIT Deassert) are always treated as edge triggered interrupts even if programmed otherwise. In the 82489DX these interrupts are always level triggered. In APIC, the interrupts generated through ICR messages are always treated as edge triggered (except INIT Deassert). In the 82489DX, ICR can be used to generate either edge or level triggered interrupts. Logical Destination register for the 82489DX supports 32 bits where as APIC supports only 8 bits. APIC ID register is 8 bits wide for the 82489DX and 4 bits wide for APIC.

#### Performance Related Differences between Pentium Processor (735\90, 815\100, 1000\120, 1110\133) APIC and 82489DX

For the 82489DX, in the lowest priority mode, all the target local APICs specified by the destination field participate in the lowest priority arbitration. Only those local APICs which have free interrupt slots will participate in the lowest priority arbitration.



**New Features Incorporated in APIC**

- The APIC supports Cluster Addressing in logical destination mode.
- Focus Processor Checking can be enabled/disabled in the APIC.
- Interrupt Input Signal polarity can be programmed in the APIC.
- The APIC supports SMI through ICR and I/O redirection table.
- The APIC incorporates an Error Status Register to log and report error to the processor.

**19.3.7. Dual Processing Bootup Handshake Protocol Sequence With Examples**

The following constants and data definitions are used in this document code examples. They are based on the addresses of the APIC registers as defined in Table 19-2.

ICR_LOW	EQU 0FEE00300H
ICR_HI	EQU 0FEE00310H
SVR	EQU 0FEE000F0H
APIC_ID	EQU 0FEE00020H
LVT3	EQU 0FEE00370H
APIC_ENABLED	EQU 100H
BOOT_ID	DW ?
UPGRD_ID	DW ?

**Dual Processing Sequence of Events**

1. The Primary processor boots at standard Intel architecture address and executes until ready to activate the Dual processor.
2. It should be determined that the processor is a "GenuineIntel" by executing the CPUID instruction with 0 in EAX. (See *Intel Processor Identification with the CPUID Instruction*, Order No. 241618). System software should execute CPUID with a 1 in EAX to obtain model, stepping, family and type information. The values of EAX and EDX should be saved into a configuration RAM space for use later.
3. If the type field (in the EAX register following the CPUID instruction with an input value of 1) is 01B in bits 13 and 12, respectively, the CPU is a Future Pentium® OverDrive™ processor and the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) has been put to sleep. This means it is a uniprocessor system and normal AT system configuration can continue. Skip to step 15 to configure the APIC.

If the type field is 00B, the processor is a Primary processor and detection of the Dual processor is required. Continue with steps 4 through 14.

4. Detection of the Dual processor can be done by doing the following:
  - Set a timer before sending the StartUp IPI to the Dual processor. In the Dual processor's initialization routine, it should write a value into memory indicating its presence. The

Primary processor can then use the timer expiration to check if something has been written into memory. If the timer expires and nothing has been written into memory, the Dual processor is not present or some error has occurred.

5. Load StartUp code for dual processor in 4kb page in lower 1Mb of memory.
6. Get into protected mode (to access APIC address space above 1Mb).
7. Determine Pentium Processor (735\90, 815\100, 1000\120, 1110\133) APIC ID from local APIC ID register (default is 0)

```
MOV ESI, APIC_ID      ; address of local APIC ID register
MOV EAX, [ESI]
AND EAX, 0F000000H   ; zero out all other bits except APIC ID
MOV BOOT_ID, EAX     ; save in memory
```

Save in configuration RAM (optional).

8. Determine APIC ID of Dual processor and save in configuration RAM (optional).
 

```
MOV EAX, BOOT_ID
XOR EAX, 100000H     ; toggle lower bit of ID field (bit 24)
MOV UPGRD_ID, EAX
```
9. Convert base address of 4-Kb page for Dual processor Bootup code into 8-bit vector. The 8-bit vector defines the address of a 4-Kb page in the Intel architecture Real Mode Space (1 MB space). For example, a vector of 0bdH specifies a StartUp memory address of 000bd000H.

Steps 10 and 11 are used if the programmer wants to use the LVT APIC error handling entry to deal with unsuccessful delivery of the StartUp IPI.

10. Enable APIC by writing to Spurious Vector Register (SVR). This is required to do APIC error handling via the local vector table.

```
MOV ESI, SVR          ; address of SVR
MOV EAX, [ESI]
OR  EAX, APIC_ENABLED ; set bit 8 to enable (0 on reset)
MOV [ESI], EAX
```

11. Program LVT3 (APIC error interrupt vector) of the local vector table with an 8-bit vector for handling APIC errors

```
MOV ESI, LVT3
MOV EAX, [ESI]
AND EAX, FFFFFFF0H   ; clear out previous vector
OR  EAX, 000000xxH   ; xx is the 8-bit vector for APIC error
                          ; handling.
MOV [ESI], EAX
```

## 12. Write APIC ICRH with address of dual processor APIC

```

MOV ESI, ICR_HI           ; address of ICR high dword
MOV EAX, [ESI]           ; get high word of ICR
AND EAX, 0F0FFFFFFFH     ; zero out ID Bits
OR  EAX, UPGRD_ID        ; write ID into appropriate bits - don't
                           ; affect reserved bits
MOV [ESI], UPGRD_ID      ; write upgrade ID to destination field

```

## 13. Set timer with an appropriate value (~100 msec).

## 14. Write APIC ICRL to send StartUp IPI message via the APIC.

```

MOV ESI, ICR_LOW         ; write address of ICR low dword
MOV EAX, [ESI]           ; get low dword of ICR
AND EAX, 0FFFFFF800H     ; zero out delivery mode and vector fields
OR  EAX, 000006xxH       ; 6 selects delivery mode 110 (StartUp IPI)
                           ; xx should be vector of 4kb page as
                           ; computed in Step 8.

MOV [ESI], EAX

```

## 15. Configure APIC as appropriate.

**Dual Processor Sequence of Events following StartUp IPI**

1. If the APIC is to be used for symmetric multiprocessing on the Dual processor, the following steps must be taken:
2. Get into protected mode in order to access the APIC addresses
3. Initialize its own APIC by writing to bit 8 of the SVR register and programming its LVT3 for error handling.
4. Configure APIC as appropriate.
5. Enable interrupts

The Dual processor can then execute a HALT instruction and wait for an IPI from the operating system or continue execution.

The Dual processor may also want to determine its own CPUID information and write into configuration RAM.

Given the following constants:

```
LVT1      EQU 0FEE00350H
LVT2      EQU 0FEE00360H
LVT3      EQU 0FEE00370H
SVR       EQU 0FEE000F0H
```

1. Mask 8259 interrupts.
2. Enable APIC via SVR (Spurious Vector Register) if not already enabled.
 

```
MOV ESI, SVR          ; address of SVR
MOV EAX, [ESI]
OR  EAX, APIC_ENABLED ; set bit 8 to enable (0 on reset)
MOV [ESI], EAX
```
3. Program LVT1 as an ExtINT which delivers the signal to the INTR signal of all processors cores listed in the destination as an interrupt that originated in an externally connected interrupt controller.
 

```
MOV ESI, LVT1
MOV EAX, [ESI]
AND EAX, 0FFFE58FFH   ; mask off bits 8-10, 12, 14 and 16
OR  EAX, 700H         ; Bit 16=0 for not masked, Bit 15=0 for
edge
                        ; triggered, Bit 13=0 for high active input
                        ; polarity, Bits 8-10 are 111b for ExtINT
MOV [ESI], EAX        ; Write to LVT1
```
4. Program LVT2 as NMI which delivers the signal on the NMI signal of all processor cores listed in the destination.
 

```
MOV ESI, LVT2
MOV EAX, [ESI]
AND EAX, 0FFFE58FFH   ; mask off bits 8-10 and 15
OR  EAX, 0FFFF0400H   ; Bit 16=0 for not masked, Bit 15=0 edge
                        ; triggered, Bit 13=0 for high active input
                        ; polarity, Bits 8-10 are 100b for NMI
MOV [ESI], EAX        ; Write to LVT2
```
5. Unmask 8259 interrupts and allow NMI.



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**20**

# **Power Management**





## CHAPTER 20 POWER MANAGEMENT

### 20.1. PENTIUM® PROCESSOR (510\60,567\66) POWER MANAGEMENT

The Pentium processor (510\60, 567\66) implements Intel's System Management Mode (SMM) architecture. This chapter describes the architectural features of Pentium Processor (510\60, 567\66) and Pentium Processor (735\90, 815\100, 1000\120, 1110\133) power management. For a detailed hardware description, refer to the Power Management chapter in the *Pentium® Processor Family Developer's Manual*, Volume 1.

The Pentium microprocessor supports four modes: **Real, Virtual-86, Protected, and System Management mode (SMM)**. As an operating mode, SMM has a distinct processor environment, interface and hardware/software features.

#### 20.1.1. Introduction to System Management Mode Architecture

SMM provides the system designer with a means of adding new software controlled features to their computer products which always operate transparent to the Operating System (OS) and software applications. SMM is intended for use only by system firmware, not by applications software or general purpose systems software.

The SMM architectural extension consists of the following elements:

1. A System Management Interrupt (SMI#) hardware interface. The SMI# interrupt can be delivered through the SMI# pin.
2. A dedicated and secure memory space (SMRAM) for SMI handler code and CPU state (context) data with a status signal for the system to decode access to that memory space, SMIACT#.
3. Resume (RSM) instruction, for exiting the System Management Mode.
4. Auto HALT Restart and SMBASE relocation.

#### 20.1.2. Terminology

The following terms are used throughout the discussion of System Management Mode.

**SMM:** System Management Mode. This is the operating environment that the processor (system) enters when the System Management Interrupt is being serviced.

- SMI:** System Management Interrupt. This is part of the SMM interface. When SMI# is asserted (SMI# pin asserted low) it causes the processor to invoke SMM. In this chapter, "SMI" refers to the system management interrupt.
- SMM handler:** System Management Mode handler. This is the code that will be executed when the processor is in SMM. An example application that this code might implement is a power management control or a system control function.
- RSM:** Resume instruction. This instruction is used by the SMM handler to exit the SMM and return to the interrupted OS or Application process.
- SMRAM:** This is the physical memory dedicated to SMM. The SMM handler code and related data reside in this memory. This memory is also used by the processor to store its context before executing the SMM handler. The operating system and applications do not have access to this memory space.
- Context:** This term refers to the processor state. The SMM discussion refers to the context, or processor state, just prior to the processor invoking SMM. The context normally consists of the CPU registers that fully represent the processor state.
- Context Switch:** A context switch is the process of either saving or restoring the context. The SMM discussion refers to the context switch as the process of saving/restoring the context while invoking/exiting SMM, respectively.

### 20.1.3. Pentium Processor System Management Interrupt Processing

#### 20.1.3.1. SMRAM

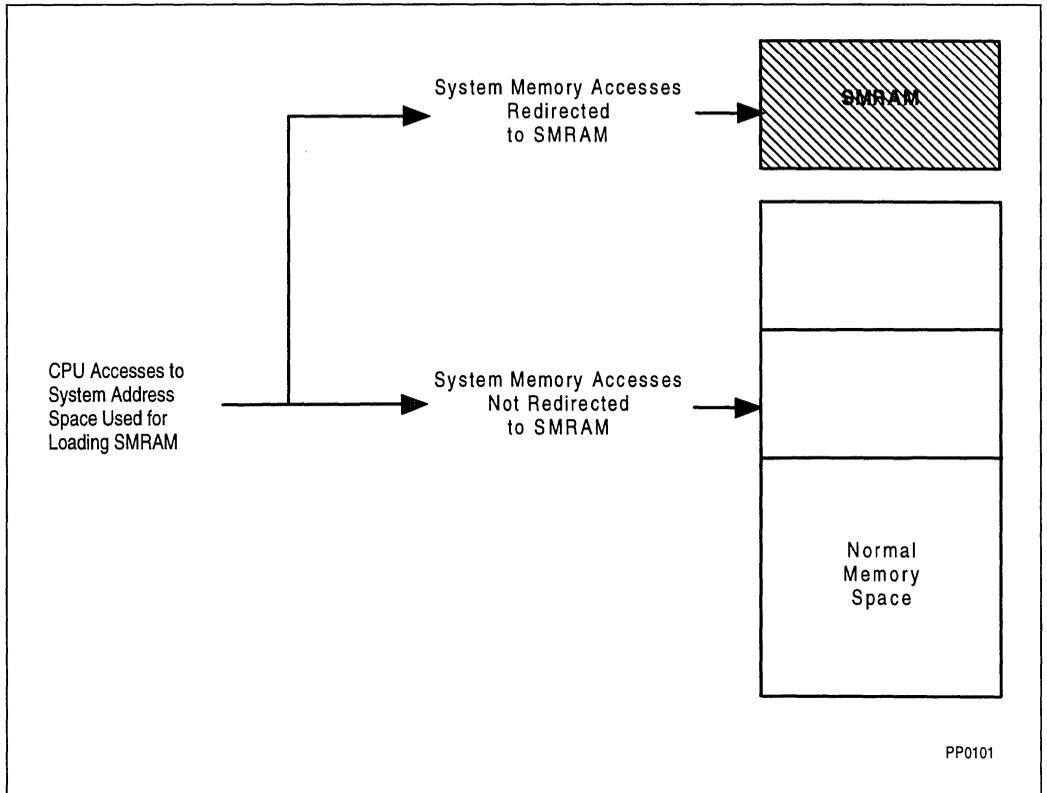
The CPU uses the SMRAM space for state save and state restore operations during an SMI. The SMI handler, which also resides in SMRAM, uses the SMRAM space to store code, data and stacks. In addition, the SMI handler can use the SMRAM for system management information such as the system configuration, configuration of a powered-down device, and system designer-specific information.

The CPU asserts the SMI $\overline{ACT}$  output during memory accesses in SMM to indicate to the memory controller that it is operating in System Management Mode. The system logic should ensure that only the CPU and SMI handler have access to this area.

The system logic is minimally required to decode the physical memory address range from SMBASE + 8000H to SMBASE + 0FFFFH as SMRAM area. The CPU will save its state to the state save area from SMBASE + 0FFFFH downward to SMBASE + 0FE00H (note: the SMBASE default following RESET is 30000H). After saving its state the CPU will jump to the address location SMBASE + 8000H to begin executing the SMI handler. The system

logic can choose to decode a larger area of SMRAM as needed. The size of this SMRAM can be between 32 Kbytes and 4 Gbytes.

The system logic should provide a programmable method for switching the SMRAM into system memory space when the CPU is **not** in SMM. This will enable initialization of the SMRAM space (i.e., loading SMI handler) before executing the SMI handler during SMM.



**Figure 20-1. Redirecting System Memory Addresses to SMRAM**

### 20.1.3.2. SMRAM STATE SAVE MAP

When the SMI# is recognized on an instruction boundary, the CPU core first sets the SMIACT# signal LOW indicating to the system logic that accesses are now being made to the system-defined SMRAM areas. The CPU then writes its state to the state save area in the SMRAM. The state save area starts at SMBASE + [8000H + 7FFFH]. The default SMBASE is 30000H, therefore the default state save area is at 3FFFFH.

Using the *SMBASE Relocation feature* (refer to section 20.1.5.3), the SMRAM addresses can be changed. The SMBASE Relocation feature is always enabled in the Pentium processor (510\60, 567\66). The following formula is used to determine the relocated addresses where the context is saved. The context will reside at SMBASE + [8000H + Register Offset], where the default initial SMBASE is 30000H and the Register Offset is listed below in the SMRAM state save map. Reserved spaces will be used to accommodate future enhancements. SMBASE must be aligned on a 32-Kbyte boundary.

Some of the registers in the SMRAM state save area may be read and changed by the SMI handler, with the changed values restored to the processor registers by the RSM instruction. Some register images are read-only, and must not be modified (modifying these registers will result in unpredictable behavior). The values stored in the areas marked reserved may change in future CPUs. An SMM handler should not rely on any values stored in an area that is marked as reserved. Table 20-1 shows the state save map.



**Table 20-1. SMRAM State Save Map**

Register Offset	Register	Writeable?
7FFC	CR0	NO
7FF8	CR3	NO
7FF4	EFLAGS	YES
7FF0	EIP	YES
7FEC	EDI	YES
7FE8	ESI	YES
7FE4	EBP	YES
7FE0	ESP	YES
7FDC	EBX	YES
7FD8	EDX	YES
7FD4	ECX	YES
7FD0	EAX	YES
7FCC	DR6	NO
7FC8	DR7	NO
7FC4	TR*	NO
7FC0	LDT Base*	NO
7FBC	GS*	NO
7FB8	FS*	NO
7FB4	DS*	NO
7FB0	SS*	NO
7FAC	CS*	NO
7FA8	ES*	NO
7FA7 - 7F98	Reserved	NO
7F94	IDT Base	NO
7F93-7F8C	Reserved	NO
7F88	GDT Base	NO

**Table 20-1. SMRAM State Save Map (Contd.)**

Register Offset	Register	Writeable?
7F87-7F04	Reserved	NO
7F02	Auto HALT Restart Slot (Word)	YES
7F00	Reserved	NO
7EFC	SMM Revision Identifier (Dword)	NO
7EF8	SMBASE Slot (Dword)	YES
7EF7 - 7E00	Reserved	NO

**NOTES:**

\* Upper two bytes are reserved

Modifying a value that is marked as not writeable will result in unpredictable behavior.

Although the following registers are not visible to the system software programmer, they are saved and restored (in areas of the state save that are marked reserved):

- CR1, CR2 and CR4, hidden descriptor registers for CS, DS, ES, FS, GS, SS.

If an SMI request is issued for the purpose of powering down the CPU, the values of all reserved locations in the SMM state save must be saved to non-volatile memory.

The following registers are not automatically saved and restored by SMI# and RSM:

- DR5-DR0, TR7-TR3, FPU registers: STn, FCS, FSW, tag word, FP instruction pointer, FP op code, and operand pointer.

These registers usually do not have to be saved during an SMI handler's execution, as their contents will not change unless an FPU instruction is executed in SMM. However, if an SMI is used to power down the CPU, a power-on reset will be required before returning to SMM, which will reset these registers back to their default values. So an SMI handler that is going to trigger power down should first read these registers directly, and save them (along with the rest of RAM) to nonvolatile storage. After the power-on reset, the continuation of the SMI handler should restore these values, along with the rest of the system's state. Anytime the SMI handler changes these registers in the CPU it must also save and restore them.

**20.1.3.3. EXIT FROM SMM**

The **RSM** instruction is only available to the SMI handler. The opcode of the instruction is 0FAAH. Execution of this instruction while the CPU is executing outside of SMM will cause an invalid op-code error. The last instruction of the SMI handler will be the RSM instruction.

The RSM instruction restores the state save image from SMRAM back to the CPU, then returns control back to the interrupted program execution. There are two SMM features that can be enabled by writing to control "slots" in the SMRAM state save area:



1. **Auto HALT Restart.** It is possible for the SMI request to interrupt the HALT state. The SMI handler can tell the RSM instruction to return control to the HALT instruction **or** to return control to the instruction following the HALT instruction by appropriately setting the Auto HALT Restart slot. The default operation is to restart the HALT instruction.
2. **SMBASE Relocation.** The system can relocate the SMRAM by setting the SMBASE Relocation slot in the state save area. The RSM instruction will set the SMBASE in the processor based on the value in the SMBASE relocation slot. The SMBASE must be 32 Kbyte aligned.

If the processor detects invalid state information, it enters the shutdown state; this happens only in the following situations:

- The value stored in the SMBASE slot during an RSM instruction is not a 32 Kbyte-aligned address.
- A reserved bit of CR4 is set to 1 on a write to CR4.
- A combination of bits written to CR0 is illegal; namely, (PG=1 and PE=0) or (NW=1 and CD=0).

In shutdown mode, the processor stops executing instructions until a RESET, INIT or NMI is asserted. FLUSH#, SMI# and R/S# are recognized by the Pentium processor (510\60, 567\66) in the shutdown state.

#### NOTE

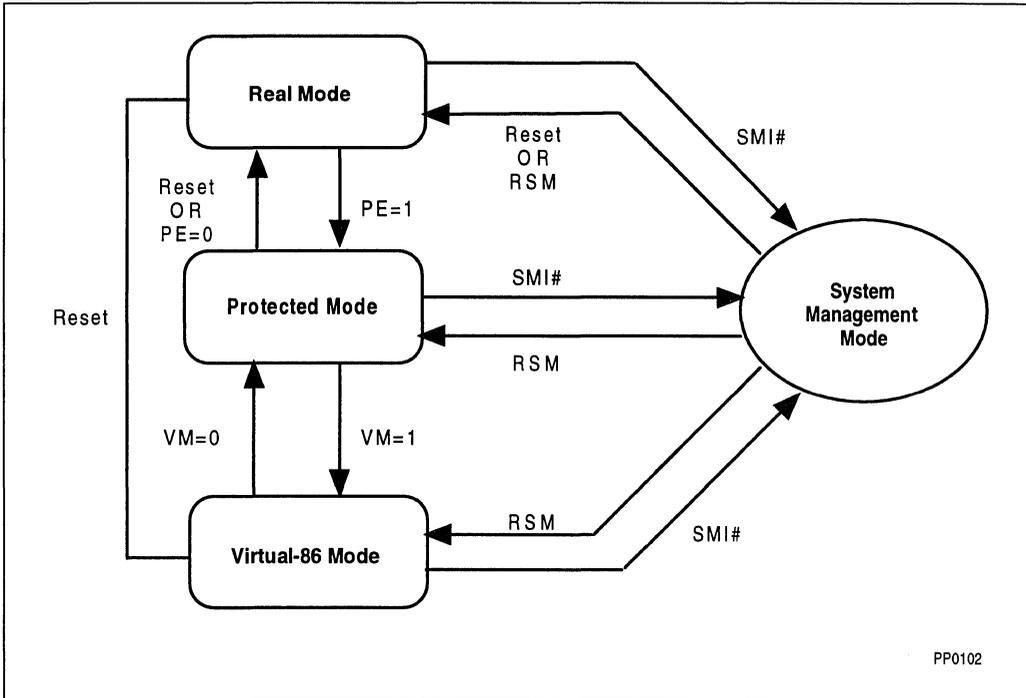
It is recommended that system designers NOT issue SMI# during the shutdown state in the Pentium processor (510\60, 567\66).

The processor generates a special bus cycle to indicate it has entered shutdown mode.

## 20.1.4. System Management Mode Programming Model

### 20.1.4.1. SMM ENTRY

SMM is one of the major operating modes, on a level with Protected mode, Real address mode or virtual-86 mode. Figure 20-2 shows how the processor can enter SMM from any of the three modes and then return.



**Figure 20-2. Transition to and from System Management Mode**

The SMI# interrupt causes the processor to switch to SMM. The RSM instruction exits SMM. SMM is transparent to applications programs and operating systems because of the following:

- The only way to enter SMM is via a type of non-maskable interrupt triggered by an external signal through the SMI# pin.
- The processor begins executing SMM code from a separate address space, referred to earlier as system management RAM (SMRAM).
- Upon entry into SMM, the processor saves the register state of the interrupted program in a part of SMRAM called the SMM context save space.
- All interrupts normally handled by the operating system or by applications are disabled upon entry into SMM.
- A special instruction, RSM, restores processor registers from the SMM context save space and returns control to the interrupted program.

SMM is similar to Real address mode in that there are no privilege levels or address mapping. An SMM program can execute all I/O and other system instructions and can address up to 4 Gbytes of memory.

**20.1.4.2. PROCESSOR ENVIRONMENT**

When an SMI# signal is recognized on an instruction execution boundary, the processor waits for all stores to complete, including emptying of the external write buffers (i.e., EWBE# driven active from the system). The final write cycle is complete when the system returns BRDY#. The processor then drives SMIACT# active, saves its register state to SMRAM space, and begins to execute the SMM handler.

SMI# has greater priority than debug exceptions and external interrupts. This means that if more than one of these conditions occur at an instruction boundary, only the SMI# processing occurs, not a debug exception or external interrupt. Subsequent SMI# requests are not acknowledged while the processor is in SMM. The first SMI# interrupt request that occurs while the processor is in SMM is latched, and serviced when the processor exits SMM with the RSM instruction. Only one SMI# will be latched by the CPU while it is in SMM.

When the CPU invokes SMM, the CPU core registers are initialized as follows:

**Table 20-3. SMM Initial CPU Core Register Settings**

Register	Contents
General purpose registers	Unpredictable
EFLAGS	00000002 H
EIP	00008000H
CS selector	3000H
CS base	SMM Base (default 30000H)
DS, ES, FS, GS, SS Selectors	0000H
DS, ES, FS, GS, SS Bases	00000000H
DS, ES, FS, GS, SS Limits	0FFFFFFFH
CR0	Bits 0,2,3 & 31 cleared (PE, EM, TS & PG); others unmodified
DR6	Unpredictable
DR7	00000400H

The following is a summary of the key features in the SMM environment:

1. Real mode style address calculation.
2. Gbyte limit checking.
3. IF flag is cleared.
4. NMI is disabled.
5. TF flag in EFLAGS is cleared; single step traps are disabled.
6. DR7 is cleared; debug traps are disabled.
7. The RSM instruction no longer generates an invalid op code error.
8. Default 16-bit op code, register and stack use.

All bus arbitration (HOLD, AHOLD, BOFF#) inputs operate normally while the CPU is in SMM.

#### **20.1.4.3. EXECUTING SYSTEM MANAGEMENT MODE HANDLER**

The processor begins execution of the SMM handler at offset 8000H in the CS segment. The CS Base is initially 30000H. The CS Base can be changed, however, *using the SMM Base relocation feature*.

When the SMM handler is invoked, the CPU's PE and PG bits in CR0 are reset to 0. The processor is in an environment similar to Real mode, but without the 64-Kbyte limit checking. However, the default operand size and the default address size are set to 16 bits.

The EM bit is cleared so that no exceptions are generated. (If the SMM was entered from Protected mode, the Real mode interrupt and exception support is not available.) The SMI handler should not use floating-point unit instructions until the FPU is properly detected (within the SMI handler) and the exception support is initialized.

Because the segment bases (other than CS) are cleared to 0 and the segment limits are set to 4 Gbytes, the address space may be treated as a single flat 4-Gbyte linear space that is unsegmented. The CPU is still in Real mode and when a segment selector is loaded with a 16-bit value, that value is then shifted left by 4 bits and loaded into the segment base cache. The limits and attributes are not modified.

In SMM, the CPU can access or jump anywhere within the 4Gbyte logical address space. The CPU can also indirectly access or perform a near jump anywhere within the 4-Gbyte logical address space.

#### **20.1.4.4. EXCEPTIONS AND INTERRUPTS WITHIN SMM**

When the CPU enters SMM, it disables INTR interrupts, debug and single step traps by clearing the EFLAGS, DR6 and DR7 registers. This is done to prevent a debug application from accidentally breaking into an SMM handler. This is necessary because the SMM handler operates from a distinct address space (SMRAM) and hence the debug trap will not represent the normal system memory space.

If an SMM handler wishes to use the debug trap feature of the processor to debug SMM handler code, it must first ensure that an SMM compliant debug handler is available. The SMM handler must also ensure DR0-DR3 is saved to be restored later. The debug registers DR0-DR3 and DR7 must then be initialized with the appropriate values.

If the processor wishes to use the single step feature of the processor, it must ensure that an SMM compliant single step handler is available and then set the trap flag in the EFLAGS register.

If the system design requires the processor to respond to hardware INTR requests while in SMM, it must ensure that an SMM compliant interrupt handler is available and then set the interrupt flag in the EFLAGS register (using the STI instruction). Software interrupts are not blocked upon entry to SMM, and the system software designer must provide an SMM compliant interrupt handler before attempting to execute any software interrupt instructions.

Note that in SMM mode the interrupt vector table has the same properties as the Real mode vector table, but in Pentium processor the IDTR base address must be initialized with the LIDT instruction before interrupts are allowed.

NMI interrupts are blocked upon entry to the SMM handler. If an NMI request occurs during the SMM handler, it is latched and serviced after the processor exits SMM. Only one NMI request will be latched during the SMM handler. If an NMI request is pending when the processor executes the RSM instruction, the NMI is serviced before the next instruction of the interrupted code sequence.

Although NMI requests are blocked when the CPU enters SMM, they may be enabled through software by invoking a dummy interrupt and vectoring to an Interrupt Service Routine. NMI interrupt requests will be recognized once the Interrupt Service Routine has begun executing. NMI interrupt requests will nest inside the SMM handler, and be handled as real mode interrupts since SMM is in real mode.

## 20.1.5. SMM Features

### 20.1.5.1. SMM REVISION IDENTIFIER

The SMM revision identifier is used to indicate the version of SMM and the SMM extensions that are supported by the processor. The SMM revision identifier is written during SMM entry and can be examined in SMRAM space at Register Offset 7EFCH. The lower word of the SMM revision identifier refers to the version of the base SMM architecture. The upper word of the SMM revision identifier refers to the extensions available.

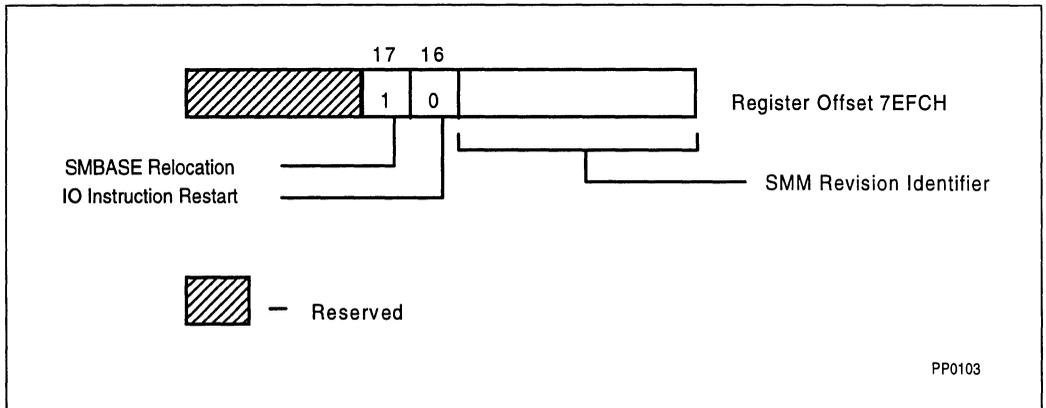
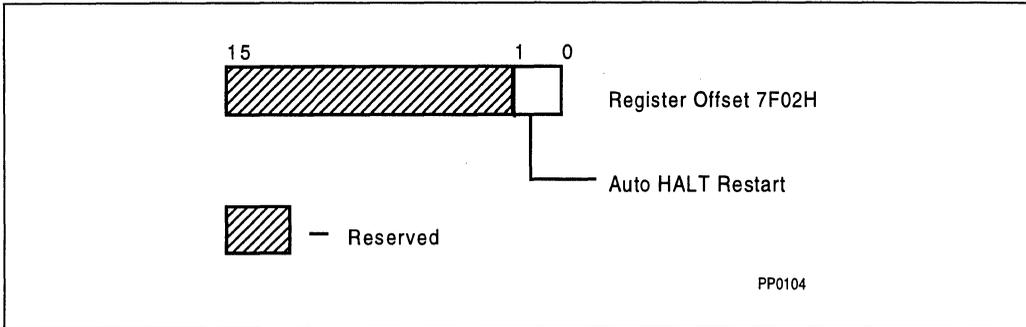


Figure 20-3. SMM Revision Identifier

Bit 16 of the SMM revision identifier is used to indicate to the SMM handler that this processor does not support the SMM I/O Instruction Restart extension (e.g. it is always 0). Bit 17 of this slot indicates that the processor supports relocation of the SMM jump vector and the SMRAM base address.

### 20.1.5.2. HALT AUTO RESTART



**Figure 20-4. Halt Auto Restart**

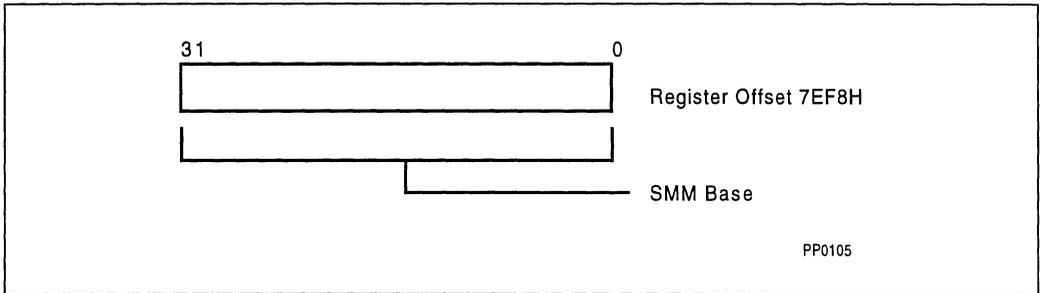
Value of Bit 0 at entry	Value of Bit 0 at exit	Comments
0	0	Returns to next instruction in interrupted program
0	1	Unpredictable
1	0	Returns to next instruction after HALT
1	1	Returns to HALT state

The Auto HALT Restart slot at register offset (word location) 7F02H in SMRAM indicates to the SMM handler that the SMI interrupted the CPU during a HALT state (bit 0 of slot 7F02H is set to 1 if the previous instruction was a HALT). If the SMI did not interrupt the CPU in a HALT state, bit 0 of the Auto HALT Restart slot is stored with a value of 0. If the previous instruction was a HALT, the SMM handler can choose to either set or reset bit 0. If this bit is set to 1, execution of the RSM instruction will force the processor to re-enter the HALT state. If this bit is set to 0 when the RSM instruction is executed, the processor will continue execution with the instruction just after the interrupted HALT instruction. Note that if the interrupted instruction was not a HALT instruction (bit 0 is set to 0 in the Auto HALT Restart slot upon SMM entry), setting bit 0 to 1 will cause unpredictable behavior when the RSM instruction is executed.

If the HALT instruction is restarted, the CPU will generate a memory access to fetch the HALT instruction (if it is not in the internal cache), and execute a HALT bus cycle.

### 20.1.5.3. SMM BASE RELOCATION

The Pentium processor (510\60, 567\66) provides a control register, SMBASE. The address space used as SMRAM can be modified by changing the SMBASE register before exiting an SMI handler routine. SMBASE can be changed to any 32K aligned value (values that are not 32K aligned will cause the CPU to enter the shutdown state when executing the RSM instruction). SMBASE is set to the default value of 30000H on RESET, but is not changed on INIT. If the SMBASE register is changed during an SMM handler, all following SMI# requests will initiate a state save at the new SMBASE.



**Figure 20-5. SMM Base Relocation**

The SMBASE slot in the SMM state save area is a feature used to indicate and change the SMI jump vector location and the SMRAM save area. Since bit 17 of the SMM Revision Identifier is set in the Pentium processor (510\60, 567\66), the SMRAM base and, consequently, the jump vector are stored. During the execution of the RSM instruction, the CPU will read this slot and initialize the CPU to use the new SMBASE during the next SMI. During an SMI, the CPU will do its context save to the new SMRAM area pointed to by the SMBASE, store the current SMBASE in the SMM Base slot (offset 7EF8H), and then start execution of the new jump vector based on the current SMBASE.

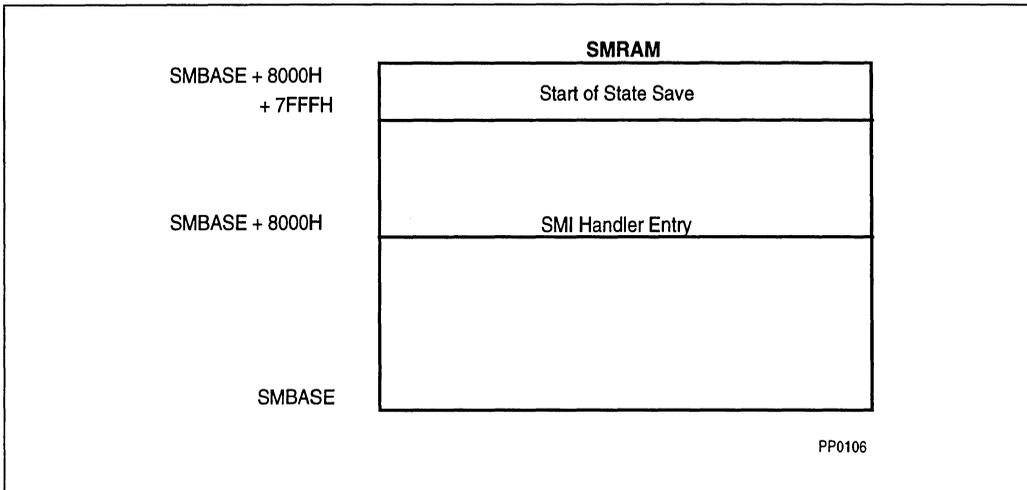
The SMBASE must be a 32-Kbyte aligned, 32-bit integer that indicates a base address for the SMRAM context save area and the SMI jump vector. For example when the processor first powers up, the minimum SMRAM area is from 38000H-3FFFFH. The default SMBASE is 30000H. Hence the starting address of the jump vector is calculated by:

$$\text{SMBASE} + 8000\text{H}$$

While the starting address for the SMRAM state save area is calculated by:

$$\text{SMM Base} + [8000\text{H} + 7\text{FFFH}]$$

Hence when this feature is enabled the SMRAM register map is addressed according to the above formula.



**Figure 20-6. SMRAM Usage**

To change the SMRAM base address and SMI jump vector location, the SMM handler should modify the SMBASE slot. Upon executing an RSM instruction, the processor will read the SMBASE slot and store it internally. Upon recognition of the next SMI request, the processor will use the new SMBASE slot for the SMRAM dump and SMI jump vector.

If the modified SMBASE slot does not contain a 32-Kbyte aligned value, execution of the RSM instruction will cause the CPU to enter the shutdown state.

## 20.1.6. Pentium Processor SMM - Software Considerations

### 20.1.6.1. SMM CODE CONSIDERATIONS

The default operand size and the default address size are 16 bits; however, operand-size override and address-size override prefixes can be used as needed to directly access data anywhere within the 4-Gbyte logical address space.

With operand-size override prefixes, the SMM handler can use jumps, calls, and returns, to transfer control to any location within the 4-Gbyte space. Note, however, the following restrictions:

- Any control transfer that does not have an operand-size override prefix truncates EIP to 16 low-order bits.
- Due to the Real mode style of base-address formation, a long jump or call cannot transfer control to a segment with a base address of more than 20 bits (one megabyte).

### 20.1.6.2. EXCEPTION HANDLING

Upon entry into SMM, external interrupts that require handlers are disabled (the IF bit in the EFLAGS is cleared). This is necessary because, while the processor is in SMM, it is running in a separate memory space. Consequently the vectors stored in the interrupt descriptor table (IDT) for the prior mode are not applicable. Before allowing exception handling (or software interrupts), the SMM program must initialize new interrupt and exception vectors. The interrupt vector table of SMM has the same format as for real model, but the IDTR base address is not initialized upon entrance to SMM in the Pentium processor. The LIDT instruction may be used to point the IDTR to a Real mode interrupt table special for SMM, or to point to the default Real mode table at zero. In the latter case, interrupt vectors which are to be used in SMM may need to be modified, to account for the separate SMM memory space, and then be restored before SMM. Until the interrupt vector table is correctly initialized, the SMM handler must not generate an exception (or software interrupt). Even though hardware interrupts are disabled, exceptions and software interrupts can still occur. Only a correctly written SMM handler can prevent internal exceptions. When new exception vectors are initialized, internal exceptions can be serviced. The following are the restrictions:

1. Due to the Real mode style of base address formation, an interrupt or exception cannot transfer control to a segment with a base address of more than 20 bits.
2. An interrupt or exception cannot transfer control to a segment offset of more than 16 bits (64 Kbytes).
3. If exceptions or interrupts are allowed to occur, only the low order 16 bits of the return address (EIP) are pushed onto the stack. If the offset of the interrupted procedure is greater than 64 Kbytes, it is not possible for the interrupt/exception handler to return control to that procedure. (One work-around could be to perform software adjustment of the return address on the stack).
4. The SMBASE Relocation feature affects the way the CPU will return from an interrupt or exception during an SMI handler.

### 20.1.6.3. HALT DURING SMM

HALT should not be executed during SMM, unless interrupts have been enabled. Interrupts are disabled in SMM and INTR, NMI, and SMI# are the only events that take the CPU out of HALT.

### 20.1.6.4. RELOCATING SMRAM TO AN ADDRESS ABOVE ONE MEGABYTE

Within SMM (or Real mode), the segment base registers can only be updated by changing the segment register. The segment registers contain only 16 bits, which allows only 20 bits to be used for a segment base address (the segment register is shifted left four bits to determine the segment base address). If SMRAM is relocated to an address above one megabyte, the segment registers can no longer be initialized to point to SMRAM.

These areas can still be accessed by using address override prefixes to generate an offset to the correct address. For example, if the SMBASE has been relocated immediately below 16M, the DS and ES registers are still initialized to 0000 0000H. We can still access data in SMRAM by using 32-bit displacement registers:

```
mov     esi,00FFxxxxH           ;64K segment immediately below 16M
mov     ax,ds:[esi]
```

## 20.2. PENTIUM® PROCESSOR (735\90, 815\100, 1000\120, 1110\133) POWER MANAGEMENT

The Pentium processor (735\90, 815\100, 1000\120, 1110\133) implements Intel's System Management Mode (SMM) architecture. This section describes the architectural features of Pentium processor (735\90, 815\100, 1000\120, 1110\133) SMM and Clock Control. For a detailed hardware description, refer to the Power Management chapter in the *Pentium® Processor Family Developer's Manual*, Volume 1.

### 20.2.1. System Management Mode Architecture

The Pentium processor (735\90, 815\100, 1000\120, 1110\133) adds the following extension to the SMM architecture: I/O Instruction Restart.

### 20.2.2. Pentium Processor (735\90, 815\100, 1000\120, 1110\133) Power Management Differences vs. Pentium Processor (510\60, 567\66)

1. System Management Interrupt can be delivered through the SMI# signal or through the local APIC using the SMI# message. The Pentium processor (510\60, 567\66) supported only the SMI# pin interface. The addition of the APIC SMI# message enhances the SMI interface, and provides for SMI delivery in APIC-based dual processing systems.
2. In dual processing systems, SMIACT# from the bus master (MRM) behaves the same as in Pentium processor (510\60, 567\66) systems. If the LRM processor is the CPU in SMM mode, SMIACT# will be inactive and remain so until that processor becomes the MRM. For additional details, refer to Chapter 14 of the *Pentium® Processor Family Developer's Manual*, Volume 1.
3. The Pentium processor (735\90, 815\100, 1000\120, 1110\133) is capable of supporting an SMM I/O Instruction Restart feature (not supported in the Pentium processor (510\60, 567\66)). This feature is disabled following RESET.
4. The Pentium processor (735\90, 815\100, 1000\120, 1110\133) default SMM Revision Identifier changes to 2 when the SMM I/O Instruction Restart feature is enabled. The Pentium processor (510\60, 567\66) revision ID is 0.



5. SMI# is NOT recognized by the Pentium processor (735\90, 815\100, 1000\120, 1110\133) in the shutdown state.
6. Clock control is implemented in the Pentium Processor (735\90, 815\100, 1000\120, 1110\133). Refer to Chapter 30 of the *Pentium® Processor Family Developer's Manual*, Volume 1, for more information.

### 20.2.3. System Management Interrupt Via APIC

When SMI# is asserted (SMI# pin asserted low or APIC SMI# message) it causes the processor to invoke SMM.

### 20.2.4. I/O Instruction Restart

This section describes how the Pentium processor (735\90, 815\100, 1000\120, 1110\133) revision identifier slot can be used to turn I/O Instruction Restart support on and off. Note that the Pentium Processor (735\90, 815\100, 1000\120, 1110\133) interrupt priority scheme is changed when the I/O instruction restart feature is enabled. For more information, refer to Chapter 19 of the *Pentium® Processor Family Developer's Manual*, Volume 1.

#### 20.2.4.1. ENABLING I/O INSTRUCTION RESTART

The Pentium Processor (735\90, 815\100, 1000\120, 1110\133) I/O Instruction Restart feature is automatically disabled following RESET. To enable the I/O Instruction Restart feature, bit 9 in TR12 must be set. See section 20.5 for effects on the System Management Mode Revision Identifier of turning this feature ON or leaving it OFF.

#### 20.2.4.2. SMRAM STATE SAVE MAP

Table 20-3 shows the state save map.

Table 20-2. SMRAM State Save Map

Register Offset	Register	Writeable?
7FFC	CR0	NO
7FF8	CR3	NO
7FF4	EFLAGS	YES
7FF0	EIP	YES
7FEC	EDI	YES
7FE8	ESI	YES
7FE4	EBP	YES
7FE0	ESP	YES
7FDC	EBX	YES
7FD8	EDX	YES
7FD4	ECX	YES
7FD0	EAX	YES
7FCC	DR6	NO
7FC8	DR7	NO
7FC4	TR*	NO
7FC0	LDT Base*	NO
7FBC	GS*	NO
7FB8	FS*	NO
7FB4	DS*	NO
7FB0	SS*	NO
7FAC	CS*	NO
7FA8	ES*	NO
7FA7 - 7F98	Reserved	NO
7F94	IDT Base	NO

**Table 20-3. SMRAM State Save Map (Contd.)**

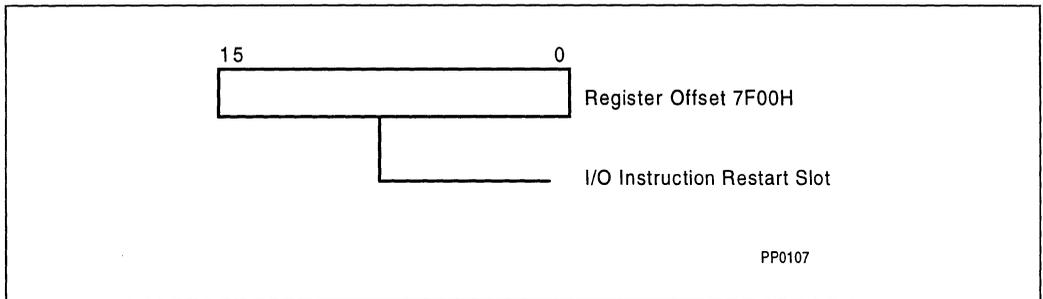
Register Offset	Register	Writeable?
7F93-7F8C	Reserved	NO
7F88	GDT Base	NO
7F87-7F04	Reserved	NO
7F02	Auto HALT Restart Slot (Word)	YES
7F00	I/O Instruction Restart Slot (Word)	YES
7EFC	SMM Revision Identifier (Dword)	NO
7EF8	SMBASE Slot (Dword)	YES
7EF7 - 7E00	Reserved	NO

**NOTES:**

\* Upper two bytes are reserved

Modifying a value that is marked as not writeable will result in unpredictable behavior.

**20.2.4.2.1. I/O Instruction Restart Slot**



**Figure 20-7. I/O Instruction Restart Slot**

Value at entry	Value at exit	Comments
00H	00H	Do not restart trapped I/O instruction
00H	0FFH	Restart trapped I/O instruction

The I/O instruction restart slot (register offset 7F00H in SMRAM) gives the SMM handler the option of causing the RSM instruction to automatically re-execute the interrupted I/O instruction. When the RSM instruction is executed, if the I/O instruction restart slot contains the value 0FFH, then the EIP is modified to point to the instruction immediately preceding the SMI# request, and the CPU will automatically re-execute the I/O instruction that the SMI trapped. If the I/O instruction restart slot contains the value 00H when the RSM

instruction is executed, then the CPU will not re-execute the I/O instruction. The CPU automatically initializes the I/O instruction restart slot to 00H during SMM entry. The I/O instruction restart slot should be written only by the SMM handler when the processor has asserted the SMI# pin on an I/O instruction boundary. Processor operation is unpredictable when the I/O instruction restart slot is set when the processor is servicing an SMI# pin assertion that originated on a non-I/O instruction boundary.

#### **20.2.4.3. BACK-TO-BACK SMI# AND I/O INSTRUCTION RESTART**

If a new SMI# request is received while the CPU is executing an SMM handler, the CPU will service this SMI# request before restarting the original I/O instruction. If the I/O restart slot is set when the CPU executes the RSM instruction for the second SMM handler, execution of the RSM instruction will decrement the restored EIP again. The EIP now points to an address different from the originally interrupted instruction, and the CPU will begin execution of the interrupted application code at an incorrect entry point.

#### **WARNING**

The SMM handler routine must not set the I/O Instruction Restart slot during the second of two consecutive SMM invocations.

#### **20.2.4.4. EXIT FROM SMM**

There is one additional Pentium processor (735\90, 815\100, 1000\120, 1110\133) SMM feature (to exit from SMM) that can be enabled by writing to control "slots" in the SMRAM state save area:

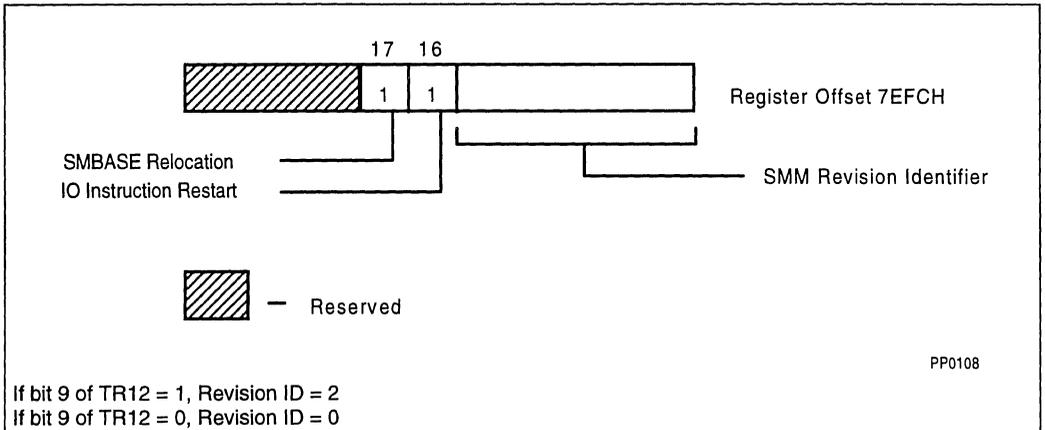
#### **I/O Instruction Restart**

If the SMI# interrupt was generated on an I/O access to a powered-down device, the SMI handler can tell the RSM instruction to re-execute that I/O instruction by setting the I/O Instruction Restart slot.

### **20.2.5. System Management Mode Revision Identifier**

The SMM revision identifier is used to indicate the version of SMM and the SMM extensions that are supported by the processor. The SMM revision identifier is written during SMM entry and can be examined in SMRAM space at Register Offset 7EFCH. The lower word of the SMM revision identifier refers to the version of the base SMM architecture. The upper word of the SMM revision identifier refers to the extensions available.





**Figure 20-8. System Revision Identifier**

Bits	Value	Comments
16	0	Processor does not support I/O Instruction Restart *
16	1	Processor supports I/O Instruction Restart (default)
17	0	Processor does not support SMBASE relocation
17	1	Processor supports SMBASE relocation

**NOTE:**

\* Pentium processor (510\60, 567\66) only

Bit 16 of the SMM revision identifier indicates to the SMM handler whether or not this processor supports the SMM I/O Instruction Restart extension. If this bit is high, then this processor supports the SMM I/O Instruction Restart extension. If this bit is low, then this processor does not support I/O trapping using the I/O trap slot mechanism.

Bit 17 of this slot indicates whether the processor supports relocation of the SMM jump vector and the SMRAM base address.

The Pentium processor (735\90, 815\100, 1000\120, 1110\133) supports both the I/O Instruction Restart and the SMBASE relocation features. To turn ON the I/O Instruction Restart feature, bit 9 in TR12 must be set in the Pentium Processor (735\90, 815\100, 1000\120, 1110\133).

### 20.2.6. SMM — Dual Processing Considerations

Although the SMM functions the same when the Dual processor is inserted into Socket 5, the dual processor operation of the system must be carefully considered. The issues have to be addressed with the following: SMI# delivery, SMRAM and SMIACT#.

### **20.2.6.1. DP SMI DELIVERY**

In the Pentium processor (735\90, 815\100, 1000\120, 1110\133), System Management Interrupt may be delivered via the SMI# pin or the local APIC. For additional details, refer to Chapter 30 of the *Pentium® Processor Family Developer's Manual*, Volume 1.

### **20.2.6.2. DP SMRAM**

SMM is not re-entrant due the fact that the SMRAM State Save Map is fixed relative to the SMBASE. If there is a need to support both processors in SMM mode at the same time then the Primary and Dual processors should have dedicated, non-overlapping SMRAM spaces. This can be done by using the SMBASE Relocation feature that the Primary and Dual processors support. For additional details, refer to section 20.5.3 of this document.

### **20.2.6.3. DP SMIACT#**

During dual processing operation, SMIACT# is driven only by the MRM processor, and should be sampled with ADS#. For additional details, refer to Chapter 30 of the *Pentium® Processor Family User's Manual*, Volume 1.



# **Part III**

## **Compatibility**





**21**

## **Mixing 16-Bit and 32-Bit Code**



## CHAPTER 21

# MIXING 16-BIT AND 32-BIT CODE

The Pentium processor running in protected mode, like the Intel486 and Intel386 processors, is a complete 32-bit architecture, but it supports programs written for the 16-bit architecture of earlier Intel processors. There are three levels of this support:

1. Running 8086 and 80286 code with complete compatibility.
2. Mixing 16-bit modules with 32-bit modules.
3. Mixing 16-bit and 32-bit addresses and data within one module.

The first level is discussed in Chapter 9, Chapter 22, and Chapter 23. Chapter 18 shows how 16-bit and 32-bit modules can cooperate with one another, and how one module can use both 16-bit and 32-bit operands and addressing.

The Pentium processor functions most efficiently when the processor can distinguish between pure 16-bit modules and pure 32-bit modules. A pure 16-bit module has these characteristics:

- All segments occupy 64 Kbytes or less.
- Data items are primarily 8 bits or 16 bits wide.
- Pointers to code and data have 16-bit offsets.
- Control is transferred only among 16-bit segments.

A pure 32-bit module has these characteristics:

- Segments may occupy more than 64 Kbytes (0 bytes to 4 gigabytes).
- Data items are primarily 8 bits or 32 bits wide.
- Pointers to code and data have 32-bit offsets.
- Control is transferred only among 32-bit segments.

A program written for 16-bit processor would be pure 16-bit code. A new program written for the protected mode of the Pentium processor would be pure 32-bit code.

### 21.1. USING 16-BIT AND 32-BIT ENVIRONMENTS

The features of the architecture which permit the Pentium processor to mix 16-bit and 32-bit address and operand size include:

- The D-bit (default bit) of code-segment descriptors, which determines the default choice of operand-size and address-size for the instructions of a code segment. (In real-address mode and virtual-8086 mode, which do not use descriptors, the default is 16 bits.) A code segment whose D-bit is set is a 32-bit segment; a code segment whose D-bit is clear

is a 16-bit segment. The D-bit eliminates the need to put the operand size and address size in instructions when all instructions use operands and effective addresses of the same size.

- Instruction prefixes to override the default choice of operand size and address size (available in protected mode as well as in real-address mode and virtual-8086 mode).
- Separate 32-bit and 16-bit gates for intersegment control transfers (including call gates, interrupt gates, and trap gates). The operand size for the control transfer is determined by the type of gate, not by the D-bit or prefix of the transfer instruction.
- Registers which can be used both for 16-bit and 32-bit operands and effective-address calculations.
- The B bit (Big bit) of the stack segment descriptor, which specifies the size of stack pointer (the 32-bit ESP register or the 16-bit SP register) used by the processor for implicit stack references. The B bit for all data descriptors also controls upper address range for expand down segments.

## 21.2. MIXING 16-BIT AND 32-BIT OPERATIONS

The Pentium processor has two instruction prefixes which allow mixing of 32-bit and 16-bit operations within one segment:

- The operand-size prefix (66H)
- The address-size prefix (67H)

These prefixes *reverse* the default size selected by the Default bit. For example, the processor can interpret the MOV mem, reg instruction in any of four ways:

- In a 32-bit segment:
  1. Moves 32 bits from a 32-bit register to memory using a 32-bit effective address.
  2. If preceded by an operand-size prefix, moves 16 bits from a 16-bit register to memory using a 32-bit effective address.
  3. If preceded by an address-size prefix, moves 32 bits from a 32-bit register to memory using a 16-bit effective address.
  4. If preceded by both an address-size prefix and an operand-size prefix, moves 16 bits from a 16-bit register to memory using a 16-bit effective address.
- In a 16-bit segment:
  1. Moves 16 bits from a 16-bit register to memory using a 16-bit effective address.
  2. If preceded by an operand-size prefix, moves 32 bits from a 32-bit register to memory using a 16-bit effective address.
  3. If preceded by an address-size prefix, moves 16 bits from a 16-bit register to memory using a 32-bit effective address.



4. If preceded by both an address-size prefix and an operand-size prefix, moves 32 bits from a 32-bit register to memory using a 32-bit effective address.

These examples show that any instruction can generate any combination of operand size and address size regardless of whether the instruction is in a 16- or 32-bit segment. The choice of the 16- or 32-bit default for a code segment is based upon these criteria:

1. The need to address instructions or data in segments which are larger than 64 Kbytes.
2. The predominant size of operands.
3. The addressing modes desired.

The Default bit should be given a setting which allows the predominant size of operands to be accessed without operand-size prefixes.

### 21.3. SHARING DATA AMONG MIXED-SIZE CODE SEGMENTS

Because the choice of operand size and address size is specified in code segments and their descriptors, data segments can be shared freely among both 16-bit and 32-bit code segments. The only limitation is imposed by pointers with 16-bit offsets, which only can point to the first 64 Kbytes of a segment. When a data segment with more than 64 Kbytes is to be shared among 16- and 32-bit segments, the data which is to be accessed by the 16-bit segments must be located within the first 64 Kbytes.

A stack which spans less than 64 Kbytes can be shared by both 16- and 32-bit code segments. This class of stacks includes:

- Stacks in expand-up segments with the Granularity and Big bits clear.
- Stacks in expand-down segments with the Granularity and Big bits clear.
- Stacks in expand-up segments with the Granularity bit set and the Big bit clear, in which the stack is contained completely within the lower 64 Kbytes. (Offsets greater than 0FFFFH can be used for data, other than the stack, which is not shared.)

The B-bit of a stack segment cannot, in general, be used to change the size of stack used by a 16-bit code segment. The size of stack pointer used by the processor for implicit stack references is controlled by the B-bit of the data-segment descriptor for the stack. Implicit references are those caused by interrupts, exceptions, and instructions such as the PUSH, POP, CALL, and RET instructions. Although it seems like the B bit could be used to increase the stack segment for 16-bit programs beyond 64 Kbytes, this may not be done. The B-bit does not control *explicit* stack references, such as accesses to parameters or local variables. A 16-bit code segment can use a "big" stack only if the code is modified so that all explicit references to the stack are preceded by the address-size prefix, causing those references to use 32-bit addressing and explicit writes to the stack pointer are preceded by an operand-size prefix.

In big, expand-down segments (the Big, and Expand-down bits set), all offsets may be greater than 64K, therefore 16-bit code cannot use this kind of stack segment unless the code

segment is modified to use 32-bit addressing. (See Chapter 12 for more information about the B and E bits.)

## 21.4. TRANSFERRING CONTROL AMONG MIXED-SIZE CODE SEGMENTS

When transferring control among procedures in 16-bit and 32-bit code segments, programmers must be aware of three points:

- Addressing limitations imposed by pointers with 16-bit offsets.
- Matching of operand-size attribute in effect for the CALL/RET instruction pair and the Interrupt/IRET pair for managing the stack correctly.
- Translation of parameters, especially pointer parameters.
- The validity of the SP register must be noted when using 16-bit gates (see Section 21.4.2.).

Clearly, 16-bit effective addresses cannot be used to address data or code located beyond 0FFFFH in a 32-bit segment, nor can large 32-bit parameters be squeezed into a 16-bit word; however, except for these obvious limits, most interface problems between 16-bit and 32-bit modules can be solved. Some solutions involve inserting interface code between modules.

### 21.4.1. Size of Code-Segment Pointer

For control-transfer instructions which use a pointer to identify the next instruction (i.e., those which do not use gates), the size of the offset portion of the pointer is determined by the operand-size attribute. The implications of the use of two different sizes of code-segment pointer are:

- A JMP, CALL, or RET instruction from a 32-bit segment to a 16-bit segment is always possible using a 32-bit operand size.
- A JMP, CALL, or RET instruction from a 16-bit segment using a 16-bit operand size cannot address a destination in a 32-bit segment if the address of the destination is greater than 0FFFFH.

An interface procedure can provide a mechanism for transfers from 16-bit segments to destinations in 32-bit segments beyond 64K. The requirements for this kind of interface procedure are discussed later in this chapter.

### 21.4.2. Stack Management for Control Transfer

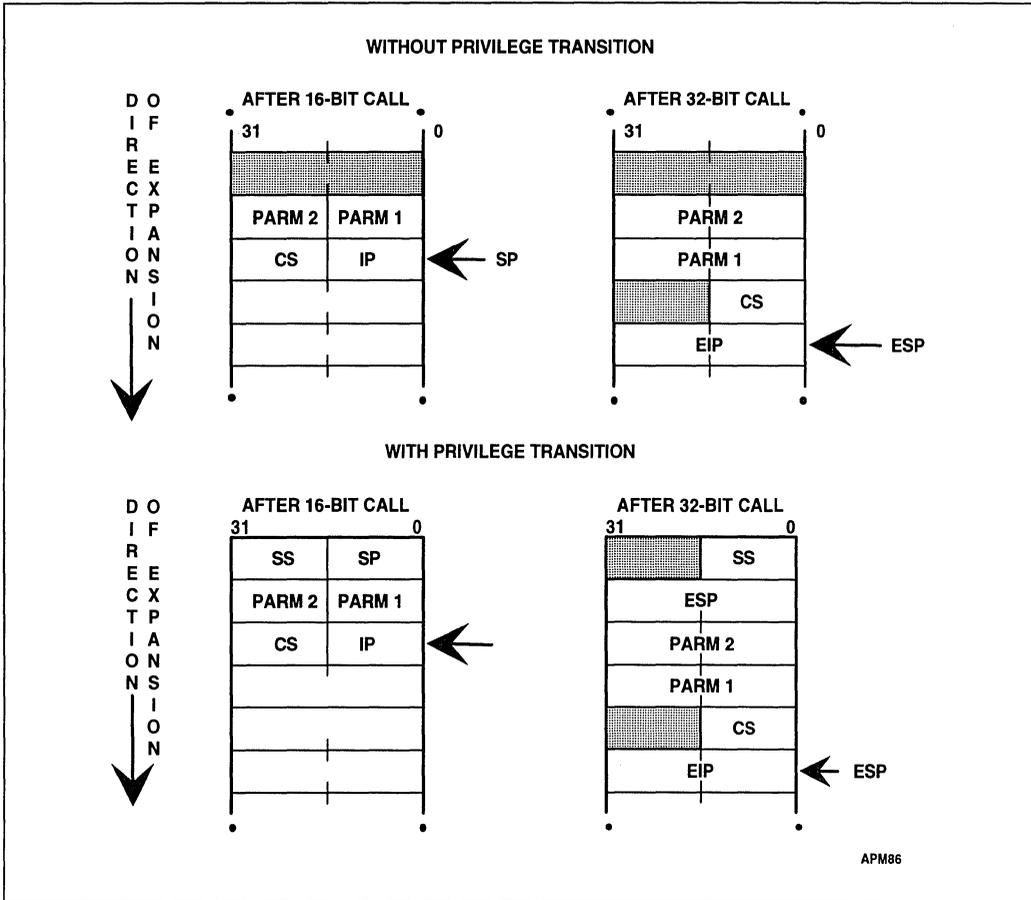
Because stack management is different for 16-bit CALL and RET instructions than for 32-bit CALL and RET instructions, the operand size of the RET instruction must match the CALL instruction. (See Figure 21-1.) A 16-bit CALL instruction pushes the contents of the 16-bit IP



register and (for calls between privilege levels) the 16-bit SP register. The matching RET instruction also must use a 16-bit operand size to pop these 16-bit values from the stack into the 16-bit registers. A 32-bit CALL instruction pushes the contents of the 32-bit EIP register and (for interlevel calls) the 32-bit ESP register. The matching RET instruction also must use a 32-bit operand size to pop these 32-bit values from the stack into the 32-bit registers. If the two parts of a CALL/RET instruction pair do not have matching operand sizes, the stack will not be managed correctly and the values of the instruction pointer and stack pointer will not be restored to correct values.

While executing 32-bit code, if a call to 16-bit code at a higher or equal privilege level (i.e.,  $DPL \leq CPL$ ) is made via a 16-bit call gate, then the upper 16-bits of the ESP register may be unreliable upon returning to the 32-bit code (i.e., after executing a RET in the 16-bit code segment).

When the CALL instruction and its matching RET instruction are in segments which have D bits with the same values (i.e., both have 32-bit defaults or both have 16-bit defaults), the default settings may be used. When the CALL instruction and its matching RET instruction are in segments which have different D-bit values, an operand size prefix must be used.



**Figure 21-1. Stack after Far 16- and 32-Bit Calls**

There are three ways for a 16-bit procedure to make a 32-bit call:

1. Use a 16-bit call to a 32-bit interface procedure. The interface procedure uses a 32-bit call to the intended destination.
2. Make the call through a 32-bit call gate.
3. Modify the 16-bit procedure, inserting an operand-size prefix before the call, to change it to a 32-bit call.

Likewise, there are three ways to cause a 32-bit procedure to make a 16-bit call:

1. Use a 32-bit call to a 32-bit interface procedure. The interface procedure uses a 16-bit call to the intended destination.
2. Make the call through a 16-bit call gate (the offset cannot exceed 0FFFFH).

3. Modify the 32-bit procedure, inserting an operand-size prefix before the call, thereby changing it to a 16-bit call. (Be certain that the return offset does not exceed 0FFFFH.)

Programmers can use any of the preceding methods to make a CALL instruction in a 16-bit segment match the corresponding RET instruction in a 32-bit segment, or to make a CALL instruction in a 32-bit segment match the corresponding RET instruction in a 16-bit segment.

#### NOTE:

When POP SS is used to switch from a 32-bit stack to a 16-bit stack, the Pentium processor updates ESP[15:0] (or the SP register), based on the new value of the B bit (B = '0') of the stack segment descriptor. In the case where the value in ESP before the switch contains a boundary condition (e.g., ESP[31:0] = 07ffffch), the new value in ESP after the switch will only be reflected on the lower 16 bits (i.e., ESP[31:0] = 07ff0000h). Therefore, code that switches from a 32-bit stack to a 16-bit stack via the POP SS instruction must not rely on ESP[31:16].

Similar considerations apply when switching from 16-bit to 32-bit stacks. When executing POP SS to switch from 16-bit stack to 32-bit stack, only SP (the old stack size) is used to increment the stack pointer, instead of ESP (the new stack size, 32-bit).

#### 21.4.2.1. CONTROLLING THE OPERAND SIZE FOR A CALL

The operand-size attribute in effect for the CALL instruction is specified by the D bit for the segment containing the destination and by any operand-size instruction prefix.

When the selector of the pointer referenced by a CALL instruction selects a gate descriptor, the type of call is determined by the type of call gate. Calls gates with descriptor type 4 have a 16-bit operand-size attribute; call gates with descriptor type 12 have a 32-bit operand-size attribute. The offset to the destination is taken from the gate descriptor; therefore, even a 16-bit procedure can call a procedure located more than 64 Kbytes from the base of a 32-bit segment, because a 32-bit call gate contains a 32-bit offset.

An unmodified 16-bit code segment which has run successfully on an 8086 processor or in real-mode on an Intel 286 processor will have a D-bit which is clear and will not use operand-size override prefixes; therefore, it will use 16-bit versions of the CALL instruction. The only modification needed to make a 16-bit procedure produce a 32-bit call is to relink the call to a 32-bit call gate.

#### 21.4.2.2. CHANGING SIZE OF A CALL

When adding 32-bit gates to 16-bit procedures, it is important to consider the number of parameters. The count field of the gate descriptor specifies the size of the parameter string to copy from the current stack to the stack of the more privileged procedure. The count field of a 16-bit gate specifies the number of 16-bit words to be copied, whereas the count field of a

32-bit gate specifies the number of 32-bit doublewords to be copied; therefore, the 16-bit procedure must use an even number of words as parameters.

### 21.4.3. Interrupt Control Transfers

With a control transfer caused by an exception or interrupt, a gate is used. The operand-size attribute for the interrupt is determined by the gate descriptor in the interrupt descriptor table (IDT).

A 32-bit interrupt or trap gate (descriptor type 14 or 15) to a 32-bit interrupt handler can be used to interrupt either 32-bit or 16-bit procedures. However, sometimes it is not practical to permit an interrupt or exception to call a 16-bit handler when 32-bit code is running, because a 16-bit interrupt procedure has a return offset of only 16 bits saved on its stack. If the 32-bit procedure is running at an address beyond 0FFFFH, the 16-bit interrupt procedure cannot provide the return address.

### 21.4.4. Parameter Translation

When segment offsets or pointers (which contain segment offsets) are passed as parameters between 16-bit and 32-bit procedures, some translation is required. If a 32-bit procedure passes a pointer to data located beyond 64K to a 16-bit procedure, the 16-bit procedure cannot use it. Except for this limitation, interface code can perform any format conversion between 32-bit and 16-bit pointers which may be needed.

Parameters passed by value between 32-bit and 16-bit code also may require translation between 32-bit and 16-bit formats. The form of the translation is application-dependent.

### 21.4.5. The Interface Procedure

Placing interface code between 32-bit and 16-bit procedures can be the solution to several interface problems:

- Allowing procedures in 16-bit segments to call procedures with offsets greater than 0FFFFH in 32-bit segments.
- Matching operand size between CALL and RET instructions.
- Translating parameters (data).
- Possible invalidation of the upper bits of the ESP register.

The interface code is simplified where these restrictions are followed.

- Interface code resides in a code segment whose D-bit is set, which indicates a default operand size of 32 bits.
- All procedures which may be called by 16-bit procedures have offsets which are not greater than 0FFFFH.

- All return addresses saved by 16-bit procedures also have offsets not greater than 0FFFFH.

The interface code becomes more complex if any of these restrictions are violated. For example, if a 16-bit procedure calls a 32-bit procedure with an entry point beyond 0FFFFH, the interface code will have to provide the offset to the entry point. The mapping between 16- and 32-bit addresses only is performed automatically when a call gate is used, because the descriptor for a call gate contains a 32-bit address. When a call gate is not used, the descriptor must provide the 32-bit address.

The interface code calls procedures in other segments. There may be two kinds of interface:

- Where 16-bit procedures call 32-bit procedures. The interface code is called by 16-bit CALL instructions and uses the operand-size prefix before RET instructions for performing a 16-bit RET instruction. Calls to 32-bit segments are 32-bit CALL instructions (by default, because the D-bit is set), and the 32-bit code returns with 32-bit RET instructions.
- Where 32-bit procedures call 16-bit procedures. The interface code is called by 32-bit CALL instructions, and returns with 32-bit RET instructions (by default, because the D-bit is set). CALL instructions to 16-bit procedures use the operand-size prefix; 16-bit procedures return with 16-bit RET instructions.



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**22**

## **Virtual-8086 Mode**





## CHAPTER 22

# VIRTUAL-8086 MODE

The Pentium processor supports execution of one or more 8086 or 8088 programs in a Pentium processor protected-mode environment. An 8086 program runs in this environment as part of a virtual-8086 task. Virtual-8086 tasks take advantage of the hardware support for multitasking offered by the protected mode. Not only can there be multiple virtual-8086 tasks, each one running an 8086 program, but virtual-8086 tasks can be multitasked with other Pentium processor tasks.

The purpose of a virtual-8086 task is to form a "virtual machine" for running programs written for the 8086 processor. A complete virtual machine consists of hardware and system software. The emulation of an 8086 processor is the result of software using hardware in the following ways:

- The hardware provides a virtual set of registers (through the TSS), a virtual memory space (the first megabyte of the linear address space of the task), and virtual interrupt support and directly executes all instructions which deal with these registers and with this address space.
- The software controls the external interfaces of the virtual machine (I/O, interrupts, and exceptions) in a manner consistent with the larger environment in which it runs. Software can choose to emulate I/O and interrupt and exception handling or let the hardware execute them directly without software intervention.

Software which supports virtual 8086 machines is called a virtual-8086 monitor. The Pentium processor includes extensions to its virtual-8086 mode of operation that improve the performance of applications by eliminating the overhead of faulting to a virtual-8086 monitor for emulation of certain operations. For more information on the virtual mode extensions on the Pentium processor, see Appendix H.

### 22.1. EXECUTING 8086 CPU CODE

The processor runs in virtual-8086 mode when the VM (virtual machine) bit in the EFLAGS register is set. The processor tests this flag under two general conditions:

1. When loading segment registers, to know whether to use 8086-style address translation.
2. When decoding instructions, to determine which instructions are sensitive to IOPL and which instructions are not supported (as in real mode).

### 22.1.1. Registers and Instructions

The register set available in virtual-8086 mode includes all the registers defined for the 8086 processor plus new registers introduced after the 8086 processor (FS and GS). Instructions, which explicitly operate on the segment registers FS and GS, are available. The segment-override prefixes can be used to cause instructions to use the FS and GS registers for address calculations. Instructions can take advantage of 32-bit operands through the use of the operand size prefix.

Programs running as virtual-8086 tasks can take advantage of the new application-oriented instructions added to the architecture by the introduction of the Intel 286, Intel386, Intel486, and Pentium processors:

- New instructions introduced on the Intel 286 processors.
  - PUSH immediate data
  - Push all and pop all (PUSHA and POPA)
  - Multiply immediate data
  - Shift and rotate by immediate count
  - String I/O
  - ENTER and LEAVE instructions
  - BOUND instruction
- New instructions introduced on the Intel386 processors.
  - LSS, LFS, LGS instructions
  - Long-displacement conditional jumps
  - Single-bit instructions
  - Bit scan instructions
  - Double-shift instructions
  - Byte set on condition instruction
  - Move with sign/zero extension
  - Generalized multiply instruction
- New instructions introduced on the Intel486 processor.
  - BSWAP instruction
  - XADD instruction
  - CMPXCHG instruction
- New instructions introduced on the Pentium processor.
  - CMPXCHG8B instruction
  - CPUID instruction



Existing interrupt flag sensitive instructions provide significant performance improvement when using the virtual mode extensions of the Pentium processor. See Appendix H for more information.

### 22.1.2. Address Translation

In virtual-8086 mode, the Pentium processor does not interpret 8086 selectors by referring to descriptors; instead, it forms linear addresses as an 8086 processor would. It shifts the selector left by four bits to form a 20-bit base address. The effective address is extended with four clear bits in the upper bit positions and added to the base address to create a linear address, as shown in Figure 22-1.

Because of the possibility of a carry, the resulting linear address may have as many as 21 significant bits. An 8086 program may generate linear addresses anywhere in the range 0 to 10FFEFH (1 megabyte plus approximately 64 Kbytes) of the task's linear address space.

Virtual-8086 tasks generate 32-bit linear addresses. While an 8086 program can use only the lowest 21 bits of a linear address, the linear address can be mapped using paging to any 32-bit physical address.

Unlike the 8086 and 80286 processors, but like the Intel386 and Intel486 processors, the Pentium processor can generate 32-bit effective addresses using an address override prefix. However in virtual-8086 mode, the value of a 32-bit address may not exceed 65,535 without causing an exception. Protection faults (interrupt 12 or 13 with no error code) occur if an effective address is generated outside the range 0 through 65,535.

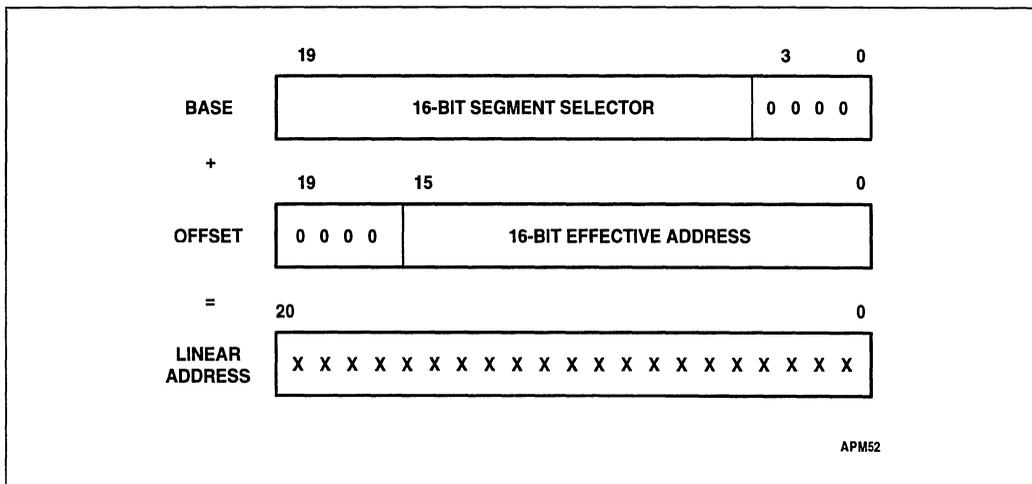


Figure 22-1. 8086 Address Translation

## 22.2. STRUCTURE OF A VIRTUAL-8086 TASK

A virtual-8086 task consists of the 8086 program to be run and the 32-bit "native mode" code which serves as the virtual-machine monitor. The task must be represented by a 32-bit TSS (not a 16-bit TSS). The processor enters virtual-8086 mode to run the 8086 program and returns to protected mode to run the monitor or other 32-bit protected-mode tasks.

To run in virtual-8086 mode, an existing 8086 processor program needs the following:

- A virtual-8086 monitor.
- Operating-system services.

The virtual-8086 monitor is 32-bit protected-mode code which runs at privilege-level 0 (most privileged). The monitor mostly consists of initialization, exception-handling procedures, and I/O emulation in order to virtualize the PC platform. As with any other Pentium processor program, code-segment descriptors for the monitor must exist in the GDT or in the task's LDT. The linear addresses above 10FFEFH are available for the virtual-8086 monitor, the operating system, and other system software. The monitor also may need data-segment descriptors so it can examine the interrupt vector table or other parts of the 8086 program in the first megabyte of the address space.

In general, there are two options for implementing the 8086 operating system:

1. The 8086 operating system may run as part of the 8086 program. This approach is desirable for either of the following reasons:
  - The 8086 application code modifies the operating system.
  - There is not sufficient development time to reimplement the 8086 operating system as a Pentium processor operating system.
2. The 8086 operating system may be implemented or emulated in the virtual-8086 monitor. This approach is desirable for any of the following reasons:
  - Operating system functions can be more easily coordinated among several virtual-8086 tasks.
  - The functions of the 8086 operating system can be easily emulated by calls to the Pentium processor operating system.

Note that the approach chosen for implementing the 8086 processor operating system may have different virtual-8086 tasks using different 8086 operating systems.

### 22.2.1. Paging for Virtual-8086 Tasks

Paging is not necessary for a single virtual-8086 task, but paging is useful or necessary for any of the following reasons:

- Creating multiple virtual-8086 tasks. Each task must map the lower megabyte of linear addresses to different physical locations.



- Emulating the address wraparound which occurs at 1 megabyte. With members of the 8086 family, it is possible to specify addresses larger than 1 megabyte. For example, with a selector value of 0FFFFH and an offset of 0FFFFH, the effective address would be 10FFEFH (1 megabyte plus 65519 bytes). The 8086 processor, which can form addresses only up to 20 bits long, truncates the high-order bit, thereby "wrapping" this address to 0FFEFH. The Pentium processor, however, does not truncate such an address. If any 8086 processor programs depend on address wraparound, the same effect can be achieved in a virtual-8086 task by mapping linear addresses between 100000H and 110000H and linear addresses between 0 and 10000H to the same physical addresses.
- Creating a virtual address space larger than the physical address space.
- Sharing 8086 operating system or ROM code which is common to several 8086 programs running in multitasking.
- Redirecting or trapping references to memory-mapped I/O devices.

### 22.2.2. Protection within a Virtual-8086 Task

Protection is not enforced between the segments of an 8086 program. To protect the system software running in a virtual-8086 task from the 8086 application program, software designers may follow either of these approaches:

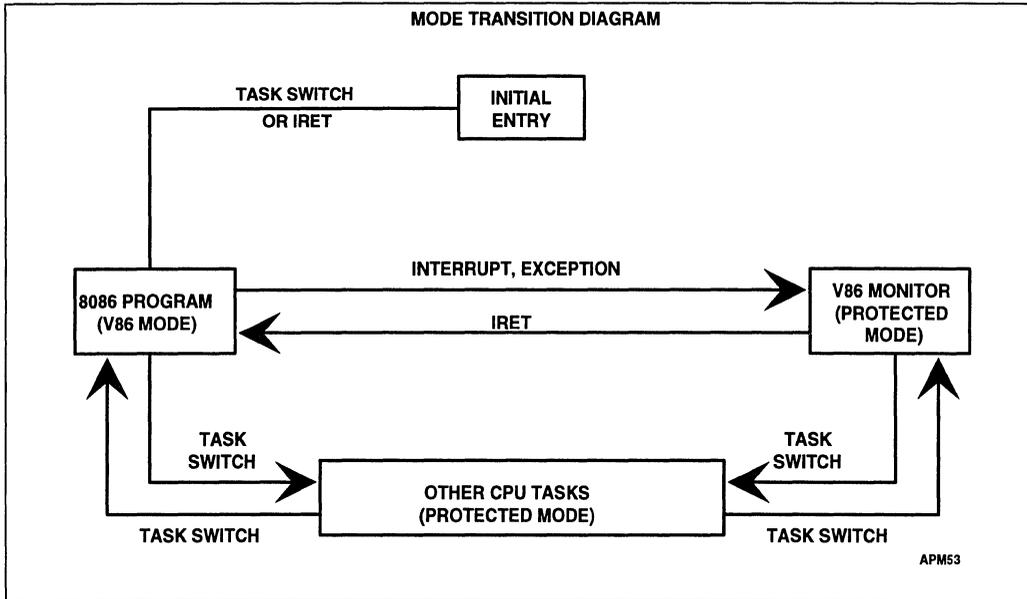
- Reserve the first megabyte (plus 64 Kbytes) of each task's linear address space for the 8086 processor program. An 8086 processor task cannot generate addresses outside this range.
- Use the U/S bit of page-table entries to protect the virtual-machine monitor and other system software in each virtual-8086 task's space. When the processor is in virtual-8086 mode, the CPL is 3 (least privileged). Therefore, an 8086 processor program has only user privileges. If the pages of the virtual-machine monitor have supervisor privilege, they cannot be accessed by the 8086 program.

## 22.3. ENTERING AND LEAVING VIRTUAL-8086 MODE

Figure 22-2 summarizes the ways to enter and leave an 8086 program. Virtual-8086 mode is entered when the VM flag is set. There are two ways to do this:

1. A switch to a task loads the image of the EFLAGS register from the new TSS. The TSS of the new task must be a 32-bit TSS, not a 16-bit TSS, because the 16-bit TSS does not load the high word of the EFLAGS register, which contains the VM flag. A set VM flag in the new contents of the EFLAGS register indicates that the new task is executing 8086 instructions; therefore, while loading the segment registers from the TSS, the processor forms base addresses in the 8086 style.
2. An IRET instruction from a procedure of a task loads the EFLAGS register from the stack. A set VM flag indicates the procedure to which control is being returned to be an

8086 procedure. The CPL at the time the IRET instruction is executed must be 0, otherwise the processor does not change the state of the VM flag.

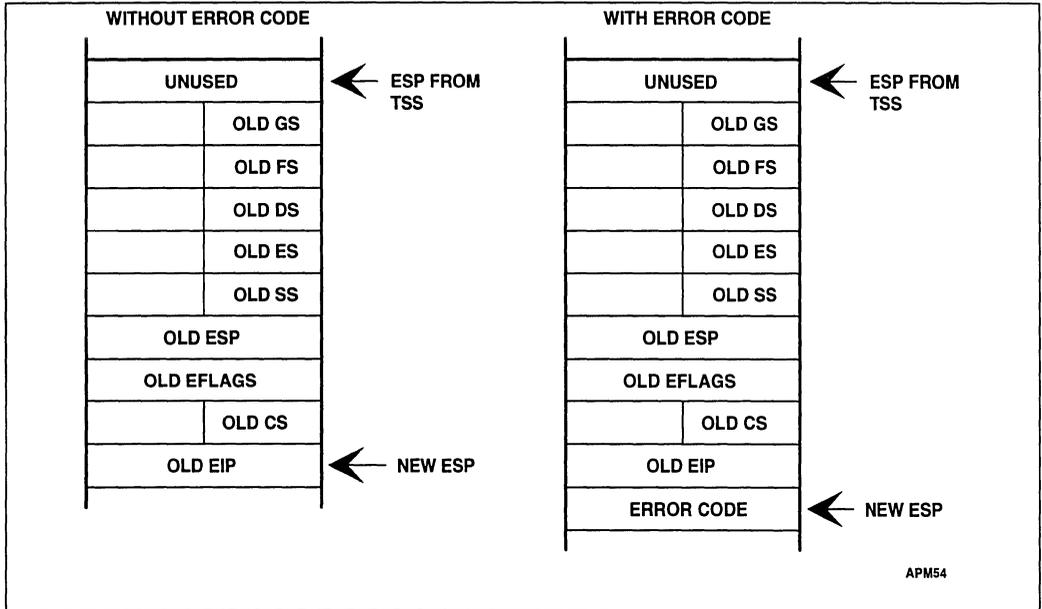


**Figure 22-2. Entering and Leaving Virtual-8086 Mode**

When a task switch is used to enter virtual-8086 mode, the segment registers are loaded from a TSS. When an IRET instruction is used to set the VM flag, however, the segment registers are loaded from the segment registers on the PL0 stack (see Figure 22-3).

The processor leaves virtual-8086 mode when an interrupt or exception occurs. There are two cases:

1. The interrupt or exception causes a task switch. A task switch from a virtual-8086 task to any other task loads the EFLAGS register from the TSS of the new task. If the new TSS is a 32-bit TSS and the VM flag in the new contents of the EFLAGS register is clear or if the new TSS is a 16-bit TSS, the processor clears the VM flag of the EFLAGS register, loads the segment registers from the new TSS using protected-mode address formation, and begins executing the instructions of the new task in 32-bit protected mode.
2. The interrupt or exception calls a privilege-level 0 procedure (most privileged). The processor stores the current contents of the EFLAGS register on the stack, then clears the VM flag. The interrupt or exception handler, therefore, runs as "native" 32-bit protected-mode code. If an interrupt or exception calls a procedure in a conforming segment or in a segment at a privilege level other than 0 (most privileged), the processor generates a general-protection exception; the error code is the selector of the code segment to which a call was attempted.



**Figure 22-3. Privilege Level 0 Stack after Interrupt in Virtual-8086 Mode**

System software does not change the state of the VM flag directly, but instead changes states in the image of the EFLAGS register stored on the stack or in the TSS. The virtual-8086 monitor sets the VM flag in the EFLAGS image on the stack or in the TSS when first creating a virtual-8086 task. Exception and interrupt handlers can examine the VM flag on the stack. If the interrupted procedure was running in virtual-8086 mode, the handler may need to call the virtual-8086 monitor.

### 22.3.1. Transitions Through Task Switches

A task switch to or from a virtual-8086 task may have any of three causes:

1. An interrupt which calls a task gate.
2. An action of the scheduler of the 32-bit operating system.
3. Executing an IRET instruction when the NT flag is set.

In any of these cases, the processor changes the VM flag in the EFLAGS register according to the image in the new TSS. If the new TSS is a 16-bit TSS, the upper word of the EFLAGS register is not in the TSS; the processor clears the VM flag in this case. The processor updates the VM flag prior to loading the segment registers from their images in the new TSS. The new setting of the VM flag determines whether the processor interprets the new segment-register images as 8086 selectors, 80286 selectors or 32-bit selectors.



## 22.3.2. Transitions Through Trap Gates and Interrupt Gates

The processor may leave virtual-8086 mode as the result of an exception or interrupt which calls a trap or interrupt gate. The exception or interrupt handler returns to the 8086 program by executing an IRET instruction.

Exceptions and interrupts can be handled in one of three ways:

1. By the the virtual-8086 monitor.
2. The virtual-8086 monitor can pass control to the 8086 program's interrupt handler.
3. By a protected-mode interrupt service routine.

If the interrupt or exception is one which the monitor needs to handle and the VM flag is set in the EFLAGS image stored on the stack, the interrupt handler passes control to the virtual-8086 monitor. The virtual-8086 monitor may choose one of the first two methods listed above. If the exception or interrupt is one which the monitor does not need to handle, the IOPL can be set to 3 allowing the protected-mode interrupt handler to execute for all virtual-mode interrupts.

Because it was designed to run on an 8086 processor, an 8086 program in a virtual-8086 task has an 8086-style interrupt table, which starts at linear address 0. However, for exceptions and interrupts requiring virtual-8086 monitor intervention and a transition into protected mode, the processor does not use this table directly. Instead, the processor calls handlers through the IDT. The IDT entry for an interrupt or exception in a virtual-8086 task must contain either:

- A task gate.
- A 32-bit trap gate (descriptor type 14) or 32-bit interrupt gate (descriptor type 15), which must point to a nonconforming, privilege-level 0 (most privileged), code segment.

Interrupts and exceptions which call 32-bit trap or interrupt gates use privilege-level 0. The contents of the segment registers are stored on the stack for this privilege level. Figure 22-3 shows the format of this stack after an exception or interrupt which occurs while a virtual-8086 task is running an 8086 program.

After the processor saves the 8086 segment registers on the stack for privilege level 0, it clears the segment registers before running the handler procedure. This lets the interrupt handler safely save and restore the DS, ES, FS, and GS registers as though they were Pentium processor selectors. Interrupt handlers, which may be called in the context of either a regular task or a virtual-8086 task, can use the same code sequences for saving and restoring the registers for any task. Clearing these registers before execution of the IRET instruction does not cause a trap in the interrupt handler. Interrupt procedures which expect values in the segment registers or which return values in the segment registers must use the register images saved on the stack for privilege level 0. Interrupt handlers which need to know whether the interrupt occurred in virtual-8086 mode can examine the VM flag in the stored contents of the EFLAGS register.

Sending an interrupt or exception back to the 8086 program involves the following steps:

1. Use the 8086 interrupt vector to locate the appropriate handler procedure.



2. Store the FLAGS, CS and IP values of the 8086 program on the privilege-level 3 stack (least privileged).
3. Change the return link on the privilege-level 0 stack to point to the privilege-level 3 handler procedure.
4. Execute an IRET instruction to pass control to the handler.
5. When the IRET instruction from the privilege-level 3 handler again calls the virtual-8086 monitor, restore the return link on the privilege-level 0 stack to point to the original, interrupted, privilege-level 3 procedure.
6. Execute an IRET instruction to pass control back to the interrupted procedure.

If the IOPL is set to three and the DPL of the interrupt gate is set to three, INT n instructions will trap with the given vector number n. Interrupt vectors that must have their IDT gates set to three can examine the VM bit in the EFLAGS image on the stack to determine if the interrupt needs to be redirected to the virtual-8086 monitor or passed to the 8086 program's interrupt handler.

## 22.4. SENSITIVE INSTRUCTIONS

When the Pentium processor is running in virtual-8086 mode, the CLI, STI, PUSHF, POPF, INT n, and IRET instructions are sensitive to IOPL. The IN, INS, OUT, and OUTS instructions, which are sensitive to IOPL in protected mode, are not sensitive in virtual-8086 mode. Following is a complete list of instructions which are sensitive in virtual-8086 mode:

CLI	— Clear Interrupt-Enable Flag
STI	— Set Interrupt-Enable Flag
PUSHF	— Push Flags
POPF	— Pop Flags
INT n	— Software Interrupt
IRET	— Interrupt Return

The CPL is always 3 while running in virtual-8086 mode; if the IOPL is less than 3, an attempt to use the instructions listed above triggers a general-protection exception. These instructions are sensitive to IOPL in order to give the virtual-8086 monitor a chance to emulate the facilities they affect. For information on the behavior of these instructions using the virtual mode extensions, see Appendix H.

## 22.5. VIRTUAL INTERRUPT SUPPORT

Many 8086 programs written for non-multitasking systems set and clear the IF flag to control interrupts. This may cause problems in a multitasking environment. As a result, virtual monitors running on the Intel386 and Intel486 processors require maintaining a virtual interrupt flag in software. All instructions affecting the IF flag trap to the virtual-8086

monitor for emulation on these processors. For more information on Pentium processor support of a virtual interrupt flag, see Appendix H.

## 22.6. EMULATING 8086 OPERATING SYSTEM CALLS

Many 8086 operating systems are called by pushing parameters onto the stack, then executing an `INT n` instruction. The `INT n` instruction is sensitive to `IOPL` to allow the virtual-8086 monitor to emulate the function of the 8086 operating system or send the interrupt back to the 8086 operating system.

When the `IOPL < 3`, `INT n` instructions are intercepted by the virtual-8086 monitor. When the `IOPL = 3`, interrupts are serviced by the protected-mode interrupt service routine in a manner compatible with the Intel486 processor. On the Intel386 and Intel486 processors, all `INT n` instructions running in virtual-8086 mode require interception by the virtual-8086 monitor when the `IOPL` is less than 3. For information on Pentium processor virtual mode extension support of interrupt handling, see Appendix H.

Table 22-1 determines what action the Pentium processor takes in virtual-8086 mode for a software interrupt based on the `IOPL`.

**Table 22-1. Software Interrupt Operation**

IOPL	Processor Action
=3	<p><b>Interrupt from Virtual-8086 Mode to Protected Mode:</b></p> <ul style="list-style-type: none"> <li>Clears VM and TF flags</li> <li>If service through interrupt gate, clears IF flag</li> <li>Changes to PL0 stack using TSS values</li> <li>Pushes GS, FS, DS and ES onto PL0 stack</li> <li>Clears GS, FS, DS and ES to 0</li> <li>Pushes SS, ESP, EFLAGS, CS and EIP of interrupted task onto PL0 stack</li> <li>Sets CS and EIP from interrupt gate</li> </ul>
<3	<b>General protection exception</b>

## 22.7. VIRTUAL I/O

Many 8086 programs written for non-multitasking systems directly access I/O ports. This may cause problems in a multitasking environment. If more than one program accesses the same port, they may interfere with each other. Most multitasking systems require application programs to access I/O ports through the operating system. This results in simplified, centralized control.



The processor provides I/O protection for creating I/O which is compatible with the environment and transparent to 8086 programs. Designers may take any of several possible approaches to protecting I/O ports:

- Protect the I/O address space and generate exceptions for all attempts to perform I/O directly.
- Let the 8086 processor program perform I/O directly.
- Generate exceptions on attempts to access specific I/O ports.
- Generate exceptions on attempts to access specific memory-mapped I/O ports.

The method of controlling access to I/O ports depends upon whether they are I/O-mapped or memory-mapped.

### 22.7.1. I/O-Mapped I/O

The I/O permission bit map can be used to generate exceptions on attempts to access specific I/O addresses. The I/O permission bit map of each virtual-8086 task determines which I/O addresses generate exceptions for that task. Because each task may have a different I/O permission bit map, the addresses which generate exceptions for one task may be different from the addresses for another task. This differs from protected mode because the IOPL is not checked. See Chapter 8 for more information about the I/O permission bit map.

### 22.7.2. Memory-Mapped I/O

In systems which use memory-mapped I/O, the paging facilities of the processor can be used to generate exceptions for attempts to access I/O ports. The virtual-8086 monitor may use paging to control memory-mapped I/O in these ways:

- Map part of the linear address space of each task which needs to perform I/O to the physical address space where I/O ports are placed. By putting the I/O ports at different addresses (in different pages), the paging mechanism can enforce isolation between tasks.
- Map part of the linear address space to pages which are not-present. This generates an exception whenever a task attempts to perform I/O to those pages. System software then can interpret the I/O operation being attempted.

Software emulation of the I/O space may require too much operating system intervention under some conditions. In these cases, it may be possible to generate an exception for only the first attempt to access I/O. The system software then may determine whether a program can be given exclusive control of I/O temporarily, the protection of the I/O space may be lifted, and the program allowed to run at full speed.

### 22.7.3. Special I/O Buffers

Buffers of intelligent controllers (for example, a bit-mapped frame buffer) also can be emulated using page mapping. The linear space for the buffer can be mapped to a different physical space for each virtual-8086 task. The virtual-8086 monitor then can control which virtual buffer to copy onto the real buffer in the physical address space.

## 22.8. DIFFERENCES FROM 8086 CPU

In general, virtual-8086 mode will run software written for the 8086 and 8088 processors. The following list shows the minor differences between the 8086 processor and the virtual-8086 mode of the Pentium processor and other 32-bit processors.

#### 1. Instruction clock counts.

The 32-bit processors takes fewer clocks for most instructions than the 8086 processor.

The areas most likely to be affected include:

- Delays required by I/O devices between I/O operations.
- Assumed delays with 8086 processor operating in parallel with an 8087.

#### 2. Divide exceptions point to the DIV instruction.

Divide exceptions on the Pentium processor always leave the saved CS:IP value pointing to the instruction which failed. On the 8086 processor, the CS:IP value points to the next instruction.

#### 3. Undefined 8086 processor opcodes.

Opcodes which were not defined for the 8086 processor generate an invalid-opcode or execute as one of the new instructions defined for the Pentium processor.

#### 4. Value written by PUSH SP.

The Pentium processor pushes a different value on the stack for PUSH SP than the 8086 processor. The Pentium processor pushes the value in the SP register before it is decremented as part of the push operation; the 8086 processor pushes the value of the SP register after it is decremented. If the pushed value is important, replace PUSH SP instructions with the following three instructions:

```
PUSH     BP
MOV BP,  SP
XCHG    BP, [BP]
```

This code functions as the 8086 PUSH SP instruction on the Pentium processor.

#### 5. Shift or rotate by more than 31 bits.

The Pentium processor masks all shift and rotate counts to the lowest five bits. This limits the count to a maximum of 31 bit positions.

#### 6. Redundant prefixes.

The Pentium processor limits instructions to 15 bytes. The only way to violate this limit is with redundant prefixes before an instruction. A general-protection exception is

generated if the limit on instruction length is violated. The 8086 processor has no instruction length limit.

7. Operand crossing offset 0 or 65,535.

On the 8086 processor, an attempt to access a memory operand which crosses offset 65,535 (e.g., MOV a word to offset 65,535) or offset 0 (e.g., PUSH a word when the contents of the SP register are 1) causes the offset to wrap around modulo 65,536. The Pentium processor generates an exception in these cases, a general-protection exception if the segment is a data segment (i.e., if the CS, DS, ES, FS, or GS register is being used to address the segment), or a stack exception if the segment is a stack segment (i.e., if the SS register is being used).

8. Sequential execution across offset 65,535.

On the 8086 processor, if sequential execution of instructions proceeds past offset 65,535, the processor fetches the next instruction byte from offset 0 of the same segment. On the Pentium processor, the processor generates a general-protection exception.

9. LOCK is restricted to certain instructions.

The LOCK prefix and its output signal should only be used to prevent other bus masters from interrupting a data movement operation. The LOCK prefix only may be used with the following Pentium processor instructions when they modify memory. An invalid-opcode exception results from using LOCK before any other instruction, or with these instructions when no write operation is made to memory.

- Bit test and change: the BTS, BTR, and BTC instructions.
- Exchange: the XCHG, XADD, CMPXCHG, and CMPXCH8B instructions (no LOCK prefix is needed for the XCHG instruction).
- One-operand arithmetic and logical: the INC, DEC, NOT, NEG instructions
- Two-operand arithmetic and logical: the ADD, ADC, SUB, SBB, AND, OR, and XOR instructions.

10. Single-stepping external interrupt handlers.

The priority of the Pentium processor single-step exception is different from that of the 8086 processor. This change prevents an external interrupt handler from being single-stepped if the interrupt occurs while a program is being single-stepped. The Pentium processor single-step exception has higher priority than any external interrupt. The Pentium processor will still single-step through an interrupt handler called by the INT instruction or by an exception.

11. IDIV exceptions for quotients of 80H or 8000H.

The Pentium processor can generate the largest negative number as a quotient from the IDIV instruction. The 8086 processor generates a divide-error exception instead.

12. Flags in stack.

The contents of the EFLAGS register stored by the PUSHF instruction, by interrupts, and by exceptions is different from that stored by the 8086 processor in bit positions 12 through 15. On the 8086 processor these bits are stored as though they were set, but in virtual-8086 mode bit 15 is always clear, and bits 14 through 12 have the last value loaded into them.

13. NMI interrupting NMI handlers.

After an NMI interrupt is accepted by the Pentium processor, the NMI interrupt is masked until an IRET instruction is executed.

14. Floating-point errors call the floating-point error exception.

Floating-point exceptions on the Pentium processor call the floating-point error exception handler. If an 8086 processor uses another exception for the 8087 interrupt, both exception vectors should call the floating-point error exception handler. The Pentium processor has signals which, with the addition of external logic, support user-defined error reporting for emulation of the interrupt mechanism used in many personal computers.

15. Numeric exception handlers should allow prefixes.

On the Pentium processor, the value of the CS and IP registers saved for floating-point exceptions points at any prefixes which come before the ESC instruction. On the 8086 processor, the saved CS:IP points to the ESC instruction.

16. Floating-Point Unit does not use interrupt controller.

The floating-point error signal to the Pentium processor does not pass through an interrupt controller (an INT signal from 8087 coprocessor does). Some instructions in a coprocessor-error exception handler may need to be deleted if they use the interrupt controller. The Pentium processor has signals which, with the addition of external logic, support user-defined error reporting for emulation of the interrupt mechanism used in many personal computers.

17. Response to bus hold.

Unlike the 8086 and Intel 286 processors, the Pentium processor responds to requests for control of the bus from other potential bus masters, such as DMA controllers, between transfers of parts of an unaligned operand, such as two words which form a doubleword.

18. CPL is 3 in virtual-8086 mode.

The 8086 processor does not support protection, so it has no CPL. Virtual-8086 mode uses a CPL of 3, which prevents the execution of privileged instructions. These are:

- LIDT instruction
- LGDT instruction
- LMSW instruction
- Special forms of the MOV instruction for loading and storing the control registers
- CLTS instruction
- HLT instruction
- INVD instruction
- WBINVD instruction
- INVLPG instruction
- RDMSR instruction
- WRMSR instruction



— RSM instruction

These instructions may be executed while the processor is in real-address mode following reset initialization. They allow system data structures, such as descriptor tables, to be set up before entering protected mode. Since virtual-8086 mode is entered from protected mode, these structures will already be set up.

19. Denormal exception handling is different. See Chapter 23 for details on exception handling differences.

## 22.9. DIFFERENCES FROM INTEL 286 CPU

The differences between virtual-8086 mode and Intel 286 real-address mode affect the interface between applications and the operating system. The application runs at privilege level 3 (user mode), so all attempts to use privilege-protected instructions and architectural features generate calls to the virtual-machine monitor. The monitor examines these calls and emulates them.

### 22.9.1. Privilege Level

Programs running in virtual-8086 mode have a privilege level of 3 (user mode), which prevents the execution of privileged instructions. These are:

- LIDT instruction
- LGDT instruction
- LMSW instruction
- Special forms of the MOV instruction for loading and storing the control and debug registers
- CLTS instruction
- HLT instruction
- INVD instruction
- WBINVD instruction
- INVLPG instruction
- RDMSR instruction
- WRMSR instruction
- RSM instruction

Virtual-8086 mode is entered from protected mode, so it should have no need for these instructions. These instructions, while not executable in virtual-8086 mode, can be executed in real-address mode.

## 22.9.2. Bus Lock

The Intel 286 processor implements the bus lock function differently than the Intel386, Intel486, and Pentium processors. This fact may or may not be apparent to 8086 programs, depending on how the virtual-8086 monitor handles the LOCK prefix. Instructions with the LOCK prefix are sensitive to the IOPL; software designers can choose to emulate its function. If, however, 8086 programs are allowed to execute LOCK directly, programs which use forms of memory locking specific to the 8086 processor may not run properly when run on the Pentium and other 32-bit processors.

The LOCK prefix and its bus signal only should be used to prevent other bus masters from interrupting a data movement operation. The LOCK prefix only may be used with the following Pentium CPU instructions when they modify memory. An invalid-opcode exception results from using the LOCK prefix before any other instruction, or with these instructions when no write operation is made to memory (i.e., when the destination operand is in a register).

- Bit test and change: the BTS, BTR, and BTC instructions.
- Exchange: the XCHG, XADD, and CMPXCHG instructions (no LOCK prefix is needed for the XCHG instruction).
- One-operand arithmetic and logical: the INC, DEC, NOT, NEG instructions.
- Two-operand arithmetic and logical: the ADD, ADC, SUB, SBB, AND, OR, and XOR instructions.

A locked instruction is guaranteed to lock only the area of memory defined by the destination operand, but may lock a larger memory area. For example, typical 8086 and Intel 286 configurations lock the entire physical memory space.

Unlike the 8086 and Intel 286 processors, the Intel386, Intel486 and Pentium processors respond to requests for control of the bus from other potential bus masters, such as DMA controllers, between transfers of parts of an unaligned operand, such as two words which form a doubleword.

## 22.10. DIFFERENCES FROM Intel386™ AND Intel486™ CPUs

Real-address mode behavior is the same on the Intel386, Intel486, and Pentium processors. When the virtual mode extensions are disabled (VME bit in CR4 is set to zero), the virtual-8086 mode behavior of the Pentium processor is the same as on the Intel386 and Intel486 processors. By enabling the virtual mode extensions (VME bit in CR4 is set to one), however, the virtual-8086 mode performance of the Pentium processor is significantly improved. See Appendix H for obtaining information on these extensions. For maximum performance, programs ported to the Pentium processor should be run with the cache enabled.



**intel**<sup>®</sup>

**23**

# **Compatibility**





## CHAPTER 23 COMPATIBILITY

The Pentium processor is fully binary compatible with the Intel486 DX and SX CPU's, the Intel386 DX and SX CPU's, the Intel 286 CPU and the 8086/8088 CPU's. Compatibility means that, within certain limited constraints, programs that execute on any previous generations of compatible microprocessors will produce identical results when executed on the Pentium processor. There are, however, slightly different implementations of architectural features. These limitations and any implementation differences are listed in this chapter.

The Pentium processor also includes extensions to the registers, instruction set, and control functions of the Intel486 architecture just as the Intel486 CPU included extensions to the Intel386 CPU. Those extensions have been defined with consideration for compatibility with previous and future microprocessors. This section also summarizes the compatibility considerations for those extensions.

### 23.1. RESERVED BITS

Throughout this manual, certain bits are marked as reserved in many register and memory layout descriptions. When bits are marked as undefined or reserved, it is essential for compatibility with future processors that software treat these bits as having a future, though unknown effect. Software should follow these guidelines in dealing with reserved bits:

- Do not depend on the states of any reserved bits when testing the values of registers or memory locations which contain such bits. Mask out the reserved bits before testing.
- Do not depend on the states of any reserved bits when storing to memory or to a register.
- Do not depend on the ability to retain information written into any reserved bits.
- When loading a register, always load the reserved bits with the values indicated in the documentation, if any, or reload them with values previously stored from the same register.

Depending on the values of reserved register bits will make software dependent upon the unspecified manner in which the Pentium processor handles these bits. Depending upon reserved values risks incompatibility with future processors. **AVOID ANY SOFTWARE DEPENDENCE UPON THE STATE OF RESERVED PENTIUM PROCESSOR REGISTER BITS.**

Software written for an Intel386 or Intel486 CPU which uses reserved bits correctly will port to the Pentium processor without generating general exceptions.

## 23.2. INTEGER UNIT

This section identifies the new features and the implementation differences of existing features in the integer unit, which includes added registers and flags, exception handling, memory management and protected-mode features.

### 23.2.1. New Functions and Modes

New control functions defined for the Pentium processor are enabled by mode bits in newly defined registers, discussed below, that were not present in the Intel486 architecture. The instructions that are executed to read and write these new registers are undefined on the Intel486 processor, and an invalid opcode exception occurs when an attempt is made to execute one of these instructions on the Intel486 processor. Consequently, programs that execute correctly on the Intel486 processor cannot erroneously enable these functions. However, when an instruction is executed to write one of the new registers and an attempt is made to set a reserved bit to a value other than the original value, then a general protection exception occurs on the Pentium processor so programs that execute on the Pentium processor cannot erroneously enable functions that may be implemented in future processors. The Pentium processor does not check for attempts to set reserved bits in model-specific registers. It is the obligation of the software writer to enforce this discipline. These reserved bits may be used in future Intel processors.

### 23.2.2. Serializing Instructions

Certain instructions have been defined to serialize instruction execution to ensure that modifications to flags, registers and memory are completed before the next instruction is fetched and executed. Because the Pentium processor uses branch-prediction techniques to improve performance, instruction execution is not generally serialized when a branch instruction is executed. As a result, branch instructions do not necessarily flush the prefetch queue on the Pentium processor and serializing instructions should replace branch instructions used for this purpose. Refer to Chapter 18 and the *Pentium® Processor Family Developer's Manual*, Volume 1 for more information on serializing instructions and for more information on branch prediction.

### 23.2.3. Detecting the Presence of New Features

As the Pentium processor provides extensions to the architecture of the Intel486 processor, other models within the processor family have provided both extensions to previous models and features specific to that model (such as testability functions). Consequently, software that wishes to use the extensions or specific features must identify on which model it is executing to determine what features are available. Programmers have developed code sequences that can be executed to distinguish between the 8086, Intel 286, Intel386, and Intel486 microprocessors. The code sequences commonly test which bits in the processor's FLAGS register are implemented. (For an example see Chapter 5.) The CPUID instruction has been

defined to provide a straightforward way for software to identify what family, model and stepping of processor it is running on. This can be accomplished as follows:

1. One of the code sequences described in Chapter 5 can be executed to determine that the software is executing on an Intel486 CPU or a later model that implements a superset of the Intel486 architecture. (This is typically done by testing the ability to change the value of the AC flag.)
2. Having determined that the processor is "at least" an Intel486 processor, a software sequence can test whether it is able to change the value of the ID bit. If software is able to change the value of the ID bit, then the processor supports the CPUID instruction.
3. The sequence can then continue by executing the CPUID instruction. In order to use a particular architecture extension, software should check that the appropriate feature bit returned by this instruction is set. Refer to this instruction in Chapter 25 for more information about its operation.

#### **23.2.4. Undefined Opcodes**

All new instructions defined for the Pentium processor use binary encodings for which the invalid opcode exception occurs when an attempt is made to execute these instructions on the Intel486 processor. Consequently, programs that execute correctly on the Intel486 processor cannot erroneously execute these instructions and thereby produce unexpected results.

#### **23.2.5. Clock Counts**

Each processor takes fewer clocks for most instructions than earlier processors. The areas most likely to be affected include:

- Delays required by I/O devices between I/O operations.
- Assumed delays with 8086 processor operating in parallel with an 8087.

#### **23.2.6. Initialization and Reset**

This section identifies the state of the integer and floating-point units for the various microprocessors and numeric processor extensions.

##### **23.2.6.1. INTEGER UNIT INITIALIZATION AND RESET**

Table 23-1 identifies the values of the integer unit registers following hardware reset for the 32-bit Intel architecture. These values are the same regardless of whether the Built-In Self Test (BIST) is invoked.

### **23.2.6.2. FPU/NPX INITIALIZATION AND RESET**

The Pentium processor, following RESET, contain 0 in ST0-ST7 stack registers (See Table 23-2) with the tags set to valid (10) (but visible to the programmer as 01 via FSAVE/FSTENV). The Pentium processor, in addition, has an INIT pin which, when asserted, causes the processor to reset without altering the FPU state. The state of the Intel486 processor FPU is left unchanged when the Built-In Self Test (BIST) is not requested during RESET.



**Table 23-1. Processor State Following Power-Up**

Register	Pentium® Processor	Intel486™ CPU	Intel386™ CPU
EFLAGS <sup>1</sup>	00000002H	00000002H	FFFC802AH
EIP	0000FFF0H	0000FFF0H	0000FFF0H
CR0	60000010H	60000010H	7FFFFFFE0H
CR2	00000000H	00000000H	00000000H
CR3	00000000H	00000000H	00000000H
CR4	00000000H	00000000H	00000000H
CS	0F000H base=0FFFF000H limit=0FFFFH AR=00000093H	0F000H base=0FFFF000H limit=0FFFFH AR=0FF3F93FFH	0F000F000H base=0FFFF000H limit=0FFFFH AR=0FF3F93FFH
SS, DS, ES, FS, GS	0000 base=00000000H limit=0FFFFH AR=00000093H	0000 base=00000000H limit=0FFFFH AR=0FF3F93FFH	0000 base=00000000H limit=0FFFFH AR=0FF3F93FFH
EDX	0000x5xxH	0000x4xxH	00000308H
EAX	0 <sup>2</sup>	0 <sup>2</sup>	0 <sup>2</sup>
EBX, ECX, ESI, EDI, EBP, ESP	00000000H	00000000H	00000000H
GDTR,LDTR	00000000 base=00000000H limit=0FFFFH AR=00000082H	xxxx0000 base=00000000H limit=0FFFFH AR=0FFFFFFFHH	00000000 base=00000000H limit=0FFFFH AR=0FFFFFFFHH
IDTR	00000000 base=00000000H limit=0FFFFH AR=00000082H	xxxx0000 base=00000000H limit=0FFFFH AR=0FFFFFFFHH	00000000 base=00000000H limit=0FFFFH AR=0FFFFFFFHH
DR0, DR1, DR2, DR3	00000000H	00000000H	00000000H
DR6	FFFF0FF0H	FFFF1FF0H	FFFF1FF0H
DR7	00000400H	00000000H	00000000H
Time Stamp Counter	0	NA <sup>3</sup>	NA
Control and Event Select	0	NA	NA
TR12	0	NA	NA
All Other MSR's	Undefined	NA	NA
Data and Code Cache	Invalid	Invalid	NA
TLB(s)	Invalid	Invalid	NA

**NOTES:**

1. The high ten (14 for the Intel486 and Intel386 CPU's) bits of the EFLAGS register are undefined following power-up. Undefined bits are reserved. Software should not depend on the states of any of these bits.
2. If Built-In Self Test is invoked, EAX is 0 only if all tests passed.
3. Not Applicable.

Upon hardware RESET on a system with an Intel386 CPU and an Intel387 math coprocessor, the floating-point registers will remain unchanged unless the BIST is requested. When the BIST is requested, hardware RESET has almost the same effect as the FINIT instruction; the only difference is that FINIT leaves the stack registers unchanged, while hardware RESET with BIST resets them to 0. This could show up as a difference in the value of the tag word observed after the FSAVE/FSTENV instructions are executed. The FINIT instruction clears both the data and instruction error pointers.

Following an Intel386 processor reset, the processor identifies the type of its coprocessor (Intel287 or Intel387 DX math coprocessor) by sampling its ERROR# input some time after the falling edge of RESET and before execution of the first ESC instruction. The Intel287 coprocessor keeps its ERROR# output in inactive state after hardware reset; the Intel387 coprocessor keeps its ERROR# output in active state after hardware reset. Upon hardware RESET or FINIT, the Intel387 math coprocessor signals an error condition. The Pentium and Intel486 processors, like the Intel287 coprocessor, do not. Table 23-2 provides a summary of the differences between the Intel386, Intel486, and Pentium processors FPU's following power-up.

**Table 23-2. FPU and NPX State Following Power-Up**

Register	Pentium® Processor FPU	Intel486™ Processor FPU	Intel387™ CoProcessor NPX
Control Word	0040H	037FHH	037FH
Status Word	0000H	0000H	0000H
Tag Word	5555H	0FFFFH	0FFFFH
IP Offset	00000000H	00000000H	00000000H
Data Operand Offset	00000000H	00000000H	00000000H
CS Selector	0000H	0000H	0000H
Operand Selector	0000H	0000H	0000H
FSTACK	All zeroes	All zeroes	All zeroes

**NOTES:**

The state of the FPU is left unchanged on the Pentium processor following INIT. The state of the FPU is left unchanged on the Intel486 processor FPU following RESET w/o BIST.

### 23.2.6.3. Intel486 SX MICROPROCESSOR AND Intel487™ SX MATH COPROCESSOR INITIALIZATION

This interface is designed for two distinct sockets: one for the Intel486 SX CPU and one for end-user/dealer upgrade with Intel487 SX math coprocessor. Refer to the *Intel486™ SX Microprocessor/Intel487™ SX Math CoProcessor Data Book* for more details. The following should be considered when designing an Intel486 SX CPU/Intel487 SX math coprocessor system.

1. The timing loops should be independent of clock speed and clocks per instruction. One way to attain this is to implement these loops in hardware and not in software (e.g., BIOS).
2. The initialization routine should check the presence of a math coprocessor (e.g., Intel487 SX math coprocessor) and should set the floating-point related bits in the CR0 register accordingly (see Chapter 10 for a complete description of these bits). The recommended bit pattern is given in Table 23-3. The FSTCW instruction will give a value of FFFh for the Intel486 SX microprocessor and 037Fh for the Intel487 SX math coprocessor.

**Table 23-3. Recommended Values of the FP Related Bits for Intel486™ SX Microprocessor/Intel487™ SX Math CoProcessor System**

CR0 Bit	Intel486™ SX Microprocessor	Intel487™ SX Math CoProcessor
EM	1	0
MP	0	1
NE	1	0, for DOS systems 1, for user-defined exception handler

Following is an example code sequence to initialize the system and check for the presence of Intel486 SX microprocessor/Intel487 SX math coprocessor. Refer to Chapter 5 for complete CPU and coprocessor identification information.

```
fninit
fstcw mem_loc
mov ax, mem_loc
cmp ax, 037fh
jz Intel487_SX_Math_CoProcessor_present ;ax=037fh
jmp Intel486_SX_microprocessor_present ;ax=ffffh
```

If the Intel487 SX math coprocessor is not present, the following code can be run to set the CR0 register for the Intel486 SX microprocessor.

```
mov eax, cr0
and eax, ffffffffh ;make MP=0
or eax, 0024h ;make EM=1, NE=1
mov cr0, eax
```

The above initialization will cause any floating-point instruction to generate the interrupt 7. The software emulation will then take control to execute these instructions. This code is not

required if an Intel487 SX math coprocessor is present in the system, thereupon the typical initialization routine for the Intel486 SX microprocessor will be adequate.

The interpretation of different combinations of the EM and MP bits is shown in Table 23-4.

**Table 23-4. EM and MP Bits Interpretations**

EM	MP	Interpretation
0	0	Numeric instructions are passed to FPU; WAIT ignores TS
0	1	Numeric instructions are passed to FPU; WAIT tests TS
1	0	Numeric instructions trap to emulator; WAIT ignores TS
1	1	Numeric instructions trap to emulator, WAIT tests TS

## 23.2.7. New Instructions

This section identifies the introduction of new instructions for the 32-bit microprocessors.

### 23.2.7.1. NEW PENTIUM PROCESSOR INSTRUCTIONS

The Pentium processor introduces three new application instructions:

- CMPXCHG8B instruction
- CPUID instruction
- RDTSC instruction — For more information on RDTSC, see Chapter 25 of this document.

There are four new system instructions, used for reading from and writing to the new control register (CR4) and model specific registers, and resuming from system management mode:

- MOV CR4, r32 and MOV r32, CR4
- RDMSR
- WRMSR
- RSM

The form of the MOV instruction used to access the test registers has been removed on the Pentium processor. New test registers have been defined for the cache, the TLB's and the BTB which are accessed through the model-specific registers on the Pentium processor. For more information on the test registers used with the RDMSR and WRMSR instructions, see Chapter 25 of this document.

### 23.2.7.2. NEW Intel486 PROCESSOR INSTRUCTIONS

The Intel486 CPU introduced three new application instructions:

- BSWAP instruction
- XADD instruction
- CMPXCHG instruction

Three new system instructions, used for managing the cache and TLB, were introduced:

- INVD instruction
- WBINVD instruction
- INVLPG instruction

### 23.2.7.3. NEW Intel386 PROCESSOR INSTRUCTIONS

New instructions introduced on the Intel386 processor include:

- LSS, LFS, LGS instructions
- Long-displacement conditional jumps
- Single-bit instructions
- Bit scan instructions
- Double-shift instructions
- Byte set on condition instruction
- Move with sign/zero extension
- Generalized multiply instruction
- MOV to and from control registers
- MOV to and from test registers (now obsolete)
- MOV to and from debug registers

### 23.2.8. Obsolete Instructions

The following instructions no longer supported include:

- MOV to and from test registers (removed from the Pentium processor)

Execution of these instructions generates an invalid opcode fault.

### 23.2.9. Flags

This section discusses the flag bits additions to the EFLAGS register as shown in Figure 23-1.



### 23.2.10. Control Registers

This section identifies the addition of new control registers and control register bits in the 32-bit Intel architecture. See Figure 23-2 for extensions to the control registers for the Intel486 and Pentium processors. These extensions are discussed further in the following subsections.

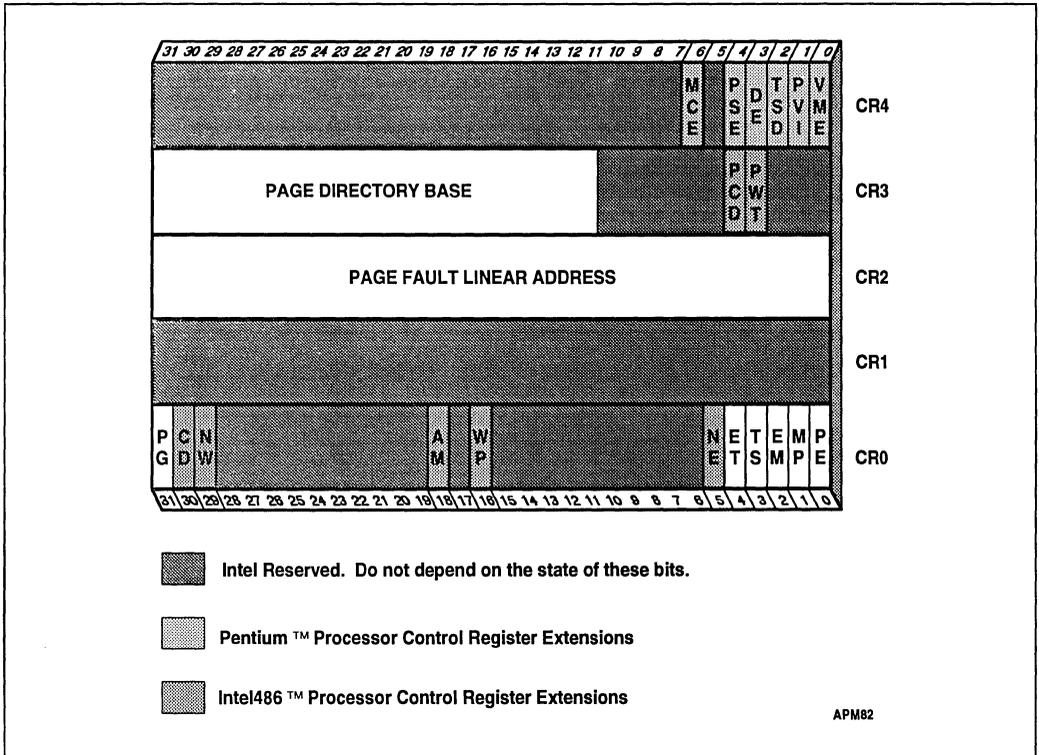


Figure 23-2. Control Register Extensions

#### 23.2.10.1. PENTIUM® PROCESSOR CONTROL REGISTERS

The recommended values for the CD and NW bits in CR0 (00) implements a writeback strategy for the data cache of the Pentium processor. On the Intel486 processor, these values implement a writethrough strategy. See Table 23-5 for a comparison of these bits on the Intel486 and Pentium processors. For complete information on caching, refer to Chapter 18.

One new Control Register (CR4) is defined. CR4 contains bits that enable certain extensions to the Intel486 architecture provided in the Pentium processor. These include:

- VME — For more information, see Appendix H.
- PVI — For more information, see Appendix H.
- TSD — For more information, see Appendix H.
- DE — While this bit is 1, Debugging Extensions are enabled, providing support for I/O breakpoints. Refer to Chapter 17 for more information.
- PSE — For more information, see Appendix H.
- MCE — While this bit is 1, Machine Check Exceptions are enabled, allowing exception handling for certain hardware error conditions. Refer to the *Pentium® Processor Data Book* for more information.

The content of CR4 is zero following reset.

### 23.2.10.2. Intel486™ PROCESSOR CONTROL REGISTERS

Five new bits are defined in the CR0 register for the Intel486 processor:

- NE — The Numeric Error bit enables the standard mechanism for reporting floating-point numeric errors.
- WP — The Write Protect bit write-protects pages against supervisor-mode accesses.
- AM — The Alignment Mask bit, in conjunction with the AC (Alignment Check) flag, controls whether alignment checking is performed.
- NW — The Not Writethrough bit enables writethroughs and cache invalidation cycles when clear and disables invalidation cycles and writethroughs which hit in the cache when set.
- CD — The Cache Disable bit enables the internal cache when clear and disables the cache when set.

Two new bits have been defined in the CR3 register:

- PCD — The state of the Page-Level Cache Disable bit is driven on the PCD pin during bus cycles which are not paged, such as interrupt acknowledge cycles, when paging is enabled. The PCD pin is used to control caching in an external cache on a cycle-by-cycle basis.



**Table 23-5. Cache Mode Differences Between the Pentium® and Intel486™ Processors**

CD	NW	Pentium® Processor Description	Intel486™ CPU Description
0	0	<p><b>Normal highest performance cache operation.</b>  Read hits access the cache.  Read misses may cause replacements.  These lines will enter the Exclusive or Shared state under the control of the WB/WT# pin.  Write hits update the cache.  Only writes to shared lines and write misses appear externally  Writes to Shared lines can be changed to the Exclusive State under the control of the WB/WT# pin.  Invalidations are allowed.</p>	<p><b>Normal highest performance cache operation</b>  Read hits access the cache.  Read misses may cause replacements.    Write hits update the cache.  All writes appear externally.    Invalidations are allowed.</p>
0	1	<p><b>Invalid Operation</b>  GP(0)</p>	<p><b>Invalid Operation</b>  GP(0)</p>
1	0	<p><b>Cache disabled. Memory consistency maintained. Contents locked in cache.</b>  Read hits access the cache.    Read misses do not cause replacement.  Write hits update the cache.  Only writes to Shared lines and write misses update external memory  Writes to Shared lines can be changed to the Exclusive State under the control of the WB/WT# pin.  Invalidations are allowed.</p>	<p><b>Cache disabled. Memory consistency maintained. Contents locked in cache.</b>  Read hits access the cache.  Read misses do not cause replacement.  Write hits update the cache.  All writes update external memory    Invalidations are allowed.</p>
1	1	<p><b>Cache disabled. Memory consistency not maintained.</b>  Read hits access the cache.  Read misses do not cause replacement.  Write hits update the cache, but do not access memory.  Write hits will cause Exclusive State lines to change to Modified State  Shared lines will remain in the Shared state after write hits.  Write misses access memory.  Inquire and Invalidation Cycles do not effect the cache state or contents.  This is the state after reset.</p>	<p><b>Cache disabled. Memory consistency not maintained.</b>  Read hits access the cache.  Read misses do not cause replacement.  Write hits update the cache, but do not access memory.    Write misses access memory.  Inquire and Invalidation Cycles do not effect the cache state or contents.  This is the state after reset.</p>

- PWT — The state of the Page-Level Writethrough bit is driven on the PWT pin during bus cycles which are not paged, such as interrupt acknowledge cycles, when paging is enabled. The PWT pin is used to control writethrough in an external cache on a cycle-by-cycle basis.

### 23.2.11. Debug Registers

The Pentium processor includes extensions to the Intel486 processor debugging support for breakpoints on I/O references. To use the new breakpoint features, it is necessary to set CR4.DE to 1.

#### 23.2.11.1. DIFFERENCES IN DR6

It is not possible to write a 1 to reserved bit 12 in DR6 on the Pentium processor. However, on the Intel486 processor, it is possible to write a 1 in bit position 12.

See "Initialization Values" in this chapter for differences of this register at processor reset.

#### 23.2.11.2. DIFFERENCES IN DR7

The Pentium processor determines the type of breakpoint access by the bits R/W0 to R/W3 in DR7 as follows:

- 00 Break on instruction execution only
- 01 Break on data writes only
- 10 Undefined if CR4.DE=0, break on I/O reads or writes but not instruction fetches if CR4.DE=1
- 11 Break on data reads or writes but not instruction fetches

On the Pentium processor, reserved bits 11, 12, 14 and 15 are hard-wired to 0. On the Intel486 CPU, however, bit 12 can be set.

See "Initialization Values" above for differences of this register at processor reset.

#### 23.2.11.3. DEBUG REGISTERS 4 AND 5

Although the DR4 and DR5 registers have been documented as "Reserved," previous generations of processors aliased references to these registers to Debug Registers 6 and 7, respectively. When Debug Extensions are not enabled (CR4.DE=0), the Pentium processor remains compatible with existing software by allowing these aliased references. However, when Debug Extensions are enabled (CR4.DE=1), attempts to reference DR4 or DR5 will result in an invalid opcode exception.



### 23.2.12. Test Registers

The implementation of test registers on the Intel486 CPU used for testing the cache and TLB has been redesigned using model specific registers (discussed below) on the Pentium processor. The MOV to and from test register instructions generate invalid opcode exceptions on the Pentium processor. For more information on the use of the test registers, see *Pentium® Processor Developer's Manual*, Volume 1, Chapter 33.

### 23.2.13. Model Specific Registers

Certain features of the Pentium processor that are described in the *Pentium® Processor Developer's Manual*, Volume 1 are specific to the Pentium processor and may not be continued in the same way in future processors. Examples are functions for testability, performance monitoring, and machine check errors. These features are accessed through Model Specific Registers. The new instructions RDMSR and WRMSR are used to read and write these registers. In order to use such model-specific features, software should check that the "Family" number reported by the CPUID instruction is equal to 5. Software which uses these registers and functions may be incompatible with future processors. For more information, see *Pentium® Processor Developer's Manual*, Volume 1 Chapter 33.

### 23.2.14. Exceptions

This section identifies the introduction of new exceptions in the 32-bit microprocessor family and implementation differences in existing exception handling.

#### 23.2.14.1. NEW PENTIUM® PROCESSOR EXCEPTIONS

The Pentium processor includes the following extensions and conditions to the Intel486 architecture for exceptions and interrupts:

- Exception #13 — A General-Protection exception occurs when an attempt is made to write 1 to a reserved bit position of a special register.
- Exception #14 — A Page Fault exception occurs when a 1 is detected in any of the reserved bit positions of a page table entry, page directory entry, or page directory pointer during address translation by the Pentium processor.
- Exception #18 — A Machine Check Exception is newly defined for reporting parity errors and other hardware errors. This is a model-specific exception and may not be implemented the same in future processors. For compatibility reasons, the MCE bit in the CR4 register acts as the machine check enable bit. When this bit is clear (which it is at reset), the processor inhibits generation of the machine check abort. In the event that a system is using the machine check interrupt vector for another purpose and the MCE bit in CR4 is set, the interrupt routine must examine the state of the CHK bit in the model-specific Machine Check Type register to determine the cause of the interrupt.

See the *Pentium® Processor Developer's Manual*, Volume 1 for more information on the Machine Check Type register and model-specific registers.

See Chapter 14 for details on exceptions and interrupts.

#### **23.2.14.2. NEW Intel486™ PROCESSOR EXCEPTIONS**

The Intel486 processor includes the following extensions and conditions to the Intel486 architecture for exceptions and interrupts:

- Exception #17 — An Alignment Check exception reports unaligned memory references when alignment checking is being performed.

#### **23.2.14.3. NEW Intel386™ PROCESSOR EXCEPTIONS**

The Intel386 processor introduced new conditions which can occur even in systems designed for the Intel 286 processor.

- Exception #6 — The Invalid Opcode exception can result from improper use of the LOCK instruction prefix.
- Exception #14 — A Page Fault exception can occur in a 16-bit program if the operating system enables paging. Paging can be used in a system with 16-bit tasks if all tasks use the same page directory. Because there is no place in a 16-bit TSS to store the PDBR register, switching to a 16-bit task does not change the value of the PDBR register. Tasks ported from the Intel 286 processor should be given 32-bit TSSs so they can make full use of paging.
- Exception #13 — The Intel386 processor set a limit of 15 bytes on instruction length. The only way to violate this limit is by putting redundant prefixes before an instruction. A general-protection exception is generated if the limit on instruction length is violated. The 8086 processor has no instruction length limit.

#### **23.2.14.4. INTERRUPT PROPAGATION DELAY**

External hardware interrupts on the Pentium processor may be recognized on different instruction boundaries due to the pipe-lined execution of the Pentium processor and possibly an extra instruction passing through the v-pipe concurrently with an instruction in the u-pipe. When the two instructions complete execution, the interrupt is then serviced. Therefore, the EIP pushed onto the stack when servicing the interrupt on the Pentium processor may be different than that for the Intel486 processor (i.e., it is serviced later).

#### **23.2.14.5. PRIORITY OF EXCEPTIONS**

The priority of exceptions are broken down into several major categories:

- Traps on the previous instruction



- External interrupts
- Faults on fetching the next instruction
- Faults in decoding the next instruction
- Faults on executing an instruction

There are no changes in the priority of these major categories between the different processors, however, exceptions within these categories are implementation dependent and may change from processor to processor. See Table 14-2 in Chapter 14 of this document for more information.

#### **23.2.14.6. DIVIDE-ERROR EXCEPTIONS**

Divide-error exceptions on the Pentium, Intel486, and Intel386 processors always leave the saved CS:IP value pointing to the instruction which failed. On the 8086 processor, the CS:IP value points to the next instruction.

The Pentium, Intel486, and Intel386 processors can generate the largest negative number as a quotient for the IDIV instruction (80H and 8000H). The 8086 processor generates a divide-error exception instead.

#### **23.2.14.7. WRITES USING THE CS REGISTER PREFIX**

Following a switch from protected mode to real-address mode, the Intel486 processor requires the coding of a far jump control flow instruction prior to performing a write using the CS segment register prefix (for example: MOV CS:[0], EAX). The far jump in protected mode on the Intel486 processor reloads the CS access rights to be writable. If this requirement is not met, a general protection exception occurs. This requirement has been eliminated on the Pentium processor which leaves the access rights unchanged and ignores code segment access right protection checks in real-address mode. As a result, the code segment register can be used as a prefix in a write operation in real-address mode without generating an exception. For upwards and downwards compatibility, however, programmers may wish to include the far jump instruction prior to any writes to the code segment in real-address mode.

The code segment can not be written to in protected mode on either the Intel486 or Pentium processors.

#### **23.2.14.8. NMI INTERRUPTS**

After an NMI interrupt is recognized by the Intel 286, Intel386, Intel486 and Pentium processors, the NMI interrupt is masked until the first IRET instruction is executed, unlike the 8086 processor.

### **23.2.14.9. INTERRUPT VECTOR TABLE LIMIT**

The LIDT instruction can be used to set a limit on the size of the interrupt vector table. The double fault exception is generated if an interrupt or exception attempts to read a vector beyond the limit. Shutdown then occurs on the 32-bit Intel architecture processors if the double fault handler vector is beyond the limit. (The 8086 processor does not have a shutdown mode nor a limit.)

### **23.2.14.10. INTERRUPTS INSIDE SYSTEM MANAGEMENT MODE**

In the Pentium processor, entrance into System Management Mode (SMM) automatically resets the properties of the interrupt vector table to the Real mode, but does not reset the Interrupt Descriptor Table Register (IDTR) to the default Real mode table base address of zero. In the Intel386™ SL, Intel486 SL and SL Enhanced Intel486 processors, the IDTR is reset (to base address zero) upon entrance to SMM. An LIDT instruction may be used at the beginning of an SMM handler to allow the handler, if desired, to use the default Real mode interrupt vector table in either a Pentium processor or an earlier Intel SL processor.

## **23.2.15. Descriptor Types and Contents**

Operating-system code which manages space in descriptor tables often contains an invalid value in the access-rights field of descriptor-table entries to identify unused entries. Access rights values of 80H and 00H remain invalid for the Intel 286, Intel386, Intel486, and Pentium processors. Other values which were invalid on the Intel 286 processor may be valid on the 32-bit processors because uses for these bits have been defined.

## **23.2.16. Changes in Segment Descriptor Loads**

On the Intel386 processors, loading a segment descriptor always causes a locked read and write to set the accessed bit of the descriptor. On the Pentium and Intel486 processors, the locked read and write occur only if the bit is not already set.

## **23.2.17. Task Switching and Task State Segments**

This section identifies the implementation differences of task switching, additions to the task state segment and the handling of TSS's and TSS selectors.

### **23.2.17.1. PENTIUM PROCESSOR TASK STATE SEGMENTS**

The Pentium processor TSS may contain additional information used in virtual-8086 mode by the virtual mode extensions to the Pentium processor. For more information on virtual mode extensions, see Appendix H.



### **23.2.17.2. TSS SELECTOR WRITES**

During task state saves, the Intel486 CPU writes two-byte selectors into a 32-bit TSS, leaving the upper 16 bits undefined. For performance reasons, the Pentium processor writes four-byte selectors into the TSS with the upper two bytes being zero. For compatibility reasons, code should not depend on the value of the upper 16 bits of the selector in the TSS.

### **23.2.17.3. ORDER OF READS/WRITES TO THE TSS**

The order of reads and writes into the TSS is processor dependent. The Pentium processor may generate different page fault addresses (CR2) in the same TSS area than the Intel486 CPU, if a TSS crosses a page boundary (which is not recommended).

### **23.2.17.4. USING A 16-BIT TSS WITH 32-BIT CONSTRUCTS**

Task switches using 16-bit TSS's should be used only for pure 16-bit code. Any new code written using 32-bit constructs (operands, addressing, or the upper word of the EFLAGS register) should use only 32-bit TSSs. This is due to the fact that the 32-bit processors do not save the upper 16 bits of EFLAGS to a 16-bit TSS. A task switch back to a 16-bit task that was executing in virtual mode will never re-enable the virtual mode, as this bit was not saved in the upper half of the EFLAGS value in the TSS. Therefore, it is strongly recommended that any code using 32-bit constructs use a only a 32-bit TSS to ensure correct behavior in a multitasking environment.

#### **23.2.17.4.1. Differences in I/O Map Base Addresses**

The Intel486 processor considers the TSS segment to be a 16-bit segment and wraps around the 64K boundary. Any I/O accesses check for permission to access this I/O address at the I/O base address plus the I/O offset. If the I/O map base address exceeds the specified limit of 0DFFFH, an I/O access will wrap around and obtain the permission for the I/O address at an incorrect location within the TSS. A TSS limit violation does not occur in this situation on the Intel486 processor. However, the Pentium processor considers the TSS to be a 32-bit segment and a limit violation occurs when the I/O base address plus the I/O offset is greater than the TSS limit. By following the recommended specification for the I/O base address to be less than 0DFFFH, the Intel486 processor will not wrap around and access incorrect locations within the TSS for I/O port validation and the Pentium processor will not experience general protection faults. Figure 23-3 demonstrates the different areas accessed by the Intel486 and Pentium processors.

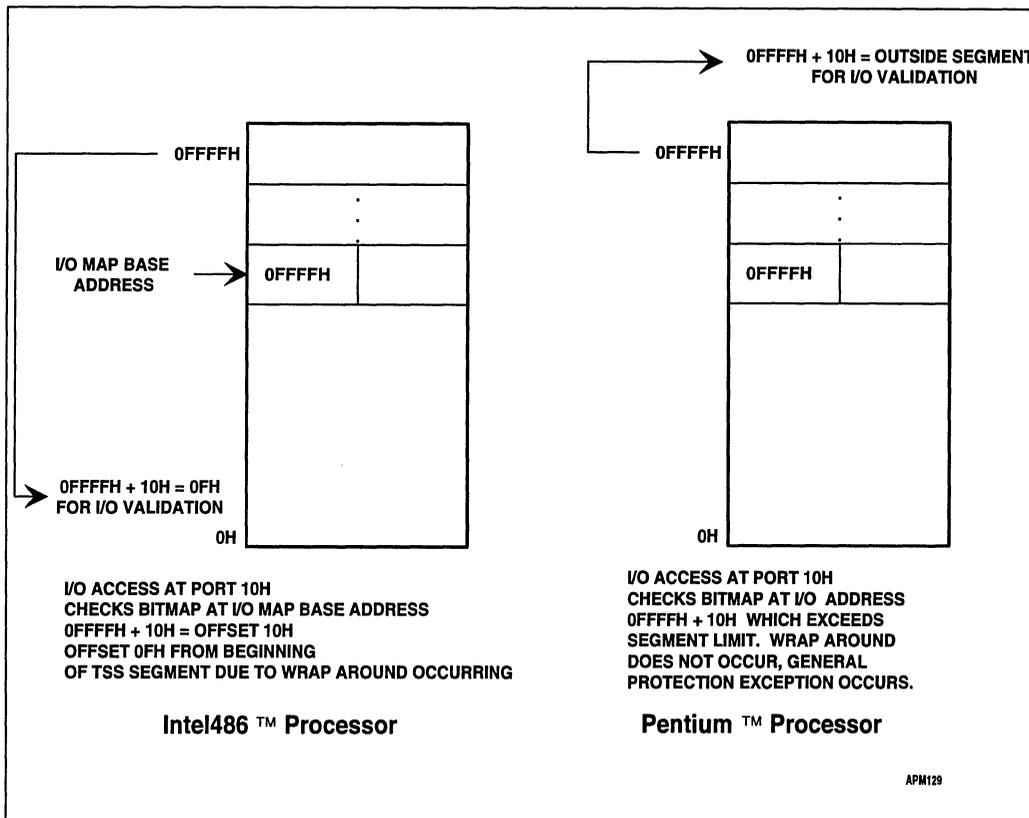


Figure 23-3. I/O Map Base Address Differences

### 23.2.17.4.2. Caching, Pipe-lining, Prefetching

The Pentium processor includes separate instruction and data caches. The data cache supports a writeback (or alternatively writethrough, on a line by line basis) policy for memory updates. Refer to Chapter 18 and the *Pentium® Processor Developer's Manual*, Volume 1 for more information about the organization and operation of the Pentium processor caches.

The Intel486 processor includes a single internal cache for both instructions and data.

The meaning of bits CD and NW in CR0 have been redefined so the recommended value (00) enables writeback for the data cache of the Pentium processor. In the Intel486 processor the same value for these bits enables writethrough for the cache. However, it is possible for external system hardware to force the Pentium processor to disable caching or to use writethrough policy should that be required. Refer to Chapter 18 and the *Pentium® Processor Developer's Manual*, Volume 1 for more information about hardware control of the Pentium processor caches.

The Pentium processor supports page-level cache management in the same manner as the Intel486 processor by using the PCD and PWT bits in CR3, page directory pointers, page directory entries, and page table entries. The Intel486 processor, however, is not affected by the state of the PWT bit since the internal cache of the Intel486 processor is a writethrough cache.

#### **23.2.17.5. SELF MODIFYING CODE WITH CACHE ENABLED**

Previous versions of Intel processors maintained compatibility on sequences of self modifying code that include a jump instruction immediately after any write that modifies an instruction. The Pentium processor maintains this compatibility. See section 18.2.3 for further clarification.

Historically the purpose of the jump has been to flush old versions of the instructions that have already been fetched into the prefetch buffer. Because the Pentium processor employs branch prediction, its prefetch queues are not necessarily flushed. In order to support self modifying code the Pentium processor includes a mechanism to compare the address of a write instruction to the addresses of instructions that have been prefetched.

Because the linear address of the write is checked against the linear address of the instructions that have been prefetched, special care must be taken for self-modifying code to work correctly when the physical addresses of the instruction and the written data are the same, but the linear addresses differ. In such cases, it is necessary to execute a serializing operation to flush the prefetch queue after the write and before executing the modified instruction. See Chapter 18 for more information on serializing instructions. Because of the requirement for writing compatible self modifying code across generations of processors, both sets of constraints need to be complied—specifically that a jump is required and that either there is no aliasings or that a serializing instruction is executed.

#### **NOTE**

The check on linear addresses described above is not in practice a concern for compatibility. Applications that include self-modifying code use the same linear address for modifying and fetching the instruction. Systems software, such as a debugger, that might possibly modify an instruction using a different linear address than that used to fetch the instruction must execute a serializing operation, such as IRET, before the modified instruction is executed.

For compatibility across Intel processors it is necessary to use the jump and observe the precaution described above.

### **23.2.18. Paging**

This section identifies enhancements made to the paging unit and implementation differences in the paging mechanism.

### 23.2.18.1. PENTIUM® PROCESSOR PAGING

The Pentium processor provides an extension to the memory management/paging functions of the Intel486 CPU to support larger page sizes. See Appendix H for more information.

### 23.2.18.2. Intel486™ PROCESSOR PAGING

Two bits introduced in the Intel486 processor have been defined in page table entries for controlling caching of pages:

- PCD — The Page-Level Cache Disable bit controls caching on a page-by-page basis.
- PWT — The Page-Level Writethrough bit controls the use of a writethrough of or writeback policy on a page-by-page basis. Since the internal cache of the Intel486 processor is a writethrough cache, it is not affected by the state of the PWT bit.

### 23.2.18.3. ENABLING AND DISABLING PAGING

Paging is enabled and disabled by a MOV CR0, REG instruction that modifies the PG bit. The Intel386 CPU family, the Intel486 CPU family, and the Pentium processor have slightly different requirements on the following code used to enable and disable paging:

1. MOV CR0, REG followed immediately by a short JMP instruction.
2. Identity map the entire sequence bounded by the MOV and JMP instructions.

The Intel386 CPU family require steps 1 *or* 2 be performed. The Pentium processor and Intel486 CPU family require that both steps 1 *and* 2 be performed. The instructions modifying the PG bit should be followed immediately by a JMP instruction and those instructions should reside on a page whose linear and physical addresses are identical.

## 23.2.19. Stack Operations

This section identifies the differences in stack implementation between the various microprocessors.

### 23.2.19.1. PUSH SP

The Pentium processor, Intel486, Intel386, and Intel 286 processors push a different value on the stack for a PUSH SP instruction than the 8086 processor. The 32-bit processors push the value of the SP register before it is decremented as part of the push operation; the 8086 processor pushes the value of the SP register after it is decremented. If the value pushed is important, replace PUSH SP instructions with the following three instructions:

```
PUSH BP
MOV BP, SP
XCHG BP, [BP]
```



This code functions as the 8086 processor PUSH SP instruction on the Pentium processor.

### 23.2.19.2. FLAGS PUSHED ON THE STACK

The setting of the flags stored by the PUSHF instruction, by interrupts, and by exceptions is different on the 32-bit processors than that stored by the 8086 and Intel 286 processors in bits 12 and 13 (IOPL), 14 (NT), and 15 (reserved). The differences are as follows:

- 8086 processor — bits 12 through 15 are always set.
- Intel 286 processor — bits 12 through 15 are always clear in real-address mode.
- 32-bit processors in real-address mode, bit 15 is always clear, and bits 14 through 12 have the last value loaded into them.

Other bits that can be used to differentiate between the 32 bit processors include:

- Bit 18 (AC) can be used to distinguish an Intel386 processor from the Intel486 and Pentium processors. Since it is not implemented on the Intel386 processor, it will always be clear.
- Bit 21 (ID) can be used to determine if an application can execute the CPUID instruction. This instruction supplies information to applications at run time that identifies the family, model, stepping, vendor and what features are implemented on the processor in a system. The ability to set and clear this bit indicates that the CPUID is supported on a processor.
- Bits 19 and 20 will always be zero on processors that do not support virtual mode extensions. For more information on virtual mode extensions, see Appendix H.

These differences can be used to distinguish what type of processor is present and are used in the CPU identification code example in Chapter 5.

### 23.2.19.3. SELECTOR PUSHES/POPS

On selector pushes, the Intel486 CPU writes 2 bytes onto 4-byte stacks and decrements ESP by 4. The Pentium processor writes 4 bytes with the upper 2 bytes being zeros.

On selector pops, the Intel486 CPU reads only 2 bytes. The Pentium processor reads 4 bytes and discards the upper 2 bytes. This may have an effect if the ESP is close to the stack segment limit. On the Pentium processor, ESP+4 may be above the stack limit in which case a fault will be generated. On the Intel486 CPU, ESP+2 may be less than the stack limit and no fault is generated.

### 23.2.19.4. ERROR CODE PUSHES

The Intel486 CPU implements the error code pushed on the stack as a 16-bit value. When pushed onto a 32-bit stack, the Intel486 CPU only pushes 2 bytes and updates ESP by 4. The Pentium processor error code is a full 32 bits with the upper 16 bits set to zero. The Pentium

processor, therefore, pushes 4 bytes and updates ESP by 4. Any code that relies on the state of the upper 16 bits may produce inconsistent results.

### **23.2.19.5. FAULT HANDLING EFFECTS ON THE STACK**

During the handling of certain instructions, such as CALL and PUSH, faults may occur in different sequences for the different processors. For example, during far calls, the Intel486 CPU pushes the old CS and EIP before a possible branch fault is resolved. A branch fault is a fault from a branch instruction occurring from a segment limit or access rights violation. If a branch fault is taken, the Intel486 CPU will have corrupted memory below the stack pointer. However, ESP is backed up in order to make the instruction restartable. The Pentium processor issues the branch before the pushes. Therefore, if a branch fault does occur, the Pentium processor does not corrupt memory below the stack pointer. This implementation difference, however, does not constitute a compatibility problem, as only values at or above the stack pointer are considered to be valid.

### **23.2.19.6. INTERLEVEL RET/IRET FROM A 16-BIT INTERRUPT OR CALL GATE**

If a call or interrupt is made from a 32-bit stack environment through a 16-bit gate, only 16 bits of the old ESP can be pushed onto the stack. On the subsequent RET/IRET, the 16-bit ESP is popped but the full 32-bit ESP is updated since control is being resumed in a 32-bit stack environment. The Intel486 processor writes the SS selector into the upper 16 bits of ESP. The Pentium processor writes zeros into the upper 16 bits.

### **23.2.20. Mixing 16- and 32-Bit Segments**

The features of the 16-bit Intel 286 processor are an object-code compatible subset of those of the Pentium processor. The Default bit in segment descriptors indicates whether the processor is to treat a code, data, or stack segment as a 16-bit or 32-bit segment.

The segment descriptors used by the Intel 286 processor are supported by the 32-bit processors if the Intel-reserved word (highest word) of the descriptor is clear. On the 32-bit Intel architecture, this word includes the upper bits of the base address and the segment limit.

The segment descriptors for data segments, code segments, local descriptor tables (there are no descriptors for global descriptor tables), and task gates are the same for the 16- and 32-bit processors. Other 16-bit descriptors (TSS segment, call gate, interrupt gate, and trap gate) are supported by the 32-bit processors. The 32-bit processors also have descriptors for TSS segments, call gates, interrupt gates, and trap gates which support the 32-bit architecture. Both kinds of descriptors can be used in the same system.

For those segment descriptors common to both 16- and 32-bit processors, clear bits in the reserved word cause the 32-bit processors to interpret these descriptors exactly as an Intel 286 processor does; for example:



- **Base Address**—The upper eight bits of the 32-bit base address are clear, which limits base addresses to 24 bits.
- **Limit**—The upper four bits of the limit field are clear, restricting the value of the limit field to 64 Kbytes.
- **Granularity bit**—The Granularity bit is clear, indicating the value of the 16-bit limit is interpreted in units of 1 byte.
- **Big bit**—In a data-segment descriptor, the B bit is clear in the segment descriptor used by the 32-bit processors, indicating the segment is no larger than 64 Kbytes.
- **Default bit**—In a code-segment descriptor, the D bit is clear, indicating 16-bit addressing and operands are the default. In a stack-segment descriptor, the D bit is clear, indicating use of the SP register (instead of the ESP register) and a 64-Kbyte maximum segment limit.

For formats of these descriptors and documentation of their use see the *iAPX 286 Programmer's Reference Manual*. For information on mixing 16- and 32-bit code in applications, see Chapter 21.

### 23.2.21. Segment and Address Wraparound

This section discusses differences in segment and address wraparound between the Pentium, Intel486, Intel386, Intel 286, and 8086 processors.

#### 23.2.21.1. SEGMENT WRAPAROUND

On the 8086 processor, an attempt to access a memory operand which crosses offset 65,535 or 0FFFFH or offset 0 (e.g., MOV a word to offset 65,535 or PUSH a word when SP = 1) causes the offset to wrap around modulo 65,536 or 010000H. With the Intel 286 processor, any base and offset combination which addresses beyond 16 megabytes wraps around to the first megabyte of the address space. The Pentium, Intel486, and Intel386 processors in real-address mode generate an exception in these cases: a general-protection exception if the segment is a data segment (i.e., if the CS, DS, ES, FS, or GS register is being used to address the segment) or a stack exception if the segment is a stack segment (i.e., if the SS register is being used). An exception to this behavior occurs when a stack access is datum aligned, and the stack pointer is pointing to the last aligned datum of that size at the top of the stack (ESP=0FFFFFFC). When this data is popped, no segment limit violation occurs and the stack pointer will wrap around to 0.

The address space of the Pentium and Intel486 processors may wraparound at 1 megabyte in real-address mode. An external pin A20M# forces wraparound if enabled. On members of the 8086 family, it is possible to specify addresses greater than 1 megabyte. For example, with a selector value 0FFFFH and an offset of 0FFFFH, the effective address would be 10FFEFH (1 megabyte + 65519 bytes). The 8086 processor, which can form addresses up to 20 bits long, truncates the uppermost bit, which "wraps" this address to 0FFEFH. However, the Pentium and Intel486 processors do not truncate this bit if A20M# is not enabled.

If a stack operation wraps around the address limit, shutdown occurs. (The 8086 processor does not have a shutdown mode nor a limit.)

### 23.2.22. Write Buffers and Memory Ordering

The Pentium processor has two write buffers, one corresponding to each of the pipe-lines, to enhance the performance of consecutive writes to memory. These write buffers can be filled simultaneously in one clock e.g., by two simultaneous write misses in the two pipe-lines. Writes in these buffers are driven out on the external bus in the order they were generated by the processor core. No reads (as a result of cache miss) are reordered around previously generated writes sitting in the write buffers. The implication of this is that the write buffers will be flushed or emptied before a subsequent bus cycle is run on the external bus.

It should be noted that only memory writes are buffered and I/O writes are not. The Pentium and Intel486 processors do not synchronize the completion of memory writes on the bus and instruction execution after the write. The OUT instruction or a serializing instruction needs to be executed to synchronize writes with the next instruction. Refer to Chapter 18 for information on serializing instructions.

No re-ordering of read cycles occurs on the Pentium processor. Specifically, the write buffers are flushed before the IN instruction is executed.

On the Intel486 CPU, under certain conditions, a memory read will go onto the external bus before the memory writes pending in the buffer even though the writes occurred earlier in the program execution. A memory read will only be reordered in front of all writes pending in the buffers if all writes pending in the buffers are cache hits and the read is a cache miss. Under these conditions, the Intel486 processor will not read from an external memory location that needs to be updated by one of the pending writes.

Locked bus cycles are used for read-modify-write accesses to memory. During a locked bus cycle, the Intel486 processor will always access external memory, it will never look for the location in the on-chip cache. All data pending in the Intel486 processor's write buffers will be written to memory before a locked cycle is allowed to proceed to the external bus. Thus, the locked bus cycle can be used for eliminating the possibility of reordering read cycles on the Intel486 processor. If the line is present in the cache, the Pentium processor will write it back if it was dirty and invalidate the line.

I/O reads are never reordered in front of buffered memory writes on the Intel486 processor. This ensures an update of all memory locations before reading the status from an I/O device.

### 23.2.23. Bus Locking

The LOCK prefix and its bus signal only should be used to prevent other bus masters from interrupting a data movement operation. The LOCK prefix only may be used with the following Pentium processor, Intel486 CPU, and Intel386 CPU instructions when they modify memory. An invalid-opcode exception results from using the LOCK prefix before



any other instruction, or with these instructions when no write operation is made to memory (i.e., when the destination operand is in a register).

- Bit test and change: the BTS, BTR, and BTC instructions.
- Exchange: the XCHG, XADD, CMPXCHG, and CMPXCHG8B instructions (no LOCK prefix is needed for the XCHG instruction).
- One-operand arithmetic and logical: the INC, DEC, NOT, NEG instructions.
- Two-operand arithmetic and logical: the ADD, ADC, SUB, SBB, AND, OR, and XOR instructions.

The Intel 286 processor performs the bus lock function differently than the Intel486 processor. Programs which use forms of memory locking specific to the Intel 286 processor may not run properly when run on the Intel486 processor.

A locked instruction is guaranteed to lock only the area of memory defined by the destination operand, but may lock a larger memory area. For example, typical 8086 and Intel 286 configurations lock the entire physical memory space. Programmers should not depend on this.

On the Intel 286 processor, the LOCK prefix is sensitive to IOPL; if CPL is less privileged than the IOPL, a general protection exception is generated. On the Intel386 DX, Intel486, and Pentium processors, no check against IOPL is performed.

### 23.2.24. Bus Hold

Unlike the 8086 and Intel 286 processors, but like the Intel386 and Intel486 processors, the Pentium processor respond to requests for control of the bus from other potential bus masters, such as DMA controllers, between transfers of parts of an unaligned operand, such as two words which form a doubleword. Unlike the Intel386 processor, the Pentium and Intel486 processors respond to bus hold during reset initialization.

### 23.2.25. Two Ways to Run Intel 286 CPU Tasks

When porting 16-bit programs to the Pentium processor, there are two approaches to consider:

1. Porting an entire 16 software system to a 32-bit processor, complete with the old operating system, loader, and system builder.  
In this case, all tasks will have 16-bit TSSs. The 32-bit processor is being used as if it were a faster version of the 16-bit processor.
2. Porting selected 16-bit applications to run in a 32-bit processor environment with a 32-bit operating system, loader, and system builder.

In this case, the TSSs used to represent 286 tasks should be changed to 32-bit TSSs. It is possible to mix 16 and 32-bit TSSs, but the benefits are small and the problems are great.

All tasks in a 32-bit software system should have 32-bit TSSs. It is not necessary to change the 16-bit object modules themselves; TSSs are usually constructed by the operating system, by the loader, or by the system builder. See Chapter 21 for more discussion of the interface between 16-bit and 32-bit code.

Because the 32-bit processors use the contents of the reserved word of 16-bit segment descriptors, 16-bit programs which place values in this word may not run correctly on the 32-bit processors.

## **23.3. FLOATING-POINT UNIT**

This section addresses the issues that must be faced when transporting numerical software to a Pentium processor with integrated FPU from one of its predecessor systems. To software, the Pentium processor looks very much like an Intel486 DX processor system, an Intel486 SX and Intel487 SX math coprocessor system, or an Intel386 CPU and Intel387 math coprocessor system. Software which runs on any of these systems will run with at most minor modifications on the Pentium processor. To transport code directly from an Intel 286 CPU with an Intel287 math coprocessor-based system or an 8086 CPU with an 8087 math coprocessor-based system to the Intel486 processor, certain additional issues must be addressed.

### **23.3.1. Control Register Bits**

This section summarizes the differences in control register bits that may affect numerical software.

#### **23.3.1.1. EXTENSION TYPE (ET) BIT**

The ET (Extension Type) bit of the CR0 control register is used in the Intel386 processor to indicate whether the math coprocessor in the system is an Intel287 math coprocessor (ET=0) or an Intel387 DX math coprocessor (ET=1). This bit is not used by Pentium processor or Intel486 processor hardware. The ET bit is hardwired to "1."

#### **23.3.1.2. NUMERIC EXCEPTION (NE) BIT**

The NE (Numeric Exception) bit of the CR0 register is used in the Pentium and Intel486 processors to determine whether unmasked floating-point exceptions are reported internally via interrupt vector 16 (NE=1) or through external interrupt (NE=0). On reset, the NE bit is initialized to 0, so software using the automatic internal error-reporting mechanism must set this bit to 1. This bit is nonexistent on the Intel386 processor.



### 23.3.1.3. MONITOR COPROCESSOR (MP) BIT

As on the Intel 286 and Intel386 processors, the MP (Monitor coProcessor) bit of the CRO control register determines whether WAIT instructions trap when the context of the FPU is different from that of the currently-executing task. If MP=1 and TS=1, then a WAIT instruction will cause a Device Not Available fault (interrupt vector 7). The MP bit is used on the Intel 286 and Intel386 microprocessors to support the use of a WAIT instruction to wait on a device other than a numeric coprocessor. The device reports its status through the BUSY# pin. Since the Pentium and Intel486 processors do not have such a pin, the MP bit has no relevant use, and should be set to 1 for normal operation.

### 23.3.1.4. FPU STATUS WORD

This section identifies differences to the FPU status word for the different Intel architecture processors/math coprocessors, as well as the reason for the differences, and their impact on software.

- Bits C3-C0 — After FINIT and hardware reset, these bits are set to zero on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor. After FINIT and hardware reset, the Intel287 and 8087 math coprocessors leave these bits intact (they contain the prior value). This has no impact on software and provides a consistent state after reset. Transcendental instruction results in the core range of the Pentium processor (as defined in Chapter 7) may differ from the Intel486 DX and Intel487 SX CPU's by around 2 to 3 units in last place (ulps). As a result, C1 may also differ.
- Bits C3, C1, C0 — After an incomplete FPREM/FPREM1, these bits are set on zero on the Pentium processor, Intel486 processor and the Intel387 math coprocessor. On the 8087 and the Intel287 math coprocessor, these bits are left intact following incomplete FPREM/FPREM1 execution.
- Bit C2 — Bit 10 serves as an incomplete bit for FPTAN on the Pentium and Intel486 processors and the Intel387 math coprocessor. This bit is undefined for FPTAN on the Intel287 and 8087 math coprocessors. This change has no impact on software as programs do not check C2 after FPTAN. This upgrade allows fast checking of operand range.
- Status Word Bit 6 for Stack Fault — When an invalid-operation exception occurs on the Pentium processor, Intel486 CPU, or Intel387 math coprocessor due to stack overflow or underflow, not only is bit 0 (IE) of the status word set, but also bit 6 is set to indicate a stack fault and bit 9 (C1) specifies overflow or underflow. Bit 6 is called SF and serves to distinguish invalid exceptions caused by stack overflow/underflow from those caused by numeric operations. When an invalid-operation exception occurs on the Intel287 or 8087 math coprocessor due to stack overflow or underflow, only bit 0 (IE) of the status word is set. Bit 6 is RESERVED. This has no impact on software. Existing exception handlers need not change, but may be upgraded to take advantage of the additional information. Newly written handlers will be more effective. This upgrade provides performance improvement.

### 23.3.1.5. CONTROL WORD

Only affine closure is supported for infinity control on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. Bit 12 remains programmable but has no effect on operation. On the Intel287 and 8087 math coprocessors, both affine and projective closures are supported. After RESET, the default value in the control word is projective. Software that requires projective infinity arithmetic may give different results. This change was made in order to conform to IEEE Standard 754.

### 23.3.1.6. TAG WORD

This section describes the differences in the tag word for the difference Intel architectures, the reason for the differences, and their impact on software.

- When loading the tag word of the Pentium processor, Intel486 CPU, or Intel387 math coprocessor NPX with an FLDENV or FRSTOR instruction, the processor examines the incoming tag and classifies the location only as empty or non-empty. Thus, tag values of 00, 01, and 10 are interpreted by the CPU to indicate a non-empty location. Tag values of 11 are interpreted by the CPU to indicate an empty location. Subsequent operations on a nonempty register always examine the value in the register, not the value in its tag. The FSTENV and FSAVE instructions examine the nonempty registers and put the correct values in the tags before storing the tag word.

The corresponding tag for the Intel287 and 8087 math coprocessors is checked before each register access to determine the class of operand in the register; the tag is updated after every change to a register so that the tag always reflects the most recent status of the register. Programmers can load a tag with a value that disagrees with the contents of a register (for example, the register contains valid contents, but the tag says *special*; the Intel287 and 8087 math coprocessors, in this case, honor the tag and do not examine the register).

Software may not operate correctly if it uses FLDENV or FRSTOR to change tags to values (other than empty) that are different from actual register contents.

The reason for this change was due to performance improvement.

- The encoding in the tag word for the Pentium processor/Intel486 CPU/Intel487 math coprocessors NPX for the unsupported data formats is "special data" (type 10). The encoding the Intel287 and 8087 math coprocessors for pseudo-zero and unnormal is "valid" (type 00); the others are "special data" (type 10). Exception handlers may need to be changed if programmers use such data types.

The reason for this difference is IEEE Standard 754 compatibility.

## 23.3.2. Data Types

This section discusses the differences of data types for the various microprocessors/math coprocessors, the reason for the differences, and their impact on software.



### 23.3.2.1. NaNs

The Pentium processor, Intel486 DX CPU, Intel487 SX math coprocessor NPX, and Intel387 math coprocessor NPX distinguish between signaling NaNs and quiet NaNs. These processors only generate quiet NaNs. An invalid-operation exception is raised only upon encountering a signaling NaN (except for FCOM, FIST, and FBSTP which also raise IE for quiet NaNs).

The Intel287 and 8087 math coprocessors only generate one kind of NaN (the equivalent of a quiet NaN) but raise an invalid-operation exception upon encountering any kind of NaN.

Uninitialized memory locations that contain QNaNs should be changed to SNaNs to cause the Pentium and Intel486 processors and the Intel387 math coprocessor to fault when uninitialized memory locations are referenced.

The reason for the difference is IEEE Standard 754 compatibility.

### 23.3.2.2. PSEUDOZERO, PSEUDO-NaN, PSEUDEOINFINITY, AND UNNORMAL FORMATS

The Pentium processor/Intel486 CPU/Intel387 math coprocessor NPX neither generate nor support these formats; they raise an invalid-operation exception whenever they encounter them in an arithmetic operation. The Intel287 and 8087 math coprocessors define and support special handling for these formats.

This difference has no impact on software. The Pentium and Intel486 processors and the Intel387 DX math coprocessor do not generate these formats, and therefore will not encounter them unless a programmer deliberately enters them.

The reason for this difference is to conform to IEEE Standard 754.

## 23.3.3. Exceptions

This section identifies the implementation differences in exception handling of floating-point instructions.

### 23.3.3.1. DENORMAL EXCEPTIONS

The denormal exception is not raised in transcendental instructions and FXTRACT on the Intel287 and 8087 math coprocessors. The denormal exception is raised in transcendental instructions and FXTRACT on the Pentium and Intel486 processors and the Intel387 math coprocessor. The exception handler needs to be changed only if it gives special treatment to different opcodes. The reason for this change was performance enhancement for normal cases.

Because the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX automatically normalize denormalized numbers when possible, an 8087 program that uses the denormal exception solely to normalize denormalized operands can run on the 32-bit

Intel architecture FPU's by masking the denormal exception. The 8087 denormal exception handler would not be used by the 32-bit Intel architecture FPU's in this case. A numerics program runs faster when the FPU performs normalization of denormalized operands.

### 23.3.3.2. OVERFLOW EXCEPTIONS

There are differences in overflow exception behavior when it is masked and unmasked.

On the Pentium processor/Intel486 CPU/Intel487 math coprocessor NPX when the overflow exception is masked, and the rounding mode is set to chop (toward zero), the result is the largest positive or smallest negative number. The Intel287 and 8087 math coprocessors do not signal the overflow exception when the masked response is not infinity; i.e., they signal overflow only when the rounding control is not set to round to zero. If rounding is set to chop (toward zero), the result is positive or negative infinity. Under the most common rounding modes, there is no impact on software.

If rounding is toward zero (chop), a program on the Pentium processor/Intel486 CPU/Intel387 math coprocessor NPX produces, under overflow conditions, a result that is different in the least significant bit of the significand, compared to the result on the Intel287 math coprocessor. The reason for this difference is IEEE Standard 754 compatibility.

When the overflow exception is not masked, the precision exception is flagged on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. When the result is stored in the stack, the significand is rounded according to the precision control (PC) bit of the control word or according to the opcode. On the Intel287 and 8087 math coprocessors, the precision exception is not flagged and the significand is not rounded. The impact on software is that if the result is stored on the stack, a program on the Pentium and Intel486 processors and the Intel387 math coprocessor produce a different result under overflow conditions than on the Intel287 and 8087 math coprocessors. The difference is apparent only to the exception handler. This difference is for IEEE Standard 754 compatibility.

### 23.3.3.3. UNDERFLOW EXCEPTIONS

Two related events contribute to underflow:

1. The creation of a *tiny* (denormal) result. A tiny number, because it is so small, may cause some other exception later (such as overflow upon division).
2. Loss of accuracy during the denormalization of a tiny number.

Which of these events triggers the underflow exception depends on whether the underflow exception is masked.

When the underflow exception is masked on the 32-bit FPU's and NPX's, the underflow exception is signaled when both the result is tiny and denormalization results in a loss of accuracy. When the underflow exception is unmasked and the instruction is supposed to store the result on the stack, the significand is rounded to the appropriate precision (according to the precision control (PC) bit of the control word, for those instructions controlled by PC, otherwise to extended precision), after adjusting the exponent.



When the underflow exception is masked on the Intel287 and 8087 math coprocessors and rounding is toward zero, the underflow exception flag is raised on tininess, regardless of loss of accuracy. When the underflow exception is not masked and the destination is the stack, the significand is not rounded but rather is left as is.

When the underflow exception is masked, there is no impact on software. The underflow exception occurs less often when rounding is toward zero.

When the underflow exception not masked. A program on a 32-bit Intel architecture FPU or NPX produces a different result during underflow conditions than on the Intel287 and 8087 math coprocessors if the result is stored on the stack. The difference is only in the least significant bit of the significand and is apparent only to the exception handler.

The reason for these differences are due to IEEE Standard 754 compatibility.

#### **23.3.3.4. EXCEPTION PRECEDENCE**

There is no difference in the precedence of the denormal exception on the Pentium and Intel487 processors and the Intel387 math coprocessor NPX, whether it be masked or not. When the denormal exception is not masked on the Intel287 and 8087 math coprocessors, it takes precedence over all other exceptions. This difference causes no impact on software, but some unneeded normalization of denormalized operands is prevented on the Intel486 CPU and Intel387 math coprocessor NPX. Operational improvement is the reason for this difference.

#### **23.3.3.5. CS AND IP FOR FPU EXCEPTIONS**

On the Intel 32-bit Intel architecture FPU's and NPX's, the value of the CS and IP registers saved for floating-point exceptions points at any prefixes which come before the ESC instruction. On the 8086 processor, the saved CS:IP points to the ESC instruction.

#### **23.3.3.6. FPU ERROR SIGNALS**

The floating-point error signals to the Pentium and Intel486 processors do not pass through an interrupt controller (an INT signal from Intel387, Intel287 or 8087 math coprocessors do). If an 8086 processor uses another exception for the 8087 interrupt, both exception vectors should call the floating-point error exception handler. Some instructions in a floating-point error exception handler may need to be deleted if they use the interrupt controller. The Pentium and Intel486 processors have signals which, with the addition of external logic, support reporting for emulation of the interrupt mechanism used in many personal computers.

On the Pentium and Intel486 processors, an undefined ESC opcode will cause an Invalid Opcode exception (interrupt vector 6). Undefined ESC opcodes, like legal ESC opcodes, cause a Device Not Available exception (interrupt vector 7) when either the TS or the EM bit of CR0 is set. The Pentium and Intel486 processors do not check for floating-point error conditions on encountering an undefined ESC opcode.

### **23.3.3.7. INVALID OPERATION ON DENORMALS**

No invalid opcode exception is raised on the Pentium processor/Intel486 CPU/Intel487 math coprocessor NPX upon encountering a denormal in FSQRT, FDIV, or FPREM or upon conversion to BCD or to integer. The operation proceeds by first normalizing the value. On Intel287 and 8087 math coprocessors, upon encountering a denormal in FSQRT, FDIV, or FPREM or upon conversion to BCD or to integer, the invalid-operation exception is raised. This difference has no impact on software. Software on the Pentium processor/Intel486 CPU/Intel387 math coprocessor NPX continues to execute in cases where Intel287 and 8087 math coprocessors trap. The reason for this change was to eliminate an exception from being raised.

### **23.3.3.8. ALIGNMENT EXCEPTIONS**

A misaligned data operand on the Pentium and Intel486 processors causes an alignment exception (interrupt vector 17) in level 3 software, except for the stack portion of an FSAVE/FRSTOR operation.

### **23.3.3.9. SEGMENT FAULT DURING FLDENV**

On the Intel486 processor, when a segment fault occurs in the middle of an FLDENV operation, it can happen that part of the environment is loaded and part not. In such cases, the FPU control word is left with a value of 007FH. The Pentium processor ensures the internal state is correct at all times by attempting to read the first and last bytes of the environment before updating the internal state.

### **23.3.3.10. INTERRUPT 7 — DEVICE NOT AVAILABLE**

Interrupt 7 will occur in the Pentium and Intel486 processors when executing ESC instructions with either TS (task switched) or EM (emulation) of the MSW set (TS=1 or EM=1). If TS and MP are set, then a WAIT instruction will also cause interrupt 7. An exception handler should be included in the Pentium processor and Intel486 processor code to handle these situations.

### **23.3.3.11. INTERRUPT 9 — COPROCESSOR SEGMENT OVERRUN**

Interrupt 9 does not occur in the Pentium and Intel486 processors. In cases where the Intel387 math coprocessor would cause interrupt 9, the Pentium and Intel486 processors simply abort the instruction. Some care is necessary, however. Memory faults (especially page faults), if they occur in FLDENV or FRSTOR while the operating system is performing a task switch, can cause the floating-point environment to be lost. Intel strongly recommends that the floating-point save area be the same page as the TSS.



### 23.3.3.12. INTERRUPT 13 — GENERAL PROTECTION

Interrupt 13 occurs if the starting address of a numeric operand falls outside a segment's size. An exception handler should be included to report these programming errors.

### 23.3.3.13. INTERRUPT 16 — FLOATING-POINT ERROR

In real mode and protected mode (not including virtual 8086 mode), interrupt vector 16 must point to the numeric exception handling routine. In virtual 8086 mode, the virtual-8086 monitor can be programmed to accommodate a different location of the interrupt vector for numeric exceptions.

## 23.3.4. Instructions

This section identifies the differences in instructions for the various Intel architectures, the reason for the differences, and their impact on software.

- **FDIV, FPREM, FSQRT** — Operation on denormalized operands is supported on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX and an underflow exception can occur. Operation on denormalized operands raise an invalid-operation exception on the Intel287 and 8087 math coprocessors and underflow is not possible. The exception handler for underflow may require change only if it gives different treatment to different opcodes. Possibly fewer invalid-operation exceptions will occur. The reason for this change was for IEEE Standard 754 compatibility.
- **FSCALE** — The range of the scaling operand on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX is not restricted. If  $0 < |ST(1)| < 1$ , the scaling factor is zero; therefore,  $ST(0)$  remains unchanged. If the rounded result is not exact or if there was a loss of accuracy (masked underflow), the precision exception is signaled. The range of the scaling operand on the Intel287 math coprocessor and 8087 NPX's is restricted. If  $0 < |ST(1)| < 1$ , the result is undefined and no exception is signaled. The impact on software is that a different result will occur when  $0 < |ST(1)| < 1$ . This change was to upgrade the existing range of scaling.
- **FPREM1** — The Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX perform partial remainder according to the IEEE Standard 754 standard. This instruction does not exist on the Intel287 math coprocessor and 8087 NPX's. There is no impact on software but provides IEEE Standard 754 compatibility and an upgrade to the architecture.
- **FPREM** — Bits C0, C3, C1 of the status word on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX correctly reflect the three low-order bits of the quotient. On the Intel287 math coprocessor and 8087 NPX's, the quotient bits are incorrect when performing a reduction of  $64^N + M$  when  $N \geq 1$  and  $M=1$  or  $M=2$ . This has no impact on software. Software that works around the bug should not be affected.

- **FUCOM, FUCOMP, FUCOMPP** — The Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX perform unordered compare according to IEEE Standard 754 standard. These instructions do not exist on the Intel287 math coprocessor and 8087 NPX's. There is no impact on existing software and provides IEEE Standard 754 compatibility.
- **FPTAN** — The range of operand is much less restricted ( $|ST(0)| < 2^{63}$ ) on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX; reduces operand internally using an internal  $\pi/4$  constant that is more accurate. The range of operand is restricted ( $|ST(0)| < \pi/4$ ) on the Intel287 math coprocessor and 8087 NPX's; the operand must be reduced to range using FPREM. There is no impact on software due to this difference but provides a performance upgrade.

After a stack overflow, when the invalid-operation exception is masked on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX, both ST and ST(1) contain quiet NaNs. After a stack overflow when the invalid-operation exception is masked on the Intel287 math coprocessor and 8087 NPX's, the original operand remains unchanged, but is pushed to ST(1). This has no impact on software and provides IEEE Standard 754 compatibility.

- **FSIN, FCOS, FSINCOS** — These instructions perform three common trigonometric functions on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. They do not exist on the Intel287 math coprocessor and 8087 NPX's and their presence on more recent architectures have no impact on existing software but provide a performance upgrade.
- **FPATAN** — The range of operands is unrestricted on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX.  $|ST(0)|$  must be smaller than  $|ST(1)|$  on the Intel287 math coprocessor and 8087 NPX's. There is no software compatibility impact but serves as a performance upgrade only.
- **F2XM1** — The Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX support a wider range of operands ( $-1 < ST(0) < +1$ ). The supported operand range on the Intel287 math coprocessor and 8087 NPX's is  $0 \leq ST(0) \leq 0.5$ . There is no software compatibility impact but serves as a performance upgrade only.
- **FLD extended-real** — On the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX, this instruction does not report denormal exception because the instruction is not arithmetic. The Intel287 math coprocessor and 8087 NPX's report denormal exception. There is no software compatibility impact but serves as a performance upgrade only.
- **FXTRACT** — If the operand is zero on the Pentium processor, Intel486 CPU, or Intel387 math coprocessor NPX, the zero-divide exception is reported and  $-\infty$  is delivered to ST(1). If the operand is  $+\infty$ , no exception is reported. If the operand is zero on the Intel287 math coprocessor and 8087 NPX's, ST(1) is zero and no exception is reported. If the operand is  $+\infty$ , the invalid-operation exception is reported. There is no



impact on software due to these differences. Software usually bypasses zero and  $\infty$ . This change is due to the IEEE 754 recommendation to fully support the `logb` function.

- **FLD constant** — Rounding control is in effect for the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. Rounding control is not in effect for the Intel287 math coprocessor and 8087 NPX's. Results for `FLDPI`, `FLDLN2`, `FLDLG2`, and `FLDL2E` are the same as for the Intel287 math coprocessor and 8087 NPX's when rounding control is set to round to nearest or round to  $+\infty$ . They are the same for `FLDL2T` when rounding control is set to round to nearest, round to  $-\infty$ , or round to zero. Results are different from the Intel287 math coprocessor and 8087 NPX's in the least significant bit of the mantissa if rounding control is set to round to  $-\infty$  or round to 0 for `FLDPI`, `FLDLN2`, `FLDLG2`, and `FLDL2E`; they are different for `FLDL2T` if round to  $+\infty$  is specified. These changes were implemented due to IEEE 754 recommendations.
- **FLD single/double precision** — Loading a denormal on the Pentium processor, Intel486 CPU, or Intel387 math coprocessor NPX causes the number to be converted to extended precision (because it is put on the stack). Loading a denormal on the Intel287 math coprocessor and 8087 NPX causes the number to be converted to an unnormal. If the next instruction is `FEXTRACT` or `FXAM`, the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX will give a different result than the Intel287 math coprocessor and 8087 NPX's. This change was made for IEEE Standard 754 compatibility.
- **FLD single/double precision** — When loading a signaling NaN, the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX raises an invalid exception. The Intel287 math coprocessor and 8087 NPX's do not raise an exception when loading a signaling NaN. The exception handler needs to be updated to handle this condition. This change was made for IEEE Standard 754 compatibility.
- **FSETPM** — This instruction is treated as `FNOP` (no operation) on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. This instruction informs the Intel287 math coprocessor that the system is in protected mode. There is no impact on software as a result of this difference. The Pentium processor, Intel486 CPU, and Intel386 CPU handle all addressing and exception-pointer information, whether in protected mode or not.
- **FXAM** — Encountering an empty register on the Pentium processor, Intel486 CPU, or Intel387 math coprocessor NPX will not generate combinations of `C3-C0` equal to 1101 or 1111. The Intel287 math coprocessor and 8087 NPX's may generate these combinations, among others. There is no impact on software but provides a performance upgrade, to provide repeatable results.
- **FSAVE, FSTENV** — The address of a memory operand pointer stored by `FSAVE` or `FSTENV` is undefined if the previous `ESC` instruction did not refer to memory on the Pentium and Intel486 processor FPUs and the Intel387 math coprocessor NPX.

### 23.3.5. Transcendental Instructions

The numeric results of the Pentium processor for transcendental instructions in the core range (as defined in Chapter 7) may differ from the Intel486 processors by about 2 or 3 ulps. The C1 bit may differ as a result. Some operands raise the precision exception in the Pentium processor that did not in the Intel486; see section 7.1.13. The exact threshold for underflow/overflow will vary by a few ulps. The Pentium processor results will have a worst case error of less than 1 ulp when rounding to the nearest-even and less than 1.5 ulps when rounding in other modes. The transcendental instructions are guaranteed to be monotonic, with respect to the input operands, throughout the domain supported by the instruction. See Appendix G for more information on transcendental accuracy.

On the Intel486 processor but not on the Pentium processor, transcendental instructions can be aborted at certain checkpoints during execution if an INTR is pending. Transcendental instructions should therefore be used only in an environment where INTRs are not expected to come as close as 200 clocks apart.

Transcendental instructions may generate different results in the round-up bit (C1) of status word on the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX. The round-up bit of the status word is undefined for these instructions on the Intel287 math coprocessor and 8087 NPX's. There is no impact on software due to this difference but it serves as an upgrade to signal rounding status.

### 23.3.6. Obsolete Instructions

The 8087 processor instructions FENI and FDISI and the Intel287 coprocessor instruction FSETPM are treated as NOPS in the Pentium processor, Intel486 CPU, and Intel387 math coprocessor. However, the FENI, FDISI, and FSETPM instructions do check for device-not-available faults. If these opcodes are detected in the instruction stream, no specific operation is performed and no internal states are affected.

The *80387 DX User's Manual Programmer's Reference* and the *Intel486™ DX Processor Programmer's Reference Manual* indicate that the Intel287 math coprocessor and 8087 floating-point unit (FPU) opcodes for FENI, FDISI, and FSETPM are treated as FNOP in the Intel387 math coprocessor NPX and the Intel486 processor and Pentium processor FPUs. However, FNOP checks for unmasked floating-point exceptions and these instructions do not. Thus, these instructions are integer NOP instructions rather than FNOP's in the Intel387 math coprocessor NPX, and in the Intel486 processor and Pentium processor FPU's.

#### 23.3.6.1. WAIT PREFIX DIFFERENCES

On the Intel486 processor, when a WAIT prefix precedes a numeric instruction (one which itself automatically synchronizes with the previous numeric instruction), the WAIT is treated as an NOP. Pending numeric exceptions from a previous numeric instruction are processed not on the WAIT but on the numeric instruction following the WAIT. In such a case, the report of a numeric exception may appear one instruction later on the Intel486 processor than on an Intel386 CPU/Intel387 math coprocessor NPX system or Pentium processor.



### 23.3.6.2. OPERANDS SPLIT ACROSS SEGMENTS/PAGES

On the Pentium and Intel486 processors, when the first half of an operand to be written is inside a page or segment and the second half is outside, a memory fault can cause the first half to be stored without the second. In such cases, Intel386 CPU/Intel387 math coprocessor NPX systems store nothing.

### 23.3.6.3. FPU INSTRUCTION SYNCHRONIZATION

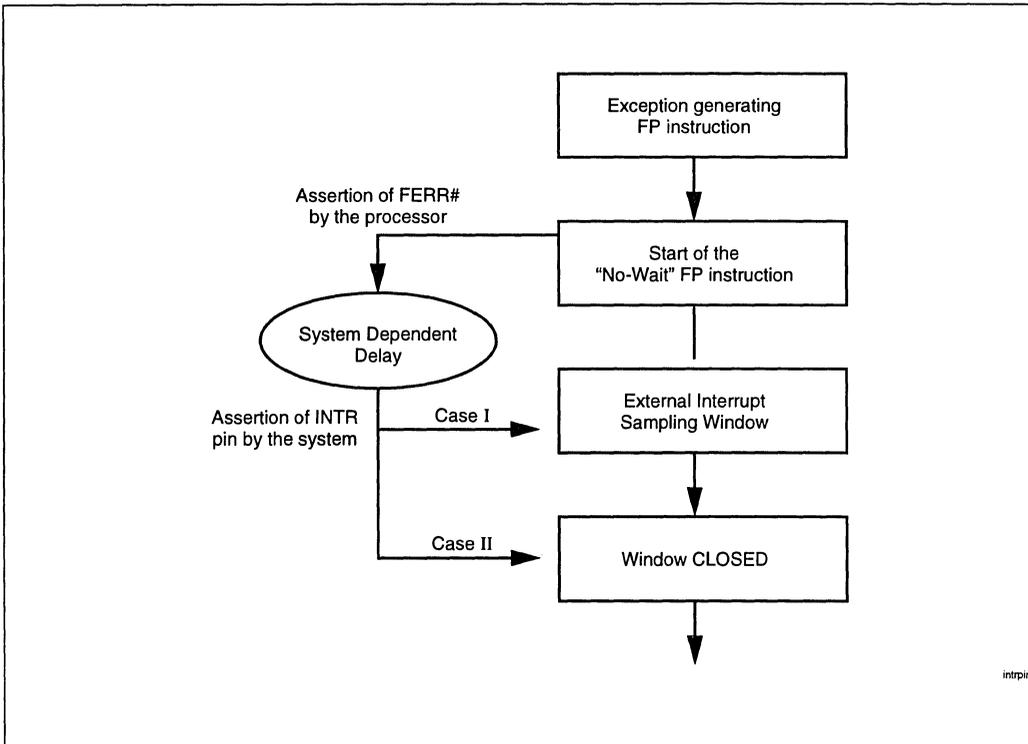
All of the Pentium processor, Intel486 CPU, and Intel387 math coprocessor NPX numeric instructions are automatically synchronized—the processor automatically waits until the previous numeric instruction has completed before executing the next ESC instruction. No explicit WAIT instructions are required to assure this synchronization. For the 8087 used with 8086 and 8088 processors, explicit WAITs are required before each numeric instruction to ensure synchronization. Although 8087 programs having explicit WAIT instructions execute perfectly on the 32-bit Intel architecture processors without reassembly, these WAIT instructions are unnecessary.

Since the 32-bit Intel architecture FPU's do not require WAIT instructions before each numeric instruction, the ASM386/486 assembler does not automatically generate these WAIT instructions. The ASM86 assembler, however, automatically precedes every ESC instruction with a WAIT instruction. Although numeric routines generated using the ASM86 assembler will generally execute correctly on the 32-bit Intel architecture FPU's, reassembly using ASM386/486 may result in a more compact code image and faster execution. The control instructions for the 32-bit Intel architecture FPU's can be coded using either a WAIT or No-WAIT form of mnemonic. The WAIT forms of these instructions cause ASM386/486 to precede the ESC instruction with a WAIT instruction, in the identical manner as does ASM86.

## 23.3.7. Numeric Exceptions: Interrupt Sampling Window

This section must be read in conjunction with section 7.1.8.2 on Software Exception Handling. The other relevant section is the FERR# pin description in the *Pentium® Processor Developer's Manual*, Volume 1, section 5.2.21.

The Pentium processor and the Intel486 processor implement the “No-Wait” class of instructions asserts the FERR# pin. This is to indicate the pending exception. These instructions are implemented such that during their execution, there is a window in which the processor will sample and accept external interrupts. If there is a pending interrupt the processor services the interrupt first before resuming the execution of the instruction. Consequently, it is possible that the “No-Wait” Floating-Point instruction may accept the external interrupt caused by it's own assertion of the FERR# pin in the event of a pending unmasked numeric exception. This is illustrated by Figure 23-4.



**Figure 23-4. The two cases that arise depending on the timing of the receipt of the external interrupt**

A floating-point instruction, belonging to the class which asserts the FERR# pin only on encountering the next floating-point instruction, causes an unmasked numeric exception. The next floating-point instruction following this instruction is one of the “No-Wait” floating-point instructions. After the assertion of the FERR# pin the “No-Wait” floating-point instruction opens a window where the pending external interrupts are sampled. There are two cases possible depending on the timing of the receipt of the interrupt via the INTR pin (asserted by the system in response to the FERR# pin) by the processor.

**Case I:** If the system responds to the assertion of FERR# pin by the “No-Wait” floating-point instruction via the INTR pin during this window then the interrupt is serviced first before resuming the execution of the “No-Wait” floating-point instruction.

**Case II:** If the system responds via the INTR pin after the window has closed then the interrupt is recognized only at the next instruction boundary.

### 23.3.7.1. USAGE OF THE “NO-WAIT” FLOATING-POINT INSTRUCTION CLASS

The “No-Wait” Floating-Point instructions proceed in the presence of pending numeric exceptions. Note, however, that this does not mean that the pending numeric exception is discarded. As pointed out in section 23.3.7, the “No-Wait” Floating-Point instructions report any pending numeric exceptions via FERR# (CR0.NE = 0).

The “No-Wait” Floating-Point instructions are useful in floating point exception handlers and in context switching code in multi-threaded systems. Note that when CR.NE = 0, system software must be prepared to service an interrupt from FERR# at any time. This is not a function of the behavior of the “No-Wait” Floating-Point instructions, but is an implication of using an asynchronous interrupt to report numeric exceptions. In particular, during a context switch where the floating point unit is being reallocated to a new process, exception synchronization is required to ensure that exceptions generated by the old context are not unintentionally associated with the new thread of execution. In the case of a floating point exception handler, however, further exception synchronization is not necessary, as the exception handler is being executed because FERR# was previously (and remains) asserted.

Note further that FNINIT, FNCLEX, and FNSAVE modify the FPU status word exception flags. Software that uses these instructions must be prepared for their implications on exception synchronization. In particular, if an FERR# is asserted before or by an FNINIT, FNCLEX, or FNSAVE, and the resulting interrupt is serviced after completion of the instruction, the FPU status word will not reflect the conditions that caused the interrupt.

See section 6.4.1.8 for more information on the proper synchronization of floating point exceptions.



# **Part IV**

## **Optimization**



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**24**

# **Optimization**



## CHAPTER 24 OPTIMIZATION

This chapter provides some general guidelines for programming Intel's architectures. For additional information refer to AP-500, *Optimizations for Intel's 32-Bit Processors*, order number 241799.

### 24.1. ADDRESSING MODES AND REGISTER USAGE

This section identifies instruction examples that result on delays based on addressing modes and register usage.

An Address Generation Interlock (AGI) occurs when a register being used as the base or index component of an effective address calculation was the destination register of a previous instruction. It causes a 1-clock delay.

In the following sequence, the MOV instruction has a one clock stall on both the Intel486 and the Pentium processors.

```
add edx, 4
mov esi, [edx]
```

On the Intel486 processor, only adjacent instructions can cause AGI's. On the Pentium processor, with its higher degree of concurrent execution, instructions which are up to three instructions away can interact to cause an AGI. Consider the following fabricated worst case sequence:

```
add esi, 4
pop ebx
inc ebx
mov edx, [esi]
```

This sequence executes on the Intel486 processor in four clocks. Due to the pairing of instructions on the Pentium processor, the MOV needs the value of ESI, which is not available until the ADD completes the execute (EX) stage, the MOV stalls for one clock. Therefore, the above instruction sequence executes in three clocks on the Pentium processor.

Note that some instructions have implicit writes/reads to registers. Instructions that generate addresses implicitly through ESP (PUSH/POP/RET/CALL) also suffer from the AGI penalty (explicit write followed by explicit or implicit read).

#### Examples:

```
sub esp, 24          / 1 cycle stall
  (sub)
push ebx
```

```
mov esp, ebp          / 1 cycle stall
  (mov)
pop ebp
```

PUSH and POP also implicitly write to ESP. This, however, does not cause an AGI when the next instruction addresses through ESP (implicit write followed by explicit or implicit read through ESP). The following example demonstrates that an implicit write followed by an explicit or implicit read of ESP does not generate an AGI.

**Example:**

```
push edi              / no stall
mov ebx, [esp]
```

On the Intel486 CPU, there is a one clock penalty for decoding an instruction with either an index or an immediate-displacement combination. On the Pentium processor, there is no one clock penalty. There also is no penalty for an indexed instruction on the Pentium processor.

**Example:**

```
mov result, 555      / 555 is immediate, result
                    /   is displacement
mov dword ptr [esp+4], 1 / 1 is immediate, 4 is
                    displacement
```

Unlike the Intel486 CPU, there is no one clock penalty when using a register immediately after its sub-register was written.

**Example (Pentium processor):**

```
mov al, 0            /1
mov [ebp], eax      /2 no delay on Pentium processor
```

**Example (Intel486 CPU):**

```
mov al, 0            /1
  (mov)              /2 one clock delay on Intel486 CPU
mov [ebp], eax      /3
```

## 24.2. ALIGNMENT

The effect of data misalignment on the Pentium processor is similar to its effect on the Intel486 CPU. However, code alignment requirements are not as strict as on the Intel486 CPU.

### 24.2.1. Code Alignment

Unlike the Intel486 CPU, alignment of code on a cache line boundary (32-byte on Pentium processor, 16-byte on Intel486 CPU) does not have a substantial effect on Pentium processor performance. However, labels may be aligned as recommended for the Intel486 CPU because

the incremental cost on the Pentium processor is negligible and it improves the efficiency of the Intel486 CPU.

### 24.2.2. Data Alignment

A misaligned access in the data cache costs an extra 3 cycles on both the Intel486 and Pentium processors.

- **4-byte Data.** The alignment of 4-byte objects should be on a 4-byte boundary.
- **2-byte Data.** A 2-byte object should be fully contained within an aligned 4-byte word (i.e., its binary address should be xxxx00, xxxx01, xxxx10, but not xxxx11). (A 2-byte data object has to be aligned on a 2-byte boundary to avoid a penalty.)
- **8-byte Data.** The penalty for a misaligned 8-byte data object (64-bit, e.g., double precision reals) access is 3 cycles (as in Intel486 CPU). An 8-byte datum should be aligned on an 8-byte boundary.

### 24.3. PREFIXED OPCODES

The prefixes lock, segment override, address size, two-byte opcode map (0F), and operand size are decoded in one clock for each prefix. Note that this includes all the 16-bit instructions when executing in 32-bit mode because an operand size prefix is required (e.g., MOV WORD PTR [..], ADD WORD PTR [..], ...). Use 32-bit operands for 32-bit segments and 16-bit operands for 16-bit segments as much as possible to avoid the additional byte for prefixes.

The near conditional jump instructions that have a 0FH prefix are decoded differently. In this case, the processor does not take an extra clock. Other 0F opcodes behave as normal prefixed instructions.

### 24.4. OPERAND AND REGISTER USAGE

This section discusses some guidelines to follow and delays which can occur based on the type of operand and register selection.

- Use the EAX register when possible. Many instructions are one byte shorter when the EAX register is used, such as loads and stores to memory when absolute addresses are used, transfers to other registers using the XCHG instruction, and operations using immediate operands.
- Use the DS register to access the data segment when possible. Instructions which deal with the DS register are one byte shorter than instructions which use the other data segments, because of the lack of a segment-override prefix.
- Use the ESP register to reference the stack in the deepest level of subroutines.

- When several references are made to a variable addressed with a displacement, load the displacement into a register.

## 24.5. INTEGER INSTRUCTION SELECTION

This section highlights some instruction sequences to avoid and some sequences to use when generating Intel architecture assembly code.

### 1. LEA

The LEA instruction can be advantageous in the following circumstances:

- LEA may be used sometimes as a three/four operand addition instruction. LEA ECX,[EAX+EBX\*4+ARRAY\_NAME] ).
- In many cases an LEA instruction (or a sequence of of LEA, add and shift instructions) may be used to replace constant multiply instructions.
- This can also be used to avoid copying a register when both operands to an ADD are being used after the add, since LEA need not overwrite its operands.

The disadvantage of the LEA instruction is that it increases the possibility of an AGI stall with previous instructions.

### 2. Complex Instructions

Avoid using complex instructions (ENTER, LEAVE, LOOP, string instructions, etc.). Use sequences of simple instructions instead.

### 3. Zero-Extension of Short Integers

The MOVZX instruction has a prefix and takes 3 cycles to execute (a total of 4 cycles). As with the Intel486 CPU, it is recommended to use the following sequence instead:

```
xor eax, eax
mov al, mem
```

If this occurs within a loop, it may be possible to pull the XOR out of the loop if the only assignment to EAX is the MOV AL, MEM. This has greater importance for the Pentium processor due to its concurrency of instruction execution.

Access 16-bit data with the MOVSX and MOVZX instructions. These instructions sign-extend and zero-extend word operands to doubleword length. This eliminates the need for an extra instruction to initialize the high word.

### 4. 8/16-Bit Operands

With 8-bit operands, try to use the byte opcodes, rather than using 32-bit operations on sign and zero extended bytes. Prefixes for operand size override apply to 16-bit operands, not to 8-bit operands.

Sign Extension is usually quite expensive. Often, the semantics can be maintained by zero extending 16-bit operands. Specifically, the C code in the following example does not need sign extension nor does it need prefixes for operand size overrides.



```
static short int a,b;
if (a==b) {
}
```

## 5. Compares

Use **TEST** when comparing a value in a register with 0. Test essentially **AND**'s the operands together without writing to a destination register. If you **AND** a value with itself and the result sets the zero condition flag, the value was zero.

Use **TEST** when comparing the result of a boolean **AND** with an immediate constant for equality or inequality if the register is **EAX**. (**IF (AVAR & 8) { }**).

## 6. Address Calculations

Pull address calculations into load and store instructions. Internally, memory reference instructions can have 4 operands: a relocatable load time segment base, a base register, a displacement, and a scaled index register. In many cases, several integer instructions can be eliminated by fully using the operands of memory references.

When there is a choice to use either a base or index register, always choose the base because there is a one clock penalty on an Intel486 CPU for using an index.

## 7. Clearing a Register

The preferred sequence to move zero to a register is **XOR REG, REG**. This saves code space but sets the condition codes. In contexts where the condition codes must be preserved, use: **MOV REG, 0**.

## 8. Integer Divide

Typically, an integer divide is preceded by a **CDQ** instruction. (Divide instructions use **EDX:EAX** as the dividend and **CDQ** sets up **EDX**.) It is better to copy **EAX** into **EDX**, then right shift **EDX** 31 places to sign extend. The copy/shift takes the same number of clocks as **CDQ** on both the Pentium processor and Intel486 CPU, but the copy/shift scheme allows two other instructions to execute at the same time on the Pentium processor. If you know the value is positive, use **XOR EDX, EDX**.

## 9. Avoid Compares with Immediate Zero

Often when a value is compared with zero, the operation producing the value sets condition codes which can be tested directly by a **JCC** instruction. (The most notable exceptions are **MOV** and **LEA**. In these cases, use **TEST**.)

## 10. Integer Multiply by Constant

The integer multiply by an immediate can usually be replaced by a faster series of shift's, add's, sub's, and lea's.

In general, if there are 8 or fewer bits set in the binary representation of the constant, it is better not to do the integer multiply. On an Intel486 CPU, the break even point is lower: it is profitable if 6 bits or less are in the constant. Basically, shift and add for each bit set.

## 11. In place of using an **ENTER** instruction at lexical level 0, use a code sequence like:

```
PUSH EBP
MOV EBP, ESP
SUB ESP, BYTE_COUNT
```

## 12. Jump Instructions

The jump instructions come in two forms: one form has an eight-bit immediate for relative jumps in the range from 128 bytes back to 127 bytes forward, the other form has a full 32-bit displacement. Many assemblers use the long form in situations where the short form can be used. When it is clear that the short form may be used, explicitly specify the destination operand as being byte length. This tells the assembler to use the short form. Note that some assemblers perform this optimization automatically.

13. For fastest task switching, perform task switching in software. This allows a smaller processor state to be saved and restored. See Chapter 13 for a discussion of multitasking.
14. Minimize segment register loads and use of far pointers as much as possible. Increased protection between segments costs performance as a substantial number of clocks are required to load the segment registers.



# **Part V**

## **Instruction Set**



**intel**<sup>®</sup>

**25**

# **Instruction Set**





## CHAPTER 25

# INSTRUCTION SET

This chapter presents the instructions in alphabetical order. For each instruction, the forms are given for each operand combination, including object code produced, operands required, execution time, and a description. For each instruction, there is an operational description and a summary of exceptions generated.

### 25.1. OPERAND-SIZE AND ADDRESS-SIZE ATTRIBUTES

When executing an instruction, the processor can address memory using either 16 or 32-bit addresses. Consequently, each instruction that uses memory addresses has associated with it an address-size attribute of either 16 or 32 bits. The use of 16-bit addresses implies both the use of 16-bit displacements in instructions and the generation of 16-bit address offsets (segment relative addresses) as the result of the effective address calculations. 32-bit addresses imply the use of 32-bit displacements and the generation of 32-bit address offsets. Similarly, an instruction that accesses words (16 bits) or doublewords (32 bits) has an operand-size attribute of either 16 or 32 bits.

The attributes are determined by a combination of defaults, instruction prefixes, and (for programs executing in protected mode) size-specification bits in segment descriptors.

#### 25.1.1. Default Segment Attribute

For programs running in protected mode, the D bit in executable-segment descriptors specifies the default attribute for both address size and operand size. These default attributes apply to the execution of all instructions in the segment. A clear D bit sets the default address size and operand size to 16 bits; a set D bit, to 32 bits.

Programs that execute in real mode or virtual-8086 mode have 16-bit addresses and operands by default.

#### 25.1.2. Operand-Size and Address-Size Instruction Prefixes

The internal encoding of an instruction can include two byte-long prefixes: the address-size prefix, 67H, and the operand-size prefix, 66H. (A later section, "Instruction Format," shows the position of the prefixes in an instruction's encoding.) These prefixes *override* the default segment attributes for the instruction that follows. Table 25-1 shows the effect of each possible combination of defaults and overrides.

**Table 25-1. Effective Size Attributes**

Segment Default D = ...	0	0	0	0	1	1	1	1
Operand-Size Prefix 66H	N	N	Y	Y	N	N	Y	Y
Address-Size Prefix 67H	N	Y	N	Y	N	Y	N	Y
Effective Operand Size	16	16	32	32	32	32	16	16
Effective Address Size	16	32	16	32	32	16	32	16

Y = Yes, this instruction prefix is present

N = No, this instruction prefix is not present

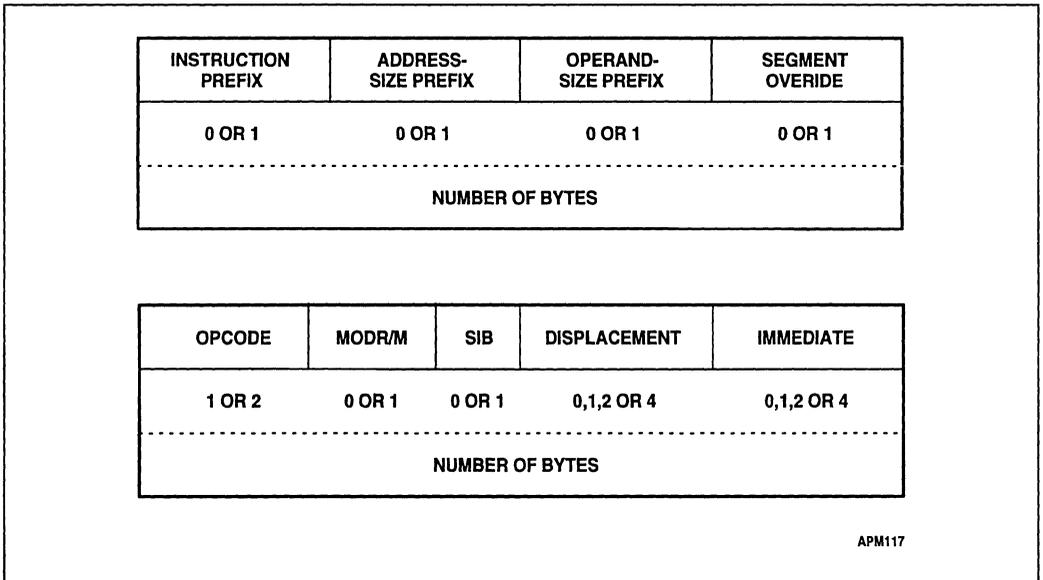
### 25.1.3. Address-Size Attribute for Stack

Instructions that use the stack implicitly (for example: POP EAX) also have a stack address-size attribute of either 16 or 32 bits. Instructions with a stack address-size attribute of 16 use the 16-bit SP stack pointer register; instructions with a stack address-size attribute of 32 bits use the 32-bit ESP register to form the address of the top of the stack.

The stack address-size attribute is controlled by the B bit of the data-segment descriptor in the SS register. A value of zero in the B bit selects a stack address-size attribute of 16; a value of one selects a stack address-size attribute of 32.

## 25.2. INSTRUCTION FORMAT

All instruction encodings are subsets of the general instruction format shown in Figure 25-1. Instructions consist of optional instruction prefixes (in any order), one or two primary opcode bytes, possibly an address specifier consisting of the ModR/M byte and the SIB (Scale Index Base) byte, a displacement, if required, and an immediate data field, if required.



**Figure 25-1. Instruction Format**

Smaller encoding fields can be defined within the primary opcode or opcodes. These fields define the direction of the operation, the size of the displacements, the register encoding, or sign extension; encoding fields vary depending on the class of operation.

Most instructions that can refer to an operand in memory have an addressing form byte following the primary opcode byte(s). This byte, called the ModR/M byte, specifies the address form to be used. Certain encodings of the ModR/M byte indicate a second addressing byte, the SIB (Scale Index Base) byte, which follows the ModR/M byte and is required to fully specify the addressing form.

Addressing forms can include a displacement immediately following either the ModR/M or SIB byte. If a displacement is present, it can be 8-, 16- or 32-bits.

If the instruction specifies an immediate operand, the immediate operand always follows any displacement bytes. The immediate operand, if specified, is always the last field of the instruction.

Zero or one bytes are reserved for each group of prefixes. The prefixes are grouped as follows:

1. Instruction Prefixes: REP, REPE/REPZ, REPNE/REPNZ, LOCK
2. Segment Override Prefixes: CS, SS, DS, ES, FS, GS
3. Operand Size Override
4. Address Size Override

For each instruction, one prefix may be used from each group. The effect of redundant prefixes (more than one prefix from a group) is undefined and may vary from processor to processor. The prefixes may come in any order.

The following are the allowable instruction prefix codes:

F3H	REP prefix (used only with string instructions)
F3H	REPE/REPZ prefix (used only with string instructions)
F2H	REPNE/REPZ prefix (used only with string instructions)
F0H	LOCK prefix

The following are the segment override prefixes:

2EH	CS segment override prefix
36H	SS segment override prefix
3EH	DS segment override prefix
26H	ES segment override prefix
64H	FS segment override prefix
65H	GS segment override prefix
66H	Operand-size override
67H	Address-size override

### 25.2.1. ModR/M and SIB Bytes

The ModR/M and SIB bytes follow the opcode byte(s) in many of the processor instructions. They contain the following information:

- The indexing type or register number to be used in the instruction
- The register to be used, or more information to select the instruction
- The base, index, and scale information

The ModR/M byte contains three fields of information:

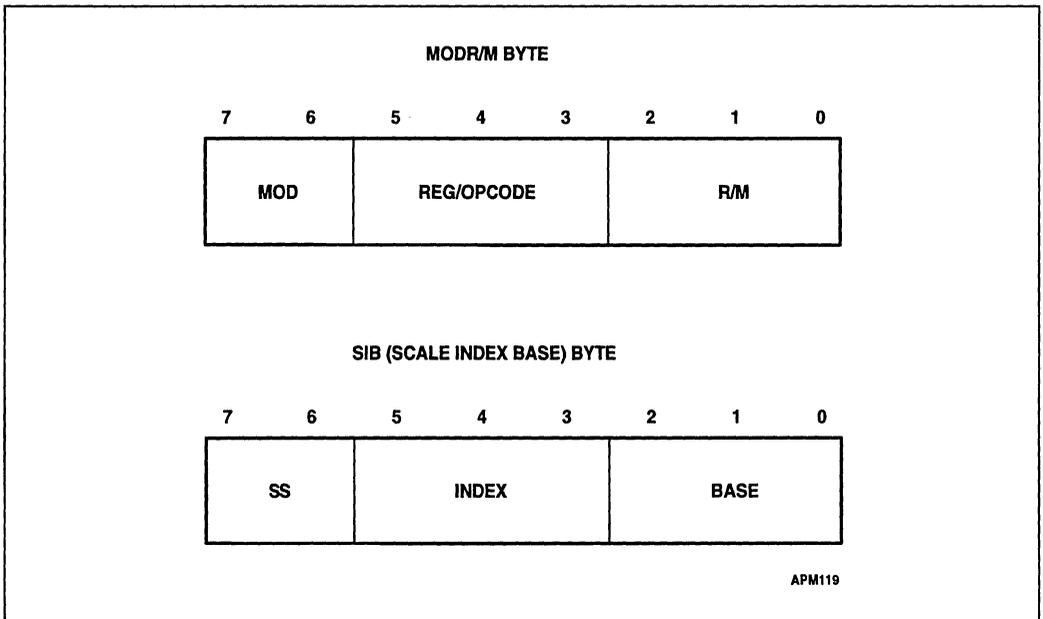
- The **mod** field, which occupies the two most significant bits of the byte, combines with the *r/m* field to form 32 possible values: eight registers and 24 indexing modes.
- The **reg** field, which occupies the next three bits following the mod field, specifies either a register number or three more bits of opcode information. The meaning of the reg field is determined by the first (opcode) byte of the instruction.
- The **r/m** field, which occupies the three least significant bits of the byte, can specify a register as the location of an operand, or can form part of the addressing-mode encoding in combination with the **mod** field as described above.

The based indexed and scaled indexed forms of 32-bit addressing require the SIB byte. The presence of the SIB byte is indicated by certain encodings of the ModR/M byte. The SIB byte then includes the following fields:



- The **ss** field, which occupies the two most significant bits of the byte, specifies the scale factor.
- The **index** field, which occupies the next three bits following the **ss** field and specifies the register number of the index register.
- The **base** field, which occupies the three least significant bits of the byte, specifies the register number of the base register.

Figure 25-2 shows the formats of the ModR/M and SIB bytes.



**Figure 25-2. ModR/M and SIB Byte Formats**

The values and the corresponding addressing forms of the ModR/M and SIB bytes are shown in Table 25-2 through Table 25-4. The 16-bit addressing forms specified by the ModR/M byte are in Table 25-2. The 32-bit addressing forms specified by the ModR/M byte are in Table 25-3. Table 25-4 shows the 32-bit addressing forms specified by the SIB byte.

Table 25-2. 16-Bit Addressing Forms with the ModR/M Byte

r8(/r) r16(/r) r32(/r) /digit (Opcode) REG =	AL AX EAX 0 000	CL CX ECX 1 001	DL DX EDX 2 010	BL BX EBX 3 011	AH SP ESP 4 100	CH BP EBP 5 101	DH SI ESI 6 110	BH DI EDI 7 111		
Effective Address	Mod	R/M	ModR/M Values in Hexadecimal							
[BX+SI] [BX+DI] [BP+SI] [BP+DI] [SI] [DI] disp16 [BX]	00	000 001 010 011 100 101 110 111	00 01 02 03 04 05 06 07	08 09 0A 0B 0C 0D 0E 0F	10 11 12 13 14 15 16 17	18 19 1A 1B 1C 1D 1E 1F	20 21 22 23 24 25 26 27	28 29 2A 2B 2C 2D 2E 2F	30 31 32 33 34 35 36 37	38 39 3A 3B 3C 3D 3E 3F
[BX+SI]+disp8 [BX+DI]+disp8 [BP+SI]+disp8 [BP+DI]+disp8 [SI]+disp8 [DI]+disp8 [BP]+disp8 [BX]+disp8	01	000 001 010 011 100 101 110 111	40 41 42 43 44 45 46 47	48 49 4A 4B 4C 4D 4E 4F	50 51 52 53 54 55 56 57	58 59 5A 5B 5C 5D 5E 5F	60 61 62 63 64 65 66 67	68 69 6A 6B 6C 6D 6E 6F	70 71 72 73 74 75 76 77	78 79 7A 7B 7C 7D 7E 7F
[BX+SI]+disp16 [BX+DI]+disp16 [BP+SI]+disp16 [BP+DI]+disp16 [SI]+disp16 [DI]+disp16 [BP]+disp16 [BX]+disp16	10	000 001 010 011 100 101 110 111	80 81 82 83 84 85 86 87	88 89 8A 8B 8C 8D 8E 8F	90 91 92 93 94 95 96 97	98 99 9A 9B 9C 9D 9E 9F	A0 A1 A2 A3 A4 A5 A6 A7	A8 A9 AA AB AC AD AE AF	B0 B1 B2 B3 B4 B5 B6 B7	B8 B9 BA BB BC BD BE BF
EAX/AX/AL ECX/CX/CL EDX/DX/DL EBX/BX/BL ESP/SP/AH EBP/BP/CH ESI/SI/DH EDI/DI/BH	11	000 001 010 011 100 101 110 111	C0 C1 C2 C3 C4 C5 C6 C7	C8 C9 CA CB CC CD CE CF	D0 D1 D2 D3 D4 D5 D6 D7	D8 D9 DA DB DC DD DE DF	E0 E1 E2 E3 E4 E5 E6 E7	E8 E9 EA EB EC ED EE EF	F0 F1 F2 F3 F4 F5 F6 F7	F8 F9 FA FB FC FD FE FF

## NOTES:

- disp8** denotes an 8-bit displacement following the ModR/M byte, to be sign-extended and added to the index.
- disp16** denotes a 16-bit displacement following the ModR/M byte, to be added to the index. Default segment register is SS for the effective addresses containing a BP index, DS for other effective addresses.

**Table 25-3. 32-Bit Addressing Forms with the ModR/M Byte**

r8(/r) r16(/r) r32(/r) /digit (Opcode) REG =	AL AX EAX 0 000	CL CX ECX 1 001	DL DX EDX 2 010	BL BX EBX 3 011	AH SP ESP 4 100	CH BP EBP 5 101	DH SI ESI 6 110	BH DI EDI 7 111		
Effective Address	Mod	R/M	ModR/M Values in Hexadecimal							
[EAX] [ECX] [EDX] [EBX] <sub>1</sub> [--][--] <sup>1</sup> disp32 [ESI] [EDI]	00	000 001 010 011 100 101 110 111	00 01 02 03 04 05 06 07	08 09 0A 0B 0C 0D 0E 0F	10 11 12 13 14 15 16 17	18 19 1A 1B 1C 1D 1E 1F	20 21 22 23 24 25 26 27	28 29 2A 2B 2C 2D 2E 2F	30 31 32 33 34 35 36 37	38 39 3A 3B 3C 3D 3E 3F
disp8[EAX] disp8[ECX] disp8[EDX] disp8[EBX]; disp8[--][--] disp8[EBP] disp8[ESI] disp8[EDI]	01	000 001 010 011 100 101 110 111	40 41 42 43 44 45 46 47	48 49 4A 4B 4C 4D 4E 4F	50 51 52 53 54 55 56 57	58 59 5A 5B 5C 5D 5E 5F	60 61 62 63 64 65 66 67	68 69 6A 6B 6C 6D 6E 6F	70 71 72 73 74 75 76 77	78 79 7A 7B 7C 7D 7E 7F
disp32[EAX] disp32[ECX] disp32[EDX] disp32[EBX] disp32[--][--] disp32[EBP] disp32[ESI] disp32[EDI]	10	000 001 010 011 100 101 110 111	80 81 82 83 84 85 86 87	88 89 8A 8B 8C 8D 8E 8F	90 91 92 93 94 95 96 97	98 99 9A 9B 9C 9D 9E 9F	A0 A1 A2 A3 A4 A5 A6 A7	A8 A9 AA AB AC AD AE AF	B0 B1 B2 B3 B4 B5 B6 B7	B8 B9 BA BB BC BD BE BF
EAX/AX/AL ECX/CX/CL EDX/DX/DL EBX/BX/BL ESP/SP/AH EBP/BP/CH ESI/SI/DH EDI/DI/BH	11	000 001 010 011 100 101 110 111	C0 C1 C2 C3 C4 C5 C6 C7	C8 C9 CA CB CC CD CE CF	D0 D1 D2 D3 D4 D5 D6 D7	D8 D9 DA DB DC DD DE DF	E0 E1 E2 E3 E4 E5 E6 E7	E8 E9 EA EB EC ED EE EF	F0 F1 F2 F3 F4 F5 F6 F7	F8 F9 FA FB FC FD FE FF

**NOTES:**

- <sup>1</sup> [--][--] means a SIB follows the ModR/M byte.
- <sup>2</sup> **disp8** denotes an 8-bit displacement following the SIB byte, to be sign-extended and added to the index.  
**disp32** denotes a 32-bit displacement following the SIB byte, to be added to the index.

Table 25-4. 32-Bit Addressing Forms with the SIB Byte

r32 Base = Base =			EAX 0 000	ECX 1 001	EDX 2 010	EBX 3 011	ESP 4 100	[*] 5 101	ESI 6 110	EDI 7 111
Scaled Index	SS	Index	SIB Values in Hexadecimal							
[EAX]	00	000	00	01	02	03	04	05	06	07
[ECX]		001	08	09	0A	0B	0C	0D	0E	0F
[EDX]		010	10	11	12	13	14	15	16	17
[EBX]		011	18	19	1A	1B	1C	1D	1E	1F
none		100	20	21	22	23	24	25	26	27
[EBP]		101	28	29	2A	2B	2C	2D	2E	2F
[ESI]		110	30	31	32	33	34	35	36	37
[EDI]		111	38	39	3A	3B	3C	3D	3E	3F
[EAX*2]	01	000	40	41	42	43	44	45	46	47
[ECX*2]		001	48	49	4A	4B	4C	4D	4E	4F
[ECX*2]		010	50	51	52	53	54	55	56	57
[EBX*2]		011	58	59	5A	5B	5C	5D	5E	5F
none		100	60	61	62	63	64	65	66	67
[EBP*2]		101	68	69	6A	6B	6C	6D	6E	6F
[ESI*2]		110	70	71	72	73	74	75	76	77
[EDI*2]		111	78	79	7A	7B	7C	7D	7E	7F
[EAX*4]	10	000	80	81	82	83	84	85	86	87
[ECX*4]		001	88	89	8A	8B	8C	8D	8E	8F
[EDX*4]		010	90	91	92	93	94	95	96	97
[EBX*4]		011	98	99	9A	9B	9C	9D	9E	9F
none		100	A0	A1	A2	A3	A4	A5	A6	A7
[EBP*4]		101	A8	A9	AA	AB	AC	AD	AE	AF
[ESI*4]		110	B0	B1	B2	B3	B4	B5	B6	B7
[EDI*4]		111	B8	B9	BA	BB	BC	BD	BE	BF
[EAX*8]	11	000	C0	C1	C2	C3	C4	C5	C6	C7
[ECX*8]		001	C8	C9	CA	CB	CC	CD	CE	CF
[EDX*8]		010	D0	D1	D2	D3	D4	D5	D6	D7
[EBX*8]		011	D8	D9	DA	DB	DC	DD	DE	DF
none		100	E0	E1	E2	E3	E4	E5	E6	E7
[EBP*8]		101	E8	E9	EA	EB	EC	ED	EE	EF
[ESI*8]		110	F0	F1	F2	F3	F4	F5	F6	F7
[EDI*8]		111	F8	F9	FA	FB	FC	FD	FE	FF

**NOTES:**

[\*] means a disp32 with no base if MOD is 00, [EBP] otherwise. This provides the following addressing modes:

disp32[index] (MOD=00)

disp8[EBP][index] (MOD=01)

disp32[EBP][index] (MOD=10)

## 25.2.2. How to Read the Instruction Set Pages

The following is an example of the format used for each processor instruction description in this chapter:

### CMC—Complement Carry Flag

Opcode	Instruction	Clocks	Description
F5	CMC	2	Complement carry flag

The above table is followed by paragraphs labeled "Operation," "Description," "Flags Affected," "Protected Mode Exceptions," "Real Address Mode Exceptions," and, optionally, "Notes." The following sections explain the notational conventions and abbreviations used in these paragraphs of the instruction descriptions.

#### 25.2.2.1. OPCODE COLUMN

The "Opcode" column gives the complete object code produced for each form of the instruction. When possible, the codes are given as hexadecimal bytes, in the same order in which they appear in memory. Definitions of entries other than hexadecimal bytes are as follows:

- **/digit:** (digit is between 0 and 7) indicates that the ModR/M byte of the instruction uses only the *r/m* (register or memory) operand. The **reg** field contains the digit that provides an extension to the instruction's opcode.
- **/r:** indicates that the ModR/M byte of the instruction contains both a register operand and an *r/m* operand.
- **cb, cw, cd, cp:** a 1-byte (cb), 2-byte (cw), 4-byte (cd) or 6-byte (cp) value following the opcode that is used to specify a code offset and possibly a new value for the code segment register.
- **ib, iw, id:** a 1-byte (ib), 2-byte (iw), or 4-byte (id) immediate operand to the instruction that follows the opcode, ModR/M bytes or scale-indexing bytes. The opcode determines if the operand is a signed value. All words and doublewords are given with the low-order byte first.

- **+rb, +rw, +rd:** a register code, from 0 through 7, added to the hexadecimal byte given at the left of the plus sign to form a single opcode byte. The codes are—

rb		rw		rd	
AL	= 0	AX	= 0	EAX	= 0
CL	= 1	CX	= 1	ECX	= 1
DL	= 2	DX	= 2	EDX	= 2
BL	= 3	BX	= 3	EBX	= 3

rb		rw		rd	
AH	= 4	SP	= 4	ESP	= 4
CH	= 5	BP	= 5	EBP	= 5
DH	= 6	SI	= 6	ESI	= 6
BH	= 7	DI	= 7	EDI	= 7

- **+i:** used in floating-point instructions when one of the operands is ST(i) from the FPU register stack. The number i (which can range from 0 to 7) is added to the hexadecimal byte given at the left of the plus sign to form a single opcode byte.

#### 25.2.2.2. INSTRUCTION COLUMN

The "Instruction" column gives the syntax of the instruction statement as it would appear in an ASM386 program. The following is a list of the symbols used to represent operands in the instruction statements:

- **rel8:** a relative address in the range from 128 bytes before the end of the instruction to 127 bytes after the end of the instruction.
- **rel16, rel32:** a relative address within the same code segment as the instruction assembled. **rel16** applies to instructions with an operand-size attribute of 16 bits; **rel32** applies to instructions with an operand-size attribute of 32 bits.
- **ptr16:16, ptr16:32:** a far pointer, typically in a code segment different from that of the instruction. The notation **16:16** indicates that the value of the pointer has two parts. The value to the left of the colon is a 16-bit selector or value destined for the code segment register. The value to the right corresponds to the offset within the destination segment. **ptr16:16** is used when the instruction's operand-size attribute is 16 bits; **ptr16:32** is used with the 32-bit attribute.
- **r8:** one of the byte registers AL, CL, DL, BL, AH, CH, DH, or BH.
- **r16:** one of the word registers AX, CX, DX, BX, SP, BP, SI, or DI.
- **r32:** one of the doubleword registers EAX, ECX, EDX, EBX, ESP, EBP, ESI, or EDI.
- **imm8:** an immediate byte value. **imm8** is a signed number between -128 and +127 inclusive. For instructions in which **imm8** is combined with a word or doubleword

operand, the immediate value is sign-extended to form a word or doubleword. The upper byte of the word is filled with the topmost bit of the immediate value.

- **imm16:** an immediate word value used for instructions whose operand-size attribute is 16 bits. This is a number between  $-32768$  and  $+32767$  inclusive.
- **imm32:** an immediate doubleword value used for instructions whose operand-size attribute is 32 bits. It allows the use of a number between  $+2147483647$  and  $-2147483648$  inclusive.
- **r/m8:** a one-byte operand that is either the contents of a byte register (AL, BL, CL, DL, AH, BH, CH, DH), or a byte from memory.
- **r/m16:** a word register or memory operand used for instructions whose operand-size attribute is 16 bits. The word registers are: AX, BX, CX, DX, SP, BP, SI, DI. The contents of memory are found at the address provided by the effective address computation.
- **r/m32:** a doubleword register or memory operand used for instructions whose operand-size attribute is 32 bits. The doubleword registers are: EAX, EBX, ECX, EDX, ESP, EBP, ESI, EDI. The contents of memory are found at the address provided by the effective address computation.
- **r/m64:** a quadword register or memory operand used for instructions whose operand-size attribute is 64 bits. The reg/opcode field represents the opcode. The contents of memory are found at the address provided by the effective address computation.
- **m:** a 16- or 32-bit memory operand.
- **m8:** a memory byte addressed by DS:[E]SI or ES:[E]DI (used only by string instructions).
- **m16:** a memory word addressed by DS:[E]SI or ES:[E]DI (used only by string instructions).
- **m32:** a memory doubleword addressed by DS:[E]SI or ES:[E]DI (used only by string instructions).
- **m16:16, m16:32:** a memory operand containing a far pointer composed of two numbers. The number to the left of the colon corresponds to the pointer's segment selector. The number to the right corresponds to its offset.
- **m16&32, m16&16, m32&32:** a memory operand consisting of data item pairs whose sizes are indicated on the left and the right side of the ampersand. All memory addressing modes are allowed. **m16&16** and **m32&32** operands are used by the BOUND instruction to provide an operand containing an upper and lower bounds for array indices. **m16&32** is used by LIDT and LGDT to provide a word with which to load the limit field, and a doubleword with which to load the base field of the corresponding Global and Interrupt Descriptor Table Registers.
- **mooffs8, mooffs16, mooffs32:** (memory offset) a simple memory variable of type BYTE, WORD, or DWORD used by some variants of the MOV instruction. The actual address is given by a simple offset relative to the segment base. No ModR/M byte is used in the

instruction. The number shown with **moffs** indicates its size, which is determined by the address-size attribute of the instruction.

- **Sreg**: a segment register. The segment register bit assignments are ES=0, CS=1, SS=2, DS=3, FS=4, and GS=5.
- **m32real**, **m64real**, **m80real**: (respectively) single-, double-, and extended-real floating-point operands in memory.
- **m16int**, **m32int**, **m64int**: (respectively) word-, short-, and long-integer floating-point operands in memory.
- **mNbyte**: *N*-byte floating-point operand in memory.
- **ST** or **ST(0)**: Top element of the FPU register stack.
- **ST(i)**: *i*<sup>th</sup> element from the top of the FPU register stack. (*i*=0..7)

### 25.2.2.3. CLOCKS COLUMN

The "Clocks" column gives the approximate number of clock cycles the instruction takes to execute. The clock count calculations makes the following assumptions:

- Data and instruction accesses hit in the cache.
- The target of a jump instruction is in the cache.
- No invalidate cycles contend with the instruction for use of the cache.
- Page translation hits in the TLB.
- Memory operands are aligned.
- Effective address calculations use a base register which is not the destination register of the preceding instruction.
- No exceptions are detected during execution.
- There are no write-buffer delays.

For a discussion of the performance penalties incurred when these conditions do not hold, see Appendix F.

The following symbols are used in the clock count specifications:

- **n**, which represents a number of repetitions.
- **m**, which represents the number of components in the next instruction executed, where the entire displacement (if any) counts as one component, the entire immediate data (if any) counts as one component, and every other byte of the instruction and prefix(es) each counts as one component.
- **pm=**, a clock count that applies when the instruction executes in Protected Mode. **pm=** is not given when the clock counts are the same for Protected and Real Address Modes.



When an exception occurs during the execution of an instruction and the exception handler is in another task, the instruction execution time is increased by the number of clocks to effect a task switch. This parameter depends on several factors:

- The type of TSS used to represent the new task (32-bit TSS or 16-bit TSS).
- Whether the current task is in V86 mode.
- Whether the new task is in V86 mode.
- Whether accesses hit in the cache.
- Whether a task gate on an interrupt/trap gate is used.

Table 25-5 summarizes the task switch times for exceptions, assuming cache hits and the use of task gates. For full details, see Appendix F.

**Table 25-5. Task Switch Times for Exceptions**

Old Task	New Task		
	To 32 Bit TSS	To 16 Bit TSS	To VM TSS
VM/32-bit/16-bit TSS	85	87	71

**25.2.2.4. DESCRIPTION COLUMN**

The "Description" column following the "Clocks" column briefly explains the various forms of the instruction. The "Operation" and "Description" sections contain more details of the instruction's operation.

**25.2.2.5. OPERATION**

The "Operation" section contains an algorithmic description of the instruction which uses a notation similar to the Algol or Pascal language. The algorithms are composed of the following elements:

- Comments are enclosed within the symbol pairs "(" and "\*").
- Compound statements are enclosed between the keywords of the "if" statement (IF, THEN, ELSE, FI) or of the "do" statement (DO, OD), or of the "case" statement (CASE ... OF, ESAC).
- Execution continues until the END statement is encountered.
- A register name implies the contents of the register. A register name enclosed in brackets implies the contents of the location whose address is contained in that register. For example, ES:[DI] indicates the contents of the location whose ES segment relative address is in register DI. [SI] indicates the contents of the address contained in register SI relative to SI's default segment (DS) or overridden segment.



- Brackets are also used for memory operands, where they mean that the contents of the memory location is a segment-relative offset. For example, [SRC] indicates that the contents of the source operand is a segment-relative offset.
- $A \leftarrow B$ ; indicates that the value of B is assigned to A.
- The symbols =, <>, ≥, and ≤ are relational operators used to compare two values, meaning equal, not equal, greater or equal, less or equal, respectively. A relational expression such as  $A = B$  is TRUE if the value of A is equal to B; otherwise it is FALSE.



The following identifiers are used in the algorithmic descriptions:

- **OperandSize** represents the operand-size attribute of the instruction, which is either 16 or 32 bits. **AddressSize** represents the address-size attribute, which is either 16 or 32 bits. For example,
 

```
IF instruction = CMPSW
THEN OperandSize ← 16;
ELSE
  IF instruction = CMPSD
  THEN OperandSize ← 32;
FI;
```

 indicates that the operand-size attribute depends on the form of the CMPS instruction used. Refer to the explanation of address-size and operand-size attributes at the beginning of this chapter for general guidelines on how these attributes are determined.
- **StackAddrSize** represents the stack address-size attribute associated with the instruction, which has a value of 16 or 32 bits, as explained earlier in the chapter.
- **SRC** represents the source operand. When there are two operands, SRC is the one on the right.
- **DEST** represents the destination operand. When there are two operands, DEST is the one on the left.
- **LeftSRC**, **RightSRC** distinguishes between two operands when both are source operands.
- **eSP** represents either the SP register or the ESP register depending on the setting of the B-bit for the current stack segment.

The following functions are used in the algorithmic descriptions:

- **Truncate to 16 bits(value)** reduces the size of the value to fit in 16 bits by discarding the uppermost bits as needed.
- **Addr(operand)** returns the effective address of the operand (the result of the effective address calculation prior to adding the segment base).
- **ZeroExtend(value)** returns a value zero-extended to the operand-size attribute of the instruction. For example, if **OperandSize** = 32, **ZeroExtend** of a byte value of **-10** converts the byte from **F6H** to doubleword with hexadecimal value **000000F6H**. If the value passed to **ZeroExtend** and the operand-size attribute are the same size, **ZeroExtend** returns the value unaltered.
- **SignExtend(value)** returns a value sign-extended to the operand-size attribute of the instruction. For example, if **OperandSize** = 32, **SignExtend** of a byte containing the value **-10** converts the byte from **F6H** to a doubleword with hexadecimal value **FFFFFFF6H**. If the value passed to **SignExtend** and the operand-size attribute are the same size, **SignExtend** returns the value unaltered.

- **Push(value)** pushes a value onto the stack. The number of bytes pushed is determined by the operand-size attribute of the instruction. The action of Push is as follows:

```

IF StackAddrSize = 16
THEN
    IF OperandSize = 16
    THEN
        SP ← SP - 2;
        SS:[SP] ← value; (* 2 bytes assigned starting at byte address in SP *)
    ELSE (* OperandSize = 32 *)
        SP ← SP - 4;
        SS:[SP] ← value; (* 4 bytes assigned starting at byte address in SP *)
    FI;
ELSE (* StackAddrSize = 32 *)
    IF OperandSize = 16
    THEN
        ESP ← ESP - 2;
        SS:[ESP] ← value; (* 2 bytes assigned starting at byte address in ESP*)
    ELSE (* OperandSize = 32 *)
        ESP ← ESP - 4;
        SS:[ESP] ← value; (* 4 bytes assigned starting at byte address in ESP*)
    FI;
FI;

```

- **Pop(value)** removes the value from the top of the stack and returns it. The statement  $EAX \leftarrow \text{Pop}( )$ ; assigns to EAX the 32-bit value that Pop took from the top of the stack. Pop will return either a word or a doubleword depending on the operand-size attribute. The action of Pop is as follows:

```

IF StackAddrSize = 16
THEN
    IF OperandSize = 16
    THEN
        ret val ← SS:[SP]; (* 2-byte value *)
        SP ← SP + 2;
    ELSE (* OperandSize = 32 *)
        ret val ← SS:[SP]; (* 4-byte value *)
        SP ← SP + 4;
    FI;
ELSE (* StackAddrSize = 32 *)
    IF OperandSize = 16
    THEN
        ret val ← SS:[ESP]; (* 2 byte value *)
        ESP ← ESP + 2;
    ELSE (* OperandSize = 32 *)
        ret val ← SS:[ESP]; (* 4 byte value *)
        ESP ← ESP + 4;
    FI;
FI;

```



FI;  
RETURN(ret val); (\*returns a word or doubleword\*)

Pop ST is used on floating-point instruction pages to mean *pop the FPU register stack*.

- **Bit[BitBase, BitOffset]** returns the value of a bit within a bit string, which is a sequence of bits in memory or a register. Bits are numbered from low-order to high-order within registers and within memory bytes. In memory, the two bytes of a word are stored with the low-order byte at the lower address.

If the base operand is a register, the offset can be in the range 0..31. This offset addresses a bit within the indicated register. An example, 'BIT[EAX, 21]' is illustrated in Figure 25-3.

If BitBase is a memory address, BitOffset can range from -2 gigabits to 2 gigabits. The addressed bit is numbered (Offset MOD 8) within the byte at address (BitBase + (BitOffset DIV 8)), where DIV is signed division with rounding towards negative infinity, and MOD returns a positive number. This is illustrated in Figure 25-4.

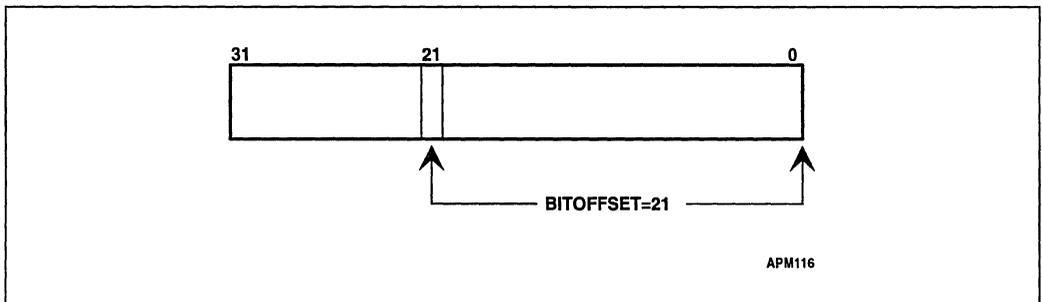
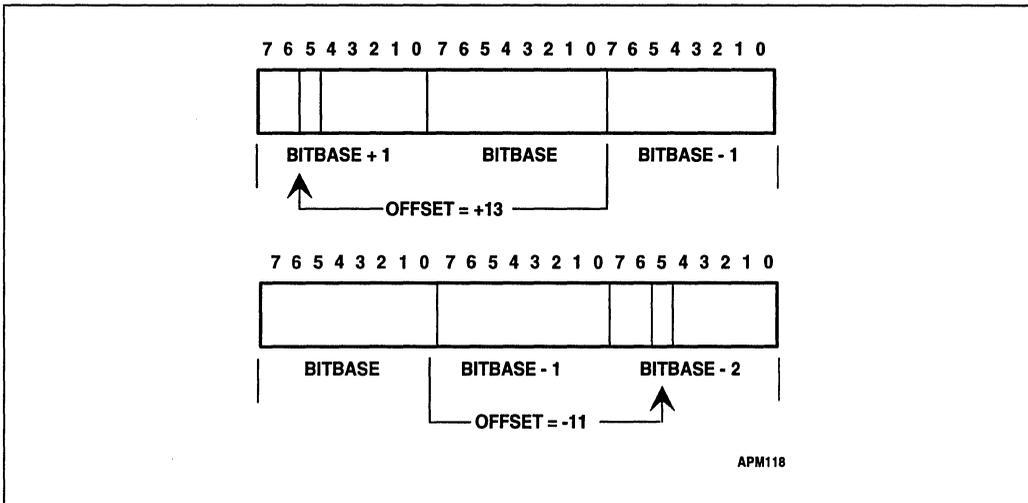


Figure 25-3. Bit Offset for BIT[EAX,21]



**Figure 25-4. Memory Bit Indexing**

- **I-O-Permission(I-O-Address, width)** returns TRUE or FALSE depending on the I/O permission bitmap and other factors. This function is defined as follows:  
 IF TSS type is 16 bit THEN RETURN FALSE; FI;  
 Ptr ← [TSS + 66]; (\* fetch bitmap pointer \*)  
 BitStringAddr ← SHR (I-O-Address, 3) + Ptr;  
 MaskShift ← I-O-Address AND 7;  
 CASE width OF:  
   BYTE: nBitMask ← 1;  
   WORD: nBitMask ← 3;  
   DWORD: nBitMask ← 15;  
 ESAC;  
 mask ← SHL (nBitMask, MaskShift);  
 CheckString ← [BitStringAddr] AND mask;  
 IF CheckString = 0  
 THEN RETURN (TRUE);  
 ELSE RETURN (FALSE);  
 FI;
- **Switch-Tasks** is the task switching function described in Chapter 13.

#### 25.2.2.6. DESCRIPTION

The "Description" section contains further explanation of the instruction's operation.

#### 25.2.2.7. FLAGS AFFECTED

The "Flags Affected" section lists the flags that are affected by the instruction, as follows:

- If a flag is always cleared or always set by the instruction, the value is given (0 or 1) after the flag name. Arithmetic and logical instructions usually assign values to the status flags in the uniform manner described in Appendix C. Nonconventional assignments are described in the "Operation" section.
- The values of flags listed as "undefined" may be changed by the instruction in an indeterminate manner.

All flags not listed are unchanged by the instruction.

The floating-point instruction pages have a section called "FPU Flags Affected," which tells how each instruction can affect the four condition code bits of the FPU status word. These pages also have a section called "Numeric Exceptions," which lists the exception flags of the FPU status word that each instruction can set.

### 25.2.2.8. PROTECTED MODE EXCEPTIONS

This section lists the exceptions that can occur when the instruction is executed in protected mode. The exception names are a pound sign (#) followed by two letters and an optional error code in parentheses. For example, #GP(0) denotes a general protection exception with an error code of 0. Table 25-6 associates each two-letter name with the corresponding interrupt number.

**Table 25-6. Exceptions**

Mnemonic	Interrupt	Description
#UD	6	Invalid opcode
#NM	7	Device not available
#DF	8	Double fault
#TS	10	Invalid TSS
#NP	11	Segment or gate not present
#SS	12	Stack fault
#GP	13	General protection fault
#PF	14	Page fault
#MF	16	Floating-point error
#AC	17	Alignment check

Chapter 14 describes the exceptions and the processor state upon entry to the exception.

Application programmers should consult the documentation provided with their operating systems to determine the actions taken when exceptions occur.

### **25.2.2.9. REAL ADDRESS MODE EXCEPTIONS**

Because less error checking is performed by the Pentium processor in Real Address Mode, this mode has fewer exception conditions. Refer to Chapter 9 for further information on these exceptions.

### **25.2.2.10. VIRTUAL-8086 MODE EXCEPTIONS**

Virtual 8086 tasks provide the ability to simulate Virtual 8086 machines. Virtual 8086 Mode exceptions are similar to those for the 8086 processor, but there are some differences. Refer to Chapter 22 for complete information on Virtual Mode exceptions.

## AAA—ASCII Adjust after Addition

Opcode	Instruction	Clocks	Description
37	AAA	3	ASCII adjust AL after addition

### Operation

```

ALcarry ← AL > 0F9H; (* 1 if true *)
IF ((AL AND 0FH) > 9) OR (AF = 1)
THEN
    AL ← (AL + 6) AND 0FH;
    AH ← AH + 1 + ALcarry;
    AF ← 1;
    CF ← 1;
ELSE
    AF ← 0;
    CF ← 0;
    AL ← AL AND 0FH;
FI;

```

### Description

Execute the AAA instruction only following an ADD instruction that leaves a byte result in the AL register. The lower nibbles of the operands of the ADD instruction should be in the range 0 through 9 (BCD digits). In this case, the AAA instruction adjusts the AL register to contain the correct decimal digit result. If the addition produced a decimal carry, the AH register is incremented, and the CF and AF flags are set. If this same addition also produced FH in the upper nibble of AL then AH is incremented again. If there was no decimal carry, the CF and AF flags are cleared and the AH register is unchanged. In either case, the AL register is left with its top nibble set to 0. To convert the AL register to an ASCII result, follow the AAA instruction with OR AL, 30H.

### Flags Affected

The AF and CF flags are set if there is a decimal carry, cleared if there is no decimal carry; the OF, SF, ZF, and PF flags are undefined.

### Protected Mode Exceptions

None.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.



## AAD—ASCII Adjust AX before Division

Opcode	Instruction	Clocks	Description
D5 0A	AAD	10	ASCII adjust AX before division

### Operation

regAL = AL;  
 regAH = AH;  
 $AL \leftarrow (\text{regAH} * \text{imm8} + \text{regAL}) \text{ AND } 0\text{FFH}$ ;  
 AH  $\leftarrow$  0;

### NOTE:

imm8 has the value of the instruction's second byte. The second byte under normally assembly of this instruction will be 0A, however, explicit modification of this byte will result in the operation described above and may alter results.

### Description

The AAD instruction is used to prepare two unpacked BCD digits (the least-significant digit in the AL register, the most-significant digit in the AH register) for a division operation that will yield an unpacked result. This is accomplished by setting the AL register to  $AL +$  (second byte of opcode \* AH), and then clearing the AH register. The AX register is then equal to the binary equivalent of the original unpacked two-digit number.

### Flags Affected

The SF, ZF, and PF flags are set according to the result; the OF, AF, and CF flags are undefined.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

**AAM—ASCII Adjust AX after Multiply**

Opcode	Instruction	Clocks	Description
D4 0A	AAM	18	ASCII adjust AX after multiply

**Operation**

$\text{regAL} \leftarrow \text{AL};$   
 $\text{AH} \leftarrow \text{regAL} / \text{imm8};$   
 $\text{AL} \leftarrow \text{regAL} \text{ MOD } \text{imm8};$

**NOTE:**

imm8 has the value of the instruction's second byte. The second byte under normally assembly of this instruction will be 0A, however, explicit modification of this byte will result in the operation described above and may alter results.

**Description**

Execute the AAM instruction only after executing a MUL instruction between two unpacked BCD digits that leaves the result in the AX register. Because the result is less than 100, it is contained entirely in the AL register. The AAM instruction unpacks the AL result by dividing AL by the second byte of the opcode, leaving the quotient (most-significant digit) in the AH register and the remainder (least-significant digit) in the AL register.

**Flags Affected**

The SF, ZF, and PF flags are set according to the result; the OF, AF, and CF flags are undefined.

**Protected Mode Exceptions**

None.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.



## AAS—ASCII Adjust AL after Subtraction

Opcode	Instruction	Clocks	Description
3F	AAS	3	ASCII adjust AL after subtraction

### Operation

$AL_{borrow} \leftarrow AL < 6; \quad (* 1 \text{ if true } *)$

IF  $(AL \text{ AND } 0FH) > 9$  OR  $AF = 1$

THEN

$AL \leftarrow (AL - 6) \text{ AND } 0FH;$

$AH \leftarrow AH - 1 - AL_{borrow};$

$AF \leftarrow 1;$

$CF \leftarrow 1;$

ELSE

$CF \leftarrow 0;$

$AF \leftarrow 0;$

$AL \leftarrow AL \text{ AND } 0FH;$

FI;

### Description

Execute the AAS instruction only after a SUB instruction that leaves the byte result in the AL register. The lower nibbles of the operands of the SUB instruction must have been in the range 0 through 9 (BCD digits). In this case, the AAS instruction adjusts the AL register so it contains the correct decimal digit result. If the subtraction produced a decimal carry, the AH register is decremented, and the CF and AF flags are set. If no decimal carry occurred, the CF and AF flags are cleared, and the AH register is unchanged. In either case, the AL register is left with its top nibble set to 0. To convert the AL result to an ASCII result, follow the AAS instruction with OR AL, 30H.

### Flags Affected

The AF and CF flags are set if there is a decimal carry, cleared if there is no decimal carry; the OF, SF, ZF, and PF flags are undefined.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

**Virtual 8086 Mode Exceptions**

None.



## ADC—Add with Carry

Opcode	Instruction	Clocks	Description
14 <i>ib</i>	ADC AL, <i>imm8</i>	1	Add with carry immediate byte to AL
15 <i>iw</i>	ADC AX, <i>imm16</i>	1	Add with carry immediate word to AX
15 <i>id</i>	ADC EAX, <i>imm32</i>	1	Add with carry immediate dword to EAX
80 /2 <i>ib</i>	ADC <i>r/m8</i> , <i>imm8</i>	1/3	Add with carry immediate byte to <i>r/m</i> byte
81 /2 <i>iw</i>	ADC <i>r/m16</i> , <i>imm16</i>	1/3	Add with carry immediate word to <i>r/m</i> word
81 /2 <i>id</i>	ADC <i>r/m32</i> , <i>imm32</i>	1/3	Add with CF immediate dword to <i>r/m</i> dword
83 /2 <i>ib</i>	ADC <i>r/m16</i> , <i>imm8</i>	1/3	Add with CF sign-extended immediate byte to <i>r/m</i> word
83 /2 <i>ib</i>	ADC <i>r/m32</i> , <i>imm8</i>	1/3	Add with CF sign-extended immediate byte into <i>r/m</i> dword
10 <i>r</i>	ADC <i>r/m8</i> , <i>r8</i>	1/3	Add with carry byte register to <i>r/m</i> byte
11 <i>r</i>	ADC <i>r/m16</i> , <i>r16</i>	1/3	Add with carry word register to <i>r/m</i> word
11 <i>r</i>	ADC <i>r/m32</i> , <i>r32</i>	1/3	Add with CF dword register to <i>r/m</i> dword
12 <i>r</i>	ADC <i>r8</i> , <i>r/m8</i>	1/2	Add with carry <i>r/m</i> byte to byte register
13 <i>r</i>	ADC <i>r16</i> , <i>r/m16</i>	1/2	Add with carry <i>r/m</i> word to word register
13 <i>r</i>	ADC <i>r32</i> , <i>r/m32</i>	1/2	Add with CF <i>r/m</i> dword to dword register

### Operation

DEST ← DEST + SRC + CF;

### Description

The ADC instruction performs an integer addition of the two operands DEST and SRC and the carry flag, CF. The result of the addition is assigned to the first operand (DEST), and the flags are set accordingly. The ADC instruction is usually executed as part of a multi-byte or multi-word addition operation. When an immediate byte value is added to a word or doubleword operand, the immediate value is first sign-extended to the size of the word or doubleword operand.

### Flags Affected

The OF, SF, ZF, AF, CF, and PF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## ADD—Add

Opcode	Instruction	Clocks	Description
04 <i>ib</i>	ADD AL, <i>imm8</i>	1	Add immediate byte to AL
05 <i>iw</i>	ADD AX, <i>imm16</i>	1	Add immediate word to AX
05 <i>id</i>	ADD EAX, <i>imm32</i>	1	Add immediate dword to EAX
80 /0 <i>ib</i>	ADD <i>r/m8</i> , <i>imm8</i>	1/3	Add immediate byte to <i>r/m</i> byte
81 /0 <i>iw</i>	ADD <i>r/m16</i> , <i>imm16</i>	1/3	Add immediate word to <i>r/m</i> word
81 /0 <i>id</i>	ADD <i>r/m32</i> , <i>imm32</i>	1/3	Add immediate dword to <i>r/m</i> dword
83 /0 <i>ib</i>	ADD <i>r/m16</i> , <i>imm8</i>	1/3	Add sign-extended immediate byte to <i>r/m</i> word
83 /0 <i>ib</i>	ADD <i>r/m32</i> , <i>imm8</i>	1/3	Add sign-extended immediate byte to <i>r/m</i> dword
00 <i>lr</i>	ADD <i>r/m8</i> , <i>r8</i>	1/3	Add byte register to <i>r/m</i> byte
01 <i>lr</i>	ADD <i>r/m16</i> , <i>r16</i>	1/3	Add word register to <i>r/m</i> word
01 <i>lr</i>	ADD <i>r/m32</i> , <i>r32</i>	1/3	Add dword register to <i>r/m</i> dword
02 <i>lr</i>	ADD <i>r8</i> , <i>r/m8</i>	1/2	Add <i>r/m</i> byte to byte register
03 <i>lr</i>	ADD <i>r16</i> , <i>r/m16</i>	1/2	Add <i>r/m</i> word to word register
03 <i>lr</i>	ADD <i>r32</i> , <i>r/m32</i>	1/2	Add <i>r/m</i> dword to dword register

### Operation

DEST ← DEST + SRC;

### Description

The ADD instruction performs an integer addition of the two operands (DEST and SRC). The result of the addition is assigned to the first operand (DEST), and the flags are set accordingly.

When an immediate byte is added to a word or doubleword operand, the immediate value is sign-extended to the size of the word or doubleword operand.

### Flags Affected

The OF, SF, ZF, AF, CF, and PF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## AND—Logical AND

Opcode	Instruction	Clocks	Description
24 <i>ib</i>	AND AL, <i>imm8</i>	1	AND immediate byte to AL
25 <i>iw</i>	AND AX, <i>imm16</i>	1	AND immediate word to AX
25 <i>id</i>	AND EAX, <i>imm32</i>	1	AND immediate dword to EAX
80 <i>/4 ib</i>	AND <i>r/m8,imm8</i>	1/3	AND immediate byte to <i>r/m</i> byte
81 <i>/4 iw</i>	AND <i>r/m16,imm16</i>	1/3	AND immediate word to <i>r/m</i> word
81 <i>/4 id</i>	AND <i>r/m32,imm32</i>	1/3	AND immediate dword to <i>r/m</i> dword
83 <i>/4 ib</i>	AND <i>r/m16,imm8</i>	1/3	AND sign-extended immediate byte with <i>r/m</i> word
83 <i>/4 ib</i>	AND <i>r/m32,imm8</i>	1/3	AND sign-extended immediate byte with <i>r/m</i> dword
20 <i>/r</i>	AND <i>r/m8,r8</i>	1/3	AND byte register to <i>r/m</i> byte
21 <i>/r</i>	AND <i>r/m16,r16</i>	1/3	AND word register to <i>r/m</i> word
21 <i>/r</i>	AND <i>r/m32,r32</i>	1/3	AND dword register to <i>r/m</i> dword
22 <i>/r</i>	AND <i>r8,r/m8</i>	1/2	AND <i>r/m</i> byte to byte register
23 <i>/r</i>	AND <i>r16,r/m16</i>	1/2	AND <i>r/m</i> word to word register
23 <i>/r</i>	AND <i>r32,r/m32</i>	1/2	AND <i>r/m</i> dword to dword register

### Operation

DEST ← DEST AND SRC;

CF ← 0;

OF ← 0;

### Description

Each bit of the result of the AND instruction is a 1 if both corresponding bits of the operands are 1; otherwise, it becomes a 0.

### Flags Affected

The CF and OF flags are cleared; the PF, SF, and ZF flags are set according to the result; the AF flag is undefined.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## ARPL—Adjust RPL Field of Selector

Opcode	Instruction	Clocks	Description
63 <i>r</i>	ARPL <i>r/m16,r16</i>	pm=7	Adjust RPL of <i>r/m16</i> to not less than RPL of <i>r16</i>

### Operation

```

IF RPL bits(0,1) of DEST < RPL bits(0,1) of SRC
THEN
    ZF ← 1;
    RPL bits(0,1) of DEST ← RPL bits(0,1) of SRC;
ELSE
    ZF ← 0;
FI;

```

### Description

The ARPL instruction has two operands. The first operand is a 16-bit memory variable or word register that contains the value of a selector. The second operand is a word register. If the RPL field ("requested privilege level"—bottom two bits) of the first operand is less than the RPL field of the second operand, the ZF flag is set and the RPL field of the first operand is increased to match the second operand. Otherwise, the ZF flag is cleared and no change is made to the first operand.

The ARPL instruction appears in operating system software, not in application programs. It is used to guarantee that a selector parameter to a subroutine does not request more privilege than the caller is allowed. The second operand of the ARPL instruction is normally a register that contains the CS selector value of the caller.

### Flags Affected

The ZF flag is set if the RPL field of the first operand is less than that of the second operand, otherwise ZF is cleared.

### Protected Mode Exceptions

#GP(0) if the result is a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6; the ARPL instruction is not recognized in Real Address Mode.

### **Virtual 8086 Mode Exceptions**

Interrupt 6; the ARPL instruction is not recognized in Virtual 8086 Mode.



## BOUND—Check Array Index Against Bounds

Opcode	Instruction	Clocks	Description
62 /r	BOUND <i>r16,m16&amp;16</i>	8 (within bounds) int+32 (out of bounds)	Check if <i>r16</i> is within bounds
62 /r	BOUND <i>r32,m32&amp;32</i>	8 (within bounds) int+32 (out of bounds)	Check if <i>r32</i> is within bounds

### Operation

IF (LeftSRC < [RightSRC] OR LeftSRC > [RightSRC + OperandSize/8])

(\* Under lower bound or over upper bound \*)

THEN Interrupt 5;

FI;

### Description

The BOUND instruction ensures that a signed array index is within the limits specified by a block of memory consisting of an upper and a lower bound. Each bound uses one word when the operand-size attribute is 16 bits and a doubleword when the operand-size attribute is 32 bits. The first operand (a register) must be greater than or equal to the first bound in memory (lower bound), and less than or equal to the second bound in memory (upper bound) plus the number of bytes occupied for the operand size. If the register is not within bounds, an Interrupt 5 occurs; the return EIP points to the BOUND instruction.

The bounds limit data structure is usually placed just before the array itself, making the limits addressable via a constant offset from the beginning of the array.

### Flags Affected

None.

### Protected Mode Exceptions

Interrupt 5 if the bounds test fails, as described above; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

The second operand must be a memory operand, not a register. If the BOUND instruction is executed with a ModR/M byte representing a register as the second operand, #UD occurs.

### Real Address Mode Exceptions

Interrupt 5 if the bounds test fails; Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH; Interrupt 6 if the second operand is a register.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**BSF—Bit Scan Forward**

Opcode	Instruction	Clocks	Description
0F BC	BSF <i>r16,r/m16</i>	6-34/6-35	Bit scan forward on <i>r/m</i> word
0F BC	BSF <i>r32,r/m32</i>	6-42/6-43	Bit scan forward on <i>r/m</i> dword

**Operation**

```

IF r/m = 0
THEN
    ZF ← 1;
    register ← UNDEFINED;
ELSE
    temp ← 0;
    ZF ← 0;
    WHILE BIT[r/m, temp] = 0
    DO
        temp ← temp + 1;
        register ← temp;
    OD;
FI;

```

**Description**

The BSF instruction scans the bits in the second word or doubleword operand starting with bit 0. The ZF flag is set if all the bits are 0; otherwise, the ZF flag is cleared and the destination register is loaded with the bit index of the first set bit.

**Flags Affected**

The ZF flag is set if all bits are 0; otherwise, the ZF flag is cleared. OF, SF, AF, PF, CF = undefined.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## BSR—Bit Scan Reverse

Opcode	Instruction	Clocks	Description
0F BD	BSR <i>r16, r/m16</i>	7-39/7-40	Bit scan reverse on <i>r/m</i> word
0F BD	BSR <i>r32, r/m32</i>	7-71/7-72	Bit scan reverse on <i>r/m</i> dword

### Operation

```

IF r/m = 0
THEN
  ZF ← 1;
  register ← UNDEFINED;
ELSE
  temp ← OperandSize – 1;
  ZF ← 0;
  WHILE BIT[r/m, temp] = 0
  DO
    temp ← temp – 1;
    register ← temp;
  OD;
FI;
  
```

### Description

The BSR instruction scans the bits in the second word or doubleword operand from the most significant bit to the least significant bit. The ZF flag is set if all the bits are 0; otherwise, the ZF flag is cleared and the destination register is loaded with the bit index of the first set bit found when scanning in the reverse direction.

### Flags Affected

The ZF flag is set if all bits are 0; otherwise, the ZF flag is cleared. OS, SF, AF, PF, CF = undefined.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



**BSWAP—Byte Swap**

Opcode	Instruction	Clocks	Description
0F C8+rd	BSWAP r32	1	Swap bytes to convert little/big endian data in a 32-bit register to big/little endian form.

**Operation**

TEMP ← r32

r32(7..0) ← TEMP(31..24)

r32(15..8) ← TEMP(23..16)

r32(23..16) ← TEMP(15..8)

r32(31..24) ← TEMP(7..0)

**Description**

The BSWAP instruction reverses the byte order of a 32-bit register, converting a value in little/big endian form to big/little endian form. When BSWAP is used with 16-bit operand size, the result left in the destination register is undefined.

**Flags Affected**

None.

**Protected Mode Exceptions**

None.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.

**Notes**

BSWAP is not supported on Intel386 processors. Include functionally-equivalent code for Intel386 CPU's.

**BT—Bit Test**

Opcode	Instruction	Clocks	Description
0F A3	BT <i>r/m16,r16</i>	4/9	Save bit in carry flag
0F A3	BT <i>r/m32,r32</i>	4/9	Save bit in carry flag
0F BA /4 <i>ib</i>	BT <i>r/m16,imm8</i>	4	Save bit in carry flag
0F BA /4 <i>ib</i>	BT <i>r/m32,imm8</i>	4	Save bit in carry flag

**Operation**

CF ← BIT[LeftSRC, RightSRC];

**Description**

The BT instruction saves the value of the bit indicated by the base (first operand) and the bit offset (second operand) into the CF flag.

**Flags Affected**

The CF flag contains the value of the selected bit.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

The index of the selected bit can be given by the immediate constant in the instruction or by a value in a general register. Only an 8-bit immediate value is used in the instruction. This operand is taken modulo 32, so the range of immediate bit offsets is 0..31. This allows any bit within a register to be selected. For memory bit strings, this immediate field gives only the bit offset within a word or doubleword.

Immediate bit offsets larger than 31 are supported by some assemblers by using the immediate bit offset field in combination with the displacement field of the memory operand.

In this case, the low-order 3 to 5 bits (3 for 16-bit operands, 5 for 32-bit operands) of the immediate bit offset are stored in the immediate bit offset field, and the high-order bits are shifted and combined with the byte displacement in the addressing mode by the assembler. The processor will ignore the high order bits if they are not zero.

When accessing a bit in memory, the processor may access four bytes starting from the memory address given by:

$$\text{Effective Address} + (4 * (\text{BitOffset DIV } 32))$$

for a 32-bit operand size, or two bytes starting from the memory address given by:

$$\text{Effective Address} + (2 * (\text{BitOffset DIV } 16))$$

for a 16-bit operand size. It may do so even when only a single byte needs to be accessed in order to reach the given bit. You must therefore avoid referencing areas of memory close to address space holes. In particular, avoid references to memory-mapped I/O registers. Instead, use the MOV instructions to load from or store to these addresses, and use the register form of these instructions to manipulate the data.

## BTC—Bit Test and Complement

Opcode	Instruction	Clocks	Description
0F BB	BTC <i>r/m16,r16</i>	7/13	Save bit in carry flag and complement
0F BB	BTC <i>r/m32,r32</i>	7/13	Save bit in carry flag and complement
0F BA <i>/7 ib</i>	BTC <i>r/m16,imm8</i>	7/8	Save bit in carry flag and complement
0F BA <i>/7 ib</i>	BTC <i>r/m32,imm8</i>	7/8	Save bit in carry flag and complement

### Operation

CF ← BIT[LeftSRC, RightSRC];  
 BIT[LeftSRC, RightSRC] ← NOT BIT[LeftSRC, RightSRC];

### Description

The BTC instruction saves the value of the bit indicated by the base (first operand) and the bit offset (second operand) into the CF flag and then complements the bit.

### Flags Affected

The CF flag contains the complement of the selected bit.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

The index of the selected bit can be given by the immediate constant in the instruction or by a value in a general register. Only an 8-bit immediate value may be used in the instruction. This operand is taken modulo 32, so the range of immediate bit offsets is 0..31. This allows any bit within a register to be selected. For memory bit strings, this immediate field gives only the bit offset within a word or doubleword.

Immediate bit offsets larger than 31 are supported by some assemblers by using the immediate bit offset field in combination with the displacement field of the memory operand. In this case, the low-order 3 to 5 bits (3 for 16 bit operands, 5 for 32 bit operands) of the immediate bit offset are stored in the immediate bit offset field, and the high-order bits are shifted and combined with the byte displacement in the addressing mode by the assembler. The processor will ignore the high order bits if they are not zero.

When accessing a bit in memory, the processor may access four bytes starting from the memory address given by:

$$\text{Effective Address} + (4 * (\text{BitOffset DIV } 32))$$

for a 32-bit operand size, or two bytes starting from the memory address given by:

$$\text{Effective Address} + (2 * (\text{BitOffset DIV } 16))$$

for a 16-bit operand size. It may do so even when only a single byte needs to be accessed in order to reach the given bit. Therefore, referencing areas of memory close to address space holes should be avoided. In particular, avoid references to memory-mapped I/O registers. Instead, use the MOV instructions to load from or store to these addresses, and use the register form of these instructions to manipulate the data.

**BTR—Bit Test and Reset**

Opcode	Instruction	Clocks	Description
0F B3	BTR <i>r/m16,r16</i>	7/13	Save bit in carry flag and reset
0F B3	BTR <i>r/m32,r32</i>	7/13	Save bit in carry flag and reset
0F BA /6 <i>ib</i>	BTR <i>r/m16,imm8</i>	7/8	Save bit in carry flag and reset
0F BA /6 <i>ib</i>	BTR <i>r/m32,imm8</i>	7/8	Save bit in carry flag and reset

**Operation**

CF ← BIT[LeftSRC, RightSRC];  
 BIT[LeftSRC, RightSRC] ← 0;

**Description**

The BTR instruction saves the value of the bit indicated by the base (first operand) and the bit offset (second operand) into the CF flag and then stores 0 in the bit.

**Flags Affected**

The CF flag contains the value of the selected bit.

**Protected Mode Exceptions**

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

The index of the selected bit can be given by the immediate constant in the instruction or by a value in a general register. Only an 8-bit immediate value is used in the instruction. This operand is taken modulo 32, so the range of immediate bit offsets is 0..31. This allows any bit within a register to be selected. For memory bit strings, this immediate field gives only the bit offset within a word or doubleword.

Immediate bit offsets larger than 31 are supported by some assemblers by using the immediate bit offset field in combination with the displacement field of the memory operand. In this case, the low-order 3 to 5 bits (3 for 16-bit operands, 5 for 32-bit operands) of the immediate bit offset are stored in the immediate bit offset field, and the high-order bits are shifted and combined with the byte displacement in the addressing mode by the assembler. The processor will ignore the high order bits if they are not zero.

When accessing a bit in memory, the processor may access four bytes starting from the memory address given by:

$$\text{Effective Address} + 4 * (\text{BitOffset DIV } 32)$$

for a 32-bit operand size, or two bytes starting from the memory address given by:

$$\text{Effective Address} + 2 * (\text{BitOffset DIV } 16)$$

for a 16-bit operand size. It may do so even when only a single byte needs to be accessed in order to reach the given bit. You must therefore avoid referencing areas of memory close to address space holes. In particular, avoid references to memory-mapped I/O registers. Instead, use the MOV instructions to load from or store to these addresses, and use the register form of these instructions to manipulate the data.

## BTS—Bit Test and Set

Opcode	Instruction	Clocks	Description
0F AB	BTS <i>r/m16,r16</i>	7/13	Save bit in carry flag and set
0F AB	BTS <i>r/m32,r32</i>	7/13	Save bit in carry flag and set
0F BA /5 <i>ib</i>	BTS <i>r/m16,imm8</i>	7/8	Save bit in carry flag and set
0F BA /5 <i>ib</i>	BTS <i>r/m32,imm8</i>	7/8	Save bit in carry flag and set

### Operation

CF ← BIT[LeftSRC, RightSRC];  
BIT[LeftSRC, RightSRC] ← 1;

### Description

The BTS instruction saves the value of the bit indicated by the base (first operand) and the bit offset (second operand) into the CF flag and then stores 1 in the bit.

### Flags Affected

The CF flag contains the value of the selected bit.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

The index of the selected bit can be given by the immediate constant in the instruction or by a value in a general register. Only an 8-bit immediate value is used in the instruction. This operand is taken modulo 32, so the range of immediate bit offsets is 0..31. This allows any bit within a register to be selected. For memory bit strings, this immediate field gives only the bit offset within a word or doubleword.

Immediate bit offsets larger than 31 are supported by some assemblers by using the immediate bit offset field in combination with the displacement field of the memory operand. In this case, the low-order 3 to 5 bits (3 for 16-bit operands, 5 for 32-bit operands) of the immediate bit offset are stored in the immediate bit offset field, and the high-order bits are shifted and combined with the byte displacement in the addressing mode by the assembler. The processor will ignore the high order bits if they are not zero.

When accessing a bit in memory, the processor may access four bytes starting from the memory address given by:

$$\text{Effective Address} + (4 * (\text{BitOffset DIV } 32))$$

for a 32-bit operand size, or two bytes starting from the memory address given by:

$$\text{Effective Address} + (2 * (\text{BitOffset DIV } 16))$$

for a 16-bit operand size. It may do this even when only a single byte needs to be accessed in order to get at the given bit. You must therefore be careful to avoid referencing areas of memory close to address space holes. In particular, avoid references to memory-mapped I/O registers. Instead, use the MOV instructions to load from or store to these addresses, and use the register form of these instructions to manipulate the data.

## CALL—Call Procedure

Opcode	Instruction	Clocks	Description
E8 <i>cw</i>	CALL <i>rel16</i>	1	Call near, displacement relative to next instruction
FF /2	CALL <i>r/m16</i>	2	Call near, register indirect/memory indirect
9A <i>cd</i>	CALL <i>ptr16:16</i>	4	Call intersegment, to full pointer given
9A <i>cd</i>	CALL <i>ptr16:16</i>	<i>pm=22</i>	Call gate, same privilege
9A <i>cd</i>	CALL <i>ptr16:16</i>	<i>pm=44</i>	Call gate, more privilege, no parameters
9A <i>cd</i>	CALL <i>ptr16:16</i>	<i>pm=45+2x</i>	Call gate, more privilege, x parameters
9A <i>cd</i>	CALL <i>ptr16:16</i>	<i>pm=21+ts</i>	Call to task
FF /3	CALL <i>m16:16</i>	5	Call intersegment, address at <i>r/m</i> dword
FF /3	CALL <i>m16:16</i>	<i>pm=22</i>	Call gate, same privilege
FF /3	CALL <i>m16:16</i>	<i>pm=44</i>	Call gate, more privilege, no parameters
FF /3	CALL <i>m16:16</i>	<i>pm=45+2x</i>	Call gate, more privilege, x parameters
FF /3	CALL <i>m16:16</i>	<i>pm=21+ts</i>	Call to task
E8 <i>cd</i>	CALL <i>rel32</i>	1	Call near, displacement relative to next instruction
FF /2	CALL <i>r/m32</i>	2	Call near, indirect
9A <i>cp</i>	CALL <i>ptr16:32</i>	4	Call intersegment, to full pointer given
9A <i>cp</i>	CALL <i>ptr16:32</i>	<i>pm=22</i>	Call gate, same privilege
9A <i>cp</i>	CALL <i>ptr16:32</i>	<i>pm=44</i>	Call gate, more privilege, no parameters
9A <i>cp</i>	CALL <i>ptr16:32</i>	<i>pm=45+2x</i>	Call gate, more privilege, x parameters
9A <i>cp</i>	CALL <i>ptr16:32</i>	<i>pm=21+ts</i>	Call to task
FF /3	CALL <i>m16:32</i>	5	Call intersegment, address at <i>r/m</i> dword
FF /3	CALL <i>m16:32</i>	<i>pm=22</i>	Call gate, same privilege
FF /3	CALL <i>m16:32</i>	<i>pm=44</i>	Call gate, more privilege, no parameters
FF /3	CALL <i>m16:32</i>	<i>pm=45+2x</i>	Call gate, more privilege, x parameters
FF /3	CALL <i>m16:32</i>	<i>pm=21+ts</i>	Call to task

**NOTE:** Values of *ts* are given by the following table:

Old Task	New Task		
	To 32 Bit TSS	To 16 Bit TSS	To VM TSS
VM/32-bit/16-bit TSS	85	87	71

## Operation

IF *rel16* or *rel32* type of call  
 THEN (\* near relative call \*)  
   IF OperandSize = 16  
   THEN  
     Push(IP);  
     EIP ← (EIP + *rel16*) AND 0000FFFFH;  
   ELSE (\* OperandSize = 32 \*)  
     Push(EIP);  
     EIP ← EIP + *rel32*;  
   FI;  
 FI;

IF *r/m16* or *r/m32* type of call  
 THEN (\* near absolute call \*)  
 IF OperandSize = 16  
 THEN  
   Push(IP);  
   EIP ← [*r/m16*] AND 0000FFFFH;  
 ELSE (\* OperandSize = 32 \*)

```

    Push(EIP);
    EIP ← [r/m32];
  FI;
FI;

IF (PE = 0 OR (PE = 1 AND VM = 1))
(* real mode or virtual 8086 mode *)
  AND instruction = far CALL
  (* i.e., operand type is m16:16, m16:32, ptr16:16, ptr16:32 *)
THEN
  IF OperandSize = 16
  THEN
    Push(CS);
    Push(IP); (* address of next instruction; 16 bits *)
  ELSE
    Push(CS); (* padded with 16 high-order bits *)
    Push(EIP); (* address of next instruction; 32 bits *)
  FI;
  IF operand type is m16:16 or m16:32
  THEN (* indirect far call *)
    IF OperandSize = 16
    THEN
      CS:IP ← [m16:16];
      EIP ← EIP AND 0000FFFFH; (* clear upper 16 bits *)
    ELSE (* OperandSize = 32 *)
      CS:EIP ← [m16:32];
    FI;
  FI;
  IF operand type is ptr16:16 or ptr16:32
  THEN (* direct far call *)
    IF OperandSize = 16
    THEN
      CS:IP ← ptr16:16;
      EIP ← EIP AND 0000FFFFH; (* clear upper 16 bits *)
    ELSE (* OperandSize = 32 *)
      CS:EIP ← ptr16:32;
    FI;
  FI;
FI;

IF (PE = 1 AND VM = 0) (* Protected mode, not V86 mode *)
  AND instruction = far CALL
THEN
  If indirect, then check access of EA doubleword;
  #GP(0) if limit violation;
  New CS selector must not be null else #GP(0);
  Check that new CS selector index is within its

```

descriptor table limits; else #GP(new CS selector);  
 Examine AR byte of selected descriptor for various legal values;  
 depending on value:  
 go to CONFORMING-CODE-SEGMENT;  
 go to NONCONFORMING-CODE-SEGMENT;  
 go to CALL-GATE;  
 go to TASK-GATE;  
 go to TASK-STATE-SEGMENT;  
 ELSE #GP(code segment selector);  
 FI;

#### CONFORMING-CODE-SEGMENT:

DPL must be  $\leq$  CPL ELSE #GP(code segment selector);  
 Segment must be present ELSE #NP(code segment selector);  
 Stack must be big enough for return address ELSE #SS(0);  
 Instruction pointer must be in code segment limit ELSE #GP(0);  
 Load code segment descriptor into CS register;  
 Load CS with new code segment selector;  
 Load EIP with zero-extend(new offset);  
 IF OperandSize=16 THEN EIP  $\leftarrow$  EIP AND 0000FFFFH; FI;

#### NONCONFORMING-CODE-SEGMENT:

RPL must be  $\leq$  CPL ELSE #GP(code segment selector)  
 DPL must be = CPL ELSE #GP(code segment selector)  
 Segment must be present ELSE #NP(code segment selector)  
 Stack must be big enough for return address ELSE #SS(0)  
 Instruction pointer must be in code segment limit ELSE #GP(0)  
 Load code segment descriptor into CS register  
 Load CS with new code segment selector  
 Set RPL of CS to CPL  
 Load EIP with zero-extend(new offset);  
 IF OperandSize=16 THEN EIP  $\leftarrow$  EIP AND 0000FFFFH; FI;

#### CALL-GATE:

Call gate DPL must be  $\geq$  CPL ELSE #GP(call gate selector)  
 Call gate DPL must be  $\geq$  RPL ELSE #GP(call gate selector)  
 Call gate must be present ELSE #NP(call gate selector)  
 Examine code segment selector in call gate descriptor:  
 Selector must not be null ELSE #GP(0)  
 Selector must be within its descriptor table  
 limits ELSE #GP(code segment selector)  
 AR byte of selected descriptor must indicate code  
 segment ELSE #GP(code segment selector)  
 DPL of selected descriptor must be  $\leq$  CPL ELSE  
 #GP(code segment selector)  
 IF non-conforming code segment AND DPL < CPL  
 THEN go to MORE-PRIVILEGE



ELSE go to SAME-PRIVILEGE  
FI;

**MORE-PRIVILEGE:**

Get new SS selector for new privilege level from TSS  
Check selector and descriptor for new SS:  
Selector must not be null ELSE #TS(0)  
Selector index must be within its descriptor  
table limits ELSE #TS(SS selector)  
Selector's RPL must equal DPL of code segment  
ELSE #TS(SS selector)  
Stack segment DPL must equal DPL of code  
segment ELSE #TS(SS selector)  
Descriptor must indicate writable data segment  
ELSE #TS(SS selector)  
Segment present ELSE #SS(SS selector)  
IF OperandSize=32  
THEN  
New stack must have room for parameters plus 16 bytes  
ELSE #SS(SS selector)  
EIP must be in code segment limit ELSE #GP(0)  
Load new SS:eSP value from TSS  
Load new CS:EIP value from gate  
ELSE  
New stack must have room for parameters plus 8 bytes  
ELSE #SS(SS selector)  
IP must be in code segment limit ELSE #GP(0)  
Load new SS:eSP value from TSS  
Load new CS:IP value from gate  
FI;  
Load CS descriptor  
Load SS descriptor  
Push long pointer of old stack onto new stack  
Get word count from call gate, mask to 5 bits  
Copy parameters from old stack onto new stack  
Push return address onto new stack  
Set CPL to stack segment DPL  
Set RPL of CS to CPL

**SAME-PRIVILEGE:**

IF OperandSize=32  
THEN  
Stack must have room for 6-byte return address (padded to 8 bytes)  
ELSE #SS(0)  
EIP must be within code segment limit ELSE #GP(0)  
Load CS:EIP from gate  
ELSE

Stack must have room for 4-byte return address ELSE #SS(0)

IP must be within code segment limit ELSE #GP(0)

Load CS:IP from gate

FI;

Push return address onto stack

Load code segment descriptor into CS register

Set RPL of CS to CPL

#### TASK-GATE:

Task gate DPL must be  $\geq$  CPL ELSE #TS(gate selector)

Task gate DPL must be  $\geq$  RPL ELSE #TS(gate selector)

Task Gate must be present ELSE #NP(gate selector)

Examine selector to TSS, given in Task Gate descriptor:

Must specify global in the local/global bit ELSE #TS(TSS selector)

Index must be within GDT limits ELSE #TS(TSS selector)

TSS descriptor AR byte must specify nonbusy TSS

ELSE #TS(TSS selector)

Task State Segment must be present ELSE #NP(TSS selector)

SWITCH-TASKS (with nesting) to TSS

IP must be in code segment limit ELSE #TS(0)

#### TASK-STATE-SEGMENT:

TSS DPL must be  $\geq$  CPL ELSE #TS(TSS selector)

TSS DPL must be  $\geq$  RPL ELSE #TS(TSS selector)

TSS descriptor AR byte must specify available TSS

ELSE #TS(TSS selector)

Task State Segment must be present ELSE #NP(TSS selector)

SWITCH-TASKS (with nesting) to TSS

IP must be in code segment limit ELSE #TS(0)

## Description

The CALL instruction causes the procedure named in the operand to be executed. When the procedure is complete (a return instruction is executed within the procedure), execution continues at the instruction that follows the CALL instruction.

The action of the different forms of the instruction are described below.

Near calls are those with destinations of type *r/m16*, *r/m32*, *rel16*, *rel32*; changing or saving the segment register value is not necessary. The CALL *rel16* and CALL *rel32* forms add a signed offset to the address of the instruction following the CALL instruction to determine the destination. The *rel16* form is used when the instruction's operand-size attribute is 16 bits; *rel32* is used when the operand-size attribute is 32 bits. The result is stored in the 32-bit EIP register. With *rel16*, the upper 16 bits of the EIP register are cleared, resulting in an offset whose value does not exceed 16 bits. CALL *r/m16* and CALL *r/m32* specify a register or memory location from which the absolute segment offset is fetched. The offset fetched from *r/m* is 32 bits for an operand-size attribute of 32 (*r/m32*), or 16 bits for an operand-size of 16 (*r/m16*). The offset of the instruction following the CALL instruction is pushed onto the

stack. It will be popped by a near RET instruction within the procedure. The CS register is not changed by this form of CALL.

The far calls, CALL *ptr16:16* and CALL *ptr16:32*, use a four-byte or six-byte operand as a long pointer to the procedure called. The CALL *m16:16* and *m16:32* forms fetch the long pointer from the memory location specified (indirection). In Real Address Mode or Virtual 8086 Mode, the long pointer provides 16 bits for the CS register and 16 or 32 bits for the EIP register (depending on the operand-size attribute). These forms of the instruction push both the CS and IP or EIP registers as a return address.

In Protected Mode, both long pointer forms consult the AR byte in the descriptor indexed by the selector part of the long pointer. Depending on the value of the AR byte, the call will perform one of the following types of control transfers:

- A far call to the same protection level
- An inter-protection level far call
- A task switch

A CALL-indirect-thru-memory, which uses the stack pointer (ESP) as a base register, references memory before the CALL. The base used is the value of the ESP before the instruction executes.

For more information on Protected Mode control transfers, refer to Chapter 6 and Chapter 7.

### Flags Affected

All flags are affected if a task switch occurs; no flags are affected if a task switch does not occur.

### Protected Mode Exceptions

For far calls: #GP, #NP, #SS, and #TS, as indicated in the “Operation” section.

For near direct calls: #GP(0) if procedure location is beyond the code segment limits; #SS(0) if pushing the return address exceeds the bounds of the stack segment; #PF (fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

For a near indirect call: #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #GP(0) if the indirect offset obtained is beyond the code segment limits; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

Any far call from a 32-bit code segment to a 16-bit code segment should be made from the first 64 Kbytes of the 32-bit code segment, because the operand-size attribute of the instruction is set to 16, allowing only a 16-bit return address offset to be saved.



## CBW/CWDE— Convert Byte to Word/Convert Word to Doubleword

Opcode	Instruction	Clocks	Description
98	CBW	3	AX ← sign-extend of AL
98	CWDE	3	EAX ← sign-extend of AX

### Operation

```
IF OperandSize = 16 (* instruction = CBW *)
THEN AX ← SignExtend(AL);
ELSE (* OperandSize = 32, instruction = CWDE *)
  EAX ← SignExtend(AX);
FI;
```

### Description

The CBW instruction converts the signed byte in the AL register to a signed word in the AX register by extending the most significant bit of the AL register (the sign bit) into all of the bits of the AH register. The CWDE instruction converts the signed word in the AX register to a doubleword in the EAX register by extending the most significant bit of the AX register into the two most significant bytes of the EAX register. Note that the CWDE instruction is different from the CWD instruction. The CWD instruction uses the DX:AX register pair rather than the EAX register as a destination.

### Flags Affected

None.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

## **CDQ—Convert Double to Quad**

See entry for CWD/CDQ — Convert Word to Double/Convert Double to Quad.

## CLC—Clear Carry Flag

Opcode	Instruction	Clocks	Description
F8	CLC	2	Clear carry flag

### Operation

CF ← 0;

### Description

The CLC instruction clears the CF flag. It does not affect other flags or registers.

### Flags Affected

The CF flag is cleared.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

## CLD—Clear Direction Flag

Opcode	Instruction	Clocks	Description
FC	CLD	2	Clear direction flag; SI and DI will increment during string instructions

### Operation

DF ← 0;

### Description

The CLD instruction clears the direction flag. No other flags or registers are affected. After a CLD instruction is executed, string operations will increment the index registers (SI and/or DI) that they use.

### Flags Affected

The DF flag is cleared.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.



## CLI—Clear Interrupt Flag

Opcode	Instruction	Clocks	Description
FA	CLI	7	Clear interrupt flag; interrupts disabled when interrupt flag cleared

### Operation

```

IF PE = 0
THEN
    IF ← 0;
ELSE
    IF VM = 0 (* Executing in protected Mode *)
    THEN
        IF IOPL = 3
        THEN IF ← 0;
        ELSE IF CPL ≤ IOPL
        THEN IF ← 0;
        ELSE #GP(0);
        FI;
    FI;
    ELSE (* Executing in Virtual-8086 mode *)
    IF IOPL = 3
    THEN IF ← 0;
    ELSE #GP(0);
    FI;
    FI;
FI;

```

### Decision Table

The following decision table indicates which action in the lower portion of the table is taken given the conditions in the upper portion of the table.

PE =	0	1	1	1	1
VM =	–	0	–	0	1
CPL	–	≤ IOPL	–	>IOPL	–
IOPL	–	–	= 3	–	< 3
IF ← 0	Y	Y	Y		
#GP(0)				Y	Y

#### NOTES:

- Don't care
- Blank Action Not Taken
- Y Action in Column 1 taken

**Description**

The CLI instruction clears the IF flag if the current privilege level is at least as privileged as IOPL. No other flags are affected. External interrupts are not recognized at the end of the CLI instruction from that point on until the IF flag is set.

**Flags Affected**

IF

**Protected Mode Exceptions**

#GP(0) if the current privilege level is greater (has less privilege) than the I/O privilege level in the flags register. The I/O privilege level specifies the least privileged level at which I/O can be performed.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

#GP(0) as for protected mode.

**Notes**

For information on this instruction when using virtual mode extensions, see Appendix H.



**CLTS—Clear Task-Switched Flag in CR0**

Opcode	Instruction	Clocks	Description
0F 06	CLTS	10	Clear task-switched flag

**Operation**

TS Flag in CR0  $\leftarrow$  0;

**Description**

The CLTS instruction clears the task-switched (TS) flag in the CR0 register. This flag is set by the processor every time a task switch occurs. The TS flag is used to manage processor extensions as follows:

- Every execution of an ESC instruction is trapped if the TS flag is set.
- Execution of a WAIT instruction is trapped if the MP flag and the TS flag are both set.

Thus, if a task switch was made after an ESC instruction was begun, the floating-point unit's context may need to be saved before a new ESC instruction can be issued. The fault handler saves the context and clears the TS flag.

The CLTS instruction appears in operating system software, not in application programs. It is a privileged instruction that can only be executed at privilege level 0.

**Flags Affected**

The TS flag is cleared (the TS flag is in the CR0 register, not the flags register).

**Protected Mode Exceptions**

#GP(0) if the CLTS instruction is executed with a current privilege level other than 0.

**Real Address Mode Exceptions**

None (valid in Real Address Mode to allow initialization for Protected Mode).

**Virtual 8086 Mode Exceptions**

Same exceptions as in Protected Mode.

## CMC—Complement Carry Flag

Opcode	Instruction	Clocks	Description
F5	CMC	2	Complement carry flag

### Operation

CF ← NOT CF;

### Description

The CMC instruction reverses the setting of the CF flag. No other flags are affected.

### Flags Affected

The CF flag contains the complement of its original value.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.



## CMP—Compare Two Operands

Opcode	Instruction	Clocks	Description
3C <i>ib</i>	CMP AL, <i>imm8</i>	1	Compare immediate byte to AL
3D <i>iw</i>	CMP AX, <i>imm16</i>	1	Compare immediate word to AX
3D <i>id</i>	CMP EAX, <i>imm32</i>	1	Compare immediate dword to EAX
80 <i>77 ib</i>	CMP <i>r/m8,imm8</i>	1/2	Compare immediate byte to <i>r/m</i> byte
81 <i>77 iw</i>	CMP <i>r/m16,imm16</i>	1/2	Compare immediate word to <i>r/m</i> word
81 <i>77 id</i>	CMP <i>r/m32,imm32</i>	1/2	Compare immediate dword to <i>r/m</i> dword
83 <i>77 ib</i>	CMP <i>r/m16,imm8</i>	1/2	Compare sign extended immediate byte to <i>r/m</i> word
83 <i>77 ib</i>	CMP <i>r/m32,imm8</i>	1/2	Compare sign extended immediate byte to <i>r/m</i> dword
38 <i>7r</i>	CMP <i>r/m8,r8</i>	1/2	Compare byte register to <i>r/m</i> byte
39 <i>7r</i>	CMP <i>r/m16,r16</i>	1/2	Compare word register to <i>r/m</i> word
39 <i>7r</i>	CMP <i>r/m32,r32</i>	1/2	Compare dword register to <i>r/m</i> dword
3A <i>7r</i>	CMP <i>r8,r/m8</i>	1/2	Compare <i>r/m</i> byte to byte register
3B <i>7r</i>	CMP <i>r16,r/m16</i>	1/2	Compare <i>r/m</i> word to word register
3B <i>7r</i>	CMP <i>r32,r/m32</i>	1/2	Compare <i>r/m</i> dword to dword register

### Operation

LeftSRC - SignExtend(RightSRC);

(\* CMP does not store a result; its purpose is to set the flags \*)

### Description

The CMP instruction subtracts the second operand from the first but, unlike the SUB instruction, does not store the result; only the flags are changed. The CMP instruction is typically used in conjunction with conditional jumps and the SETcc instruction. (Refer to Appendix D for the list of signed and unsigned flag tests provided.) If an operand greater than one byte is compared to an immediate byte, the byte value is first sign-extended.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## CMPS/CMPSB/CMPSW/CMPSD—Compare String Operands

Opcode	Instruction	Clocks	Description
A6	CMPS <i>m8,m8</i>	5	Compare bytes ES:[(E)DI] (second operand) with [(E)SI] (first operand)
A7	CMPS <i>m16,m16</i>	5	Compare words ES:[(E)DI] (second operand) with [(E)SI] (first operand)
A7	CMPS <i>m32,m32</i>	5	Compare dwords ES:[(E)DI] (second operand) with [(E)SI] (first operand)
A6	CMPSB	5	Compare bytes ES:[(E)DI] with DS:[SI]
A7	CMPSW	5	Compare words ES:[(E)DI] with DS:[SI]
A7	CMPSD	5	Compare dwords ES:[(E)DI] with DS:[SI]

### Operation

```

IF (instruction = CMPSD) OR
  (instruction has operands of type DWORD)
THEN OperandSize ← 32;
ELSE OperandSize ← 16;
FI;
IF AddressSize = 16
THEN
  use SI for source-index and DI for destination-index
ELSE (* AddressSize = 32 *)
  use ESI for source-index and EDI for destination-index;
FI;
IF byte type of instruction
THEN
  set ZF based on
  [source-index] - [destination-index]; (* byte comparison *)
  IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;
ELSE
  IF OperandSize = 16
  THEN
    set ZF based on
    [source-index] - [destination-index]; (* word comparison *)
    IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;
  ELSE (* OperandSize = 32 *)
    set ZF based on
    [source-index] - [destination-index]; (* dword comparison *)
    IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI;
  FI;
FI;
source-index = source-index + IncDec;
destination-index = destination-index + IncDec;
  
```

## Description

The CMPS instruction compares the byte, word, or doubleword pointed to by the source-index register with the byte, word, or doubleword pointed to by the destination-index register.

If the address-size attribute of this instruction is 16 bits, the SI and DI registers will be used for source- and destination-index registers; otherwise the ESI and EDI registers will be used. Load the correct index values into the SI and DI (or ESI and EDI) registers before executing the CMPS instruction.

The comparison is done by subtracting the operand indexed by the destination-index register from the operand indexed by the source-index register.

Note that the direction of subtraction for the CMPS instruction is  $[SI] - [DI]$  or  $[ESI] - [EDI]$ . The left operand (SI or ESI) is the source and the right operand (DI or EDI) is the destination. This is the reverse of the usual Intel convention in which the left operand is the destination and the right operand is the source.

The result of the subtraction is not stored; only the flags reflect the change. The types of the operands determine whether bytes, words, or doublewords are compared. For the first operand (SI or ESI), the DS register is used, unless a segment override byte is present. The second operand (DI or EDI) must be addressable from the ES register; no segment override is possible.

After the comparison is made, both the source-index register and destination-index register are automatically advanced. If the DF flag is 0 (a CLD instruction was executed), the registers increment; if the DF flag is 1 (an STD instruction was executed), the registers decrement. The registers increment or decrement by 1 if a byte is compared, by 2 if a word is compared, or by 4 if a doubleword is compared.

The CMPSB, CMPSW and CMPSD instructions are synonyms for the byte, word, and doubleword CMPS instructions, respectively.

The CMPS instruction can be preceded by the REPE or REPNE prefix for block comparison of CX or ECX bytes, words, or doublewords. Refer to the description of the REP instruction for more information on this operation.

## Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are set according to the result.

## Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## CMPXCHG—Compare and Exchange

Opcode	Instruction	Clocks	Description
0F B0/r	CMPXCHG <i>r/m8,r8</i>	6	Compare AL with <i>r/m</i> byte. If equal, set ZF and load byte reg into <i>r/m</i> byte. Else, clear ZF and load <i>r/m</i> byte into AL.
0F B1/r	CMPXCHG <i>r/m16,r16</i>	6	Compare AX with <i>r/m</i> word. If equal, set ZF and load word reg into <i>r/m</i> word. Else, clear ZF and load <i>r/m</i> word into AX.
0F B1/r	CMPXCHG <i>r/m32,r32</i>	6	Compare EAX with <i>r/m</i> dword. If equal, set ZF and load dword reg into <i>r/m</i> dword. Else, clear ZF and load <i>r/m</i> dword into EAX.

### Operation

IF accumulator=DEST

ZF ← 1

DEST ← SRC

ELSE

ZF ← 0

accumulator ← DEST

### Description

The CMPXCHG instruction compares the accumulator (AL, AX, or EAX register) with DEST. If they are equal, SRC is loaded into DEST. Otherwise, DEST is loaded into the accumulator.

### Flags Affected

The CF, PF, AF, SF, and OF flags are affected as if a CMP instruction had been executed with DEST and the accumulator as operands. The ZF flag is set if the destination operand and the accumulator are equal; otherwise it is cleared.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in real-address mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

This instruction can be used with a LOCK prefix. In order to simplify interface to the processor's bus, the destination operand receives a write cycle without regard to the result of the comparison. DEST is written back if the comparison fails, and SRC is written into the destination otherwise. (The processor never produces a locked read without also producing a locked write.) This instruction is not supported on Intel386 processors. See Chapter 23 to use CMPXCHG compatible with Intel386 processors.

**CMPXCHG8B—Compare and Exchange 8 Bytes**

Opcode	Instruction	Clocks	Description
OF C7 /1 m64	CMPXCHG8B <i>r/m64</i>	10	Compare EDX:EAX with <i>r/m</i> qword. If equal, set ZF and load ECX:EBX into <i>r/m</i> qword. Else, clear ZF and load <i>r/m</i> qword into EDX:EAX.

**Operation**

```

IF EDX:EAX=DEST
    ZF ← 1
    DEST ← ECX:EBX
ELSE
    ZF ← 0
    EDX:EAX ← DEST

```

**Description**

The CMPXCHG8B instruction compares the 64-bit value in EDX:EAX with DEST. EDX contains the high-order 32 bits, and EAX contains the low-order 32 bits of the 64-bit value. If they are equal, the 64-bit value in ECX:EBX is stored into DEST. ECX contains the high-order 32 bits and EBX contains the low order 32 bits. Otherwise, DEST is loaded into EDX:EAX.

**Flags Affected**

The ZF flag is set if the destination operand and EDX:EAX are equal; otherwise it is cleared. The CF, PF, AF, SF, and OF flags are unaffected.

**Protected Mode Exceptions**

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

The destination operand must be a memory operand, not a register. If the CMPXCHG8B instruction is executed with a *modr/m* byte representing a register as the destination operand, #UD occurs.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3. #UD if modr/m byte represents a register as the destination.

### Notes

This instruction can be used with a LOCK prefix. In order to simplify interface to the processor's bus, the destination operand receives a write cycle without regard to the result of the comparison. DEST is written back if the comparison fails, and SRC is written into the destination otherwise. (The processor never produces a locked read without also producing a locked write.)

The "r/m64" syntax had previously been used only in the context of floating-point operations. It indicates a 64-bit value, in memory at an address determined by the modr/m byte. This instruction is not supported on Intel486 processors.

**CPUID—CPU Identification**

Opcode	Instruction	Clocks	Description
0F A2	CPUID	14	EAX ← CPU identification information

**Operation**

switch (EAX)

case 0:

EAX ← hv; (\* hv=1 for the Pentium processor \*)  
 (\* hv is the highest input value that is understood by CPUID.\*)

EBX ← Vendor identification string;  
 EDX ← Vendor identification string;  
 ECX ← Vendor identification string;  
 break;

case 1:

EAX[3:0] ← Stepping ID;  
 EAX[7:4] ← Model;  
 EAX[11:8] ← Family;  
 EAX[31:12] ← Reserved;

EBX ← reserved; (\* 0 \*)  
 ECX ← reserved; (\* 0 \*)  
 EDX ← feature flags;  
 break;

default: (\* EAX > hv \*)

EAX ← reserved, undefined;  
 EBX ← reserved, undefined;  
 ECX ← reserved, undefined;  
 EDX ← reserved, undefined;  
 break;

end-of-switch

**Description**

The CPUID instruction provides information to software to identify Intel as the vendor, including family, model, and stepping of microprocessor on which it is executing. An input value loaded into the EAX register for this instruction indicates what information should be returned by the CPUID instruction.

Following execution of the CPUID instruction with a zero in EAX, the EAX register contains the highest input value understood by the CPUID instruction. For the Pentium processor, the value in EAX will be a one. Also included in the output of this instruction with an input value of zero in EAX is a vendor identification string contained in the EBX, EDX, and ECX registers. EBX contains the first four characters, EDX contains the next four characters and

ECX contains the last four characters. For Intel processors, the vendor identification string is "GenuineIntel" as follows:

EBX ← 756e6547h (\* "Genu", with G in the low nibble of BL \*)

EDX ← 49656e69h (\* "inel", with i in the low nibble of DL \*)

ECX ← 6c65746eh (\* "ntel", with n in the low nibble of CL \*)

Following execution of the CPUID instruction with an input value of one loaded into the EAX register, EAX[3:0] contains the stepping id of the microprocessor, EAX[7:4] contains the model (the first model will be indicated by 0001B in these bits) and EAX[11:8] contains the family (5 for the Pentium processor family). EAX[31:12] are reserved, as well as EBX, and ECX. The Pentium processor sets the feature register, EDX, to 1BFH indicating which features the Pentium processor supports. A feature flag set to one indicates that the corresponding feature is supported. The feature set register is defined as follows:

EDX[0:0] FPU on chip

EDX[2:2] I/O Breakpoints

EDX[4:4] Time Stamp Counter

EDX[5:5] Pentium-CPU-style model specific registers

EDX[6:1] For more information on these bits, see Appendix H

EDX[7:7] Machine Check Exception

EDX[8:8] CMPXCHG8B Instruction

EDX[31:9] Reserved

Software should identify Intel as the vendor in order to properly interpret the feature register flag bits. For more information on the feature set register, see Appendix H.

### Flags Affected

None.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

### Notes

Refer to the guidelines in Chapter 2, "Reserved Bits."

**CWD/CDQ—Convert Word to Double/Convert Double to Quad**

Opcode	Instruction	Clocks	Description
99	CWD	2	DX ← sign-extend of AX
99	CDQ	2	EDX ← sign-extend of EAX

**Operation**

```

IF OperandSize = 16 (* instruction = CWD *)
THEN DX ← SignExtend(AX);
ELSE (* OperandSize = 32, instruction = CDQ *)
  EDX ← SignExtend(EAX);
FI;

```

**Description**

CWD and CDQ double the size of the source operand. The CWD instruction copies the sign (bit 15) of the word in the AX register into every bit position in the DX register. The CDQ instruction copies the sign (bit 31) of the doubleword in the EAX register into every bit position in the EDX register. The CWD instruction can be used to produce a doubleword dividend from a word before a word division, and the CDQ instruction can be used to produce a quadword dividend from a doubleword before doubleword division. The CWD and CDQ instructions are different mnemonics for the same opcode. Which one gets executed is determined by whether it is in a 16- or 32-bit segment and the presence of any operand-size override prefixes.

**Flags Affected**

None.

**Protected Mode Exceptions**

None.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.



**CWDE—Convert Word to Doubleword**

See entry for CBW/CWDE—Convert Byte to Word/Convert Word to Doubleword.

## DAA—Decimal Adjust AL after Addition

Opcode	Instruction	Clocks	Description
27	DAA	3	Decimal adjust AL after addition

### Operation

IF (((AL AND 0FH) > 09H) or EFLAGS.AF = 1)

THEN

AL ← AL + 06H;

FI;

IF ((AL AND 0F0H) > 90H) or EFLAGS.CF = 1)

THEN

AL ← AL + 60H;

CF ← 1;

FI;

### Description

Execute the DAA instruction only after executing an ADD instruction that leaves a two-BCD-digit byte result in the AL register. The ADD operands should consist of two packed BCD digits. The DAA instruction adjusts the AL register to contain the correct two-digit packed decimal result.

### Flags Affected

The AF and CF flags are set if there is a decimal carry, cleared if there is no decimal carry; the SF, ZF and PF flags are set according to the result. The OF flag is undefined.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.



**DAS—Decimal Adjust AL after Subtraction**

Opcode	Instruction	Clocks	Description
2F	DAS	3	Decimal adjust AL after subtraction

**Operation**

```

tmpCF ← 0;
tmpAL ← AL;
IF (((tmpAL AND 0FH) > 9H) or AF = 1)
THEN
    AF ← 1;
    AL ← AL - 6H;
    tmpCF ← (AL < 0) OR CF;
FI;
IF ((tmpAL > 99H) or CF = 1)
THEN
    AL ← AL - 60H;
    tmpCF ← 1;
FI;
CF ← tmpCF;

```

**Description**

Execute the DAS instruction only after a subtraction instruction that leaves a two-BCD-digit byte result in the AL register. The operands should consist of two packed BCD digits. The DAS instruction adjusts the AL register to contain the correct packed two-digit decimal result.

**Flags Affected**

The AF and CF flags are set if there is a decimal borrow, cleared if there is no decimal borrow; the SF, ZF and PF flags are set according to the result. The OF flag is undefined.

**Protected Mode Exceptions**

None.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.

**DEC—Decrement by 1**

Opcode	Instruction	Clocks	Description
FE /1	DEC r/m8	1/3	Decrement r/m byte by 1
FF /1	DEC r/m16	1/3	Decrement r/m word by 1
FF /1	DEC r/m32	1/3	Decrement r/m dword by 1
48+rw	DEC r16	1	Decrement word register by 1
48+rd	DEC r32	1	Decrement dword register by 1

**Operation**

DEST ← DEST – 1;

**Description**

The DEC instruction subtracts 1 from the operand. The DEC instruction does not change the CF flag. To affect the CF flag, use the SUB instruction with an immediate operand of 1.

**Flags Affected**

The OF, SF, ZF, AF, and PF flags are set according to the result.

**Protected Mode Exceptions**

#GP(0) if the result is a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## DIV—Unsigned Divide

Opcode	Instruction	Clocks	Description
F6 /6	DIV AL, <i>r/m8</i>	17	Unsigned divide AX by <i>r/m</i> byte (AL=Quo, AH=Rem)
F7 /6	DIV AX, <i>r/m16</i>	25	Unsigned divide DX:AX by <i>r/m</i> word (AX=Quo, DX=Rem)
F7 /6	DIV EAX, <i>r/m32</i>	41	Unsigned divide EDX:EAX by <i>r/m</i> dword (EAX=Quo, EDX=Rem)

### Operation

```
temp ← dividend / divisor;
IF temp does not fit in quotient
THEN Interrupt 0;
ELSE
    quotient ← temp;
    remainder ← dividend MOD (r/m);
FI;
```

Note: Divisions are unsigned. The divisor is given by the ***r/m*** operand. The dividend, quotient, and remainder use implicit registers. Refer to the table under "Description."

### Description

The DIV instruction performs an unsigned division. The dividend is implicit; only the divisor is given as an operand. The remainder is always less than the divisor. The type of the divisor determines which registers to use as follows:

Size	Dividend	Divisor	Quotient	Remainder
byte	AX	<i>r/m8</i>	AL	AH
word	DX:AX	<i>r/m16</i>	AX	DX
dword	EDX:EAX	<i>r/m32</i>	EAX	EDX

### Flags Affected

The OF, SF, ZF, AF, PF, CF flags are undefined.

### Protected Mode Exceptions

Interrupt 0 if the quotient is too large to fit in the designated register (AL, AX, or EAX), or if the divisor is 0; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 0 if the quotient is too big to fit in the designated register (AL, AX, or EAX), or if the divisor is 0; Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## ENTER—Make Stack Frame for Procedure Parameters

Opcode	Instruction	Clocks	Description
C8 <i>iw</i> 00	ENTER <i>imm16</i> ,0	11	Make procedure stack frame
C8 <i>iw</i> 01	ENTER <i>imm16</i> ,1	15	Make stack frame for procedure parameters
C8 <i>iw</i> ib	ENTER <i>imm16</i> , <i>imm8</i>	15+2 <i>imm8</i>	Make stack frame for procedure parameters

### Operation

level ← level MOD 32

2ndOperand <- 2ndOperand MOD 32

IF operand\_size = 16 THEN Push(bp) ELSE Push ebp) FI;

IF stkSize = 16 THEN framePtr = sp ELSE framePtr = esp FI;

IF (level>0)

FOR i ← 1 TO (2ndOperand - 1)

DO

IF operand\_size = 16

THEN

IF stkSize = 16

THEN

bp = bp - 2

Push( [bp] ) (\* word push \*)

ELSE (\* stkSize = 32 \*)

ebp = ebp - 2

Push( [ebp] ) (\* word push \*)

FI;

ELSE (\* operand\_size = 32 \*)

IF stkSize = 16

bp = bp - 4

Push( [bp] ) (\* doubleword push \*)

ELSE (\* stkSize = 32 \*)

ebp = ebp - 4

Push( [ebp] ) (\* doubleword push \*)

FI;

FI;

OD;

IF operand\_size = 16

THEN Push(framePtr); (\* word push \*)

ELSE Pushd(framePtr); (\* doubleword push \*)

FI;

FI;

IF stkSize = 16

THEN

bp = framePtr

sp = sp - 1stOperand

ELSE

ebp = framePtr

esp = esp - 1stOperand

FI;

## Description

The ENTER instruction creates the stack frame required by most block-structured high-level languages. The first operand specifies the number of bytes of dynamic storage allocated on the stack for the routine being entered. The second operand gives the lexical nesting level (0 to 31) of the routine within the high-level language source code. It determines the number of stack frame pointers copied into the new stack frame from the preceding frame.

Both the operand-size attribute and the stack-size attribute are used to determine whether BP or EBP is used for the current frame pointer and SP or ESP is used for the stack pointer.

If the operand-size attribute is 16 bits, the processor uses the BP register as the frame pointer and the SP register as the stack pointer, unless the stack-size attribute is 32 bits in which case it uses EBP for the frame pointer and ESP for the stack pointer. If the operand-size attribute is 32 bits, the processor uses the EBP register for the frame pointer and the ESP register for the stack pointer, unless the stack-size attribute is 16 bits in which case it uses BP for the frame pointer and SP for the stack pointer.

If the second operand is 0, the ENTER instruction pushes the frame pointer (BP or EBP register) onto the stack; the ENTER instruction then subtracts the first operand from the stack pointer and sets the frame pointer to the current stack-pointer value.

For example, a procedure with 12 bytes of local variables would have an ENTER 12,0 instruction at its entry point and a LEAVE instruction before every RET instruction. The 12 local bytes would be addressed as negative offsets from the frame pointer.

## Flags Affected

None.

## Protected Mode Exceptions

#SS(0) if the SP or ESP value would exceed the stack limit at any point during instruction execution; #PF(fault-code) for a page fault.

## Real Address Mode Exceptions

None.

## Virtual 8086 Mode Exceptions

None.



**F2XM1—Compute  $2^X-1$** 

Opcode	Instruction	Clocks	Description
D9 F0	F2XM1	13-57	Replace ST with $(2^{ST}-1)$

**Operation**

$ST \leftarrow (2^{ST}-1);$

**Description**

F2XM1 replaces the contents of ST with  $(2^{ST}-1)$ . ST must lie in the range  $-1 < ST < 1$ .

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

P, U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand is outside the acceptable range, the result of F2XM1 is undefined.

Values other than 2 can be exponentiated using the formula

$$x^y = 2^{(y \times \log_2 x)}$$

The instructions FLDL2T and FLDL2E load the constants  $\log_2 10$  and  $\log_2 e$ , respectively. FYL2X can be used to calculate  $y \times \log_2 x$  for arbitrary positive x.

## FABS—Absolute Value

Opcode	Instruction	Clocks	Description
D9 E1	FABS	1	Replace ST with its absolute value.

### Operation

sign bit of ST  $\leftarrow$  0

### Description

The absolute value instruction clears the sign bit of ST. This operation leaves a positive value unchanged, or replaces a negative value with a positive value of equal magnitude.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

The invalid-operation exception is raised only on stack underflow. No exception is raised if the operand is a signaling NaN or is in an unsupported format.



## FADD/FADDP/FIADD—Add

Opcode	Instruction	Clocks	Description
D8 /0	FADD <i>m32real</i>	3/1	Add <i>m32real</i> to ST.
DC /0	FADD <i>m64real</i>	3/1	Add <i>m64real</i> to ST.
D8 C0+i	FADD ST, ST(i)	3/1	Add ST(i) to ST.
DC C0+i	FADD ST(i), ST	3/1	Add ST to ST(i).
DE C0+i	FADDP ST(i), ST	3/1	Add ST to ST(i) and pop ST.
DE C1	FADDP	3/1	Add ST to ST(1) and pop ST.
DA /0	FIADD <i>m32int</i>	7/4	Add <i>m32int</i> to ST.
DE /0	FIADD <i>m16int</i>	7/4	Add <i>m16int</i> to ST

### Operation

DEST ← DEST +SRC;

If instruction = FADDP THEN pop ST Fi;

### Description

The addition instructions add the source and destination operands and return the sum to the destination. The operand at the stack top can be doubled by coding:

FADD ST, ST(0)

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.



## FBLD—Load Binary Coded Decimal

Opcode	Instruction	Clocks	Description
DF /4	FBLD <i>m80 dec</i>	48-58	Push <i>m80dec</i> onto the FPU stack.

### Operation

Decrement FPU stack-top pointer;  
ST(0) ← SRC;

### Description

FBLD converts the BCD source operand into extended-real format, and pushes it onto the FPU stack. See Figure 6-11 for BCD data layout.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

The source is loaded without rounding error. The sign of the source is preserved, including the case where the value is negative zero.

The packed decimal digits are assumed to be in the range 0-9. The instruction does not check for invalid digits (A-FH), and the result of attempting to load an invalid encoding is undefined.

ST(7) must be empty to avoid causing an invalid-operation exception.



## FBSTP—Store Binary Coded Decimal and Pop

Opcode	Instruction	Clocks	Description
DF /6	FBSTP m80dec	148-154	Store ST in m80dec and pop ST.

### Operation

DEST ← ST(0);  
pop ST;

### Description

FBSTP converts the value in ST into a packed decimal integer, stores the result at the destination in memory, and pops ST. Non-integral values are first rounded according to the RC field of the control word. See Figure 6-10 for BCD data layout.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, I, IS.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## FCHS—Change Sign

Opcode	Instruction	Clocks	Description
D9 E0	FCHS	1	Replace ST with a value of opposite sign.

### Operation

sign bit of ST ← NOT (sign bit of ST)

### Description

The change sign instruction inverts the sign bit of ST. This operation replaces a positive value with a negative value of equal magnitude, or vice-versa.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

The invalid-operation exception is raised only on stack underflow, even if the operand is a signaling NaN or is in an unsupported format.

## FCLEX/FNCLEX—Clear Exceptions

Opcode	Instruction	Clocks	Description
9B DB E2	FCLEX	9 + at least 1 for FWAIT	Clear floating-point exception flags after checking for floating-point error conditions.
DB E2	FNCLEX	9	Clear floating-point exception flags without checking for floating-point error conditions.*

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

SW[0..7] ← 0;

SW[15] ← 0;

### Description

FCLEX clears the exception flags, the exception status flag, and the busy flag of the FPU status word.

### FPU Flags Affected

C0, C1, C2, C3 undefined.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

FCLEX checks for unmasked floating-point error conditions before clearing the exception flags; FNCLEX does not.

## FCOM/FCOMP/FCOMPP—Compare Real

Opcode	Instruction	Clocks	Description
D8 /2	FCOM <i>m32real</i>	4/1	Compare ST with <i>m32real</i> .
DC /2	FCOM <i>m64real</i>	4/1	Compare ST with <i>m64real</i> .
D8 D0+i	FCOM ST(i)	4/1	Compare ST with ST(i).
D8 D1	FCOM	4/1	Compare ST with ST(1).
D8 /3	FCOMP <i>m32real</i>	4/1	Compare ST with <i>m32real</i> and pop ST.
DC /3	FCOMP <i>m64real</i>	4/1	Compare ST with <i>m64real</i> and pop ST.
D8 D8+i	FCOMP ST(i)	4/1	Compare ST with ST(i) and pop ST.
D8 D9	FCOMP	4/1	Compare ST with ST(1) and pop ST.
DE D9	FCOMPP	4/1	Compare ST with ST(1) and pop ST twice.

### Operation

CASE (relation of operands) OF

Not comparable: C3, C2, C0 ← 111;

ST > SRC: C3, C2, C0 ← 000;

ST < SRC: C3, C2, C0 ← 001;

ST = SRC: C3, C2, C0 ← 100;

IF instruction = FCOMP THEN pop ST; FI;

IF instruction = FCOMPP THEN pop ST; pop ST; FI;

FPU Flags	EFlags
C0	CF
C1	None
C2	PF
C3	ZF

### Description

The compare real instructions compare the stack top to the source, which can be a register or a single- or double-real memory operand. If no operand is encoded, ST is compared to ST(1). Following the instruction, the condition codes reflect the relation between ST and the source operand.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 as specified above.

### Numeric Exceptions

D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF (fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF (fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

If either operand is a NaN or is in an undefined format, or if a stack fault occurs, the invalid-operation exception is raised, and the condition bits are set to "unordered."

The sign of zero is ignored, so that  $-0.0 = +0.0$ .

**FCOS—Cosine**

Opcode	Instruction	Clocks	Description
D9 FF	FCOS	18-124	Replace ST with its cosine

**Operation**

IF operand is in range

THEN

    C2 ← 0;

    ST ← cos(ST);

ELSE

    C2 ← 1;

FI;

**Description**

The cosine instruction replaces the contents of ST with cos(ST). ST, expressed in radians, must lie in the range  $|\theta| < 2^{63}$ .

**FPU Flags Affected**

C1, C2 as described in Chapter 6; C0, C3 undefined.

**Numeric Exceptions**

P, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand is outside the acceptable range, the C2 flag is set, and ST remains unchanged. It is the programmer's responsibility to reduce the operand to an absolute value smaller than  $2^{63}$  by subtracting an appropriate integer multiple of  $2\pi$ . See Chapter 6 for a discussion of the proper value to use for  $\pi$  in performing such reductions.

**FDECSTP—Decrement Stack-Top Pointer**

Opcode	Instruction	Clocks	Description
D9 F6	FDECSTP	1	Decrement top-of-stack pointer for FPU register stack.

**Operation**

IF TOP=0  
 THEN TOP  $\leftarrow$  7;  
 ELSE TOP  $\leftarrow$  TOP-1;  
 FI;

**Description**

FDECSTP subtracts one (without carry) from the three-bit TOP field of the FPU status word.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

None.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

The effect of FDECSTP is to rotate the stack. It does not alter register tags or contents, nor does it transfer data.

**FDIV/FDIVP/FIDIV—Divide**

Opcode	Instruction	Clocks	Description
D8 /6	FDIV <i>m32real</i>	39	Divide ST by <i>m32real</i> .
DC /6	FDIV <i>m64real</i>	39	Divide ST by <i>m64real</i> .
D8 F0+i	FDIV ST, ST(i)	39	Divide ST by ST(i)
DC F8+i	FDIV ST(i), ST	39	Replace ST(i) with ST(i) ÷ ST
DE F8+i	FDIVP ST(i), ST	39	Replace ST(i) with ST(i) ÷ ST; pop ST.
DE F9	FDIVP	39	Replace ST(1) with ST(1) ÷ ST; pop ST.
DA /6	FIDIV <i>m32int</i>	42	Divide ST by <i>m32int</i> .
DE /6	FIDIV <i>m16int</i>	42	Divide ST by <i>m16int</i> .

**Operation**

FDIV DEST, SCR

DEST ← DEST ÷ SCR

IF instruction = FDIVP THEN pop ST FI;

**Description**

The division instructions divide the stack top by the other operand and return the quotient to the destination.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

P, U, O, Z, D, I, IS.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.

The performance of the division instructions depends on the PC (Precision Control) field of the FPU control word. If PC specifies a precision of 53 bits, the division instructions will execute in 33 clocks. If the specified precision is 24 bits, the division instructions will take only 19 clocks.

## FDIVR/FDIVRP/FIDIVR—Reverse Divide

Opcode	Instruction	Clocks	Description
D8 /7	FDIVR <i>m32real</i>	39	Replaces ST with <i>m32real</i> ÷ ST.
DC /7	FDIVR <i>m64real</i>	39	Replace ST with <i>m64real</i> ÷ ST.
D8 F8+i	FDIVR ST, ST(i)	39	Replace ST by ST(i) ÷ ST.
DC F0+i	FDIVR ST(i), ST	39	Divide ST(i) = ST ÷ ST(i).
DE F0+i	FDIVRP ST(i), ST	39	Divide ST(i) = ST ÷ ST(i) and pop ST.
DE F1	FDIVRP	39	Divide ST(1) = ST ÷ ST(1) and pop ST.
DA /7	FIDIVR <i>m32int</i>	42	Replace ST with <i>m32int</i> ÷ ST.
DE /7	FIDIVR <i>m16int</i>	42	Replace ST with <i>m16int</i> ÷ ST.

### Operation

FDIVR DEST, SRC

DEST ← SRC ÷ DEST

IF instruction = FDIVRP THEN pop ST FI;

### Description

The division instructions divide the other operand by the stack top and return the quotient to the destination.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, Z, D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.

The performance of the reverse division instructions depends on the PC (Precision Control) field of the FPU control word. If PC specifies a precision of 53 bits, the reverse division instructions will execute in 33 clocks. If the specified precision is 24 bits, the reverse division instructions will take only 19 clocks.

**FFREE—Free Floating-Point Register**

Opcode	Instruction	Clocks	Description
DD C0+i	FFREE ST(i)	1	Tag ST(i) as <i>empty</i> .

**Operation**

$TAG(i) \leftarrow 11B;$

**Description**

FFREE tags the destination register as *empty*.

**FPU Flags Affected**

C0, C1, C2, C3 undefined.

**Numeric Exceptions**

None.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

FFREE does not affect the contents of the destination register. The floating-point stack-top pointer (TOP) is also unaffected.



## FICOM/FICOMP—Compare Integer

Opcode	Instruction	Clocks	Description
DE /2	FICOM <i>m16int</i>	8/4	Compare ST with <i>m16int</i> .
DA /2	FICOM <i>m32int</i>	8/4	Compare ST with <i>m32int</i> .
DE /3	FICOMP <i>m16int</i>	8/4	Compare ST with <i>m16int</i> and pop ST.
DA /3	FICOMP <i>m32int</i>	8/4	Compare ST with <i>m32int</i> and pop ST.

### Operation

CASE (relation of operands) OF

Not comparable: C3, C2, C0 ← 111;

ST > SRC: C3, C2, C0 ← 000;

ST < SRC: C3, C2, C0 ← 001;

ST = SRC: C3, C2, C0 ← 100;

IF instruction = FICOMP THEN pop ST; FI;

FPU Flags	EFlags
C0	CF
C1	(none)
C2	PF
C3	ZF

### Description

The compare integer instructions compare the stack top to the source. Following the instruction, the condition codes reflect the relation between ST and the source operand.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 as specified above.

### Numeric Exceptions

D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

The memory operand is converted to extended-real format before the comparison is performed.

If either operand is a NaN or is in an undefined format, or if a stack fault occurs, the invalid-operation exception is raised, and the condition bits are set to "unordered."



## FILD—Load Integer

Opcode	Instruction	Clocks	Description
DF /0	FILD <i>m16int</i>	3/1	Push <i>m16int</i> onto the FPU stack.
DB /0	FILD <i>m32int</i>	3/1	Push <i>m32int</i> onto the FPU stack.
DF /5	FILD <i>m64int</i>	3/1	Push <i>m64int</i> onto the FPU stack.

### Operation

Decrement FPU stack-top pointer;  
ST(0) ← SRC;

### Description

FILD converts the source signed integer operand into extended-real format, and pushes it onto the FPU stack.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

The source is loaded without rounding error.

ST(7) must be empty to avoid causing an invalid-operation exception.

**FINCSTP—Increment Stack-Top Pointer**

Opcode	Instruction	Clocks	Description
D9 F7	FINCSTP	1	Increment top-of-stack pointer for FPU register stack.

**Operation**

IF TOP = 7  
 THEN TOP ← 0;  
 ELSE TOP ← TOP + 1;  
 FI;

**Description**

FINCSTP adds one (without carry) to the three-bit TOP field of the FPU status word.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

None.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

The effect of FINCSTP is to rotate the stack. It does not alter register tags or contents, nor does it transfer data. It is not equivalent to popping the stack, because it does not set the tag of the old stack-top to *empty*.

## FINIT/FNINIT—Initialize Floating-Point Unit

Opcode	Instruction	Clocks	Description
9B DB E3	FINIT	16	Initialize FPU after checking for unmasked floating-point error condition.
DB E3	FNINIT	12	Initialize FPU without checking for unmasked floating-point error condition.*

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

$CW \leftarrow 037FH$ ; (\* Control word \*)

$SW \leftarrow 0$ ; (\* Status word \*)

$TW \leftarrow FFFFH$ ; (\* Tag word \*)

$FEA \leftarrow 0$ ;  $FDS \leftarrow 0$ ; (\* Data pointer \*)

$FIP \leftarrow 0$ ;  $FOP \leftarrow 0$ ;  $FCS \leftarrow 0$ ; (\* Instruction pointer \*)

### Description

The initialization instructions set the FPU into a known state, unaffected by any previous activity.

The FPU control word is set to 037FH (round to nearest, all exceptions masked, 64-bit precision). The status word is cleared (no exception flags set, stack register R0=stack-top). The stack registers are all tagged as *empty*. The error pointers (both instruction and data) are cleared.

### FPU Flags Affected

C0, C1, C2, C3 cleared.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

**Notes**

FINIT checks for unmasked floating-point error conditions before performing the initialization; FNINIT does not.

On the Pentium processor, unlike the Intel387 math coprocessor, FINIT and FNINIT clear the error pointers.



## FIST/FISTP—Store Integer

Opcode	Instruction	Clocks	Description
DF /2	FIST <i>m16int</i>	6	Store ST in <i>m16int</i> .
DB /2	FIST <i>m32int</i>	6	Store ST in <i>m32int</i> .
DF /3	FISTP <i>m16int</i>	6	Store ST in <i>m16int</i> and pop ST.
DB /3	FISTP <i>m32int</i>	6	Store ST in <i>m32int</i> and pop ST.
DF /7	FISTP <i>m64int</i>	6	Store ST in <i>m64int</i> and pop ST.

### Operation

DEST ← ST(0);

IF instruction = FISTP THEN pop ST FI;

### Description

FIST converts the value in ST into a signed integer according to the RC field of the control word and transfers the result to the destination. ST remains unchanged. FIST accepts word and short integer destinations; FISTP accepts these and long integers as well.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, I, IS.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## FLD—Load Real

Opcode	Instruction	Clocks	Description
D9 /0	FLD <i>m32real</i>	1	Push <i>m32real</i> onto the FPU stack.
DD /0	FLD <i>m64real</i>	1	Push <i>m64real</i> onto the FPU stack.
DB /5	FLD <i>m80real</i>	3	Push <i>m80real</i> onto the FPU stack.
D9 C0+i	FLD ST(i)	1	Push ST(i) onto the FPU stack.

### Operation

Decrement FPU stack-top pointer;  
 ST(0) ← SRC;

### Description

FLD pushes the source operand onto the FPU stack. If the source is a register, the register number used is that before the stack-top pointer is decremented. In particular, coding

FLD ST(0)

duplicates the stack top.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



**Notes**

If the source operand is in single- or double-real format, it is automatically converted to the extended-real format. Loading an extended-real operand does not require conversion, so the I and D exceptions will not occur in this case.

ST(7) must be empty to avoid causing an invalid-operation exception.

## FLD1/FLDL2T/FLDL2E/ FLDPI/FLDLG2/FLDLN2/FLDZ—Load Constant

Opcode	Instruction	Clocks	Description
D9 E8	FLD1	2/2	Push +1.0 onto the FPU Stack.
D9 E9	FLDL2T	5/3	Push $\log_2 10$ onto the FPU Stack.
D9 EA	FLDL2E	5/3	Push $\log_2 e$ onto the FPU Stack.
D9 EB	FLDPI	5/3	Push $\pi$ onto the FPU Stack.
D9 EC	FLDLG2	5/3	Push $\log_{10} 2$ onto the FPU Stack.
D9 ED	FLDLN2	5/3	Push $\log_e 2$ onto the FPU Stack.
D9 EE	FLDZ	2/2	Push +0.0 onto the FPU Stack.

### Operation

Decrement FPU stack-top pointer;  
 $ST(0) \leftarrow \text{CONSTANT}$ ;

### Description

Each of the constant instructions pushes a commonly-used constant (in extended-real format) onto the FPU stack.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

ST(7) must be empty to avoid an invalid exception.

An internal 66-bit constant is used and rounded to external-real format (as specified by the RC bit of the control words). The precision exception is not raised.

**FLDCW—Load Control Word**

Opcode	Instruction	Clocks	Description
D9 /5	FNLDCW <i>m2byte</i>	7	Load FPU control word from <i>m2byte</i> .

**Operation**

$CW \leftarrow SRC;$

**Description**

FLDCW replaces the current value of the FPU control word with the value contained in the specified memory word.

**FPU Flags Affected**

C0, C1, C2, C3 undefined.

**Numeric Exceptions**

None, except for unmasking an existing exception.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

FLDCW is typically used to establish or change the FPU's mode of operation.

If an exception bit in the status word is set, loading a new control word that unmasks that exception will result in a floating-point error condition. When changing modes, the

recommended procedure is to clear any pending exceptions before loading the new control word.

## FLDENV—Load FPU Environment

Opcode	Instruction	Clocks	Description
D9 /4	FLDENV <i>m14/28byte</i>	<i>rm or vm=37</i> <i>16 bit pm=32</i> <i>32 bit pm=33</i>	Load FPU environment from <i>m14byte</i> or <i>m28byte</i> .

### Operation

FPU environment ← SRC;

### Description

FLDENV reloads the FPU environment from the memory area defined by the source operand. This data should have been written by previous FSTENV or FNSTENV instruction.

The FPU environment consists of the FPU control word, status word, tag word, and error pointers (both data and instruction). The environment layout in memory depends on both the operand size and the current operating mode of the processor. The USE attribute of the current code segment determines the operand size: the 14-byte operand applies to a USE16 segment, and the 28-byte operand applies to a USE32 segment. See Chapter 6 for figures of the environment layouts for both operand sizes in both real mode and protected mode. (In virtual-8086 mode, the real mode layout is used.) FLDENV should be executed in the same operating mode as the corresponding FSTENV or FNSTENV.

### FPU Flags Affected

C0, C1, C2, C3 as loaded.

### Numeric Exceptions

None, except for loading an unmasked exception.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.



**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the environment image contains an unmasked exception, loading it will result in a floating-point error condition.

## FMUL/FMULP/FIMUL—Multiply

Opcode	Instruction	Clocks	Description
D8 /1	FMUL <i>m32real</i>	3/1	Multiply ST by <i>m32real</i> .
DC /1	FMUL <i>m64real</i>	3/1	Multiply ST by <i>m64real</i> .
D8 C8+i	FMUL ST, ST(i)	3/1	Multiply ST by ST(i)
DC C8+i	FMUL ST(i), ST	3/1	Multiply ST(i) by ST.
DE C8+i	FMULP ST(i), ST	3/1	Multiply ST(i) by ST and pop ST.
DE C9	FMULP	3/1	Multiply ST(1) by ST and pop ST.
DA /1	FIMUL <i>m32int</i>	7/4	Multiply ST by <i>m32int</i> .
DE /1	FIMUL <i>m16int</i>	7/4	Multiply ST by <i>m16int</i> .

### Operation

DEST ← DEST x SRC;

IF instruction = FMULP THEN pop ST FI;

### Description

The multiplication instructions multiply the destination operand by the source operand and return the product to the destination.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, D, I.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.

## FNOP—No Operation

Opcode	Instruction	Clocks	Description
D9 D0	FNOP	1	No operation is performed.

### Description

FNOP performs no operation. It affects nothing except instruction pointers.

### FPU Flags Affected

C0, C1, C2, C3 undefined.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.



## FPATAN—Partial Arctangent

Opcode	Instruction	Clocks	Description
D9 F3	FPATAN	17-173	Replace ST(1) with $\arctan(\text{ST}(1) \div \text{ST})$ and pop ST.

### Operation

$\text{ST}(1) \leftarrow \arctan(\text{ST}(1) \div \text{ST});$   
pop ST;

### Description

The partial arctangent instruction computes the arctangent of  $\text{ST}(1) \div \text{ST}$ , and returns the computed value, expressed in radians, to ST(1). It then pops ST. The result has the same sign as the operand from ST(1), and a magnitude less than  $\pi$ .

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

There is no restriction on the range of arguments that FPATAN can accept.

The fact that FPATAN takes two arguments and computes the arctangent of their ratio simplifies the calculation of other trigonometric functions. For instance,  $\arcsin(x)$  (which is the arctangent of  $x \div \sqrt{1-x^2}$ ) can be computed using the following sequence of operations: Push x onto the FPU stack; compute  $\sqrt{1-x^2}$  and push the resulting value onto the stack; execute FPATAN.

**FPREM—Partial Remainder**

Opcode	Instruction	Clocks	Description
D9 F8	FPREM	16-64	Replace ST with the remainder obtained on dividing ST by ST(1).

**Operation**

$EXPDI\!F \leftarrow \text{exponent}(ST) - \text{exponent}(ST(1));$

IF  $EXPDI\!F < 64$

THEN

$Q \leftarrow$  integer obtained by chopping  $ST \div ST(1)$  toward zero;

$ST \leftarrow ST - (ST(1) \times Q);$

$C2 \leftarrow 0;$

$C0, C3, C1 \leftarrow$  three least-significant bits of  $Q;$  (\*  $Q2, Q1, Q0$  \*)

ELSE

$C2 \leftarrow 1;$

$N \leftarrow$  a number between 32 and 63;

$QQ \leftarrow$  integer obtained by chopping  $(ST \div ST(1)) \div 2^{EXPDI\!F-N}$  toward zero;

$ST \leftarrow ST - (ST(1) \times QQ \times 2^{EXPDI\!F-N});$

FI;

**Description**

The partial remainder instruction computes the remainder obtained on dividing ST by ST(1), and leaves the result in ST. The sign of the remainder is the same as the sign of the original dividend in ST. The magnitude of the remainder is less than that of the modulus.

**FPU Flags Affected**

C0, C1, C2, C3 as described in Chapter 6.

**Numeric Exceptions**

U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

## Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

FPREM produces an exact result; the precision (inexact) exception does not occur and the rounding control has no effect.

The FPREM instruction is not the remainder operation specified in IEEE Std 754. To get that remainder, the FPREM1 instruction should be used. FPREM is supported for compatibility with the 8087 and Intel287 math coprocessors.

FPREM works by iterative subtraction, and can reduce the exponent of ST by no more than 63 in one execution. If FPREM succeeds in producing a remainder that is less than the modulus, the function is complete and the C2 flag is cleared. Otherwise, C2 is set, and the result in ST is called the *partial* remainder. The exponent of the partial remainder is less than the exponent of the original dividend by at least 32. Software can re-execute the instruction (using the partial remainder in ST as the dividend) until C2 is cleared. A higher-priority interrupting routine that needs the FPU can force a context switch between the instructions in the remainder loop.

An important use of FPREM is to reduce the arguments of periodic functions. When reduction is complete, FPREM provides the three least-significant bits of the quotient in flags C3, C1, and C0. This is important in argument reduction for the tangent function (using a modulus of  $\pi/4$ ), because it locates the original angle in the correct one of eight sectors of the unit circle.

**FPREM1—Partial Remainder**

Opcode	Instruction	Clocks	Description
D9 F5	FPREM1	20-70	Replace ST with the remainder obtained on dividing ST by ST(1).

**Operation**

$EXPDI\!F \leftarrow \text{exponent}(ST) - \text{exponent}(ST(1));$

IF  $EXPDI\!F < 64$

THEN

$Q \leftarrow$  integer obtained by rounding  $ST \div ST(1)$  to to the nearest integer;  
 (\*or the nearest even integer if the result is exactly halfway between 2 integers

\*)

$ST \leftarrow ST - (ST(1) \times Q);$

$C2 \leftarrow 0;$

$C0, C3, C1 \leftarrow$  three least-significant bits of  $Q$ ; (\*  $Q2, Q1, Q0$  \*)

ELSE

$C2 \leftarrow 1;$

$N \leftarrow$  a number between 32 and 63;

$QQ \leftarrow$  integer obtained by chopping  $(ST \div ST(1)) \div 2^{EXPDI\!F-N}$  toward zero;

$ST \leftarrow ST - (ST(1) \times QQ \times 2^{EXPDI\!F-N};$

FI;

**Description**

The partial remainder instruction computes the remainder obtained on dividing ST by ST(1), and leaves the result in ST. The magnitude of the remainder is less than half the magnitude of the modulus.

**FPU Flags Affected**

C0, C1, C2, C3 as described in Chapter 6.

**Numeric Exceptions**

U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

## Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

FPREM1 produces an exact result; the precision (inexact) exception does not occur and the rounding control has no effect.

The FPREM1 instruction is the remainder operation specified in IEEE Std 754. It differs from FPREM in the way it rounds the quotient of ST and ST(1), when the exponent difference of  $\text{exp}(\text{ST}) - \text{exp}\text{ST}(1)$  is less than 64.

FPREM1 works by iterative subtraction, and can reduce the exponent of ST by no more than 63 in one execution. If FPREM1 succeeds in producing a remainder that is less than one half the modulus, the function is complete and the C2 flag is cleared. Otherwise, C2 is set, and the result in ST is called the *partial* remainder. The exponent of the partial remainder is less than the exponent of the original dividend by at least 32. Software can re-execute the instruction (using the partial remainder in ST as the dividend) until C2 is cleared. A higher-priority interrupting routine that needs the FPU can force a context switch between the instructions in the remainder loop.

An important use of FPREM1 is to reduce the arguments of periodic functions. When reduction is complete, FPREM1 provides the three least-significant bits of the quotient in flags C3, C1, and C0. This is important in argument reduction for the tangent function (using a modulus of  $\pi/4$ ), because it locates the original angle in the correct one of eight sectors of the unit circle.

**FPTAN—Partial Tangent**

Opcode	Instruction	Clocks	Description
D9 F2	FPTAN	17-173	Replace ST with its tangent and push 1 onto the FPU stack.

**Operation**

IF operand is in range  
THEN

$C2 \leftarrow 0$ ;  
     $ST \leftarrow \tan(ST)$ ;  
    Decrement stack-top pointer;  
     $ST \leftarrow 1.0$ ;

ELSE

$C2 \leftarrow 1$ ;

FI;

**Description**

The partial tangent instruction replaces the contents of ST with  $\tan(ST)$ , and then pushes 1.0 onto the FPU stack. ST, expressed in radians, must lie in the range  $|\theta| < 2^{63}$ .

**FPU Flags Affected**

C1, C2 as described in Chapter 6; C0, C3 undefined.

**Numeric Exceptions**

P, U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand is outside the acceptable range, the C2 flag is set, and ST remains unchanged. It is the programmer's responsibility to reduce the operand to an absolute value smaller than  $2^{63}$  by subtracting an appropriate integer multiple of  $2\pi$ . See Chapter 6 for a discussion of the proper value to use for  $\pi$  in performing such reductions.

The fact that FPTAN pushes 1.0 onto the FPU stack after computing  $\tan(ST)$  maintains compatibility with the 8087 and Intel287 math coprocessors, and simplifies the calculation of other trigonometric functions. For instance, the cotangent (which is the reciprocal of the tangent) can be computed by executing FDIVR after FPTAN.

ST(7) must be empty to avoid an invalid-operation exception.

**FRNDINT—Round to Integer**

Opcode	Instruction	Clocks	Description
D9 FC	FRNDINT	9-20	Round ST to an integer.

**Operation**

ST ← rounded ST;

**Description**

The round to integer instruction rounds the value in ST to an integer according to the RC field of the FPU control word.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

P, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

## FRSTOR—Restore FPU State

Opcode	Instruction	Clocks	Description
DD/4	FRSTOR <i>m94/108byte</i>	<i>16 bit rm or vm= 75 32 bit rm or vm= 95 pm = 70</i>	Load FPU state from <i>m94byte</i> or <i>m108byte</i> .

### Operation

FPU state ← SRC;

### Description

FRSTOR reloads the FPU state (environment and register stack) from the memory area defined by the source operand. This data should have been written by a previous FSAVE or FNSAVE instruction.

The FPU environment consists of the FPU control word, status word, tag word, and error pointers (both data and instruction). The environment layout in memory depends on both the operand size and the current operating mode of the processor. The USE attribute of the current code segment determines the operand size: the 14-byte operand applies to a USE16 segment, and the 28-byte operand applies to a USE32 segment. See Chapter 6 for the environment layouts for both operand sizes in both real mode and protected mode. (In virtual-8086 mode, the real mode layout is used.) The stack registers, beginning with ST and ending with ST(7), are in the 80 bytes that immediately follow the environment image. FRSTOR should be executed in the same operating mode as the corresponding FSAVE or FNSAVE.

### FPU Flags Affected

C0, C1, C2, C3 as loaded.

### Numeric Exceptions

None, except for loading an unmasked exception.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the state image contains an unmasked exception, loading it will result in a floating-point error condition.

## FSAVE/FNSAVE—Store FPU State

Opcode	Instruction	Clocks	Description
9B DD /6	FSAVE <i>m94/108byte</i>	<i>6 bit rm or vm=127</i> <i>32 bit rm or vm=151</i> <i>pm=124;</i> <i>+ at least 3 for</i> <i>FWAIT</i>	Store FPU state to <i>m94byte</i> or <i>m108byte</i> after checking for unmasked floating-point error condition. Then re-initialize the FPU.
DD /6	FNSAVE <i>m94/108byte</i>	<i>16 bit rm or vm=127</i> <i>32 bit rm or vm=151</i> <i>pm=124</i>	Store FPU state to <i>m94byte</i> or <i>m108byte</i> without checking for unmasked floating-point error condition*. Then re-initialize the FPU.

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

DEST ← FPU state;  
initialize FPU; (\* Equivalent to FNINIT \*)

### Description

The save instructions write the current FPU state (environment and register stack) to the specified destination, and then re-initialize the FPU. The environment consists of the FPU control word, status word, tag word, and error pointers (both data and instruction).

The state layout in memory depends on both the operand size and the current operating mode of the processor. The USE attribute of the current code segment determines the operand size: the 94-byte operand applies to USE16 segment, and the 108-byte operand applies to a USE32 segment. Chapter 6 for the environment layouts for both operand sizes in both real mode and protected mode. (In virtual-8086 mode, the real mode layout is used.) The stack registers, beginning with ST and ending with ST(7), are stored in the 80 bytes that immediately follow the environment image.

### FPU Flags Affected

C0, C1, C2, C3 cleared.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

FINIT/FNINIT must be used to initialize FPU state prior to using FSAVE/FNSAVE in FRC mode.

FSAVE and FNSAVE do not store the FPU state until all FPU activity is complete. Thus, the saved image reflects the state of the FPU after any previously decoded instruction has been executed.

If a program is to read from the memory image of the state following a save instruction, it must issue an FWAIT instruction to ensure that the storage is complete.

The save instructions are typically used when an operating system needs to perform a context switch, or an exception handler needs to use the FPU, or an application program wants to pass a "clean" FPU to a subroutine.



## FSCALE—Scale

Opcode	Instruction	Clocks	Description
D9 FD	FSCALE	20-31	Scale ST by ST(1).

### Operation

$ST \leftarrow ST \times 2^{ST(1)}$ ;

### Description

The scale instruction interprets the value in ST(1) as an integer, and adds this integer to the exponent of ST. Thus, FSCALE provides rapid multiplication or division by integral powers of 2.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

FSCALE can be used as an inverse to FXTRACT. Since FSCALE does not pop the exponent part, however, FSCALE must be followed by FSTP ST(1) in order to completely undo the effect of a preceding FXTRACT.

There is no limit on the range of the scale factor in ST(1). If the value is not integral, FSCALE uses the nearest integer smaller in magnitude; i.e., it chops the value toward 0. If the resulting integer is zero, the value in ST is not changed.

**FSIN—Sine**

Opcode	Instruction	Clocks	Description
D9 FE	FSIN	16-126	Replace ST with its sine.

**Operation**

IF operand is in range

THEN

    C2 ← 0;

    ST ← sin(ST);

ELSE

    C2 ← 1;

FI:

**Description**

The sine instruction replaces the contents of ST with sin(ST). ST, expressed in radians, must lie in the range  $|\theta| < 2^{63}$ .

**FPU Flags Affected**

C1, C2 as described in Chapter 6; C0, C3 undefined.

**Numeric Exceptions**

P, U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand is outside the acceptable range, the C2 flag is set, and ST remains unchanged. It is the programmer's responsibility to reduce the operand to an absolute value smaller than  $2^{63}$  by subtracting an appropriate integer multiple of  $2\pi$ . See Chapter 6 for a discussion of the proper value to use for  $\pi$  in performing such reductions.

**FSINCOS—Sine and Cosine**

Opcode	Instruction	Clocks	Description
D9 FB	FSINCOS	17-137	Compute the sine and cosine of ST; replace ST with the sine, and then push the cosine onto the FPU stack.

**Operation**

IF operand is in range

THEN

C2 ← 0;

TEMP ← cos(ST);

ST ← sin(ST);

Decrement FPU stack-top pointer;

ST ← TEMP;

ELSE

C2 ← 1;

FI:

**Description**

FSINCOS computes both sin(ST) and cos(ST), replaces ST with the sine and then pushes the cosine onto the FPU stack. ST, expressed in radians, must lie in the range  $|\theta| < 2^{63}$ .

**FPU Flags Affected**

C1, C2 as described in Chapter 6; C0, C3 undefined.

**Numeric Exceptions**

P, U, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand is outside the acceptable range, the C2 flag is set, and ST remains unchanged. It is the programmer's responsibility to reduce the operand to an absolute value smaller than  $2^{63}$  by subtracting an appropriate integer multiple of  $2\pi$ . See Chapter 6 for a discussion of the proper value to use for  $\pi$  in performing such reductions.

It is faster to execute FSINCOS than to execute both FSIN and FCOS.



**FSQRT—Square Root**

Opcode	Instruction	Clocks	Description
D9 FA	FSQRT	70	Replace ST with its square root.

**Operation**

ST ← square root of ST;

**Description**

The square root instruction replaces the value in ST with its square root.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

P, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

The square root of  $-0$  is  $-0$ .

## FST/FSTP—Store Real

Opcode	Instruction	Clocks	Description
D9 /2	FST <i>m32real</i>	2	Copy ST to <i>m32real</i> .
DD /2	FST <i>m64real</i>	2	Copy ST to <i>m64real</i> .
DD D0+i	FST ST(i)	1	Copy ST to ST(i).
D9 /3	FSTP <i>m32real</i>	2	Copy ST to <i>m32real</i> and pop ST.
DD /3	FSTP <i>m64real</i>	2	Copy ST to <i>m64real</i> and pop ST.
DB /7	FSTP <i>m80real</i>	3	Copy ST to <i>m80real</i> and pop ST.
DD D8+i	FSTP ST(i)	1	Copy ST to ST(i) and pop ST.

### Operation

DEST ← ST(0);

IF instruction = FSTP THEN pop ST FI;

### Description

FST copies the current value in the ST register to the destination, which can be another register or a single- or double-real memory operand. FSTP copies and then pops ST; it accepts extended-real memory operands as well as the types accepted by FST.

If the source is a register, the register number used is that before the stack is popped.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

Register or extended-real destinations. IS

Single- or double-real destinations: P, U, O, I, IS

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## FSTCW/FNSTCW—Store Control Word

Opcode	Instruction	Clocks	Description
9B D9 /7	FSTCW <i>m2byte</i>	2 + at least 1 for FWAIT	Store FPU control word to <i>m2byte</i> after checking for unmasked floating-point error condition.
D9 /7	FNSTCW <i>m2byte</i>	2	Store FPU control word to <i>m2byte</i> without checking for unmasked floating-point error condition.*

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

DEST ← CW;

### Description

FSTCW and FNSTCW write the current value of the FPU control word to the specified destination.

### FPU Flags Affected

C0, C1, C2, C3 undefined.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment, #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

FSTCW checks for unmasked floating-point error conditions before storing the control word; FNSTCW does not.



## FSTENV/FNSTENV—Store FPU Environment

Opcode	Instruction	Clocks	Description
9B D9 /6	FSTENV <i>m14/28byte</i>	16 bit <i>rm</i> or <i>vm</i> =50 32 bit <i>rm</i> or <i>vm</i> =48 16 bit <i>pm</i> =49 32 bit <i>pm</i> =50; + at least 3 for FWAIT	Store FPU environment to <i>m14byte</i> or <i>m28byte</i> after checking for unmasked floating-point error condition. Then mask all floating-point exceptions.
D9 /6	FNSTENV <i>m14/28byte</i>	16 bit <i>rm</i> or <i>vm</i> =50 32 bit <i>rm</i> or <i>vm</i> =48 16 bit <i>pm</i> =49 32 bit <i>pm</i> =50	Store FPU state to <i>m14byte</i> or <i>m28byte</i> without checking for unmasked floating-point error condition*. Then mask all floating-point exceptions.

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

DEST ← FPU environment;  
 CW[0..5] ← 111111B;  
 SW[15], SW[7] ← 0;

### Description

The store environment instructions write the current FPU environment to the specified destination, and then mask all floating-point exceptions. The FPU environment consists of the FPU control word, status word, tag word, and error pointer (both data and instruction).

The environment layout in memory depends on both the operand size and the current operating mode of the processor. The USE attribute of the current code segment determines the operand size: the 14-byte operand applies to a USE16 segment, and the 28-byte operand applies to a USE32 segment. Figures 6-6 through 6-8 show the environment layouts for both operand sizes in both real mode and protected mode. (In virtual-8086 mode, the real mode layout is used.)

### FPU Flags Affected

C0, C1, C2, C3 undefined.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### **Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### **Notes**

FSTENV and FNSTENV do not store the environment until all FPU activity is complete. Thus, the saved environment reflects the state of the FPU after any previously decoded instruction has been executed.

The store environment instructions are often used by exception handlers because they provide access to the FPU error pointers. The environment is typically saved onto the memory stack. After saving the environment, FSTENV and FNSTENV sets all the exception masks in the FPU control word. This prevents floating-point errors from interrupting the exception handler.

FSTENV checks for unmasked floating-point error conditions before storing the FPU environment; FNSTENV does not.



## FSTSW/FNSTSW—Store Status Word

Opcode	Instruction	Clocks	Description
9B DD /7	FSTSW <i>m2byte</i>	2 + at least 3 for FWAIT	Store FPU status word to <i>mbyte</i> after checking for unmasked floating-point error condition.
9B DF E0	FSTSW AX	2 + at least 3 for FWAIT	Store FPU status word to AX register after checking for unmasked floating-point error condition.
DD /7	FNSTSW <i>m2byte</i>	2	Store FPU status word to <i>m2byte</i> without checking for unmasked floating-point error condition.
DF E0	FNSTSW AX	2	Store FPU status word to AX register without checking for unmasked floating-point error condition.*

\* For Pentium® processor and Intel486™ processor implementation, please refer to section 23.3.7 of this document.

### Operation

DEST ← SW;

### Description

FSTSW and FNSTSW write the current value of the FPU status word to the specified destination, which can be either a two-byte location in memory or the AX register.

### FPU Flags Affected

C0, C1, C2, C3 undefined.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

FSTSW checks for unmasked floating-point error conditions before storing the status word; FNSTSW does not.

FSTSW and FNSTSW are used primarily in conditional branching (after a comparison, FPREM, FPREM1, or FXAM instruction). They can also be used to invoke exception handlers (by polling the exception bits) in environments that do not use interrupts.

When FNSTSW AX is executed, the AX register is updated before the Pentium processor executes any further instructions. The status stored is that from the completion of the prior ESC instruction.



## FSUB/FSUBP/FISUB—Subtract

Opcode	Instruction	Clocks	Description
D8 /4	FSUB <i>m32real</i>	3/1	Subtract <i>m32real</i> from ST.
DC /4	FSUB <i>m64real</i>	3/1	Subtract <i>m64real</i> from ST.
D8 E0+i	FSUB ST, ST(i)	3/1	Subtract ST(i) from ST→ST0.
DC E8+i	FSUB ST(i), ST	3/1	Replace ST(i) with ST –ST(i).
DE E8+i	FSUBP ST(i), ST	3/1	Replace ST(i) with ST –ST(i); pop ST.
DE E9	FSUBP	3/1	Replace ST(i) with ST –ST(i); pop ST.
DA /4	FISUB <i>m32int</i>	7/4	Subtract <i>m32int</i> from ST.
DE /4	FISUB <i>m16int</i>	7/4	Subtract <i>m16int</i> from ST.

### Operation

DEST ← ST – Other Operand;  
 IF instruction = FSUBP THEN pop ST FI;

### Description

The subtraction instructions subtract the other operand from the stack top and return the difference to the destination.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.



## FSUBR/FSUBRP/FISUBR—Reverse Subtract

Opcode	Instruction	Clocks	Description
D8 /5	FSUBR <i>m32real</i>	3/1	Replace ST with <i>m32real</i> – ST.
DC /5	FSUBR <i>m64real</i>	3/1	Replace ST with <i>m64real</i> – ST.
D8 E8+i	FSUBR ST, ST(i)	3/1	Replace ST with ST(i) – ST.
DC E0+i	FSUBR ST(i), ST	3/1	Subtract ST from ST(i)→ST(i).
DE E0+i	FSUBRP ST(i), ST	3/1	Subtract ST from ST(i) and pop ST.
DE E1	FSUBRP	3/1	Subtract ST from ST(1) and pop ST.
DA /5	FISUBR <i>m32int</i>	7/4	Replace ST with <i>m32int</i> – ST.
DE /5	FISUBR <i>m16int</i>	7/4	Replace ST with <i>m16int</i> – ST.

### Operation

DEST ← Other Operand – ST;  
 IF instruction = FSUBRP THEN pop ST FI;

### Description

The reverse subtraction instructions subtract the stack top from the other operand and return the difference to the destination.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, O, D, I, IS.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH; Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

If the source operand is in memory, it is automatically converted to the extended-real format.



## FTST—TEST

Opcode	Instruction	Clocks	Description
D9 E4	FTST	4/1	Compare ST with 0.0.

### Operation

CASE (relation of operands) OF

Not comparable: C3, C2, C0 ← 111;

ST > SRC: C3, C2, C0 ← 000;

ST < SRC: C3, C2, C0 ← 001;

ST = SRC: C3, C2, C0 ← 100;

FPU Flags	EFlags
C0	CF
C1	(none)
C2	PF
C3	ZF

### Description

The test instruction compares the stack top to 0.0. Following the instruction, the condition codes reflect the result of the comparison.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 as specified above.

### Numeric Exceptions

D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

**Notes**

If ST contains a NaN or an object of undefined format, or if a stack fault occurs, the invalid-operation exception is raised, and the condition bits are set to "unordered."

The sign of zero is ignored, so that  $-0.0=+0.0$ .



## FUCOM/FUCOMP/FUCOMPP—Unordered Compare Real

Opcode	Instruction	Clocks	Description
DD E0+i	FUCOM ST(i)	4/1	Compare ST with ST(i).
DD E1	FUCOM	4/1	Compare ST with ST(1).
DD E8+i	FUCOMP ST(i)	4/1	Compare ST with ST(i) and pop ST.
DD E9	FUCOMP	4/1	Compare ST with ST(1) and pop ST.
DA E9	FUCOMPP	4/1	Compare ST with ST(1) and pop ST twice.

### Operation

CASE (relation of operands) OF

Not comparable: C3, C2, C0 ← 111;

ST > SRC: C3, C2, C0 ← 000;

ST < SRC: C3, C2, C0 ← 001;

ST = SRC: C3, C2, C0 ← 100;

IF instruction = FUCOMP THEN pop ST; FI;

IF instruction = FUCOMPP THEN pop ST; pop ST; FI;

FPU Flags	EFlags
C0	CF
C1	(none)
C2	PF
C3	ZF

### Description

The unordered compare real instructions compare the stack top to the source, which must be a register. If no operand is encoded, ST is compared to ST(1). Following the instruction, the condition codes reflect the relation between ST and the source operand.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 as specified above.

### Numeric Exceptions

D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If either operand is an SNaN or is in an undefined format, or if a stack fault occurs, the invalid-operation exception is raised, and the condition bits are set to "unordered."

If either operand is a QNaN, the condition bits are set to "unordered." Unlike the ordinary compare instructions (FCOM, etc.), the unordered compare instructions do not raise the invalid-operation exception on account of a QNaN operand.

The sign of zero is ignored, so that  $-0.0 = +0.0$ .



**FWAIT—Wait**

Opcode	Instruction	Clocks	Description
9B	FWAIT	(1-3)	Alias for WAIT.

**Description**

FWAIT causes the processor to check for pending unmasked numeric exceptions before proceeding.

**FPU Flags Affected**

C0, C1, C2, C3 undefined.

**Numeric Exceptions**

None.

**Protected Mode Exceptions**

#NM if both MP and TS in CR0 are set.

**Real Address Mode Exceptions**

Interrupt 7 if both MP and TS in CR0 are set.

**Virtual 8086 Mode Exceptions**

#NM if both MP and TS in CR0 are set.

**Notes**

As its opcode shows, FWAIT is not actually an ESC instruction, but an alternate mnemonic for WAIT.

Coding FWAIT after an ESC instruction ensures that any unmasked floating-point exceptions the instruction may cause are handled before the processor has a chance to modify the instruction's results.

Information about when to use FWAIT is given in Chapter 6, in the section on "Concurrent Processing."

## FXAM—Examine

Opcode	Instruction	Clocks	Description
D9 E5	FXAM	21	Report the type of object in the ST register.

### Operation

C1 ← sign bit of ST; (\* 0 for positive, 1 for negative \*)

CASE (type of object in ST) OF

  Unsupported: C3, C2, C0 ← 000;

  NaN: C3, C2, C0 ← 001;

  Normal: C3, C2, C0 ← 010;

  Infinity: C3, C2, C0 ← 011;

  Zero: C3, C2, C0 ← 100;

  Empty: C3, C2, C0 ← 101;

  Denormal: C3, C2, C0 ← 110;

FPU Flags	EFlags
C0	CF
C1	(none)
C2	PF
C3	ZF

### Description

The examine instruction reports the type of object contained in the ST register by setting the FPU Flags.

### FPU Flags Affected

C0, C1, C2, C3 as shown above.

### Numeric Exceptions

None.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.



**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

C1 bit represents the sign of ST(0) regardless of whether ST(0) is empty or full.

## FXCH—Exchange Register Contents

Opcode	Instruction	Clocks	Description
D9 C8+i	FXCH ST(i)	1	Exchange the contents of ST and ST(i).
D9 C9	FXCH	1	Exchange the contents of ST and ST(1).

### Operation

TEMP ← ST;  
 ST ← DEST;  
 DEST ← TEMP;

### Description

FXCH swaps the contents of the destination and stack-top registers. If the destination is not coded explicitly, ST(1) is used.

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

Many numeric instructions operate only on the stack top; FXCH provides a simple means for using these instructions on lower stack elements. For example, the following sequence takes the square root of the third register from the top (assuming that ST is nonempty):

```
FXCH ST(3)
FSQRT
FXCH ST(3)
```



FXCH can be paired with some floating-point instructions (i.e., FADD, FSUB, FMUL, FLD, FCOM, FUCOM, FCHS, FTST, FABS, FDIV. This set also includes the FADDP, FSUBRP, etc. instructions.) When paired, the FXCH gets executed in parallel, and does not take any additional clocks.

## FXTRACT—Extract Exponent and Significand

Opcode	Instruction	Clocks	Description
D9 F4	FXTRACT	13	Separate ST into its exponent and significand; replace ST with the exponent and then push the significand onto the FPU stack.

### Operation

TEMP ← significand of ST;  
 ST ← exponent of ST;  
 Decrement FPU stack-top pointer;  
 ST ← TEMP;

### Description

FXTRACT splits the value in ST into its exponent and significand. The exponent replaces the original operand on the stack and the significand is pushed onto the stack. Following execution of FXTRACT, ST (the new stack top) contains the value of the original significand expressed as a real number: its sign is the same as the operand's, its exponent is 0 true (16,383 or 3FFFH biased), and its significand is identical to the original operand's. ST(1) contains the value of the original operand's true (unbiased) exponent expressed as a real number.

To illustrate the operation of FXTRACT, assume that ST contains a number whose true exponent is +4 (i.e., its exponent field contains 4003H). After executing FXTRACT, ST(1) will contain the real number +4.0; its sign will be positive, its exponent field will contain 4001H (+2 true) and its significand field will contain 1<sub>A</sub>00...00B. In other words, the value in ST(1) will be  $1.0 \times 2^2 = 4$ . If ST contains an operand whose true exponent is -7 (i.e., its exponent field contains 3FF8H), then FXTRACT will return an "exponent" of -7.0; after the instruction executes, ST(1)'s sign and exponent fields will contain C001H (negative sign, true exponent of 2), and its significand will be 1<sub>A</sub>1100...00B. In other words, the value in ST(1) will be  $-1.75 \times 2^2 = -7.0$ . In both cases, following FXTRACT, ST's sign and significand fields will be the same as the original operand's, and its exponent field will contain 3FFFH (0 true).

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

Z, D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

FXTRACT (extract exponent and significand) performs a superset of the IEEE-recommended  $\log_b(x)$  function.

If the original operand is zero, FXTRACT leaves  $-\infty$  in ST(1) (the exponent) while ST is assigned the value zero with a sign equal to that of the original operand. The zero-divide exception is raised in this case, as well.

ST(7) must be empty to avoid the invalid-operation exception.

FXTRACT is useful for power and range scaling operations. Both FXTRACT and the base 2 exponential instruction F2XM1 are needed to perform a general power operation. Converting numbers in extended-real format to decimal representations (e.g., for printing or displaying) requires not only FBSTP but also FXTRACT to allow scaling that does not overflow the range of the extended format. FXTRACT can also be useful for debugging, because it allows the exponent and significand parts of a real number to be examined separately.

**FYL2X—Compute  $y \times \log_2 x$** 

Opcode	Instruction	Clocks	Description
D9 F1	FYL2X	22-111	Replace ST(1) with $ST(1) \times \log_2 ST$ and pop ST.

**Operation**

$ST(1) \leftarrow ST(1) \times \log_2 ST;$   
pop ST;

**Description**

FYL2X computes the base-2 logarithm of ST, multiplies the logarithm by ST(1), and returns the resulting value to ST(1). It then pops ST. The operand in ST must not be negative or zero.

**FPU Flags Affected**

C1 as described in Chapter 6; C0, C2, C3 undefined.

**Numeric Exceptions**

P, U, O, Z, D, I, IS.

**Protected Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Real Address Mode Exceptions**

Interrupt 7 if either EM or TS in CR0 is set.

**Virtual 8086 Mode Exceptions**

#NM if either EM or TS in CR0 is set.

**Notes**

If the operand in ST is negative, the invalid-operation exception is raised.

The FYL2X instruction is designed with a built-in multiplication to optimize the calculation of logarithms with arbitrary positive base:

$$\log_b x = (\log_2 b)^{-1} \times \log_2 x$$

The instructions FLDL2T and FLDL2E load the constants  $\log_2 10$  and  $\log_2 e$ , respectively.

## FYL2XP1—Compute $y \times \log_2(x + 1)$

Opcode	Instruction	Clocks	Description
D9 F9	FYL2XP1	22-103	Replace ST(1) with $ST(1) \times \log_2(ST+1.0)$ and pop ST.

### Operation

$ST(1) \leftarrow ST(1) \times \log_2(ST+1.0);$   
 pop ST;

### Description

FYL2XP1 computes the base-2 logarithm of (ST+1.0), multiplies the logarithm by ST(1), and returns the resulting value to ST(1). It then pops ST. The operand in ST must be in the range

$$-(1-(\sqrt{2}/2)) \leq ST \leq \sqrt{2}-1$$

### FPU Flags Affected

C1 as described in Chapter 6; C0, C2, C3 undefined.

### Numeric Exceptions

P, U, D, I, IS.

### Protected Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Real Address Mode Exceptions

Interrupt 7 if either EM or TS in CR0 is set.

### Virtual 8086 Mode Exceptions

#NM if either EM or TS in CR0 is set.

### Notes

If the operand in ST is outside the acceptable range, the result of FYL2XP1 is undefined.

The FYL2XP1 instruction provides improved accuracy over FYL2X when computing the logarithms of numbers very close to 1. When  $\epsilon$  is small, more significant digits can be

retained by providing  $\epsilon$  as an argument to FYL2XP1 than by providing  $1+\epsilon$  as an argument to FYL2X.



## HLT—Halt

Opcode	Instruction	Clocks	Description
F4	HLT	∞	Halt

### Operation

Enter Halt state;

### Description

The HLT instruction stops instruction execution and places the processor in a HALT state. An enabled interrupt, NMI, or a reset will resume execution. If an interrupt (including NMI) is used to resume execution after an HLT instruction, the saved CS:IP (or CS:EIP) value points to the instruction following the HLT instruction.

### Flags Affected

None.

### Protected Mode Exceptions

The HLT instruction is a privileged instruction; #GP(0) if the current privilege level is not 0.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

#GP(0); the HLT instruction is a privileged instruction.

## IDIV—Signed Divide

Opcode	Instruction	Clocks	Description
F6 /7	IDIV AL, <i>r/m8</i>	22	Signed divide AX (where AH must contain sign-extension of AL) by <i>r/m</i> byte. (Results: AL=Quo, AH=Rem)
F7 /7	IDIV AX, <i>r/m16</i>	30	Signed divide DX:AX (where DX must contain sign-extension of AX) by <i>r/m</i> word. (Results: AX=Quo, DX=Rem)
F7 /7	IDIV EAX, <i>r/m32</i>	46	Signed divide EDX:EAX (where EDX must contain sign-extension of EAX) by <i>r/m</i> dword. (Results: EAX=Quo, EDX=Rem)

### Operation

```
temp ← dividend / divisor;
IF temp does not fit in quotient
THEN Interrupt 0;
ELSE
    quotient ← temp;
    remainder ← dividend MOD (r/m);
FI;
```

Notes: Divisions are signed. The dividend must be sign-extended. The divisor is given by the *r/m* operand. The dividend, quotient, and remainder use implicit registers. Refer to the table under "Description."

### Description

The IDIV instruction performs a signed division. The dividend, quotient, and remainder are implicitly allocated to fixed registers. Only the divisor is given as an explicit *r/m* operand. The type of the divisor determines which registers to use as follows:

Size	Divisor	Quotient	Remainder	Dividend
byte	<i>r/m8</i>	AL	AH	AX
word	<i>r/m16</i>	AX	DX	DX:AX
dword	<i>r/m32</i>	EAX	EDX	EDX:EAX

If the resulting quotient is too large to fit in the destination, or if the divisor is 0, an Interrupt 0 is generated. Nonintegral quotients are truncated toward 0. The remainder has the same sign as the dividend and the absolute value of the remainder is always less than the absolute value of the divisor.

### Flags Affected

The OF, SF, ZF, AF, PF, CF flags are undefined.

### Protected Mode Exceptions

Interrupt 0 if the quotient is too large to fit in the designated register (AL or AX), or if the divisor is 0; #GP (0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 0 if the quotient is too large to fit in the designated register (AL or AX), or if the divisor is 0; Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## IMUL—Signed Multiply

Opcode	Instruction	Clocks	Description
F6 /5	IMUL <i>r/m8</i>	11	AX ← AL * <i>r/m</i> byte
F7 /5	IMUL <i>r/m16</i>	11	DX:AX ← AX * <i>r/m</i> word
F7 /5	IMUL <i>r/m32</i>	10	EDX:EAX ← EAX * <i>r/m</i> dword
0F AF /r	IMUL <i>r16,r/m16</i>	10	word register ← word register * <i>r/m</i> word
0F AF /r	IMUL <i>r32,r/m32</i>	10	dword register ← dword register * <i>r/m</i> dword
6B /r ib	IMUL <i>r16,r/m16,imm8</i>	10	word register ← <i>r/m16</i> * sign-extended immediate byte
6B /r ib	IMUL <i>r32,r/m32,imm8</i>	10	dword register ← <i>r/m32</i> * sign-extended immediate byte
6B /r ib	IMUL <i>r16,imm8</i>	10	word register ← word register * sign-extended immediate byte
6B /r ib	IMUL <i>r32,imm8</i>	10	dword register ← dword register * sign-extended immediate byte
69 /r iw	IMUL <i>r16,r/m16,imm16</i>	10	word register ← <i>r/m16</i> * immediate word
69 /r id	IMUL <i>r32,r/m32,imm32</i>	10	dword register ← <i>r/m32</i> * immediate dword
69 /r iw	IMUL <i>r16,imm16</i>	10	word register ← <i>r/m16</i> * immediate word
69 /r id	IMUL <i>r32,imm32</i>	10	dword register ← <i>r/m32</i> * immediate dword

### Operation

result ← multiplicand \* multiplier;

### Description

The IMUL instruction performs signed multiplication. Some forms of the instruction use implicit register operands. The operand combinations for all forms of the instruction are shown in the "Description" column above.

The IMUL instruction clears the OF and CF flags under the following conditions (otherwise the CF and OF flags are set):

Instruction Form	Condition for Clearing CF and OF
<i>r/m8</i>	AL = sign-extend of AL to 16 bits
<i>r/m16</i>	AX = sign-extend of AX to 32 bits
<i>r/m32</i>	EDX:EAX = sign-extend of EAX to 32 bits
<i>r16,r/m16</i>	Result exactly fits within r16
<i>r/32,r/m32</i>	Result exactly fits within r32
<i>r16,r/m16,imm16</i>	Result exactly fits within r16
<i>r32,r/m32,imm32</i>	Result exactly fits within r32

### Flags Affected

The OF and CF flags as described in the table in the "Description" section above; the SF, ZF, AF, and PF flags are undefined.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

When using the accumulator forms (IMUL *r/m8*, IMUL *r/m16*, or IMUL *r/m32*), the result of the multiplication is available even if the overflow flag is set because the result is twice the size of the multiplicand and multiplier. This is large enough to handle any possible result.

**IN—Input from Port**

Opcode	Instruction	Clocks	Description
E4 <i>ib</i>	IN AL, <i>imm8</i>	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input byte from immediate port into AL
E5 <i>ib</i>	IN AX, <i>imm8</i>	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input byte from immediate port into AX
E5 <i>ib</i>	IN EAX, <i>imm8</i>	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input byte from immediate port into EAX
EC	IN AL,DX	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input byte from port DX into AL
ED	IN AX,DX	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input word from port DX into AX
ED	IN EAX,DX	7, <i>pm=4*/</i> 21**, <i>vm=19</i>	Input dword from port DX into EAX

**NOTES:**\*If  $CPL \leq IOPL$ \*\*If  $CPL \geq IOPL$ **Operation**

IF (PE = 1) AND ((VM = 1) OR (CPL &gt; IOPL))

THEN (\* Virtual 8086 mode, or protected mode with CPL &gt; IOPL \*)

IF NOT I-O-Permission (SRC, width(SRC))

THEN #GP(0);

FI;

FI;

DEST ← [SRC]; (\* Reads from I/O address space \*)

**Description**

The IN instruction transfers a data byte or data word from the port numbered by the second operand into the register (AL, AX, or EAX) specified by the first operand. Access any port from 0 to 65535 by placing the port number in the DX register and using an IN instruction with the DX register as the second parameter. These I/O instructions can be shortened by using an 8-bit port I/O in the instruction. The upper eight bits of the port address will be 0 when 8-bit port I/O is used.

**Flags Affected**

None.

**Protected Mode Exceptions**

#GP(0) if the current privilege level is larger (has less privilege) than the I/O privilege level and any of the corresponding I/O permission bits in TSS equals 1.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

#GP(0) fault if any of the corresponding I/O permission bits in TSS equals 1.

## INC—Increment by 1

Opcode	Instruction	Clocks	Description
FE /0	INC <i>r/m8</i>	1/3	Increment <i>r/m</i> byte by 1
FF /0	INC <i>r/m16</i>	1/3	Increment <i>r/m</i> word by 1
FF /0	INC <i>r/m32</i>	1/3	Increment <i>r/m</i> dword by 1
40+ <i>rw</i>	INC <i>r16</i>	1	Increment word register by 1
40+ <i>rd</i>	INC <i>r32</i>	1	Increment dword register by 1

### Operation

DEST ← DEST + 1;

### Description

The INC instruction adds 1 to the operand. It does not change the CF flag. To affect the CF flag, use the ADD instruction with a second operand of 1.

### Flags Affected

The OF, SF, ZF, AF, and PF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the operand is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## INS/INSB/INSW/INSD—Input from Port to String

Opcode	Instruction	Clocks	Description
6C	INS <i>m8</i> ,DX	9,pm=6*/ 24**,VM=22	Input byte from port DX into ES:(E)DI
6D	INS <i>m16</i> ,DX	9,pm=6*/ 24**,VM=22	Input word from port DX into ES:(E)DI
6D	INS <i>m32</i> ,DX	9,pm=6*/ 24**,VM=22	Input dword from port DX into ES:(E)DI
6C	INSB	9,pm=6*/ 24**,VM=22	Input byte from port DX into ES:(E)DI
6D	INSW	9,pm=6*/ 24**,VM=22	Input word from port DX into ES:(E)DI
6D	INSD	9,pm=6*/ 24**,VM=22	Input dword from port DX into ES:(E)DI

### NOTES:

\*If  $CPL \leq IOPL$

\*\*If  $CPL > IOPL$

### Operation

```

IF AddressSize = 16
THEN use DI for dest-index;
ELSE (* AddressSize = 32 *)
  use EDI for dest-index;
FI;
IF (PE = 1) AND ((VM = 1) OR (CPL > IOPL))
THEN (* Virtual 8086 mode, or protected mode with CPL > IOPL *)
  IF NOT I-O-Permission (SRC, width(SRC))
  THEN #GP(0);
  FI;
FI;
IF byte type of instruction
THEN
  ES:[dest-index] ← [DX]; (* Reads byte at DX from I/O address space *)
  IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;
FI;
IF OperandSize = 16
THEN
  ES:[dest-index] ← [DX]; (* Reads word at DX from I/O address space *)
  IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;
FI;
IF OperandSize = 32
THEN
  ES:[dest-index] ← [DX]; (* Reads dword at DX from I/O address space *)
  IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI; FI;
dest-index ← dest-index + IncDec;
  
```

## Description

The INS instruction transfers data from the input port numbered by the DX register to the memory byte or word at ES:dest-index. The memory operand must be addressable from the ES register; no segment override is possible. The destination register is the DI register if the address-size attribute of the instruction is 16 bits, or the EDI register if the address-size attribute is 32 bits.

The INS instruction does not allow the specification of the port number as an immediate value. The port must be addressed through the DX register value. Load the correct value into the DX register before executing the INS instruction.

The destination address is determined by the contents of the destination index register. Load the correct index into the destination index register before executing the INS instruction.

After the transfer is made, the DI or EDI register advances automatically. If the DF flag is 0 (a CLD instruction was executed), the DI or EDI register increments; if the DF flag is 1 (an STD instruction was executed), the DI or EDI register decrements. The DI register increments or decrements by 1 if a byte is input, by 2 if a word is input, or by 4 if a doubleword is input.

The INSB, INSW and INSD instructions are synonyms of the byte, word, and doubleword INS instructions. The INS instruction can be preceded by the REP prefix for block input of CX bytes or words. Refer to the REP instruction for details of this operation.

## Flags Affected

None.

## Protected Mode Exceptions

#GP(0) if the current privilege level is numerically greater than the I/O privilege level and any of the corresponding I/O permission bits in TSS equals 1; #GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the ES, segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

## Virtual 8086 Mode Exceptions

#GP(0) fault if any of the corresponding I/O permission bits in TSS equals 1; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## INT/INTO—Call to Interrupt Procedure

Opcode	Instruction	Clocks	Description
CC	INT 3	13	Interrupt 3—trap to debugger
CC	INT 3	27	Interrupt 3—Protected Mode, same privilege
CC	INT 3	44	Interrupt 3—Protected Mode, more privilege
CC	INT 3	56	Interrupt 3—from V86 mode to PL 0
CC	INT 3	19+TS	Interrupt 3—Protected Mode, via task gate
CD <i>ib</i>	INT <i>imm8</i>	16	Interrupt numbered by immediate byte
CD <i>ib</i>	INT <i>imm8</i>	31	Interrupt—Protected Mode, same privilege
CD <i>ib</i>	INT <i>imm8</i>	48	Interrupt—Protected Mode, more privilege
CD <i>ib</i>	INT <i>imm8</i>	82	Interrupt—from V86 mode to PL 0
CD <i>ib</i>	INT <i>imm8</i>	23+TS	Interrupt—Protected Mode, via task gate
CE	INTO	Pass: 13, Fail: 4	Interrupt 4—if overflow flag is 1
CE	INTO	Pass: 27, Fail: 4	Interrupt 4—Protected Mode, same privilege
CE	INTO	Pass: 44, Fail: 4	Interrupt 4—Protected Mode, more privilege
CE	INTO	Pass: 56, Fail: 4	Interrupt 4—from V86 mode to PL 0
CE	INTO	Pass: 19+TS, Fail: 4	Interrupt 4—Protected Mode, via task gate

**NOTE:** Approximate values of **TS** are given by the following table:

Old Task	New Task		
	To 32-Bit TSS	To 16-Bit TSS	To VM TSS
V86/32-bit/16-bit TSS	85	87	71

### Operation

**NOTE:** The following operational description applies not only to the above instructions but also to external interrupts and exceptions.

```

IF PE = 0
THEN CALL REAL-ADDRESS-MODE;
ELSE
  CALL PROTECTED-MODE;
  IF task gate
  THEN CALL TASK-GATE;
  ELSE
    CALL TRAP-OR-INT-GATE; (* PE=1, int/trap gate *)
    IF code segment is non-conforming AND DPL < CPL
    THEN
      IF VM=0
      THEN CALL INT-TO-INNER-PRIV; (*PE=1,int/trap gate,DPL<CPL, VM=0*)
      ELSE CALL INT-FROM-V86-MODE; (* PE=1, int/trap gate, DPL<CPL,
        VM=1 *)
    FI;
  ELSE (* PE=1, int/trap gate, DPL ≥ CPL *)
    IF code segment is conforming OR code segment DPL = CPL
    THEN CALL INT-TO-SAME-PRIV;
  
```

## INSTRUCTION SET

```

        ELSE #GP(CS selector + EXT); (* PE=1, int/trap gate, DPL>CPL *)
        FI;
    FI;
FI;
END;

```

### REAL-ADDRESS-MODE PROC

```

    Push (FLAGS);
    IF ← 0; (* Clear interrupt flag *)
    TF ← 0; (* Clear trap flag *)
    AC ← 0; (* Clear AC flag *)
    Push(CS);
    Push(IP);
    (* No error codes are pushed *)
    CS ← IDT[Interrupt number * 4].selector;
    IP ← IDT[Interrupt number * 4].offset;
    (* Start execution in real address mode *)
REAL-ADDRESS-MODE ENDPROC

```

### PROTECTED-MODE PROC

```

    Interrupt vector must be within IDT table limits,
        else #GP(vector number * 8+2+EXT);
    Descriptor AR byte must indicate interrupt gate, trap gate, or task gate,
        else #GP(vector number * 8+2+EXT);
    IF software interrupt (* i.e. caused by INT n, INT 3, or INTO *)
    THEN
        IF gate descriptor DPL < CPL
        THEN #GP(vector number * 8:2+EXT); (* PE=1, DPL<CPL, software interrupt *)
        FI;
    FI;
    Gate must be present, else #NP(vector number * 8+2+EXT);
PROTECTED-MODE ENDPROC

```

### TRAP-OR-INT-GATE PROC

```

    Examine CS selector and descriptor given in the gate descriptor;
    Selector must be non-null, else #GP (EXT);
    Selector must be within its descriptor table limits
        ELSE #GP(selector+EXT);
    Descriptor AR byte must indicate code segment
        ELSE #GP(selector + EXT);
    Segment must be present, else #NP(selector+EXT);
TRAP-OR-INT-GATE ENDPROC

```

### INT-TO-INNER-PRIV PROC

```

(* PE=1, DPL<CPL and non-conforming, (* PE=1, int/trap gate, DPL<CPL, VM=0 *)
Check selector and descriptor for new stack in current TSS;
  Selector must be non-null, else #TS(EXT);
  Selector index must be within its descriptor table limits
  ELSE #TS(SS selector+EXT);
  Selector's RPL must equal DPL of code segment, else #TS(SS
  selector+EXT);
  Stack segment DPL must equal DPL of code segment, else #TS(SS
  selector+EXT);
  Descriptor must indicate writable data segment, else #TS(SS
  selector+EXT);
  Segment must be present, else #SS(SS selector+EXT);
IF 32-bit gate
THEN New stack must have room for 20 bytes else #SS(0)
ELSE New stack must have room for 10 bytes else #SS(0)
FI;
Instruction pointer must be within CS segment boundaries else #GP(0);
Load new SS and eSP value from TSS;
IF 32-bit gate
  THEN CS:EIP ← selector:offset from gate;
  ELSE CS:IP ← selector:offset from gate;
FI;
Load CS descriptor into invisible portion of CS register;
Load SS descriptor into invisible portion of SS register;
IF 32-bit gate
THEN
  Push (long pointer to old stack) (* 3 words padded to 4 *);
  Push (EFLAGS);
  Push (long pointer to return location) (* 3 words padded to 4*);
ELSE
  Push (long pointer to old stack) (* 2 words *);
  Push (FLAGS);
  Push (long pointer to return location) (* 2 words *);
FI;
Push error code (if needed) 16 bit 2 bytes, 32 bit 4 bytes
Set CPL to new code segment DPL;
Set RPL of CS to CPL;
IF interrupt gate THEN IF ← 0 (* interrupt flag to 0 (disabled) *); FI;
TF ← 0;
NT ← 0;
INT-FROM-INNER-PRIV ENDPROC

INT-FROM-V86-MODE PROC
Check selector and descriptor for new stack in current TSS;
  Selector must be non-null, else #TS(EXT);
  Selector index must be within its descriptor table limits
  ELSE #TS(SS selector+EXT);

```

```

Selector's RPL must equal DPL of code segment, else #TS(SS
  selector+EXT);
Stack segment DPL must equal DPL of code segment, else #TS(SS
  selector+EXT);
Descriptor must indicate writable data segment, else #TS(SS
  selector+EXT);
Segment must be present, else #SS(SS selector+EXT);
IF 32-bit gate
  THEN New stack must have room for 20 bytes else #SS(0)
  ELSE New stack must have room for 10 bytes else #SS(0)
FI;
Instruction pointer must be within CS segment boundaries else #GP(0);
IF IOPL < 3
  THEN
    #GP(0); (*V86 monitor trap: PE=1,int/trap gate, DPL<CPL, VM=1, IOPL<3*)
  ELSE (* IOPL=3 *)
    IF GATE'S_DPL = 3
      THEN
        IF TARGET'S_CPL ≠ 0
          THEN #GP(0);
        ELSE
          TempEFlags ← EFLAGS;
          VM ← 0;
          TF ← 0;
          IF service through Interrupt Gate
            THEN IF ← 0;
          FI;
          TempSS ← SS;
          TempESP ← ESP;
          SS ← TSS.SS0; (* Change to level 0 stack segment *)
          ESP ← TSS.ESP0; (* Change to level 0 stack pointer *)
          Push(GS); (* padded to two words *)
          Push(FS); (* padded to two words *)
          Push(DS); (* padded to two words *)
          Push(ES); (* padded to two words *)
          GS ← 0; (* segment registers nullified - invalid in protected mode *)
          FS ← 0;
          DS ← 0;
          ES ← 0;
          Push(TempSS); (* Padded to two words *)
          Push(TempESP);
          Push(TempEFlags);
          Push(CS); (* Padded to two words *)
          Push(EIP);
          CS:EIP ← selector:offset from interrupt gate;
          (* Starts execution of new routine in Protected Mode *)
        FI;
      FI;
    FI;
  FI;

```

```

        ELSE (* GATE'S_DPL ≠ 3 *)
            #GP(0);
        FI;
    FI;
INT-FROM-V86-MODE ENDPROC

INT-TO-SAME-PRIV PROC
    (* PE=1, DPL=CPL or conforming segment *)
    IF 32-bit gate
    THEN Current stack limits must allow pushing 10 bytes, else #SS(0);
    ELSE Current stack limits must allow pushing 6 bytes, else #SS(0);
    FI;
    IF interrupt was caused by exception with error code
    THEN Stack limits must allow push of two more bytes in 16-bit gate or 4 more bytes in
        32-bit gate;
    ELSE #SS(0);
    FI;
    Instruction pointer must be in CS limit, else #GP(0);
    IF 32-bit gate
    THEN
        Push (EFLAGS);
        Push (long pointer to return location); (* 3 words padded to 4 *)
        CS:EIP ← selector:offset from gate;
    ELSE (* 16-bit gate *)
        Push (FLAGS);
        Push (long pointer to return location); (* 2 words *)
        CS:IP ← selector:offset from gate;
    FI;
    Load CS descriptor into invisible portion of CS register;
    Set the RPL field of CS to CPL;
    Push (error code); (* if any *)
    IF interrupt gate THEN IF ← 0; FI;
    TF ← 0;
    NT ← 0;
INT-TO-SAME-PRIV ENDPROC

TASK-GATE PROC (* PE=1, task gate *)
    Examine selector to TSS, given in task gate descriptor;
    Must specify global in the local/global bit, else #TS(TSS selector);
    Index must be within GDT limits, else #TS(TSS selector);
    AR byte must specify available TSS (bottom bits 00001),
        else #TS(TSS selector);
    TSS must be present, else #NP(TSS selector);
    SWITCH-TASKS with nesting to TSS;
    IF interrupt was caused by fault with error code
    THEN
        Stack limits must allow push of two more bytes, else #SS(0);

```

## INSTRUCTION SET



Push error code onto stack;

FI;

Instruction pointer must be in CS limit, else #GP(0);

TASK-GATE ENDPROC



**Decision Table**

The following decision table indicates which action in the lower portion of the table is taken given the conditions in the upper portion of the table. Each Y in the lower section of the decision table represents a procedure defined above in the Operation section for this instruction (except #GP(0)) and the number following the Y indicates the order in which the procedure is executed.

<b>PE</b>	0	1	1	1	1	1	1	1
<b>VM</b>	-	-	-	-	-	0	1	1
<b>IOPL</b>	-	-	-	-	-	-	<3	=3
<b>DPL/CPL RELATIONSHIP</b>	-	DPL< CPL	-	DPL> CPL	DPL= CPL or C	DPL< CPL & NC	-	-
<b>INTERRUPT TYPE</b>	-	S/W	-	-	-	-	-	-
<b>GATE TYPE</b>	-	-	Task	Trap or Int	Trap or Int	Trap or Int	Trap or Int	Trap or Int
<b>REAL-ADDRESS-MODE</b>	Y							
<b>PROTECTED-MODE</b>		Y1	Y1	Y1	Y1	Y1	Y1	Y1
<b>TRAP-OR-INT-GATE</b>				Y2	Y2	Y2	Y2	Y2
<b>INT-TO-INNER-PRIV</b>						Y3		
<b>INT-TO-SAME-PRIV</b>					Y3			
<b>INT-FROM-V86-MODE</b>								Y3
<b>TASK-GATE</b>			Y2					
<b>#GP</b>		Y2		Y3			Y3	

**NOTES:**

- Don't Care  
 Yx Yes, Action Taken, x = the order of execution  
 Blank Action Not Taken

**Description**

The INT *n* instruction generates a call to an interrupt handler. The immediate operand, from 0 to 255, gives the index number into the Interrupt Descriptor Table (IDT) of the interrupt routine to be called. In protected mode, the IDT consists of an array of eight-byte descriptors; the descriptor for the interrupt invoked must indicate an interrupt, trap, or task gate. In real-address mode, the IDT is an array of four byte-long pointers. In protected and real-address

modes, the base linear address of the IDT is defined by the contents of the IDTR. The initial value of IDTR is zero upon reset into real-address mode.

When the processor is executing in virtual-8086 mode (VM=1), the IOPL determines whether the INT *n* causes a general protection exception (IOPL<3) or executes a protected mode interrupt to privilege level 0. The interrupt gate's DPL must be set to three and the target CPL of the interrupt service routine must be zero to execute the protected mode interrupt to privilege level 0.

The INTO conditional software instruction is identical to the INT *n* interrupt instruction except that the interrupt number is implicitly 4, and the interrupt is made only if the overflow flag is set.

The first 32 interrupts are reserved by Intel for system use. Some of these interrupts are used for internally generated exceptions.

The INT *n* instruction generally behaves like a far call except that the flags register is pushed onto the stack before the return address. Interrupt procedures return via the IRET instruction, which pops the flags and return address from the stack.

In Real Address Mode, the INT *n* instruction pushes the flags, the CS register, and the return IP onto the stack, in that order, then jumps to the long pointer indexed by the interrupt number.

### Flags Affected

None.

### Protected Mode Exceptions

#GP, #NP, #SS, and #TS as indicated under "Operation" above.

### Real Address Mode Exceptions

None; if the SP or ESP register is 1, 3, or 5 before executing the INT or INTO instruction, the processor will shut down due to insufficient stack space.

### Virtual 8086 Mode Exceptions

#GP(0) fault if IOPL is less than 3, for the INT *n* instruction only, to permit emulation; Interrupt 3 (0CCH) generates a breakpoint exception; the INTO instruction generates an overflow exception if the OF flag is set.

### Notes

For obtaining information on this instruction using virtual mode extensions, see Appendix H.



**INVD—Invalidate Cache**

Opcode	Instruction	Clocks	Description
0F 08	INVD	15	Invalidate Entire Cache

**Operation**

INVALIDATE INTERNAL CACHE  
 SIGNAL EXTERNAL CACHE TO INVALIDATE

**Description**

The internal cache is invalidated, and a special-function bus cycle is issued which indicates that external caches should also be invalidated. Data held in write-back external caches is not instructed to be written back.

**Flags Affected**

None.

**Protected Mode Exceptions**

The INVD instruction is a privileged instruction; #GP(0) if the current privilege level is not 0.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

#GP(0); the INVD instruction is a privileged instruction.

**Notes**

INVD should be used with care. It does not writeback modified cache lines; therefore, it can cause the data cache to become inconsistent with other memories in the system. Unless there is a specific requirement or benefit to invalidate a cache without writing back the modified lines (i.e., testing or fault recovery where cache coherency with main memory is not a concern), software should use the WBINVD instruction.

This instruction is implementation-dependent; its function may be implemented differently on future Intel processors.

This instruction does not wait for the external cache to complete its invalidation before the processor proceeds. It is the responsibility of hardware to respond to the external cache invalidation indication.

This instruction is not supported on Intel386 processors. See Section Chapter 9 for CPUID detection at run time. See the WBINVD description to writeback dirty data to memory.

See Chapter 18 on disabling the cache.



**INVLPG—Invalidate TLB Entry**

Opcode	Instruction	Clocks	Description
0F 01/7	INVLPG m	25	Invalidate TLB Entry

**Operation**

INVALIDATE RELEVANT TLB ENTRY(S)

**Description**

The INVLPG instruction is used to invalidate entries in the TLB.

**Flags Affected**

None.

**Protected Mode Exceptions**

The INVLPG instruction is a privileged instruction; #GP(0) if the current privilege level is not 0. An invalid-opcode exception is generated when used with a register operand.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

An invalid-opcode exception is generated when used with a register operand. #GP(0); the INVLPG instruction is a privileged instruction.

**Notes**

This instruction is not supported on Intel386 processors. See Section Chapter 16 for detecting processor type at run time.

See Chapter 18 for information on disabling the cache.

**IRET/IRETD—Interrupt Return**

Opcode	Instruction	Clocks	Description
CF	IRET	8	Interrupt return (from real or V86 mode)
CF	IRET	10	Interrupt return (far return and pop flags)
CF	IRET	27	Interrupt return to lesser privilege
CF	IRET	TS+10	Interrupt return, different task (NT = 1)
CF	IRETD	10	Interrupt return (far return and pop flags)
CF	IRETD	27	Interrupt return to lesser privilege
CF	IRETD	TS+10	Interrupt return, different task (NT = 1)

**NOTE:** Values of **TS** are given by the following table:

Old Task	New Task		
	To 32-Bit TSS	To 16-Bit TSS	To VM TSS
VM/32-bit/16-bit	85	87	71

**Operation**

```
IF PE = 0
THEN GOTO REAL_ADDRESS_MODE;;
ELSE GOTO PROTECTED_MODE;
FI;
```

```
REAL_ADDRESS_MODE;
  IF OperandSize = 32 (* Instruction = IRETD *)
  THEN EIP ← Pop( );
  ELSE (* Instruction = IRET *)
    IP ← Pop( );
  FI;
  CS ← Pop( );
  IF OperandSize = 32 (* Instruction = IRETD *)
  THEN Pop( ); EFLAGS ← Pop( );
  ELSE (* Instruction = IRET *)
    FLAGS ← Pop( );
  FI;
END;
```

```
PROTECTED_MODE:
  IF VM = 1 (* Virtual mode: PE=1, VM=1*)
  THEN GOTO STACK_RETURN_FROM_V86; (* PE=1, VM=1 *)
  ELSE
    IF NT=1
    THEN GOTO TASK_RETURN;(* PE=1, VM=1, NT=1 *)
    ELSE
      IF VM=1 in flags image on stack
      THEN GOTO STACK_RETURN_TO_V86; (* PE=1, VM=1 in flags
        image *)
```

```

        ELSE GOTO STACK_RETURN; (* PE=1, VM=0 in flags image *)
    FI;
FI;
FI;

STACK_RETURN_FROM_V86:
    IF IOPL=3 (* Virtual mode: PE=1, VM=1, IOPL=3 *)
    THEN
        IF OperandSize = 16
        IP ← Pop(); (* 16 bit pops *)
        CS ← Pop();
        FLAGS ← Pop();
        ELSE (* OperandSize = 32 *)
        EIP ← Pop(); (* 32-bit pops *)
        CS ← Pop();
        EFLAGS ← Pop(); (*VM,IOPL,VIP,and VIF EFLAG bits are not modified by IRETD*)
    FI;
    ELSE #GP(0); (* trap to virtual-8086 monitor: PE=1, VM=1, IOPL<3 *)
    FI;
END;

STACK_RETURN_TO_V86: (* Interrupted procedure was in V86 mode: PE=1, VM=1 in flags
image *)
    IF top 36 bytes of stack not within limits
    THEN #SS(0);
    FI;
    IF instruction pointer not within code segment limit THEN #GP(0);
    FI;
    EFLAGS ← SS:[ESP + 8]; (* Sets VM in interrupted routine *)
    EIP ← Pop( );
    CS ← Pop( ); (* CS behaves as in 8086, due to VM = 1 *)
    throwaway ← Pop( ); (* pop away EFLAGS already read *)
    TempESP ← Pop( );
    TempSS ← Pop( );
    ES ← Pop( ); (* pop 2 words; throw away high-order word *)
    DS ← Pop( ); (* pop 2 words; throw away high-order word *)
    FS ← Pop( ); (* pop 2 words; throw away high-order word *)
    GS ← Pop( ); (* pop 2 words; throw away high-order word *)
    SS:ESP ← TempSS:TempESP;
    (* Resume execution in Virtual 8086 mode *)
    END;

TASK-RETURN: (* PE=1, VM=1, NT=1 *)
    Examine Back Link Selector in TSS addressed by the current task
    register:
    Must specify global in the local/global bit, else #TS(new TSS selector);
    Index must be within GDT limits, else #TS(new TSS selector);

```

```

    AR byte must specify TSS, else #TS(new TSS selector);
    New TSS must be busy, else #TS(new TSS selector);
    TSS must be present, else #NP(new TSS selector);
    SWITCH-TASKS without nesting to TSS specified by back link selector;
    Mark the task just abandoned as NOT BUSY;
    Instruction pointer must be within code segment limit ELSE #GP(0);
    END;

```

STACK-RETURN: (\* PE=1, VM=0 in flags image \*)

```

    IF OperandSize=32
    THEN Third word on stack must be within stack limits, else #SS(0);
    ELSE Second word on stack must be within stack limits, else #SS(0);
    FI;
    Return CS selector RPL must be ≥ CPL, else #GP(Return selector);
    IF return selector RPL = CPL
    THEN GOTO RETURN-SAME-LEVEL;
    ELSE GOTO RETURN-OUTER-LEVEL;
    FI;

```

RETURN-SAME-LEVEL: (\* PE=1, VM=0 in flags image, RPL=CPL \*)

```

    IF OperandSize=32
    THEN
        Top 12 bytes on stack must be within limits, else #SS(0);
        Return CS selector (at eSP+4) must be non-null, else #GP(0);
    ELSE
        Top 6 bytes on stack must be within limits, else #SS(0);
        Return CS selector (at eSP+2) must be non-null, else #GP(0);
    FI;
    Selector index must be within its descriptor table limits, else #GP
    (Return selector);
    AR byte must indicate code segment, else #GP(Return selector);
    IF non-conforming
    THEN code segment DPL must = CPL;
    ELSE #GP(Return selector); (* PE=1,VM=0 in flags image,RPL=CPL,non-conforming,DPL
    ≠CPL *)
    FI;
    IF conforming
    THEN IF DPL>CPL
        #GP(Return selector); (* PE=1,VM=0 in flags image,RPL=CPL,conforming,DPL>CPL *)
    Segment must be present, else #NP(Return selector);
    Instruction pointer must be within code segment boundaries, else #GP(0);
    FI;
    IF OperandSize=32
    THEN
        Load CS:EIP from stack;
        Load CS-register with new code segment descriptor;
        Load EFLAGS with third doubleword from stack;

```

```
    Increment eSP by 12;
ELSE
    Load CS-register with new code segment descriptor;
    Load FLAGS with third word on stack;
    Increment eSP by 6;
FI;
END;
```

**RETURN-OUTER-LEVEL:**

```
IF OperandSize=32
THEN Top 20 bytes on stack must be within limits, else #SS(0);
ELSE Top 10 bytes on stack must be within limits, else #SS(0);
FI;
Examine return CS selector and associated descriptor:
    Selector must be non-null, ELSE #GP(0);
    Selector index must be within its descriptor table limits;
        ELSE #GP(Return selector);
    AR byte must indicate code segment, else #GP(Return selector);
    IF non-conforming
    THEN code segment DPL must = CS selector RPL;
    ELSE #GP(Return selector);
    FI;
    IF conforming
    THEN code segment DPL must be > CPL;
    ELSE #GP(Return selector);
    FI;
    Segment must be present, else #NP(Return selector);
Examine return SS selector and associated descriptor:
    Selector must be non-null, else #GP(0);
    Selector index must be within its descriptor table limits
        ELSE #GP(SS selector);
    Selector RPL must equal the RPL of the return CS selector
        ELSE #GP(SS selector);
    AR byte must indicate a writable data segment, else #GP(SS selector);
    Stack segment DPL must equal the RPL of the return CS selector
        ELSE #GP(SS selector);
    SS must be present, else #NP(SS selector);
Instruction pointer must be within code segment limit ELSE #GP(0);
IF OperandSize=32
THEN
    Load CS:EIP from stack;
    Load EFLAGS with values at (eSP+8);
ELSE
    Load CS:IP from stack;
    Load FLAGS with values at (eSP+4);
FI;
Load SS:eSP from stack;
```

```

Set CPL to the RPL of the return CS selector;
Load the CS register with the CS descriptor;
Load the SS register with the SS descriptor;
FOR each of ES, FS, GS, and DS
DO;
  IF the current value of the register is not valid for the outer level;
  THEN zero the register and clear the valid flag;
  FI;
  To be valid, the register setting must satisfy the following properties:
    Selector index must be within descriptor table limits;
    AR byte must indicate data or readable code segment;
    IF segment is data or non-conforming code,
    THEN DPL must be > CPL, or DPL must be < RPL;
OD;
END:

```

## Description

In Real Address Mode, the IRET instruction pops the instruction pointer, the CS register, and the flags register from the stack and resumes the interrupted routine.

In Protected Mode, the action of the IRET instruction depends on the setting of the nested task flag (NT) bit in the flag register. When the new flag image is popped from the stack, the IOPL bits in the flag register are changed only when CPL equals 0.

If the NT flag is cleared, the IRET instruction returns from an interrupt procedure without a task switch. The code returned to must be equally or less privileged than the interrupt routine (as indicated by the RPL bits of the CS selector popped from the stack). If the destination code is less privileged, the IRET instruction also pops the stack pointer and SS from the stack.

If the NT flag is set, the IRET instruction reverses the operation of a CALL or INT that caused a task switch. The updated state of the task executing the IRET instruction is saved in its task state segment. If the task is reentered later, the code that follows the IRET instruction is executed.

## Flags Affected

All flags are affected; the flags register is popped from stack.

## Protected Mode Exceptions

#GP, #NP, or #SS, as indicated under "Operation" above; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Real Address Mode Exceptions

Interrupt 13 if any part of the operand being popped lies beyond address 0FFFFH.



**Virtual 8086 Mode Exceptions**

#GP(0) fault occurs if the I/O privilege level is less than 3, to permit emulation; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

For obtaining information on this instruction using virtual mode extensions, see Appendix H.

## Jcc—Jump if Condition is Met

Opcode	Instruction	Clocks	Description
77 <i>cb</i>	JA <i>rel8</i>	1	Jump short if above (CF=0 and ZF=0)
73 <i>cb</i>	JAE <i>rel8</i>	1	Jump short if above or equal (CF=0)
72 <i>cb</i>	JB <i>rel8</i>	1	Jump short if below (CF=1)
76 <i>cb</i>	JBE <i>rel8</i>	1	Jump short if below or equal (CF=1 or ZF=1)
72 <i>cb</i>	JC <i>rel8</i>	1	Jump short if carry (CF=1)
E3 <i>cb</i>	JCXZ <i>rel8</i>	6,5	Jump short if CX register is 0
E3 <i>cb</i>	JECXZ <i>rel8</i>	6,5	Jump short if ECX register is 0
74 <i>cb</i>	JE <i>rel8</i>	1	Jump short if equal (ZF=1)
7F <i>cb</i>	JG <i>rel8</i>	1	Jump short if greater (ZF=0 and SF=OF)
7D <i>cb</i>	JGE <i>rel8</i>	1	Jump short if greater or equal (SF=OF)
7C <i>cb</i>	JL <i>rel8</i>	1	Jump short if less (SF<>OF)
7E <i>cb</i>	JLE <i>rel8</i>	1	Jump short if less or equal (ZF=1 or SF<>OF)
76 <i>cb</i>	JNA <i>rel8</i>	1	Jump short if not above (CF=1 or ZF=1)
72 <i>cb</i>	JNAE <i>rel8</i>	1	Jump short if not above or equal (CF=1)
73 <i>cb</i>	JNB <i>rel8</i>	1	Jump short if not below (CF=0)
77 <i>cb</i>	JNBE <i>rel8</i>	1	Jump short if not below or equal (CF=0 and ZF=0)
73 <i>cb</i>	JNC <i>rel8</i>	1	Jump short if not carry (CF=0)
75 <i>cb</i>	JNE <i>rel8</i>	1	Jump short if not equal (ZF=0)
7E <i>cb</i>	JNG <i>rel8</i>	1	Jump short if not greater (ZF=1 or SF<>OF)
7C <i>cb</i>	JNGE <i>rel8</i>	1	Jump short if not greater or equal (SF<>OF)
7D <i>cb</i>	JNL <i>rel8</i>	1	Jump short if not less (SF=OF)
7F <i>cb</i>	JNLE <i>rel8</i>	1	Jump short if not less or equal (ZF=0 and SF=OF)
71 <i>cb</i>	JNO <i>rel8</i>	1	Jump short if not overflow (OF=0)
7B <i>cb</i>	JNP <i>rel8</i>	1	Jump short if not parity (PF=0)
79 <i>cb</i>	JNS <i>rel8</i>	1	Jump short if not sign (SF=0)
75 <i>cb</i>	JNZ <i>rel8</i>	1	Jump short if not zero (ZF=0)
70 <i>cb</i>	JO <i>rel8</i>	1	Jump short if overflow (OF=1)
7A <i>cb</i>	JP <i>rel8</i>	1	Jump short if parity (PF=1)
7A <i>cb</i>	JPE <i>rel8</i>	1	Jump short if parity even (PF=1)
7B <i>cb</i>	JPO <i>rel8</i>	1	Jump short if parity odd (PF=0)
78 <i>cb</i>	JS <i>rel8</i>	1	Jump short if sign (SF=1)
74 <i>cb</i>	JZ <i>rel8</i>	1	Jump short if zero (ZF=1)
0F 87 <i>cw/cd</i>	JA <i>rel16/32</i>	1	Jump near if above (CF=0 and ZF=0)
0F 83 <i>cw/cd</i>	JAE <i>rel16/32</i>	1	Jump near if above or equal (CF=0)
0F 82 <i>cw/cd</i>	JB <i>rel16/32</i>	1	Jump near if below (CF=1)
0F 86 <i>cw/cd</i>	JBE <i>rel16/32</i>	1	Jump near if below or equal (CF=1 or ZF=1)
0F 82 <i>cw/cd</i>	JC <i>rel16/32</i>	1	Jump near if carry (CF=1)
0F 84 <i>cw/cd</i>	JE <i>rel16/32</i>	1	Jump near if equal (ZF=1)
0F 84 <i>cw/cd</i>	JZ <i>rel16/32</i>	1	Jump near if zero (ZF=1)
0F 8F <i>cw/cd</i>	JG <i>rel16/32</i>	1	Jump near if greater (ZF=0 and SF=OF)
0F 8D <i>cw/cd</i>	JGE <i>rel16/32</i>	1	Jump near if greater or equal (SF=OF)
0F 8C <i>cw/cd</i>	JL <i>rel16/32</i>	1	Jump near if less (SF<>OF)
0F 8E <i>cw/cd</i>	JLE <i>rel16/32</i>	1	Jump near if less or equal (ZF=1 or SF<>OF)
0F 86 <i>cw/cd</i>	JNA <i>rel16/32</i>	1	Jump near if not above (CF=1 or ZF=1)
0F 82 <i>cw/cd</i>	JNAE <i>rel16/32</i>	1	Jump near if not above or equal (CF=1)
0F 83 <i>cw/cd</i>	JNB <i>rel16/32</i>	1	Jump near if not below (CF=0)
0F 87 <i>cw/cd</i>	JNBE <i>rel16/32</i>	1	Jump near if not below or equal (CF=0 and ZF=0)
0F 83 <i>cw/cd</i>	JNC <i>rel16/32</i>	1	Jump near if not carry (CF=0)
0F 85 <i>cw/cd</i>	JNE <i>rel16/32</i>	1	Jump near if not equal (ZF=0)
0F 8E <i>cw/cd</i>	JNG <i>rel16/32</i>	1	Jump near if not greater (ZF=1 or SF<>OF)
0F 8C <i>cw/cd</i>	JNGE <i>rel16/32</i>	1	Jump near if not greater or equal (SF<>OF)
0F 8D <i>cw/cd</i>	JNL <i>rel16/32</i>	1	Jump near if not less (SF=OF)
0F 8F <i>cw/cd</i>	JNLE <i>rel16/32</i>	1	Jump near if not less or equal (ZF=0 and SF=OF)
0F 81 <i>cw/cd</i>	JNO <i>rel16/32</i>	1	Jump near if not overflow (OF=0)
0F 8B <i>cw/cd</i>	JNP <i>rel16/32</i>	1	Jump near if not parity (PF=0)
0F 89 <i>cw/cd</i>	JNS <i>rel16/32</i>	1	Jump near if not sign (SF=0)
0F 85 <i>cw/cd</i>	JNZ <i>rel16/32</i>	1	Jump near if not zero (ZF=0)
0F 80 <i>cw/cd</i>	JO <i>rel16/32</i>	1	Jump near if overflow (OF=1)
0F 8A <i>cw/cd</i>	JP <i>rel16/32</i>	1	Jump near if parity (PF=1)
0F 8A <i>cw/cd</i>	JPE <i>rel16/32</i>	1	Jump near if parity even (PF=1)
0F 8B <i>cw/cd</i>	JPO <i>rel16/32</i>	1	Jump near if parity odd (PF=0)
0F 88 <i>cw/cd</i>	JS <i>rel16/32</i>	1	Jump near if sign (SF=1)
0F 84 <i>cw/cd</i>	JZ <i>rel16/32</i>	1	Jump near if 0 (ZF=1)

**NOTES:**

Where two clock counts appear, the first clock count is for the true condition (branch taken); the second clock count is for the false condition (branch not taken). *rel16/32* indicates that these instructions map to two; one with a 16-bit relative displacement, the other with a 32-bit relative displacement, depending on the operand-size attribute of the instruction.

**Operation**

IF condition

THEN

EIP  $\leftarrow$  EIP + SignExtend(*rel8/16/32*);

IF OperandSize = 16

THEN EIP  $\leftarrow$  EIP AND 0000FFFFH;

FI;

FI;

**Description**

Conditional jumps (except the JCXZ instruction) test the flags which have been set by a previous instruction. The conditions for each mnemonic are given in parentheses after each description above. The terms "less" and "greater" are used for comparisons of signed integers; "above" and "below" are used for unsigned integers.

If the given condition is true, a jump is made to the location provided as the operand. Instruction coding is most efficient when the target for the conditional jump is in the current code segment and within  $-128$  to  $+127$  bytes of the next instruction's first byte. The jump can also target  $-32768$  thru  $+32767$  (segment size attribute 16) or  $-2^{31}$  thru  $+2^{31}-1$  (segment size attribute 32) relative to the next instruction's first byte. When the target for the conditional jump is in a different segment, use the opposite case of the jump instruction (i.e., the JE and JNE instructions), and then access the target with an unconditional far jump to the other segment. For example, you cannot code—

```
JZ FARLABEL;
```

You must instead code—

```
JNZ BEYOND;
```

```
JMP FARLABEL;
```

```
BEYOND:
```

Because there can be several ways to interpret a particular state of the flags, ASM386 provides more than one mnemonic for most of the conditional jump opcodes. For example, if you compared two characters in AX and want to jump if they are equal, use the JE instruction; or, if you ANDed the AX register with a bit field mask and only want to jump if the result is 0, use the JZ instruction, a synonym for the JE instruction.

The JCXZ instruction differs from other conditional jumps because it tests the contents of the CX or ECX register for 0, not the flags. The JCXZ instruction is useful at the beginning of a conditional loop that terminates with a conditional loop instruction (such as LOOPNE TARGET LABEL). The JCXZ instruction prevents entering the loop with the CX or ECX

register equal to zero, which would cause the loop to execute 64K or  $2^{32}$  times instead of zero times.

**Flags Affected**

None.

**Protected Mode Exceptions**

#GP(0) if the offset jumped to is beyond the limits of the code segment.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

None.

**Notes**

The JCXZ instruction takes longer to execute than a two-instruction sequence which compares the count register to zero and jumps if the count is zero.

All branches are converted into 16-byte code fetches regardless of jump address or cacheability.



## JMP—Jump

Opcode	Instruction	Clocks	Description
EB <i>cb</i>	JMP <i>rel8</i>	1	Jump short
E9 <i>cw</i>	JMP <i>rel16</i>	1	Jump near, displacement relative to next instruction
FF /4	JMP <i>r/m16</i>	2	Jump near indirect
EA <i>cd</i>	JMP <i>ptr16:16</i>	3	Jump intersegment, 4-byte immediate address
EA <i>cd</i>	JMP <i>ptr16:16</i>	18	Jump to call gate, same privilege
EA <i>cd</i>	JMP <i>ptr16:16</i>	19+TS	Jump via task state segment
EA <i>cd</i>	JMP <i>ptr16:16</i>	20+TS	Jump via task gate
FF /5	JMP <i>m16:16</i>	4	Jump <i>r/m16:16</i> indirect and intersegment
FF /5	JMP <i>m16:16</i>	18	Jump to call gate, same privilege
FF /5	JMP <i>m16:16</i>	19+TS	Jump via task state segment
FF /5	JMP <i>m16:16</i>	20+TS	Jump via task gate
E9 <i>cd</i>	JMP <i>rel32</i>	1	Jump near, displacement relative to next instruction
FF /4	JMP <i>r/m32</i>	2	Jump near, indirect
EA <i>cp</i>	JMP <i>ptr16:32</i>	3	Jump intersegment, 6-byte immediate address
EA <i>cp</i>	JMP <i>ptr16:32</i>	18	Jump to call gate, same privilege
EA <i>cp</i>	JMP <i>ptr16:32</i>	19+TS	Jump via task state segment
EA <i>cp</i>	JMP <i>ptr16:32</i>	20+TS	Jump via task gate
FF /5	JMP <i>m16:32</i>	4	Jump intersegment, address at <i>r/m</i> dword
FF /5	JMP <i>m16:32</i>	18	Jump to call gate, same privilege
FF /5	JMP <i>m16:32</i>	19+TS	Jump via task state segment
FF /5	JMP <i>m16:32</i>	20+TS	Jump via task gate

**NOTE:** Values of *ts* are given by the following table:

Old Task	New Task		
	To 32-Bit TSS	To 16-Bit TSS	To VM TSS
VM/32-bit/16-bit TSS	85	87	71

### Operation

IF instruction = relative JMP (\* i.e. operand is *rel8*, *rel16*, or *rel32* \*)

THEN

EIP ← EIP + *rel8/16/32*;

IF OperandSize = 16

THEN EIP ← EIP AND 0000FFFFH;

FI;

FI;

IF instruction = near indirect JMP

(\* i.e. operand is *r/m16* or *r/m32* \*)

THEN

IF OperandSize = 16

THEN

EIP ← [*r/m16*] AND 0000FFFFH;

ELSE (\* OperandSize = 32 \*)

EIP ← [*r/m32*];

FI;

FI;

```

IF (PE = 0 OR (PE = 1 AND VM = 1)) (* real mode or V86 mode *)
  AND instruction = far JMP
  (* i.e., operand type is m16:16, m16:32, ptr16:16, ptr16:32 *)
THEN GOTO REAL-OR-V86-MODE;
  IF operand type = m16:16 or m16:32
  THEN (* indirect *)
    IF OperandSize = 16
    THEN
      CS:IP ← [m16:16];
      EIP ← EIP AND 0000FFFFH; (* clear upper 16 bits *)
    ELSE (* OperandSize = 32 *)
      CS:EIP ← [m16:32];
    FI;
  FI;
  IF operand type = ptr16:16 or ptr16:32
  THEN
    IF OperandSize = 16
    THEN
      CS:IP ← ptr16:16;
      EIP ← EIP AND 0000FFFFH; (* clear upper 16 bits *)
    ELSE (* OperandSize = 32 *)
      CS:EIP ← ptr16:32;
    FI;
  FI;
FI;

IF (PE = 1 AND VM = 0) (* Protected mode, not V86 mode *)
  AND instruction = far JMP
THEN
  IF operand type = m16:16 or m16:32
  THEN (* indirect *)
    check access of EA dword;
    #GP(0) or #SS(0) IF limit violation;
  FI;
  Destination selector is not null ELSE #GP(0)
  Destination selector index is within its descriptor table limits ELSE #GP(selector)
  Depending on AR byte of destination descriptor:
    GOTO CONFORMING-CODE-SEGMENT;
    GOTO NONCONFORMING-CODE-SEGMENT;
    GOTO CALL-GATE;
    GOTO TASK-GATE;
    GOTO TASK-STATE-SEGMENT;
  ELSE #GP(selector); (* illegal AR byte in descriptor *)
FI;

CONFORMING-CODE-SEGMENT:
  Descriptor DPL must be ≤ CPL ELSE #GP(selector);

```

Segment must be present ELSE #NP(selector);  
Instruction pointer must be within code-segment limit ELSE #GP(0);  
IF OperandSize = 32  
THEN Load CS:EIP from destination pointer;  
ELSE Load CS:IP from destination pointer;  
FI;  
Load CS register with new segment descriptor;

**NONCONFORMING-CODE-SEGMENT:**

RPL of destination selector must be  $\leq$  CPL ELSE #GP(selector);  
Descriptor DPL must be = CPL ELSE #GP(selector);  
Segment must be present ELSE # NP(selector);  
Instruction pointer must be within code-segment limit ELSE #GP(0);  
IF OperandSize = 32  
THEN Load CS:EIP from destination pointer;  
ELSE Load CS:IP from destination pointer;  
FI;  
Load CS register with new segment descriptor;  
Set RPL field of CS register to CPL;

**CALL-GATE:**

Descriptor DPL must be  $\geq$  CPL ELSE #GP(gate selector);  
Descriptor DPL must be  $\geq$  gate selector RPL ELSE #GP(gate selector);  
Gate must be present ELSE #NP(gate selector);  
Examine selector to code segment given in call gate descriptor:  
  Selector must not be null ELSE #GP(0);  
  Selector must be within its descriptor table limits ELSE  
    #GP(CS selector);  
  Descriptor AR byte must indicate code segment  
    ELSE #GP(CS selector);  
  IF non-conforming  
    THEN code-segment descriptor DPL must = CPL  
    ELSE #GP(CS selector);  
  FI;  
  IF conforming  
    THEN code-segment descriptor DPL must be  $\leq$  CPL;  
    ELSE #GP(CS selector);  
  FI;  
  Code segment must be present ELSE #NP(CS selector);  
  Instruction pointer must be within code-segment limit ELSE #GP(0);  
  IF OperandSize = 32  
    THEN Load CS:EIP from call gate;  
    ELSE Load CS:IP from call gate;  
  FI;  
Load CS register with new code-segment descriptor;  
Set RPL of CS to CPL

**TASK-GATE:**

Gate descriptor DPL must be  $\geq$  CPL ELSE #GP(gate selector);  
 Gate descriptor DPL must be  $\geq$  gate selector RPL ELSE #GP(gate selector);  
 Task Gate must be present ELSE #NP(gate selector);  
 Examine selector to TSS, given in Task Gate descriptor:  
   Must specify global in the local/global bit ELSE #GP(TSS selector);  
   Index must be within GDT limits ELSE #GP(TSS selector);  
   Descriptor AR byte must specify available TSS (bottom bits 00001);  
     ELSE #GP(TSS selector);  
   Task State Segment must be present ELSE #NP(TSS selector);  
 SWITCH-TASKS (without nesting) to TSS;  
 Instruction pointer must be within code-segment limit ELSE #GP(0);

**TASK-STATE-SEGMENT:**

TSS DPL must be  $\geq$  CPL ELSE #GP(TSS selector);  
 TSS DPL must be  $\geq$  TSS selector RPL ELSE #GP(TSS selector);  
 Descriptor AR byte must specify available TSS (bottom bits 00001)  
   ELSE #GP(TSS selector);  
 Task State Segment must be present ELSE #NP(TSS selector);  
 SWITCH-TASKS (without nesting) to TSS;  
 Instruction pointer must be within code-segment limit ELSE #GP(0);

**Description**

The **JMP** instruction transfers control to a different point in the instruction stream without recording return information.

The action of the various forms of the instruction are shown below.

Jumps with destinations of type *r/m16*, *r/m32*, *rel16*, and *rel32* are near jumps and do not involve changing the segment register value.

The **JMP *rel16*** and **JMP *rel32*** forms of the instruction add an offset to the address of the instruction following the **JMP** to determine the destination. The *rel16* form is used when the instruction's operand-size attribute is 16 bits (segment size attribute 16 only); *rel32* is used when the operand-size attribute is 32 bits (segment size attribute 32 only). The result is stored in the 32-bit EIP register. With *rel16*, the upper 16 bits of the EIP register are cleared, which results in an offset whose value does not exceed 16 bits.

The **JMP *r/m16*** and **JMP *r/m32*** forms specify a register or memory location from which the absolute offset from the procedure is fetched. The offset fetched from *r/m* is 32 bits for an operand-size attribute of 32 bits (*r/m32*), or 16 bits for an operand-size attribute of 16 bits (*r/m16*).

The **JMP *ptr16:16*** and ***ptr16:32*** forms of the instruction use a four-byte or six-byte operand as a long pointer to the destination. The **JMP *m16:16*** and ***m16:32*** forms fetch the long pointer from the memory location specified (indirection). In Real Address Mode or Virtual 8086 Mode, the long pointer provides 16 bits for the CS register and 16 or 32 bits for the EIP register (depending on the operand-size attribute). In Protected Mode, both long pointer

forms consult the Access Rights (AR) byte in the descriptor indexed by the selector part of the long pointer. Depending on the value of the AR byte, the jump will perform one of the following types of control transfers:

- A jump to a code segment at the same privilege level
- A task switch

For more information on protected mode control transfers, refer to Chapter 12 and Chapter 13.

### Flags Affected

All if a task switch takes place; none if no task switch occurs.

### Protected Mode Exceptions

Far jumps: #GP, #NP, #SS, and #TS, as indicated in the list above.

Near direct jumps: #GP(0) if procedure location is beyond the code segment limits; #AC for unaligned memory reference if the current privilege level is 3.

Near indirect jumps: #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #GP if the indirect offset obtained is beyond the code segment limits; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would be outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as under Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

All branches are converted into 16-byte code fetches regardless of jump address or cacheability.

## LAHF—Load Flags into AH Register

Opcode	Instruction	Clocks	Description
9F	LAHF	2	Load: AH = flags SF ZF xx AF xx PF xx CF

### Operation

AH ← SF:ZF:xx:AF:xx:PF:xx:CF;

### Description

The LAHF instruction transfers the low byte of the flags word to the AH register. The bits, from MSB to LSB, are sign, zero, indeterminate, auxiliary, carry, indeterminate, parity, indeterminate, and carry.

### Flags Affected

None.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

## LAR—Load Access Rights Byte

Opcode	Instruction	Clocks	Description
0F 02 /r	LAR r16,r/m16	8	r16 ← r/m16 masked by FF00
0F 02 /r	LAR r32,r/m32	8	r32 ← /m32 masked by 00FxFF00

### Description

The LAR instruction stores a marked form of the second doubleword of the descriptor for the source selector if the selector is visible at the current privilege level (modified by the selector's RPL) and is a valid descriptor type within the descriptor limits. The destination register is loaded with the high-order doubleword of the descriptor masked by 00FxFF00, and the ZF flag is set. The x indicates that the four bits corresponding to the upper four bits of the limit are undefined in the value loaded by the LAR instruction. If the selector is invisible or of the wrong type, the ZF flag is cleared.

If the 32-bit operand size is specified, the entire 32-bit value is loaded into the 32-bit destination register. If the 16-bit operand size is specified, the lower 16-bits of this value are stored in the 16-bit destination register.

All code and data segment descriptors are valid for the LAR instruction.

The valid special segment and gate descriptor types for the LAR instruction are given in the following table:

Type	Name	Valid/Invalid
0	Invalid	Invalid
1	Available 16-bit TSS	Valid
2	LDT	Valid
3	Busy 16-bit TSS	Valid
4	16-bit call gate	Valid
5	16-bit/32-bit task gate	Valid
6	16-bit trap gate	Invalid
7	16-bit interrupt gate	Invalid
8	Invalid	Invalid
9	Available 32-bit TSS	Valid
A	Invalid	Invalid
B	Busy 32-bit TSS	Valid
C	32-bit call gate	Valid
D	Invalid	Invalid
E	32-bit trap gate	Invalid
F	32-bit interrupt gate	Invalid

**Flags Affected**

The ZF flag is set unless the selector is invisible or of the wrong type, in which case the ZF flag is cleared.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 6; the LAR instruction is unrecognized in Real Address Mode.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode.

## LDS/LES/LFS/LGS/LSS—Load Full Pointer

Opcode	Instruction	Clocks	Description
C5 /r	LDS <i>r16,m16:16</i>	4	Load DS: <i>r16</i> with pointer from memory
C5 /r	LDS <i>r32,m16:32</i>	4	Load DS: <i>r32</i> with pointer from memory
0F B2 /r	LSS <i>r16,m16:16</i>	4/ <i>pm=8</i>	Load SS: <i>r16</i> with pointer from memory
0F B2 /r	LSS <i>r32,m16:32</i>	4/ <i>pm=8</i>	Load SS: <i>r32</i> with pointer from memory
C4 /r	LES <i>r16,m16:16</i>	4	Load ES: <i>r16</i> with pointer from memory
C4 /r	LES <i>r32,m16:32</i>	4	Load ES: <i>r32</i> with pointer from memory
0F B4 /r	LFS <i>r16,m16:16</i>	4	Load FS: <i>r16</i> with pointer from memory
0F B4 /r	LFS <i>r32,m16:32</i>	4	Load FS: <i>r32</i> with pointer from memory
0F B5 /r	LGS <i>r16,m16:16</i>	4	Load GS: <i>r16</i> with pointer from memory
0F B5 /r	LGS <i>r32,m16:32</i>	4	Load GS: <i>r32</i> with pointer from memory

### Operation

CASE instruction OF

LSS: *Sreg* is SS; (\* Load SS register \*)

LDS: *Sreg* is DS; (\* Load DS register \*)

LES: *Sreg* is ES; (\* Load ES register \*)

LFS: *Sreg* is FS; (\* Load FS register \*)

LGS: *Sreg* is GS; (\* Load GS register \*)

ESAC;

IF (OperandSize = 16)

THEN

*r16* ← [Effective Address]; (\* 16-bit transfer \*)

*Sreg* ← [Effective Address + 2]; (\* 16-bit transfer \*)

(\* In Protected Mode, load the descriptor into the segment register \*)

ELSE (\* OperandSize = 32 \*)

*r32* ← [Effective Address]; (\* 32-bit transfer \*)

*Sreg* ← [Effective Address + 4]; (\* 16-bit transfer \*)

(\* In Protected Mode, load the descriptor into the segment register \*)

FI;

### Description

The LGS, LSS, LDS, LES, and LFS instructions read a full pointer from memory and store it in the selected segment register:register pair. The full pointer loads 16 bits into the segment register SS, DS, ES, FS, or GS. The other register loads 32 bits if the operand-size attribute is 32 bits, or loads 16 bits if the operand-size attribute is 16 bits. The other 16- or 32-bit register to be loaded is determined by the **r16** or **r32** register operand specified.

When an assignment is made to one of the segment registers, the descriptor is also loaded into the segment register. The data for the register is obtained from the descriptor table entry for the selector given.

A null selector (values 0000-0003) can be loaded into DS, ES, FS, or GS registers without causing a protection exception. (Any subsequent reference to a segment whose corresponding segment register is loaded with a null selector to address memory causes a #GP(0) exception. No memory reference to the segment occurs.)

The following is a listing of the Protected Mode checks and actions taken in the loading of a segment register:

IF SS is loaded:

- IF selector is null THEN #GP(0); FI;
- Selector index must be within its descriptor table limits ELSE #GP(selector);
- Selector's RPL must equal CPL ELSE #GP(selector);
- AR byte must indicate a writable data segment ELSE #GP(selector);
- DPL in the AR byte must equal CPL ELSE #GP(selector);
- Segment must be marked present ELSE #SS(selector);
- Load SS with selector;
- Load SS with descriptor;

IF DS, ES, FS, or GS is loaded with non-null selector:

- Selector index must be within its descriptor table limits ELSE #GP(selector);
- AR byte must indicate data or readable code segment ELSE #GP(selector);
- IF data or nonconforming code THEN both the RPL and the CPL must be less than or equal to DPL in AR byte;
- ELSE #GP(selector);
- Segment must be marked present ELSE #NP(selector);
- Load segment register with selector and RPL bits;
- Load segment register with descriptor;

IF DS, ES, FS or GS is loaded with a null selector:

- Load segment register with selector;
- Clear descriptor valid bit;

## Flags Affected

None.

## Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; the second operand must be a memory operand, not a register—if a register then #UD Fault; #GP(0) if a null selector is loaded into SS; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Real Address Mode Exceptions

The second operand must be a memory operand, not a register; Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.



**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## LEA—Load Effective Address

Opcode	Instruction	Clocks	Description
8D /r	LEA <i>r16,m</i>	1	Store effective address for <i>m</i> in register <i>r16</i>
8D /r	LEA <i>r32,m</i>	1	Store effective address for <i>m</i> in register <i>r32</i>
8D /r	LEA <i>r16,m</i>	1	Store effective address for <i>m</i> in register <i>r16</i>
8D /r	LEA <i>r32,m</i>	1	Store effective address for <i>m</i> in register <i>r32</i>

### Operation

```

IF OperandSize = 16 AND AddressSize = 16
THEN r16 ← Addr(m);
ELSE
  IF OperandSize = 16 AND AddressSize = 32
  THEN
    r16 ← Truncate_to_16bits(Addr(m));    (* 32-bit address *)
  ELSE
    IF OperandSize = 32 AND AddressSize = 16
    THEN
      r32 ← Truncate_to_16bits(Addr(m)) and zero extend;
    ELSE
      IF OperandSize = 32 AND AddressSize = 32
      THEN r32 ← Addr(m);
      FI;
    FI;
  FI;
FI;

```

### Description

The LEA instruction calculates the effective address (offset part) and stores it in the specified register. The operand-size attribute of the instruction (represented by `OperandSize` in the algorithm under "Operation" above) is determined by the chosen register. The address-size attribute (represented by `AddressSize`) is determined by the attribute of the code segment. (See the "Operand-Size and Address-Size Attributes" section at the beginning of this chapter.) The address-size and operand-size attributes affect the action performed by the LEA instruction, as follows:

Operand Size	Address Size	Action Performed
16	16	16-bit effective address is calculated and stored in requested 16-bit register destination.
16	32	32-bit effective address is calculated. The lower 16 bits of the address are stored in the requested 16-bit register destination.
32	16	16-bit effective address is calculated. The 16-bit address is zero-extended and stored in the requested 32-bit register destination.
32	32	32-bit effective address is calculated and stored in the requested 32-bit register destination.

**Flags Affected**

None.

**Protected Mode Exceptions**

#UD if the second operand is a register.

**Real Address Mode Exceptions**

Interrupt 6 if the second operand is a register.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode.

**Notes**

Different assemblers may use different algorithms based on the size attribute and symbolic reference of the second operand.

## LEAVE—High Level Procedure Exit

Opcode	Instruction	Clocks	Description
C9	LEAVE	3	Set SP to BP, then pop BP
C9	LEAVE	3	Set ESP to EBP, then pop EBP

### Operation

```

IF StackAddrSize = 16
THEN
    SP ← BP;
ELSE (* StackAddrSize = 32 *)
    ESP ← EBP;
FI;
IF OperandSize = 16
THEN
    BP ← Pop();
ELSE (* OperandSize = 32 *)
    EBP ← Pop();
FI;

```

### Description

The LEAVE instruction reverses the actions of the ENTER instruction. By copying the frame pointer to the stack pointer, the LEAVE instruction releases the stack space used by a procedure for its local variables. The old frame pointer is popped into the BP or EBP register, restoring the caller's frame. A subsequent RET **nn** instruction removes any arguments pushed onto the stack of the exiting procedure.

### Flags Affected

None.

### Protected Mode Exceptions

#SS(0) if the BP register does not point to a location within the limits of the current stack segment.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode.



## **LES—Load Full Pointer**

See entry for LDS/LES/LFS/LGS/LSS.

## **LFS—Load Full Pointer**

See entry for LDS/LES/LFS/LGS/LSS.



## LGDT/LIDT—Load Global/Interrupt Descriptor Table Register

Opcode	Instruction	Clocks	Description
0F 01 /2	LGDT <i>m16&amp;32</i>	6	Load <i>m</i> into GDTR
0F 01 /3	LIDT <i>m16&amp;32</i>	6	Load <i>m</i> into IDTR

### Operation

IF instruction = LIDT

THEN

IF OperandSize = 16

THEN IDTR.Limit:Base  $\leftarrow m16:24$  (\* 24 bits of base loaded \*)

ELSE IDTR.Limit:Base  $\leftarrow m16:32$

FI;

ELSE (\* instruction = LGDT \*)

IF OperandSize = 16

THEN GDTR.Limit:Base  $\leftarrow m16:24$  (\* 24 bits of base loaded \*)

ELSE GDTR.Limit:Base  $\leftarrow m16:32$ ;

FI;

FI;

### Description

The LGDT and LIDT instructions load a linear base address and limit value from a six-byte data operand in memory into the GDTR or IDTR, respectively. If a 16-bit operand is used with the LGDT or LIDT instruction, the register is loaded with a 16-bit limit and a 24-bit base, and the high-order eight bits of the six-byte data operand are not used. If a 32-bit operand is used, a 16-bit limit and a 32-bit base is loaded; the high-order eight bits of the six-byte operand are used as high-order base address bits.

The SGDT and SIDT instructions always store into all 48 bits of the six-byte data operand. With the 16-bit processors, the upper eight bits are undefined after the SGDT or SIDT instruction is executed. With the 32-bit processors, the upper eight bits are written with the high-order eight address bits, for both a 16-bit operand and a 32-bit operand. If the LGDT or LIDT instruction is used with a 16-bit operand to load the register stored by the SGDT or SIDT instruction, the upper eight bits are stored as zeros.

The LGDT and LIDT instructions appear in operating system software; they are not used in application programs. They are the only instructions that directly load a linear address (i.e., not a segment relative address) in Protected Mode.

### Flags Affected

None.

### **Protected Mode Exceptions**

#GP(0) if the current privilege level is not 0; #UD if the source operand is a register; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault.

### **Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH; Interrupt 6 if the source operand is a register.

Note: These instructions are valid in Real Address Mode to allow power-up initialization for Protected Mode.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault.



## **LGS—Load Full Pointer**

See entry for LDS/LES/LFS/LGS/LSS.

## LLDT—Load Local Descriptor Table Register

Opcode	Instruction	Clocks	Description
0F 00 /2	LLDT <i>r/m16</i>	9	Load selector <i>r/m16</i> into LDTR

### Operation

LDTR ← SRC;

### Description

The LLDT instruction loads the Local Descriptor Table register (LDTR). The word operand (memory or register) to the LLDT instruction should contain a selector to the Global Descriptor Table (GDT). The GDT entry should be a Local Descriptor Table. If so, then the LDTR is loaded from the entry. The descriptor registers DS, ES, SS, FS, GS, and CS are not affected. The LDT field in the task state segment does not change.

The selector operand can be 0; if so, the LDTR is marked invalid. All descriptor references (except by the LAR, VERR, VERW or LSL instructions) cause a #GP fault.

The LLDT instruction is used in operating system software; it is not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the current privilege level is not 0; #GP(selector) if the selector operand does not point into the Global Descriptor Table, or if the entry in the GDT is not a Local Descriptor Table; #NP(selector) if the LDT descriptor is not present; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault.

### Real Address Mode Exceptions

Interrupt 6; the LLDT instruction is not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode (because the instruction is not recognized, it will not execute or perform a memory reference).

### Note

The operand-size attribute has no effect on this instruction.

## **LIDT—Load Interrupt Descriptor Table Register**

See entry for LGDT/LIDT—Load Global Descriptor Table Register/Load Interrupt Descriptor Table Register.

## LMSW—Load Machine Status Word

Opcode	Instruction	Clocks	Description
0F 01 /6	LMSW <i>r/m16</i>	8	Load <i>r/m16</i> in machine status word

### Operation

$MSW \leftarrow r/m16$ ; (\* 16 bits is stored in the machine status word \*)

### Description

The LMSW instruction loads the machine status word (part of the CR0 register) from the source operand. This instruction can be used to switch to Protected Mode; if so, it must be followed by an intrasegment jump to flush the instruction queue. The LMSW instruction will not switch back to Real Address Mode.

The LMSW instruction is used only in operating system software. It is not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the current privilege level is not 0; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Protected Mode.

### Notes

The operand-size attribute has no effect on this instruction. This instruction is provided for compatibility with the Intel286 processor; programs for the Intel386, Intel486, and Pentium processors should use the MOV CR0, ... instruction instead. The LMSW instruction does not affect the PG, ET, or NE bits, and it cannot be used to clear the PE bit.



## LOCK—Assert LOCK# Signal Prefix

Opcode	Instruction	Clocks	Description
F0	LOCK	1	Assert LOCK# signal for the next instruction

### Description

The LOCK prefix causes the LOCK# signal of the Pentium processor to be asserted during execution of the instruction that follows it. In a multiprocessor environment, this signal can be used to ensure that the Pentium processor has exclusive use of any shared memory while LOCK# is asserted. The read-modify-write sequence typically used to implement test-and-set on the Pentium processor is the BTS instruction.

The LOCK prefix functions only with the following instructions:

BTS, BTR, BTC	mem, reg/imm
XCHG	reg, mem
XCHG	mem, reg
ADD, OR, ADC, SBB, AND, SUB, XOR	mem, reg/imm
NOT, NEG, INC, DEC	mem
CMPXCHG, XADD	

An undefined opcode trap will be generated if a LOCK prefix is used with any instruction not listed above.

The XCHG instruction always asserts LOCK# regardless of the presence or absence of the LOCK prefix.

The integrity of the LOCK prefix is not affected by the alignment of the memory field. Memory locking is observed for arbitrarily misaligned fields.

### Flags Affected

None.

### Protected Mode Exceptions

#UD if the LOCK prefix is used with an instruction not listed in the "Description" section above; other exceptions can be generated by the subsequent (locked) instruction.

### Real Address Mode Exceptions

Interrupt 6 if the LOCK prefix is used with an instruction not listed in the "Description" section above; exceptions can still be generated by the subsequent (locked) instruction.

**Virtual 8086 Mode Exceptions**

#UD if the LOCK prefix is used with an instruction not listed in the "Description" section above; exceptions can still be generated by the subsequent (locked) instruction.

## LODS/LODSB/LODSW/LODSD—Load String Operand

Opcode	Instruction	Clocks	Description
AC	LODS <i>m8</i>	2	Load byte [(E)SI] into AL
AD	LODS <i>m16</i>	2	Load word [(E)SI] into AX
AD	LODS <i>m32</i>	2	Load dword [(E)SI] into EAX
AC	LODSB	2	Load byte DS:[(E)SI] into AL
AD	LODSW	2	Load word DS:[(E)SI] into AX
AD	LODSD	2	Load dword DS:[(E)SI] into EAX

### Operation

```

AddressSize = 16
THEN use SI for source-index
ELSE (* AddressSize = 32 *)
  use ESI for source-index;
FI;
IF byte type of instruction
THEN
  AL ← [source-index]; (* byte load *)
  IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;
ELSE
  IF OperandSize = 16
  THEN
    AX ← [source-index]; (* word load *)
    IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;
  ELSE (* OperandSize = 32 *)
    EAX ← [source-index]; (* dword load *)
    IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI;
  FI;
FI;
source-index ← source-index + IncDec
  
```

### Description

The LODS instruction loads the AL, AX, or EAX register with the memory byte, word, or doubleword at the location pointed to by the source-index register. After the transfer is made, the source-index register is automatically advanced. If the DF flag is 0 (the CLD instruction was executed), the source index increments; if the DF flag is 1 (the STD instruction was executed), it decrements. The increment or decrement is 1 if a byte is loaded, 2 if a word is loaded, or 4 if a doubleword is loaded.

If the address-size attribute for this instruction is 16 bits, the SI register is used for the source-index register; otherwise the address-size attribute is 32 bits, and the ESI register is used. The address of the source data is determined solely by the contents of the ESI or SI register. Load the correct index value into the SI register before executing the LODS instruction. The LODSB, LODSW, and LODSD instructions are synonyms for the byte, word, and doubleword LODS instructions.

The LODS instruction can be preceded by the REP prefix; however, the LODS instruction is used more typically within a LOOP construct, because further processing of the data moved into the EAX, AX, or AL register is usually necessary.

**Flags Affected**

None.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## LOOP/LOOPcond—Loop Control with CX Counter

Opcode	Instruction	Clocks	Description
E2 <i>cb</i>	LOOP <i>rel8</i>	5/6	DEC count; jump short if count <> 0
E1 <i>cb</i>	LOOPE <i>rel8</i>	7/8	DEC count; jump short if count <> 0 and ZF=1
E1 <i>cb</i>	LOOPZ <i>rel8</i>	7/8	DEC count; jump short if count <= 0 and ZF=1
E0 <i>cb</i>	LOOPNE <i>rel8</i>	7/8	DEC count; jump short if count <> 0 and ZF=0
E0 <i>cb</i>	LOOPNZ <i>rel8</i>	7/8	DEC count; jump short if count <= 0 and ZF=0

### Operation

IF AddressSize = 16 THEN CountReg is CX ELSE CountReg is ECX; FI;  
 CountReg ← CountReg – 1;

IF instruction <> LOOP  
 THEN

IF (instruction = LOOPE) OR (instruction = LOOPZ)  
 THEN BranchCond ← (ZF = 1) AND (CountReg <> 0);  
 FI;  
 IF (instruction = LOOPNE) OR (instruction = LOOPNZ)  
 THEN BranchCond ← (ZF = 0) AND (CountReg <> 0);  
 FI;

FI;

IF BranchCond  
 THEN

IF OperandSize = 16  
 THEN  
 IP ← IP + SignExtend(*rel8*);  
 ELSE (\* OperandSize = 32 \*)  
 EIP ← EIP + SignExtend(*rel8*);  
 FI;

FI;

### Description

The LOOP instruction decrements the count register without changing any of the flags. Conditions are then checked for the form of the LOOP instruction being used. If the conditions are met, a short jump is made to the label given by the operand to the LOOP instruction. If the address-size attribute is 16 bits, the CX register is used as the count register; otherwise the ECX register is used. The operand of the LOOP instruction must be in the range from 128 (decimal) bytes before the instruction to 127 bytes ahead of the instruction.

The LOOP instructions provide iteration control and combine loop index management with conditional branching. Use the LOOP instruction by loading an unsigned iteration count into the count register, then code the LOOP instruction at the end of a series of instructions to be iterated. The destination of the LOOP instruction is a label that points to the beginning of the iteration.

### **Flags Affected**

None.

### **Protected Mode Exceptions**

#GP(0) if the offset jumped to is beyond the limits of the current code segment.

### **Real Address Mode Exceptions**

None.

### **Virtual 8086 Mode Exceptions**

None.

### **Notes**

The unconditional LOOP instruction takes longer to execute than a two-instruction sequence which decrements the count register and jumps if the count does not equal zero.

All branches are converted into 16-byte code fetches regardless of jump address or cacheability.



## LSL—Load Segment Limit

Opcode	Instruction	Clocks	Description
0F 03 /r	LSL <i>r16,r/m16</i>	8	Load: <i>r16</i> ← segment limit, selector <i>r/m16</i> (byte granular)
0F 03 /r	LSL <i>r32,r/m32</i>	8	Load: <i>r32</i> ← segment limit, selector <i>r/m32</i> (byte granular)
0F 03 /r	LSL <i>r16,r/m16</i>	8	Load: <i>r16</i> ← segment limit, selector <i>r/m16</i> (page granular)
0F 03 /r	LSL <i>r32,r/m32</i>	8	Load: <i>r32</i> ← segment limit, selector <i>r/m32</i> (page granular)

### Description

The LSL instruction loads a register with an unscrambled segment limit, and sets the ZF flag, provided that the source selector is visible at the current privilege level and RPL, within the descriptor table, and that the descriptor is a type accepted by the LSL instruction. Otherwise, the ZF flag is cleared, and the destination register is unchanged. The segment limit is loaded as a byte granular value. If the descriptor has a page granular segment limit, the LSL instruction will translate it to a byte limit before loading it in the destination register (shift left 12 the 20-bit “raw” limit from descriptor, then OR with 00000FFFH).

The 32-bit forms of the LSL instruction store the 32-bit byte granular limit in the 32-bit destination register. For 16-bit operand sizes, the limit is computed to form a valid 32-bit limit. However, the upper 16 bits are chopped and only the low-order 16 bits are loaded into the destination operand.

Code and data segment descriptors are valid for the LSL instruction.

The valid special segment and gate descriptor types for the LSL instruction are given in the following table:

Type	Name	Valid/Invalid
0	Invalid	Invalid
1	Available 16-bit TSS	Valid
2	LDT	Valid
3	Busy 16-bit TSS	Valid
4	16-bit call gate	Invalid
5	16-bit/32-bit task gate	Invalid
6	16-bit trap gate	Invalid
7	16-bit interrupt gate	Invalid
8	Invalid	Invalid
9	Available 32-bit TSS	Valid
A	Invalid	Invalid
B	Busy 32-bit TSS	Valid
C	32-bit call gate	Invalid
D	Invalid	Invalid
E	32-bit trap gate	Invalid
F	32-bit interrupt gate	Invalid

### Flags Affected

The ZF flag is set unless the selector is invisible or of the wrong type, in which case the ZF flag is cleared.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6; the LSL instruction is not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode (because the instruction is not recognized, it will not execute or perform a memory reference).

## **LSS—Load Full Pointer**

See entry for LDS/LES/LFS/LGS/LSS.

## LTR—Load Task Register

Opcode	Instruction	Clocks	Description
0F 00 /3	LTR <i>r/m16</i>	10	Load EA word into task register

### Description

The LTR instruction loads the task register with a selector from the source register or memory location specified by the operand. The loaded TSS is marked busy. A task switch does not occur.

The LTR instruction is used only in operating system software; it is not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #GP(0) if the current privilege level is not 0; #GP(selector) if the object named by the source selector is not a TSS or is already busy; #NP(selector) if the TSS is marked "not present"; #PF(fault-code) for a page fault.

### Real Address Mode Exceptions

Interrupt 6, the LTR instruction is not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode.

### Notes

The operand-size attribute has no effect on this instruction.

## MOV—Move Data

Opcode	Instruction	Clocks	Description
88 /r	MOV r/m8,r8	1	Move byte register to r/m byte
89 /r	MOV r/m16,r16	1	Move word register to r/m word
89 /r	MOV r/m32,r32	1	Move dword register to r/m dword
8A /r	MOV r8,r/m8	1	Move r/m byte to byte register
8B /r	MOV r16,r/m16	1	Move r/m word to word register
8B /r	MOV r32,r/m32	1	Move r/m dword to dword register
8C /r	MOV r/m16,Sreg*	1	Move segment register to r/m word
8E /r	MOV Sreg,r/m16	2/3**	Move r/m word to segment register
A0	MOV AL,moffs8	1	Move byte at (seg:offset) to AL
A1	MOV AX,moffs16	1	Move word at (seg:offset) to AX
A1	MOV EAX,moffs32	1	Move dword at (seg:offset) to EAX
A2	MOV moffs8,AL	1	Move AL to (seg:offset)
A3	MOV moffs16,AX	1	Move AX to (seg:offset)
A3	MOV moffs32,EAX	1	Move EAX to (seg:offset)
B0+ rb	MOV reg8,imm8	1	Move immediate byte to register
B8+ rw	MOV reg16,imm16	1	Move immediate word to register
B8+ rd	MOV reg32,imm32	1	Move immediate dword to register
C6 /0	MOV r/m8,imm8	1	Move immediate byte to r/m byte
C7 /0	MOV r/m16,imm16	1	Move immediate word to r/m word
C7 /0	MOV r/m32,imm32	1	Move immediate dword to r/m dword

### NOTES:

**moffs8**, **moffs16**, and **moffs32** all consist of a simple offset relative to the segment base. The 8, 16, and 32 refer to the size of the data. The address-size attribute of the instruction determines the size of the offset, either 16 or 32 bits.

\*In 32-bit mode, use 16-bit operand size prefix (a byte with the value 66H preceding the instruction).

\*\*In protected mode, MOV SS, rm16/32 takes 7 clocks.

If the destination is a 32-bit register, the Pentium (510\60, 567\66) processor stores an undefined value in the upper 16 bits of the register. If the destination is a memory location, only a 16-bit value is stored.

### Operation

DEST ← SRC;

### Description

The MOV instruction copies the second operand to the first operand.

If the destination operand is a segment register (DS, ES, SS, etc.), then data from a descriptor is also loaded into the shadow portion of the register. The data for the register is obtained from the descriptor table entry for the selector given. A null selector (values 0000-0003) can be loaded into the DS, ES, FS, and GS registers without causing an exception; however, use of these registers causes a #GP(0) exception, and no memory reference occurs.

A MOV into SS instruction inhibits all interrupts until after the execution of the next instruction (which should be a MOV into ESP instruction).

Loading a segment register under Protected Mode results in special checks and actions, as described in the following listing:

IF SS is loaded;

THEN

IF selector is null THEN #GP(0);

Selector index must be within its descriptor table limits else #GP(selector);  
Selector's RPL must equal CPL else #GP(selector);  
AR byte must indicate a writable data segment else #GP(selector);  
DPL in the AR byte must equal CPL else #GP(selector);  
Segment must be marked present else #SS(selector);  
Load SS with selector;  
Load SS with descriptor.  
FI;  
IF DS, ES, FS or GS is loaded with non-null selector;  
THEN  
  Selector index must be within its descriptor table limits  
  else #GP(selector);  
  AR byte must indicate data or readable code segment else #GP(selector);  
  IF data or nonconforming code segment  
  THEN both the RPL and the CPL must be less than or equal to DPL in AR byte;  
  ELSE #GP(selector);  
  FI;  
  Segment must be marked present else #NP(selector);  
  Load segment register with selector;  
  Load segment register with descriptor;  
FI;  
IF DS, ES, FS or GS is loaded with a null selector;  
THEN  
  Load segment register with selector;  
  Clear descriptor valid bit;  
FI;

### Flags Affected

None.

### Protected Mode Exceptions

#GP, #SS, and #NP if a segment register is being loaded; otherwise, #GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## MOV—Move to/from Control Registers

Opcode	Instruction	Clocks	Description
0F 22 /r	MOV CR0, r32	22	Move (register) to (control register 0)
0F 22 /r	MOV CR2, r32	12	Move (register) to (control register 2)
0F 22 /r	MOV CR3, r32	21/46	Move (register) to (control register 3)
0F 22 /r	MOV CR4, r32	14	Move (register) to (control register 4)
0F 20 /r	MOV r32, CR0-4	4	Move (control register) to (register)

### Operation

DEST ← SRC;

### Description

The above forms of the MOV instruction store or load CR0, CR2, CR3, and CR4 to or from a general purpose register.

Thirty-two bit operands are always used with these instructions, regardless of the operand-size attribute.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are undefined.

### Protected Mode Exceptions

#GP(0) if the current privilege level is not 0. #GP(0) if an attempt is made to write a 1 to any reserved bits of CR4.

### Real Address Mode Exceptions

Interrupt 13 if an attempt is made to write a 1 to any reserved bits of CR4.

### Virtual 8086 Mode Exceptions

#GP(0) if instruction execution is attempted.

### Notes

The *reg* field within the ModR/M byte specifies which of the special registers in each category is involved. The two bits in the *mod* field are always 11. The *r/m* field specifies the general register involved.

Always set undefined or reserved bits to the value previously read.



## MOV—Move to/from Debug Registers

Opcode	Instruction	Clocks	Description
0F 21/r	MOV <i>r32</i> , DR0-DR3	11	Move (debug register) to (register)
0F 21/r	MOV <i>r32</i> , DR4-DR5	12	Move (debug register) to (register)
0F 21/r	MOV <i>r32</i> , DR6-DR7	11	Move (debug register) to (register)
0F 23 /r	MOV DR0-DR3, <i>r32</i>	11	Move (register) to (debug register)
0F 23 /r	MOV DR4-DR5, <i>r32</i>	12	Move (register) to (debug register)
0F 23 /r	MOV DR6-DR7, <i>r32</i>	11	Move (register) to (debug register)

### Operation

```

IF ((DE = 1) and (SRC or DEST = DR4 or DR5))
THEN
    #UD;
ELSE
    DEST ← SRC;

```

### Description

The above forms of the MOV instruction store or load the DR0, DR1, DR2, DR3, DR6 and DR7 debug registers to or from a general purpose register.

Thirty-two bit operands are always used with these instructions, regardless of the operand-size attribute.

When the DE (Debug Extension) bit in CR4 is clear, MOV instructions using debug registers operate in a manner that is compatible with Intel386 and Intel486 CPU's. References to DR4 and DR5 refer to DR6 and DR7, respectively. When the DE bit in CR4 is set, attempts to execute MOV instructions using DR4 and DR5 result in an Undefined Opcode (#UD) exception.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are undefined.

### Protected Mode Exceptions

#GP(0) if the current privilege level is not 0. #UD if the DE (Debug Extensions) bit of CR4 is set and a MOV instruction is executed using DR4 or DR5.

### Real Address Mode Exceptions

#GP(0) if an attempt is made to write a 1 to any reserved bits of CR4. #UD if the DE (Debug Extensions) bit of CR4 is set and a MOV instruction is executed using DR4 or DR5.

**Virtual 8086 Mode Exceptions**

#GP(0) if instruction execution is attempted.

**Notes**

The instructions must be executed at privilege level 0 or in real-address mode; otherwise, a protection exception will be raised.

The *reg* field within the ModR/M byte specifies which of the special registers in each category is involved. The two bits in the *mod* field are always 11. The *r/m* field specifies the general register involved.

Always set undefined or reserved bits to the value previously read.

## MOVS/MOVS<sub>B</sub>/MOVSW/MOVS<sub>D</sub>—Move Data from String to String

Opcode	Instruction	Clocks	Description
A4	MOVS <i>m8,m8</i>	4	Move byte [(E)SI] to ES:[(E)DI]
A5	MOVS <i>m16,m16</i>	4	Move word [(E)SI] to ES:[(E)DI]
A5	MOVS <i>m32,m32</i>	4	Move dword [(E)SI] to ES:[(E)DI]
A4	MOVS <sub>B</sub>	4	Move byte DS:[(E)SI] to ES:[(E)DI]
A5	MOVSW	4	Move word DS:[(E)SI] to ES:[(E)DI]
A5	MOVS <sub>D</sub>	4	Move dword DS:[(E)SI] to ES:[(E)DI]

### Operation

IF (instruction = MOVS<sub>D</sub>) OR (instruction has doubleword operands)

THEN OperandSize ← 32;

ELSE OperandSize ← 16;

IF AddressSize = 16

THEN use SI for source-index and DI for destination-index;

ELSE (\* AddressSize = 32 \*)

use ESI for source-index and EDI for destination-index;

FI;

IF byte type of instruction

THEN

[destination-index] ← [source-index]; (\* byte assignment \*)

IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;

ELSE

IF OperandSize = 16

THEN

[destination-index] ← [source-index]; (\* word assignment \*)

IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;

ELSE (\* OperandSize = 32 \*)

[destination-index] ← [source-index]; (\* doubleword assignment \*)

IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI;

FI;

FI;

source-index ← source-index + IncDec;

destination-index ← destination-index + IncDec;

### Description

The MOVS instruction copies the byte or word at [(E)SI] to the byte or word at ES:[(E)DI]. The destination operand must be addressable from the ES register; no segment override is possible for the destination. A segment override can be used for the source operand; the default is the DS register.

The addresses of the source and destination are determined solely by the contents of the (E)SI and (E)DI registers. Load the correct index values into the (E)SI and (E)DI registers before executing the MOVS instruction. The MOVS<sub>B</sub>, MOVSW, and MOVS<sub>D</sub> instructions are synonyms for the byte, word, and doubleword MOVS instructions.

After the data is moved, both the (E)SI and (E)DI registers are advanced automatically. If the DF flag is 0 (the CLD instruction was executed), the registers are incremented; if the DF flag is 1 (the STD instruction was executed), the registers are decremented. The registers are incremented or decremented by 1 if a byte was moved, 2 if a word was moved, or 4 if a doubleword was moved.

The MOVS instruction can be preceded by the REP prefix for block movement of ECX bytes or words. Refer to the REP instruction for details of this operation.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## MOVSX—Move with Sign-Extend

Opcode	Instruction	Clocks	Description
0F BE /r	MOVSX <i>r16,r/m8</i>	3	Move byte to word with sign-extend
0F BE /r	MOVSX <i>r32,r/m8</i>	3	Move byte to dword, sign-extend
0F BF /r	MOVSX <i>r32,r/m16</i>	3	Move word to dword, sign-extend

### Operation

DEST ← SignExtend(SRC);

### Description

The MOVSX instruction reads the contents of the effective address or register as a byte or a word, sign-extends the value to the operand-size attribute of the instruction (16 or 32 bits), and stores the result in the destination register.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**MOVZX—Move with Zero-Extend**

Opcode	Instruction	Clocks	Description
0F B6 /r	MOVZX r16,r/m8	3	Move byte to word with zero-extend
0F B6 /r	MOVZX r32,r/m8	3	Move byte to dword, zero-extend
0F B7 /r	MOVZX r32,r/m16	3	Move word to dword, zero-extend

**Operation**

DEST ← ZeroExtend(SRC);

**Description**

The MOVZX instruction reads the contents of the effective address or register as a byte or a word, zero extends the value to the operand-size attribute of the instruction (16 or 32 bits), and stores the result in the destination register.

**Flags Affected**

None.

**Protected Mode Exceptions**

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## MUL—Unsigned Multiplication of AL, AX, or EAX

Opcode	Instruction	Clocks	Description
F6 /4	MUL AL, <i>r/m8</i>	11	Unsigned multiply (AX ← AL * <i>r/m</i> byte)
F7 /4	MUL AX, <i>r/m16</i>	11	Unsigned multiply (DX:AX ← AX * <i>r/m</i> word)
F7 /4	MUL EAX, <i>r/m32</i>	10	Unsigned multiply (EDX:EAX ← EAX * <i>r/m</i> dword)

### Operation

IF byte-size operation

THEN AX ← AL \* *r/m8*

ELSE (\* word or doubleword operation \*)

IF OperandSize = 16

THEN DX:AX ← AX \* *r/m16*

ELSE (\* OperandSize = 32 \*)

EDX:EAX ← EAX \* *r/m32*

FI;

FI;

### Description

The MUL instruction performs unsigned multiplication. Its actions depend on the size of its operand, as follows:

- A byte operand is multiplied by the AL value; the result is left in the AX register. The CF and OF flags are cleared if the AH value is 0; otherwise, they are set.
- A word operand is multiplied by the AX value; the result is left in the DX:AX register pair. The DX register contains the high-order 16 bits of the product. The CF and OF flags are cleared if the DX value is 0; otherwise, they are set.
- A doubleword operand is multiplied by the EAX value and the result is left in the EDX:EAX register. The EDX register contains the high-order 32 bits of the product. The CF and OF flags are cleared if the EDX value is 0; otherwise, they are set.

### Flags Affected

The OF and CF flags are cleared if the upper half of the result is 0; otherwise they are set; the SF, ZF, AF, and PF flags are undefined.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## NEG—Two's Complement Negation

Opcode	Instruction	Clocks	Description
F6 /3	NEG <i>r/m8</i>	1/3	Two's complement negate <i>r/m</i> byte
F7 /3	NEG <i>r/m16</i>	1/3	Two's complement negate <i>r/m</i> word
F7 /3	NEG <i>r/m32</i>	1/3	Two's complement negate <i>r/m</i> dword

### Operation

IF  $r/m = 0$  THEN  $CF \leftarrow 0$  ELSE  $CF \leftarrow 1$ ;  $FI$ ;  
 $r/m \leftarrow -r/m$

### Description

The NEG instruction replaces the value of a register or memory operand with its two's complement. The operand is subtracted from zero, and the result is placed in the operand.

The CF flag is set, unless the operand is zero, in which case the CF flag is cleared.

### Flags Affected

The CF flag is set unless the operand is zero, in which case the CF flag is cleared; the OF, SF, ZF, and PF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## NOP—No Operation

Opcode	Instruction	Clocks	Description
90	NOP	1	No operation

### Description

The NOP instruction performs no operation. The NOP instruction is a one-byte instruction that takes up space but affects none of the machine context except the (E)IP register.

The NOP instruction is an alias mnemonic for the XCHG (E)AX, (E)AX instruction.

### Flags Affected

None.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.



## NOT—One's Complement Negation

Opcode	Instruction	Clocks	Description
F6 /2	NOT <i>r/m8</i>	1/3	Reverse each bit of <i>r/m</i> byte
F7 /2	NOT <i>r/m16</i>	1/3	Reverse each bit of <i>r/m</i> word
F7 /2	NOT <i>r/m32</i>	1/3	Reverse each bit of <i>r/m</i> dword

### Operation

$r/m \leftarrow \text{NOT } r/m;$

### Description

The NOT instruction inverts the operand; every 1 becomes a 0, and vice versa.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## OR—Logical Inclusive OR

Opcode	Instruction	Clocks	Description
0C <i>ib</i>	OR <i>AL,imm8</i>	1	OR immediate byte to AL
0D <i>iw</i>	OR <i>AX,imm16</i>	1	OR immediate word to AX
0D <i>id</i>	OR <i>EAX,imm32</i>	1	OR immediate dword to EAX
80 /1 <i>ib</i>	OR <i>r/m8,imm8</i>	1/3	OR immediate byte to <i>r/m</i> byte
81 /1 <i>iw</i>	OR <i>r/m16,imm16</i>	1/3	OR immediate word to <i>r/m</i> word
81 /1 <i>id</i>	OR <i>r/m32,imm32</i>	1/3	OR immediate dword to <i>r/m</i> dword
83 /1 <i>ib</i>	OR <i>r/m16,imm8</i>	1/3	OR sign-extended immediate byte with <i>r/m</i> word
83 /1 <i>ib</i>	OR <i>r/m32,imm8</i>	1/3	OR sign-extended immediate byte with <i>r/m</i> dword
08 <i>lr</i>	OR <i>r/m8,r8</i>	1/3	OR byte register to <i>r/m</i> byte
09 <i>lr</i>	OR <i>r/m16,r16</i>	1/3	OR word register to <i>r/m</i> word
09 <i>lr</i>	OR <i>r/m32,r32</i>	1/3	OR dword register to <i>r/m</i> dword
0A <i>lr</i>	OR <i>r8,r/m8</i>	1/2	OR byte register to <i>r/m</i> byte
0B <i>lr</i>	OR <i>r16,r/m16</i>	1/2	OR word register to <i>r/m</i> word
0B <i>lr</i>	OR <i>r32,r/m32</i>	1/2	OR dword register to <i>r/m</i> dword

### Operation

DEST ← DEST OR SRC;

CF ← 0;

OF ← 0

### Description

The OR instruction computes the inclusive OR of its two operands and places the result in the first operand. Each bit of the result is 0 if both corresponding bits of the operands are 0; otherwise, each bit is 1.

### Flags Affected

The  $\overline{OF}$  and  $\overline{CF}$  flags are cleared; the SF, ZF, and PF flags are set according to the result; the AF flag is undefined.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## OUT—Output to Port

Opcode	Instruction	Clocks	Description
E6 <i>ib</i>	OUT <i>imm8</i> ,AL	12, <i>pm</i> =9*/ 26**, <i>vm</i> =24	Output byte AL to immediate port number
E7 <i>ib</i>	OUT <i>imm8</i> ,AX	12, <i>pm</i> =9*/ 26**, <i>vm</i> =24	Output word AX to immediate port number
E7 <i>ib</i>	OUT <i>imm8</i> ,EAX	12, <i>pm</i> =9*/ 26**, <i>vm</i> =24	Output dword EAX to immediate port number
EE	OUT DX,AL	12, <i>pm</i> =9*/ 25**, <i>vm</i> =24	Output byte AL to port number in DX
EF	OUT DX,AX	12, <i>pm</i> =9*/ 25**, <i>vm</i> =24	Output word AX to port number in DX
EF	OUT DX,EAX	12, <i>pm</i> =9*/ 25**, <i>vm</i> =24	Output dword EAX to port number in DX

### NOTES:

\*If CPL ≤ IOPL

\*\*If CPL > IOPL

### Operation

```
IF (PE = 1) AND ((VM = 1) OR (CPL > IOPL))
THEN (* Virtual 8086 mode, or protected mode with CPL > IOPL *)
  IF NOT I-O-Permission (DEST, width(DEST))
  THEN #GP(0);
  FI;
FI;
[DEST] ← SRC; (* I/O address space used *)
```

### Description

The OUT instruction transfers a data byte or data word from the register (AL, AX, or EAX) given as the second operand to the output port numbered by the first operand. Output to any port from 0 to 65535 is performed by placing the port number in the DX register and then using an OUT instruction with the DX register as the first operand. If the instruction contains an eight-bit port ID, that value is zero-extended to 16 bits.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the current privilege level is higher (has less privilege) than the I/O privilege level and any of the corresponding I/O permission bits in the TSS equals 1.

### Real Address Mode Exceptions

None.

**Virtual 8086 Mode Exceptions**

#GP(0) fault if any of the corresponding I/O permission bits in the TSS equals 1.

**Notes**

After the OUT or OUTS instructions are executed, the Pentium processor ensures that the EWBE# has been sampled active before beginning to execute the next instruction. Note that the instruction may be prefetched if EWBE# is not active, but it will not execute until EWBE# is sampled active.

**OUTS/OUTSB/OUTSW/OUTSD—Output String to Port**

Opcode	Instruction	Clocks	Description
6E	OUTS DX, <i>r/m8</i>	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output byte [(E)SI] to port in DX
6F	OUTS DX, <i>r/m16</i>	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output word [(E)SI] to port in DX
6F	OUTS DX, <i>r/m32</i>	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output dword [(E)SI] to port in DX
6E	OUTSB	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output byte DS:[(E)SI] to port in DX
6F	OUTSW	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output word DS:[(E)SI] to port in DX
6F	OUTSD	13, <i>pm</i> =10/ 27**, <i>VM</i> =25	Output dword DS:[(E)SI] to port in DX

**NOTES:**\*If  $CPL \leq IOPL$ \*\*If  $CPL > IOPL$ **Operation**

IF AddressSize = 16

THEN use SI for source-index;

ELSE (\* AddressSize = 32 \*)

use ESI for source-index;

FI;

IF (PE = 1) AND ((VM = 1) OR (CPL &gt; IOPL))

THEN (\* Virtual 8086 mode, or protected mode with CPL &gt; IOPL \*)

IF NOT I-O-Permission (DEST, width(DEST))

THEN #GP(0);

FI;

FI;

IF byte type of instruction

THEN

[DX] ← [source-index]; (\* Write byte at DX I/O address \*)

IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;

FI;

IF OperandSize = 16

THEN

[DX] ← [source-index]; (\* Write word at DX I/O address \*)

IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;

FI;

IF OperandSize = 32

THEN

[DX] ← [source-index]; (\* Write dword at DX I/O address \*)

IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI;

FI;

FI;

source-index ← source-index + IncDec;

## Description

The OUTS instruction transfers data from the memory byte, word, or doubleword at the source-index register to the output port addressed by the DX register. If the address-size attribute for this instruction is 16 bits, the SI register is used for the source-index register; otherwise, the address-size attribute is 32 bits, and the ESI register is used for the source-index register.

The OUTS instruction does not allow specification of the port number as an immediate value. The port must be addressed through the DX register value. Load the correct value into the DX register before executing the OUTS instruction.

The address of the source data is determined by the contents of source-index register. Load the correct index value into the SI or ESI register before executing the OUTS instruction.

After the transfer, source-index register is advanced automatically. If the DF flag is 0 (the CLD instruction was executed), the source-index register is incremented; if the DF flag is 1 (the STD instruction was executed), it is decremented. The amount of the increment or decrement is 1 if a byte is output, 2 if a word is output, or 4 if a doubleword is output.

The OUTSB, OUTSW, and OUTSD instructions are synonyms for the byte, word, and doubleword OUTS instructions. The OUTS instruction can be preceded by the REP prefix for block output of ECX bytes or words. Refer to the REP instruction for details on this operation.

## Flags Affected

None.

## Protected Mode Exceptions

#GP(0) if the current privilege level is greater than the I/O privilege level and any of the corresponding I/O permission bits in TSS equals 1; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

## Virtual 8086 Mode Exceptions

#GP(0) fault if any of the corresponding I/O permission bits in TSS equals 1; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Notes**

After the OUT or OUTS instructions are executed, the Pentium processor ensures that the EWBE# has been sampled active before beginning to execute the next instruction. Note that the instruction may be prefetched if EWBE# is not active, but it will not execute until EWBE# is sampled active.



## POP—Pop a Word from the Stack

Opcode	Instruction	Clocks	Description
8F /0	POP <i>m16</i>	3	Pop top of stack into memory word
8F /0	POP <i>m32</i>	3	Pop top of stack into memory dword
58+ <i>rw</i>	POP <i>r16</i>	1	Pop top of stack into word register
58+ <i>rd</i>	POP <i>r32</i>	1	Pop top of stack into dword register
1F	POP DS	3	Pop top of stack into DS
07	POP ES	3	Pop top of stack into ES
17	POP SS	3	Pop top of stack into SS
0F A1	POP FS	3	Pop top of stack into FS
0F A9	POP GS	3	Pop top of stack into GS

### Operation

```

IF StackAddrSize = 16
THEN
  IF OperandSize = 16
  THEN
    DEST ← (SS:SP); (* copy a word *)
    SP ← SP + 2;
  ELSE (* OperandSize = 32 *)
    DEST ← (SS:SP); (* copy a dword *)
    SP ← SP + 4;
  FI;
ELSE (* StackAddrSize = 32 *)
  IF OperandSize = 16
  THEN
    DEST ← (SS:ESP); (* copy a word *)
    ESP ← ESP + 2;
  ELSE (* OperandSize = 32 *)
    DEST ← (SS:ESP); (* copy a dword *)
    ESP ← ESP + 4;
  FI;
FI;

```

### Description

The POP instruction replaces the previous contents of the memory, the register, or the segment register operand with the word on the top of the Pentium processor stack, addressed by SS:SP (address-size attribute of 16 bits) or SS:ESP (address-size attribute of 32 bits). The stack pointer SP is incremented by 2 for an operand-size of 16 bits or by 4 for an operand-size of 32 bits. It then points to the new top of stack.

The POP CS instruction is not a Pentium processor instruction. Popping from the stack into the CS register is accomplished with a RET instruction.

If the destination operand is a segment register (DS, ES, FS, GS, or SS), the value popped must be a selector. In protected mode, loading the selector initiates automatic loading of the

descriptor information associated with that selector into the hidden part of the segment register; loading also initiates validation of both the selector and the descriptor information.

A null value (0000-0003) may be popped into the DS, ES, FS, or GS register without causing a protection exception. An attempt to reference a segment whose corresponding segment register is loaded with a null value causes a #GP(0) exception. No memory reference occurs. The saved value of the segment register is null.

A POP SS instruction inhibits all interrupts, including NMI, until after execution of the next instruction. This allows sequential execution of POP SS and MOV eSP, eBP instructions without danger of having an invalid stack during an interrupt. However, use of the LSS instruction is the preferred method of loading the SS and eSP registers.

A POP-to-memory instruction, which uses the stack pointer (ESP) as a base register, references memory after the POP. The base used is the value of the ESP after the instruction executes.

Loading a segment register while in protected mode results in special checks and actions, as described in the following listing:

IF SS is loaded:

```
IF selector is null THEN #GP(0);
Selector index must be within its descriptor table limits ELSE
  #GP(selector);
Selector's RPL must equal CPL ELSE #GP(selector);
AR byte must indicate a writable data segment ELSE #GP(selector);
DPL in the AR byte must equal CPL ELSE #GP(selector);
Segment must be marked present ELSE #SS(selector);
Load SS register with selector;
Load SS register with descriptor;
```

IF DS, ES, FS or GS is loaded with non-null selector:

```
AR byte must indicate data or readable code segment ELSE
  #GP(selector);
IF data or nonconforming code
THEN both the RPL and the CPL must be less than or equal to DPL in
  AR byte
ELSE #GP(selector);
FI;
Segment must be marked present ELSE #NP(selector);
Load segment register with selector;
Load segment register with descriptor;
```

IF DS, ES, FS, or GS is loaded with a null selector:

```
Load segment register with selector
Clear valid bit in invisible portion of register
```

## Flags Affected

None.



## Protected Mode Exceptions

#GP, #SS, and #NP if a segment register is being loaded; #SS(0) if the current top of stack is not within the stack segment; #GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

## Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## Notes

Back-to-back PUSH/POP instruction sequences are allowed without incurring an additional clock.

The stack segment descriptor's B bit will determine the size of Stack Addr Size.

Pop ESP instructions increments the stack pointer (ESP) before data at the old top of stack is written into the destination.

When POP SS is used to switch from a 32-bit stack to a 16-bit stack, the Pentium processor updates ESP[15:0] (or the SP register), based on the new value of the B bit (B = '0') of the stack segment descriptor. In the case where the value in ESP before the switch contains a boundary condition (e.g., ESP[31:0] = 07ffffffch), the new value in ESP after the switch will only be reflected on the lower 16 bits (i.e., ESP[31:0] = 07fff0000h). Therefore, code that switches from a 32-bit stack to a 16-bit stack via the POP SS instruction must not rely on ESP[31:16].

Similar considerations apply when switching from 16-bit to 32-bit stacks. When executing POP SS to switch from 16-bit stack to 32-bit stack, only SP (the old stack size) is used to increment the stack pointer, instead of ESP (the new stack size, 32-bit).

## POPA/POPAD—Pop all General Registers

Opcode	Instruction	Clocks	Description
61	POPA	5	Pop DI, SI, BP, BX, DX, CX, and AX
61	POPAD	5	Pop EDI, ESI, EBP, EDX, ECX, and EAX

### Operation

IF OperandSize = 16 (\* instruction = POPA \*)

THEN

DI ← Pop();

SI ← Pop();

BP ← Pop();

increment ESP by 2 (\* skip next 2 bytes of stack \*)

BX ← Pop();

DX ← Pop();

CX ← Pop();

AX ← Pop();

ELSE (\* OperandSize = 32, instruction = POPAD \*)

EDI ← Pop();

ESI ← Pop();

EBP ← Pop();

increment ESP by 4 (\* skip next 4 bytes of stack \*)

EBX ← Pop();

EDX ← Pop();

ECX ← Pop();

EAX ← Pop();

FI;

### Description

The POPA instruction pops the eight 16-bit general registers. However, the SP value is discarded instead of loaded into the SP register. The POPA instruction reverses a previous PUSHA instruction, restoring the general registers to their values before the PUSHA instruction was executed. The first register popped is the DI register.

The POPAD instruction pops the eight 32-bit general registers. The ESP value is discarded instead of loaded into the ESP register. The POPAD instruction reverses the previous PUSHAD instruction, restoring the general registers to their values before the PUSHAD instruction was executed. The first register popped is the EDI register.

### Flags Affected

None.



**Protected Mode Exceptions**

#SS(0) if the starting or ending stack address is not within the stack segment; #PF(fault-code) for a page fault.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in real-address mode; #PF(fault-code) for a page fault.

## POPF/POPFD—Pop Stack into FLAGS or EFLAGS Register

Opcode	Instruction	Clocks	Description
9D	POPF	<i>pm</i> = 4, <i>rm</i> and <i>vm</i> = 6	Pop top of stack FLAGS
9D	POPFD	<i>pm</i> = 4, <i>rm</i> and <i>vm</i> = 6	Pop top of stack into EFLAGS

### Operation

IF VM=0 (\* Not in Virtual-8086 Mode \*)

THEN

IF OperandSize=32;

THEN EFLAGS ← Pop() AND 277FD7H;

ELSE FLAGS ← Pop();

FI;

ELSE (\* In Virtual-8086 Mode \*)

IF IOPL=3

THEN

IF OperandSize=32

THEN

TempEflags ← Pop();

EFLAGS ← ((EFLAGS AND 1B3000H) OR (TempEflags AND ~1B3000H))

(\* VM, RF, IOPL, VIP, and VIF of EFLAGS bits are not modified  
by POPFD \*)

ELSE

FLAGS ← Pop()

FI;

ELSE

#GP(0); (\* trap to virtual-8086 monitor \*)

FI;

FI;

### Description

The POPF and POPFD instructions pop the word or doubleword on the top of the stack and store the value in the FLAGS register. If the operand-size attribute of the instruction is 16 bits, then a word is popped and the value is stored in the FLAGS register. If the operand-size attribute is 32 bits, then a doubleword is popped and the value is stored in the EFLAGS register.

When the IOPL is less than 3 in virtual-8086 mode, the POPF instruction causes a general protection exception. When the IOPL is equal to 3 while executing in virtual-8086 mode, POPF pops a word into the FLAGS register.

Refer to Chapter 3 and Chapter 10 for information about the FLAGS and EFLAGS registers. Note that bits 16 and 17 of the EFLAGS register, called the VM and RF flags, respectively, are not affected by the POPF or POPFD instruction.

The I/O privilege level is altered only when executing at privilege level 0. The interrupt flag is altered only when executing at a level at least as privileged as the I/O privilege level.

(Real-address mode is equivalent to privilege level 0.) If a POPF instruction is executed with insufficient privilege, an exception does not occur, but the privileged bits do not change.

### Flags Affected

All flags except the VM, RF, IOPL, VIF and VIP flags.

### Protected Mode Exceptions

#SS(0) if the top of stack is not within the stack segment.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

#GP(0) fault if the I/O privilege level is less than 3 in order to permit emulation. #GP(0) if an attempt is made to execute POPF with an operand-size override prefix.

### Notes

For information on the effect of POPF and POPFD when using virtual mode extensions, see Appendix H.

**PUSH—Push Operand onto the Stack**

Opcode	Instruction	Clocks	Description
FF /6	PUSH <i>r/m16</i>	1/2	Push reg/mem word
FF /6	PUSH <i>r/m32</i>	1/2	Push reg/mem dword
50+ <i>rw</i>	PUSH <i>r16</i>	1	Push register word
50+ <i>rd</i>	PUSH <i>r32</i>	1	Push register dword
6A	PUSH <i>imm8</i>	1	Push immediate byte
68	PUSH <i>imm16</i>	1	Push immediate word
68	PUSH <i>imm32</i>	1	Push immediate dword
0E	PUSH CS	1	Push CS
16	PUSH SS	1	Push SS
1E	PUSH DS	1	Push DS
06	PUSH ES	1	Push ES
0F A0	PUSH FS	1	Push FS
0F A8	PUSH GS	1	Push GS

**Operation**

IF StackAddrSize = 16

THEN

IF OperandSize = 16 THEN

SP ← SP – 2;

(SS:SP) ← (SOURCE); (\* word assignment \*)

ELSE

SP ← SP – 4;

(SS:SP) ← (SOURCE); (\* dword assignment \*)

FI;

ELSE (\* StackAddrSize = 32 \*)

IF OperandSize = 16

THEN

ESP ← ESP – 2;

(SS:ESP) ← (SOURCE); (\* word assignment \*)

ELSE

ESP ← ESP – 4;

(SS:ESP) ← (SOURCE); (\* dword assignment \*)

FI;

FI;

**Description**

The PUSH instruction decrements the stack pointer by 2 if the operand-size attribute of the instruction is 16 bits; otherwise, it decrements the stack pointer by 4. The PUSH instruction then places the operand on the new top of stack, which is pointed to by the stack pointer.

The PUSH ESP instruction pushes the value of the ESP register as it existed before the instruction. This differs from the 8086, where the PUSH SP instruction pushes the new value (decremented by 2).

Likewise, a PUSH-from-memory instruction, which uses the stack pointer (ESP) as a base register, references memory before the PUSH. The base used is the value of the ESP before the instruction executes.

### Flags Affected

None.

### Protected Mode Exceptions

#SS(0) if the new value of the SP or ESP register is outside the stack segment limit; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

None; if the SP or ESP register is 1, the processor shuts down due to a lack of stack space.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

When used with an operand in memory, the PUSH instruction takes longer to execute than a two-instruction sequence which moves the operand through a register.

Back-to-back PUSH/POP instruction sequences are allowed without incurring an additional clock.

Selective pushes write only the top of the stack.

**PUSHA/PUSHAD—Push all General Registers**

Opcode	Instruction	Clocks	Description
60	PUSHA	5	Push AX, CX, DX, BX, original SP, BP, SI, and DI
60	PUSHAD	5	Push EAX, ECX, EDX, EBX, original ESP, EBP, ESI, and EDI

**Operation**

IF OperandSize = 16 (\* PUSHA instruction \*)

THEN Temp ← (SP);

Push(AX);  
 Push(CX);  
 Push(DX);  
 Push(BX);  
 Push(Temp);  
 Push(BP);  
 Push(SI);  
 Push(DI);

ELSE (\* OperandSize = 32, PUSHAD instruction \*)

Temp ← (ESP);  
 Push(EAX);  
 Push(ECX);  
 Push(EDX);  
 Push(EBX);  
 Push(Temp);  
 Push(EBP);  
 Push(ESI);  
 Push(EDI);

FI;

**Description**

The PUSHA and PUSHAD instructions save the 16-bit or 32-bit general registers, respectively, on the Pentium processor stack. The PUSHA instruction decrements the stack pointer (SP) by 16 to hold the eight word values. The PUSHAD instruction decrements the stack pointer (ESP) by 32 to hold the eight doubleword values. Because the registers are pushed onto the stack in the order in which they were given, they appear in the 16 or 32 new stack bytes in reverse order. The last register pushed is the DI or EDI register.

**Flags Affected**

None.

**Protected Mode Exceptions**

#SS(0) if the starting or ending stack address is outside the stack segment limit; #PF(fault-code) for a page fault.

**Real Address Mode Exceptions**

Before executing the PUSHA or PUSHAD instruction, the Pentium processor shuts down if the SP or ESP register equals 1, 3, or 5; if the SP or ESP register equals 7, 9, 11, 13, or 15, exception 13 occurs.

**Virtual 8086 Mode Exceptions**

Same exceptions as in real-address mode; #PF(fault-code) for a page fault.

**PUSHF/PUSHFD—Push Flags Register onto the Stack**

Opcode	Instruction	Clocks	Description
9C	PUSHF	<i>pm=3, rm and vm=4</i>	Push FLAGS
9C	PUSHFD	<i>pm=3,rm and vm=4</i>	Push EFLAGS

**Operation**

IF VM=0 (\* Not in Virtual-8086 Mode \*)

THEN

IF OperandSize = 32

THEN push(EFLAGS AND 0FCFFFFH); (\* VM and RF EFLAG bits are cleared \*)

ELSE push(FLAGS);

FI;

ELSE (\* In Virtual-8086 Mode \*)

IF IOPL=3

THEN

IF OperandSize = 32

THEN push(EFLAGS AND 0FCFFFFH); (\* VM and RF EFLAGS bits are cleared \*)

ELSE push(FLAGS);

FI;

ELSE

#GP(0); (\* Trap to virtual-8086 monitor \*)

FI;

FI;

**Description**

The PUSHF instruction decrements the stack pointer by 2 and copies the FLAGS register to the new top of stack; the PUSHFD instruction decrements the stack pointer by 4, and the EFLAGS register is copied to the new top of stack which is pointed to by SS:ESP. Refer to Chapter 3 and Chapter 10 for information on the EFLAGS register.

**Flags Affected**

None.

**Protected Mode Exceptions**

#SS(0) if the new value of the ESP register is outside the stack segment boundaries.

**Real Address Mode Exceptions**

None; the processor shuts down due to a lack of stack space.

**Virtual 8086 Mode Exceptions**

#GP(0) fault if the I/O privilege level is less than 3, to permit emulation.

**Notes**

For information on this instruction when using virtual mode extensions, see Appendix H.

## RCL/RCL/ROR/ROR—Rotate

Opcode	Instruction	Clocks	Description
D0 /2	RCL <i>r/m</i> ,1	1/3	Rotate 9 bits (CF, <i>r/m</i> byte) left once
D2 /2	RCL <i>r/m</i> ,CL	7-24/9-26	Rotate 9 bits (CF, <i>r/m</i> byte) left CL times
C0 /2 <i>ib</i>	RCL <i>r/m</i> , <i>imm</i> 8	8-25/10-27	Rotate 9 bits (CF, <i>r/m</i> byte) left <i>imm</i> 8 times
D1 /2	RCL <i>r/m</i> 16,1	1/3	Rotate 17 bits (CF, <i>r/m</i> word) left once
D3 /2	RCL <i>r/m</i> 16,CL	7-24/9-26	Rotate 17 bits (CF, <i>r/m</i> word) left CL times
C1 /2 <i>ib</i>	RCL <i>r/m</i> 16, <i>imm</i> 8	8-25/10-27	Rotate 17 bits (CF, <i>r/m</i> word) left <i>imm</i> 8 times
D1 /2	RCL <i>r/m</i> 32,1	1/3	Rotate 33 bits (CF, <i>r/m</i> dword) left once
D3 /2	RCL <i>r/m</i> 32,CL	7-24/9-26	Rotate 33 bits (CF, <i>r/m</i> dword) left CL times
C1 /2 <i>ib</i>	RCL <i>r/m</i> 32, <i>imm</i> 8	8-25/10-27	Rotate 33 bits (CF, <i>r/m</i> dword) left <i>imm</i> 8 times
D0 /3	RCL <i>r/m</i> ,1	1/3	Rotate 9 bits (CF, <i>r/m</i> byte) right once
D2 /3	RCL <i>r/m</i> ,CL	7-24/9-26	Rotate 9 bits (CF, <i>r/m</i> byte) right CL times
C0 /3 <i>ib</i>	RCL <i>r/m</i> , <i>imm</i> 8	8-25/10-27	Rotate 9 bits (CF, <i>r/m</i> byte) right <i>imm</i> 8 times
D1 /3	RCL <i>r/m</i> 16,1	1/3	Rotate 17 bits (CF, <i>r/m</i> word) right once
D3 /3	RCL <i>r/m</i> 16,CL	7-24/9-26	Rotate 17 bits (CF, <i>r/m</i> word) right CL times
C1 /3 <i>ib</i>	RCL <i>r/m</i> 16, <i>imm</i> 8	8-25/10-27	Rotate 17 bits (CF, <i>r/m</i> word) right <i>imm</i> 8 times
D1 /3	RCL <i>r/m</i> 32,1	1/3	Rotate 33 bits (CF, <i>r/m</i> dword) right once
D3 /3	RCL <i>r/m</i> 32,CL	7-24/9-26	Rotate 33 bits (CF, <i>r/m</i> dword) right CL times
C1 /3 <i>ib</i>	RCL <i>r/m</i> 32, <i>imm</i> 8	8-25/10-27	Rotate 33 bits (CF, <i>r/m</i> dword) right <i>imm</i> 8 times
D0 /0	ROL <i>r/m</i> ,1	1/3	Rotate 8 bits <i>r/m</i> byte left once
D2 /0	ROL <i>r/m</i> ,CL	4	Rotate 8 bits <i>r/m</i> byte left CL times
C0 /0 <i>ib</i>	ROL <i>r/m</i> , <i>imm</i> 8	1/3	Rotate 8 bits <i>r/m</i> byte left <i>imm</i> 8 times
D1 /0	ROL <i>r/m</i> 16,1	1/3	Rotate 16 bits <i>r/m</i> word left once
D3 /0	ROL <i>r/m</i> 16,CL	4	Rotate 16 bits <i>r/m</i> word left CL times
C1 /0 <i>ib</i>	ROL <i>r/m</i> 16, <i>imm</i> 8	1/3	Rotate 16 bits <i>r/m</i> word left <i>imm</i> 8 times
D1 /0	ROL <i>r/m</i> 32,1	1/3	Rotate 32 bits <i>r/m</i> dword left once
D3 /0	ROL <i>r/m</i> 32,CL	4	Rotate 32 bits <i>r/m</i> dword left CL times
C1 /0 <i>ib</i>	ROL <i>r/m</i> 32, <i>imm</i> 8	1/3	Rotate 32 bits <i>r/m</i> dword left <i>imm</i> 8 times
D0 /1	ROR <i>r/m</i> ,1	1/3	Rotate 8 bits <i>r/m</i> byte right once
D2 /1	ROR <i>r/m</i> ,CL	4	Rotate 8 bits <i>r/m</i> byte right CL times
C0 /1 <i>ib</i>	ROR <i>r/m</i> , <i>imm</i> 8	1/3	Rotate 8 bits <i>r/m</i> word right <i>imm</i> 8 times
D1 /1	ROR <i>r/m</i> 16,1	1/3	Rotate 16 bits <i>r/m</i> word right once
D3 /1	ROR <i>r/m</i> 16,CL	4	Rotate 16 bits <i>r/m</i> word right CL times
C1 /1 <i>ib</i>	ROR <i>r/m</i> 16, <i>imm</i> 8	1/3	Rotate 16 bits <i>r/m</i> word right <i>imm</i> 8 times
D1 /1	ROR <i>r/m</i> 32,1	1/3	Rotate 32 bits <i>r/m</i> dword right once
D3 /1	ROR <i>r/m</i> 32,CL	4	Rotate 32 bits <i>r/m</i> dword right CL times
C1 /1 <i>ib</i>	ROR <i>r/m</i> 32, <i>imm</i> 8	1/3	Rotate 32 bits <i>r/m</i> dword right <i>imm</i> 8 times

### Operation

(\* ROL - Rotate Left \*)

temp ← COUNT;

WHILE (temp <> 0)

DO

tmpcf ← high-order bit of (*r/m*);

*r/m* ← *r/m* \* 2 + (tmpcf);

temp ← temp - 1;

OD;

IF COUNT = 1

THEN

IF high-order bit of *r/m* <> CF

THEN OF ← 1;

ELSE OF ← 0;

FI;

ELSE OF ← undefined;

```

FI;
(* ROR - Rotate Right *)
temp ← COUNT;
WHILE (temp <> 0 )
DO
    tmpcf ← low-order bit of (r/m);
    r/m ← r/m / 2 + (tmpcf * 2width(r/m));
    temp ← temp - 1;
DO;
IF COUNT = 1
THEN
    IF (high-order bit of r/m) <> (bit next to high-order bit of r/m)
    THEN OF ← 1;
    ELSE OF ← 0;
    FI;
ELSE OF ← undefined;
FI;

```

### Description

Each rotate instruction shifts the bits of the register or memory operand given. The left rotate instructions shift all the bits upward, except for the top bit, which is returned to the bottom. The right rotate instructions do the reverse: the bits shift downward until the bottom bit arrives at the top.

For the RCL and RCR instructions, the CF flag is part of the rotated quantity. The RCL instruction shifts the CF flag into the bottom bit and shifts the top bit into the CF flag; the RCR instruction shifts the CF flag into the top bit and shifts the bottom bit into the CF flag. For the ROL and ROR instructions, the original value of the CF flag is not a part of the result, but the CF flag receives a copy of the bit that was shifted from one end to the other.

The rotate is repeated the number of times indicated by the second operand, which is either an immediate number or the contents of the CL register. To reduce the maximum instruction execution time, the Pentium processor does not allow rotation counts greater than 31. If a rotation count greater than 31 is attempted, only the bottom five bits of the rotation are used. The 8086 does not mask rotation counts. The Pentium processor in Virtual 8086 Mode does mask rotation counts.

The OF flag is defined only for the single-rotate forms of the instructions (second operand is a 1). It is undefined in all other cases. For left shifts/rotates, the CF bit after the shift is XORed with the high-order result bit. For right shifts/rotates, the high-order two bits of the result are XORed to get the OF flag.

### Flags Affected

The OF flag is affected only for single-bit rotates; the OF flag is undefined for multi-bit rotates; the CF flag contains the value of the bit shifted into it; the SF, ZF, AF, and PF flags are not affected.

**Protected Mode Exceptions**

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## RDMSR—Read from Model Specific Register

Opcode	instruction	Clocks	Description
0F 32	RDMSR	20-24	Read Model Specific Register indicated by ECX into EDX:EAX

### Operation

EDX:EAX ← MSR[ECX];

### Description

The value in ECX specifies one of the 64-bit Model Specific Registers of the Pentium processor. The content of that Model-Specific Register is copied into EDX:EAX. EDX is loaded with the high-order 32 bits, and EAX is loaded with the low-order 32 bits.

The following values are used to select model specific registers on the Pentium processor:

Value (in Hex)	Register Name	Description
00H	Machine Check Address	Stores address of cycle causing the exception
01H	Machine Check Type	Stores cycle type of cycle causing the exception

For other values used to perform cache, TLB, and BTB testing and performance monitoring, see *Pentium® Family User's Manual* Chapter 33.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if either the current privilege level is not 0 or the value in ECX does not specify a Model-Specific Register that is implemented in the Pentium processor.

### Real Address Mode Exceptions

#GP(0) if the value in ECX does not specify a Model-Specific Register that is implemented in the Pentium processor.

### Virtual 8086 Mode Exceptions

#GP(0) if instruction execution is attempted.

**Notes**

This instruction must be executed at privilege level 0 or in real-address mode; otherwise, a protection exception will be generated.

If fewer than 64 bits are implemented in a model specific register, the value returned to EDX:EAX, in the locations corresponding to the unimplemented bits, is unpredictable.

RDMSR is used to read the content of Model-Specific Registers that control functions for testability, execution tracing, performance monitoring and machine check errors. Refer to the *Pentium® Processor Data Book* for more information.

The values 3H, 0FH, and values above 13H are reserved. Do not execute RDMSR with reserved values in ECX.

**The CPUID instruction should be used to determine whether Pentium® processor-style model specific registers are supported (EDX[5] = 1) before using this instruction. A general protection exception will occur if the feature is not supported**



## RDTSC—Read from Time Stamp Counter

Opcode	Instruction	Clocks	Description
0F31	RDTSC	6-11*	Read Time Stamp Counter into EDX:EAX

**NOTES:** 6 clocks at PL0, 11 clocks at PL1-3

### Operation

EDX:EAX ← Time Stamp Counter;

### Description

The Pentium processor maintains a 64-bit Time Stamp Counter (EDX[4:4]) that increments every clock cycle. The RDTSC instruction copies the content of the Time Stamp Counter into EDX:EAX. EDX is loaded with the high-order 32 bits, and EAX is loaded with the low-order 32 bits. When the Current Privilege Level (CPL) is 0, the state of the TSD bit in CR4 does not affect the operation of this instruction. When the CPL>0, the Time Stamp Counter can be read only if CR4.TSD=0. Only a supervisor level program (CPL=0) may modify the value of the Time Stamp Counter.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the TSD bit in CR4 is set to 1 and the current privilege level is not 0.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

#GP(0) if instruction execution is attempted.

### Notes

The Time Stamp Counter is the same counter that is part of the Pentium processor's performance monitor features. The function of the RDTSC instruction is equivalent to that of the RDMSR instruction, but is available at the application level in an implementation independent manner. The privileged RDMSR instruction takes longer to execute than the RDTSC instruction because of the instruction checks that are performed for the RDMSR instruction. Because of this, sampling of the time stamp counter occurs at different points in instruction execution. This results in a different absolute count depending on whether the RDTSC or RDMSR instruction is used. However, the difference in absolute count obtained

from these two instructions is constant from event to event. The recommended method for counting the number of elapsed clocks is to use the difference in the time stamp counter value before and after the event.

**The CPUID instruction should be used to determine whether Pentium processor-style model specific registers are supported (EDX[5]=1) before using this instruction. A general protection exception will occur if the feature is not supported.**

## REP/REPE/REPZ/REPNE/REPNZ—Repeat Following String Operation

Opcode	Instruction	Clocks	Description
F3 6C	REP INS <i>r/m8, DX</i>	11+3(E)CX, $pm=8+3(E)CX^{*1}/25+$ $3(E)CX^{*2}$ , VM=23+3(E)CX	Input (E)CX bytes from port DX into ES:[(E)DI]
F3 6D	REP INS <i>r/m16,DX</i>	11+3(E)CX, $pm=8+3(E)CX^{*1}/25+$ $3(E)CX^{*2}$ , VM=23+3(E)CX	Input (E)CX words from port DX into ES:[(E)DI]
F3 6D	REP INS <i>r/m32,DX</i>	11+3(E)CX, $pm=8+3(E)CX^{*1}/25+$ $3(E)CX^{*2}$ , VM=23+3(E)CX	Input (E)CX dwords from port DX into ES:[(E)DI]
F3 A4	REP MOVS <i>m8,m8</i>	$6^{*3},13^{*4}$ , $13+(E)CX^{*5}$	Move (E)CX bytes from [(E)SI] to ES:[(E)DI]
F3 A5	REP MOVS <i>m16,m16</i>	$6^{*3},13^{*4}$ , $13+(E)CX^{*5}$	Move (E)CX words from [(E)SI] to ES:[(E)DI]
F3 A5	REP MOVS <i>m32,m32</i>	$6^{*3},13^{*4}$ , $13+(E)CX^{*5}$	Move (E)CX dwords from [(E)SI] to ES:[(E)DI]
F3 6E	REP OUTS <i>DX,r/m8</i>	13+4(E)CX, $pm=10+4(E)CX^{*1}/27$ $+4(E)CX^{*2}$ vm=25+4(E)CX	Output (E)CX bytes from [(E)SI] to port DX
F3 6F	REP OUTS <i>DX,r/m16</i>	13+4(E)CX, $pm=10+4(E)CX^{*1}/27$ $+4(E)CX^{*2}$ vm=25+4(E)CX	Output (E)CX words from [(E)SI] to port DX
F3 6F	REP OUTS <i>DX,r/m32</i>	13+4(E)CX, $pm=10+4(E)CX^{*1}/27$ $+4(E)CX^{*2}$ vm=25+4(E)CX	Output (E)CX dwords from [(E)SI] to port DX
F3 AC	REP LODS AL	$7^{*3},7+3(E)CX^{*6}$	Load (E)CX bytes from [(E)SI] to AL
F3 AD	REP LODS AX	$7^{*3},7+3(E)CX^{*6}$	Load (E)CX words from [(E)SI] to AX
F3 AD	REP LODS EAX	$7^{*3},7+3(E)CX^{*6}$	Load (E)CX dwords from [(E)SI] to EAX
F3 AA	REP STOS <i>m8</i>	$6^{*3},9(E)CX^{*6}$	Fill (E)CX bytes at ES:[(E)DI] with AL
F3 AB	REP STOS <i>m16</i>	$6^{*3},9(E)CX^{*6}$	Fill (E)CX words at ES:[(E)DI] with AX
F3 AB	REP STOS <i>m32</i>	$6^{*3},9(E)CX^{*6}$	Fill (E)CX dwords at ES:[(E)DI] with EAX
F3 A6	REPE CMPS <i>m8,m8</i>	$7^{*3},9+4(E)CX^{*6}$	Find nonmatching bytes in ES:[(E)DI] and [(E)SI]
F3 A7	REPE CMPS <i>m16,m16</i>	$7^{*3},9+4(E)CX^{*6}$	Find nonmatching words in ES:[(E)DI] and [(E)SI]
F3 A7	REPE CMPS <i>m32,m32</i>	$7^{*3},9+4(E)CX^{*6}$	Find nonmatching dwords in ES:[(E)DI] and [(E)SI]
F3 AE	REPE SCAS <i>m8</i>	$7^{*3},9+4(E)CX^{*6}$	Find non-AL byte starting at ES:[(E)DI]
F3 AF	REPE SCAS <i>m16</i>	$7^{*3},9+4(E)CX^{*6}$	Find non-AX word starting at ES:[(E)DI]
F3 AF	REPE SCAS <i>m32</i>	$7^{*3},9+4(E)CX^{*6}$	Find non-EAX dword starting at ES:[(E)DI]
F2 A6	REPNE CMPS <i>m8,m8</i>	$7^{*3},8+4(E)CX^{*6}$	Find matching bytes in ES:[(E)DI] and [(E)SI]

Opcode	Instruction	Clocks	Description
F2 A7	REPNE CMPS <i>m16,m16</i>	$7^{\cdot 3},8+4(E)CX^{\cdot 6}$	Find matching words in ES:[(E)DI] and [(E)SI]
F2 A7	REPNE CMPS <i>m32,m32</i>	$7^{\cdot 3},8+4(E)CX^{\cdot 6}$	Find matching dwords in ES:[(E)DI] and [(E)SI]
F2 AE	REPNE SCAS <i>m8</i>	$7^{\cdot 3},9+4(E)CX^{\cdot 6}$	Find AL, starting at ES:[(E)DI]
F2 AF	REPNE SCAS <i>m16</i>	$7^{\cdot 3},9+4(E)CX^{\cdot 6}$	Find AX, starting at ES:[(E)DI]
F2 AF	REPNE SCAS <i>m32</i>	$7^{\cdot 3},9+4(E)CX^{\cdot 6}$	Find EAX, starting at ES:[(E)DI]

**NOTES:**\*1 If  $CPL \leq IOPL$ \*2 If  $CPL > IOPL$ 

\*3 (E) CX=0

\*4 (E) CX =1

\*5 (E) CX &gt; 1

\*6 (E) CX &gt; 0

**Operation**

IF AddressSize = 16

THEN use CX for CountReg;

ELSE (\* AddressSize = 32 \*) use ECX for CountReg;

FI;

WHILE CountReg &lt;&gt; 0

DO

service pending interrupts (if any);

perform primitive string instruction;

CountReg ← CountReg – 1;

IF primitive operation is CMPSB, CMPSW, CMPSD, SCASB, SCASW, or SCASD

THEN

IF (instruction is REP/REPE/REPZ) AND (ZF=0)

THEN exit WHILE loop

ELSE

IF (instruction is REPNZ or REPNE) AND (ZF=1)

THEN exit WHILE loop;

FI;

FI;

FI;

OD;

**Description**

The REP, REPE (repeat while equal), and REPNE (repeat while not equal) prefixes are applied to string operation. Each prefix causes the string instruction that follows to be repeated the number of times indicated in the count register or (for the REPE and REPNE prefixes) until the indicated condition in the ZF flag is no longer met.

Synonymous forms of the REPE and REPNE prefixes are the REPZ and REPNZ prefixes, respectively.

The REP prefixes apply only to one string instruction at a time. To repeat a block of instructions, use the LOOP instruction or another looping construct.

The precise action for each iteration is as follows:

1. If the address-size attribute is 16 bits, use the CX register for the count register; if the address-size attribute is 32 bits, use the ECX register for the count register.
2. Check the count register. If it is zero, exit the iteration, and move to the next instruction.
3. Acknowledge any pending interrupts.
4. Perform the string operation once.
5. Decrement the CX or count register by one; no flags are modified.
6. Check the ZF flag if the string operation is a SCAS or CMPS instruction. If the repeat condition does not hold, exit the iteration and move to the next instruction. Exit the iteration if the prefix is REPE and the ZF flag is 0 (the last comparison was not equal), or if the prefix is REPNE and the ZF flag is one (the last comparison was equal).
7. Return to step 2 for the next iteration.

Repeated CMPS and SCAS instructions can be exited if the count is exhausted or if the ZF flag fails the repeat condition. These two cases can be distinguished by using either the JCXZ instruction, or by using the conditional jumps that test the ZF flag (the JZ, JNZ, and JNE instructions).

### Flags Affected

The ZF flag is affected by the REP CMPS and REP SCAS as described above.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

### Notes

Not all I/O ports can handle the rate at which the REP INS and REP OUTS instructions execute.

Do not use the REP prefix with the LOOP instruction. Proper LOOP operation is not guaranteed when used with the REP prefix and the effect of this combination is unpredictable.

The behavior of the REP prefix is undefined when used with non-string instructions.

When a page fault occurs during CMPS or SCAS instructions that are prefixed with REPNE, the EFLAGS value is restored to the state prior to the execution of the instruction. Since SCAS and CMPS do not use EFLAGS as an input, the processor can resume the instruction after the page fault handler.



## RET—Return from Procedure

Opcode	Instruction	Clocks	Description
C3	RET	2	Return (near) to caller
CB	RET	4	Return (far) to caller, same privilege
CB	RET	23	Return (far), lesser privilege, switch stacks
C2 <i>iw</i>	RET <i>imm16</i>	3	Return (near), pop <i>imm16</i> bytes of parameters
CA <i>iw</i>	RET <i>imm16</i>	4	Return (far), same privilege, pop <i>imm16</i> bytes
CA <i>iw</i>	RET <i>imm16</i>	23	Return (far), lesser privilege, pop <i>imm16</i> bytes

### Operation

IF instruction = near RET

THEN;

  IF OperandSize = 16

    THEN

      IP ← Pop();

      EIP ← EIP AND 0000FFFFH;

    ELSE (\* OperandSize = 32 \*)

      EIP ← Pop();

    FI;

  IF instruction has immediate operand THEN eSP ← eSP + imm16; FI;

FI;

IF (PE = 0 OR (PE = 1 AND VM = 1))

  (\* real mode or virtual 8086 mode \*)

  AND instruction = far RET

THEN;

  IF OperandSize = 16

    THEN

      IP ← Pop();

      EIP ← EIP AND 0000FFFFH;

      CS ← Pop(); (\* 16-bit pop \*)

    ELSE (\* OperandSize = 32 \*)

      EIP ← Pop();

      CS ← Pop(); (\* 32-bit pop, high-order 16-bits discarded \*)

    FI;

  IF instruction has immediate operand THEN eSP ← eSP + imm16; FI;

FI;

IF (PE = 1 AND VM = 0) (\* Protected mode, not V86 mode \*)

  AND instruction = far RET

THEN

  IF OperandSize=32

    THEN Third word on stack must be within stack limits else #SS(0);

    ELSE Second word on stack must be within stack limits else #SS(0);

  FI;

  Return selector RPL must be ≥ CPL ELSE #GP(return selector)

  IF return selector RPL = CPL

```

THEN GOTO SAME-LEVEL;
ELSE GOTO OUTER-PRIVILEGE-LEVEL;
FI;
FI;
SAME-LEVEL:
Return selector must be non-null ELSE #GP(0)
Selector index must be within its descriptor table limits ELSE
  #GP(selector)
Descriptor AR byte must indicate code segment ELSE #GP(selector)
IF non-conforming
THEN code segment DPL must equal CPL;
ELSE #GP(selector);
FI;
IF conforming
THEN code segment DPL must be ≤ CPL;
ELSE #GP(selector);
FI;
Code segment must be present ELSE #NP(selector);
Top word on stack must be within stack limits ELSE #SS(0);
IP must be in code segment limit ELSE #GP(0);
IF OperandSize=32
THEN
  Load CS:EIP from stack
  Load CS register with descriptor
  Increment eSP by 8 plus the immediate offset if it exists
ELSE (* OperandSize=16 *)
  Load CS:IP from stack
  Load CS register with descriptor
  Increment eSP by 4 plus the immediate offset if it exists
FI;
OUTER-PRIVILEGE-LEVEL:
IF OperandSize=32
THEN Top (16+immediate) bytes on stack must be within stack limits
  ELSE #SS(0);
ELSE Top (8+immediate) bytes on stack must be within stack limits ELSE
  #SS(0);
FI;
Examine return CS selector and associated descriptor:
  Selector must be non-null ELSE #GP(0);
  Selector index must be within its descriptor table limits ELSE
    #GP(selector)
  Descriptor AR byte must indicate code segment ELSE #GP(selector);
  IF non-conforming
  THEN code segment DPL must equal return selector RPL
  ELSE #GP(selector);
  FI;
  IF conforming

```

```
THEN code segment DPL must be ≤ return selector RPL;
ELSE #GP(selector);
FI;
Segment must be present ELSE #NP(selector)
Examine return SS selector and associated descriptor:
Selector must be non-null ELSE #GP(0);
Selector index must be within its descriptor table limits
ELSE #GP(selector);
Selector RPL must equal the RPL of the return CS selector ELSE
#GP(selector);
Descriptor AR byte must indicate a writable data segment ELSE
#GP(selector);
Descriptor DPL must equal the RPL of the return CS selector ELSE
#GP(selector);
Segment must be present ELSE #NP(selector);
IP must be in code segment limit ELSE #GP(0);
Set CPL to the RPL of the return CS selector;
IF OperandSize=32
THEN
    Load CS:EIP from stack;
    Set CS RPL to CPL;
    Increment eSP by 8 plus the immediate offset if it exists;
    Load SS:eSP from stack;
ELSE (* OperandSize=16 *)
    Load CS:IP from stack;
    Set CS RPL to CPL;
    Increment eSP by 4 plus the immediate offset if it exists;
    Load SS:eSP from stack;
FI;
Load the CS register with the return CS descriptor;
Load the SS register with the return SS descriptor;
For each of ES, FS, GS, and DS
DO
    IF the current register setting is not valid for the outer level,
        set the register to null (selector ← AR ← 0);
    To be valid, the register setting must satisfy the following properties:
        Selector index must be within descriptor table limits;
        Descriptor AR byte must indicate data or readable code segment;
        IF segment is data or non-conforming code, THEN
            DPL must be ≥ CPL, or DPL must be ≥ RPL;
    FI;
OD;
```

## Description

The RET instruction transfers control to a return address located on the stack. The address is usually placed on the stack by a CALL instruction, and the return is made to the instruction that follows the CALL instruction.

The optional numeric parameter to the RET instruction gives the number of stack bytes (OperandMode=16) or words (OperandMode=32) to be released after the return address is popped. These items are typically used as input parameters to the procedure called.

For the intrasegment (near) return, the address on the stack is a segment offset, which is popped into the instruction pointer. The CS register is unchanged. For the intersegment (far) return, the address on the stack is a long pointer. The offset is popped first, followed by the selector.

In real mode, the CS and IP registers are loaded directly. In Protected Mode, an intersegment return causes the processor to check the descriptor addressed by the return selector. The AR byte of the descriptor must indicate a code segment of equal or lesser privilege (or greater or equal numeric value) than the current privilege level. Returns to a lesser privilege level cause the stack to be reloaded from the value saved beyond the parameter block.

The DS, ES, FS, and GS segment registers can be cleared by the RET instruction during an interlevel transfer. If these registers refer to segments that cannot be used by the new privilege level, they are cleared to prevent unauthorized access from the new privilege level.

## Flags Affected

None.

## Protected Mode Exceptions

#GP, #NP, or #SS, as described under "Operation" above; #PF(fault-code) for a page fault.

## Real Address Mode Exceptions

Interrupt 13 if any part of the operand would be outside the effective address space from 0 to 0FFFFH.

## Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault.



## **ROL/ROR—Rotate**

See entry for RCL/RCR/ROL/ROR.

## RSM—Resume from System Management Mode

Opcode	Instruction	Clocks	Description
0F AA	RSM	83	Resume operation of interrupted program

### Operation

Resume operation of a program interrupted by a System Management Mode interrupt

### Description

The processor state is restored from the dump created upon entrance to SMM. Note, however, that the contents of the model-specific registers are not affected. The processor leaves SMM and returns control to the interrupted application or operating system. If the processor detects any invalid state information, it enters the shutdown state. This happens in any of the following situations:

- The value stored in the State Dump Base field is not a 32-Kbyte aligned address.
- Any reserved bit of CR4 is set to 1.
- Any combination of bits in CR0 is illegal; namely, (PG=1 and PE=0) or (NW=1 and CD=0).

### Flags Affected

All.

### Protected Mode Exceptions

#UD if an attempt is made to execute this instruction when the processor is not in System Management Mode.

### Real Address Mode Exceptions

#UD if an attempt is made to execute this instruction when the processor is not in System Management Mode.

### Virtual 8086 Mode Exceptions

#UD if an attempt is made to execute this instruction when the processor is not in System Management Mode.

### Notes

Please refer to Chapter 20 for more information about System Management Mode and the behavior of the RSM instruction.

## SAHF—Store AH into Flags

Opcode	Instruction	Clocks	Description
9E	SAHF	2	Store AH into flags SF ZF xx AF xx PF xx CF

### Operation

SF:ZF:xx:AF:xx:PF:xx:CF ← AH;

### Description

The SAHF instruction loads the SF, ZF, AF, PF, and CF flags with values from the AH register, from bits 7, 6, 4, 2, and 0, respectively.

### Flags Affected

The SF, ZF, AF, PF, and CF flags are loaded with values from the AH register.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

## SAL/SAR/SHL/SHR—Shift Instructions

Opcode	Instruction	Clocks	Description
D0 /4	SAL <i>r/m</i> ,1	1/3	Multiply <i>r/m</i> byte by 2, once
D2 /4	SAL <i>r/m</i> ,CL	4	Multiply <i>r/m</i> byte by 2, CL times
C0 /4 <i>ib</i>	SAL <i>r/m</i> , <i>imm</i> 8	1/3	Multiply <i>r/m</i> byte by 2, <i>imm</i> 8 times
D1 /4	SAL <i>r/m</i> 16,1	1/3	Multiply <i>r/m</i> word by 2, once
D3 /4	SAL <i>r/m</i> 16,CL	4	Multiply <i>r/m</i> word by 2, CL times
C1 /4 <i>ib</i>	SAL <i>r/m</i> 16, <i>imm</i> 8	1/3	Multiply <i>r/m</i> word by 2, <i>imm</i> 8 times
D1 /4	SAL <i>r/m</i> 32,1	1/3	Multiply <i>r/m</i> dword by 2, once
D3 /4	SAL <i>r/m</i> 32,CL	4	Multiply <i>r/m</i> dword by 2, CL times
C1 /4 <i>ib</i>	SAL <i>r/m</i> 32, <i>imm</i> 8	1/3	Multiply <i>r/m</i> dword by 2, <i>imm</i> 8 times
D0 /7	SAR <i>r/m</i> ,1	1/3	Signed divide <sup>1</sup> <i>r/m</i> byte by 2, once
D2 /7	SAR <i>r/m</i> ,CL	4	Signed divide <sup>1</sup> <i>r/m</i> byte by 2, CL times
C0 /7 <i>ib</i>	SAR <i>r/m</i> , <i>imm</i> 8	1/3	Signed divide <sup>1</sup> <i>r/m</i> byte by 2, <i>imm</i> 8 times
D1 /7	SAR <i>r/m</i> 16,1	1/3	Signed divide <sup>1</sup> <i>r/m</i> word by 2, once
D3 /7	SAR <i>r/m</i> 16,CL	4	Signed divide <sup>1</sup> <i>r/m</i> word by 2, CL times
C1 /7 <i>ib</i>	SAR <i>r/m</i> 16, <i>imm</i> 8	1/3	Signed divide <sup>1</sup> <i>r/m</i> word by 2, <i>imm</i> 8 times
D1 /7	SAR <i>r/m</i> 32,1	1/3	Signed divide <sup>1</sup> <i>r/m</i> dword by 2, once
D3 /7	SAR <i>r/m</i> 32,CL	4	Signed divide <sup>1</sup> <i>r/m</i> dword by 2, CL times
C1 /7 <i>ib</i>	SAR <i>r/m</i> 32, <i>imm</i> 8	1/3	Signed divide <sup>1</sup> <i>r/m</i> dword by 2, <i>imm</i> 8 times
D0 /4	SHL <i>r/m</i> ,1	1/3	Multiply <i>r/m</i> byte by 2, once
D2 /4	SHL <i>r/m</i> ,CL	4	Multiply <i>r/m</i> byte by 2, CL times
C0 /4 <i>ib</i>	SHL <i>r/m</i> , <i>imm</i> 8	1/3	Multiply <i>r/m</i> byte by 2, <i>imm</i> 8 times
D1 /4	SHL <i>r/m</i> 16,1	1/3	Multiply <i>r/m</i> word by 2, once
D3 /4	SHL <i>r/m</i> 16,CL	4	Multiply <i>r/m</i> word by 2, CL times
C1 /4 <i>ib</i>	SHL <i>r/m</i> 16, <i>imm</i> 8	1/3	Multiply <i>r/m</i> word by 2, <i>imm</i> 8 times
D1 /4	SHL <i>r/m</i> 32,1	1/3	Multiply <i>r/m</i> dword by 2, once
D3 /4	SHL <i>r/m</i> 32,CL	4	Multiply <i>r/m</i> dword by 2, CL times
C1 /4 <i>ib</i>	SHL <i>r/m</i> 32, <i>imm</i> 8	1/3	Multiply <i>r/m</i> dword by 2, <i>imm</i> 8 times
D0 /5	SHR <i>r/m</i> ,1	1/3	Unsigned divide <i>r/m</i> byte by 2, once
D2 /5	SHR <i>r/m</i> ,CL	4	Unsigned divide <i>r/m</i> byte by 2, CL times
C0 /5 <i>ib</i>	SHR <i>r/m</i> , <i>imm</i> 8	1/3	Unsigned divide <i>r/m</i> byte by 2, <i>imm</i> 8 times
D1 /5	SHR <i>r/m</i> 16,1	1/3	Unsigned divide <i>r/m</i> word by 2, once
D3 /5	SHR <i>r/m</i> 16,CL	4	Unsigned divide <i>r/m</i> word by 2, CL times
C1 /5 <i>ib</i>	SHR <i>r/m</i> 16, <i>imm</i> 8	1/3	Unsigned divide <i>r/m</i> word by 2, <i>imm</i> 8 times
D1 /5	SHR <i>r/m</i> 32,1	1/3	Unsigned divide <i>r/m</i> dword by 2, once
D3 /5	SHR <i>r/m</i> 32,CL	4	Unsigned divide <i>r/m</i> dword by 2, CL times
C1 /5 <i>ib</i>	SHR <i>r/m</i> 32, <i>imm</i> 8	1/3	Unsigned divide <i>r/m</i> dword by 2, <i>imm</i> 8 times

### NOTES:

<sup>1</sup>Not the same division as IDIV; rounding is toward negative infinity.

### Operation

(\* COUNT is the second parameter \*)

(temp) ← COUNT;

WHILE (temp <> 0)

DO

IF instruction is SAL or SHL

THEN CF ← high-order bit of *r/m*;

FI;

IF instruction is SAR or SHR

THEN CF ← low-order bit of *r/m*;

FI;

IF instruction = SAL or SHL

THEN *r/m* ← *r/m* \* 2;

FI;

```

IF instruction = SAR
THEN  $r/m \leftarrow r/m / 2$  (*Signed divide, rounding toward negative infinity*);
FI;
IF instruction = SHR
THEN  $r/m \leftarrow r/m / 2$ ; (* Unsigned divide *);
FI;
temp  $\leftarrow$  temp - 1;
OD;
* Determine overflow for the various instructions *)
IF COUNT = 1
THEN
  IF instruction is SAL or SHL
  THEN OF  $\leftarrow$  high-order bit of  $r/m$  <> (CF);
  FI;
  IF instruction is SAR
  THEN OF  $\leftarrow$  0;
  FI;
  IF instruction is SHR
  THEN OF  $\leftarrow$  high-order bit of operand;
  FI;
ELSE OF  $\leftarrow$  undefined;
FI;

```

## Description

The SAL instruction (or its synonym, SHL) shifts the bits of the operand upward. The high-order bit is shifted into the CF flag, and the low-order bit is cleared.

The SAR and SHR instructions shift the bits of the operand downward. The low-order bit is shifted into the CF flag. The effect is to divide the operand by two. The SAR instruction performs a signed divide with rounding toward negative infinity (not the same as the IDIV instruction); the high-order bit remains the same. The SHR instruction performs an unsigned divide; the high-order bit is cleared.

The shift is repeated the number of times indicated by the second operand, which is either an immediate number or the contents of the CL register. To reduce the maximum execution time, the Pentium processor does not allow shift counts greater than 31. If a shift count greater than 31 is attempted, only the bottom five bits of the shift count are used. (The 8086 uses all eight bits of the shift count.)

The OF flag is affected only if the single-shift forms of the instructions are used. For left shifts, the OF flag is cleared if the high bit of the answer is the same as the result of the CF flag (i.e., the top two bits of the original operand were the same); the OF flag is set if they are different. For the SAR instruction, the OF flag is cleared for all single shifts. For the SHR instruction, the OF flag is set to the high-order bit of the original operand.

### Flags Affected

If count = 0, the flags are not affected.

The CF flag contains the value of the last bit shifted out. The CF flag is undefined for SHL and SHR instructions in which the shift lengths are greater than or equal to the size of the operand to be shifted.

The OF flag is affected for single shifts; the OF flag is undefined for multiple shifts; the CF, ZF, PF, and SF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## SBB—Integer Subtraction with Borrow

Opcode	Instruction	Clocks	Description
1C <i>ib</i>	SBB AL, <i>imm8</i>	1	Subtract with borrow immediate byte from AL
1D <i>iw</i>	SBB AX, <i>imm16</i>	1	Subtract with borrow immediate word from AX
1D <i>id</i>	SBB EAX, <i>imm32</i>	1	Subtract with borrow immediate dword from EAX
80 /3 <i>ib</i>	SBB <i>r/m8</i> , <i>imm8</i>	1/3	Subtract with borrow immediate byte from <i>r/m</i> byte
81 /3 <i>iw</i>	SBB <i>r/m16</i> , <i>imm16</i>	1/3	Subtract with borrow immediate word from <i>r/m</i> word
81 /3 <i>id</i>	SBB <i>r/m32</i> , <i>imm32</i>	1/3	Subtract with borrow immediate dword from <i>r/m</i> dword
83 /3 <i>ib</i>	SBB <i>r/m16</i> , <i>imm8</i>	1/3	Subtract with borrow sign-extended immediate byte from <i>r/m</i> word
83 /3 <i>ib</i>	SBB <i>r/m32</i> , <i>imm8</i>	1/3	Subtract with borrow sign-extended immediate byte from <i>r/m</i> dword
18 / <i>r</i>	SBB <i>r/m8</i> , <i>r8</i>	1/3	Subtract with borrow byte register from <i>r/m</i> byte
19 / <i>r</i>	SBB <i>r/m16</i> , <i>r16</i>	1/3	Subtract with borrow word register from <i>r/m</i> word
19 / <i>r</i>	SBB <i>r/m32</i> , <i>r32</i>	1/3	Subtract with borrow dword register from <i>r/m</i> dword
1A / <i>r</i>	SBB <i>r8</i> , <i>r/m8</i>	1/2	Subtract with borrow <i>r/m</i> byte from byte register
1B / <i>r</i>	SBB <i>r16</i> , <i>r/m16</i>	1/2	Subtract with borrow <i>r/m</i> word from word register
1B / <i>r</i>	SBB <i>r32</i> , <i>r/m32</i>	1/2	Subtract with borrow <i>r/m</i> dword from dword register

### Operation

F SRC is a byte and DEST is a word or dword  
 THEN DEST = DEST – (SignExtend(SRC) + CF)  
 ELSE DEST ← DEST – (SRC + CF);

### Description

The SBB instruction adds the second operand (SRC) to the CF flag and subtracts the result from the first operand (DEST). The result of the subtraction is assigned to the first operand (DEST), and the flags are set accordingly.

When an immediate byte value is subtracted from a word operand, the immediate value is first sign-extended.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## SCAS/SCASB/SCASW/SCASD—Compare String Data

Opcode	Instruction	Clocks	Description
AE	SCAS <i>m8</i>	4	Compare bytes AL-ES:[(E)DI], update (E)DI
AF	SCAS <i>m16</i>	4	Compare words AX-ES:[(E)DI], update (E)DI
AF	SCAS <i>m32</i>	4	Compare dwords EAX-ES:[(E)DI], update (E)DI
AE	SCASB	4	Compare bytes AL-ES:[(E)DI], update (E)DI
AF	SCASW	4	Compare words AX-ES:[(E)DI], update (E)DI
AF	SCASD	4	Compare dwords EAX-ES:[(E)DI], update (E)DI

### Operation

```

IF AddressSize = 16
THEN use DI for dest-index;
ELSE (* AddressSize = 32 *) use EDI for dest-index;
FI;
IF byte type of instruction
THEN
  AL – [dest-index]; (* Compare byte in AL and dest *)
  IF DF = 0 THEN IncDec ← 1 ELSE IncDec ← -1; FI;
ELSE
  IF OperandSize = 16
  THEN
    AX – [dest-index]; (* compare word in AL and dest *)
    IF DF = 0 THEN IncDec ← 2 ELSE IncDec ← -2; FI;
  ELSE (* OperandSize = 32 *)
    EAX – [dest-index];(* compare dword in EAX and dest *)
    IF DF = 0 THEN IncDec ← 4 ELSE IncDec ← -4; FI;
  FI;
FI;
dest-index = dest-index + IncDec
  
```

### Description

The SCAS instruction subtracts the memory byte or word at the destination register from the AL, AX or EAX register. The result is discarded; only the flags are set. The operand must be addressable from the ES segment; no segment override is possible.

If the address-size attribute for this instruction is 16 bits, the DI register is used as the destination register; otherwise, the address-size attribute is 32 bits and the EDI register is used.

The address of the memory data being compared is determined solely by the contents of the destination register, not by the operand to the SCAS instruction. The operand validates ES segment addressability and determines the data type. Load the correct index value into the DI or EDI register before executing the SCAS instruction.

After the comparison is made, the destination register is automatically updated. If the direction flag is 0 (the CLD instruction was executed), the destination register is incremented; if the direction flag is 1 (the STD instruction was executed), it is decremented.

The increments or decrements are by 1 if bytes are compared, by 2 if words are compared, or by 4 if doublewords are compared.

The SCASB, SCASW, and SCASD instructions are synonyms for the byte, word and doubleword SCAS instructions that don't require operands. They are simpler to code, but provide no type or segment checking.

The SCAS instruction can be preceded by the REPE or REPNE prefix for a block search of CX or ECX bytes or words. Refer to the REP instruction for further details.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the ES segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## SETcc—Byte Set on Condition

Opcode	Instruction	Clocks	Description
0F 97	SETA <i>r/m8</i>	1/2	Set byte if above (CF=0 and ZF=0)
0F 93	SETAE <i>r/m8</i>	1/2	Set byte if above or equal (CF=0)
0F 92	SETB <i>r/m8</i>	1/2	Set byte if below (CF=1)
0F 96	SETBE <i>r/m8</i>	1/2	Set byte if below or equal (CF=1 or (ZF=1))
0F 92	SETC <i>r/m8</i>	1/2	Set if carry (CF=1)
0F 94	SETE <i>r/m8</i>	1/2	Set byte if equal (ZF=1)
0F 9F	SETG <i>r/m8</i>	1/2	Set byte if greater (ZF=0 and SF=OF)
0F 9D	SETGE <i>r/m8</i>	1/2	Set byte if greater or equal (SF=OF)
0F 9C	SETL <i>r/m8</i>	1/2	Set byte if less (SF<>OF)
0F 9E	SETLE <i>r/m8</i>	1/2	Set byte if less or equal (ZF=1 or SF<>OF)
0F 96	SETNA <i>r/m8</i>	1/2	Set byte if not above (CF=1 or ZF=1)
0F 92	SETNAE <i>r/m8</i>	1/2	Set byte if not above or equal (CF=1)
0F 93	SETNB <i>r/m8</i>	1/2	Set byte if not below (CF=0)
0F 97	SETNBE <i>r/m8</i>	1/2	Set byte if not below or equal (CF=0 and ZF=0)
0F 93	SETNC <i>r/m8</i>	1/2	Set byte if not carry (CF=0)
0F 95	SETNE <i>r/m8</i>	1/2	Set byte if not equal (ZF=0)
0F 9E	SETNG <i>r/m8</i>	1/2	Set byte if not greater (ZF=1 or SF<>OF)
0F 9C	SETNGE <i>r/m8</i>	1/2	Set if not greater or equal (SF<>OF)
0F 9D	SETNL <i>r/m8</i>	1/2	Set byte if not less (SF=OF)
0F 9F	SETNLE <i>r/m8</i>	1/2	Set byte if not less or equal (ZF=0 and SF=OF)
0F 91	SETNO <i>r/m8</i>	1/2	Set byte if not overflow (OF=0)
0F 9B	SETNP <i>r/m8</i>	1/2	Set byte if not parity (PF=0)
0F 99	SETNS <i>r/m8</i>	1/2	Set byte if not sign (SF=0)
0F 95	SETNZ <i>r/m8</i>	1/2	Set byte if not zero (ZF=0)
0F 90	SETO <i>r/m8</i>	1/2	Set byte if overflow (OF=1)
0F 9A	SETP <i>r/m8</i>	1/2	Set byte if parity (PF=1)
0F 9A	SETPE <i>r/m8</i>	1/2	Set byte if parity even (PF=1)
0F 9B	SETPO <i>r/m8</i>	1/2	Set byte if parity odd (PF=0)
0F 98	SETS <i>r/m8</i>	1/2	Set byte if sign (SF=1)
0F 94	SETZ <i>r/m8</i>	1/2	Set byte if zero (ZF=1)

### Operation

IF condition THEN *r/m8* ← 1 ELSE *r/m8* ← 0; FI;

### Description

The SETcc instruction stores a 1 byte at the destination specified by the effective address or register if the condition is met, or a 0 byte if the condition is not met.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a non-writable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### **Real Address Mode Exceptions**

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault.



## SGDT/SIDT—Store Global/Interrupt Descriptor Table Register

Opcode	Instruction	Clocks	Description
0F 01 /0	SGDT <i>m</i>	4	Store GDTR to <i>m</i>
0F 01 /1	SIDT <i>m</i>	4	Store IDTR to <i>m</i>

### Operation

DEST ← 48-bit BASE/LIMIT register contents;

### Description

The SGDT and SIDT instructions copy the contents of the descriptor table register to the six bytes of memory indicated by the operand. The LIMIT field of the register is assigned to the first word at the effective address. If the operand-size attribute is 16 bits, the next three bytes are assigned the BASE field of the register, and the fourth byte is undefined. Otherwise, if the operand-size attribute is 32 bits, the next four bytes are assigned the 32-bit BASE field of the register.

The SGDT and SIDT instructions are used only in operating system software; they are not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

Interrupt 6 if the destination operand is a register; #GP(0) if the destination is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6 if the destination operand is a register; Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Compatibility Note**

The 16-bit forms of the SGDT and SIDT instructions are compatible with the Intel 286 processor, if the value in the upper eight bits is not referenced. The Intel 286 processor stores 1's in these upper bits, whereas the 32-bit processors store 0's if the operand-size attribute is 16 bits. These bits were specified as undefined by the SGDT and SIDT instructions in the *80286 Programming Reference Manual* (Order No. 210498).



## **SHL/SHR—Shift Instructions**

See entry for *SAL/SAR/SHL/SHR*.

## SHLD—Double Precision Shift Left

Opcode	Instruction	Clocks	Description
0F A4	SHLD <i>r/m16,r16,imm8</i>	4	<i>r/m16</i> gets SHL of <i>r/m16</i> concatenated with <i>r16</i>
0F A4	SHLD <i>r/m32,r32,imm8</i>	4	<i>r/m32</i> gets SHL of <i>r/m32</i> concatenated with <i>r32</i>
0F A5	SHLD <i>r/m16,r16,CL</i>	4/5	<i>r/m16</i> gets SHL of <i>r/m16</i> concatenated with <i>r16</i>
0F A5	SHLD <i>r/m32,r32,CL</i>	4/5	<i>r/m32</i> gets SHL of <i>r/m32</i> concatenated with <i>r32</i>

### Operation

(\* count is an unsigned integer corresponding to the last operand of the instruction, either an immediate byte or the byte in register CL \*)

ShiftAmt ← count MOD 32;

inBits ← register; (\* Allow overlapped operands \*)

IF ShiftAmt = 0

THEN no operation

ELSE

IF ShiftAmt ≥ OperandSize

THEN (\* Bad parameters \*)

*r/m* ← UNDEFINED;

CF, OF, SF, ZF, AF, PF ← UNDEFINED;

ELSE (\* Perform the shift \*)

CF ← BIT[Base, OperandSize – ShiftAmt];

(\* Last bit shifted out on exit \*)

FOR i ← OperandSize – 1 DOWNTO ShiftAmt

DO

BIT[Base, i] ← BIT[Base, i – ShiftAmt];

OF;

FOR i ← ShiftAmt – 1 DOWNTO 0

DO

BIT[Base, i] ← BIT[inBits, i – ShiftAmt + OperandSize];

OD;

Set SF, ZF, PF (*r/m*);

(\* SF, ZF, PF are set according to the value of the result \*)

AF ← UNDEFINED;

FI;

FI;

### Description

The SHLD instruction shifts the first operand provided by the *r/m* field to the left as many bits as specified by the count operand. The second operand (**r16** or **r32**) provides the bits to shift in from the right (starting with bit 0). The result is stored back into the *r/m* operand. The register remains unaltered.

The count operand is provided by either an immediate byte or the contents of the CL register. These operands are taken MODULO 32 to provide a number between 0 and 31 by which to shift. Because the bits to shift are provided by the specified registers, the operation is useful for multiprecision shifts (64 bits or more). The SF, ZF and PF flags are set according to the value of the result. The CF flag is set to the value of the last bit shifted out. The OF and AF flags are left undefined.

### Flags Affected

If count = 0, the flags are not affected.

The SF, ZF, and PF, flags are set according to the result; the CF flag is set to the value of the last bit shifted out; after a shift of one bit position, the OF flag is set if a sign change occurred, otherwise it is cleared; after a shift of more than one bit position, the OF flag is undefined; the AF flag is undefined, except for a shift count of zero, which does not affect any flags.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## SHRD—Double Precision Shift Right

Opcode	Instruction	Clocks	Description
OF AC	SHRD <i>r/m16,r16,imm8</i>	4	<i>r/m16</i> gets SHR of <i>r/m16</i> concatenated with <i>r16</i>
OF AC	SHRD <i>r/m32,r32,imm8</i>	4	<i>r/m32</i> gets SHR of <i>r/m32</i> concatenated with <i>r32</i>
OF AD	SHRD <i>r/m16,r16,CL</i>	4/5	<i>r/m16</i> gets SHR of <i>r/m16</i> concatenated with <i>r16</i>
OF AD	SHRD <i>r/m32,r32,CL</i>	4/5	<i>r/m32</i> gets SHR of <i>r/m32</i> concatenated with <i>r32</i>

### Operation

(\* count is an unsigned integer corresponding to the last operand of the instruction, either an immediate byte or the byte in register CL \*)

ShiftAmt ← count MOD 32;

inBits ← register; (\* Allow overlapped operands \*)

IF ShiftAmt = 0

THEN no operation

ELSE

IF ShiftAmt ≥ OperandSize

THEN (\* Bad parameters \*)

*r/m* ← UNDEFINED;

CF, OF, SF, ZF, AF, PF ← UNDEFINED;

ELSE (\* Perform the shift \*)

CF ← BIT[*r/m*, ShiftAmt – 1]; (\* last bit shifted out on exit \*)

FOR i ← 0 TO OperandSize – 1 – ShiftAmt

DO

BIT[*r/m*, i] ← BIT[*r/m*, i – ShiftAmt];

OD;

FOR i ← OperandSize – ShiftAmt TO OperandSize–1

DO

BIT[*r/m*,i] ← BIT[inBits,i+ShiftAmt – OperandSize];

OD;

(\* SF, ZF, PF are set according to the value of the result \*)

Set SF, ZF, PF (*r/m*);

AF ← UNDEFINED;

FI;

FI;

### Description

The SHRD instruction shifts the first operand provided by the *r/m* field to the right as many bits as specified by the count operand. The second operand (*r16* or *r32*) provides the bits to shift in from the left (starting with bit 31). The result is stored back into the *r/m* operand. The register remains unaltered.

The count operand is provided by either an immediate byte or the contents of the CL register. These operands are taken MODULO 32 to provide a number between 0 and 31 by which to shift. Because the bits to shift are provided by the specified register, the operation is useful for multi-precision shifts (64 bits or more). The SF, ZF and PF flags are set according to the

value of the result. The CF flag is set to the value of the last bit shifted out. The OF and AF flags are left undefined.

### Flags Affected

If count = 0, the flags are not affected.

The SF, ZF, and PF flags are set according to the result; the CF flag is set to the value of the last bit shifted out; after a shift of one bit position, the OF flag is set if a sign change occurred, otherwise it is cleared; after a shift of more than one bit position, the OF flag is undefined; the AF flag is undefined, except for a shift count of zero, which does not affect any flags.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #AC for unaligned memory reference if the current privilege level is 3.

## **SIDT—Store Interrupt Descriptor Table Register**

See entry for SGDT/SIDT.

## SLDT—Store Local Descriptor Table Register

Opcode	Instruction	Clocks	Description
0F 00 /0	SLDT <i>r/m16</i>	2	Store LDTR to EA word
0F 00 /0	SLDT <i>r/m32</i>	2	Store LDTR to low 16 bits of <i>r/m32</i> High 16 bits are undefined

### Operation

*r/m16* ← LDTR;

### Description

The SLDT instruction stores the Local Descriptor Table Register (LDTR) in the two-byte register or memory location indicated by the effective address operand. This register is a selector that points into the Global Descriptor Table.

The SLDT instruction is used only in operating system software. It is not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6; the SLDT instruction is not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode (because the instruction is not recognized, it will not execute or perform a memory reference).

### Notes

When the destination is a 32-bit register, the 16-bit source operand is copied into the lower 16 bits of the destination register, and the upper 16 bits of the register are undefined. With a 16-bit register operand, only the lower 16 bits of the destination are affected (the upper 16 bits remain unchanged). With a memory operand, the source is written to memory as a 16-bit

quantity, regardless of operand size. As a result, 32-bit software should always treat the destination as 16-bits and mask bits 16-31, if necessary.



## SMSW—Store Machine Status Word

Opcode	Instruction	Clocks	Description
0F 01 /4	SMSW <i>r/m16</i>	4	Store machine status word to EA word

### Operation

*r/m16* ← MSW;

### Description

The SMSW instruction stores the machine status word (part of the CR0 register) in the two-byte register or memory location indicated by the effective address operand.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

This instruction is provided for compatibility with the Intel 286 processor; programs for the Pentium processor should use the MOV ..., CR0 instruction.

When the destination is a 32-bit register, the 16-bit source operand is copied into the lower 16 bits of the destination register, and the upper 16 bits of the register are undefined. With a 16-bit register operand, only the lower 16 bits of the destination are affected (the upper 16 bits remain unchanged). With a memory operand, the source is written to memory as a 16-bit quantity, regardless of operand size. As a result, 32-bit software should always treat the destination as 16-bits and mask bits 16-31, if necessary.

## STC—Set Carry Flag

Opcode	Instruction	Clocks	Description
F9	STC	2	Set carry flag

### Operation

$CF \leftarrow 1$ ;

### Description

The STC instruction sets the CF flag.

### Flags Affected

The CF flag is set.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.



## STD—Set Direction Flag

Opcode	Instruction	Clocks	Description
FD	STD	2	Set direction flag so (E)SI and/or (E)DI decrement

### Operation

DF ← 1;

### Description

The STD instruction sets the direction flag, causing all subsequent string operations to decrement the index registers, (E)SI and/or (E)DI, on which they operate.

### Flags Affected

The DF flag is set.

### Protected Mode Exceptions

None.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

None.

## STI—Set Interrupt Flag

Opcode	Instruction	Clocks	Description
FB	STI	7	Set interrupt flag; interrupts enabled at the end of the next instruction

### Operation

```

IF PE=0 (* Executing in real-address mode *)
THEN
  IF ← 1; (* Set Interrupt Flag *)
ELSE (* Executing in protected mode or virtual-8086 mode *)
  IF VM=0 (* Executing in protected mode*)
  THEN
    IF IOPL=3
    THEN IF ← 1; (* Set Interrupt Flag *)
    ELSE IF CPL ≤ IOPL
    THEN IF ← 1;
    ELSE #GP(0);
    FI;
  FI;
  ELSE (* Executing in Virtual-8086 mode *)
    #GP(0); (* Trap to virtual-8086 monitor *)
  FI;
FI;

```

### Decision Table

The following decision table indicates which action in the lower portion of the table is taken given the conditions in the upper portion of the table.

PE =	0	1	1	1
VM =	–	0	0	1
CPL	–	≤ IOPL	> IOPL	=3
IOPL	–	–	–	=3
IF ← 1	Y	Y		Y
#GP(0)			Y	

#### NOTES:

- Don't care
- Blank Action not taken
- Y Action in Column 1 taken



**Description**

The STI instruction sets the IF. The processor then responds to external interrupts after executing the next instruction if the next instruction allows the IF flag to remain enabled. If external interrupts are disabled and the STI instruction is followed by the RET instruction (such as at the end of a subroutine), the RET instruction is allowed to execute before external interrupts are recognized. Also, if external interrupts are disabled and the STI instruction is followed by a CLI instruction which clears the IF flag, then external interrupts are not recognized because the CLI instruction clears the IF flag during its execution.

**Flags Affected**

The IF flag is set.

**Protected Mode Exceptions**

#GP(0) if the current privilege level is greater (has less privilege) than the I/O privilege level.

**Real Address Mode Exceptions**

None.

**Virtual 8086 Mode Exceptions**

#GP(0) as for protected mode.

**Notes**

In case of an NMI, trap, or fault following STI the interrupt will be taken before executing the next sequential instruction in the code.

For information on this instruction when using virtual mode extensions, see Appendix H.

## STOS/STOSB/STOSW/STOSD—Store String Data

Opcode	Instruction	Clocks	Description
AA	STOS <i>m8</i>	3	Store AL in byte ES:[(E)DI], update (E)DI
AB	STOS <i>m16</i>	3	Store AX in word ES:[(E)DI], update (E)DI
AB	STOS <i>m32</i>	3	Store EAX in dword ES:[(E)DI], update (E)DI
AA	STOSB	3	Store AL in byte ES:[(E)DI], update (E)DI
AB	STOSW	3	Store AX in word ES:[(E)DI], update (E)DI
AB	STOSD	3	Store EAX in dword ES:[(E)DI], update (E)DI

### Operation

```

IF AddressSize = 16
THEN use ES:DI for DestReg
ELSE (* AddressSize = 32 *) use ES:EDI for DestReg;
FI;
IF byte type of instruction
THEN
  (ES:DestReg) ← AL;
  IF DF = 0
  THEN DestReg ← DestReg + 1;
  ELSE DestReg ← DestReg – 1;
  FI;
ELSE IF OperandSize = 16
  THEN
    (ES:DestReg) ← AX;
    IF DF = 0
    THEN DestReg ← DestReg + 2;
    ELSE DestReg ← DestReg – 2;
    FI;
  ELSE (* OperandSize = 32 *)
    (ES:DestReg) ← EAX;
    IF DF = 0
    THEN DestReg ← DestReg + 4;
    ELSE DestReg ← DestReg – 4;
    FI;
  FI;
FI;

```

### Description

The STOS instruction transfers the contents of the AL, AX, or EAX register to the memory byte or word given by the destination register relative to the ES segment. The destination register is the DI register for an address-size attribute of 16 bits or the EDI register for an address-size attribute of 32 bits.

The destination operand must be addressable from the ES register. A segment override is not possible.



The address of the destination is determined by the contents of the destination register, not by the explicit operand of the STOS instruction. This operand is used only to validate ES segment addressability and to determine the data type. Load the correct index value into the destination register before executing the STOS instruction.

After the transfer is made, the (E)DI register is automatically updated. If the DF flag is 0 (the CLD instruction was executed), the (E)DI register is incremented; if the DF flag is 1 (the STD instruction was executed), the (E)DI register is decremented. The (E)DI register is incremented or decremented by 1 if a byte is stored, by 2 if a word is stored, or by 4 if a doubleword is stored.

The STOSB, STOSW, and STOSD instructions are synonyms for the byte, word, and doubleword STOS instructions, that do not require an operand. They are simpler to use, but provide no type or segment checking.

The STOS instruction can be preceded by the REP prefix for a block fill of CX or ECX bytes, words, or doublewords. Refer to the REP instruction for further details.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the ES segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## STR—Store Task Register

Opcode	Instruction	Clocks	Description
0F 00 /1	STR <i>r/m16</i>	2	Store task register to EA word

### Operation

*r/m* ← task register;

### Description

The contents of the task register are copied to the two-byte register or memory location indicated by the effective address operand.

The STR instruction is used only in operating system software. It is not used in application programs.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6; the STR instruction is not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode.

### Notes

When the destination is a 32-bit register, the 16-bit source operand is copied into the lower 16 bits of the destination register, and the upper 16 bits of the register are undefined. With a 16-bit register operand, only the lower 16 bits of the destination are affected (the upper 16 bits remain unchanged). With a memory operand, the source is written to memory as a 16-bit quantity, regardless of operand size. As a result, 32-bit software should always treat the destination as 16-bits and mask bits 16-31, if necessary.



## SUB—Integer Subtraction

Opcode	Instruction	Clocks	Description
2C <i>ib</i>	SUB AL, <i>imm8</i>	1	Subtract immediate byte from AL
2D <i>iw</i>	SUB AX, <i>imm16</i>	1	Subtract immediate word from AX
2D <i>id</i>	SUB EAX, <i>imm32</i>	1	Subtract immediate dword from EAX
80 <i>/5 ib</i>	SUB <i>r/m8</i> , <i>imm8</i>	1/3	Subtract immediate byte from <i>r/m</i> byte
81 <i>/5 iw</i>	SUB <i>r/m16</i> , <i>imm16</i>	1/3	Subtract immediate word from <i>r/m</i> word
81 <i>/5 id</i>	SUB <i>r/m32</i> , <i>imm32</i>	1/3	Subtract immediate dword from <i>r/m</i> dword
83 <i>/5 ib</i>	SUB <i>r/m16</i> , <i>imm8</i>	1/3	Subtract sign-extended immediate byte from <i>r/m</i> word
83 <i>/5 ib</i>	SUB <i>r/m32</i> , <i>imm8</i>	1/3	Subtract sign-extended immediate byte from <i>r/m</i> dword
28 <i>/r</i>	SUB <i>r/m8</i> , <i>r8</i>	1/3	Subtract byte register from <i>r/m</i> byte
29 <i>/r</i>	SUB <i>r/m16</i> , <i>r16</i>	1/3	Subtract word register from <i>r/m</i> word
29 <i>/r</i>	SUB <i>r/m32</i> , <i>r32</i>	1/3	Subtract dword register from <i>r/m</i> dword
2A <i>/r</i>	SUB <i>r8</i> , <i>r/m8</i>	1/2	Subtract <i>r/m</i> byte from byte register
2B <i>/r</i>	SUB <i>r16</i> , <i>r/m16</i>	1/2	Subtract <i>r/m</i> word from word register
2B <i>/r</i>	SUB <i>r32</i> , <i>r/m32</i>	1/2	Subtract <i>r/m</i> dword from dword register

### Operation

IF SRC is a byte and DEST is a word or dword  
 THEN DEST = DEST – SignExtend(SRC);  
 ELSE DEST ← DEST – SRC;  
 FI;

### Description

The SUB instruction subtracts the second operand (SRC) from the first operand (DEST). The first operand is assigned the result of the subtraction, and the flags are set accordingly.

When an immediate byte value is subtracted from a word operand, the immediate value is first sign-extended to the size of the destination operand.

### Flags Affected

The OF, SF, ZF, AF, PF, and CF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## TEST—Logical Compare

Opcode	Instruction	Clocks	Description
A8 <i>ib</i>	TEST AL, <i>imm8</i>	1	AND immediate byte with AL
A9 <i>iw</i>	TEST AX, <i>imm16</i>	1	AND immediate word with AX
A9 <i>id</i>	TEST EAX, <i>imm32</i>	1	AND immediate dword with EAX
F6 /0 <i>ib</i>	TEST <i>r/m8</i> , <i>imm8</i>	1/2	AND immediate byte with <i>r/m</i> byte
F7 /0 <i>iw</i>	TEST <i>r/m16</i> , <i>imm16</i>	1/2	AND immediate word with <i>r/m</i> word
F7 /0 <i>id</i>	TEST <i>r/m32</i> , <i>imm32</i>	1/2	AND immediate dword with <i>r/m</i> dword
84 <i>rb</i>	TEST <i>r/m8</i> , <i>rb</i>	1/2	AND byte register with <i>r/m</i> byte
85 <i>rw</i>	TEST <i>r/m16</i> , <i>r16</i>	1/2	AND word register with <i>r/m</i> word
85 <i>rd</i>	TEST <i>r/m32</i> , <i>r32</i>	1/2	AND dword register with <i>r/m</i> dword

### Operation

DEST := LeftSRC AND RightSRC;

CF ← 0;

OF ← 0;

### Description

The TEST instruction computes the bit-wise logical AND of its two operands. Each bit of the result is 1 if both of the corresponding bits of the operands are 1; otherwise, each bit is 0. The result of the operation is discarded and only the flags are modified.

### Flags Affected

The OF and CF flags are cleared; the SF, ZF, and PF flags are set according to the result.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

## VERR, VERW—Verify a Segment for Reading or Writing

Opcode	Instruction	Clocks	Description
0F 00 /4	VERR <i>r/m16</i>	7	Set ZF=1 if segment can be read, selector in <i>r/m16</i>
0F 00 /5	VERW <i>r/m16</i>	7	Set ZF=1 if segment can be written, selector in <i>r/m16</i>

### Operation

IF segment with selector at (*r/m*) is accessible  
with current protection level

AND ((segment is readable for VERR) OR  
(segment is writable for VERW))

THEN ZF ← 1;

ELSE ZF ← 0;

FI;

### Description

The two-byte register or memory operand of the VERR and VERW instructions contains the value of a selector. The VERR and VERW instructions determine whether the segment denoted by the selector is reachable from the current privilege level and whether the segment is readable (VERR) or writable (VERW). If the segment is accessible, the ZF flag is set; if the segment is not accessible, the ZF flag is cleared. To set the ZF flag, the following conditions must be met:

- The selector must denote a descriptor within the bounds of the table (GDT or LDT); the selector must be "defined."
- The selector must denote the descriptor of a code or data segment (not that of a task state segment, LDT, or a gate).
- For the VERR instruction, the segment must be readable. For the VERW instruction, the segment must be a writable data segment.
- If the code segment is readable and conforming, the descriptor privilege level (DPL) can be any value for the VERR instruction. Otherwise, the DPL must be greater than or equal to (have less or the same privilege as) both the current privilege level and the selector's RPL.

The validation performed is the same as if the segment were loaded into the DS, ES, FS, or GS register, and the indicated access (read or write) were performed. The ZF flag receives the result of the validation. The selector's value cannot result in a protection exception, enabling the software to anticipate possible segment access problems.

### Flags Affected

The ZF flag is set if the segment is accessible, cleared if it is not.



### Protected Mode Exceptions

Faults generated by illegal addressing of the memory operand that contains the selector; the selector is not loaded into any segment register, and no faults attributable to the selector operand are generated.

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 6; the VERR and VERW instructions are not recognized in Real Address Mode.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #AC for unaligned memory reference if the current privilege level is 3.

**WAIT—Wait**

Opcode	Instruction	Clocks	Description
9B	WAIT	1	Causes processor to check for numeric exceptions.

**Description**

WAIT causes the processor to check for pending unmasked numeric exceptions before proceeding.

**Flags Affected**

None.

**Protected Mode Exceptions**

#NM if both MP and TS in CR0 are set.

**Real Address Mode Exceptions**

Interrupt 7 if both MP and TS in CR0 are set.

**Virtual 8086 Mode Exceptions**

#NM if both MP and TS in CR0 are set.

**Notes**

Coding WAIT after an ESC instruction ensures that any unmasked floating-point exceptions the instruction may cause are handled before the processor has a chance to modify the instruction's results.

FWAIT is an alternate mnemonic for WAIT.

Information about when to use WAIT (FWAIT) is given in Chapter 6, in the section on "Concurrent Processing."



## WBINVD—Write-Back and Invalidate Cache

Opcode	Instruction	Clocks	Description
0F 09	WBINVD	2000+	Write-Back and Invalidate Entire Cache

### Operation

FLUSH INTERNAL CACHE  
 SIGNAL EXTERNAL CACHE TO WRITE-BACK  
 SIGNAL EXTERNAL CACHE TO FLUSH

### Description

The internal cache is flushed, and a special-function bus cycle is issued which indicates that external cache should write-back its contents to main memory. Another special-function bus cycle follows, directing the external cache to flush itself.

### Flags Affected

None.

### Protected Mode Exceptions

The WBINVD instruction is a privileged instruction; #GP(0) if the current privilege level is not 0.

### Real Address Mode Exceptions

None.

### Virtual 8086 Mode Exceptions

#GP(0); the WBINVD instruction is a privileged instruction.

### Notes

INVD should be used with care. It does not writeback modified cache lines; therefore, it can cause the data cache to become inconsistent with other memories in the system. Unless there is a specific requirement or benefit to invalidate a cache without writing back the modified lines (i.e., testing or fault recovery where cache coherency with main memory is not a concern), software should use the WBINVD instruction.

This instruction is implementation-dependent; its function may be implemented differently on future Intel processors.

It is the responsibility of hardware to respond to the external cache write-back and flush indications.

This instruction is not supported on Intel386 processors. See Chapter 16 for detecting processor type at runtime. See Chapter 18 on disabling the cache.



## WRMSR—Write to Model Specific Register

Opcode	Instruction	Clocks	Description
0F 30	WRMSR	30-45	Write the value in EDX:EAX to Model Specific Register indicated by ECX

### Operation

MSR[ECX] ← EDX:EAX;

### Description

The value in ECX specifies one of the 64-bit Model Specific Registers of the Pentium processor. The contents of EDX:EAX is copied into that Model-Specific Register. The high-order 32 bits are copied from EDX and the low-order 32 bits are copied from EAX.

The following values are used to select model specific registers on the Pentium processor:

Value (in Hex)	Register Name	Description
00H	Machine Check Address	Stores address of cycle causing the exception
01H	Machine Check Type	Stores cycle type of cycle causing the exception

For other values used to perform cache, TLB, and BTB testing and performance monitoring, see *Pentium® Processor User's Developers' Chapter 33*.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if either the current privilege level is not 0 or the value in ECX does not specify a Model-Specific Register that is implemented in the Pentium processor.

### Real Address Mode Exceptions

#GP(0) if the value in ECX does not specify a Model-Specific Register that is implemented in the Pentium processor. No error code is pushed.

### Virtual 8086 Mode Exceptions

#GP(0) if instruction execution is attempted.

## Notes

Always set undefined or reserved bits to the value previously read.

**The CPUID instruction should be used to determine whether Pentium processor-style model specific registers are supported (EDX[5] = 1) before using this instruction. A general protection exception will occur if this feature is not supported.**

WRMSR is used to write the content of Model-Specific Registers that control functions for testability, execution tracing, performance monitoring, and machine check errors. Refer to the *Pentium® Processor Data Book* for more information.

The values 3H, 0FH, and values above 13H are reserved. Do not execute WRMSR with reserved values in ECX.



## XADD—Exchange and Add

Opcode	Instruction	Clocks	Description
0F C0/r	XADD <i>r/m8,r8</i>	3/4	Exchange byte register and <i>r/m</i> byte; load sum into <i>r/m</i> byte.
0F C1/r	XADD <i>r/m16,r16</i>	3/4	Exchange word register and <i>r/m</i> word; load sum into <i>r/m</i> word.
0F C1/r	XADD <i>r/m32,r32</i>	3/4	Exchange dword register and <i>r/m</i> dword; load sum into <i>r/m</i> dword.

### Operation

TEMP ← SRC + DEST  
 SRC ← DEST  
 DEST ← TEMP

### Description

The XADD instruction loads DEST into SRC, and then loads the sum of DEST and the original value of SRC into DEST.

### Flags Affected

The CF, PF, AF, SF, ZF, and OF flags are affected as if an ADD instruction had been executed.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #NM if either EM or TS in CR0 is set; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in real-address mode; #PF(fault code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Notes

This instruction can be used with a LOCK prefix. The Intel386 DX microprocessor does not implement this instruction. If this instruction is used, you should provide an equivalent code

sequence that runs on an Intel386 DX processor as well. See Section Chapter 9 for detecting a Pentium processor at run time.



## XCHG—Exchange Register/Memory with Register

Opcode	Instruction	Clocks	Description
90+rw	XCHG AX,r16	2	Exchange word register with AX
90+rw	XCHG r16,AX	2	Exchange word register with AX
90+rd	XCHG EAX,r32	2	Exchange dword register with EAX
90+rd	XCHG r32,EAX	2	Exchange dword register with EAX
86 /r	XCHG r/m8,r8	3	Exchange byte register with EA byte
86 /r	XCHG r8,r/m8	3	Exchange byte register with EA byte
87 /r	XCHG r/m16,r16	3	Exchange word register with EA word
87 /r	XCHG r16,r/m16	3	Exchange word register with EA word
87 /r	XCHG r/m32,r32	3	Exchange dword register with EA dword
87 /r	XCHG r32,r/m32	3	Exchange dword register with EA dword

### Operation

temp ← DEST

DEST ← SRC

SRC ← temp

### Description

The XCHG instruction exchanges two operands. The operands can be in either order. If a memory operand is involved, the LOCK# signal is asserted for the duration of the exchange, regardless of the presence or absence of the LOCK prefix or of the value of the IOPL.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) if either operand is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### Virtual 8086 Mode Exceptions

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

**Note**

XCHG can be used for BSWAP for 16-bit data.



## XLAT/XLATB—Table Look-up Translation

Opcode	Instruction	Clocks	Description
D7	XLAT <i>mB</i>	4	Set AL to memory byte DS:((E)BX + unsigned AL]
D7	XLATB	4	Set AL to memory byte DS:((E)BX + unsigned AL]

### Operation

IF AddressSize = 16

THEN

AL ← (BX + ZeroExtend(AL))

ELSE (\* AddressSize = 32 \*)

AL ← (EBX + ZeroExtend(AL));

FI;

### Description

The XLAT instruction changes the AL register from the table index to the table entry. The AL register should be the unsigned index into a table addressed by the DS:BX register pair (for an address-size attribute of 16 bits) or the DS:EBX register pair (for an address-size attribute of 32 bits).

The operand to the XLAT instruction allows for the possibility of a segment override. The XLAT instruction uses the contents of the BX register even if they differ from the offset of the operand. The offset of the operand should have been moved into the BX or EBX register with a previous instruction.

The no-operand form, the XLATB instruction, can be used if the BX or EBX table will always reside in the DS segment.

### Flags Affected

None.

### Protected Mode Exceptions

#GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

### **Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.



## XOR—Logical Exclusive OR

Opcode	Instruction	Clocks	Description
34 <i>ib</i>	XOR AL, <i>imm8</i>	1	Exclusive-OR immediate byte to AL
35 <i>iw</i>	XOR AX, <i>imm16</i>	1	Exclusive-OR immediate word to AX
35 <i>id</i>	XOR EAX, <i>imm32</i>	1	Exclusive-OR immediate dword to EAX
80 /6 <i>ib</i>	XOR <i>r/m8</i> , <i>imm8</i>	1/3	Exclusive-OR immediate byte to <i>r/m</i> byte
81 /6 <i>iw</i>	XOR <i>r/m16</i> , <i>imm16</i>	1/3	Exclusive-OR immediate word to <i>r/m</i> word
81 /6 <i>id</i>	XOR <i>r/m32</i> , <i>imm32</i>	1/3	Exclusive-OR immediate dword to <i>r/m</i> dword
83 /6 <i>ib</i>	XOR <i>r/m16</i> , <i>imm8</i>	1/3	XOR sign-extended immediate byte with <i>r/m</i> word
83 /6 <i>ib</i>	XOR <i>r/m32</i> , <i>imm8</i>	1/3	XOR sign-extended immediate byte with <i>r/m</i> dword
30 /r	XOR <i>r/m8</i> , <i>r8</i>	1/3	Exclusive-OR byte register to <i>r/m</i> byte
31 /r	XOR <i>r/m16</i> , <i>r16</i>	1/3	Exclusive-OR word register to <i>r/m</i> word
31 /r	XOR <i>r/m32</i> , <i>r32</i>	1/3	Exclusive-OR dword register to <i>r/m</i> dword
32 /r	XOR <i>r8</i> , <i>r/m8</i>	1/2	Exclusive-OR byte register to <i>r/m</i> byte
33 /r	XOR <i>r16</i> , <i>r/m16</i>	1/2	Exclusive-OR word register to <i>r/m</i> word
33 /r	XOR <i>r32</i> , <i>r/m32</i>	1/2	Exclusive-OR dword register to <i>r/m</i> dword

### Operation

DEST ← LeftSRC XOR RightSRC

CF ← 0

OF ← 0

### Description

The XOR instruction computes the exclusive OR of the two operands. Each bit of the result is 1 if the corresponding bits of the operands are different; each bit is 0 if the corresponding bits are the same. The answer replaces the first operand.

### Flags Affected

The CF and OF flags are cleared; the SF, ZF, and PF flags are set according to the result; the AF flag is undefined.

### Protected Mode Exceptions

#GP(0) if the result is in a nonwritable segment; #GP(0) for an illegal memory operand effective address in the CS, DS, ES, FS, or GS segments; #SS(0) for an illegal address in the SS segment; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

### Real Address Mode Exceptions

Interrupt 13 if any part of the operand would lie outside of the effective address space from 0 to 0FFFFH.

**Virtual 8086 Mode Exceptions**

Same exceptions as in Real Address Mode; #PF(fault-code) for a page fault; #AC for unaligned memory reference if the current privilege level is 3.

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**26**

**Performance  
Monitoring**





## CHAPTER 26

# Performance Monitoring

This chapter introduces the model specific registers (MSR's) as they are implemented on the Pentium processor. Model specific registers are used to provide access to features that are generally tied to implementation dependent aspects of a particular processor. For example, testability features that provide test access to physical structures such as caches, and branch target buffers are inherently model specific. Features to measure the performance of the processor or particular components within the processor are also model specific.

The features provided by the model specific registers are expected to change from processor generation to processor generation and may even change from model to model within the same generation. Because these features are implementation dependent, they are not recommended for use in portable software. Specifically, software developers should not expect that the features implemented within the MSR's will be supported in an upward compatible manner across generations or even across different models within the same generation.

### 26.1. MODEL SPECIFIC REGISTERS

The Pentium processor implements two new instructions and several model specific registers. The RDMSR and WRMSR instructions are used to read and write the MSR's respectively. A feature bit in EDX (bit 5), reported by the CPUID instruction, indicates that the processor supports the RDMSR and WRMSR instructions.

#### 26.1.1. Model Specific Register Usage Restrictions

**Proper use of the features described in this chapter requires that the CPUID instruction be used to validate not only that the FAMILY and MODEL reported in EAX are equal to "5" and "1" or "2" respectively. Note that this requirement is significantly more restrictive than is required for new architectural features where it is sufficient to validate that the FAMILY is equal to or greater than that of the first family to implement the new feature. For more information regarding the use of the CPUID instruction, refer to the "Instruction Set" chapter of Volume 3 of the *Pentium® Processor Developer's Manual*.**

## 26.1.2. Model Specific Registers Related to Performance Monitoring

Access to the model specific registers is provided through the RDMSR and WRMSR instructions. Table 26-1 lists the model specific registers that are related to performance monitoring.

**Table 26-1. Model Specific Registers Related to Performance Monitoring**

ECX Value (in Hex)	Register Name	Description
10	Time Stamp Counter	Performance Monitor
11	Control and Event Select	Performance Monitor
12	Counter 0	Performance Monitor
13	Counter 1	Performance Monitor
14+	RESERVED	

## 26.2. PERFORMANCE MONITORING

The Pentium processor includes features to measure and monitor various parameters that contribute to the performance of the processor. This information can be then used for compiler and memory system tuning. For memory system tuning, it is possible to measure data and instruction cache hit rates, and time spent waiting for the external bus. The performance monitor allows compiler writers to gauge the effectiveness of instruction scheduling algorithms by measuring address generation interlocks and parallelism.

While the performance monitoring features that are provided by the Pentium processor are generally model specific and available only to privileged software, the Pentium processor also provides an *architectural* Time Stamp Counter that is available at the user. With this notable exception, the performance monitor features and the events they monitor are otherwise implementation dependent, and consequently, they are not considered part of the Pentium processor *architecture*. The performance monitor features are expected to change in future implementations. *It is essential that software abide by the usage restrictions for accessing model specific registers discussed in Section 0 above.*

### 26.2.1. Performance Monitoring Feature Overview

Pentium processor performance monitoring features include:

**Table 26-2. Architectural Performance Monitoring Features**

<b>RDTSC</b>	Read Time Stamp Counter - a user level instruction to provide read access to a 64-bit free-running counter
<b>CPUID (EDX.TSC)</b>	Time Stamp Counter Feature Bit - Bit 4 of EDX is set to 1 to indicate that the processor implements the TSC and RDTSC instruction.
<b>CR4.TSD</b>	Time Stamp Disable - A method for a supervisor program to disable user access to the time stamp counter in secure systems. When bit 2 of CR4 is set to 1, an attempt to execute the RDTSC instruction generates a general protection exception (#GP).

**Table 26-3. Model Specific Performance Monitoring Features**

<b>CTR0, CTR1</b>	Counter 0, Counter 1 - two programmable counters
<b>CESR</b>	Control and Event Select Register - programs CTR0, CTR1
<b>TSC</b>	Time Stamp Counter - provides read and write access to the architectural 64-bit counter in a manner that is model specific
<b>PM0/BP0, PM1/BP1</b>	Event Monitoring Pins - These pins allow external hardware to monitor the activity in CTR0 and CTR1.

### 26.2.2. Time Stamp Counter - TSC

A dedicated, free-running, 64-bit time stamp counter is provided on-chip. Note that on the Pentium processor, this counter increments on every clock cycle, although it is not guaranteed that this will be true on future processors. As a time stamp counter, the RDTSC instruction reports values that are guaranteed to be unique and monotonically increasing. Portable software should not expect that the counter reports absolute time or clock counts. The user level RDTSC (Read Time Stamp Counter) instruction is provided to allow a program of any privilege level to sample its value. A bit in CR4, TSD (Time Stamp Disable) is provided to disable this instruction in secure environments. Supervisor mode programs may sample this counter using the RDMSR instruction or reset/preset this counter with a WRMSR instruction. The counter is cleared after reset.

While the user level RDTSC instruction and a corresponding 64-bit time stamp counter will be provided in all future Pentium CPU compatible processors, access to this counter via the RDMSR/WRMSR instructions is dependent upon the particular implementation.

### 26.2.3. Programmable Event Counters - CTR0, CTR1

Two programmable 40-bit counters CTR0 and CTR1 are provided. Each counter may be programmed to count any event from a pre-determined list of events. These events, which are described in the *Events* section of this chapter, are selected by programming the Control and Event Select Register (CESR). The counters are not affected by writes to CESR and must be cleared or pre-set when switching to a new event. The counters are undefined after RESET.

Associated with each counter is an event pin (PM1/BP1, PM0/BP0) which externally signals the occurrence of the selected event.

Note that neither the CTR0/CTR1 nor CESR are part of the processor state that is automatically saved and restored during a context switch. If it is desired to coordinate the use of the programmable counters in a multiprocessing system, it is the software's responsibility to share or restrict the use of these counters through a semaphore or other appropriate mechanism.

### 26.2.4. Control and Event Select Register - CESR

A 32-bit Control and Event Select Register (CESR) is used to control operation of the programmable counters and their associated pins. Figure 26-1 depicts the CESR. For each counter, the CESR contains a 6-bit Event Select field (ES), a Pin Control bit (PC), and a three bit control field (CC). It is not possible to selectively write a subset of the CESR. If only one event needs to be changed, the CESR must first be read, the appropriate bits modified, and all bits must be written back. At reset, all bits in the Control and Event Select Register are cleared.

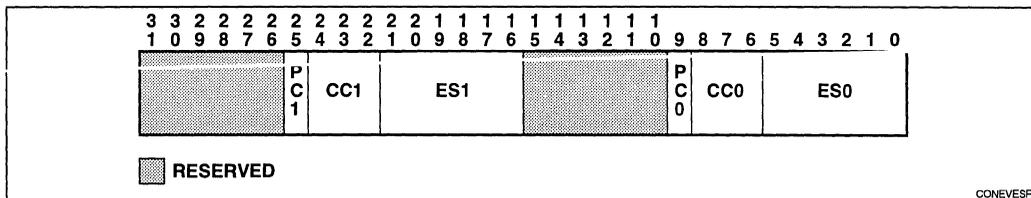


Figure 26-1. Control and Event Select Register

#### 26.2.4.1. EVENT SELECT - ES0, ES1

Up to two independent events, may be monitored by placing the appropriate event code in the Event Select field. The events and codes are listed in the Events section of this chapter.

**26.2.4.2. COUNTER CONTROL - CC0, CC1**

A three bit field is used to control the operation of the counter. the highest order bit selects between counting events and counting clocks. The middle bit enables counting when the CPL=3. The low order bit enables counting when the CPL=0, 1 or 2.

<b>CC</b>	<b>Meaning</b>
000	Count Nothing (Disable Counter)
001	Count the selected Event while the CPL=0, 1 or 2
010	Count the selected Event while the CPL=3
011	Count the selected Event regardless of the CPL
100	Count Nothing (Disable Counter)
101	Count Clocks while the CPL=0, 1 or 2
110	Count Clocks while the CPL=3
111	Count Clocks regardless of the CPL

While a counter need not be stopped to sample its contents, it must be stopped and cleared or pre-set before switching to a new event.

**26.2.4.3. PIN CONTROL - PC0, PC1**

Associated with CTR0 and CTR1 are two pins, PM0 and PM1 (PM0/BP0, PM1/BP1), and two bits which control their operation, PC0 and PC1. These pins may be individually programmed by the PC0/PC1 bits in the CESR to indicate either that the associated counter has incremented or that it has overflowed. Note that the external signalling of the event on the pins will lag the internal event by a “few” clocks as the signals are latched and buffered.

<b>PC</b>	<b>PM pin signals when the corresponding counter:</b>
0	has incremented
1	has overflowed

When the pins are configured to signal that a counter has incremented, it should be noted that although the counters may increment by 1 or 2 in a single clock, the pins can only indicate that the event occurred. Moreover, since the internal clock frequency may be higher than the external clock frequency, a single external clock may correspond to multiple internal clocks.

A "count up to" function may be provided when the event pin is programmed to signal an overflow of the counter. Because the counters are 40 bits, a carry out of bit 39 indicates an overflow. A counter may be preset to a specific value less than  $2^{40} - 1$ . After the counter has been enabled and the prescribed number of events has transpired, the counter will overflow.



Approximately 5 clocks later, the overflow is indicated externally and appropriate action, such as signaling an interrupt, may then be taken.

When the performance monitor pins are configured to indicate when the performance monitor counter has incremented and an "occurrence event" is being counted, the associated PM pin is asserted (high) each time the event occurs. When a "duration event" is being counted the associated PM pin is asserted for the entire duration of the event. When the performance monitor pins are configured to indicate when the counter has overflowed, the associated PM pin is not asserted until the counter has overflowed.

The PM0/BP0, PM1/BP1 pins also serve to indicate breakpoint matches during in Circuit Emulation, during which time the counter increment or overflow function of these pins is not available. After RESET, the PM0/BP0, PM1/BP1 pins are configured for performance monitoring, however a hardware debugger may re-configure these pins to indicate breakpoint matches.

### 26.2.5. Events

Events may be considered to be of two types: those that count OCCURRENCES, and those that count DURATION. Each of the events listed below is classified accordingly.

Occurrences events are counted each time the event takes place. If the PM0 or PM1 pins are configured to indicate when a counter increments, they are asserted each clock the counter increments. Note that if an event can happen twice in one clock the counter increments by 2, however the PM0/1 pins are asserted only once.

For Duration events, the counter counts the total number of clocks that the condition is true. When configured to indicate when a counter increments, the PM0 and PM1 pins are asserted for the duration of the event.

Table 26-4 lists the events that can be counted, and their encodings for the Control and Event Select Register.



**Table 26-4. Performance Monitoring Events**

<b>Encoding</b>	<b>Performance Monitoring Event</b>	<b>Occurrence or Duration?</b>
000000	Data Read	OCCURRENCE
000001	Data Write	OCCURRENCE
101000	Data Read or Data Write	OCCURRENCE
000010	Data TLB Miss	OCCURRENCE
000011	Data Read Miss	OCCURRENCE
000100	Data Write Miss	OCCURRENCE
101001	Data Read Miss or Data Write Miss	OCCURRENCE
000101	Write (hit) to M or E state lines	OCCURRENCE
000110	Data Cache Lines Written Back	OCCURRENCE
000111	External Snoops	OCCURRENCE
001000	Data Cache Snoop Hits	OCCURRENCE
001001	Memory Accesses in Both Pipes	OCCURRENCE
001010	Bank Conflicts	OCCURRENCE
001011	Misaligned Data Memory or I/O References	OCCURRENCE
001100	Code Read	OCCURRENCE
001101	Code TLB Miss	OCCURRENCE
001110	Code Cache Miss	OCCURRENCE
001111	Any Segment Register Loaded	OCCURRENCE
010010	Branches	OCCURRENCE
010011	BTB Hits	OCCURRENCE
010100	Taken Branch or BTB Hit	OCCURRENCE
010101	Pipeline Flushes	OCCURRENCE
010110	Instruction Executed	OCCURRENCE
010111	Instructions Executed in the v-pipe e.g., parallelism/pairing	OCCURRENCE
011000	Clocks while a bus cycle is in progress (bus utilization)	DURATION
011001	Number of clocks stalled due to full write buffers	DURATION
011010	Pipeline stalled waiting for data memory read	DURATION

**Table 26-4. Performance Monitoring Events (Contd)**

Encoding	Performance Monitoring Event	Occurrence or Duration?
011011	Stall on write to an E or M state line	DURATION
011100	Locked Bus Cycle	OCCURRENCE
011101	I/O Read or Write Cycle	OCCURRENCE
011110	Non-cacheable memory reads	OCCURRENCE
011111	Pipeline stalled because of an address generation interlock	DURATION
100010	FLOPs	OCCURRENCE
100011	Breakpoint match on DR0 Register	OCCURRENCE
100100	Breakpoint match on DR1 Register	OCCURRENCE
100101	Breakpoint match on DR2 Register	OCCURRENCE
100110	Breakpoint match on DR3 Register	OCCURRENCE
100111	Hardware interrupts	OCCURRENCE

The following descriptions clarify the events. The event codes are provided in parenthesis.

Data Read (000000), Data Write (000001), Data Read or Data Write (101000):

These are memory data reads and/or writes (internal data cache hit and miss combined), I/O is not included. The individual component reads and writes for split cycles are counted individually. Data Memory Reads that are part of TLB miss processing are not included. These events may occur at a maximum of two per clock.

Data TLB Miss (000010):

This event counts the number of misses to the data cache translation look-aside buffer.

Data Read Miss (000011), Data Write Miss (000100), Data Read Miss or Data Write Miss (101001):

These are memory read and/or write accesses that miss the internal data cache whether or not the access is cacheable or non-cacheable. Data accesses that are part of TLB miss processing are not included. Accesses directed to I/O space are not included.

Write (hit) to M or E state lines (000101):

This measures the number of write hits to exclusive or modified lines in the data cache. (These are the writes which may be held up if EWBE# is inactive.) This event may occur at a maximum of two per clock.

**Data Cache Lines Written Back (000110):**

This counts ALL Dirty lines that are written back, regardless of the cause. Replacements and internal and external snoops can all cause writeback and are counted.

**External Snoops (000111), Data Cache Snoop Hits (001000):**

The first event counts accepted external snoops whether they hit in the code cache or data cache or neither. Assertions of EADS# outside of the sampling interval are not counted. No internal snoops are counted. The second event applies to the data cache only. Snoop hits to a valid line in either the data cache, the data line fill buffer, or one of the write back buffers are all counted as hits.

**Memory Accesses in Both Pipes (001001):**

Data memory reads or writes which are paired in the pipeline. Note that these accesses are not necessarily run in parallel due to cache misses, bank conflicts, etc.

**Bank Conflicts (001010):**

These are the number of actual bank conflicts.

**Misaligned Data Memory or I/O References (001011):**

Memory or I/O reads or writes that are misaligned. A two or four byte access is misaligned when it crosses a four byte boundary; an eight byte access is misaligned when it crosses an eight byte boundary. Ten byte accesses are treated as two separate accesses of eight and two bytes each.

**Code Read (001100), Code TLB Miss (001101), Code Cache Miss (001110):**

Total instruction reads and reads that miss the code TLB or miss the internal code cache whether or not the read is cacheable or non-cacheable. Individual eight byte non-cacheable instruction reads are not counted.

**Any Segment Register Loaded (001111):**

Writes into any segment register in real or protected mode including the LDTR, GDTR, IDTR, and TR. Segment loads are caused by explicit segment register load instructions, far control transfers, and task switches. Far control transfers and task switches causing a privilege level change will signal this event twice. Note that interrupts and exceptions may initiate a far control transfer.

**Branches (010010):**

In addition to taken conditional branches, jumps, calls, returns, software interrupts, and interrupt returns, the Pentium processor treats the following operations as causing taken branches: serializing instructions, some segment descriptor loads, hardware interrupts (including FLUSH#), and programmatic exceptions that invoke a trap or fault handler. Both Taken and Not Taken Branches are counted. The pipe is not necessarily flushed. The number of branches actually executed is measured, not the number of predicted branches.

**BTB Hits (010011):**

Hits are counted only for those instructions that are actually executed.

**Taken Branch or BTB Hit (010100):**

This is a logical OR of taken branch and BTB hit. It represents an event that may cause a hit in the BTB. Specifically, it is either a candidate for a space in the BTB, or it is already in the BTB.

**Pipeline Flushes (010101):**

BTB Misses on taken branches, mis-predictions, exceptions, interrupts, and some segment descriptor loads all cause pipeline flushes.

**Instructions Executed (010110):**

Up to two per clock. Invocations of a fault handler are considered instructions.

**Instructions Executed in the v-pipe e.g. parallelism/pairing (010111):**

This event counts the number of instructions actually executed in the v-pipe. It indicates the number of instructions that were paired.

**Clocks while a bus is in progress (bus utilization) (011000):**

Including HLDA, AHOLD, BOFF# clocks.

**Number of clocks stalled due to full write buffers (011001):**

This event counts the number of clocks that the internal pipeline is stalled due to full write buffers. Full write buffers stall data memory read misses, data memory write misses, and data memory write hits to S state lines. Stalls on I/O accesses are not included.

**Pipeline stalled waiting for data memory read (011010):**

Data TLB Miss processing is also included. The pipeline stalls while a data memory read is in progress including attempts to read that are not bypassed while a line is being filled.

**Locked Bus Cycle (011100):**

LOCK prefix or LOCK instruction, Page Table Updates, and Descriptor Table Updates. Only the Read portion of the Locked Read-Modify-Write is counted. Split Locked cycles (SCYC active) count as two separate accesses. Cycles restarted due to BOFF# are not re-counted.

**I/O Read or Write Cycle (011101):**

Bus cycles directed to I/O space. Misaligned I/O accesses will generate two bus cycles. Bus cycles restarted due to BOFF# are not re-counted.

**Non-cacheable memory reads (011110):**

Non-cacheable instruction or data memory read bus cycles. Includes read cycles caused by TLB misses; does not include read cycles to I/O space. Cycles restarted due to BOFF# are not re-counted.



Pipeline stalled because of an address generation interlock (011111):

Number of address generation interlocks (AGIs). An AGI occurring in both the U and V pipelines in the same clock signals this event twice. An AGI occurs when the instruction in the execute stage of either of U or V pipelines is writing to either the index or base address register of an instruction in the D2 (address generation) stage of either the U or V pipelines.

FLOPs (100010):

Number of floating point adds, subtracts, multiplies, divides, remainders, and square roots. The transcendental instructions consist of multiple adds and multiplies and will signal this event multiple times. Instructions generating the divide by zero, negative square root, special operand, or stack exceptions will not be counted. Instructions generating all other floating point exceptions will be counted. As the integer multiply instructions share the floating point multiplier, they will signal this counter.

Breakpoint match on DR0 Register (100011),

Breakpoint match on DR1 Register (100100),

Breakpoint match on DR2 Register (100101),

Breakpoint match on DR3 Register (100110):

If programmed for one of these breakpoint match events, the performance monitor counters will be incremented in the event of a breakpoint match whether or not breakpoints are enabled. These events correspond to the signals driven on the BP[3:0] pins. Please refer to the Debugging chapter in the *Pentium® Processor Developer's Manual*, Volume 3.

Hardware Interrupts (100111):

Number of taken INTR and NMI only.





# Opcode Map





# APPENDIX A OPCODE MAP

The opcode tables in this section aid in interpreting Pentium processor object code. Use the high-order four bits of the opcode as an index to a row of the opcode table; use the low-order four bits as an index to a column of the table. If the opcode is 0FH, refer to the two-byte opcode table and use the second byte of the opcode to index the rows and columns of that table.

**All blanks in the OPCODE map are reserved and should not be used. Do not depend on the operation of unspecified OPCODEs. 0F0Bh or 0FB9h should be used when deliberately generating an illegal opcode exception.**

The escape opcode tables for floating-point instructions identify the high-order eight bits of the opcode at the top of each page. If the accompanying modR/M byte is in the range 00h-BFh, bits 3 through 5 identified along the top row of the third table on each page, along with the REG bits of the modR/M, determine the opcode. ModR/M bytes outside the range 00h-BFh are mapped by the bottom two tables on each page.

## A.1. KEY TO ABBREVIATIONS

Operands are identified by a two-character code of the form Zz. The first character, an uppercase letter, specifies the addressing method; the second character, a lowercase letter, specifies the type of operand.

## A.2. CODES FOR ADDRESSING METHOD

- A Direct address; the instruction has no modR/M byte; the address of the operand is encoded in the instruction; no base register, index register, or scaling factor can be applied; e.g., far JMP (EA).
- C The reg field of the modR/M byte selects a control register; e.g., MOV (0F20, 0F22).
- D The reg field of the modR/M byte selects a debug register; e.g., MOV (0F21, 0F23).
- E A modR/M byte follows the opcode and specifies the operand. The operand is either a general register or a memory address. If it is a memory address, the address is computed from a segment register and any of the following values: a base register, an index register, a scaling factor, a displacement.
- F Flags Register.
- G The reg field of the modR/M byte selects a general register; e.g., AX (000).
- I Immediate data. The value of the operand is encoded in subsequent bytes of the instruction.

- J The instruction contains a relative offset to be added to the instruction pointer register; e.g., JMP short, LOOP.
- M The modR/M byte may refer only to memory; e.g., BOUND, LES, LDS, LSS, LFS, LGS, CMPXCHG8B.
- O The instruction has no modR/M byte; the offset of the operand is coded as a word or double word (depending on address size attribute) in the instruction. No base register, index register, or scaling factor can be applied; e.g., MOV (A0–A3).
- R The mod field of the modR/M byte may refer only to a general register; e.g., MOV (0F20-0F24, 0F26).
- S The reg field of the modR/M byte selects a segment register; e.g., MOV (8C,8E).
- T The reg field of the modR/M byte selects a test register; e.g., MOV (0F24,0F26).
- X Memory addressed by the DS:SI register pair; e.g., MOVS, CMPS, OUTS, LODS.
- Y Memory addressed by the ES:DI register pair; e.g., MOVS, CMPS, INS, STOS, SCAS.

### A.3. CODES FOR OPERAND TYPE

- a Two one-word operands in memory or two double-word operands in memory, depending on operand size attribute (used only by BOUND).
- b Byte (regardless of operand size attribute).
- c Byte or word, depending on operand size attribute.
- d Double word (regardless of operand size attribute).
- p Thirty-two bit or 48-bit pointer, depending on operand size attribute.
- q Quad word (regardless of operand size attribute).
- s Six-byte pseudo-descriptor.
- v Word or double word, depending on operand size attribute.
- w Word (regardless of operand size attribute).

### A.4. REGISTER CODES

When an operand is a specific register encoded in the opcode, the register is identified by its name; e.g., AX, CL, or ESI. The name of the register indicates whether the register is 32-, 16-, or 8-bits wide. A register identifier of the form eXX is used when the width of the register depends on the operand size attribute; for example, eAX indicates that the AX register is used when the operand size attribute is 16 and the EAX register is used when the operand size attribute is 32.



## A.5. OPCODE LOOK-UP EXAMPLES

This section provides several examples to demonstrate how the following opcode maps are used. See Chapter 25 for detailed information on the modR/M byte, register values and the various addressing forms.

### A.5.1. One-Byte Opcode Integer Instructions

Given the hexadecimal opcode, the instruction and its operands can be determined:

**Opcode: 03050000000H**

LSB address					MSB address
03	05	00	00	00	00

Looking at the one-byte opcode map, the first digit (0) of the opcode indicates the row and the second digit (3) indicates the column. The instruction located at row 0, column 3 is an ADD instruction using the operand types Gv, Ev. The first operand of type Gv indicates a general register that is a word or doubleword depending on the operand size attribute. The second operand (Ev) indicates that a modR/M byte follows specifying whether the operand is a word or doubleword general register or a memory address. The modR/M byte for this instruction is 05H indicating (see Chapter 25) that a 32-bit displacement follows (00000000H). The reg/opcode portion of the modR/M byte (bits 3-5) is 000 indicating the EAX register. Thus, it can be determined that the instruction for this opcode is ADD EAX, mem\_op and the offset of mem\_op is 00000000H.

### A.5.2. Two-Byte Opcode Integer Instructions

Instructions that begin with 0FH can be found in the two-byte opcode map. The second opcode byte is then used to reference a particular row and column. For example, the opcode 0FA405000000003H, is located on the first page of the two-byte opcode map in row A, column 4. This indicates a SHLD instruction with the operands EvGvIb. These operands are defined as follows:

- Ev = modR/M byte follows opcode to specify word or doubleword operand
- Gv = reg field of modR/M byte selects a general register
- Ib = immediate data encoded in subsequent byte of instruction.

The third byte is the modR/M byte (05H). The mod and opcode/reg fields indicate that a 32-bit displacement follows and the EAX register is the source (see Chapter 25 for information on the modR/M byte).

The next part of the opcode is the 32-bit displacement for the destination memory operand (00000000H) and finally the immediate byte representing the count of the shift (03H).

By this breakdown, it has been shown that this opcode represents the instruction:

SHLD DS:00000000H, EAX, 3

### A.5.3. Escape Opcodes

The escape opcode maps are slightly different than the integer opcode maps. For instructions that have a modR/M byte in the range of 00H-BFH, bits 3-5 of the modR/M byte are used to determine the opcode. ModR/M bytes outside the range 00H-BFH are mapped by the tables at the bottom of each page.

#### A.5.3.1. OPCODES WITH MODR/M BYTES IN THE 00H-BFH RANGE

The opcode DD0504000000 can be interpreted as follows. This instruction can be located on the page indicating DD as the first byte. Since the modR/M byte is in the 00H-BFH range (05H or 00000101B), bits 3-5 (000) of this byte indicate the opcode to be an FLD double-real instruction. The double-real to be loaded is at 00000004H which is the following 32-bit displacement in this opcode.

#### A.5.3.2. OPCODES WITH MODR/M BYTES OUTSIDE THE 00H-BFH RANGE

Since the opcode of D8C1 has a modR/M byte outside the range 00H-BFH, the bottom two tables are used to determine this escape instruction on the page with D8 as the first byte. C1 indicates row C, column 1 which is an FADD instruction using ST, ST(1) as the operands.



**One-Byte Opcode Map**

	0	1	2	3	4	5	6	7	
0	ADD						PUSH	POP	
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	ES	ES	
1	ADC						PUSH	POP	
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	SS	SS	
2	AND						SEG	DAA	
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	=ES		
3	XOR						SEG	AAA	
	Eb,Gb	Ev,Gv	Gb,Eb	Gb,Ev	AL,lb	eAX,lv	=SS		
4	INC general register								
	eAX	eCX	eDX	eBX	eSP	eBP	eSI	eDI	
5	PUSH general register								
	eAX	eCX	eDX	eBX	eSP	eBP	eSI	eDI	
6	PUSHA	POPA	BOUND	ARPL	SEG	SEG	Operand	Address	
	PUSHAD	POPAD	Gv,Ma	Ew,Gw	=FS	=GS	Size	Size	
7	Short-displacement jump on condition (Jb)								
	JO	JNO	JB/JNAE/J	JNB/JAE/J	JZ	JNZ	JBE	JNBE	
8	Immediate Grpl		Immediate Grpl	Grpl	TEST		XCHG		
	Eb,lb	Ev,lv	Ev,lb		Eb,lb	Eb,Gb	Ev,Gv	Eb,Gb	Ev,Gv
9	NOP	XCHG word or double-word register with eAX							
		eCX	eDX	eBX	eSP	eBP	eSI	eDI	
A	MOV				MOVSB	MOVSW	CMPSB	CMPSW	
	AL,Ob	eAX,Ov	Ob,AL	Ov,eAX	Xb,Yb	Xv,Yv	Xb,Yb	Xv,Yv	
B	MOV immediate byte into byte register								
	AL	CL	DL	BL	AH	CH	DH	BH	
C	Shift Grp2a		RET near		LES	LDS	MOV		
	Eb,lb	Ev,lb	lw		Gv,Mp	Gv,Mp	Eb,lb	Ev,lv	
D	Shift Grp2				AAM	AAD		XLAT	
	Eb,1	Ev,1	Eb,CL	Ev,CL					
E	LOOPN	LOOPE	LOOP	JCXZ/JEC	IN		OUT		
	Jb	Jb	Jb	Jb	AL,lb	eAX,lb	lb,AL	lb,eAX	
F	LOCK		REPNE	REP	HLT	CMC	Unary Grp3		
				REPE			Eb	Ev	

**One-Byte Opcode Map**

	8	9	A	B	C	D	E	F
0	OR						PUSH	2-byte
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	CS	escape
1	SBB						PUSH	POP
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	DS	DS
2	SUB						SEG	DAS
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	=CS	
3	CMP						SEG	AAS
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	AL,lb	eAX,lv	=DS	
4	DEC general register							
	eAX	eCX	eDX	eBX	eSP	eBP	eSI	eDI
5	POP into general register							
	eAX	eCX	eDX	eBX	eSP	eBP	eSI	eDI
6	PUSH	IMUL	PUSH	IMUL	INSB	INSW/D	OUTSB	OUTSW/D
	lv	Gv,Ev,lv	lb	Gv,Ev,lb	Yb,DX	Yv,DX	Dx,Xb	DX,Xv
7	Short-displacement jump on condition (Jb)							
	JS	JNS	JP	JNP	JL	JNL	JLE	JNLE
8	MOV				MOV	LEA	MOV	POP
	Eb,Gb	Ev,Gv	Gb,Eb	Gv,Ev	Ew,Sw	Gv,M	Sw,Ew	Ev
9	CBW	CWD/CDQ	CALL	WAIT	PUSHF	POP	SAHF	LAHF
			aP		Fv	Fv		
A	TEST		STOSB	STOSW/D	LODSB	LODSW/D	SCASB	SCASW/D
	AL,lb	eAX,lv	Yb,AL	Yv,eAX	AL,Xb	eAX,Xv	AL,Yb	eAX,Yv
B	MOV immediate word or double into word or double register							
	eAX	eCX	eDX	eBX	eSP	eBP	eSI	eDI
C	ENTER	LEAVE	RET far	RET far	INT	INT	INTO	IRET
	lw, lb		lw		3	lb		
D	ESC (Escape to coprocessor instruction set)							
E	CALL	JMP			IN		OUT	
	Jv	Jv	Ap	Jb	AL,DX	eAX,DX	DX,AL	DX,eAX
F	CLC	STC	CLI	STI	CLD	STD	INC/DEC	INC/DEC
							Grp4	Grp5

**Two Byte Opcode Map (First byte is 0FH)**

	0	1	2	3	4	5	6	7
0	Grp6		LAR Gv,Ew	LSL Gv,Ew			CLTS	
1	*	*	*	*				
2	MOV Rd,Cd	MOV Rd,Dd	MOV Cd,Rd	MOV Dd,Rd				
3	WRMSR	RDTSC	RDMSR					
4								
5								
6								
7								
8	Long-displacement jump on condition (Jv)							
	JO	JNO	JB	JNB	JZ	JNZ	JBE	JNBE
9	Byte Set on condition (Eb)							
	SETO	SETNO	SETB	SETNB	SETZ	SETNZ	SETBE	SETNBE
A	PUSH FS	POP FS	CPUID	BT Ev,Gv	SHLD Ev,Gv,Ib	SHLD Ev,Gv,CL		
B	CMPXCH Eb,Gb	CMPXCH Ev,Gv	LSS Mp	BTR Ev,Gv	LFS Mp	LGS Mp	MOVZX	
							Gv,Eb	Gv,Ew
C	XADD Eb,Gb	XADD Ev,Gv						Group 9
D								
E								
F								

Two-Byte Opcode Map (First byte is 0FH)

	8	9	A	B	C	D	E	F
0	INVD	WBINVD		Illegal opcode				
1								
2								
3								
4								
5								
6								
7								
8	Long-displacement jump on condition (Jv)							
	JS	JNS	JP	JNP	JL	JNL	JLE	JNLE
	Byte set on condition (Eb)							
9	SETS Eb	SETNS Eb	SETP Eb	SETNP Eb	SETL Eb	SETNL Eb	SETLE Eb	SETNLE Eb
A	PUSH GS	POP GS	RSM	BTS Ev,Gv	SHRD Ev,Gv,Ib	SHRD Ev,Gv,CL		IMUL Gv,Ev
B		Illegal opcode	Grp-8 Ev,Ib	BTC Ev,Gv	BSF Gv,Ev	BSR Gv,Ev	MOV SX Gv,Eb Gv,Ew	
C	BSWAP EAX	BSWAP ECX	BSWAP EDX	BSWAP EBX	BSWAP ESP	BSWAP EBP	BSWAP ESI	BSWAP EDI
D								
E								
F								



**A.5.3.2.1. Opcodes Determined by Bits 5,4,3 of ModR/M Byte**

	mod			nnn			R/M	
Group	000	001	010	011	100	101	110	111
1	ADD	OR	ADC	SBB	AND	SUB	XOR	CMP
2	ROL	ROR	RCL	RCR	SHL SAL	SHR		SAR
3	TEST Ib/lv		NOT	NEG	MUL AL/eAX	IMUL AL/eAX	DIV AL/eAX	IDIV AL/eAX
4	INC Eb	DEC Eb						
5	INC Ev	DEC Ev	CALL Ev	CALL Ep	JMP Ev	JMP Ep	PUSH Ev	
6	SLDT Ew	STR Ew	LLDT Ew	LTR Ew	VERR Ew	VERW Ew		
7	SGDT Ms	SIDT Ms	LGDT Ms	LIDT Ms	SMSW Ew		LMSW Ew	INVLPG
8					BT	BTS	BTR	BTC
9		CMPXCH 8BMq						

### A.5.3.2.2. Escape Opcodes with D8 as First Byte

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FADD single-real	FMUL single-real	FCOM single-real	FCOMP single-real	FSUB single-real	FSUBR single-real	FDIV single-real	FDIVR single-real

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C	FADD							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
D	FCOM							
	ST,ST(0)	ST,ST(1)	ST,T(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
E	FSUB							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
F	FDIV							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)

	8	9	A	B	C	D	E	F
C	FMUL							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
D	FCOMP							
	ST,ST(0)	ST,ST(1)	ST,T(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
E	FSUBR							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
F	FDIVR							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)

**A.5.3.2.3. Escape Opcodes with D9 as First Byte**

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FLD single-real		FST single-real	FSTP single-real	FLDENV 14/28	FLDCW 2 bytes	FSTENV 14/28	FSTCW 2 bytes

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	7
C	FLD						
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)
D	FNOP						
E	FCHS	FABS			FTST	FXAM	
F	F2XM1	FYL2X	FPTAN	FPATAN	FEXTRACT	FPREM1	FDECSTP

	8	9	A	B	C	D	E	F
C	FXCH							
	ST,ST(0)	ST,ST(1)	ST,ST(2)	ST,ST(3)	ST,ST(4)	ST,ST(5)	ST,ST(6)	ST,ST(7)
D								
E	FLD1	FLDL2T	FLDL2E	FLDPI	FLDLG2	FLDLN2	FLDZ	
F	FPREM	FYL2XP1	FSQRT	FSINCOS	FRNDINT	FSCALE	FSIN	FCOS

**A.5.3.2.4. Escape Opcodes with DA as First Byte**

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FIADD short-int*	FIMUL short-int*	FICOM short-int*	FICOMP short-int*	FISUB short-int*	FISUBR short-int*	FIDIV short-int*	FIDIVR short-int*

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C								
D								
E								
F								

	8	9	A	B	C	D	E	F
C								
D								
E		FUCOMPP						
F								

**NOTE:** \*Short-int = 32 bit integer.



**A.5.3.2.5. Escape Opcodes with DB as First Byte**

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FILD short-int*		FIST short-int*	FISTP short-int*		FLD ext-real		FSTP ext-real

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C								
D								
E			FCLEX	FINIT				
F								

	8	9	A	B	C	D	E	F
C								
D								
E								
F								

**NOTE:** \*Short-int = 32 bit integer.

**A.5.3.2.6. Escape Opcodes with DC as First Byte**

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FADD double-real	FMUL double-real	FCOM double-real	FCOMP double-real	FSUB double-real	FSUBR double-real	FDIV double-real	FDIVR double-real

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C	FADD							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
D								
E	FSUBR							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
F	FDIVR							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST

	8	9	A	B	C	D	E	F
C	FMUL							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
D								
E	FSUB							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
F	FDIV							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST

**A.5.3.2.7. Escape Opcodes with DD as First Byte**

<b>mod</b>	<b>nnn</b>	<b>R/M</b>
------------	------------	------------

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FLD double-real		FST double-real	FSTP double-real	FRSTOR 98/108bytes		FSAVE 98/108bytes	FSTSW 2 bytes

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C	FFREE							
	ST(0)	ST(1)	ST(2)	ST(3)	ST(4)	ST(5)	ST(6)	ST(7)
D	FST							
	ST(0)	ST(1)	ST(2)	ST(3)	ST(4)	ST(5)	ST(6)	ST(7)
E	FUCOM							
	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
F								
	8	9	A	B	C	D	E	F
C								
D	FSTP							
	ST(0)	ST(1)	ST(2)	ST(3)	ST(4)	ST(5)	ST(6)	ST(7)
E	FUCOMP							
	ST(0)	ST(1)	ST(2)	ST(3)	ST(4)	ST(5)	ST(6)	ST(7)
F								

### A.5.3.2.8. Escape Opcodes with DE as First Byte

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FIADD word-int	FIMUL word-int	FICOM word-int	FICOMP word-int	FISUB word-int	FISUBR word-int	FIDIV word-int	FIDIVR word-int

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C	FADDP							
D	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
E	FSUBRP							
F	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
C	FDIVRP							
D	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
E	FMULP							
F	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
D	FCOMPP							
E	FSUBP							
F	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST
C	FDIVP							
D	ST(0),ST	ST(1),ST	ST(2),ST	ST(3),ST	ST(4),ST	ST(5),ST	ST(6),ST	ST(7),ST

**A.5.3.2.9. Escape Opcodes with DF As First Byte**

mod	nnn	R/M
-----	-----	-----

ModR/M bytes in range of 00h-BFh, nnn are mapped according to the following table (opcode is determined by bits 5,4,3 of modR/M byte).

000	001	010	011	100	101	110	111
FILD word-int		FIST word-int	FISTP word-int	FBLD packed- BCD	FILD long-int	FBSTP packed- BCD	FISTP long-int

ModR/M bytes outside the range 00h-BFh are mapped by the tables below:

	0	1	2	3	4	5	6	7
C								
D								
E	FSTSW AX							
F								

	8	9	A	B	C	D	E	F
C								
D								
E								
F								







**B**

## **Flag Cross-Reference**



## APPENDIX B FLAG CROSS-REFERENCE

This flag cross-reference is a summary of the flags affected by each instruction. For detailed information on how flags are affected for different modes of operation on the Pentium processor, see Chapter 25.

### B.1. Key to Codes

T	= instruction tests flag
M	= instruction modifies flag (either sets or resets depending on operands)
0	= instruction resets flag
1	= instruction sets flag
—	= instruction's effect on flag is undefined
R	= instruction restores prior value of flag<xin>
blank	= instruction does not affect flag

Instruction	OF	SF	ZF	AF	PF	CF	TF	IF	DF	NT	RF
AAA	—	—	—	TM	—	M					
AAD	—	M	M	—	M	—					
AAM	—	M	M	—	M	—					
AAS	—	—	—	TM	—	M					
ADC	M	M	M	M	M	TM					
ADD	M	M	M	M	M	M					
AND	0	M	M	—	M	0					
ARPL			M								
BOUND											
BSF/BSR	—	—	M	—	—	—					
BSWAP											
BT/BTS/BTR/BTC	—	—	—	—	—	M					
CALL											
CBW											
CLC						0					
CLD									0		
CLI								0			
CLTS											
CMC						M					
CMP	M	M	M	M	M	M					

Instruction	OF	SF	ZF	AF	PF	CF	TF	IF	DF	NT	RF
CMPS	M	M	M	M	M	M			T		
CMPXCHG	M	M	M	M	M	M					
CMPXCHG8B			M								
CPUID											
CWD											
DAA	—	M	M	TM	M	TM					
DAS	—	M	M	TM	M	TM					
DEC	M	M	M	M	M						
DIV	—	—	—	—	—	—					
ENTER											
ESC											
HLT											
IDIV	—	—	—	—	—	—					
IMUL	M	—	—	—	—	M					
IN											
INC	M	M	M	M	M						
INS									T		
INT							0			0	
INTO	T						0			0	
INVD											
INVLPG											
IRET	R	R	R	R	R	R	R	R	R	T	
Jcond	T	T	T		T	T					
JCXZ											
JMP											
LAHF											
LAR			M								
LDS/LES/LSS/LFS/LGS											
LEA											
LEAVE											
LGDT/LIDT/LLDT/LMSW											
LOCK											
LODS									T		
LOOP											
LOOPE/LOOPNE			T								
LSL			M								
LTR											
MOV											
MOV control, debug, test	—	—	—	—	—	—					
MOVS									T		
MOVSB/MOVSX/MOVSXDQ											
MUL	M	—	—	—	—	M					
NEG	M	M	M	M	M	M					
NOP											



Instruction	OF	SF	ZF	AF	PF	CF	TF	IF	DF	NT	RF
NOT OR OUT OUTS	0	M	M	—	M	0			T		
POP/POPA POPF PUSH/PUSHA/PUSHF RCL/RCR 1	R  M	R	R	R	R	R TM	R	R	R	R	
RCL/RCR count RDMSR RDTSC REP/REPE/REPNE	—					TM					
RET ROL/ROR 1 ROL/ROR count RSM	M — M					M M M		M	M	M	M
SAHF SAL/SAR/SHL/SHR 1 SAL/SAR/SHL/SHR count SBB	M — M	R M M	R M M	R — M	R M M	R M M TM					
SCAS SET cond SGDT/SIDT/SLDT/SMSW SHLD/SHRD	M T —	M T M	M T M	M  —	M T M	M T M			T		
STC STD STI STOS						1		1	1 T		
STR SUB TEST VERR/VERRW	M 0	M M	M M M	M —	M M	M 0					
WAIT WBINVD WRMSR XADD	M	M	M	M	M	M					
XCHG XLAT XOR	0	M	M	—	M	0					



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**C**

# **Status Flag Summary**

**I**



## APPENDIX C STATUS FLAG SUMMARY

### C.1. STATUS FLAGS FUNCTIONS

Bit	Name	Function
0	CF	Carry Flag—Set on high-order bit carry or borrow; cleared otherwise.
2	PF	Parity Flag—Set if low-order eight bits of result contain an even number of 1 bits; cleared otherwise.
4	AF	Adjust Flag—Set on carry from or borrow to the low order four bits of AL; cleared otherwise. Used for decimal arithmetic.
6	ZF	Zero Flag—Set if result is zero; cleared otherwise.
7	SF	Sign Flag—Set equal to high-order bit of result (0 is positive, 1 if negative).
11	OF	Overflow Flag—Set if result is too large a positive number or too small a negative number (excluding sign-bit) to fit in destination operand; cleared otherwise.

### C.2. KEY TO CODES

T	= instruction tests flag
M	= instruction modifies flag either sets or resets depending on operands)
0	= instruction resets flag
—	= instruction's effect on flag is undefined
blank	= instruction does not affect flag

STATUS FLAG SUMMARY



Instruction	OF	SF	ZF	AF	PF	CF
AAA	—	—	—	TM	—	M
AAS	—	—	—	TM	—	M
AAD	—	M	M	—	M	—
AAM	—	M	M	—	M	—
DAA	—	M	M	TM	M	TM
DAS	—	M	M	TM	M	TM
ADC	M	M	M	M	M	TM
ADD	M	M	M	M	M	M
XADD	M	M	M	M	M	M
SBB	M	M	M	M	M	TM
SUB	M	M	M	M	M	M
CMP	M	M	M	M	M	M
CMPS	M	M	M	M	M	M
CMPXCHG	M	M	M	M	M	M
CMPXCHG8B			M			
SCAS	M	M	M	M	M	M
NEG	M	M	M	M	M	M
DEC	M	M	M	M	M	
INC	M	M	M	M	M	
IMUL	M	—	—	—	—	M
MUL	M	—	—	—	—	M
RCL/RCL 1	M					TM
RCL/RCL count	—					TM
ROL/ROR 1	M					M
ROL/ROR count	—					M
SAL/SAR/SHL/SHR 1	M	M	M	—	M	M
SAL/SAR/SHL/SHR count	—	M	M	—	M	M
SHLD/SHRD	—	M	M	—	M	M
BSF/BSR	—	—	M	—	—	—
BT/BTS/BTR/BTC	—	—	—	—	—	M
AND	0	M	M	—	M	0
OR	0	M	M	—	M	0
TEST	0	M	M	—	M	0
XOR	0	M	M	—	M	0





**D**

## **Condition Codes**



## APPENDIX D CONDITION CODES

**Note:** The terms "above" and "below" refer to the relation between two unsigned values (neither the SF flag nor the OF flag is tested). The terms "greater" and "less" refer to the relation between two signed values (the SF and OF flags are tested).

### D.1. DEFINITION OF CONDITIONS

**For Conditional Instructions Jcond and SETcond**

Mnemonic	Meaning	Instruction Subcode	Condition Tested
O	Overflow	0000	OF = 1
NO	No overflow	0001	OF = 0
B NAE	Below Neither above nor equal	0010	CF = 1
NB AE	Not below Above or equal	0011	CF = 0
E Z	Equal Zero	0100	ZF = 1
NE NZ	Not equal Not zero	0101	ZF = 0
BE NA	Below or equal Not above	0110	(CF or ZF) = 1
NBE A	Neither below nor equal Above	0111	(CF or ZF) = 0
S	Sign	1000	SF = 1
NS	No sign	1001	SF = 0
P PE	Parity Parity even	1010	PF = 1
NP PO	No parity Parity odd	1011	PF = 0
L NGE	Less Neither greater nor equal	1100	(SF xor OF) = 1
NL GE	Not less Greater or equal	1101	(SF xor OF) = 0

## For Conditional Instructions Jcond and SETcond (Contd)

Mnemonic	Meaning	Instruction Subcode	Condition Tested
LE NG	Less or equal Not greater	1110	$((SF \text{ xor } OF) \text{ or } ZF) = 1$
NLE G	Neither less nor equal Greater	1111	$((SF \text{ xor } OF) \text{ or } ZF) = 0$



**E**

# **Numeric Exception Summary**



## APPENDIX E

# NUMERIC EXCEPTION SUMMARY

The following table lists the instruction mnemonics in alphabetical order. For each mnemonic, it summarizes the exceptions that the instruction may cause. When writing numeric programs that may be used in an environment that employs numerics exception handlers, assembly-language programmers should be aware of the possible exceptions for each instruction in order to determine the need for exception synchronization. Chapter 18 explains the need for exception synchronization.

Mnemonic	Instruction	IS	I	D	Z	O	U	P
F2XM1	$2^X-1$	Y	Y	Y			Y	Y
FABS	Absolute value	Y						
FADD(P)	Add real	Y	Y	Y		Y	Y	Y
FBLD	BCD load	Y						
FBSTP	BCD store and pop	Y	Y					Y
FCHS	Change sign	Y						
FCLEX	Clear exceptions							
FCOM(P)(P)	Compare real	Y	Y	Y				
FCOS	Cosine	Y	Y	Y			Y	Y
FDECSTP	Decrement stack pointer							
FDIV(R)(P)	Divide real	Y	Y	Y	Y	Y	Y	Y
FFREE	Free register							
FIADD	Integer add	Y	Y	Y		Y	Y	Y
FICOM(P)	Integer compare	Y	Y	Y				
FIDIV	Integer divide	Y	Y	Y	Y		Y	Y
FIDIVR	Integer divide reversed	Y	Y	Y	Y	Y	Y	Y
FILD	Integer load	Y						
FIMUL	Integer multiply	Y	Y	Y		Y	Y	Y
FINCSTP	Increment stack pointer							
FINIT	Initialize processor							
FIST(P)	Integer store	Y	Y					Y
FISUB(R)	Integer subtract	Y	Y	Y		Y	Y	Y
FLD extended or stack	Load real	Y						
FLD single or double	Load real	Y	Y	Y				
FLD1	Load + 1.0	Y						
FLDCW	Load Control word	Y	Y	Y	Y	Y	Y	Y
FLDENV	Load environment	Y	Y	Y	Y	Y	Y	Y
FLDL2E	Load $\log_2 e$	Y						
FLDL2T	Load $\log_2 10$	Y						
FLDLG2	Load $\log_{10} 2$	Y						
FLDLN2	Load $\log_e 2$	Y						

Mnemonic	Instruction	IS	I	D	Z	O	U	P
FLDPI	Load $\pi$	Y						
FLDZ	Load + 0.0	Y						
FMUL(P)	Multiply real	Y	Y	Y		Y	Y	Y
FNOP	No operation							
FPATAN	Partial arctangent	Y	Y	Y			Y	Y
FPREM	Partial remainder	Y	Y	Y			Y	
FPREM1	IEEE partial remainder	Y	Y	Y			Y	
FPTAN	Partial tangent	Y	Y	Y			Y	Y
FRNDINT	Round to integer	Y	Y	Y				Y
FRSTOR	Restore state	Y	Y	Y	Y	Y	Y	Y
FSAVE	Save state							
FSCALE	Scale	Y	Y	Y		Y	Y	Y
FSIN	Sine	Y	Y	Y			Y	Y
FSINCOS	Sine and cosine	Y	Y	Y			Y	Y
FSQRT	Square root	Y	Y	Y				Y
FST(P) stack or extended	Store real	Y						
FST(P) single or double	Store real	Y	Y	Y		Y	Y	Y
FSTCW	Store control word							
FSTENV	Store environment							
FSTSW (AX)	Store status word							
FSUB(R)(P)	Subtract real	Y	Y	Y		Y	Y	Y
FTST	Test	Y	Y	Y				
FUCOM(P)(P)	Unordered compare real	Y	Y	Y				
FWAIT	CPU Wait							
FXAM	Examine							
FXCH	Exchange registers	Y						
FX1HAC1	Extract	Y	Y	Y	Y			
FYL2X	$Y \cdot \log_2 X$	Y	Y	Y	Y	Y	Y	Y
FYL2XP1	$Y \cdot \log_2(X + 1)$	Y	Y	Y			Y	Y

IS — Invalid operand due to stack overflow/underflow

I — Invalid operand due to other cause

D — Denormal operand

Z — Zero-divide

O — Overflow

U — Underflow

P — Inexact result (precision)





**F**

# **Instruction Format and Timing**





# APPENDIX F

## INSTRUCTION FORMAT AND TIMING

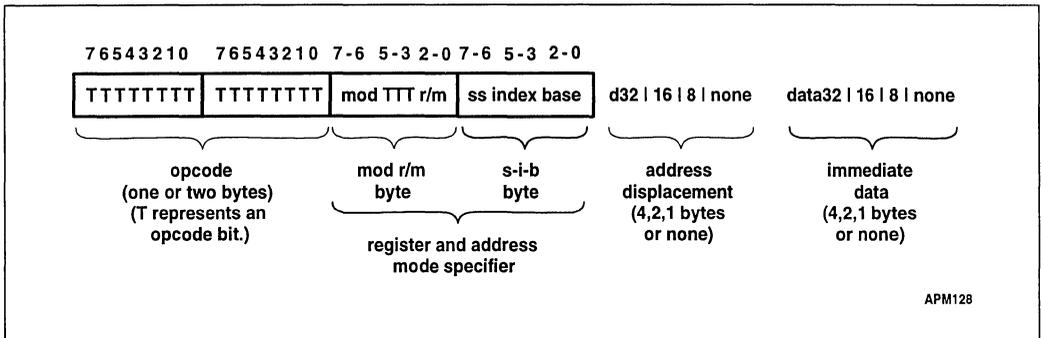
Table F-2, Table F-3, and Table F-5 list all instructions along with instruction encoding diagrams and clock counts.

### F.1. INTEGER INSTRUCTION FORMAT AND TIMING

The following sections explain how to use each of the columns of Table F-2.

#### Format

All instruction encodings are subsets of the general instruction format shown in Figure F-1. Instructions consist of one or two primary opcode bytes, possibly an address specifier consisting of the **mod r/m** byte and scale-index-base byte, a displacement if required, and an immediate data field if required.



**Figure F-1. General Instruction Format**

Within the primary opcode or opcodes, smaller encoding fields may be defined. These fields vary according to the class of operation. The fields define such information as direction of the operation, size of displacements, register encoding, or sign extension.

Almost all instructions referring to an operand in memory have an addressing mode byte following the primary opcode byte(s). This byte, the **mod r/m** byte, specifies the address mode to be used. Certain encodings of the **mod r/m** byte indicate that a second addressing byte, the scale-index-base byte, follows the **mod r/m** byte to fully specify the addressing mode.

Addressing modes can include a displacement immediately following the **mod r/m** byte or scale-index-base byte. If a displacement is present, the possible sizes are 8, 16, or 32 bits.

If the instruction specifies an immediate operand, the immediate operand follows any displacement bytes. The immediate operand, if specified, is always the last field of the instruction.

Figure F-1 illustrates several of the fields that can appear in an instruction, such as the **mod** field and the **r/m** field, but the figure does not show all fields. Several smaller fields also appear in certain instructions, sometimes within the opcode bytes themselves. Table F-1 is a complete list of all fields appearing in the instruction set. Subsequent tables list the values for each of the fields.

**Table F-1. Fields within Instructions**

Field Name	Description	Number of Bits
d	Specifies direction of data operation	1
eee	Specifies a special-purpose (test, debug, or control) register	
reg	General register specifier	3
s	Specifies if an immediate data field must be sign-extended	1
sreg2	Segment register specifier for CS, SS, DS, ES	2
sreg3	Segment register specifier for CS, SS, DS, ES, FS, GS	3
ttn	For conditional instructions, specifies a condition asserted or a condition negated	4
w	Specifies if data is byte of full-sized (full-sized is either 16 or 32 bits)	1

In many two-operand instructions, the **d** field indicates which operand is considered the source and which is the destination.

**Encoding of Operation Direction (d) Field**

d	Source	Destination
0	reg field	mod r/m or mod ss index base field
1	mod r/m or mod ss index base field	reg field

**Encoding of Special-Purpose Register (eee) Field**

eee	Control Register	Debug Register
000	CR0	DR0
001	<i>reserved</i>	DR1
010	CR2	DR2
011	CR3	DR3
100	<i>CR4</i>	<i>reserved</i>
101	<i>reserved</i>	<i>reserved</i>
110	<i>reserved</i>	DR6
111	<i>reserved</i>	DR7

**NOTE:** Do not use reserved encodings.

**Encoding of reg Field When w Field is Not Present in Instruction**

reg Field	Register Selected during 16-Bit Data Operations	Register Selected during 32-Bit Data Operations
000	AX	EAX
001	CX	ECX
010	DX	EDX
011	BX	EBX
100	SP	ESP
101	BP	EBP
110	SI	ESI
111	DI	EDI

## Encoding of reg Field When w Field is Present in Instruction

Register Specified by reg Field during 16-Bit Data Operations			Register Specified by reg Field during 32-Bit Data Operations		
reg	Function of w Field		reg	Function of w Field	
	When w = 0	When w = 1		When w = 0	When w = 1
000	AL	AX	000	AL	EAX
001	CL	CX	001	CL	ECX
010	DL	DX	010	DL	EDX
011	BL	BX	011	BL	EBX
100	AH	SP	100	AH	ESP
101	CH	BP	101	CH	EBP
110	DH	SI	110	DH	ESI
111	BH	DI	111	BH	EDI

The *s* field occurs primarily in instructions with immediate data fields. The *s* field has an effect only if the size of the immediate data is 8 bits and is being placed in a 16-bit or 32-bit destination.

## Encoding of Sign-Extend (s) Field

s	Effect on Immediate Data8	Effect on Immediate Data16 or Data32
0	None	None
1	Sign-extend data8 to fill 16-bit or 32-bit destination	None

## Encoding of the Segment Register (sreg) Field

2-Bit sreg2 Field	Segment Register Selected	3-Bit sreg3 Field	Segment Register Selected
00	ES	000	ES
01	CS	001	CS
10	SS	010	SS
11	DS	011	DS
		100	FS
		101	GS
		110	<i>do not use</i>
		111	<i>do not use</i>

For the conditional instructions (conditional jumps and set on condition), **tttn** is encoded such that **ttt** gives the condition to test and **n** indicates whether to use the condition (**n** = 0) or its negation (**n** = 1).

**Encoding of Conditional Test (tttn) Field**

<b>tttn</b>	<b>Mnemonic</b>	<b>Condition</b>
0000	O	Overflow
0001	NO	No overflow
0010	B, NAE	Below, Not above or equal
0011	NB, AE	Not below, Above or equal
0100	E, Z	Equal, Zero
0101	NE, NZ	Not equal, Not zero
0110	BE, NA	Below or equal, Not above
0111	NBE, A	Not below or equal, Above
1000	S	Sign
1001	NS	Not sign
1010	P, PE	Parity, Parity Even
1011	NP, PO	Not parity, Parity Odd
1100	L, NGE	Less than, Not greater than or equal to
1101	NL, GE	Not less than, Greater than or equal to
1110	LE, NG	Less than or equal to, Not greater than
1111	NLE, G	Not less than or equal to, Greater than

For any given instruction performing a data operation, the instruction is executing as a 32-bit operation or a 16-bit operation. Within the constraints of the operation size, the **w** field encodes the operand size as either one byte or the full operation size, as shown in the following table.

**Encoding of Operand Length (w) Field**

<b>w Field</b>	<b>Operand Size during 16-Bit Data Operations</b>	<b>Operand Size during 32-Bit Data Operations</b>
0	8 bits	8 bits
1	16 bits	32 bits

### Clock Counts

To calculate elapsed time for an instruction, multiply the instruction clock count as listed in the tables by the processor clock period (for example, 15 ns for a 66-MHz processor).

The clock count tables assume that data and instruction access hit their respective caches. A cache miss forces the processor to run an external bus cycle. The 64-bit burst bus of the Pentium processor is defined as  $r$ - $b$ - $w$ , where:

$r$  = The number of clocks in the first cycle of a burst read or the number of clocks per data cycle in a nonburst read.

$b$  = The number of clocks for the second and subsequent cycles in a burst read.

$w$  = The number of clocks for a write.

The fastest bus the Pentium processor can support is 2-1-2, assuming zero wait states. The clock counts in the cache miss penalty column assume a 2-1-2 bus. For slower buses, add  $r - 2$  clocks to the cache miss penalty for the first quadword accessed. Other factors also affect instruction clock counts.

To simplify the tables, the following assumptions are made:

1. The external bus is available for reads or writes at all times. Otherwise, add clocks to reads until the bus is available. The processor stalls if the write buffers become full and the external bus is busy. In that case, add clocks to writes until the bus becomes available.
2. If the write buffers become full, subsequent writes are delayed until the write buffers become empty. For the worst case, add  $w$  clocks.
3. Accesses are aligned. Add three clocks to each misaligned access.
4. Operands are in the data cache. Add  $3 + (\text{number of wait states})$  for each cache miss.
5. The target of a jump is in the code cache. If not, add  $r$  clocks for accessing the destination instruction of a jump. If the destination instruction is not completely contained in the first qword read, add a maximum of  $3b$  clocks. If the destination instruction is not completely contained in the first 32-byte burst, add a maximum of another  $r + 3b$  clocks. The penalty for branch misprediction is three clocks.
6. Cache fills complete before subsequent accesses to the same line. If a read misses the cache during a cache fill due to a previous read or prefetch, the read must wait for the cache fill to complete. If a read or write accesses a cache line still being filled, it must wait for the fill to complete.
7. Page translation hits in TLB. A TLB miss typically adds from 13 to 28 clocks to the instruction depending on whether the Accessed or Dirty bit of the page entries needs to be set in memory. This assumes that neither page entry is in the data cache and that a page fault does not occur during address translation.
8. No exceptions are detected during instruction execution. Refer to the Interrupt Clock Counts Table for extra clocks if an interrupt is detected.
9. Instructions that read multiple consecutive data items (for example, task switch, POPA, etc.) and miss the cache are assumed to start the first access on a 32-byte boundary. If not, an extra cache line fill may be necessary, which may add up to  $r + 3b$  clocks to the cache miss penalty.

10. No address generation interlocks (AGI). AGIs occur when a register being used as part of an address calculation is the destination register of a previous instruction in either the pipelines. AGIs cause a one clock delay.

The following abbreviations are used in the clock count columns:

- TS The time for a task switch, which depends on the target TSS type as shown in the Task Switch Clock Counts Table.
- INT The time for an interrupt, which depends on processor mode and type of gate used, as shown in the Interrupt Clock Counts Table.

**Task Switch Clock Counts Table**

Method		Value of TS
From	To	
32-Bit, 16-Bit, or V86 TSS	32-Bit TSS	85
32-Bit, 16-Bit, or V86 TSS	16-Bit TSS	85
32-Bit, 16-Bit, or V86 TSS	V86 TSS	71

**Interrupt Clock Counts Table**

Method	Value of INT		
	Cache Hit	Miss Penalty	Notes
Real Mode	11	3	
Protected Mode			
Interrupt/Trap gate, same level	25	6	9
Interrupt/Trap gate, different level	42	12	9
Task gate	17 + TS	3	9,10
Virtual 8086 Mode			
Interrupt/Trap, same level	13	3	
Interrupt/Trap gate, different level	54	12	
Task gate	17 + TS	3	10

**Notes**

The following abbreviations in the Notes column help to interpret the other columns:

- 16/32      Clocks apply to 16- and 32-bit modes respectively
- L/NL      Clocks apply to loop and no loop cases respectively
- MN/MX     Clocks shown define a range from minimum to maximum
- P          Clocks apply to protected mode
- R          Clocks apply to real-address mode
- RV/P      First clock applies to real and V86 mode; second applies to protected mode

- T/NT      Clocks apply to taken and not taken cases respectively
- U/L      Clocks apply to unlocked and locked cases respectively
1.      Assuming that the operand address and stack address fall in different cache interleaves.
  2.      Always locked. Always forced to miss cache.
  4.      Clocks      = {quotient(count/operand length)}\*7 + 9  
                    = 8 if count ≤ operand length (8/16/32).
  5.      Clocks      = {quotient(count/operand length)}\*7 + 9  
                    = 9 if count ≤ operand length (8/16/32).
  8.      Penalty for cache miss: add 2 clocks for every stack value copied to the new stack frame.
  9.      Add 8 clocks for each load of an unaccessed descriptor.
  10.     Refer to Task Switch Clock Counts Table for value of TS.
- For notes 12 – 13:    b = 0 – 3, nonzero byte number;  
                                  i = 0 – 1, nonzero nibble number;  
                                  n = 0 – 3, nonzero bit number in nibble.
12.     Clocks      = 8 + 4(b + 1) + 3(i + 1) + 3(n + 1)  
                    = 6 if second operand = 0.
  13.     Clocks      = 9 + 4(b + 1) + 3(i + 1) + 3(n + 1)  
                    = 7 if second operand = 0.
- For notes 14 – 15: n = bit position (0 – 31).
14.     Clocks      = 7 + 2(32 – n)  
                    = 6 if second operand = 0.
  15.     Clocks      = 8 + 2(32 – n)  
                    = 7 if second operand = 0.
  16.     Assuming that the two string addresses fall in different cache interleaves.
  21.     Refer to the Interrupt Clock Counts Table for value of INT.
  23.     Add  $r + 3b$  for instruction cache miss. Add 3 for branch misprediction.
  24.     Clocks shown define a range from minimum to maximum.
  25.     Add  $r + 3b$  for instruction cache miss.

**Table F-2. Integer Clock Count Summary**

Instruction	Format	Clocks	Notes	Pairing
<b>AAA – ASCII Adjust after Addition</b>	0011 0111	3		NP
<b>AAD – ASCII Adjust AX before Division</b>	1101 0101 : 0000 1010	10		NP
<b>AAM – ASCII Adjust AX after Multiply</b>	1101 0100 : 0000 1010	18		NP
<b>AAS – ASCII Adjust AL after Subtraction</b>	0011 1111	3		NP
<b>ADC – ADD with Carry</b>				PU
reg1 to reg2	0001 000w : 11 reg1 reg2	1		
reg2 to reg1	0001 001w : 11 reg1 reg2	1		
memory to register	0001 001w : mod reg r/m	2		
register to memory	0001 000w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 010 reg : immediate data	1		
immediate to accumulator	0001 010w : immediate data	1		
immediate to memory	1000 00sw : mod 010 r/m : immediate data	3	U/L	
<b>ADD – Add</b>				UV
reg1 to reg2	0000 000w : 11 reg1 reg2	1		
reg2 to reg1	0000 001w : 11 reg1 reg2	1		
memory to register	0000 001w : mod reg r/m	2		
register to memory	0000 000w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 000 reg : immediate data	1		
immediate to accumulator	0000 010w : immediate data	1		
immediate to memory	1000 00sw : mod 000 r/m : immediate data	3	U/L	
<b>AND – Logical AND</b>				UV
reg1 to reg2	0010 000w : 11 reg1 reg2	1		
reg2 to reg1	0010 001w : 11 reg1 reg2	1		
memory to register	0010 001w : mod reg r/m	2		
register to memory	0010 000w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 100 reg : immediate data	1		
immediate to accumulator	0010 010w : immediate data	1		
immediate to memory	1000 00sw : mod 100 r/m : immediate data	3	U/L	
<b>ARPL – Adjust RPL Field of Selector</b>				NP
from register	0110 0011 : 11 reg1 reg2	7		
from memory	0110 0011 : mod reg r/m	7		

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>BOUND – Check Array Against Bounds</b>				NP
	0110 0010 : mod reg r/m			
if within bounds		8		
if out of bounds		INT + 32	21	
<b>BSF – Bit Scan Forward</b>				NP
reg1, reg2	0000 1111 : 1011 1100 : 11 reg2 reg1			
word		6–34	MN/MX, 12	
doubleword		6–42	MN/MX, 12	
memory, reg	0000 1111 : 1011 1100 : mod reg r/m			
word		6–35	MN/MX, 13	
doubleword		6–43	MN/MX, 13	
<b>BSR – Bit Scan Reverse</b>				
reg1, reg2	0000 1111 : 1011 1101 : 11 reg2 reg1			
word		7–39	MN/MX, 14	
doubleword		7–71	MN/MX, 14	
memory, reg	0000 1111 : 1011 1101 : mod reg r/m			
word		7–40	MN/MX, 15	
doubleword		7–72	MN/MX, 15	
<b>BSWAP – Byte Swap</b>		0000 1111 : 1100 1 reg	1	NP
<b>BT – Bit Test</b>				NP
register, immediate	0000 1111 : 1011 1010 : 11 100 reg: imm8 data	4		
memory, immediate	0000 1111 : 1011 1010 : mod 100 r/m : imm8 data	4		
reg1, reg2	0000 1111 : 1010 0011 : 11 reg2 reg1	4		
memory, reg	0000 1111 : 1010 0011 : mod reg r/m	9		
<b>BTC – Bit Test and Complement</b>				NP
register, immediate	0000 1111 : 1011 1010 : 11 111 req: imm8 data	7		
memory, immediate	0000 1111 : 1011 1010 : mod 111 r/m : imm8 data	8	U/L	
reg1, reg2	0000 1111 : 1011 1011 : 11 reg2 reg1	7		
memory, reg	0000 1111 : 1011 1011 : mod reg r/m	13	U/L	
<b>BTR – Bit Test and Reset</b>				NP
register, immediate	0000 1111 : 1011 1010 : 11 110 reg: imm8 data	7		
memory, immediate	0000 1111 : 1011 1010 : mod 110 r/m : imm8 data	8	U/L	
reg1, reg2	0000 1111 : 1011 0011 : 11 reg2 reg1	7		
memory, reg	0000 1111 : 1011 0011 : mod reg r/m	13	U/L	
<b>BTS – Bit Test and Set</b>				NP
register, immediate	0000 1111 : 1011 1010 : 11 101 reg: imm8 data	7		
memory, immediate	0000 1111 : 1011 1010 : mod 101 r/m : imm8 data	8	U/L	
reg1, reg2	0000 1111 : 1010 1011 : 11 reg2 reg1	7		
memory, reg	0000 1111 : 1010 1011 : mod reg r/m	13	U/L	
<b>CALL – Call Procedure (in same segment)</b>				
direct	1110 1000 : full displacement	1	23	PV
register indirect	1111 1111 : 11 010 reg	2	23	NP
memory indirect	1111 1111 : mod 010 r/m	2	23	NP

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>CALL – Call Procedure (in other segment)</b>				
direct	1001 1010 : unsigned full offset, selector	4	R,23	NP
to same level		4–13	P,9,23,24	
thru gate to same level		22	P,9,25	
to inner level, no parameters		44	P,9,25	
to inner level, x parameters (d)words		45+2	P,9,25	
to TSS		x	P,10,9,2	
thru task gate		21+T	5	
		S	P,10,9,2	
		22+T	5	
		S		
indirect	1111 1111 : mod 011 r/m	5	R,23	
to same level		5–14	P,9,23,24	
thru gate to same level		22	P,9,25	
to inner level, no parameters		44	P,9,25	
to inner level, x parameters (d)words		45+2	P,9,25	
to TSS		x	P,10,9,2	
thru task gate		21+T	5	
		S	P,10,9,2	
		22+T	5	
		S		
<b>CBW – Convert Byte to Word</b>	1001 1000	3		NP
<b>CWDE – Convert Word to Doubleword</b>				
<b>CLC – Clear Carry Flag</b>	1111 1000	2		NP
<b>CLD – Clear Direction Flag</b>	1111 1100	2		NP
<b>CLI – Clear Interrupt Flag</b>	1111 1010	7		NP
<b>CLTS – Clear Task-Switched Flag in CR0</b>	0000 1111 : 0000 0110	10		NP
<b>CMC – Complement Carry Flag</b>	1111 0101	2		NP
<b>CMP – Compare Two Operands</b>				
reg1 with reg2	0011 100w : 11 reg1 reg2	1		UV
reg2 with reg1	0011 101w : 11 reg1 reg2	1		
memory with register	0011 100w : mod reg r/m	2		
register with memory	0011 101w : mod reg r/m	2		
immediate with register	1000 00sw : 11 111 reg : immediate data	1		
immediate with accumulator	0011 110w : immediate data	1		
immediate with memory	1000 00sw : mod 111 r/m	2		
<b>CMPS/CMPSB/CMPSW/CMPSD – Compare String Operands</b>	1010 011w	5	16	NP
<b>CMPXCHG – Compare and Exchange</b>				
reg1, reg2	0000 1111 : 1011 000w : 11 reg2 reg1	5		NP
memory, reg	0000 1111 : 1011 000w : mod reg r/m	6	U/L	

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>CMPXCHG8B – Compare and Exchange 8 Bytes</b>				NP
memory, reg	0000 1111 : 1100 0111 : mod reg r/m	10	U/L	
<b>CPUID – CPU Identification</b>	0000 1111 : 1010 0010	12		
<b>CWD – Convert Word to Dword</b> <b>CDQ – Convert Dword to Qword</b>	1001 1001	2		NP
<b>DAA – Decimal Adjust AL after Addition</b>	0010 0111	3		NP
<b>DAS – Decimal Adjust AL after Subtraction</b>	0010 1111	3		NP
<b>DEC – Decrement by 1</b>				UV
reg	1111 111w : 11 001 reg	1		
or	0100 1 reg	1		
memory	1111 111w : mod 001 r/m	3	U/L	
<b>DIV – Unsigned Divide</b>				NP
accumulator by register	1111 011w : 11 110 reg			
divisor —	byte	17		
	word	25		
	doubleword	41		
accumulator by memory	1111 011w : mod 110 r/m			
divisor —	byte	17		
	word	25		
	doubleword	41		
<b>ENTER – Make Stack Frame for Procedure Parameters</b>	1100 1000 : 16-bit displacement : 8-bit level (L)			NP
L = 0		11		
L = 1		15		
L > 1		15 + 2L	8	
<b>HLT – Halt</b>	1111 0100			
<b>IDIV – Signed Divide</b>				NP
accumulator by register	1111 011w : 11 111 reg			
divisor —	byte	22		
	word	30		
	doubleword	46		
accumulator by memory	1111 011w : mod 111 r/m			
divisor —	byte	22		
	word	30		
	doubleword	46		

**Table F-2. Integer Clock Count Summary (Contd)**

<b>Instruction</b>	<b>Format</b>	<b>Clocks</b>	<b>Notes</b>	<b>Pairing</b>
<b>IMUL – Signed Multiply</b>				NP
accumulator with register multiplier —	1111 011w : 11 101 reg byte word doubleword	11 11 10		
accumulator with memory multiplier —	1111 011w : mod 101 reg byte word doubleword	11 11 10		
reg1 with reg2 multiplier —	0000 1111 : 1010 1111 : 11 : reg1 reg2 byte word doubleword	10 10 10		
register with memory multiplier —	0000 1111 : 1010 1111 : mod reg r/m byte word doubleword	10 10 10		
reg1 with imm. to reg2 multiplier —	0110 10s1 : 11 reg1 reg2 : immediate data byte word doubleword	10 10 10		
mem. with imm. to reg multiplier —	0110 10s1 : mod reg r/m : immediate data byte word doubleword	10 10 10		
<b>INC – Increment by 1</b>				UV
reg or memory	1111 111w : 11 000 reg 0100 0 reg 1111 111w : mod 000 r/m	1 1 3	U/L	
<b>INT n – Interrupt Type n</b>	1100 1101 : type	INT + 6	21,25	NP
<b>INT – Single-Step Interrupt 3</b>	1100 1100	INT + 5	21,25	NP
<b>INTO – Interrupt 4 on Overflow</b>	1100 1110			NP
taken not taken		INT + 5 4	21,25 21,25	
<b>INVD – Invalidate Cache</b>	0000 1111 : 0000 1000	15		NP
<b>INVLPG – Invalidate TLB Entry</b>	0000 1111 : 0000 0001 : mod 111 r/m	29		NP

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>IRET/IRETD – Interrupt Return</b> real mode or virtual 8086 mode protected mode to same level to outer level to nested task	1100 1111	7  10– 19 27 10 + TS	R,23  P,9,23,2 4 P,9,25 P,9,10,2 5	NP
<b>Jcc – Jump if Condition is Met</b> 8-bit displacement full displacement	0111 tttt : 8-bit displacement 0000 1111 : 1000 tttt : full displacement	1 1	23 23	PV
<b>JCXZ/JECXZ – Jump on CX/ECX Zero</b> address size prefix differentiates JCXZ from JECXZ	1110 0011 : 8-bit displacement	6/5	T/NT,23	NP
<b>JMP – Unconditional Jump (to same segment)</b> short direct register indirect memory indirect	1110 1011 : 8-bit displacement 1110 1001 : full displacement 1111 1111 : 11 100 reg 1111 1111 : mod 100 r/m	1 1 2 2	23 23 23 23	PV PV NP NP
<b>JMP – Unconditional Jump (to other segment)</b> direct intersegment to same level thru call gate ro same level thru TSS thru task gate  indirect intersegment to same level thru call gate ro same level thru TSS thru task gate	1110 1010 : unsigned full offset, selector     1111 1111 : mod 101 r/m	3 3–12 18 19 + TS 20 + TS 4 4–13 18 19 + TS 20 + TS	R,23 P,9,23,24 P,9,25 P,10,9,2 5 P,10,9,2 5 R,23 P,9,23,24 P,9,25 P,10,9,2 5 P,10,9,2 5	NP
<b>LAHF – Load Flags into AH Register</b>	1001 1111	2		NP
<b>LAR – Load Access Rights Byte</b> from register from memory	0000 1111 : 0000 0010 : 11 reg1 reg2 0000 1111 : 0000 0010 : mod reg r/m	8 8		NP
<b>LDS – Load Pointer to DS</b>	1100 0101 : mod reg r/m	4–13	9,24	NP
<b>LEA – Load Effective Address</b>	1000 1101 : mod reg r/m	1		UV
<b>LEAVE – High Level Procedure Exit</b>	1100 1001	3		NP

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>LES – Load Pointer to ES</b>	1100 0100 : mod reg r/m	4–13	9,24	NP
<b>LFS – Load Pointer to FS</b>	0000 1111 : 1011 0100 : mod reg r/m	4–13	9,24	NP
<b>LGDT – Load Global Descriptor Table Register</b>	0000 1111 : 0000 0001 : mod 010 r/m	6		NP
<b>LGS – Load Pointer to GS</b>	0000 1111 : 1011 0101 : mod reg r/m	4–13	9,24	NP
<b>LIDT – Load Interrupt Descriptor Table Register</b>	0000 1111 : 0000 0001 : mod 011 r/m	6		NP
<b>LLDT – Load Local Descriptor Table Register</b>				NP
LDTR from register	0000 1111 : 0000 0000 : 11 010 reg	9		
LDTR from memory	0000 1111 : 0000 0000 : mod 010 r/m	9		
<b>LMSW – Load Machine Status Word</b>				NP
from register	0000 1111 : 0000 0001 : 11 110 reg	8		
from memory	0000 1111 : 0000 0001 : mod 110 r/m	8		
<b>LOCK – Assert LOCK# Signal Prefix</b>	1111 0000	1		NP
<b>LODS/LODSB/LODSW/LODSD – Load String Operand</b>	1010 110w	2		NP
<b>LOOP – Loop Count</b>	1110 0010 : 8-bit displacement	5/6	L/NL,23	NP
<b>LOOPZ/LOOPE – Loop Count while Zero/Equal</b>	1110 0001 : 8-bit displacement	7/8	L/NL,23	NP
<b>LOOPNZ/LOOPNE – Loop Count while not Zero/Equal</b>	1110 0000 : 8-bit displacement	7/8	L/NL,23	NP
<b>LSL – Load Segment Limit</b>				NP
from register	0000 1111 : 0000 0011 : 11 reg1 reg2	8		
from memory	0000 1111 : 0000 0011 : mod reg r/m	8		
<b>LSS – Load Pointer to SS</b>	0000 1111 : 1011 0010 : mod reg r/m	4–13/ 8–17	RV/P,9,24	NP
<b>LTR – Load Task Register</b>				NP
from register	0000 1111 : 0000 0000 : 11 011 reg	10		
from memory	0000 1111 : 0000 0000 : mod 011 r/m	10		
<b>MOV – Move Data</b>				UV
reg1 to reg2	1000 100w : 11 reg1 reg2	1		
reg2 to reg1	1000 101w : 11 reg1 reg2	1		
memory to reg	1000 101w : mod reg r/m	1		
reg to memory	1000 100w : mod reg r/m	1		
immediate to reg	1100 011w : 11 000 reg : immediate data	1		
or	1011 w reg : immediate data	1		
immediate to memory	1100 011w : mod 000 r/m : immediate data	1		
memory to accumulator	1010 000w : full displacement	1		
accumulator to memory	1010 001w : full displacement	1		

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>MOV – Move to/from Control Registers</b>				NP
CR0 from register	0000 1111 : 0010 0010 : 11 000 reg	22		
CR2 from register	0000 1111 : 0010 0010 : 11 010reg	12		
CR3 from register	0000 1111 : 0010 0010 : 11 011 reg	21		
CR4 from register	0000 1111 : 0010 0010 : 11 100 reg	14		
register from CR0-4	0000 1111 : 0010 0000 : 11 eee reg	4		
<b>MOV – Move to/from Debug Registers</b>				NP
DR0-3 from register	0000 1111 : 0010 0011 : 11 eee reg	11		
DR4-5 from register	0000 1111 : 0010 0011 : 11 eee reg	12		
DR6-7 from register	0000 1111 : 0010 0011 : 11 eee reg	11		
register from DR6-7	0000 1111 : 0010 0001 : 11 eee reg	11		
register from DR4-5	0000 1111 : 0010 0001 : 11 eee reg	12		
register from DR0-3	0000 1111 : 0010 0001 : 11 eee reg	2		
<b>MOV – Move to/from Segment Registers</b>				NP
reg to segment reg	1000 1110 : 11 sreg3 reg	2–11	9,24	
reg to SS	1000 1110 : 11 sreg3 reg	2–11/ 8–17	RV/P,9,24	
memory to segment reg	1000 1110 : mod sreg3 r/m	3	9,24	
memory to SS	1000 1110 : mod sreg3 r/m	3–12/ 8–17	RV/P,9,24	
segment reg to reg	1000 1100 : 11 sreg3 reg	1		
segment reg to memory	1000 1100 : mod sreg3 r/m	1		
<b>MOVS/MOVS<sub>B</sub>/MOVSW/ MOVSD – Move Data from String to String</b>	1010 010w	4	16	NP
<b>MOV<sub>SX</sub> – Move with Sign-Extend</b>				NP
reg2 to reg1	0000 1111 : 1011 111w : 11 reg1 reg2	3		
memory to reg	0000 1111 : 1011 111w : mod reg r/m	3		
<b>MOV<sub>ZX</sub> – Move with Zero-Extend</b>				
reg2 to reg1	0000 1111 : 1011 011w : 11 reg1 reg2	3		
memory to reg	0000 1111 : 1011 011w : mod reg r/m	3		
<b>MUL – Unsigned Multiplication of AL or AX</b>				NP
accumulator with register	1111 011w : 11 100 reg			
multiplier —	byte	11		
	word	11		
	doubleword	10		
accumulator with memory	1111 011w : mod 100 reg			
multiplier —	byte	11		
	word	11		
	doubleword	10		

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>NEG – Two's Complement Negation</b>				
reg	1111 011w : 11 011 reg	1		NP
memory	1111 011w : mod 011 r/m	3	U/L	
<b>NOP – No Operation</b>				
	1001 0000	1		UV
<b>NOT – One's Complement Negation</b>				
reg	1111 011w : 11 010 reg	1		NP
memory	1111 011w : mod 010 r/m	3	U/L	
<b>OR – Logical Inclusive OR</b>				
reg1 to reg2	0000 100w : 11 reg1 reg2	1		UV
reg2 to reg1	0000 101w : 11 reg1 reg2	1		
memory to register	0000 101w : mod reg r/m	2		
register to memory	0000 100w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 001 reg : immediate data	1		
immediate to accumulator	0000 110w : immediate data	1		
immediate to memory	1000 00sw : mod 001 r/m : immediate data	3	U/L	
<b>POP – Pop a Word from the Stack</b>				
reg	1000 1111 : 11 000 reg	1		UV
or	0101 1 reg	1		UV
memory	1000 1111 : mod 000 r/m	3	1	NP
<b>POP – Pop a Segment Register from the Stack</b>				
segment reg CS, DS, ES	000 sreg2 111	3–12	9,24	NP
segment reg SS	000 sreg2 111	3–12/ 8–17	RV/P,9,24	
segment reg FS, GS	0000 1111: 10 sreg3 001	3–12	9,24	
<b>POPA/POPAD – Pop All General Registers</b>				
	0110 0001	5		NP
<b>POPF/POPFD – Pop Stack into FLAGS or EFLAGS Register</b>				
	1001 1101	4/14	RV/P	NP
<b>PUSH – Push Operand onto the Stack</b>				
reg	1111 1111 : 11 110 reg	1		UV
or	0101 0 reg	1		UV
memory	1111 1111 : mod 110 r/m	2	1	NP
immediate	0110 10s0 : immediate data	1		UV
<b>PUSH – Push Segment Register onto the Stack</b>				
segment reg CS,DS,ES,SS	000 sreg2 110	1		NP
segment reg FS,GS	0000 1111: 10 sreg3 000	1		
<b>PUSHA/PUSHAD – Push All General Registers</b>				
	0110 0000	5		NP
<b>PUSHF/PUSHFD – Push Flags Register onto the Stack</b>				
	1001 1100	3/9	RV/P	NP

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>RCL – Rotate thru Carry Left</b>				
reg by 1	1101 000w : 11 010 reg	1		PU
memory by 1	1101 000w : mod 010 r/m	3		PU
reg by CL	1101 001w : 11 010 reg	7–24	MN/MX,4	NP
memory by CL	1101 001w : mod 010 r/m	9–26	MN/MX,5	NP
reg by immediate count	1100 000w : 11 010 reg : imm8 data	8–25	MN/MX,4	PU
memory by immediate count	1100 000w : mod 010 r/m : imm8 data	10–27	MN/MX,5	PU
<b>RCR – Rotate thru Carry Right</b>				
reg by 1	1101 000w : 11 011 reg	1		PU
memory by 1	1101 000w : mod 011 r/m	3		PU
reg by CL	1101 001w : 11 011 reg	7–24	MN/MX,4	NP
memory by CL	1101 001w : mod 011 r/m	9–26	MN/MX,5	NP
reg by immediate count	1100 000w : 11 011 reg : imm8 data	8–25	MN/MX,4	PU
memory by immediate count	1100 000w : mod 011 r/m : imm8 data	10–27	MN/MX,5	PU
<b>RDMSR – Read from Model-Specific Register</b>	0000 1111 : 0011 0010	20–24	MN/MX	NP
<b>RDTSC – Read from Time Stamp Counter</b>	0000 1111 : 0011 0001	6, 11	1	
<b>REP LODS – Load String</b>	1111 0011 : 1010 110w			NP
C = 0		7		
C > 0		7 + 3c	16	
<b>REP MOVS – Move String</b>	1111 0011 : 1010 010w			NP
C = 0		6		
C = 1		13	16	
C > 1		13 + c	16	
<b>REP STOS – Store String</b>	1111 0011 : 1010 101w			NP
C = 0		6		
C > 0		9 + c		
<b>REPE CMPS – Compare String (Find Non-Match)</b>	1111 0011 : 1010 011w			NP
C = 0		7		
C > 0		8 + 4c	16	
<b>REPE SCAS – Scan String (Find Non-AL/AX/EAX)</b>	1111 0011 : 1010 111w			NP
C = 0		7		
C > 0		8 + 4c	16	

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>REPNE CMPS – Compare String (Find Match)</b> C = 0 C > 0	1111 0010 : 1010 011w	7 9+ 4c	16	NP
<b>REPNE SCAS – Scan String (Find AL/AX/EAX)</b> C = 0 C > 0	1111 0010 : 1010 111w	7 8+ 4c	16	NP
<b>RET – Return from Procedure (to same segment)</b> 1100 0011 adding immediate to SP	1100 0011 1100 0010 : 16-bit displacement	2 3		NP
<b>RET – Return from Procedure (to other segment)</b> intersegment to same level to outer level adding immediate to SP to same level to outer level	1100 1011 1100 1010 : 16-bit displacement	4 4–13 23 4 4–13 23	R,23 P,9,23,24 P,9,25 R,23 P,9,23,24 P,9,25	NP
<b>ROL – Rotate (not thru Carry) Left</b> reg by 1 memory by 1 reg by CL memory by CL reg by immediate count memory by immediate count	1101 000w : 11 000 reg 1101 000w : mod 000 r/m 1101 001w : 11 000 reg 1101 001w : mod 000 r/m 1100 000w : 11 000 reg : imm8 data 1100 000w : mod 000 r/m : imm8 data	1 3 4 4 1 3		PU PU NP NP PU PU
<b>ROR – Rotate (not thru Carry) Right</b> reg by 1 memory by 1 reg by CL memory by CL reg by immediate count memory by immediate count	1101 000w : 11 001 reg 1101 000w : mod 001 r/m 1101 001w : 11 001 reg 1101 001w : mod 001 r/m 1100 000w : 11 001 reg : imm8 data 1100 000w : mod 001 r/m : imm8 data	1 3 4 4 1 3		PU PU NP NP PU PU
<b>RSM – Resume from System Management Mode</b>	0000 1111 : 1010 1010			NP
<b>SAHF – Store AH into Flags</b>	1001 1110	2		NP
<b>SAL – Shift Arithmetic Left</b>	same instruction as SHL			

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>SAR – Shift Arithmetic Right</b>				
reg by 1	1101 000w : 11 111 reg	1		PU
memory by 1	1101 000w : mod 111 r/m	3		PU
reg by CL	1101 001w : 11 111 reg	4		NP
memory by CL	1101 001w : mod 111 r/m	4		NP
reg by immediate count	1100 000w : 11 111 reg : imm8 data	1		PU
memory by immediate count	1100 000w : mod 111 r/m : imm8 data	3		PU
<b>SBB – Integer Subtraction with Borrow</b>				
reg1 to reg2	0001 100w : 11 reg1 reg2	1		PU
reg2 to reg1	0001 101w : 11 reg1 reg2	1		
memory to register	0001 101w : mod reg r/m	2		
register to memory	0001 100w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 011 reg : immediate data	1		
immediate to accumulator	0001 110w : immediate data	1		
immediate to memory	1000 00sw : mod 011 r/m : immediate data	3	U/L	
<b>SCAS/SCASB/SCASW/SCASD – Scan String</b>	1101 111w	4		NP
<b>SETcc – Byte Set on Condition</b>				
reg	0000 1111 : 1001 ttn : 11 000 reg	1		NP
memory	0000 1111 : 1001 ttn : mod 000 r/m	2		
<b>SGDT – Store Global Descriptor Table Register</b>	0000 1111 : 0000 0001 : mod 000 r/m	4		NP
<b>SHL – Shift Left</b>				
reg by 1	1101 000w : 11 100 reg	1		PU
memory by 1	1101 000w : mod 100 r/m	3		PU
reg by CL	1101 001w : 11 100 reg	4		NP
memory by CL	1101 001w : mod 100 r/m	4		NP
reg by immediate count	1100 000w : 11 100 reg : imm8 data	1		PU
memory by immediate count	1100 000w : mod 100 r/m : imm8 data	3		PU
<b>SHLD – Double Precision Shift Left</b>				
register by immediate count	0000 1111 : 1010 0100 : 11 reg2 reg1 : imm8	4		NP
memory by immediate count	0000 1111 : 1010 0100 : mod reg r/m : imm8	4		NP
register by CL	0000 1111 : 1010 0101 : 11 reg2 reg1	4		NP
memory by CL	0000 1111 : 1010 0101 : mod reg r/m	5		NP
<b>SHR – Shift Right</b>				
reg by 1	1101 000w : 11 101 reg	1		PU
memory by 1	1101 000w : mod 101 r/m	3		PU
reg by CL	1101 001w : 11 101 reg	4		NP
memory by CL	1101 001w : mod 101 r/m	4		NP
reg by immediate count	1100 000w : 11 101 reg : imm8 data	1		PU
memory by immediate count	1100 000w : mod 101 r/m : imm8 data	3		PU

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>SHRD – Double Precision Shift Right</b>				
register by immediate count	0000 1111 : 1010 1100 : 11 reg2 reg1 : imm8	4		NP
memory by immediate count	0000 1111 : 1010 1100 : mod reg r/m : imm8	4		NP
register by CL	0000 1111 : 1010 1101 : 11 reg2 reg1	4		NP
memory by CL	0000 1111 : 1010 1101 : mod reg r/m	5		NP
<b>SIDT – Store Interrupt Descriptor Table Register</b>				
	0000 1111 : 0000 0001 : mod 001 r/m	4		NP
<b>SLDT – Store Local Descriptor Table Register</b>				
to register	0000 1111 : 0000 0000 : 11 000 reg	2		NP
to memory	0000 1111 : 0000 0000 : mod 000 r/m	2		NP
<b>SMSW – Store Machine Status Word</b>				
to register	0000 1111 : 0000 0001 : 11 100 reg	4		NP
to memory	0000 1111 : 0000 0001 : mod 100 r/m	4		NP
<b>STC – Set Carry Flag</b>				
	1111 1001	2		NP
<b>STD – Set Direction Flag</b>				
	1111 1101	2		NP
<b>STI – Set Interrupt Flag</b>				
	1111 1011	7		
<b>STOS/STOSB/STOSW/STOSD – Store String Data</b>				
	1010 101w	3		NP
<b>STR – Store Task Register</b>				
to register	0000 1111 : 0000 0000 : 11 001 reg	2		NP
to memory	0000 1111 : 0000 0000 : mod 001 r/m	2		NP
<b>SUB – Integer Subtraction</b>				
reg1 to reg2	0010 100w : 11 reg1 reg2	1		UV
reg2 to reg1	0010 101w : 11 reg1 reg2	1		UV
memory to register	0010 101w : mod reg r/m	2		UV
register to memory	0010 100w : mod reg r/m	3	U/L	UV
immediate to register	1000 00sw : 11 101 reg : immediate data	1		UV
immediate to accumulator	0010 110w : immediate data	1		UV
immediate to memory	1000 00sw : mod 101 r/m : immediate data	3	U/L	UV
<b>TEST – Logical Compare</b>				
reg1 and reg2	1000 010w : 11 reg1 reg2	2		UV
memory and register	1000 010w : mod reg r/m	1		UV
immediate and register	1111 011w : 11 000 reg : immediate data	1		NP
immediate and accumulator	1010 100w : immediate data	1		UV
immediate and memory	1111 011w : mod 000 r/m : immediate data	2		NP
<b>VERR – Verify a Segment for Reading</b>				
register	0000 1111 : 0000 0000 : 11 100 reg	7		NP
memory	0000 1111 : 0000 0000 : mod 100 r/m	7		NP
<b>VERW – Verify a Segment for Writing</b>				
register	0000 1111 : 0000 0000 : 11 101 reg	7		NP
memory	0000 1111 : 0000 0000 : mod 101 r/m	7		NP

Table F-2. Integer Clock Count Summary (Contd)

Instruction	Format	Clocks	Notes	Pairing
<b>WAIT – Wait</b>	1001 1011	1/1		NP
<b>WBINVD – Writeback and Invalidate Data Cache</b>	0000 1111 : 0000 1001	2000+		NP
<b>WRMSR – Write to Model-Specific Register</b>	0000 1111 : 0011 0000	30–45	MN/MX	NP
<b>XADD – Exchange and Add</b>				NP
reg1, reg2	0000 1111 : 1100 000w : 11 reg2 reg1	3		
memory, reg	0000 1111 : 1100 000w : mod reg r/m	4	U/L	
<b>XCHG – Exchange Register/Memory with Register</b>				NP
reg1 with reg2	1000 011w : 11 reg1 reg2	3	2	
accumulator with reg	1001 0 reg	2	2	
memory with reg	1000 011w : mod reg r/m	3	2	
<b>XLAT/XLATB – Table Look-up Translation</b>	1101 0111	4		NP
<b>XOR – Logical Exclusive OR</b>				UV
reg1 to reg2	0011 000w : 11 reg1 reg2	1		
reg2 to reg1	0011 001w : 11 reg1 reg2	1		
memory to register	0011 001w : mod reg r/m	2		
register to memory	0011 000w : mod reg r/m	3	U/L	
immediate to register	1000 00sw : 11 110 reg : immediate data	1		
immediate to accumulator	0011 010w : immediate data	1		
immediate to memory	1000 00sw : mod 110 r/m : immediate data	3	U/L	

**Table F-2. Integer Clock Count Summary (Contd)**

Instruction	Format	Clocks	Notes	Pairing
<b>Prefix Bytes</b>				
address size	0110 0111	1		
LOCK	1111 0000	1		
operand size	0110 0110	1		
CS segment override	0010 1110	1		
DS segment override	0011 1110	1		
ES segment override	0010 0110	1		
FS segment override	0110 0100	1		
GS segment override	0110 0101	1		
SS segment override	0011 0110	1		
<b>External Interrupt</b>		INT + 14	21	
<b>NMI – Non-Maskable Interrupt</b>		INT + 6	21	
<b>Page Fault</b>		INT + 40	21	
<b>Virtual 8086 Mode Exceptions</b>				
CLI		INT + 9	21	
STI		INT + 9	21	
INT n		INT + 9		
PUSHF		INT + 9	21	
POPF		INT + 9	21	
IRET		INT + 9		
IN				
fixed port		INT + 34	21	
variable port		INT + 34	21	
OUT				
fixed port		INT + 34	21	
variable port		INT + 34	21	
INS		INT + 34	21	
OUTS		INT + 34	21	
REP INS		INT + 34	21	
REP OUTS		INT + 34	21	

**NOTES:**

1. Clock counts apply to PL0 and PL1-3, respectively..

## F.2. I/O INSTRUCTION FORMAT AND TIMING

**Table F-3. I/O Instructions Clock Count Summary**

Instruction	Format	Real Mode	Protected Mode CPL≤ IOPL	Protected Mode CPL>I OPL	Virtual 8086 Mode	Notes
<b>IN – Input from:</b>						
fixed port number	1110 010w : port	7	4	21	19	
variable port	1110 110w	7	4	21	19	
<b>OUT – Output to:</b>						
fixed port number	1110 011w : port	12	9	26	24	
variable port	1110 111w	12	9	26	24	
<b>INS – Input from DX Port</b>	0110 110w	9	6	24	22	
<b>OUTS – Output to DX Port</b>	0110 111w	13	10	27	25	1
<b>REP INS – Input String</b> 110w	1111 0011 : 0110	11 + 3c	8 + 3c	25 + 3c	23 + 3c	2
<b>REP OUTS – Output String</b> 111w	1111 0011 : 0110	13 + 4c	10 + 4c	27 + 4c	25 + 4c	3

**NOTES:**

1. Two clock cache miss penalty in all cases.
2. c = count in CX or ECX
3. Cache miss penalty in all modes: Add 2 clocks for every 16 bytes. Entire penalty on second operation.

## F.3. FLOATING-POINT INSTRUCTION FORMAT AND TIMING

The following sections explain how to use the columns of Table F-5.

### F.3.1. Format

Instructions for the FPU assume one of the five forms shown in Table F-4. In all cases, instructions are at least two bytes long and begin with the bit pattern 11011.

**Table F-4. General Floating-Point Instruction Format**

		Instruction										Optional Fields			
		First Byte				Second Byte									
1		11011	OPA		1	mod		1	OPB		r/m		s-i-b	disp	
2		11011	MF		OPA		mod		OPB		r/m		s-i-b	disp	
3		11011	d	P	OPA		1	1	OPB		R	ST(i)			
4		11011	0	0	1	1	1	1	OP						
5		11011	0	1	1	1	1	1	OP						
		15-11	10	9	8	7	6	5	4	3	2	1	0		

MF = Memory Format

00 — 32-bit real

01 — 32-bit integer

10 — 64-bit real

11 — 16-bit integer

P = Pop

0 — Do not pop stack

1 — Pop stack after operation

d = Destination

0 — Destination is ST(0)

1 — Destination is ST(i)

R XOR d = 0 — Destination OP Source

R XOR d = 1 — Source OP Destination

ST(i) = Register stack element *i*

000 = Stack Top

001 = Second stack element

111 = Eighth stack element

The **mod** (mode field) and **r/m** (register/memory specifier) have the same interpretation as the corresponding fields of the integer instructions. The **s-i-b** (scale index base) and **disp** (displacement) are optionally present in instructions that have **mod** and **r/m** fields. Their presence depends on the values of **mod** and **r/m**, as for integer instructions.

### F.3.2. Clock Counts

Two clock counts separated by a slash (/) are the latency and throughput, respectively. Throughput may be less than latency due to pipelining.

Two clock counts separated by a dash indicate a range of possible timings.

### F.3.3. Notes

1. If CW.PC indicates 24-bit precision, subtract 20 clocks. If CW.PC indicates 53-bit precision, subtract 6 clocks.
2. If there is a numeric error pending from a previous instruction, add 60 clocks.
3. FXCH takes 0 clocks when paired. Second FXCH will pair in V-pipe if two FXCH instructions are issued back-to-back.
4. FMUL followed by FMUL has throughput of 2.

### F.3.4. Pairing

FX — Pairs with FXCH

NP — No pairing.



**Table F-5. Floating-Point Clock Count Summary**

Instruction	Format	Clocks	Notes	Pairing
<b>F2XM1 – Compute <math>2^{ST(0)} - 1</math></b>	11011 001 : 1111 0000	13–57		NP
<b>FABS – Absolute Value</b>	11011 001 : 1110 0001	1/1		FX
<b>FADD – Add</b>				FX
ST(0) $\leftarrow$ ST(0) + 32-bit memory	11011 000 : mod 000 r/m	3/1		
ST(0) $\leftarrow$ ST(0) + 64-bit memory	11011 100 : mod 000 r/m	3/1		
ST(d) $\leftarrow$ ST(0) + ST(i)	11011 d00 : 11 000 ST(i)	3/1		
<b>FADDP – Add and Pop</b>				FX
ST(0) $\leftarrow$ ST(0) + ST(i)	11011 110 : 11 000 ST(i)	3/1		
<b>FBLD – Load Binary Coded Decimal</b>	11011 111 : mod 100 r/m	48–58		NP
<b>FBSTP – Store Binary Coded Decimal and Pop</b>	11011 111 : mod 110 r/m	148–154		NP
<b>FCHS – Change Sign</b>	11011 001 : 1110 0000	1/1		FX
<b>FCLEX – Clear Exceptions</b>	11011 011 : 1110 0010	9/9	2	NP
<b>FCOM – Compare Real</b>				FX
32-bit memory	11011 000 : mod 010 r/m	4/1		
64-bit memory	11011 100 : mod 010 r/m	4/1		
ST(i)	11011 000 : 11 010 ST(i)	4/1		
<b>FCOMP – Compare Real and Pop</b>				FX
32-bit memory	11011 000 : mod 011 r/m	4/1		
64-bit memory	11011 100 : mod 011 r/m	4/1		
ST(i)	11011 000 : 11 011 ST(i)	4/1		
<b>FCOMPP – Compare Real and Pop Twice</b>	11011 110 : 11 011 001	4/1		
<b>FCOS – Cosine of ST(0)</b>	11011 001 : 1111 1111	18–124		NP
<b>FDECSTP – Decrement Stack-Top Pointer</b>	11011 001 : 1111 0110	1/1		NP
<b>FDIV – Divide</b>				FX
ST(0) $\leftarrow$ ST(0) $\div$ 32-bit memory	11011 000 : mod 110 r/m	39	1	
ST(0) $\leftarrow$ ST(0) $\div$ 64-bit memory	11011 100 : mod 110 r/m	39	1	
ST(d) $\leftarrow$ ST(0) $\div$ ST(i)	11011 d00 : 1111 R ST(i)	39	1	
<b>FDIVP – Divide and Pop</b>				FX
ST(0) $\leftarrow$ ST(0) $\div$ ST(i)	11011 110 : 1111 1 ST(i)	39	1	
<b>FDIVR – Reverse Divide</b>				FX
ST(0) $\leftarrow$ 32-bit memory $\div$ ST(0)	11011 000 : mod 111 r/m	39	1	
ST(0) $\leftarrow$ 64-bit memory $\div$ ST(0)	11011 100 : mod 111 r/m	39	1	
ST(d) $\leftarrow$ ST(i) $\div$ ST(0)	11011 d00 : 1111 R ST(i)	39	1	
<b>FDIVRP – Reverse Divide and Pop</b>				FX
ST(0) $\leftarrow$ ST(i) $\div$ ST(0)	11011 110 : 1111 0 ST(i)	39	1	
<b>FFREE – Free ST(i) Register</b>	11011 101 : 1100 0 ST(i)	1/1		NP
<b>FIADD – Add Integer</b>				NP
ST(0) $\leftarrow$ ST(0) + 16-bit memory	11011 110 : mod 000 r/m	7/4		
ST(0) $\leftarrow$ ST(0) + 32-bit memory	11011 010 : mod 000 r/m	7/4		

Table F-5. Floating-Point Clock Count Summary (Contd.)

Instruction	Format	Clocks	Notes	Pairing
<b>FICOM – Compare Integer</b>				
16-bit memory	11011 110 : mod 010 r/m	8/4		NP
32-bit memory	11011 010 : mod 010 r/m	8/4		
<b>FICOMP – Compare Integer and Pop</b>				
16-bit memory	11011 110 : mod 011 r/m	8/4		NP
32-bit memory	11011 010 : mod 011 r/m	8/4		
<b>FIDIV</b>				
ST(0) ← ST(0) + 16-bit memory	11011 110 : mod 110 r/m	42	1	NP
ST(0) ← ST(0) + 32-bit memory	11011 010 : mod 110 r/m	42	1	
<b>FIDIVR</b>				
ST(0) ← ST(0) + 16-bit memory	11011 110 : mod 111 r/m	42	1	NP
ST(0) ← ST(0) + 32-bit memory	11011 010 : mod 111 r/m	42	1	
<b>FILD – Load Integer</b>				
16-bit memory	11011 111 : mod 000 r/m	3/1		NP
32-bit memory	11011 011 : mod 000 r/m	3/1		
64-bit memory	11011 111 : mod 101 r/m	3/1		
<b>FIMUL</b>				
ST(0) ← ST(0) + 16-bit memory	11011 110 : mod 001 r/m	7/4		NP
ST(0) ← ST(0) + 32-bit memory	11011 010 : mod 001 r/m	7/4		
<b>FINCSTP – Increment Stack Pointer</b>				
	11011 001 : 1111 0111	1/1		NP
<b>FINIT – Initialize Floating-Point Unit</b>				
	11011 011 : 1110 0011	16/12	2	NP
<b>FIST – Store Integer</b>				
16-bit memory	11011 111 : mod 010 r/m	6/6		NP
32-bit memory	11011 011 : mod 010 r/m	6/6		
<b>FISTP – Store Integer and Pop</b>				
16-bit memory	11011 111 : mod 011 r/m	6/6		NP
32-bit memory	11011 011 : mod 011 r/m	6/6		
64-bit memory	11011 111 : mod 111 r/m	6/6		
<b>FISUB</b>				
ST(0) ← ST(0) + 16-bit memory	11011 110 : mod 100 r/m	7/4		NP
ST(0) ← ST(0) + 32-bit memory	11011 010 : mod 100 r/m	7/4		
<b>FISUBR</b>				
ST(0) ← ST(0) + 16-bit memory	11011 110 : mod 101 r/m	7/4		NP
ST(0) ← ST(0) + 32-bit memory	11011 010 : mod 101 r/m	7/4		
<b>FLD – Load Real</b>				
32-bit memory	11011 001 : mod 000 r/m	1/1		FX
64-bit memory	11011 101 : mod 000 r/m	1/1		FX
80-bit memory	11011 011 : mod 101 r/m	3/3		NP
ST(i)	11011 001 : 11 000 ST(i)	1/1		FX

**Table F-5. Floating-Point Clock Count Summary (Contd.)**

Instruction	Format	Clocks	Notes	Pairing
<b>FLD1 – Load +1.0 into ST(0)</b>	11011 001 : 1110 1000	2/2		NP
<b>FLDCW – Load Control Word</b>	11011 001 : mod 101 r/m	7/7		NP
<b>FLDENV – Load FPU Environment</b>	11011 001 : mod 100 r/m			NP
real and v86 modes, 16-bit address		37		
real and v86 modes, 32-bit address		37		
protected mode, 16-bit address		32		
protected mode, 32-bit address		33		
<b>FLDL2E – Load <math>\log_2(\epsilon)</math> into ST(0)</b>	11011 001 : 1110 1010	5/3		NP
<b>FLDL2T – Load <math>\log_2(10)</math> into ST(0)</b>	11011 001 : 1110 1001	5/3		NP
<b>FLDLG2 – Load <math>\log_{10}(2)</math> into ST(0)</b>	11011 001 : 1110 1100	5/3		NP
<b>FLDLN2 – Load <math>\log_e(2)</math> into ST(0)</b>	11011 001 : 1110 1101	5/3		NP
<b>FLDPI – Load <math>\pi</math> into ST(0)</b>	11011 001 : 1110 1011	5/3		NP
<b>FLDZ – Load +0.0 into ST(0)</b>	11011 001 : 1110 1110	2/2		NP
<b>FMUL – Multiply</b>				FX
ST(0) $\leftarrow$ ST(0) $\times$ 32-bit memory	11011 000 : mod 001 r/m	3/1	4	
ST(0) $\leftarrow$ ST(0) $\times$ 64-bit memory	11011 100 : mod 001 r/m	3/1	4	
ST(d) $\leftarrow$ ST(0) $\times$ ST(i)	11011 d00 : 1100 1 ST(i)	3/1	4	
<b>FMULP – Multiply</b>				FX
ST(0) $\leftarrow$ ST(0) $\times$ ST(i)	11011 110 : 1100 1 ST(i)	3/1		
<b>FNOP – No Operation</b>	11011 001 : 1101 0000	1/1		NP
<b>FPATAN – Partial Arctangent</b>	11011 001 : 1111 0011	19–134		NP
<b>FPREM – Partial Remainder</b>	11011 001 : 1111 1000	16–64		NP
<b>FPREM1 – Partial Remainder (IEEE)</b>	11011 001 : 1111 0101	20–70		NP
<b>FPTAN – Partial Tangent</b>	11011 001 : 1111 0010	17–173		NP
<b>FRNDINT – Round to Integer</b>	11011 001 : 1111 1100	9–20		
<b>FRSTOR – Restore FPU State</b>	11011 101 : mod 100 r/m			NP
real and v86 modes, 16-bit address		75/75		
real and v86 modes, 32-bit address		95/95		
protected mode, 16-bit address		70/70		
protected mode, 32-bit address		70/70		
<b>FSAVE – Store FPU State</b>	1101 101 : mod 110 r/m			NP
real and v86 modes, 16-bit address		127/127	2	
real and v86 modes, 32-bit address		151/1	2	
protected mode, 16-bit address		51	2	
protected mode, 32-bit address		124/1	2	
		24		
		124/1		
		24		
<b>FSCALE – Scale</b>	11011 001 : 1111 1101	20–31		NP
<b>FSIN – Sine</b>	11011 001 : 1111 1110	16–126		NP
<b>FSINCOS – Sine and Cosine</b>	11011 001 : 1111 1011	17–137		NP

Table F-5. Floating-Point Clock Count Summary (Contd.)

Instruction	Format	Clocks	Notes	Pairing
<b>FSQRT – Square Root</b>	11011 001 : 1111 1010	70/70		NP
<b>FST – Store Real</b>				NP
32-bit memory	11011 001 : mod 010 r/m	2/2		
64-bit memory	11011 101 : mod 010 r/m	2/2		
ST(i)	11011 101 : 11 010 ST(i)	1/1		
<b>FSTCW – Store Control Word</b>	11011 001 : mod 111 r/m	2/2	2	NP
<b>FSTENV – Store FPU Environment</b>	11011 001 : mod 110 r/m			NP
real and v86 modes, 16-bit address		50/50	2	
real and v86 modes, 32-bit address		48/50	2	
protected mode, 16-bit address		49/50	2	
protected mode, 32-bit address		50/50	2	
<b>FSTP – Store Real and Pop</b>				NP
32-bit memory	11011 001 : mod 011 r/m	2/2		
64-bit memory	11011 101 : mod 011 r/m	2/2		
80-bit memory	11011 011 : mod 111 r/m	3/3		
ST(i)	11011 101 : 11 011 ST(i)	1/1		
<b>FSTSW – Store Status Word into AX</b>	11011 111 : 1110 0000	6/2	2	NP
<b>FSTSW – Store Status Word into Memory</b>	11011 101 : mod 111 r/m	5/2	2	NP
<b>FSUB – Subtract</b>				FX
ST(0) ← ST(0) – 32-bit memory	11011 000 : mod 100 r/m	3/1		
ST(0) ← ST(0) – 64-bit memory	11011 100 : mod 100 r/m	3/1		
ST(d) ← ST(0) – ST(i)	11011 d00 : 1110 R ST(i)	3/1		
<b>FSUBP – Subtract and Pop</b>				F-X
ST(0) ← ST(0) – ST(i)	11011 110 : 1110 1 ST(i)	3/1		
<b>FSUBR – Reverse Subtract</b>				FX
ST(0) ← 32-bit memory – ST(0)	11011 000 : mod 101 r/m	3/1		
ST(0) ← 64-bit memory – ST(0)	11011 100 : mod 101 r/m	3/1		
ST(d) ← ST(i) – ST(0)	11011 d00 : 1110 R ST(i)	3/1		
<b>FSUBRP – Reverse Subtract and Pop</b>				FX
ST(i) ← ST(i) – ST(0)	11011 110 : 1110 0 ST(i)	3/1		
<b>FTST – Test</b>	11011 001 : 1110 0100	4/1		FX
<b>FUCOM – Unordered Compare Real</b>	11011 101 : 1110 0 ST(i)	4/1		FX
<b>FUCOMP – Unordered Compare and Pop</b>	11011 101 : 1110 1 ST(i)	4/1		FX
<b>FUCOMP – Unordered Compare and Pop Twice</b>	11011 010 : 1110 1001	4/1		FX
<b>FXAM – Examine</b>	11011 001 : 1110 0101	21/21		NP
<b>FXCH – Exchange ST(0) and ST(i)</b>	11011 001 : 1100 1 ST(i)	1		

**Table F-5. Floating-Point Clock Count Summary (Contd.)**

Instruction	Format	Clocks	Notes	Pairing
<b>FXTRACT – Extract Exponent and Significand</b>	11011 001 : 1111 0100	13/13		NP
<b>FYL2X – <math>ST(1) \times \log_2(ST(0))</math></b>	11011 001 : 1111 0001	22–111		NP
<b>FYL2XP1 – <math>ST(1) \times \log_2(ST(0) + 1.0)</math></b>	11011 001 : 1111 1001	22–103		NP
<b>FWAIT – Wait until FPU Ready</b>	1001 1011	1/1		



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**G**

**Report on  
Transcendental  
Functions**

**I**



# APPENDIX G

## REPORT ON TRANSCENDENTAL FUNCTIONS

The Pentium microprocessor employs a new set of algorithms to implement its transcendental instructions. This chapter includes:

- A brief introduction to the algorithms
- A summary of their accuracy, monotonicity, and speed characteristics
- A description of the verification effort to validate the accuracy and monotonicity of the implemented algorithms

### G.1. INTRODUCTION

There are two traditional classes of algorithm for implementing elementary transcendental functions.

The first class transforms an input argument to one with very small magnitude. An approximation to the function at that small argument is obtained by simple calculation, typically a couple of adds with a multiplication or division. Finally, the desired result is obtained by another transformation. This class of algorithm is referred to as *CORDIC* and has the characteristic that the underlying operations are very simple, typically involving only shifts and fixed-point additions. The bulk of the work in a CORDIC algorithm lies in the initial and final transformations, and the performance of the algorithm is limited by the sequential nature of the long series of shifts and adds. For descriptions of CORDIC algorithms, see [6, 7, 10]. There are several examples of microprocessors (including the Intel486 microprocessor) that implement these algorithms using on-chip hardware and firmware.

The second class of algorithm employs a rather simple transformation on an input argument, reducing it to one of moderate magnitude. To approximate the function value at the transformed argument, a polynomial or a rational function is evaluated at that point. To obtain roughly 64 bits of accuracy, a typical polynomial or rational function would require roughly 10 floating-point multiplications and additions, and one additional division if a rational function is used. Finally, a simple transformation is applied to create the value desired. These algorithms do not have a name analogous to CORDIC; they can simply be called polynomial-based algorithms. The bulk of the work here lies in the second step that involves a polynomial or rational function evaluation. For descriptions of this class of algorithm, see [2, 4].

In the past, hardware implementations of elementary functions mostly employed CORDIC algorithms because of their relatively simple hardware requirements. Recent hardware advancements resulting in the high speed of basic floating-point operations have made it possible and advantageous to implement polynomial-based algorithms.

The algorithms for the transcendental functions on the Pentium microprocessor can be thought of as a middle ground between the two approaches. By using tables of function values stored in ROM, one can significantly shorten the polynomial calculations that would normally be required in a polynomial-based algorithm. This class of algorithm is usually referred to as *table-driven*. Table-driven algorithms are by no means new, and recent uses for them can be found in [1, 3, 5, 8]. Such algorithms have been implemented in software libraries in the past, but never before on-chip. Although such algorithms require a moderate amount of ROM space and a small increase in argument reduction complexity, they offer a number of important advantages, especially if implemented on-chip. These are:

1. Accuracy. The combination of simple argument reduction and small reduced arguments leads to highly accurate final results. Also, access to internal data paths that are wider than the paths available to a software library further enhances the accuracy.
2. Monotonicity. The high accuracy also leads to monotonicity.
3. Proof of correctness. Rigorous error analyses become straightforward and also lead to tight error bounds.
4. Performance. The overall implementation algorithm leads to higher performance due to several reasons. The simple core calculations are marked by short polynomials. Access to microprogramming at the low level afforded within the Pentium processor chip provides richer parallelism and control flow than that available to software libraries. The striking simplicity of the implementation adds no additional critical paths to the chip, allowing the clock rate to be taken to the limit imposed by other features.

## G.2. SUMMARY OF ACCURACY, MONOTONICITY AND SPEED

### G.2.1. Accuracy

Accuracy is measured in terms of units in the last place (ulp). For a given argument  $x$ , let  $f(x)$  and  $F(x)$  be the correct and computed function values respectively. The error in ulps is defined to be

$$\left| \frac{f(x) - F(x)}{2^{k-63}} \right|$$

where  $k$  is an integer such that  $1 \leq 2^{-k}f(x) < 2$ . Note that even if  $F(x)$  is the same as  $f(x)$  correctly rounded to 64 significant bits, the worst-case error is 1/2 ulp when rounding in nearest mode. An implementation  $F(x)$  is considered extremely satisfactory if the worst-case error is under 1 ulp.

On the Pentium microprocessor, the worst case error on all transcendental functions is less than 1 ulp when rounding in nearest mode, and less than 1.5 ulps when rounding in other modes. This is summarized in Table G-1.

**Table G-1. Summary of Accuracy**

Function	Round to Nearest Mode	All Other Rounding Modes
All functions	Worst case error is less than 1 ulp.	Worst case error is less than 1.5 ulp.

### G.2.2. Monotonicity

For a given argument  $x$  with  $x_-$  and  $x_+$  as its lower and upper neighbors, the implemented function  $F$  is monotonic with respect to its input argument if...

$$F(x_-) \leq F(x) \leq F(x_+), \text{ if } f \text{ is increasing at } x,$$

or if...

$$F(x_-) \geq F(x) \geq F(x_+), \text{ if } f \text{ is decreasing at } x.$$

The functions are guaranteed to be monotonic with respect to the input operands throughout the domain supported by the instruction.

### G.2.3. Speed

The speed is described by specifying the latency in terms of clock counts. The latency varies from function to function, with typical performance from 54 to 115 clocks. Table G-2 summarizes the latency of each of the functions. Three clock count numbers are provided. The first number is for special operands such as zero or infinity; the second and third numbers are the lower and upper bounds for non-special operands in the domain. For example, for FYL2X, when  $x = 0$ , the processor takes 22 clocks, and it takes 104 and 114 clocks when  $|x - 1| \geq 1/8$  and when  $|x - 1| < 1/8$  respectively.

## G.3. VERIFICATION SUMMARY

A rigorous mathematical error analysis was performed for each function. Furthermore, a comprehensive verification program was undertaken to confirm the correctness of the error analysis (and consequently the accuracy and monotonicity characteristics) of the implemented algorithms.

**Table G-2. Speed of Functions at Typical Arguments**

Function	Latency* (clocks)	Function	Latency* (clocks)
F2XM1	13, 54, 60	FSIN	12, 59, 126
FCOS	14, 59, 126	FSINCOS	13, 83, 138
FPATAN	19, 98, 137	FPTAN	13, 115, 174
FYL2X	22, 104, 114	FYL2XP1	22, 103, 106

\*The first number is for special operands, such as zero or infinity; the second and third numbers are the lower and upper bounds for nonspecial operands in the domain.

For each function, an average of 8500 specially chosen points were used to compare the results from the Pentium microprocessor against a set of results that are accurate to about 112 bits, derived from the VAX\* VMS\* H-functions Math Library. In addition, about 300 million points were randomly chosen for accuracy testing in a manner such that each binade of the input domain was covered; i.e., test points were chosen to cover intervals corresponding to each exponent value of the input domain.

For all cases tested, the actual error was found to lie below the bound obtained by the theoretical error analysis. Figure G-1 through Figure G-22 are ulp plots that illustrate this characterization information. For a given argument in the X-axis, a dot is printed to indicate the error in ulps of the function at that argument. Of particular interest are the peaks and the envelopes of these plots. The scatter plot characteristics observed track the error analyses closely. Table G-3 summarizes the number of arguments tested.

**Table G-3. Number of Arguments Used in Accuracy Tests**

Function	No. of Arguments (Million)	Function	No. of Arguments (Million)
FYL2X	35	FYL2XP1	28
FSIN	28	FCOS	37
FSINCOS	54	FPTAN	37
FPATAN	50	F2XM1	30

All the functions were tested for monotonicity. A total of about 145 million points were used for monotonicity characterization. No failures were found. Table G-4 summarizes the number of arguments tested.

**Table G-4. Number of Arguments Used in Monotonicity Tests**

Function	No. of Arguments (Million)	Function	No. of Arguments (Million)
FYL2X	30	FYL2XP1	18
FSIN	4	FCOS	8.5
FSINCOS	24.5	FPTAN	23.5
FPATAN	10	F2XM1	26

G.4. SCATTER PLOTS

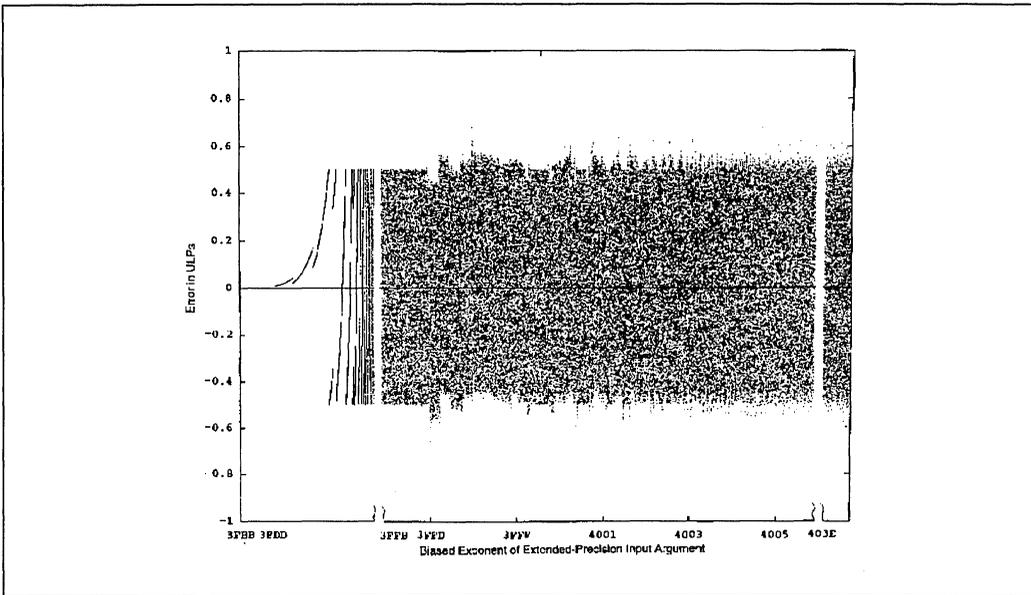


Figure G-1. Scatterplot for FSIN (3FBB-403E)

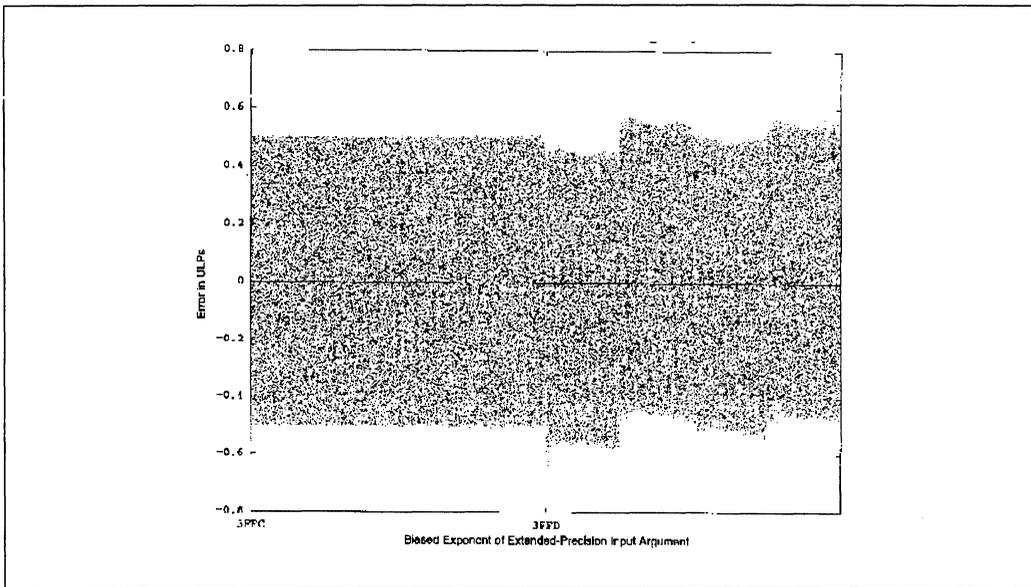


Figure G-2. Scatterplot for FSIN (3FFC-3FFD)

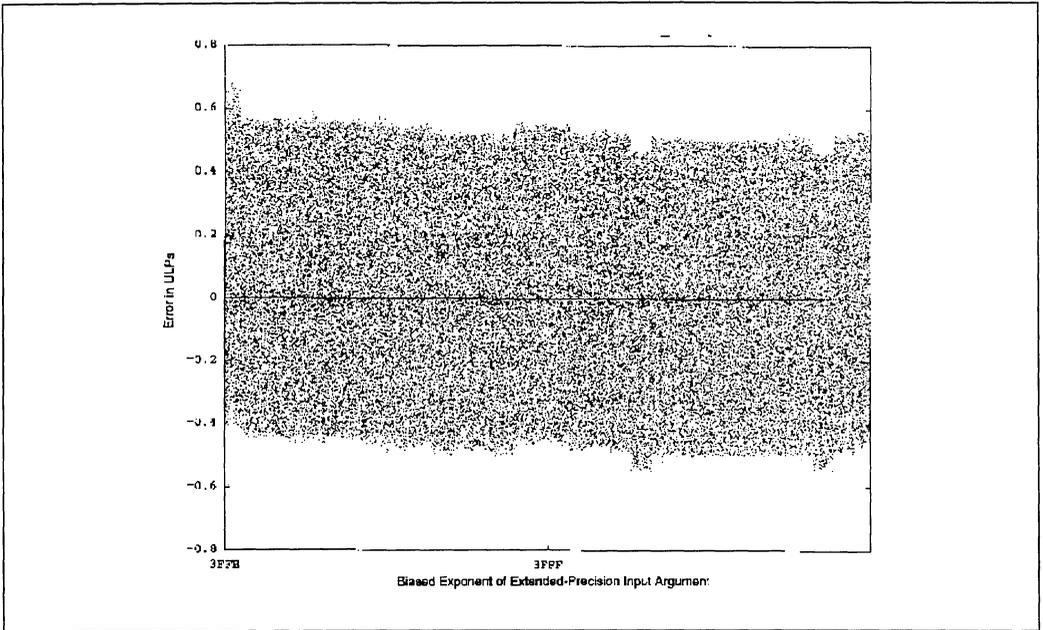


Figure G-3. Scatterplot for FSIN (3FFE-3FFF)

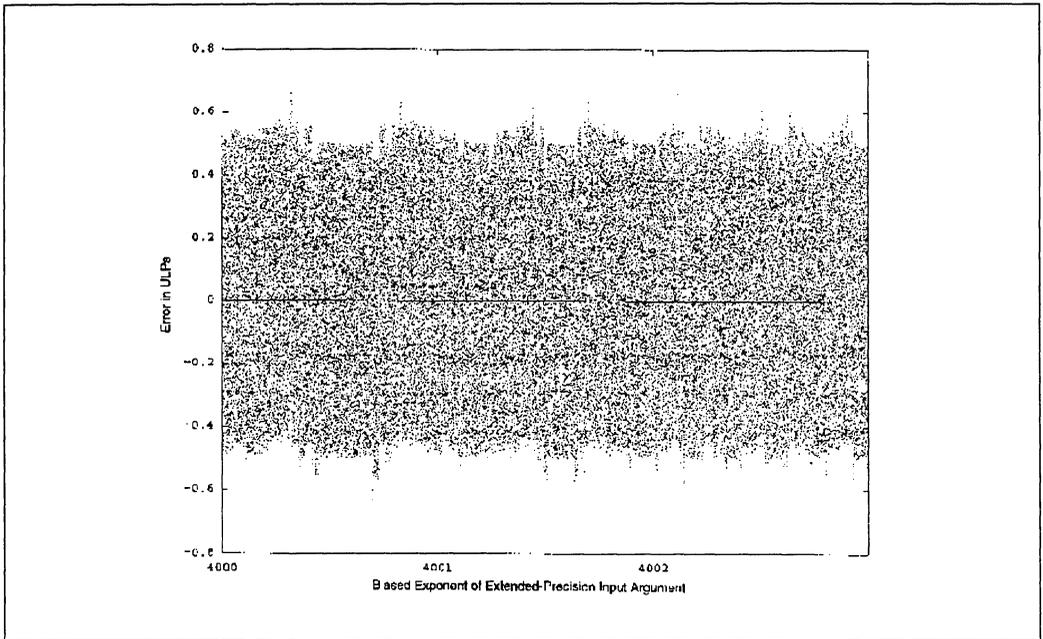


Figure G-4. Scatterplot for FSIN (4000-4002)

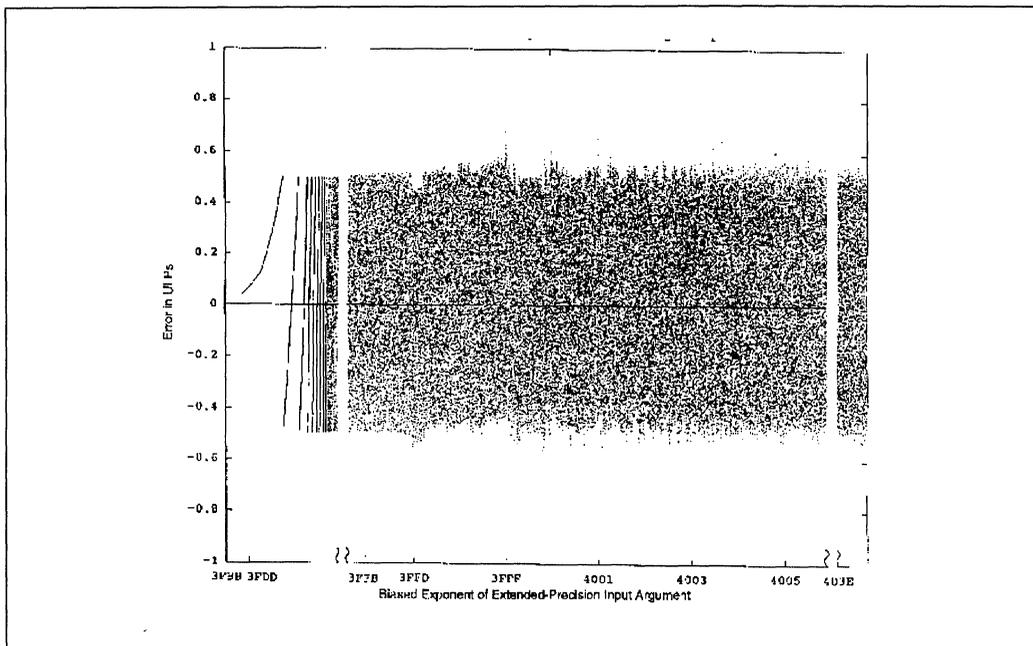


Figure G-5. Scatterplot for FCOS (3FBB-403E)

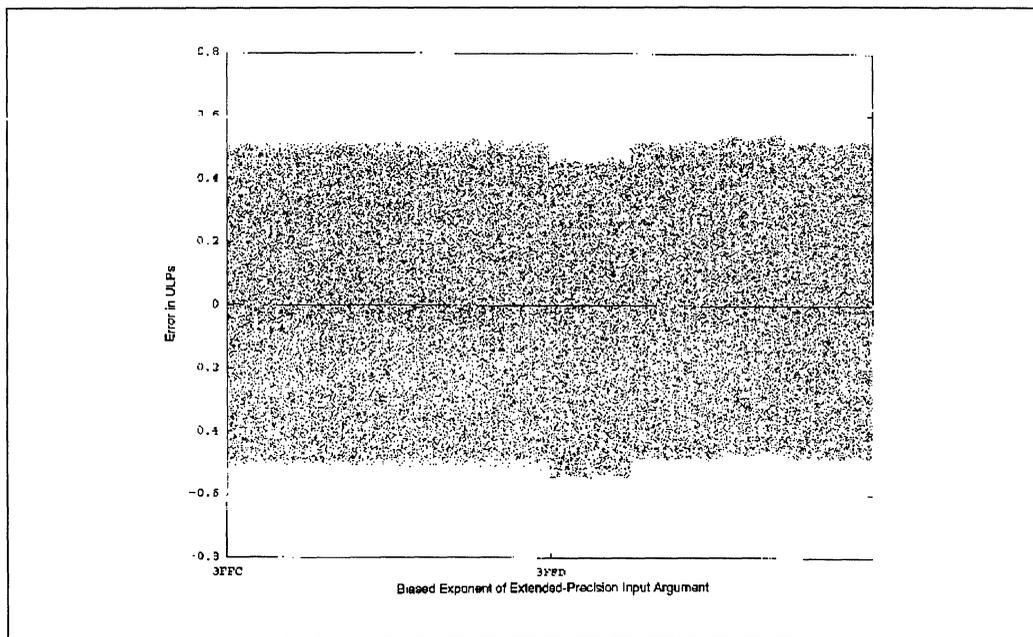


Figure G-6. Scatterplot for FCOS (3FFC-3FFD)



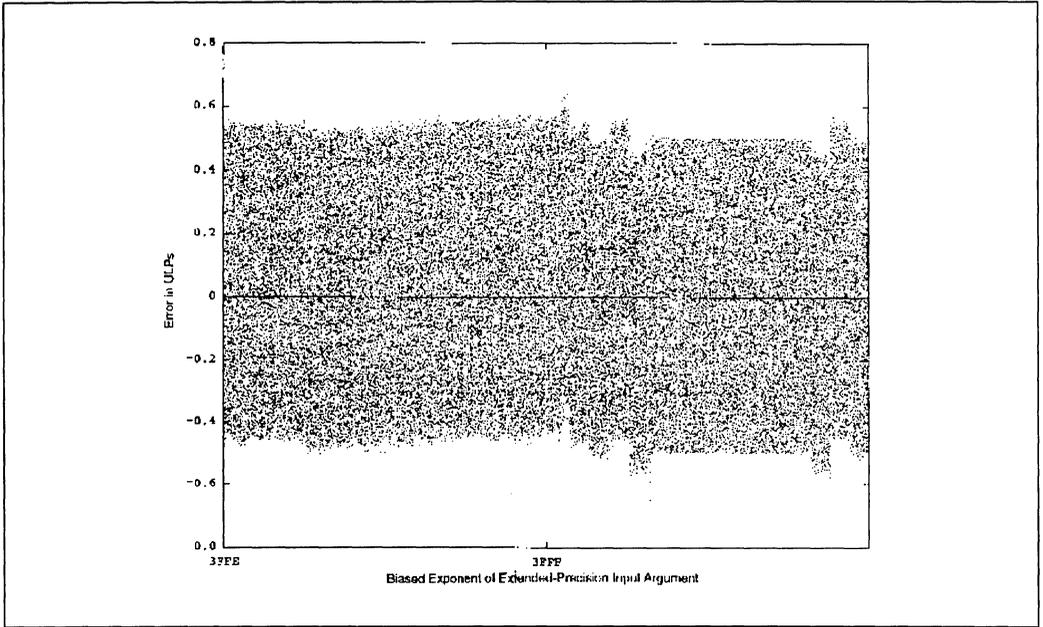


Figure G-7. Scatterplot for FCOS (3FFE-3FFF)

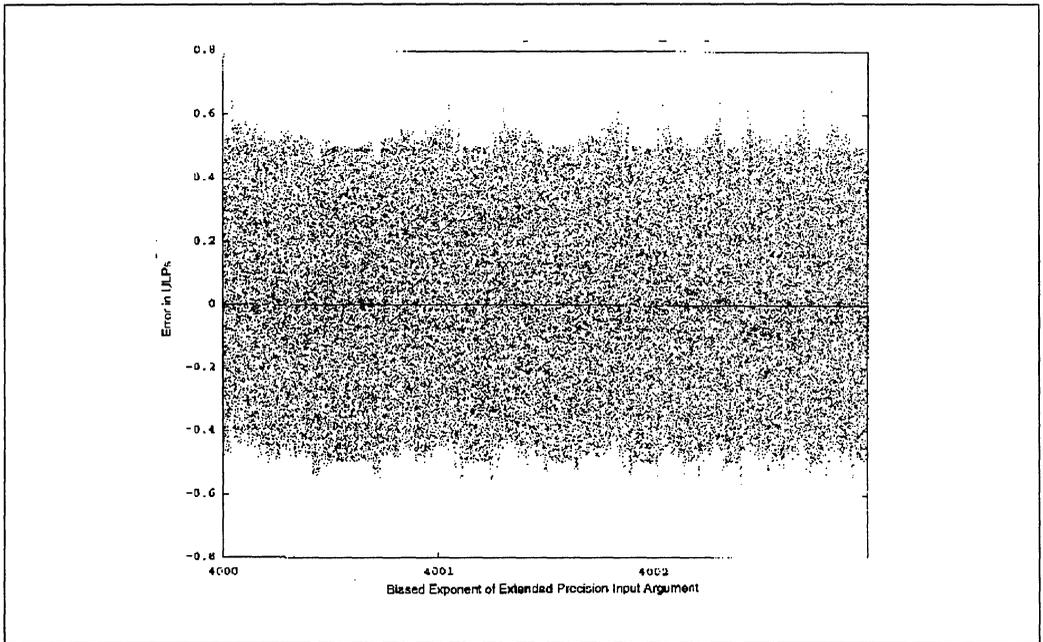


Figure G-8. Scatterplot for FCOS (4000-4002)

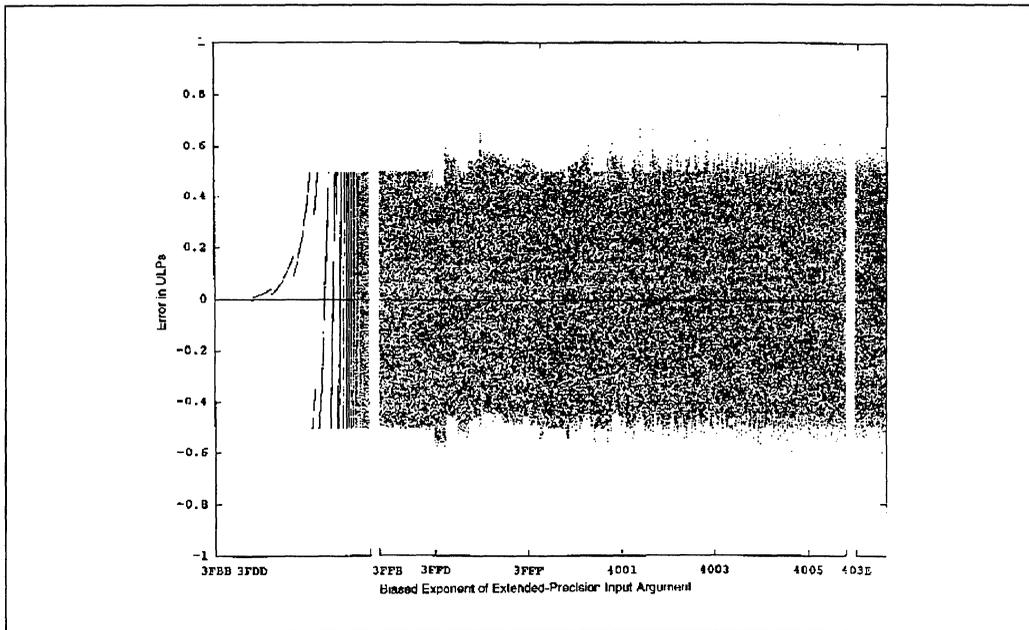


Figure G-9. Scatterplot for FSINCOS (SIN, 3FBB-403E)

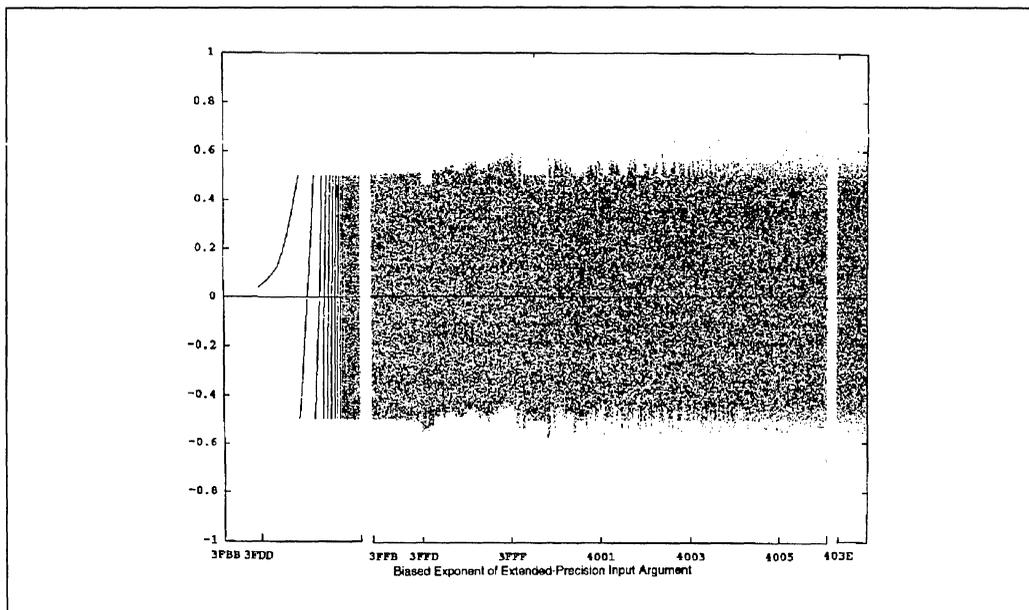


Figure G-10. Scatterplot for FSINCOS (COS, 3FBB-403E)



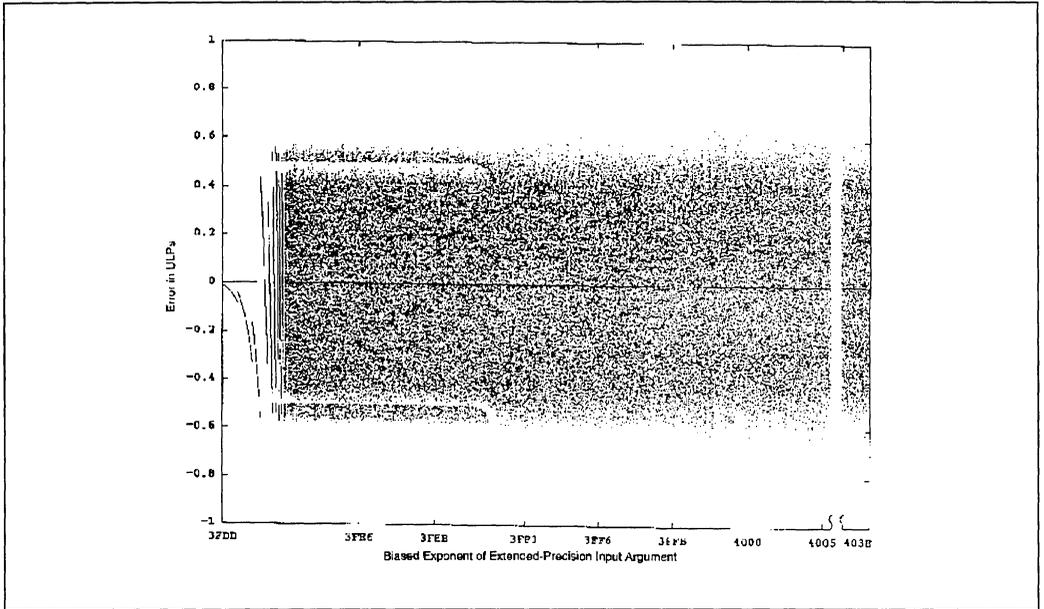


Figure G-11. Scatterplot for FPTAN (3FDD-403E)

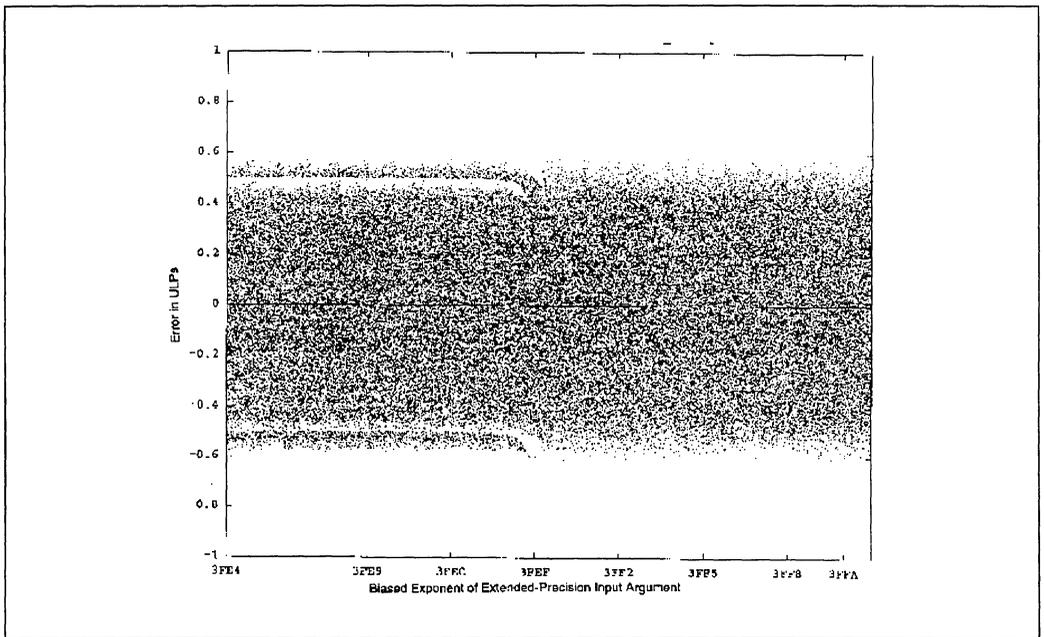


Figure G-12. Scatterplot for FPTAN (3FE4-3FFA)

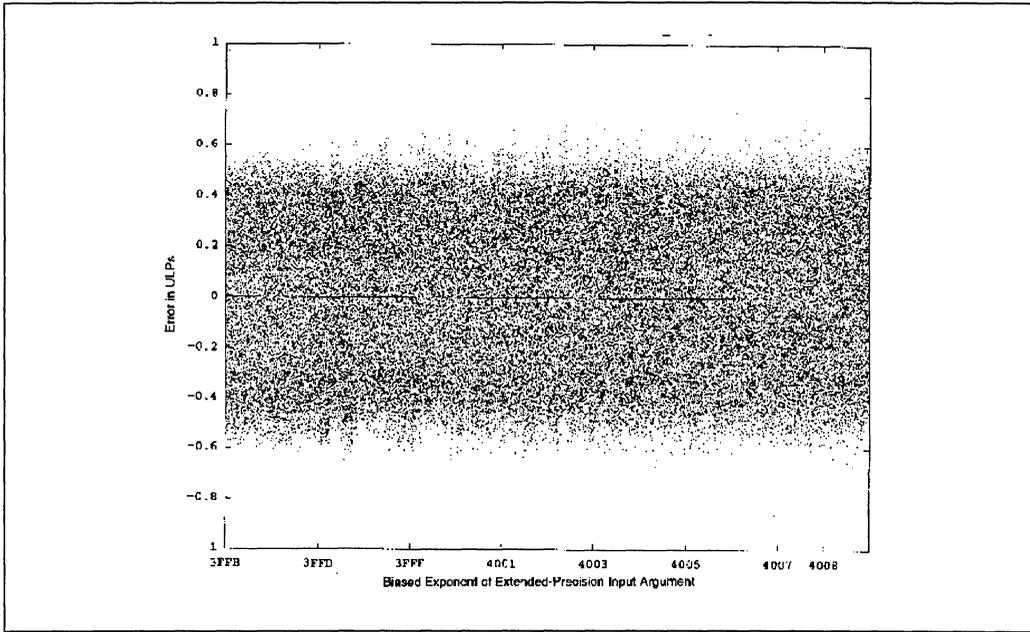


Figure G-13. Scatterplot for FPTAN (3FFB-4008)

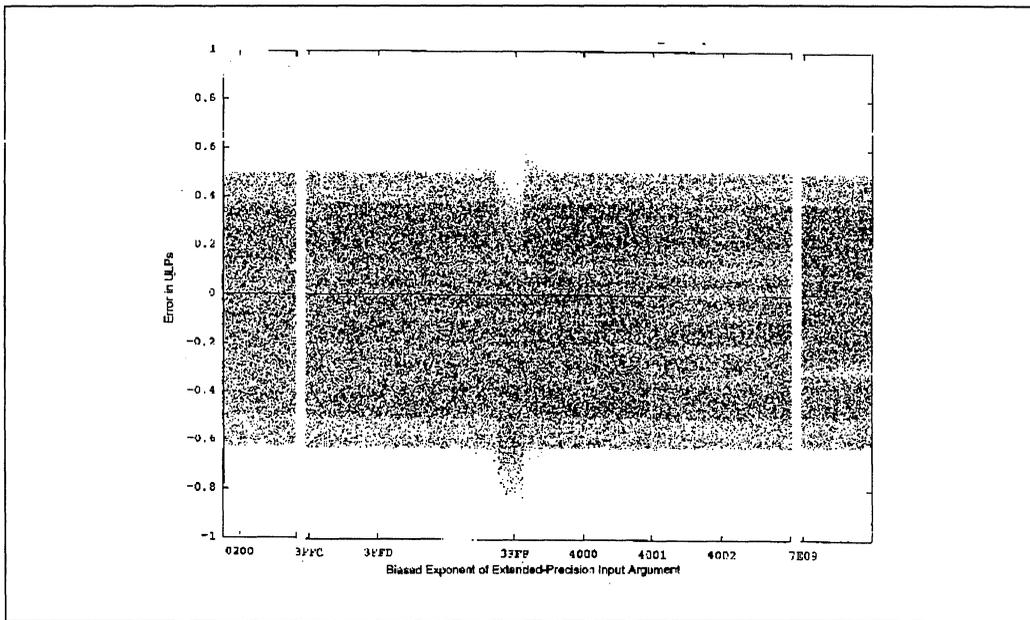


Figure G-14. Scatterplot for FYL2X (0001-7FFD)



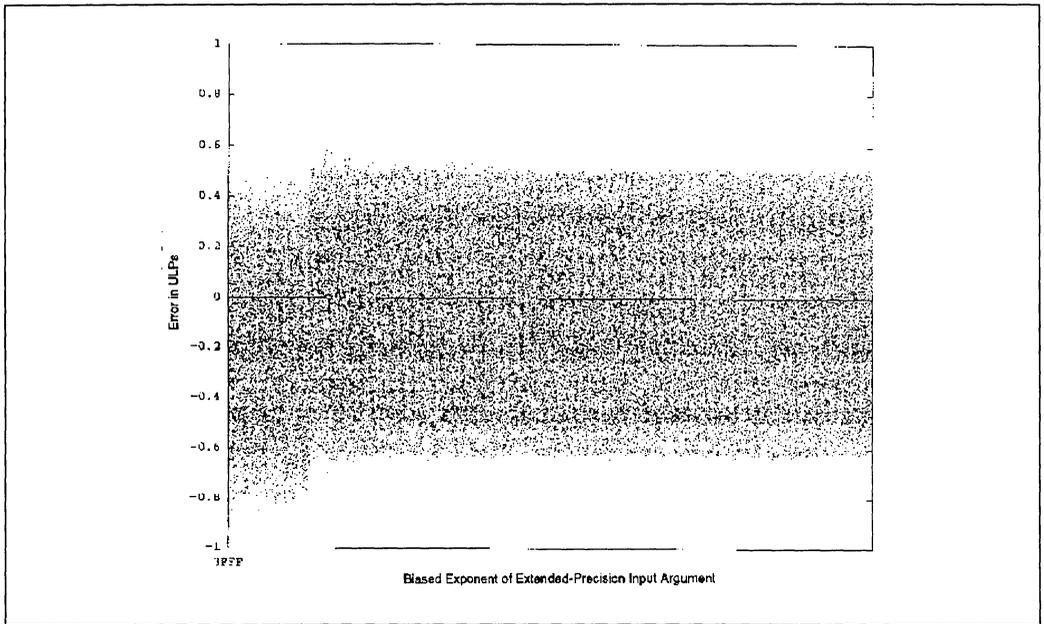


Figure G-15. Scatterplot for FYL2X (3FFF-3FFF)

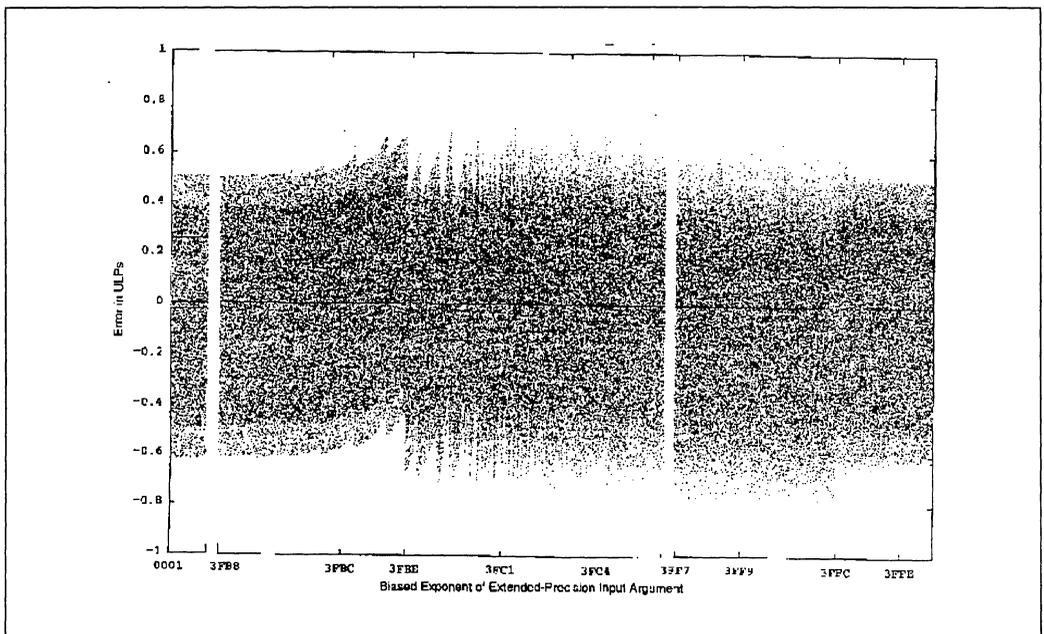


Figure G-16. Scatterplot for FYL2XP1 (0001-3FFE)

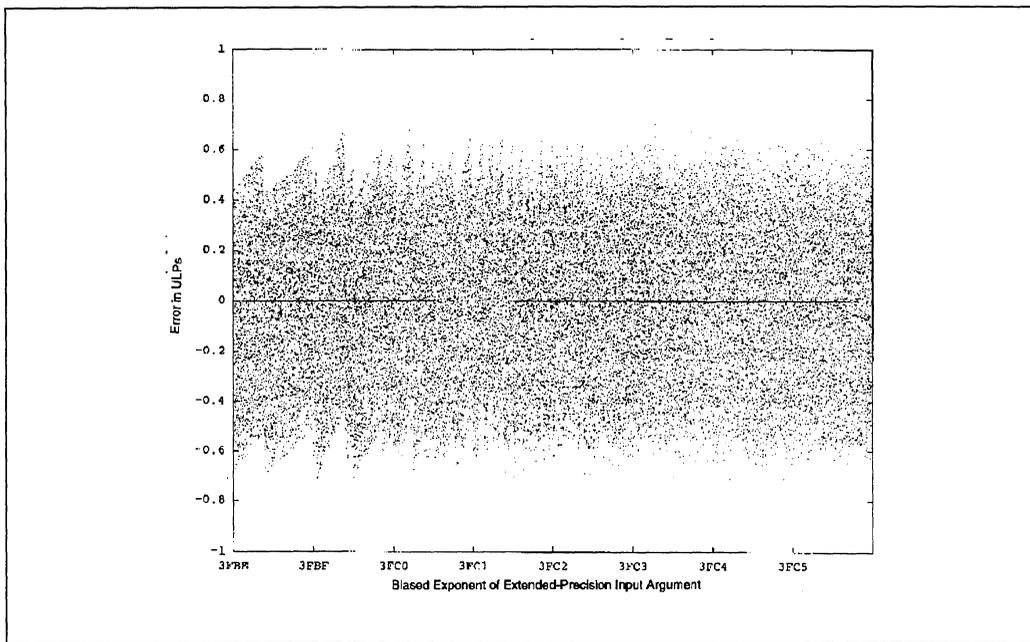


Figure G-17. Scatterplot for FYL2XP1 (3FBE-3FC5)

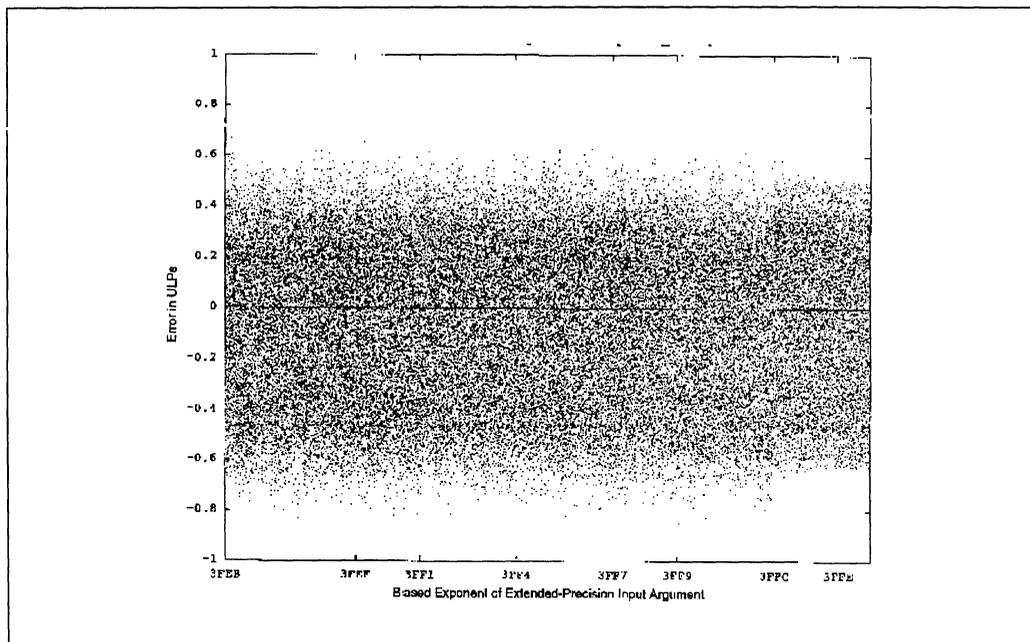


Figure G-18. Scatterplot for FYL2XP1 (3FEB-3FFE)



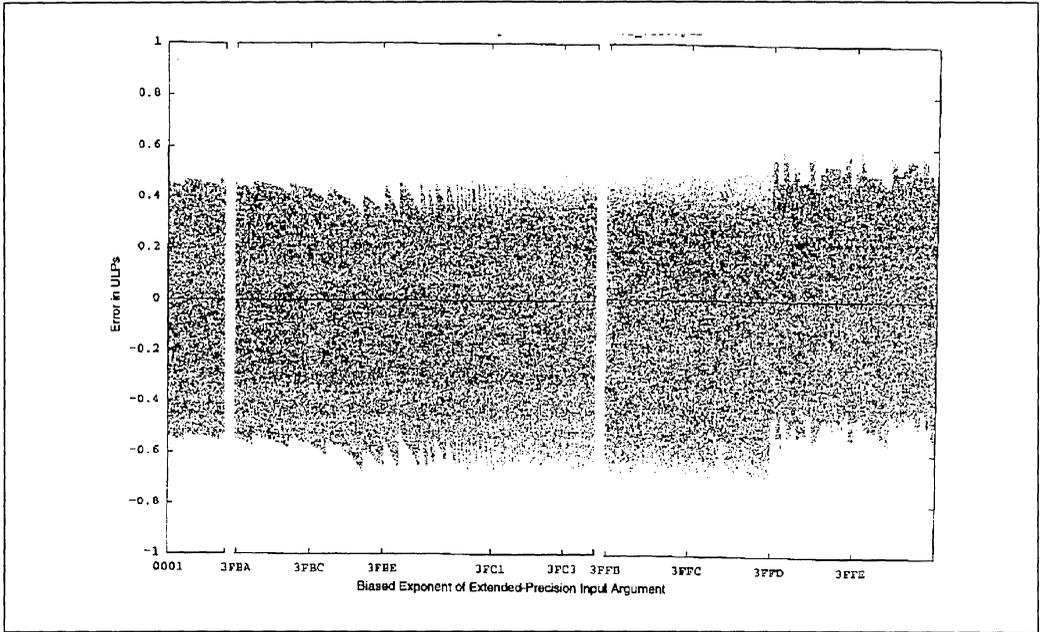


Figure G-19. Scatterplot for F2XM1 (0001-3FFE)

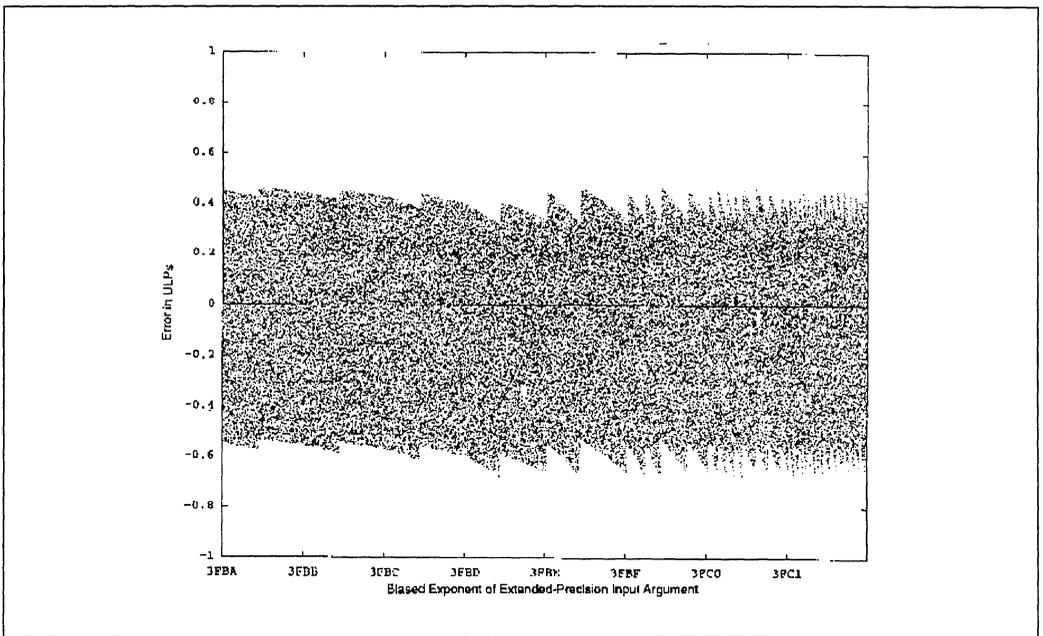


Figure G-20. Scatterplot for F2XM1 (3FBA-3FFE)

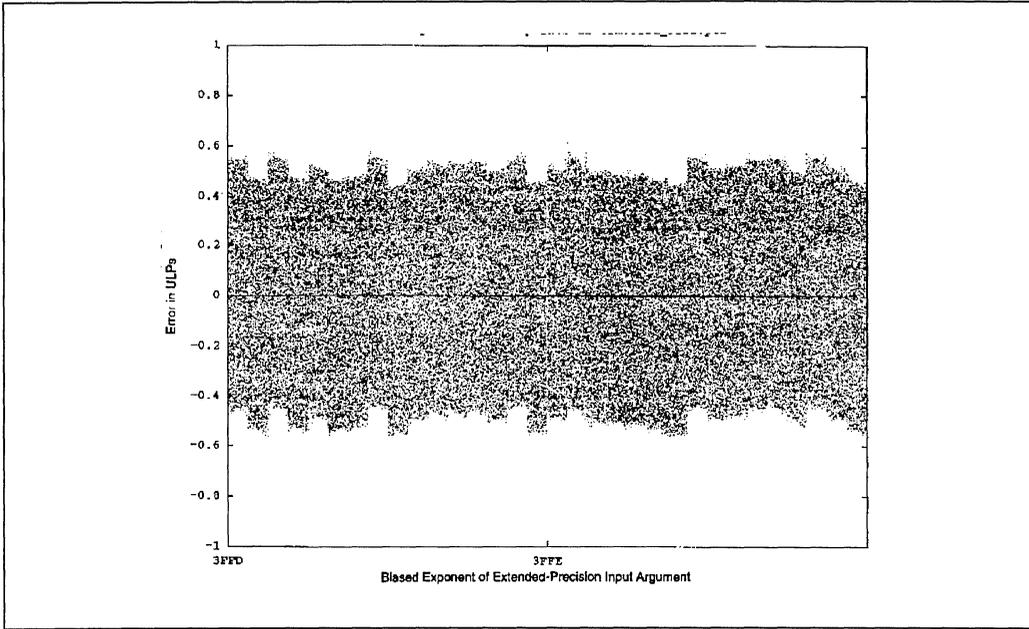


Figure G-21. Scatterplot for F2XM1 (3FFD-3FFE)

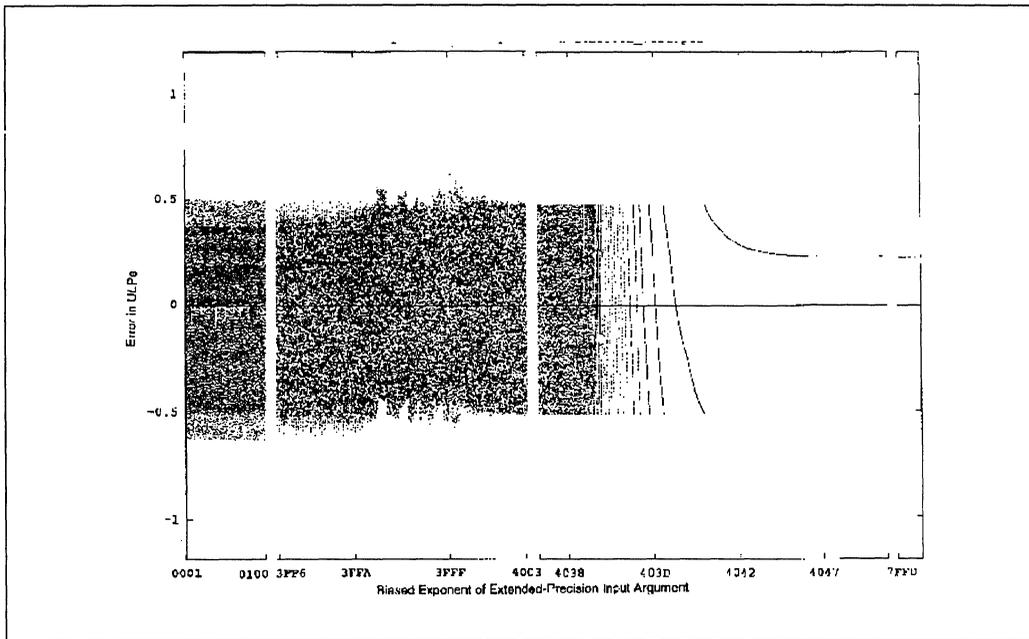


Figure G-22. Scatterplot for FPATAN (0001-7FFD)



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**H**

# **Advanced Features**

**I**





## APPENDIX H ADVANCED FEATURES

Some non-essential information regarding the Pentium processor are considered Intel confidential and proprietary and have not been documented in this publication. This information is provided in the *Supplement to the Pentium® Processor Developer's Manual* and is available with the appropriate non-disclosure agreements in place. Please contact Intel Corporation for details.

The *Supplement to the Pentium® Processor Developer's Manual* contains Intel confidential information on architecture extensions to the Pentium processor which are non-essential for standard applications. This includes low-level registers that provide access to such features as page size extensions, virtual mode extensions, testing and performance monitoring.

This information is specifically targeted at writers of the following types of software:

- Operating system kernels
- Virtual memory managers
- BIOS software

If you are writing software that does not fall into one of these categories, this information is non-essential and all required programming details are contained in the publicly available *Pentium® Processor Developer's Manual*, three-volume set.





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FAX: (407) 834-0865

**Pioneer Technologies Group**  
674 South Military Trail  
Deerfield Beach 33442  
Tel: (305) 428-8877  
FAX: (305) 481-2950

**Wyle Laboratories**  
1000 112th Circle North  
Street Petersburg  
33716  
Suite 900  
Tel: (813) 579-1518  
FAX: (813) 579-1518

### GEORGIA

**Anthem Electronics**  
2400 Pleasant Hill  
Road  
Suites 9 & 10  
Duluth 30136  
Tel: (404) 931-3900  
FAX: (404) 931-3902

**Arrow Commercial System Group**  
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Duluth 30136  
Tel: (404) 623-8825  
FAX: (404) 623-8802

**Arrow/Schweber Electronics**  
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Pkwy.  
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Tel: (404) 497-1300  
FAX: (404) 476-1493

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Suite G  
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Tel: (800) 426-7999

**Hall-Mark Computer**  
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Suite G & A  
Duluth 30136  
Tel: (800) 409-1483

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Tel: (404) 623-5475  
FAX: (404) 623-5490

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**Anthem Electronics**  
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FAX: (708) 885-0480

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Itasca 60143  
Tel: (708) 250-0500

**Avnet Computer**  
1124 Thorndale  
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Bensenville 60106  
Tel: (800) 426-7999

**Hall-Mark Computer**  
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Avenue  
Bensenville 60106  
Tel: (800) 409-1483

**Hamilton Hallmark**  
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Bensenville 60106  
Tel: (800) 426-7999

**MTI Systems Sales**  
1140 West Thorndale  
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FAX: (708) 495-9831

**Wyle Laboratories**  
2055 Army Trail Road  
Suite 140  
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Tel: (800) 853-9953  
FAX: (708) 620-1610

**Zeus Arrow Electronics**  
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Itasca 60143  
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Carmel 46032  
Tel: (800) 426-7999

**Hall-Mark Computer**  
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Carmel 46032  
Tel: (800) 409-1483

**Hamilton Hallmark**  
655 West Carmel Drive  
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Tel: (317) 575-3500  
FAX: (317) 575-3535

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Drive  
Indianapolis 46250  
Tel: (317) 573-0880  
FAX: (317) 573-0979

### KANSAS

**Arrow/Schweber Electronics**  
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Tel: (913) 541-9542  
FAX: (913) 541-0328

**Avnet Computer**  
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Lenexa 66219  
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**Hamilton Hallmark**  
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FAX: (913) 888-0523

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**Anthem Electronics**  
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Gateway Drive  
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Tel: (800) 239-6039

**Arrow Commercial System Group**  
200 Perry Parkway  
Gaithersburg 20877  
Tel: (301) 670-1600  
FAX: (301) 670-0188

**Arrow/Schweber Electronics**  
9800J Patuxent Woods  
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FAX: (301) 995-6201

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Gateway Drive  
Suite G  
Columbia 21045  
Tel: (800) 426-7999

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Gateway Drive  
Suite G  
Columbia 21046  
Tel: (800) 409-1483

**Hamilton Hallmark**  
10240 Old Columbia  
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Columbia 21046  
Tel: (800) 409-1483

**North Atlantic Industries Systems Division**  
7125 River Wood Drive  
Columbia 21046  
Tel: (301) 312-5800  
FAX: (301) 312-5850

**Pioneer Technologies Group**  
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Gaithersburg 20877  
Tel: (301) 921-0660  
FAX: (301) 670-6746

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Tel: (301) 490-2170  
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**Avnet Computer**  
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**Hall-Mark Computer**  
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Peabody 01960  
Tel: (800) 409-1483

**Hamilton Hallmark**  
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Tel: (508) 531-7430  
FAX: (508) 532-9802

**Pioneer Standard**  
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**Arrow/Schweber Electronics**  
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Road  
Suite 120  
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Tel: (800) 426-7999

**Hall-Mark Computer**  
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Suite 120  
Novi 48375  
Tel: (800) 409-1483

**Hamilton Hallmark**  
44191 Plymouth Oaks  
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Suite 1300  
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FAX: (313) 416-5811

**Hamilton Hallmark**  
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FAX: (313) 347-4021

**Pioneer Standard**  
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FAX: (616) 698-1831

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### MINNESOTA

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FAX: (612) 944-3045

**Arrow/Schweber Electronics**  
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9401 James Avenue  
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FAX: (612) 881-9461

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**Hall-Mark Computer**  
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Earth City 63045  
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FAX: (314) 291-0362

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Mountain Lakes 07046  
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FAX: (716) 427-0735

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FAX: (516) 231-1072

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Tel: (800) 426-7999

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**Hamilton Hallmark**  
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FAX: (516) 434-7491

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FAX: (716) 475-9119

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250 West 34th Street  
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Binghamton 13904  
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FAX: (607) 722-9562

**Pioneer Standard**  
60 Crossway Park  
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11797  
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840 Fairport Park  
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FAX: (919) 878-9517

**Avnet Computer**  
4421 Stuart Andrew  
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Suite 600  
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**Hall-Mark Computer**  
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Road  
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**Hamilton Hallmark**  
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Tel: (800) 409-1483

**Pioneer Technologies**  
**Group**  
2200 Gateway Cir.  
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Morrisville 27560  
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### OHIO

**Arrow Commercial**  
**System Group**  
284 Cramer Creek  
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Dublin 43017  
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FAX: (614) 889-9680

**Arrow/Schweber**  
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6573 Cochran Road  
Suite E  
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FAX: (216) 248-1106

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8200 Washington  
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FAX: (513) 435-2049

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7764 Washington  
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Tel: (800) 426-7999

**Avnet Computer**  
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Tel: (800) 426-7999

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5821 Harper Road  
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**Hall-Mark Computer**  
777 Dearborn Park  
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**Hamilton Hallmark**  
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Tel: (216) 498-1100  
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**Hamilton Hallmark**  
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Tel: (614) 888-3313  
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**MTI Systems Sales**  
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**Hamilton Hallmark**  
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Tulsa 74146  
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Tel: (503) 629-8090  
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Tel: (503) 643-1114  
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9750 Southwest  
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**Hamilton Hallmark**  
9750 Southwest  
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Tel: (503) 526-6200  
FAX: (503) 641-5339

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8905 Southwest  
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Tel: (503) 626-7300  
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9640 Sunshine Court  
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Beaverton 97005  
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### PENNSYLVANIA

**Anthem Electronics**  
355 Business Center  
Drive  
Horsham 19044  
Tel: (215) 443-5150  
FAX: (215) 675-9875

**Avnet Computer**  
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Suite 320  
Mars 16046  
Tel: (800) 426-7999

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FAX: (412) 963-8255

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Tel: (713) 530-4700

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FAX: (609) 985-8757

### TEXAS

**Anthem Electronics**  
651 N. Plano Road  
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Richardson 75081  
Tel: (214) 238-7100  
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14050 Summit Drive  
Suite 119  
Tel: (512) 388-0049  
FAX: (512) 388-0271

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**Electronics**  
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**Arrow/Schweber**  
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3220 Commander Drive  
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Dallas 75244  
Tel: (800) 426-7999

**Avnet Computer**  
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Houston 77008  
Tel: (800) 426-7999

**Hall-Mark Computer**  
12211 Technology  
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Tel: (800) 409-1483

**Hall-Mark Computer**  
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Suite 200  
Dallas 75244  
Tel: (800) 409-1483

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1235 North Loop West  
Houston 77008  
Tel: (800) 409-1483

**Hamilton Hallmark**  
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Salt Lake City 84121  
Tel: (800) 426-7999

**Hall-Mark Computer**  
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Salt Lake City  
Tel: (800) 409-1483

**Hamilton Hallmark**  
1100 East 6600 South  
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Tel: (801) 268-2022  
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1325 West 2200 South  
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19017 120th Avenue  
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Suite 102  
Bothell 98011  
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FAX: (206) 486-0571

**Avnet Computer**  
8630 154th Avenue  
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Tel: (800) 426-7999

**Hamilton Hallmark**  
8630 154th Avenue  
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Tel: (206) 881-6697  
FAX: (206) 867-0159

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Tel: (800) 426-7999

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Street  
New Berlin 53146  
Tel: (800) 409-1483

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FAX: (414) 879-0474

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## CANADA

### ALBERTA

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Fax: 525 703 1772

**Dicopel Inc.**  
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FAX: (619) 423-3394

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FAX: 42 871 528

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**AAE Systems, Inc.**  
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\*Carry-in locations

Focusing on the Pentium® processor family architecture, this manual includes architecture and programming information specific to the Pentium processors at iCOMP® index 1110\133MHz, 1000\120MHz, 815\100MHz, 735\90MHz and 615\75MHz. Additionally, a comprehensive listing of the Pentium processor family instruction set and several code examples are included.

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